# IITM High-Resolution Global Forecast Model Version 1: An attempt

# to resolve monsoon prediction deadlock

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Abstract. The prediction of Indian monsoon rainfall variability, affecting a country with a population of billions, remained one of the major challenges of the numerical weather prediction community. While in recent years, there has been a significant improvement in predicting the synoptic scale transients associated with the monsoon circulation, the intricacies of rainfall variability remained a challenge. Here, an attempt is made to develop a global model using a dynamic core of a cubic octahedral grid that provides a higher resolution of 6.5 km over the global tropics. This high-resolution model has been developed to resolve the monsoon convection. Reforecasts with the IITM High-resolution Global Forecast Model (HGFM) have been run daily from June through September 2022. The HGFM model has a wavenumber truncation of 1534 in the cubic octahedral grid. The monsoon events have been predicted with a ten-day lead time. The HGFM model is compared to the operational GFS T1534. While the HGFM provides skills comparable to the GFS, it shows better skills for higher precipitation thresholds. This model is currently being run in experimental mode and will be made operational.

#### 1 Introduction

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In spite of significant improvement in numerical weather prediction skills in the last decades (Bechtold et al., 2008; 56 Magnusson and Kallen, 2013; Hoffman et al., 2018), predictions of tropical rainfall variability remain a challenge (Westra et 57 58 al., 2014; Prakash et al., 2016). Stephens et al. (2010) demonstrated that the models predict too many rainy days in the tropics, which are in the lighter rain category. The challenges of tropical rainfall variability have also been demonstrated by 59 60 Watson et al., 2017. The vagaries of the Indian monsoon every year affect the lifestyle of billions of people and the economy of the Indian sub-continent, modulating its Gross Domestic Product (GDP) (Gadgil and Gadgil, 2006). It is, therefore, of the 61 utmost importance to improve the weather prediction skill in general and extreme precipitation events in particular. With the 62 increase in computing power, the resolution of numerical weather prediction models has been increasing, and global models 63 with a resolution of 1~7 km have become a reality (Majewski et al., 2002; Satoh et al., 2005; Miura et al., 2007; Staniforth 64 65 and Thuburn, 2012; Li et al., 2015; Satoh et al., 2019; Wedi et al., 2020). The higher resolution of Numerical Weather Prediction (NWP) models has been found to produce a realistic rainfall variability across scales including diurnal variation, 66 better Madden Julian Oscillation (MJO) variability and seasonal mean climate (Kinter et al., 2013; Rajendran and Kitoh, 67 2008; Skamarock et al., 2012; Molod et al., 2015; Crueger et al., 2018; Giorgetta et al., 2018). In India, operational NWP 68 was initiated with a moderate resolution of T80 and then gradually enhanced to T382, T574 (Prasad et al., 2011, 2014, 69 70 2017), and very recently to T1534 (Mukhopadhyay et al., 2019). The advantage of using a higher resolution (T1534~12.5 71 km) as against the lower resolution T574 (~27 km) was found by enhancement of the model skill by 2 days (Rao et al., 72 2019). The National Centre for Environmental Prediction (NCEP) GFS model with 21 members has been used for 73 probabilistic forecasts since June 2018 (Deshpande et al., 2021). The high-resolution GFS T1534 is found to enhance the skill of heavy rainfall events (Mukhopadhyay et al., 2019), tropical cyclones, and even block level prediction of rainfall 74 75 (block is a sub-division of districts in India, typically of the size of the grid of GFS T1534). However, the skill of the GFS T1534 for the prediction of extremely heavy precipitation can still be improved, particularly over the orographic regions of 76 India, such as the southern coastal state of Kerala, India (Mukhopadhyay et al., 2021). 77 78 The 12-km deterministic and the ensemble model based on the GFS show reasonably good skill in capturing the monsoon rainfall with 3 to 5 days lead time. The skill of the GFS forecast for the Indian monsoon has been reported by 79 80 Mukhopadhyay et al. (2019), and the skill of tropical cyclones with the Global Ensemble Forecast System (GEFS) has also 81 been reported by Deshpande et al. (2021) and Kanase et al. (2023). However, in a recent study, Mukhopadhyay et al. (2021) showed that three state-of-the-art ensemble forecast systems, namely the GEFS, the United Kingdom Meteorological Office 82 (UKMO) based NCMRWF Ensemble Prediction System (NEPS) run by National Centre for Medium Range Weather 83 Forecasting (NCMRWF) and the Integrated Forecasting System (IFS) by ECMWF struggled to capture the extremely heavy 84 85 rainfall over Kerala state of India during August 2018 and August 2019 extremely heavy rainfall episode. This, in fact, 86 brought up the limitation of the model in resolving the rainfall variability over the Indian region and, more importantly, over the orographic region. One of the limitations in resolving the regional variabilities of rainfall is the horizontal resolution 87

88 which does not allow the model to resolve the smaller scale processes. Therefore, a need was felt to enhance the horizontal 89 resolution of the existing GFS-based forecasting system. As running a model close to the convection permitting model (at a 90 resolution lesser than 10 km) is computationally too expensive in conventional linear reduced Gaussian grids, it was thought 91 to build a weather model with a grid that has a variable resolution from the pole to the equator. In view of this, the GFS 92 linear reduced Gaussian Grid at triangular truncation 1534 is replaced by an equivalent truncation of 1534 in a triangular 93 cubic octahedral (Tco) grid. The equivalent model resolutions of the linear T1534 and the cubic Tco1543 grids are displayed in Fig. 1a. Indeed, as the linear grid has a roughly uniform grid point resolution of 12.5 km, the octahedral grid has a 94 95 resolution of about 8 km in the Polar Regions and around 6 km in the tropical band. One of the prominent examples of the 96 Global NWP model with the Tco grid is that of the European Centre for Medium-Range Weather Forecasts (ECMWF) model suites. The Tco grid provides several advantages (ECMWF Documentation Cy43r1, 2016) over that of the 97 98 conventional reduced Gaussian linear grid (Fig. 1a), to name a few-significant reduction in computation cost, improved 99 representation of orography, better filtering, and better conservation properties. These properties of Tco make it a better 100 candidate, particularly for the utilization of high-performance computers (HPC). 101 To the best of our knowledge, this paper is the first attempt towards building a model close to a convection permitting global 102 weather model in India with an emphasis on Indian monsoon rainfall variability. The details of the model development and 103 the experiments conducted have been elaborated in Sect. 2. The model results are analysed in Sect. 3, and the conclusion of

# 2 Model, Data, and Methodology

the study is summarized in Sect. 4.

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106 This new grid, namely the Triangular Cubic Octahedral (Tco) grid, has been adopted to change the existing GFS (semi-107 lagrangian) Gaussian linear model system. In the spectral domain, dynamical fields are represented by the sum of spherical harmonics. The total wavenumber characterizes the spherical harmonics, and the associated wavelength is the ratio of the 108 109 circumference of the Earth to the total wavenumber. The value of the maximum wavenumber (n max) used to represent a 110 field as the sum of spherical harmonics is also the spectral truncation of the model. In the case of both GFS and Tco, the 111 value of n max is 1534. For the same spectral truncation n max, the number of latitude circles from the equator to the pole can vary depending on the choice of spectral transformation. For a linear grid, n max=2N-1, and for a cubic grid, n max=N-112 113 1. Therefore, for a linear Gaussian grid, the smallest wavelength is represented by only two grid points, as is the case with 114 the GFS 1534 model. However, in the case of triangular truncation, the smallest wavelength is represented by four grid points (in the case of the Tco grid). In triangular truncation, for the same spectral truncation, the number of latitude circles is 115 about double that of the linear truncation. For the GFS model, the horizontal resolution is ~12.5 km, and applying the cubic 116 117 grid ensures that the horizontal resolution becomes ~6.5 km in the tropics (about half of the currently used model resolution) 118 for the Tco grid. In the Tco grid, the number of latitude circles is 1535.

Once a particular choice of spectral truncation is made, the number of latitude circles becomes obvious. However, the number of longitude circles per latitude circle remains to be prescribed for creating the global grid structure. In a fully Gaussian grid, the number of longitude circles per latitude circle remains the same throughout the latitudes from the equator to the pole. Thus, the effective resolution near the poles becomes very high compared to the equatorial regions. This specific requirement demands too many computational resources and poses numerical instability problems. To overcome that, in the linear Gaussian grid, the number of latitude circles decreases in a certain way from the equator toward the pole to ensure almost the same zonal resolution. For the cubic octahedral grid, the number of longitude points per latitude circle is prescribed differently. The latitude circle closest to the pole consists of 20 longitude points, and the number of longitude points increases by 4 at each latitude circle, moving from poles towards the equator. The number of longitude points at the equator in the case of the Tco grid is given by Nx=20+1534\*4=6156. Therefore, the zonal grid length=2pi\*R/Nx~6.5 km. In the original reduced Gaussian grid, the number of longitude points per latitude remains fixed in different blocks of latitudes. The number of latitude points jumps from one block to another by a constant number. Unlike the linear reduced Gaussian grid, the horizontal resolution varies more smoothly with latitudes in Tco. The Collignon projection of a sphere obtains this configuration onto an octahedron. In the current study, the Tco grid at truncation wavenumber of 1534 is being used. This new version of the model is mentioned as HGFM (High-resolution Global Forecast Model Version 1) throughout the manuscript. Fig. 1a and Fig. 1b depict the variation of grid resolution with latitude in the GFS (SL) and HGFM (Tco). Before testing the HGFM with complete physics (see Table 1 for a description of physics used in both versions of the model), we have developed a version of HGFM with only a dynamical core following the approach of Held and Suarez (1994), referred to as HS94. The HS94 was run to check the stability of the Tco grid framework. Surface boundary conditions for the Tco grid were meticulously prepared to ensure the accuracy of grid-point representation. Moreover, the HGFM (Tco1534) has been developed with complete physics and incorporates essential boundary conditions, including global topography, global land-use-land-cover, etc. The HGFM at Tco1534 truncation is depicted over the globe in Fig. 1. The model has been run daily for ten days forecast at IITM Pratyush HPC system. To understand the computational efficiency of the Tco model, the time taken for one day forecast is compared for GFS 1534 and HGFM model (Tco 765 in this case) (see Fig. 1c). A comparison between GFS 1534 and Tco 765 is made because both models have nearly the same number of grid points. It is evident that Tco 765 significantly saves the runtime in dynamical core and total time as well. Moreover, the Tco model is in general more scalable for higher number of cores (not shown). The model has been running since 2022, and here, the analyses for the summer monsoon season of June, July, August, and September (JJAS) 2022 are being presented. A detailed analysis of the model run is discussed in the results section. Apart from the monsoon season

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(JJAS 2022), a few case studies are also discussed.

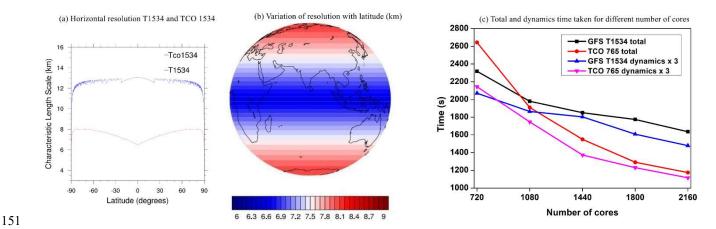


Figure 1. Variation of grid length with latitude in GFS (blue) and Tco (red) (a), depiction of grid resolution over the globe in Tco grid (b), total and dynamics time taken for different number of cores (c). Time taken by GFS and HGFM for one day forecast (Left vertical axis is total time taken and model dynamics time multiplied by 3).

To verify the model forecast, the daily observed gridded rainfall data from the Integrated Multi-satellite Retrievals for GPM (IMERG) version 06B (Huffman et al., 2019) rainfall data at  $0.1^{\circ} \times 0.1^{\circ}$  (10 km) horizontal resolution is utilized for the year of 2022 for JJAS season. Additionally, for the validation of a heavy rainfall event over India, gridded rainfall data from the India Meteorological Department (IMD) at 25 km resolution is used. The IMD rainfall data are a merged product of gridded rain gauge observations and GPM satellite-estimated rainfall over the Indian Summer Monsoon (ISM) region (Mitra et al., 2014). Further, the reanalysis-based parameters from the fifth generation of ECMWF atmospheric reanalyses (ERA5) products (Hersbach and Dee, 2016) at 25 km horizontal resolution are utilized during JJAS season of the year 2022.

Table 1. Details of domain configuration and physics options used in HGFM.

Physics	Description
Radiation	Rapid Radiative Transfer Model (RRTM) for both Shortwave and Longwave (Iacono et al., 2000; Clough et al., 2005) with Monte Carlo Independent Column Approximation (McICA)
Microphysics	Formulated grid-scale condensation and precipitation (Sundqvist et al., 1989; Zhao and Carr, 1997)
Convection	Aerosol aware and Mass flux based Simplified Arakawa-Schubert (SAS) shallow convection (Pan and Wu, 1995; Han and Pan, 2011; Arakawa and Wu, 2013; Han et al., 2017)
Planetary Boundary Layer (PBL)	Hybrid Eddy-Diffusivity Mass Flux vertical turbulent mixing scheme (Han and Pan, 2011; Han et al., 2016)
Gravity Wave Drag (GWD)	Mountain blocking (Alpert et al., 1988; Kim and Arakawa, 1995; Lott and Miller, 1997) and stationary convective-forced GWD (Chun and Baik, 1998)

#### 164 3 Results and Discussions

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### 3.1 200 hPa Kinetic Energy Spectra

Before going into the details of model validation, the first metric to evaluate the model fidelity is to validate the Kinetic 166 167 Energy (KE) spectra of 200 hPa wind. The KE spectra provide information about the distribution of kinetic energy across 168 scales. A close resemblance between observed /reanalysis-based spectra and spectra produced by the model gives confidence about the accuracy of overall model configuration. The kinetic energy (KE) spectrum in the upper troposphere exhibits two 169 clearly defined power-law patterns. From observational studies, it is established that at large scale, rotational modes prevail 170 (k<sup>-3</sup>), while at mesoscales, divergent modes are dominant (k<sup>-5/3</sup>) (Nastrom and Gage, 1985). Figure 2 shows the KE spectra of 171 200 hPa wind simulated by HGFM and GFS T1534. The KE spectra for the forecast up to 3 days lead time have been 172 compared with ERA5 data. While both the models reasonably capture k<sup>-5/3</sup> behaviour of the mesoscale at the higher 173 174 wavenumber, HGFM appears to capture the k<sup>-3</sup> behaviour of the large scale at the lower wavenumber closer to observation. 175 It is observed that beyond wavenumber 10<sup>-4</sup> there is a slight departure of the spectra from observation, especially for HGFM. However, the regions of interest in KE spectra are the k<sup>-3</sup> dependence for the large scale and a less steep, k<sup>-5/3</sup> dependence for 176 the mesoscale. The tail of the spectra at higher wavenumbers typically has less energy due to the dissipation of kinetic 177 178 energy with an increase of wavenumber. However, models tend to dissipate the energy at higher wavenumbers at a much 179 faster rate depending on the damping used in the model (Skamarock, 2004). To keep the spectra realistic, a common practice 180 is to reduce the damping, which may increase the energy at higher wavenumbers, as observed in this case for HGFM. However, this will not have much impact on our analysis as these are the small-scale features. The KE spectra indicate that 181 182 the overall configuration of both versions of the model is robust. Therefore, we now turn our attention towards verification 183 of convective available potential energy and rainfall simulations, the most desirable parameters in model forecasts.

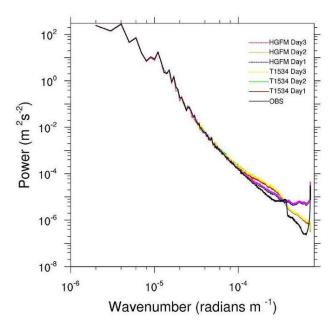


Figure 2. Kinetic energy spectra of 200 hPa wind for observation and different lead times of GFS T1534 and HGFM.

#### 3.2 Quasi-equilibrium in models

Both model versions are run at high-resolutions, close to convection-permitting models' resolution. However, in this case, a scale-aware convection scheme is used to parameterize deep convection in the model. From observational studies, it has been established that tropical atmosphere deviates significantly from the convective-quasi equilibrium (e.g., Zhang, 2003). The convective quasi-equilibrium (CQE) is the fundamental approach used in most models for parameterization of deep convection (Arakawa and Schubert, 1974). To understand the extent to which both model versions obey CQE, we adopted the methodology suggested by Kumar et al. (2022). The absolute value of changes in Convective Available Potential Energy (CAPE) at daily timescales is analysed from GFS T1534 and HGFM models for the year 2022 during JJAS and compared with the ERA-5 data (Figure not shown). Notable changes were observed in the daily dCAPE values between GFS T1534 and HGFM compared to ERA-5. The daily dCAPE values from ERA-5 data match better with the HGFM than GFS T1534 for day 1 and day 3 lead times. The difference of dCAPE between ERA-5 and models is presented for day-1 and day-3 lead time forecasts (Fig. 3). The dCAPE difference quantified from ERA-5 with GFS T1534 were –49.0570 (J/kg/day) and –47.3799 (J/kg/day) for day1 and day 3 lead times, respectively. Similarly, with HGFM, the values were –49.1278 (J/kg/day) and –43.7668 (J/kg/day) for day 1 and day 3 lead times, respectively.

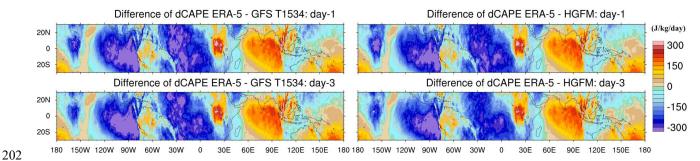


Figure 3. The difference of dCAPE between ERA-5 and GFS T1534 for day-1 and day-3 (left panels), and between ERA-5 and HGFM for day-1 and day-3 (right panels).

### 3.3 Analysis of Global Precipitation

The global precipitation bias of GFS (left panel of Fig. 4 and HGFM (right panel) with respect to Integrated Multi-satellite Retrievals for GPM (IMERG) data, with day 1, day 3, and day 5 lead times, is shown in Fig. 4. Both the models broadly show a similar rainfall bias over the global land and global ocean. However, there are some subtle differences. The day 1 forecast (Fig. 4a) of GFS shows a wet bias over the equatorial eastern Pacific extending up to the tropical western Pacific. On the other hand, the HGFM on day 1 lead (Fig. 4d) also shows a wet bias mostly confined over the tropical eastern Pacific and a slight negative bias over the western Pacific. For HGFM, the positive bias of rainfall over the tropical ocean appears to be mainly over the eastern Pacific, while that of GFS appears to extend from the eastern pacific towards the central and west Pacific for all the lead times. The eastern Pacific precipitation overestimation could be due to improper representation of shallow convection over the region. Raymond (2017) highlighted the complex nature of SST and associated cloudiness and convection over the region. Apart from the oceanic region, the major global land regions (central African Continent, Maritime continent, Indian summer monsoon region, northern part of South America) show a negative bias in both the models at different lead times (Fig. 4) which is likely related to the model's physical parameterizations.

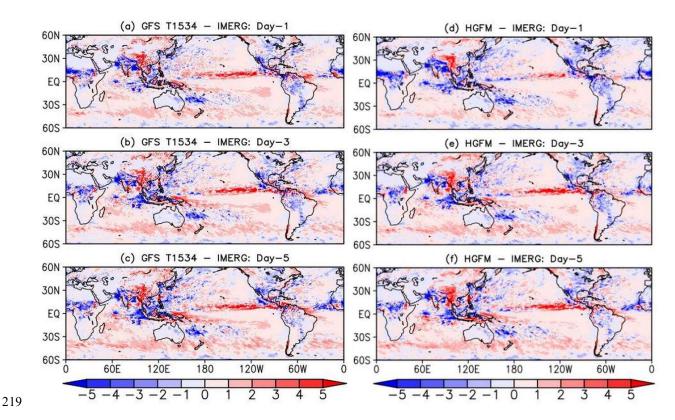


Figure 4. Global JJAS precipitation bias (cm/day) of GFS T1534 (left panel) with respect to IMERG for (a) day-1, (b) day-3 and (c) day-5 lead time. Right column (d-f) indicates similar plots but for HGFM.

#### 3.4 Indian summer monsoon precipitation and related features

While Fig. 4 depicted the precipitation bias over the global domain, it will be interesting to investigate the model forecast performance over the complex orographic region over the Indian domain, the region of our utmost interest. As mentioned earlier, one of the major advantages of using a Tco grid is that it better represents orography. Therefore, it is imperative to investigate the forecast skill of the high-resolution HGFM model over the mountainous Himalayan foothills, adjoining northeast India, and Western Ghats (WGs) region (shown in Fig. 5 and 6 respectively). The GFS T1534 model forecasts indicate spurious rainfall activity over the Himalayan foothills and northeast India region for all lead times (Fig. 5b-d). On contrary, the HGFM model with finer horizontal resolution largely resolves the spurious rainfall over the region, as shown in Fig. 5e-g. The Gibbs waves are largely suppressed over the mountainous terrains in HGFM compared to GFS T1534. Similarly, the precipitation distribution over the WGs region shows considerable overestimation in GFS T1534 for all lead times (Fig. 6b-d). On the other hand, the magnitude of overestimation is decreased considerably in HGFM forecasts, as depicted in Fig. 6e-g. Thus, the above analysis highlights the fact that HGFM shows its potential in predicting realistic rainfall distribution over the orographic regions.

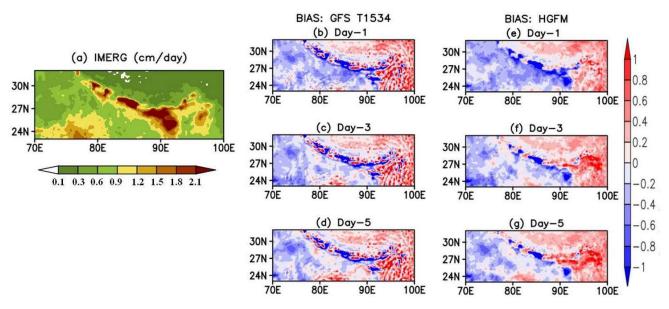


Figure 5. Comparison of JJAS mean precipitation (cm/day) and Bias in IMERG data (cm/day) (a) with GFS T1534 (b, c, d) and TCO 1534 (e, f, g) during 2022 over Himalayan foothills and Northeast India for day-1 day-3 and day-5 lead time.

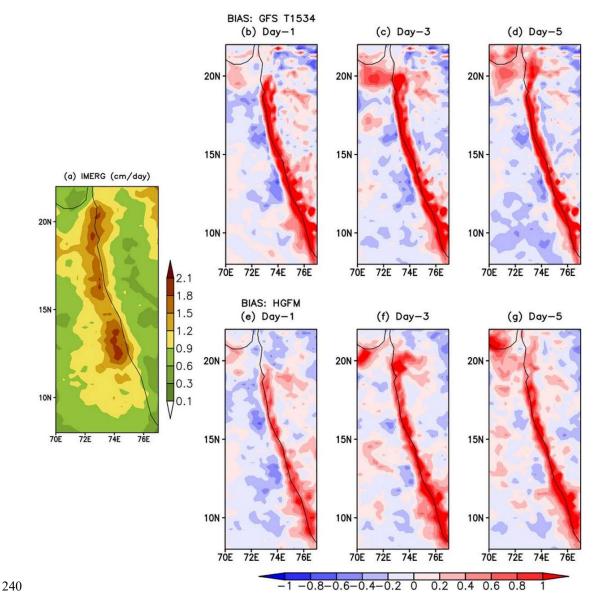


Figure 6. Comparison of JJAS mean precipitation (cm/day) and Bias in IMERG data (cm/day) (a) with GFS T1534 (b, c, d) and TCO 1534 (e, f, g) during 2022 over Western Ghats region for day-1 day-3 and day-5 lead time.

One of the prominent features of ISM is the vertical shear of zonal wind. Previous studies (Jiang et al., 2004; Abhik et al., 2013) demonstrated that the vertical easterly wind shear plays a crucial role in inducing baroclinic vorticity ahead of the northward propagation of summer intra-seasonal oscillation. To assess the model forecast skill in predicting realistic easterly wind shear (difference between zonal wind at 200 and 850 hPa) during the summer monsoon season of 2022, the vertical wind shear calculated and is represented in Fig. 7a and 7b for GFS T1534 and HGFM, respectively, over the ISM region. Figure 7a indicates slightly weaker easterly shear in GFS T1534 compared to ERA5 around 10°N and 0°-15°S for all lead

250 7b. It is noticeable that both models overestimate the magnitude of easterly shear around 20°N for Day-3 and Day-5 lead 251 times. 252 Another key feature of tropical precipitation is almost equipartition of rainfall into convective and stratiform rain. Therefore, 253 it is important to investigate whether the relative improvement in the precipitation distribution over the ISM region in HGFM 254 forecasts is contributed by improved convective and large-scale precipitation. The model forecasted convective and largescale rainfall ratios are shown in Fig. 7c and 7d respectively. It is noteworthy that the large-scale or stratiform rainfall plays 255 256 an important role in the propagation and maintenance of the tropical intraseasonal convection, associated with its top-heavy 257 heating profile (Fu and Wang, 2004; Chattopadhyay et al., 2009; Deng et al., 2015). The heating profile associated with stratiform rain also helps in large-scale organization of convection (see, for example, Choudhary and Krishnan, 2011, Kumar 258 259 et al., 2017). The contribution of convective rainfall to the total rainfall appears to be more than 80 % in GFS T1534 forecasts for all lead times (Fig. 7c). A similar overestimation of convective rainfall in GFS T1534 is reported by Ganai et al. 260 261 (2021). The observed convective (large-scale) rainfall ratio is around 55 % (45 %), as shown in Abhik et al. (2017). The 262 HGFM forecast shows relative improvement in predicting convective and large-scale rainfall ratios compared to GFS T1534 263 (Fig. 7c and 7d). The decrease (increase) in convective (large-scale) rainfall contribution to total rain is noted in HGFM 264 forecast. The finer horizontal resolution in HGFM possibly allows for a more accurate representation of deep convection due 265 to scale-aware representation. 266

times. On the contrary, the HGFM predicts more realistic easterly wind shear over the above regions, as shown in the Fig.

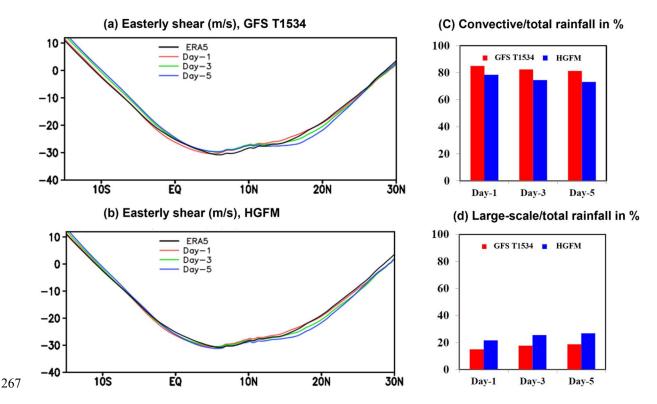


Figure 7. Comparison of easterly shear (m/s) from ERA-5 with GFS T1534 (a) and HGFM (b) along with convective/total rainfall (c) and large scale/total rainfall (d) between GFS T1534 and HGFM during JJAS 2022 for day-1 day-3 and day-5 lead time.

cyclone forecasts.

To attain further clarity about the model precipitation and moist convective processes, the vertical profile of relative humidity as a function of rain rate is analyzed for JJAS of 2022 over the ISM region (60° E-100° E, 10° S-30° N). The bias analysis suggests that GFS T1534 has systematically underestimated the lower-level moisture for all lead times (Fig. 8b). This is consistent with the findings of Mukhopadhyay et al. (2019), and Ganai et al. (2021), who reported a similar underestimation of lower-level moisture over the ISM region in GFS T1534 forecast. In contrast, the HGFM shows relative improvement in the lower-level moisture distribution, as depicted in Fig. 4c for all lead times. The enhancement of the lower-level moisture is noticeable compared to the GFS T1534 forecast. However, the upper troposphere is too moist for both model forecasts and requires further improvement.

It is observed that the overall statistics of monsoon rainfall and related convective processes have significantly improved in the HGFM model. In the next section, a case of heavy rainfall is discussed, followed by the analysis of recent tropical

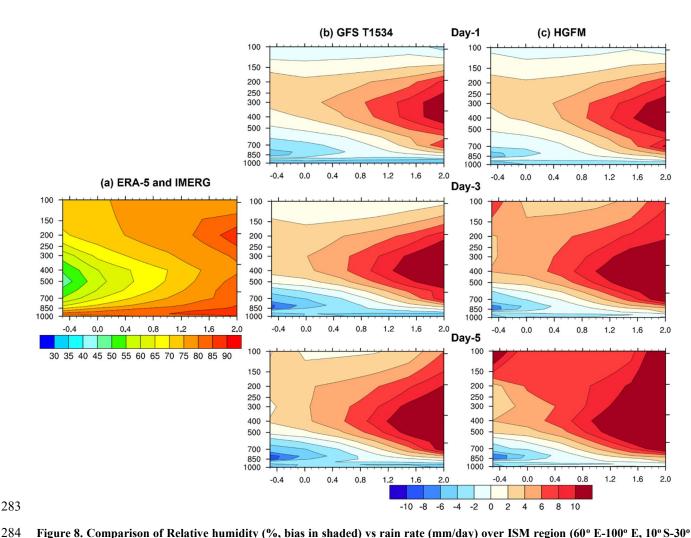


Figure 8. Comparison of Relative humidity (%, bias in shaded) vs rain rate (mm/day) over ISM region (60° E-100° E, 10° S-30° N) during JJAS-2022 from ERA-5 and IMERG (a) with GFS T1534 (b) and HGFM (c) during JJAS 2022 for day-1 day-3 and day-5 lead time.

# 3.5 Evaluation of Heavy Rainfall event

A very heavy rainfall event occurred on 22 August 2022 over central India. This event was well captured by both GFS T1534 and HGFM models as compared to the observed rain from IMD-GPM (shown in Fig. 9). Both HGFM (Fig. 9a, b, c) and GFS T1534 (Fig. 9d, e, f) models simulated the heavy rainfall signature compared to IMD-GPM (Fig. 9g) on day 1 and day 3 forecasts. However, a significant difference was noted in rainfall intensity and spatial distribution at longer lead times (day 5) in HGFM and GFS T1534. Both the models underestimated rainfall compared to observations. Nevertheless, the HGFM captures the signal of heavy rainfall occurrence even at day 5 lead time, which is almost negligible in the GFS T1534 forecast. Further, the precipitation probability distribution function (PDF) is analyzed (figure not shown) for the JJAS 2022

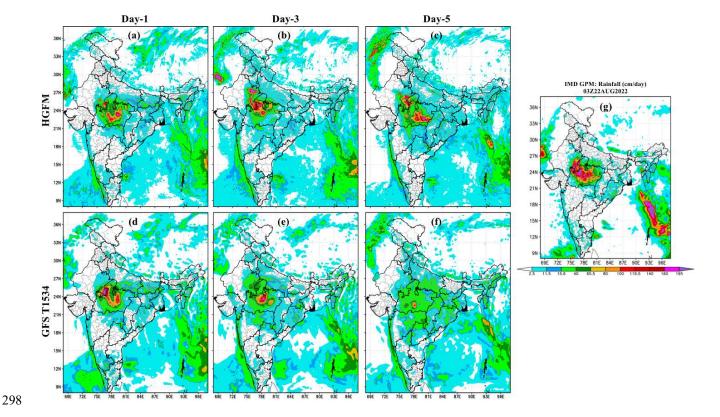


Figure 9. Comparison of heavy rainfall event on 22 August 2022 with HGFM (a, b, c), GFS T1534 (d, e, f) for day-1, day-3, and day-5 lead times with IMD GPM (g) rainfall.

## 3.5 Evaluation of Tropical Cyclone Forecast

A Total of eight named tropical cyclones occurred during 2022 and 2023 (RSMC 2022, RSMC 2023), which are considered in the present study. Out of these eight cases, two cyclones formed over the Arabian Sea and six cyclones over the Bay of Bengal (BOB). The best track data of track, intensity, and landfall is obtained from IMD and referred to as observations henceforth in the text. Figure 10 shows the observed tracks (Fig. 10a) and observed intensity in terms of the Maximum Sustained Wind Speed (MSW Fig. 10b) of the cyclones. The cyclones in the present study have different tracks and various ranges of severity in terms of intensity over both basins.

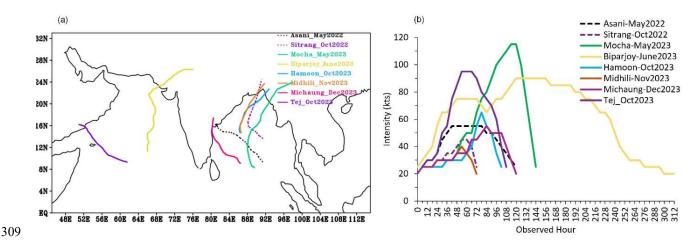


Figure 10. a) Observed tracks of the cyclones b) Observed Intensity in terms of Maximum Sustained Wind Speed (kts) during year 2022-2023.

## 3.5.1 Verification of GFS T1534 and HGFM Forecast for tropical cyclone cases during 2022 and 2023

For this verification, the lifetime of the cyclone is considered starting from the depression stage untill landfall, as per the observation. The total sample includes a minimum of four and a maximum ten initial conditions for typical cases, depending on the lifespan of the case. The errors calculated here are averaged for each forecast hour within the sample.

The Root Mean Square Error (RMSE) for track and intensity is shown in Fig. 11a and b, respectively. Initially, upto 4 days, GFS T1534 and HGFM perform equally well, but considerable improvement with HGFM is noted after 4 days in both track and intensity forecasts. Figure 11c-d depicts the average track error and average intensity errors for all the cyclones. The average track errors, as well as average intensity errors, are reduced drastically in HGFM with longer lead hours (4 days or more). Average track errors (average intensity errors) are ~300 km (~20 kts) with 7 days leads in HGFM. The average landfall errors (both position and time) are also evaluated with IMD observations and are shown in Fig. 12. With 4 days lead, average landfall position errors are ~200 km in HGFM and about 250 km for GFS T1534. Overall, the landfall position errors are less for HGFM. Remarkable improvements are seen in the average landfall time errors in HGFM throughout the life cycle of cyclones. Overall, the track and intensity forecast are improved with HGFM for longer lead hours (~4 days or more), which is an added advantage for the early warning and mitigation purposes. Here, one of the cyclone cases (cyclone Biparjoy) is discussed in detail.

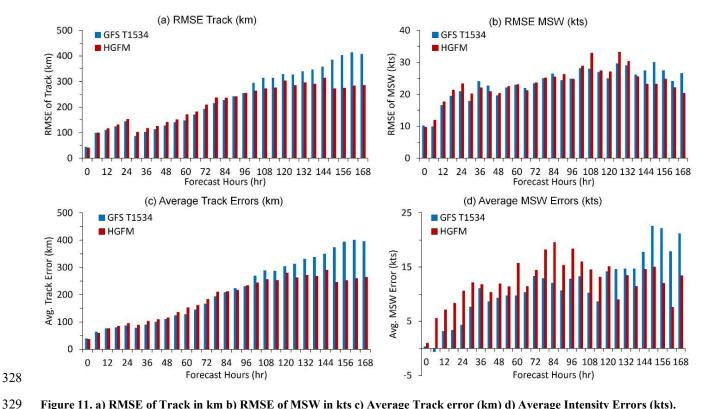


Figure 11. a) RMSE of Track in km b) RMSE of MSW in kts c) Average Track error (km) d) Average Intensity Errors (kts).

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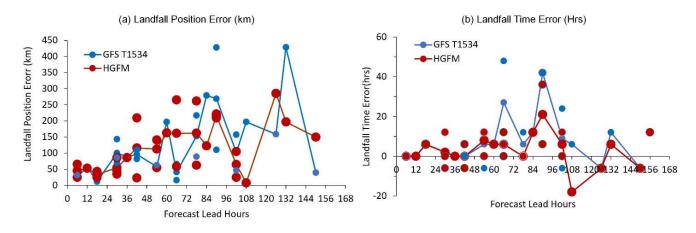


Figure 12. a) Average Landfall position errors in km b) Average Landfall time Errors in hours. The continuous lines represent the average errors for GFS T1534 (Blue) and HGFM (Red). The different sizes of the dots are for making the overlapped points visible.

# 3.5.2 A case study - Cyclone Biparjoy

During the monsoon onset of the 2023 season, tropical cyclone Biparjoy evolved in the Arabian Sea and hit the north-western state of Gujarat, India. The cyclone Biparjoy lasted for quite a long-time during 6-19 June 2023. As seen in figure 13a, it moved almost parallel to the Indian west coast and eventually recurved to make landfall over the northern part of Gujarat and adjoining Pakistan. It underwent rapid intensification during its genesis and growth stages on 6 and 7 June. This case was particularly challenging for prediction due to combination of recurving track, rapid intensification, slow movement, and a long lifespan. The HGFM and GFS T1534 track and intensity forecast of TC Biparjoy, based on 6 June (day of genesis) initial condition, are shown in Fig. 13 a and b, along with the best track data from IMD. It is evident that the HGFM predicts a track much closer to the observation compared to GFS T1534. Particularly, the recurvature is better captured by HGFM at about 6-7 days lead time. Both models overestimated the intensity untill 120 hrs of forecast, after which they indicated the dissipation phase.



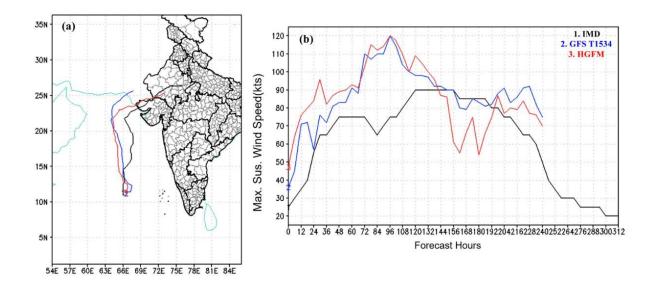


Figure 13. (a) track and (b) intensity variation forecast by GFS T1534, HGFM and as reported by IMD for the case of oTropical cyclone Biparjoy over Arabian Sea based on 6 June 2023 initial condition.

To assess the robustness of the performance, verification is carried out for this particular case considering forecasts from all the initial conditions (from 6 June 00UTC to 15 June 00UTC, initialized at 24-hours interval). A comparative analysis of landfall position and landfall time errors for HGFM and GFS T1534, with respect to the data reported by IMD, is presented in Table 2. It is evident that the landfall position error of the cyclone has been significantly improved by HGFM forecast,

though the landfall time error appears to be almost equivalent as compared to GFS T1534. Further, the average track and intensity errors (obtained from a total of 10 initial conditions) are depicted in Fig. 14a and 14b. It is evident that HGFM consistently produces accurate predictions of track and intensity with lesser errors at longer lead times, while the errors for shorter lead times are more or less the same.

Table 2. Landfall position (km) and landfall time (hr) errors for the forecasts started with different initial conditions. -ve (+ve) sign indicates early (late) landfall with respect to observed landfall time. The bold numbers indicates the significant improvement in the landfall position errors with HGFM.

Forecast Hours from Observed	Initial Condition	Landfall Position Error (km)		Landfall Time Error (Hr)		363
landfall (Hr)		GFS T1534	HGFM	GFS T1534	HGFM	364
228	2023060600	298	57	0	-30	365
204	2023060700	No Landfall				366 367
180	2023060800	616	201	0	0	368 369
156	2023060900	349	197	12	12	370 371
132	2023061000	428	197	12	6	372
108	2023061100	197	7	6	-18	373 374
84	2023061200	279	123	12	12	375
60	2023061300	197	163	6	6	376 377
36	2023061400	89	86	0	0	378
12	20220(1500	57	<b>5</b> 2	0	0	379
12	2023061500	57	53	0	0	380 381

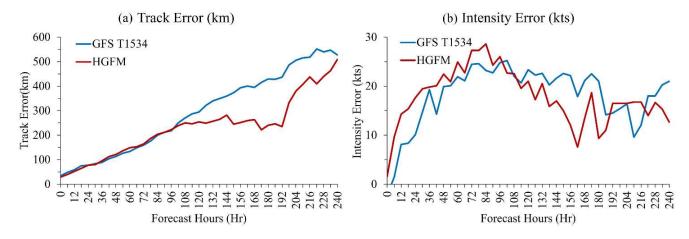


Figure 14. a) Average track error and b) average intensity error for the tropical cyclone Biparjoy over Arabian Sea.

# 4 Conclusions

For the first time, a version of the GFS model utilizing a new grid structure, the triangular cubic octahedral (Tco) grid, has been developed and is being run on an experimental basis for short to medium-range weather prediction over the Indian region, designated as IITM High resolution Global Forecast Model (HGFM). The Tco grid provides a higher resolution over the tropics, enabling the model to achieve a 6.5 km horizontal resolution near the tropics. This higher resolution represents a substantial leap from the existing Gaussian linear GFS T1534 which maintains a resolution of 12.5 km across the globe. The KE spectra of 200 hPa zonal wind have also revealed reasonable power by both the models with HGFM showing marginally better power in the Kolmogorov region, indicating the fidelity of the model structure.

It is worth mentioning that the present dynamical core, using the cubic octahedral grid, has been implemented in ECMWF weather forecast model since 2016 (Malardel et al., 2016). This has led to a significant increase in forecast accuracy and computational efficiency in the ECMWF model. In the present study, it is found that this dynamical core in the GFS T1534 has improved the orographic rainfall and reduces the Gibbs noise over the mountainous regions, in addition to improved precipitation skill over the Indian landmass region. The June-September monsoon rainfall and a case study of heavy rainfall have been analyzed in detail. The newly developed HGFM shows significantly better skill, particularly in the longer lead and for heavier rain categories. Rainfall biases over the entire globe appear broadly similar between HGFM and GFS T1534. A case of heavy rainfall in and around central India during the monsoon season has been analysed, where validation shows a significant gain in forecast lead time by HGFM compared to GFS T1534. The HGFM captures the rainfall signature at 5 days lead time, when there is hardly any indication in the GFS T1534 model forecast.

Several cases of tropical cyclones during 2022 and 2023 were analysed, indicating better performance of HGFM compared to GFS T1534 in predicting tracks and intensity. A detailed evaluation of tropical cyclone Biparjoy, based on IMD observation, reveals that the HGFM model provides better accuracy in cyclone position across almost all lead times (Table

2). Additionally, the average track error for HGFM is significantly lower than GFS T1534 at longer lead times. However, the average track and intensity errors for both the models are found to be equivalent. This paper highlights the initial results of the newly developed HGFM model and its skill as compared to the operational GFS T1534 model. Subsequently more analyses for many events will be carried out and the model will be made operational for weather forecasts over India. The current setup of the HGFM model uses the same physics as the GFS model. However, the HGFM model would require some parameter tuning to optimize and enchance the performance of the model and its fidelity. The future work will be focused on detailed validation of model simulations with optimal set of physical parameterizations.

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# Code and Data Availability

- 420 The model simulated data used for HGFM and GFS T1534 in the study are available at "TCO model data" by R Phani
- 421 Murali Krishna, Kumar Siddharth, Athipatta Gopinathan Prajeesh, Malay Ganai, B. Revanth Reddy, Kumar Roy and
- 422 Parthasarathi Mukhopadhyay, DOI: <a href="https://doi.org/10.5281/zenodo.12569807">https://doi.org/10.5281/zenodo.12569807</a>. The model code is available at "GFS TCO
- 423 Model code" by R Phani Murali Krishna, Kumar Siddharth, Athipatta Gopinathan Prajeesh, Parthasarathi Mukhopadhyay.
- 424 DOI: https://doi.org/10.5281/zenodo.12526400

### **Author Contributions**

- 427 RPMK, SK, AGP and PM conceptualised the problem and made necessary changes/modification development of code for
- 428 Too and wrote the major part of the Introduction, data, methodology and over all sequences. PB and NW helped during
- 429 formulation of the Tco grid in GFS and helped in improving the manuscript writing. KR, MG, ST, BRR and TG made all the
- 430 forecast analysis of monsoon parameters and wrote the respective portion on analyses. RK, MD and SS made the analysis
- 431 related to cyclone forecast by HGFM model and wrote the section on the cyclone forecast analysis and BRR made the
- 432 dCAPE analysis and extracted the post processed variables for the analysis.

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