NAQPMS-PDAF v2.0: A Novel Hybrid Nonlinear Data Assimilation System for Improved Simulation of PM_{2.5} Chemical Components

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13 Abstract. Identifying PM_{2.5}, a complex mixture with diverse chemical components, exerts significant impacts on the 14 environment, is crucial for formulating emission strategies, estimating radiative forcing, and assessing human health, and 15 elimate change. effects. However, precisely accurately describing spatiotemporal variations of PM_{2.5} chemical components 16 remains a difficultychallenge. In our earlier work, we developed an aerosol extinction coefficient data assimilation (DA) system 17 (NAQPMS-PDAF v1.0) that is suboptimal for chemical components. This paper introduces a novel hybrid nonlinear chemical 18 DA system (NAQPMS-PDAF v2.0) to accurately interpret key chemical components (SO4²⁻, NO3⁻, NH4⁺, OC, and EC). 19 NAQPMS-PDAF v2.0 improves upon v1.0 by effectively handling and balancing stability and nonlinearity in chemical 20 DA, which is achieved by incorporating the non-Gaussian-distribution ensemble perturbation and hybrid Localized Kalman-21 Nonlinear Ensemble Transform Filter with an adaptive forgetting factor for the first time. The dependence tests demonstrate 22 that NAQPMS-PDAF v2.0 provides excellent DA results with a minimal ensemble size of 10, surpassing previous reports and 23 v1.0. A one-month DA experiment shows that the analysis field generated by NAQPMS-PDAF v2.0 is in good agreement with 24 observations, especially in reducing the underestimation of NH_4^+ and NO_3^- and the overestimation of SO_4^{2-} , OC, and EC. In particular, the CORR values for NO3⁻, OC, and EC are above 0.96, and R² values are above 0.93. NAQPMS-PDAF v2.0 also 25 26 demonstrates superior spatiotemporal interpretation, with most DA sites showing improvements of over 50%-200% in CORR 27 and over 50%-90% in RMSE for the five chemical components. Compared to the poor performance in global reanalysis dataset 28 (CORR: 0.42-0.55, RMSE: 4.51-12.27 µg/m³) and NAQPMS-PDAF v1.0 (CORR: 0.35-0.98, RMSE: 2.46-15.50 µg/m³), 29 NAQPMS-PDAF v2.0 has the highest CORR of 0.86-0.99 and the lowest RMSE of 0.14-3.18 µg/m³. The uncertainties in 30 ensemble DA are also examined, further highlighting the potential of NAQPMS-PDAF v2.0 for advancing aerosol chemical 31 component studies.

32 1 Introduction

33 $PM_{2.5}$ is a complex mixture of various chemical fractions, mainly including sulfate (SO4²⁻), nitrate (NO3⁻), ammonium (NH4⁺), 34 organic carbon (OC), and elemental carbon (EC), which diversely). These chemical components exert diverse influences on 35 the atmospheric environment (Khanna et al., 2018), human health (Bell et al., 2007; Schlesinger, 2007; Li et al., 2022a; Alves 36 et al., 2023), and climate change (Schult et al., 1997; Park et al., 2014; Wilcox et al., 2016). However, current detection 37 technologies, such as fielddirect observation with in situby sampling and chemical analysis (Zhang et al., 2015; Ming et al., 38 2017), ground-based remote-sensing inversion (Nishizawa et al., 2008; Nishizawa et al., 2011; Nishizawa et al., 2017), and 39 observation-based machine learning (Lin et al., 2022; Su Lee et al., 2023); Li et al., 2025), are insufficient in interpreting 40 spatiotemporally continuous information of PM2.5 chemical components due to the spatiotemporal discontinuity and limited 41 ehemical species number of observation sites or platforms. Although atmospheric chemistry transport models (CTMs) (Wang 42 et al., 2014; Wang et al., 2015; Jia et al., 2017; Yang et al., 2019; Li et al., 2020; Lv et al., 2020) are commonly widely used to 43 characterize the spatiotemporal distribution of multiple chemical species, CTMs are associated with constrained by 44 uncertainties in initial-boundary conditions, physiochemical mechanisms, emission inventories, and meteorological fields (Sax 45 and Isakov, 2003; Mallet and Sportisse, 2006; Rodriguez et al., 2007; Chang et al., 2015; Miao et al., 2020; Xie et al., 2022), 46 resulting in biases relative to real situation notable discrepancies between the model simulations and accurate observations.

48 Data assimilation (DA) offers a solution to integrate the multi-source observations, CTMs, and their uncertainties effectively 49 to enhance the simulation and forecasting capabilities of CTMs. Variational methods (3D-Var/4D-Var) (Talagrand and Courtier, 50 1987), Ensemble Kalman Filter (EnKF) (Evensen, 1994; Evensen, 2003), EnKF-variants (EnKFs) (Bishop et al., 2001; Tippett 51 et al., 2003; Hunt et al., 2007; Nerger et al., 2012), and hybrid EnKF-Var methods (Hamill and Snyder, 2000; Schwartz et al., 52 2014) are most widely applied in DA. However, variational methods have a flow-independent Background Error Covariance 53 (BEC) with the assumption of isotropic, static, and uniform characteristics, and they need to develop the tangent linear adjoint 54 model, which is difficult to practice for complex models. Although EnKFs and hybrid EnKF-Var methods have a flow-55 dependent BEC, they are sensitive to inadequate ensemble sampling and have high computational costs. Importantly, these 56 methods cannot address model nonlinearity and non-Gaussian error distribution, yielding suboptimal results for DA in highly 57 nonlinear CTMs.

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Currently, nonlinear filters, such as Particle Filter (PF) (Gordon et al., 1993) and Nonlinear Ensemble Transform Filter (NETF)
 (Tödter and Ahrens, 2015), have been proposed to approximate the complete posterior probability distribution of model states
 and provide a better representation of non-Gaussian information based on Monte Carlo random sampling and Bayesian theory.

- However, PF is unstable and susceptible to filter degeneration compared to EnKFs. In a recent study, Nerger (2022) proposed the hybrid Kalman-Nonlinear Ensemble Transform Filter (KNETF) to achieve excellent DA performance in the Lorenz-63 and Lorenz-96 model with a smaller ensemble size, which combines the stability of EnKFs and the nonlinearity of NETF (Nerger, 2022). However, to the author's knowledge, this algorithm has not been applied to the chemical DA of CTMs.
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67 Studies on chemical DA involve the assimilation of aerosol optical properties, such as aerosol optical depth (AOD) and 68 extinction coefficient (EXT), and the particulate matters (PMs), such as the mass concentrations of PM_{2.5} and PM₁₀. The 69 commonly AOD observations for DA include OMI-AOD (Ali et al., 2013), MODIS-AOD (Zhang et al., 2008; Huneeus et al., 70 2012; Huneeus et al., 2013; Rubin and Collins, 2014; Lynch et al., 2016; Werner et al., 2019; Kumar et al., 2020), AERONET-71 AOD (Schutgens et al., 2010; Li et al., 2016), Sun-Sky Photometer-Multiband AOD (Chang et al., 2021), GOCI-AOD (Saide 72 et al., 2014; Luo et al., 2020; Kim et al., 2021), and Fengyun/Himawari8-AOD (Bao et al., 2019; Jin et al., 2019; Xia et al., 73 2019; Xia et al., 2020). These studies indicated that AOD observations can enhance the accuracy of aerosol simulation and 74 forecast. Compared to AOD, EXT DA effectively improves the interpretation of aerosol vertical distribution (Zhang et al., 75 2014; Cheng et al., 2019; Wang et al., 2022). Additionally, the simultaneous DA of aerosol optical properties and PMs is widely 76 applied in aerosol studies (Tang et al., 2015; Chai et al., 2017). According to our literature review (Yang et al., 2023), there is 77 currently no DA study on aerosol chemical components due to the limited DA influence of PMs and AOD on chemical 78 compositions (Chang et al., 2021) and the limited chemical observations with an extensive spatial range. Moreover, the aerosol 79 chemical components exhibit nonlinearity and a non-Gaussian distribution (Ha, 2022), while current main-stream algorithms, 80 such as variational methods or EnKFs, are suboptimal for chemical component DA.

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82 In our previous work, we developed an aerosol vertical DA system (NAQPMS-PDAF v1.0) based on EnKFs to improve the 83 simulation of the extinction coefficient vertical profile (Wang et al., 2022). In this study, we present a novel hybrid nonlinear 84 DA system (NAQPMS-PDAF v2.0) towards various PM2.5 chemical components through online integration of Parallel Data 85 Assimilation Framework (PDAF, version 2.1, released on February 21st, 2023), Observation Module Infrastructure (OMI) and 86 Nested Air Quality Prediction Model System (NAQPMS). We collected 1-month hourly surface observations of five PM2.5 87 chemical components (NH4⁺, SO4²⁻, NO3⁻, OC, and EC) over Northern China and surrounding areas. We utilized the hybrid 88 Localized Kalman-Nonlinear Ensemble Transform Filter (LKNETF) to generate a high-resolution and high-accuracy 89 reanalysis dataset of PM2.5 chemical components for the first time. Notably, the ensemble members in NAQPMS-PDAF v2.0 90 are generated by perturbing emission species based on their uncertainties and non-Gaussian distribution assumption. Section 91 2 briefly introduces NAQPMS and PDAF v2.1 with OMI, respectively, and details the development of NAQPMS-PDAF v2.0,

92 including system structure, configuration, ensemble generation, and LKNETF algorithm. The data used in this study and 93 experimental settings are also described in Section 2. Section 3 presents the DA results, including evaluatingan evaluation of 94 dependencies, performance, and external comparisons. Besides, Section 3 discusses, as well as a discussion of the ensemble 95 DA uncertainty. Section 4 summarizes the conclusions and outlook.

96 2 Method and data

97 **2.1 NAQPMS**

98 The Nested Air Quality Prediction Modeling System (NAQPMS), developed by the Institute of Atmospheric Physics 99 (IAP), Chinese Academy of Sciences (CAS), is used to provide background fields of key aerosol chemical components in this 00 study. for key aerosol chemical components in this study. NAQPMS is a multi-scale gridded 3-dimensional Eulerian chemical 01 transport model based on continuity equations. The nested grids in the horizontal direction enable data exchange between 02 different domains. Applying terrain-following coordinates in the vertical direction mitigates numerical calculation errors to 03 enhance model accuracy. The NAQPMS comprises an input section, a numerical computation section, and an output section. 04 The input section incorporates static terrain data, emission inventories, meteorological fields, and initial-boundary conditions. 05 The numerical computation section performs multiple physicochemical process calculations, including the advection process, 06 eddy diffusion, dry deposition, wet scavenging, gas-phase chemistry, aqueous chemistry, aerosol physicochemical processes 07 (including heterogeneous reactions at the aerosol surface), and other processes. The schemes and features of the 08 physicochemical processes are summarized in Table S1. The output section is responsible for model post-processing, data 09 diagnostics, and source identification.

10

NAQPMS is capable of characterizing the three-dimensional spatiotemporal distribution of various atmospheric compositions at global and regional scales through multiple physicochemical processes (shown in Table S1) and has been widely used in atmospheric pollution and chemistry research, such as O₃ pollution; (Wang et al., 2001), haze episodes (Wang et al., 2014; Du et al., 2021), regional transport (Wang et al., 2017; Wang et al., 2019), source identification (Li et al., 2022b), air quality simulation at global scale (Ye et al., 2021) and at urban-street scale (Wang et al., 2023), and acid deposition (Ge et al., 2014).

16 **2.2 PDAF v2.1 with OMI**

17 The Parallel Data Assimilation Framework (PDAF, <u>https://pdaf.awi.de/trac/wiki</u>) is an open-source and high-expandability 18 software developed by the Alfred Wegener Institute (AWI) in Germany to integrate observations, numerical models, and 19 assimilation systems for DA tasks, widely applied in meteorology, oceanography, land surface and atmospheric chemistry 20 (Kurtz et al., 2016; Nerger et al., 2020; Mingari et al., 2022; Strebel et al., 2022; Wang et al., 2022; Yu et al., 2022). The initial 21 version of PDAF (PDAF v1.0) was released in 2004. It has undergone continuous improvements and updates, with major 22 updates including the introduction of Ensemble Transform Kalman Filter (ETKF) and its localized variant (LETKF) in version 23 1.6, the implementation of PDAF-OMI (Observation Module Infrastructure) in version 1.16, the integration of 3D-Var methods 24 in version 2.0, and the incorporation of the hybrid KNETF and its localized variant (LKNETF) for the first time in version 2.1, 25 which was released in 2023 to handle the complex DA situations, such as the nonlinearity of system and non-Gaussian error 26 distribution of model state. Notably, the version of PDAF coupled in NAQPMS-PDAF v1.0 is PDAF v1.15 (released in 2019), 27 implying that NAQPMS-PDAF v1.0 has more limited applicability and functionality. In this work, the PDAF v2.1 is coupled 28 in NAQPMS-PDAF v2.0.

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30 PDAF has two modes, namely offline and online modemodes. For the offline mode, PDAF and the model perform separately 31 without coupling, which is easy obviating the need to writemodify the model code. For the online mode, PDAF is coupled with 32 the model, and model calculation and data assimilation performare performed continuously. Compared to the offline mode, 33 the online coupling has several advantages. Firstly, the initialization process of the PDAF and the model only needs to be 34 executed once instead of twice independently is integrated, necessitating a single execution rather than two separate executions. 35 Secondly, the model integration result can be directly passed to PDAF for data assimilation. Additionally, the assimilation 36 result of PDAF can be directly passed to the model for the next model integration. This The online mode eliminates the need 37 for intermediate steps and improves efficiency. Thirdly, the online mode is controlled by a main program, which allows for 38 efficient use of several processors in the high-performance computing cluster. Conversely, in the offline mode, the PDAF and 39 the model are managed by distinct programs, often with a reduced number offewer processors available for each program. 40 Therefore, the online-mode PDAF is used in this study.

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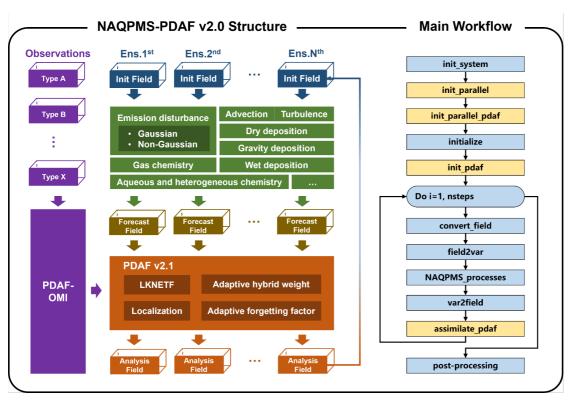
42 PDAF-OMI, an extension of PDAF, provides I/O interfaces for multi-type observations, simplifying user observation handling 43 by offering generic PDAF-OMI core routines and independent user-supplied routines for each observational type. The user-44 supplied routines, namely *init dim obs/init dim obs l, obs op*, and *localize covar*, are responsible for reading and writing 45 multi-type observations, applying corresponding observation operators, and performing covariance localization, respectively. 46 The modules for all observation types are integrated into the *callback obs pdafomi*, allowing free combinations between 47 different observation types without interference and facilitating the collaborative DA for various aerosol chemical components. 48 PDAF-OMI was not applied in NAQPMS-PDAF v1.0. Consequently, NAQPMS-PDAF v1.0 cannot switch between different 49 observational type combinations, and users need to define complete routines for each observation type for the DA process,

50 resulting in more tedious code writing and higher computational costs in NAQPMS-PDAF v1.0.

51 2.3 NAQPMS-PDAF v2.0

52 2.3.1 Structure of NAQPMS-PDAF v2.0

53 Figure 1 illustrates the structure (left portion) and main workflow (right portion) of NAQPMS-PDAF v2.0. The 54 observationalAs described in the left portion of Fig. 1, the observation part involves the integration of multi-type observations 55 (the purple cuboid patterns) and the utilization of PDAF-OMI. PDAF-OMI enables the simultaneous access and scheduling of 56 multi-type and multi-source data throughobservations by employing observational indices, which allows for thereby 57 facilitating flexible combination.combinations of observations. The ensemble initial fields (the deep blue cuboid patterns) are 58 crucial inputs for the numerical simulation of NAQPMS. The ensemble forecast/background fields (the deep yellow cuboid 59 patterns) are generated by perturbing emission species based on hypothesized distributions (see Sect. 2.3.3) and 60 NAQPMS performing physiochemical calculations in NAQPMS (the green part in Fig. 1).rectangular patterns). Then, chemical 61 DA is performed by a novel hybrid localized nonlinear DA algorithm (LKNETF, see Sect. 2.3.4) with an adaptive hybrid 62 weight and an adaptive forgetting factor to generate analysis/initial fields (the orange cuboid patterns) for the next realization.



63

64 Figure 1: The structure of NAQPMS-PDAF v2.0

65Figure 1: The structure of NAQPMS-PDAF v2.0 (Left: the purple cuboid patterns represent the multi-type observations, the deep66blue cuboid patterns represent the initial fields, the deep yellow cuboid patterns represent the forecast or background fields, and the

67 orange cuboid patterns represent the analysis fields. Ens.1st represents the first ensemble member, and Ens.Nth represents the Nth

68 ensemble member. Right: the main workflow in NAQPMS-PDAF v2.0, blue rectangular patterns represent the modules in NAQPMS,

69 and yellow rectangular patterns represent the modules in PDAF).

70 NAQPMS-PDAF v2.0 implements an online coupling between NAQPMS and PDAF v2.1 with OMI, utilizing a level-2 71 parallel computational framework. The description of level-2 parallel implementation was detailed in our previous work (Wang 72 et al., 2022). The online coupling ensures the continuous operation of model forecasts and assimilation analysis at each time 73 step, achieved by directly integrating PDAF routines into the prototype code of NAQPMS (In Fig. 1the right partportion of 74 Fig. 1, the blue represents NAQPMS main routines, while the yellow represents PDAF main routines). The level-2 parallel 75 computational framework, which utilizes the Message Passing Interface standard (MPI), facilitates concurrent processing and 76 data exchange among multiple ensemble members and parallel computation among model state matrixes within each ensemble 77 member, enhancing the efficiency of ensemble analysis and numerical model computations. The description of level 2 parallel 78 implementation was detailed in our previous work (Wang et al.For instance, the operation of twenty ensemble members 79 necessitates the execution of twenty model tasks, each of which performs integral calculations on a large model grid. Twenty 80 model tasks can be executed simultaneously at twenty computational nodes with sufficient computational resources. Each 81 model task can then perform parallel computation with multiple processors by splitting the large model grid into multiple sub-82 grids. As illustrated in the right portion of Fig. 1, the 2022). The workflow of NAQPMS-PDAF v2.0 is outlined as follows: 83 Step 1. *init system* module initializes NAQPMS, such as by defining all model state variables, allocating numerical matrixes,

84 configuring parameters, I/O of meteorological fields, and emission input.

85 Step 2. *init_parallel* module initializes MPI (MPI_COMM_WORLD) and model communicator (MPI_COMM_MODEL),

86 their number of processes, and the rank of a process, followed by *init_parallel_pdaf*, which initializes MPI communicators for

87 the model tasks, filter tasks and the coupling between model and filter tasks.

Step 3. *initialize* module initializes the target field (such as PM_{2.5} chemical components), such as their spatiotemporal
dimensions (longitude, latitude, and time steps) and variable dimensions.

Step 4. *init_pdaf* module initializes PDAF variables, such as the local state dimension, global state dimension, and settings for
analysis steps.

Step 5. Perform the time loop of forecast and analysis. The *convert_field* module is employed to match the matrix storage rule of the target field between NAQPMS and PDAF to ensure compatibility. The *field2var* module collects the analysis field/initial field and establishes a relationship between the initial field/analysis field and sub-variables in NAQPMS. Subsequently, the analysis field values are allocated to the corresponding NAQPMS sub-variables, and then the *NAQPMS_processes* module performs the forecast. After that, the *var2field* module, the inverse of the *field2var* module, assigns the NAQPMS sub-variables to the forecast field/background field. Finally, the *assimilate_pdaf* module assimilates the target field with observations to generate an analysis field for the next iteration. 99 Step 6. <u>The post-processing module</u> is responsible for finalizing NAPQMS-PDAF, data analysis, and DA evaluation.

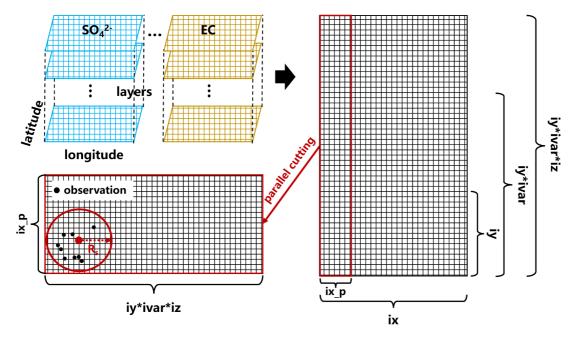
00 2.3.2 ConfiguresConfigurations

01 The meteorological field for NAOPMS is provided by the Weather Research and Forecasting model version 4.0 (WRFV4.0, 02 https://www.mmm.ucar.edu/models/wrf). The initial-boundary conditions for WRF are obtained from NCEP GDAS Final 03 Analysis (https://rda.ucar.edu/datasets/ds083.3/), with a horizontal resolution of $0.25^{\circ} \times 0.25^{\circ}$ and the temporal resolution of 6 04 hours, produced by the Global Data Assimilation System (GDAS). The land use data for WRF was updated by USGS's 05 MCD12Q1 v006 in 2019 (https://lpdaac.usgs.gov/products/mcd12q1v006/) with 20 categories. Three nested model domains 06 are conducted with the horizontal resolutions of 45 km in the East Asia region (domain1), 15 km in most areas of China except 07 for the western area (domain2), and 5 km in the Northern China region (domain3, target research region). WRF and NAOPMS 08 have 40 vertical layers with 27 layers within 2 km. The parameterization schemes for physical processes in WRF are shown 09 in Table S2. The boundary condition input for NAQPMS is provided by the global chemistry transport Model for OZone And 10 Related chemical Tracers version 2.4 (MOZART V2.4) (Horowitz et al., 2003). The anthropogenic emissions for NAQPMS 11 are from Tsinghua University's 2016 Multi-resolution Emissions Inventory for China (MEIC, http://www.meicmodel.org/) 12 with a spatial resolution of $0.25^{\circ} \times 0.25^{\circ}$, including residential sources, transportation sources, agricultural sources, industrial 13 sources, and power plant sources. The computational platform is the high-performance supercomputer subsystem cluster with 14 320 computation nodes, a total of 12,800 processors, and about 153 TB memory at the Big Data Cloud Service Infrastructure 15 Platform (BDCSIP), which meets the demand for high-performance parallel computing of NAOPMS-PDAF v2.0.

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17 The model state variables include NH4⁺, SO4²⁻, NO3⁻, OC, EC, Na⁺, Brown carbon, soil PM2.5, soil PM10, sea salt, fine dust, 18 coarse dust, SO₂, NO₂ and RH. As shown in Fig. 2, the model state has a 4-dimensional (4-D) structure, with longitudinal 19 dimension (ix, 300 grids), latitudinal dimension (iy, 249 grids), variable dimension (ivar, 15), and vertical dimension (iz, 40 20 layers) in that order. The 4-D model state with 15 variables is converted to a 2-D state matrix in PDAF, the number of grids in 21 the horizontal axis direction is ix, and the number of grids in the vertical axis direction is iv*ivar*iz. Notably, the 2-D state 22 matrix coordinate index-of the 2-D state matrix contains 3-D information for each variable to implement the horizontal and 23 vertical domain localization separately, because the horizontal and vertical resolutions are not uniform. This structure has two 24 advantages. First, the parallel cutting of the horizontal axis enables the local domain to retain the full dimensional information 25 (ix p*iy*ivar*iz, where ix p is the longitudinal dimension of the local domain). Secondly, the localization in the local domain 26 permits the analysis to execute only executes within a small domain (ix p*iy) when the length of the horizontal localization 27 radius (Rs) is smaller than iy, which effectively reduces reducing the influence of spurious correlations between different state 28 variables. In this study, we set the horizontal and vertical domain localization radius to 200 km (40 grids) and 1 layer. Besides,

- 29 we further implemented the observation localization to consider the influence of distance between analysis grid and
- 30 observational grid (see Sect. 2.3.4). To minimize computational complexity, the observation errors were assumed to be spatially
- 31 isotropic, with 0.40 µg/m³, 1.00 µg/m³, 0.50 µg/m³, 3.00 µg/m³, and 0.50 µg/m³ for NH₄⁺, SO₄²⁻, NO₃⁻, OC and EC, respectively.



32

33 Figure 2: The structure of state variables in NAQPMS-PDAF v2.0.

34 2.3.3 Generation of ensemble members

35 In ensemble DA, ensemble members interpret the uncertainty of the model or system, characterized by BEC, which 36 significantly impacts the DA performance (Dai et al., 2014). For CTMs, emission input directly influences the chemical 37 calculation and substantially contributes to the uncertainty. Perturbing emission input can effectively represent the uncertainty 38 in aerosol emissions and enhance the consistency of ensemble error spread, thereby improving aerosol DA (Huang et al., 2023). 39 CTMs are nonlinear, and model state errors are non-Gaussian distributions. To obtain non-Gaussian error distributions, we 40 followed the Kong et al. (2021)'s method to assume that the emission errors are spatially correlated by an isotropic correlation 41 model with thea decorrelation length of 150 km and generate perturbation coefficient matrixes with the same Gaussian 42 distribution as the emission species, which are subsequently transformed into non-Gaussian distribution matrixes through non-43 Gaussian process generation v1.2 (https://github.com/ECheynet/Gaussian to nonGaussian/).(Cheynet, 2024).

44

The target PM_{2.5} chemical components are NH₄⁺, SO₄²⁻, NO₃⁻, OC, and EC, and the. The perturbed emission species correspondinglythat can directly or indirectly affect the component concentration calculations include SO₂, NO_x, VOC_s, NH₃, CO, PM₁₀, PM_{2.5}, EC, and OC, with the corresponding uncertainties (δ) listed in Table 1. As shown in Eq. (1), the original emission input matrix (E_p) is multiplied by the corresponding perturbation coefficient matrix (θ_i) to generate the perturbed

emission input matrix (E_i) for each emission species. The calculation of the perturbation coefficient matrix (θ_i) is followed by Eq. (2)-(3). Firstly, N two-dimensional pseudorandom perturbation fields (P_i) are created using Evensen's method (Evensen, 1994). The uncertainties (δ) of the emission species are incorporated into the two-dimensional pseudorandom perturbation fields (P_i) to obtain the final perturbation coefficient matrixes (θ_i). Finally, the Gaussian-distribution perturbation coefficient matrixes (θ_i) were transformed into non-Gaussian distribution coefficient matrixes with a given target skewness (set to 1) and kurtosis (set to 6) by non-Gaussian process generation v1.2, which employs the Moment Based Hermite Transformation Model and a cubic transformation.

56 Table 1: The uncertainties of emission species in NAQPMS-PDAF v2.0

Species	SO_2	NO_x	VOC _s	NH ₃	CO	PM10	PM _{2.5}	EC	0
Uncertainty δ	2.00	0.31	0.68	0.53	0.70	1.32	1.30	2.08	2.5

57
$$E_i = E_p \times \theta_i, i = 1, 2, ..., N$$
, (1)

58
$$\ln \theta_{0i} = \left(\frac{(P_i - \frac{1}{N} \times \sum_{i=1}^{N} P_i)}{\sqrt{\frac{1}{N} \times \sum_{i=1}^{N} (P_i - \frac{1}{N} \times \sum_{i=1}^{N} P_i)^2}} - \frac{1}{2} \times \ln(1 + \delta^2)\right) \times \sqrt{\ln(1 + \delta^2)} ,$$
(2)

$$59 \qquad \theta_{i} = \frac{\left(\theta_{o_{i}} - \frac{1}{N} \times \sum_{i=1}^{N} \theta_{o_{i}}\right)}{\sqrt{\frac{1}{N} \times \sum_{i=1}^{N} \left(\theta_{o_{i}} - \frac{1}{N} \times \sum_{i=1}^{N} \theta_{o_{i}}\right)^{2}}} \times \left(\frac{1}{N} \times \sum_{i=1}^{N} \theta_{o_{i}}\right) \times \delta + \frac{1}{N} \times \sum_{i=1}^{N} \theta_{o_{i}} , \qquad (3)$$

Notably, all matrix operations involved are Schur <u>ProductProducts</u>. Where E_i denotes the ith ensemble perturbed emission input matrix, E_p <u>denotesindicates</u> the original unperturbed emission input matrix and θ_i represents the ith ensemble perturbation coefficient matrix. θ_{o_i} is the ith ensemble original perturbation coefficient matrix, which is obtained by mathematical transformation of the ith ensemble pseudorandom perturbation matrix P_i , including standardization, scaling by uncertainty (δ), and logarithm.

65 2.3.4 Hybrid nonlinear DA algorithm with adaptive forgetting factor

To thoroughly integrate the stability of EnKFs with the nonlinearity of nonlinear filters and be ideal for the nonlinear and non-Gaussian-distribution situations, the hybrid LKNETF is used in this study. This section reviews the algorithms of LETKF, LNETF, and their combination (LKNETF).

69

ETKF, a deterministic filter in EnKFs, efficiently obtains analysis samples using a transformation matrix and the square root of the forecast error covariance (Bishop et al., 2001). In contrast to stochastic filters in EnKFs, ETKF prevents underestimation of the analysis error covariance resulting from the random observation perturbations. And it is particularly applicable in situations with small ensemble sizes (Lawson and Hansen, 2004). The realization of ETKF can be divided into the forecast and analysis steps.

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In the forecast step, the forecast state vector (\mathbf{x}_t^f) at t is generated by numerical model (**M**) integration of the analysis state vector (\mathbf{x}_{t-1}^a) at t-1. The forecast error covariance matrix (\mathbf{P}_t^f) can be calculated by the perturbation of the forecast ensemble ($\mathbf{X}_t^{f'}$).

79
$$\mathbf{x}_{t}^{f} = \mathbf{M}(\mathbf{x}_{t-1}^{a}), \mathbf{X}_{t}^{f} = [\mathbf{x}_{1t}^{f}, \mathbf{x}_{2t}^{f}, ..., \mathbf{x}_{Kt}^{f}],$$
 (4)

80
$$\mathbf{P}_{t}^{f} = \mathbf{X}_{t}^{f' \mathbf{X}_{t}^{f'^{T}}}, \qquad (5)$$

81 Where \mathbf{X}_{t}^{f} is the forecast ensemble at t, and K is the number of ensemble members. $\mathbf{X}_{t}^{f'}$ is the perturbation of the forecast 82 ensemble at t, calculated by \mathbf{X}_{t}^{f} and the forecast ensemble mean $\overline{\mathbf{X}_{t}^{f}}$ at t.

83

In the analysis step, the forecast error covariance matrix (\mathbf{P}_t^f) at t is transformed to the analysis error covariance matrix (\mathbf{P}_t^a) at t by a transform matrix (**T**).

86
$$\mathbf{P}_{t}^{a} = \mathbf{X}_{t}^{f'} \mathbf{T} \mathbf{X}_{t}^{f'^{1}} , \qquad (6)$$

The transform matrix (**T**) is defined as follows and can be decomposed to a left singular vector matrix (**U**), a singular value matrix (**S**), and a right singular vector matrix (**V**) through the singular value decomposition.

89
$$\mathbf{T}^{-1} = \rho_{adaptive} (\mathbf{K} - 1) \mathbf{I} + (\mathbf{H} \mathbf{X}_{t}^{f'})^{\mathrm{T}} (\mathbf{L} \cdot \mathbf{R}^{-1}) \mathbf{H} \mathbf{X}_{t}^{f'} = \mathbf{U} \mathbf{S} \mathbf{V} , \qquad (7)$$

90
$$\rho_{adaptive} = \frac{\sigma_{ens}^2}{\sigma_{resid}^2 - \sigma_{obs}^2}$$
, (8)

91 Where $\rho_{adaptive}$ is an adaptive forgetting factor; used for the inflation of error covariance estimation (the initial $\rho_{adaptive}$ is 92 set to 0.9 in this study). σ_{ens}^2 is the mean ensemble variance, σ_{resid}^2 is mean of observation-minus-forecast residual, σ_{obs}^2 is 93 mean observation variance. I is the identity matrix. H is the observation operator. L is the localization matrix, a weight 94 matrix calculated by the 5th-order polynomial (Nerger, 2015), implemented in LETKF for observation localization analysis to 95 avoid observational spurious correlation and filter divergence effectively (Hunt et al., 2007). **R** is the observation error 96 covariance matrix.

97

The analysis state vector (\mathbf{x}_t^a) at t is calculated by the forecast state vector (\mathbf{x}_t^f) at t, the perturbation of the forecast ensemble $(\mathbf{X}_t^{f'})$ at t and a weight vector (\mathbf{w}) .

$$00 \mathbf{x}_{t}^{a} = \mathbf{x}_{t}^{f} + \mathbf{X}_{t}^{f'} \mathbf{w} {,} (9)$$

01 The weight vector (\mathbf{w}) is given by the following equation.

02
$$\mathbf{w} = \mathbf{T}(\mathbf{H}\mathbf{X}_{t}^{f'})^{\mathrm{T}}(\mathbf{L} \cdot \mathbf{R}^{-1})(\mathbf{y} - \mathbf{H}\mathbf{x}_{t}^{f}) , \qquad (10)$$

03 Where **y** is observations.

04

The analysis ensemble (\mathbf{X}_t^a) at t can be obtained by forecast ensemble mean $(\overline{\mathbf{X}_t^f})$ at t, the perturbation of the forecast ensemble $(\mathbf{X}_t^{f'})$ at t and a transform matrix (**C**) represented by the symmetric square root of **T**.

$$07 \qquad \mathbf{X}_{t}^{a} = \overline{\mathbf{X}_{t}^{f}} + \sqrt{\mathbf{K} - 1} \mathbf{X}_{t}^{f'} \mathbf{C} , \qquad (11)$$

08 The transform matrix (**C**) is calculated as follows.

$$\mathbf{09} \quad \mathbf{C} = \mathbf{U}\mathbf{S}^{-1/2}\mathbf{U}^{\mathrm{T}} , \qquad (12)$$

10 NETF is a 2nd-order exact ensemble square root filter effectively applied to the nonlinear and non-Gaussian DA (Tödter and 11 Ahrens, 2015). Like PF, NETF indirectly updates the model state by using observations to affect the weights of the prior 12 ensemble. However, PF and NETF differ in the sampling method. PF utilizes the Monte Carlo and Bayesian 13 methods approaches to calculate particle weights based on observations, which are then used to generate the analysis ensemble 14 by weighting the resampling forecast ensemble. In high-dimensional systems, as the DA progresses, the weight differences of 15 particles increase, with most particles having weights close to 0, leading to filter degeneration. In contrast, NETF generates 16 the analysis ensemble through a deterministic matrix square root transformation of the forecast ensemble, where the mean and 17 covariance matrix of the analysis ensemble match the weighted values in PF (as shown in Eq. (13)-(14)). Due to the similarity 18 between NETF and ETKF, the localization can be implemented in NETF (LNETF) (Tödter et al., 2016).

19
$$\bar{\mathbf{x}}^{a} = \frac{1}{\kappa} \sum_{i=1}^{\kappa} \mathbf{x}_{i}^{a} = \frac{1}{\kappa} \sum_{i=1}^{\kappa} \mathbf{w}_{i} \mathbf{x}_{i}^{f} , \qquad (13)$$

Where $\bar{\mathbf{x}}^{a}$ is the analysis state vector mean, K is the number of ensemble members, \mathbf{x}_{i}^{a} is the ith analysis state vector, w_{i} is the ith particle weight vector in PF, which is calculated by the Bayesian method $w_{i} = p(\mathbf{y}|\mathbf{x}_{i}^{f})/p(\mathbf{y})$, \mathbf{y} is the observations, \mathbf{x}_{i}^{f} is the ith forecast state vector.

23
$$\mathbf{P}^{a} = \frac{1}{K-1} \sum_{i=1}^{K} (\mathbf{x}_{i}^{a} - \bar{\mathbf{x}}^{a}) (\mathbf{x}_{i}^{a} - \bar{\mathbf{x}}^{a})^{T} = \sum_{i=K}^{K} w_{i} (\mathbf{x}_{i}^{f} - \bar{\mathbf{x}}^{f}) (\mathbf{x}_{i}^{f} - \bar{\mathbf{x}}^{f})^{T} , \qquad (14)$$

Where P^a is the error covariance matrix of the analysis ensemble, calculated by the perturbation of the analysis ensemble.
In NETF, A performs as a transform matrix like the transform matrix (T) in ETKF, which can be obtained from the weight matrix (w).

$$27 \mathbf{P}^{\mathbf{a}} = \mathbf{X}^{\mathbf{f}'} \mathbf{A} {\mathbf{X}^{\mathbf{f}'}}^{\mathrm{T}}$$
(15)

28
$$\mathbf{A}^{1/2} = (\mathbf{W} - \mathbf{w}\mathbf{w}^{\mathrm{T}})^{1/2} = \mathbf{V}\mathbf{D}^{1/2}\mathbf{V}^{\mathrm{T}}$$
, (16)

29 Where the matrix $\mathbf{W} \equiv \text{diag}(\mathbf{w})$ is defined as a diagonal matrix created from the weight matrix (\mathbf{w}). A can be decomposed

30 $(\mathbf{A} = \mathbf{V}\mathbf{D}\mathbf{V}^{\mathrm{T}})$ by a singular value decomposition as it is a real, symmetric, positive semidefinite matrix. **V** is the orthogonal 31 matrix, and **D** is a diagonal matrix.

32

Then, the perturbation of the analysis ensemble $(X^{a'})$ and the analysis ensemble (X^{a}) can be obtained by applying the square root of **A** as a transform matrix.

$$35 \qquad \mathbf{X}^{\mathbf{a}'} = \sqrt{\mathbf{K}} \mathbf{X}^{\mathbf{f}'} \mathbf{A}^{1/2} \quad , \tag{17}$$

36
$$\mathbf{X}^{a} = \overline{\mathbf{X}}^{f} + \mathbf{X}^{f'} (\overline{\mathbf{W}} + \sqrt{K} \mathbf{A}^{1/2}) , \qquad (18)$$

137 LKNETF combines the LETKF and LNETF through a hybrid weight γ to perform better in systems with different non-1 linearity degrees and implement in situations with smaller ensemble sizes (Nerger, 2022). When γ approaches 1, the analysis 1 increment (ΔX_{LETKF}) computed by LETKF becomes more significant and appropriate for linear systems with Gaussian 1 distributions. Conversely, when γ approaches 0, the analysis increment (ΔX_{LNETF}) computed by LNETF becomes more 1 significant and appropriate for non-linear systems with non-Gaussian distributions. The one-step update scheme is used in this 1 study.

43
$$\mathbf{X}_{\mathrm{HSync}}^{\mathrm{a}} = \mathbf{X}^{\mathrm{f}} + (1 - \gamma)\Delta\mathbf{X}_{\mathrm{LNETF}} + \gamma\Delta\mathbf{X}_{\mathrm{LETKF}} , \qquad (19)$$

44 2.4 Data

45 2.4.1 Observation

46 The one-month (February 2022) hourly mass concentration observations of five PM_{2.5} chemical components (NH₄⁺, SO₄²⁻, 47 NO3⁻, OC, and EC) from 33 ground-based sites in Northern China and surrounding areas were collected for this work (Fig. 3). 48 Out of the 33 sites, 24 (DA sites) were utilized for DA and internal validation, and the remaining 9 (VE sites) were used for 49 independent verification to assess the influence of DA sites on neighboring areas. These sites were divided using the K-means 50 clustering algorithm (Lloyd, 1982; Arthur and Vassilvitskii, 2007). The supplement provides a detailed description (Text S1). 51 PM2.5 hourly observations from the China National Environmental Monitoring Centre (CNEMC, http://www.cnemc.cn/) were 52 employed to assess the overall mass concentration of PM2.5 chemical components in NAQPMS-PDAF v2.0. Due to incomplete 53 spatial overlap between the PM_{2.5} sites and the chemical component sites, the PM_{2.5} sites were selected based on the closest 54 coordinate Euclidean distance between PM_{2.5} sites and chemical component sites.

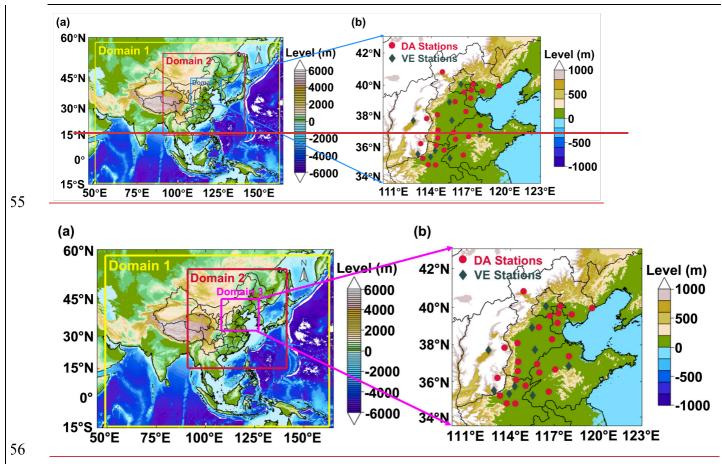


Figure 3: The model domains in WRF simulation (a) and the location of observations (b). <u>The domainDomain</u> 3 in (a) is the target area <u>inof</u> this study. Twenty-four red sites in (b) represent the sites for data assimilation, and nine green sites in (b) represent the sites for spatial independent validation. The topographic dataset is from the ETOPO1 1 arc-minute Global Relief Model, taken from the National Geophysical Data Center (Amante and Eakins, 2009).

61 2.4.2 Global reanalysis dataset

62 The global reanalysis datasets of PM2.5 chemical components in February 2022 were obtained from the Copernicus Atmosphere 63 Monitoring Service ReAnalysis (CAMSRA, 0.75°×0.75°) (Inness et al., 2019) and the Modern-Era Retrospective analysis for 64 Research and Applications, Version 2 (MERRA-2, 0.5°×0.625°) (Randles et al., 2017) to compare with reanalysis dataset 65 generated by NAQPMS-PDAF v2.0. For the data consistency-of data comparison, the global reanalysis surface grid data 66 located in the observation sites of PM2.5 chemical component were extracted through the k-nearest neighbor search method 67 (Friedman et al., 1977), which can efficiently match grid points and observation sites based on longitude and latitude data and 68 Euclidean distances. Our 3-hourly NAQPMS-PDAF v2.0 output of NO3⁻ and NH4⁺ were extracted to compare with the 69 CAMSRA dataset, and hourly NAQPMS-PDAF v2.0 output of SO4²⁻, OC, and EC were extracted to compare with MERRA-70 2 M2T1NXAER dataset.

71 **2.5 Experimental setting and evaluation method**

72 In our study, four tests were conducted to evaluate the performance of NAQPMS-PDAF v2.0 with hourly observations of five

PM_{2.5} chemical components, including (1) the dependence on ensemble size and assimilation frequency, (2) the interpretation ability on mass concentration and spatiotemporal characteristics, (3) the superiorityguality of output data compared to other reanalysis dataset<u>datasets</u>, and (4) the uncertainty in ensemble assimilation. In practice, the ratio of ensemble size to the number of processes with 1:50 in high-performance computers was the <u>bestoptimal</u> parallel scheme to balance computing efficiency and computing resources (Wang et al., 2022).

78

79	All the tests were run in NAQPMS-PDAF v2.0 after a spin-up experiment with 24 timesteps from 00:00 to 23:00 (LST) on
80	February 1st, 2022. (1) For the first test, we assimilated the hourly observations of five PM _{2.5} chemical components from all
81	sites with 48 timesteps from 00:00 (LST) on February 2 nd to 23:00 (LST) on February 3 rd , 2022. In the first situationscenario,
82	we controlled a fixed assimilation frequency of 1 hour and changed the ensemble size to 2, 5, 10, 15, 20, 30, 40, and 50. In the
83	second situationscenario, we controlled a fixed ensemble size of 20 and changed the assimilation frequency to 1 hour, 2 hours,
84	3 hours, 4 hours, 5 hours, 6 hours, 8 hours, and 12 hours. (2) For the second test, we set an ensemble size of 20 and an
85	assimilation frequency of 1 h and assimilated the hourly observations of five PM2.5 chemical components from DA sites with
86	648 timesteps from 00:00 (LST) on February 2nd to 23:00 (LST) on February 28th, 2022. We also conducted a free running
87	(FR) experiment without assimilation in the same period for comparison. (3) For the third test, we followed the settings in the
88	second test but assimilated the observation from all sites to generate a high-quality reanalysis dataset of five PM _{2.5} chemical
89	components. (4) The lastfinal test was like analogous to the first test but with a different situation to investigate distinct scenario
90	designed to examine the impactinfluence of ensemble perturbation on ensemble assimilation. From Table 2, we fixed species
91	uncertainty (M4 setting) with five distribution types in the first situationscenario and fixed distribution type (T2 setting) with
92	five SO ₂ uncertainties in the second.

93	Table 2: The experiment settings for emission perturbation					
	Experiment	Distribution (Fixed species uncertainty)				
	T1	Gaussian				
	T2	Non-Gaussian (m3=1, m4=6)				

Т3	Non-Gaussian (m3=-1, m4=6)
T4	Non-Gaussian (m3=1, m4=12)
T5	Non-Gaussian (m3=-1, m4=12)
	SO ₂ uncertainty (Fixed distribution)
M1	12%
M2	50%
M3	100%
M4	200%
M5	300%

94

95 We used the Continuous Ranked Probability Score (CRPS) to evaluate ensemble size dependency, which measures the

96 consistency between ensemble forecast distribution and corresponding observations (Jolliffe and Stephenson, 2012). The 97 calculation rules are referred to in Hersbach's study (Hersbach, 2000). Besides, four common statistical indicators, the Pearson 98 correlation coefficient (CORR), root mean square error (RMSE), mean absolute error (MAE), and coefficient of determination 99 (R^2), were used to assess the DA system performance in interpreting PM_{2.5} chemical components (SO4²⁻, NO3⁻, NH4⁺, OC, and 90 EC). The CORR measures the correlation between the system outputs and corresponding observations, the RMSE and MAE 91 indicates indicate the overall system accuracy, and the R² reflects the proportion of variability in the observations explained by 92 the assimilation system.

03 3 Results and discussion

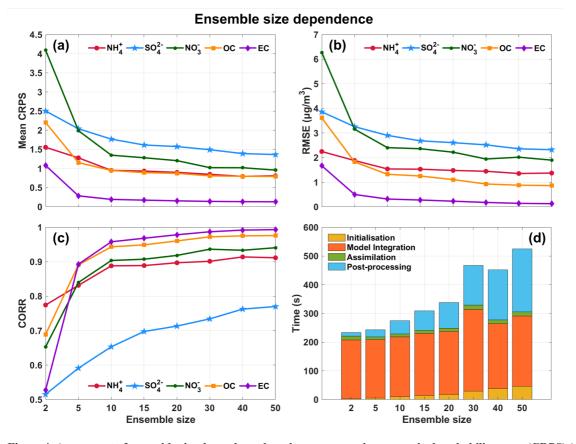
04 **3.1** The Dependence on Ensemble Size and Assimilation Frequency for Five Components

05 Ensemble size is a crucial parameter in ensemble assimilation, determining the model state's uncertainty range. A larger 06 ensemble size more accurately represents the error distribution of state variables but requires considerable computing resources 07 and time, especially for high-dimension systems. A smaller ensemble size can easily lead to underestimating the error 08 covariance matrix, especially for the fine-resolution model (Kong et al., 2021). Thus, identifying an appropriate ensemble size 09 to balance computational efficiency and accuracy is the primary step in ensemble DA. A prior study (NAQPMS-PDAF v1.0) 10 only evaluated the correlation between ensemble size and parallel efficiency and concluded that the ratio of ensemble size to 11 high-performance computing processors was 1:50 (Wang et al., 2022), while the impact of ensemble size on the accuracy and 12 computational efficiency was neglected. In this This study, we assessed the NAQPMS-PDAF v2.0 dependency on ensemble 13 size through three statistical indicators (CRPS, RMSE, and CORR). Figure 4 shows the mean CRPS, RMSE, and CORR values 14 and the statistical averages of the elapsed time over 48 timesteps with the ensemble sizes of 2, 5, 10, 15, 20, 30, 40, and 50.

15

16 From Fig. 4a, when the ensemble size is at its minimum level of 2, the mean CRPS values of the five PM_{2.5} chemical 17 components are more significant, with NO3⁻ exhibiting the most considerable difference between the simulation distribution 18 and observations (more than 4). With each increase in ensemble size, the mean CRPS values of the five chemical components 19 progressively reduce and eventually reach convergence when the ensemble size is 10, implying that a hybrid nonlinear filter 20 can maintain high accuracy and reliability in ensemble assimilation with an ensemble size that is smaller than the traditional 21 minimum of 20 ensemble members, as observed in prior ensemble assimilation studies (Constantinescu et al., 2007; Miyazaki 22 et al., 2012; Schwartz et al., 2014; Rubin et al., 2017; Kong et al., 2021; Tsikerdekis et al., 2021; Wang et al., 2022), including 23 NAQPMS-PDAF v1.0. The mean CRPS value of EC is the lowest among the five chemical components, indicating the highest 24 accuracy and reliability of EC ensemble DA. The performance of other components is similar. Like CRPS values, the values

of RMSE and CORR decrease and increase, respectively, as the ensemble size increases, and convergence begins to occur when the ensemble size is 10 (Fig. 4b and c). Compared with other chemical components, the CORR value of SO_4^{2-} is significantly lower, less than 0.8, possibly due to its estimated background field error covariance driven by the inadequate ensemble perturbations. Therefore, in the Discussion section, we deeply discuss the uncertainties of ensemble perturbations.



29

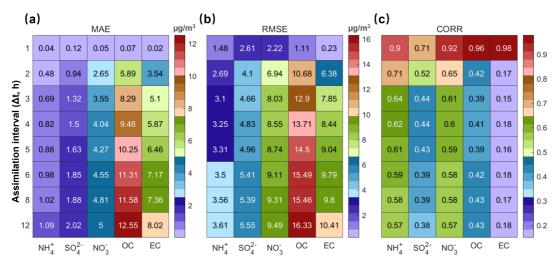
Figure 4: Assessment of ensemble size dependency based on mean continuous ranked probability score (CRPS) (a), root mean square
 error (RMSE) (b), correlation coefficient (CORR) (c), and time (d).

32 Figure 4d shows the time required for the four processes of ensemble assimilation under different ensemble sizes, including 33 initialization, model integration, assimilation, and post-processing. The model integration process in NAQPMS-PDAF v2.0 34 takes the longest, followed by post-processing, initialization, and assimilation. The required time for initialization and post-35 processing increases with increasing ensemble size, while for model integration and assimilation, except for ensemble size 30, 36 the required time is the same under different ensemble sizes. Generally, the time needed for ensemble sizes of 30-50 is 37 considerably higher than that for smaller ones. Although convergence occurs with an ensemble size of 10, our work illustrates 38 a similar time required between ensemble sizes 10 and 20. Consequently, we selected an ensemble size of 20 to ensure optimal 39 performance of NAQPMS-PDAF v2.0, considering both assimilation efficiency and accuracy.

40

The assimilation frequency is the interval at which observational data is introduced into the DA system, directly affecting the practical assimilation data volume and computation cost. High-frequency DA with high-quality observations is crucial for

43 improving numerical simulations and forecasts (Liu et al., 2021). Figure 5 demonstrates that the MAE values of the five 44 chemical components analysis fields range from 0.02 to 0.12 µg/m³, RMSE values range from 0.23 to 2.61 µg/m³, and CORR 45 values range from 0.71 to 0.98 at a 1-hour assimilation time interval, which is significantly better than the statistical indicators 46 at lower assimilation frequencies. Even at a 2-hour assimilation frequency, the assimilation effect drops sharply compared to 47 the 1-hour interval, especially for NO₃⁻, OC, and EC. The values of MAE and RMSE increase by 2.6-5.82 µg/m³ and 4.72-48 9.57 µg/m³, respectively, and the CORR values decrease by 0.27-0.81. Gradual increasing trends in MAE and RMSE values 49 and a slight decreasing trend in CORR values are observed as assimilation frequency decreases from the 2-hour interval. 50 Therefore, the fast-updating assimilation with a 1-hour interval significantly improves the NAQPMS simulation. For the 51 forecasting field (Fig. S2), the low sensitivity of state variables to assimilation frequency suggests that NAQPMS-PDAF v2.0 52 can appropriately reduce assimilation frequency during the actual forecasting phase, lowering the demand for high temporal 53 resolution observations and computational resources.



54

Figure 5: Assessment of assimilation interval dependency based on mean absolute error (MAE) (a), root mean square error (RMSE)
(b), and correlation coefficient (CORR) (c) at the analysis step.

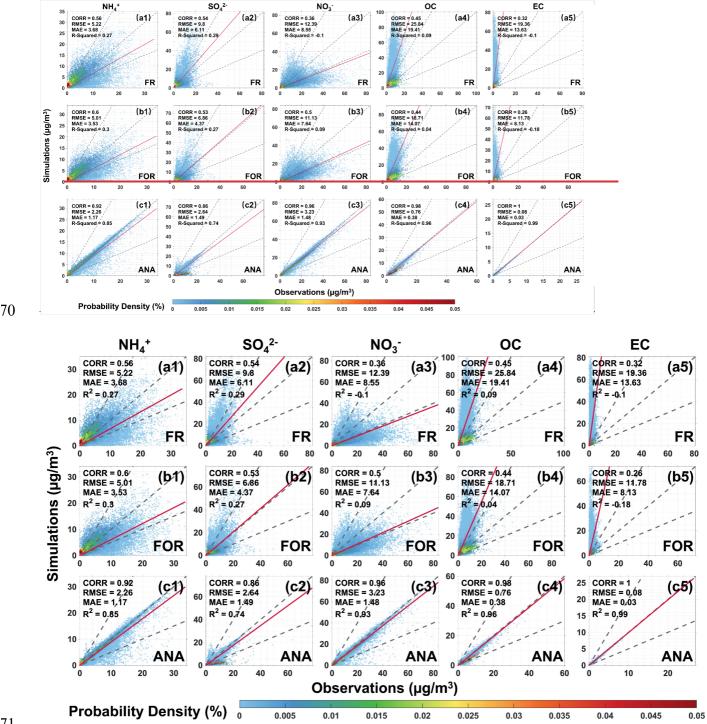
57 **3.2 Evaluation of NAQPMS-PDAF v2.0 performance**

58 **3.2.1 Overall validation of DA results**

We conducted a control experiment (free-running field, FR) without any DA and a DA experiment. This section verified the forecast filed<u>field</u> (FOR) and analysis field (ANA) at 24 DA sites and 9 VE sites, respectively. Figure 6 shows the scatter distribution of observations and simulations at DA sites. For FR (Fig. 6a1-a5), five chemical components have CORR values ranging from 0.32 to 0.56, and R² values do not exceed 0.3, indicating poor consistency between observations and simulations. In detail, the simulated mass concentrations of SO₄²⁻, OC, and EC are significantly overestimated, while the simulated concentrations of NH₄⁺ and NO₃⁻ are underestimated. OC has the most significant error, with an RMSE value of 25.84 μ g/m³

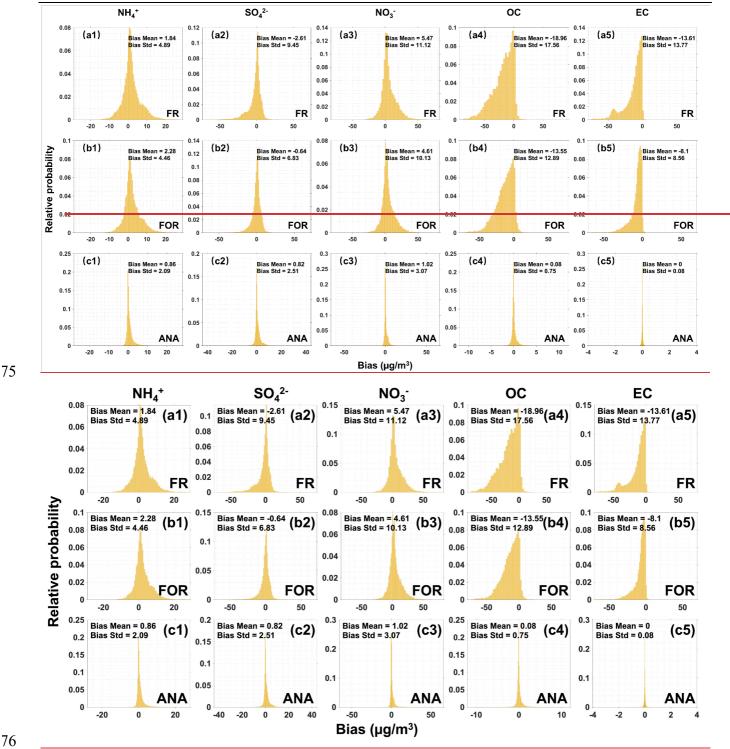
and an MAE value of 19.41 μ g/m³. Besides, the error distributions of SO₄²⁻, NO₃⁻ and NH₄⁺ are close to a symmetric distribution

with a mean value of 0, while the error distributions of OC and EC are skewed to the left from the mean value of 0 (Fig. 7a1a5), showing the relatively better simulations in SO_4^{2-} , NO_3^{-} and NH_4^+ than in OC and EC. Overall, NAQPMS cannot interpret the mass concentrations of the five chemical components with significant errors, mainly due to the uncertainties in chemical mechanisms (Miao et al., 2020).



71 _ 72 F

Figure 6: Scatterplots of the DA-site simulations versus the DA-site observations with probability density for the free-running field (FR, a1-a5), forecast field (FOR, b1-b5), and analysis field (ANA, c1-c5). The dotted gray lines represent the 2:1, 1:1, and 1:2 lines, and the solid red line represents the fitting regression line.



76

77 Figure 7: Probability distributions of bias between DA-site observations and DA-site simulations for the free-running field (FR, a1-78 a5), forecast field (FOR, b1-b5), and analysis field (ANA, c1-c5).

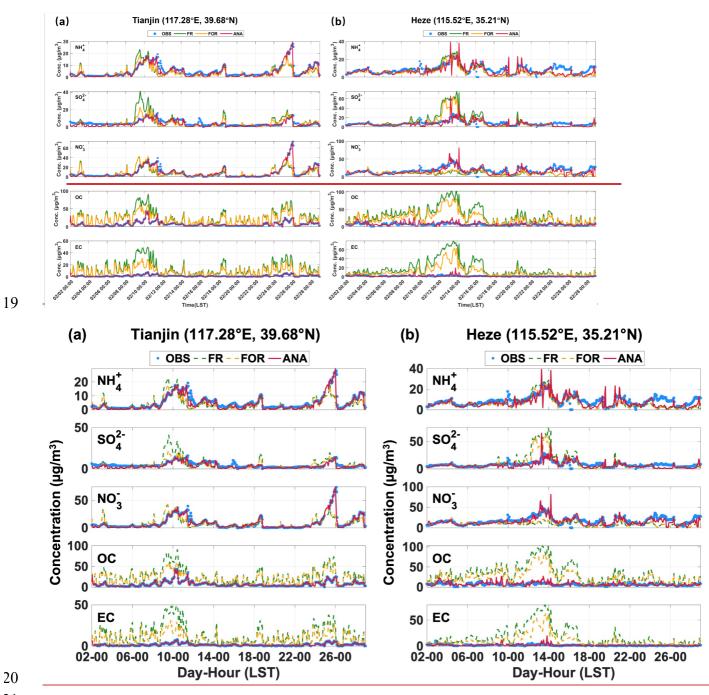
79 After DA, FOR shows a slight improvement with a slight increase in CORR and R^2 and a decrease in RMSE and MAE, 80 especially for NH4⁺ and NO3⁻ (Fig. 6b1-b5). Although SO4²⁻, OC, and EC are significantly overestimated with a slight decrease 81 in CORR and R², the RMSE and MAE values decrease. Besides, the error distributions of the five chemical components are 82 concentrated at 0, and the overestimation of OC and EC has been improved compared to FR (Fig. 7b1-b5). These results 83 indicate that DA reduces the overall FOR errors in NAQPMS due to improved forecasting ability by obtaining optimal initial

84 fields. However, further improvements are necessary to address the NAQPMS uncertainties in emission sources, 85 meteorological input, and imperfect physiochemical mechanisms. For ANA (Fig. 6c1-c5), DA significantly improves the 86 simulations of the five chemical components, making the ANA consistent with the observations. The CORR values are not 87 less than 0.86, the RMSE and MAE values do not exceed 3.23 µg/m³ and 1.49 µg/m³, respectively, and the R² values are not 88 less than 0.74. Specifically, the CORR values for NO_3^- , OC, and EC are not less than 0.96, and the R^2 values are not less than 89 0.93. The error distributions of the five chemical components concentrate to 0 with the mean bias ranging from $0\pm0.08 \,\mu\text{g/m}^3$ 90 to 1.02±3.07 µg/m³ (Fig. 7c1-c5). The results of VE sites show similar characteristics to the DA sites (Fig. S3 and S4). 91 Compared to FR, the overall errors of the FOR and ANA for the five chemical components decrease with a significant 92 improvement in ANA, showing that the CORR values of NH4⁺ and NO3⁻ increase by 0.15 and 0.45, respectively, the R² values 93 of NH₄⁺ and NO₃⁻ increase by 0.22 and 0.81, respectively, the RMSE values of OC and EC decrease by 21.77 μ g/m³ and 17.79 94 µg/m³, respectively. Overall, the FOR and ANA errors decreased significantly. The ANA of the five chemical components at 95 DA sites is almost entirely consistent with the observations, indicating excellent DA performance.

96 **3.2.2** Assessment of temporal variation in chemical components

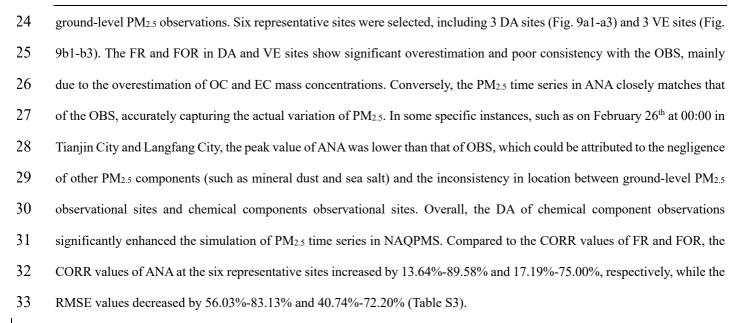
97 The ensemble DA employs a cyclic updating process wherein the forecast and analysis steps are continuously completed at 98 each iteration (Evensen, 2003; Houtekamer and Zhang, 2016). In the forecast step, the ANA at the current time step serves as 99 the optimal initial field to advance the model integration and obtain the FOR at the next step. In the analysis step, the FOR at 00 the next time step provides background field information for the subsequent DA analysis to generate the ANA at the next time 01 step. The FOR and ANA interact with each other in the temporal dimension. Therefore, in this section, we assess the ability of 02 NAQPMS-PDAF v2.0 to interpret the temporal variations of the five chemical components. Figure 8 illustrates the time series 03 of the five chemical components at two representative sites, including a DA site in Tianjin City and a VE site in Heze City. For 04 the DA site (Fig. 8a), the temporal variations of NH4⁺ and NO3⁻ in FR and FOR exhibit better agreement with the observed 05 temporal variations (OBS) than those of SO₄²⁻, OC, and EC. However, NH₄⁺ and NO₃⁻ mass concentrations are significantly 06 lower than the high-value mass concentrations observed on February 25^{th} . The mass concentration of SO₄²⁻ in FR is greatly 07 overestimated during the periods of Feb. 8th-11th, Feb. 18th-19th, and Feb. 24th-25th. The mass concentrations of OC and EC in 08 FR are overestimated throughout February with substantial temporal fluctuations. Although the time series of SO4²⁻, OC, and 09 EC in FOR show some improvement, noticeable differences from the OBS are still apparent. After DA, the ANA time series 10 for the five chemical components align well with the OBS, indicating good consistency and accurate representation of temporal 11 characteristics, such as the NH₄NO₃ pollution captured on February 25th. Notably, the mass concentrations of SO₄²⁻, NO₃⁻, and 12 NH4⁺ peaked on Feb. 8th-11th and February 25th, indicating intensified atmospheric secondary chemical reactions primarily due 13 to neutralization reactions of acidic pollutants capturing NH₃. The temporal variations of NH_4^+ and NO_3^- are more similar

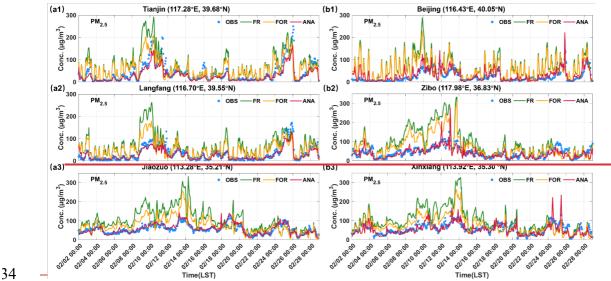
because atmospheric NO₃⁻ primarilymainly exists as NH4NO₃ rather than other metal nitrates, and NH4NO₃ can form before the complete neutralization of H₂SO₄ (Ge et al., 2017). The improvements at the VE site (Fig. 8b) are like those at the DA site, with the ANA time series of the five chemical components showing closer agreement with the OBS, which suggests that the localization analysis in DA effectively facilitates the propagation of observations within a specific spatial range and mitigates the assimilation anomalies caused by spurious correlations from the distant sites (Hunt et al., 2007).



21 Figure 8: Hourly variation of five PM_{2.5} chemical components in a representative DA site (a) and a representative VE site (b).

NH₄⁺, SO₄²⁻, NO₃⁻, OC, and EC are critical chemical components of $PM_{2.5}$, and the sum of their mass concentrations can be approximated as the $PM_{2.5}$ mass concentration. We further assessed the simulation enhancement of $PM_{2.5}$ time series based on





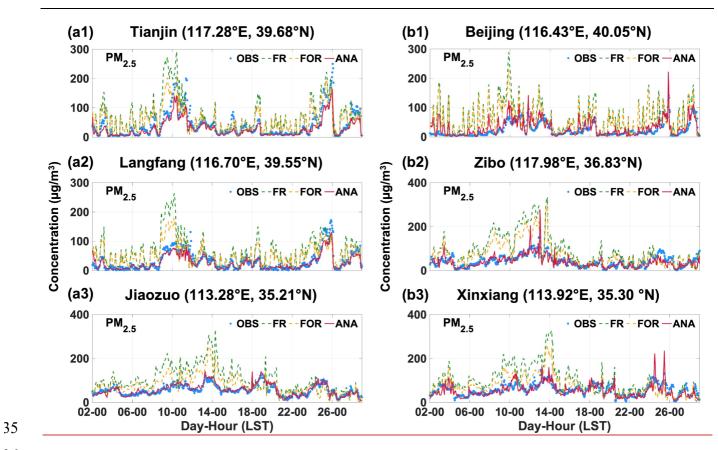


Figure 9: Hourly variation of PM_{2.5} in three representative DA sites (a1-a3) and three representative VE sites (b1-b3).

37 **3.2.3** Assessment of spatial distribution in chemical components

38 DA can improve the interpretation of model states in the analysis domain by using a limited number of observations. The 39 ability to represent spatial distribution accurately is a crucial performance for aerosol DA. Figure 10 displays the spatial 40 distribution of the monthly average mass concentrations for the five chemical components, including OBS, FR, FOR, ANA, 41 and analysis increment (INC). The spatial distributions of bias and statistical indicators for FR, FOR, and ANA are shown in 42 Fig. 11 and Fig. 12, respectively.

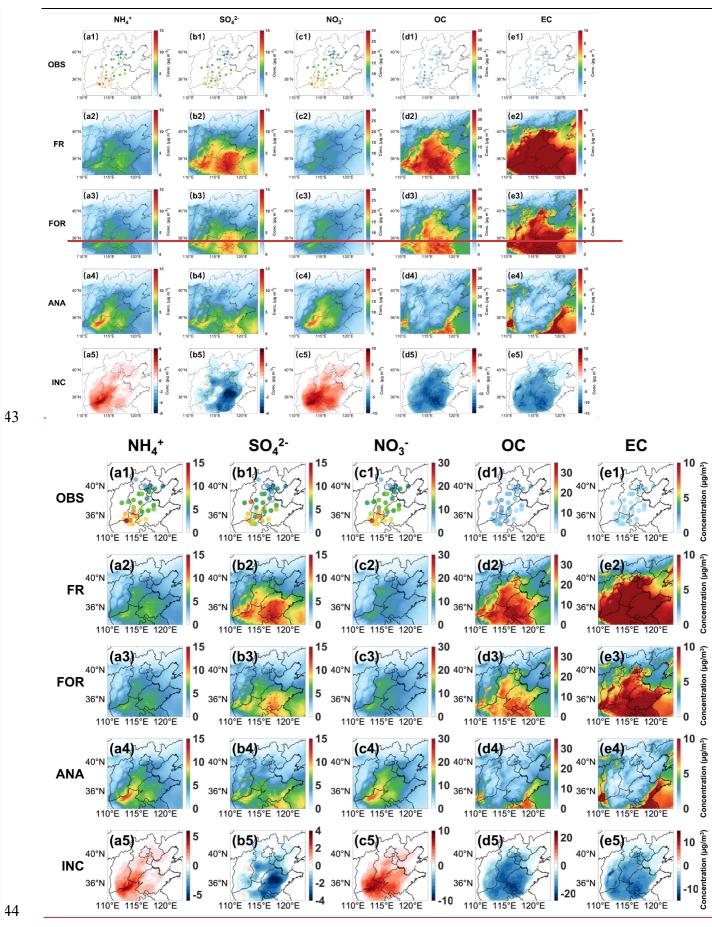
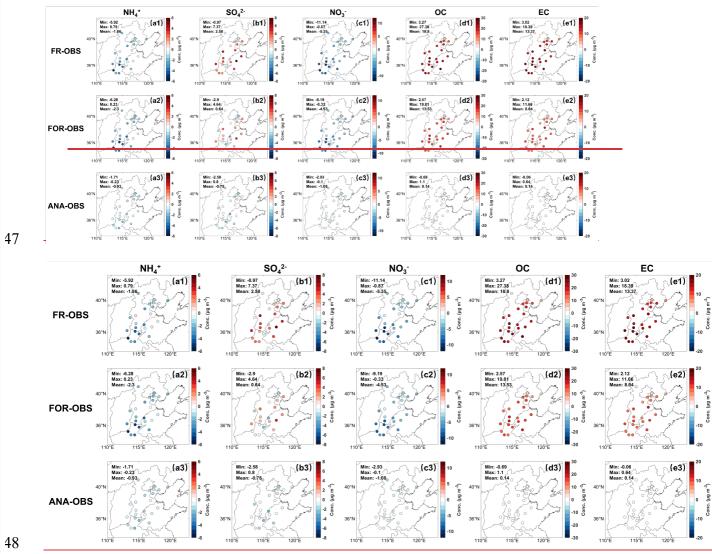
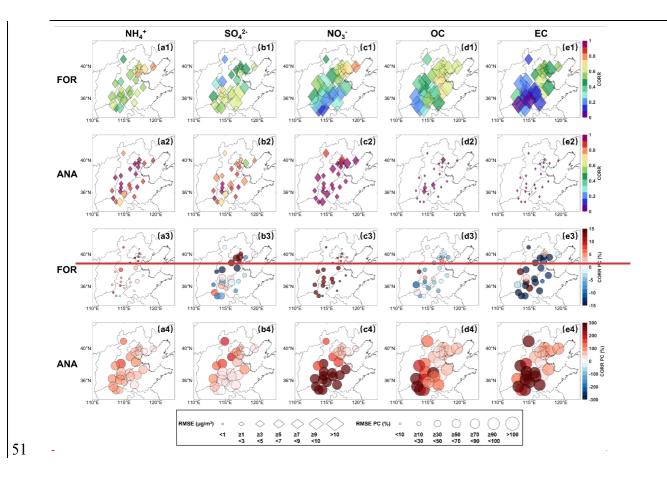


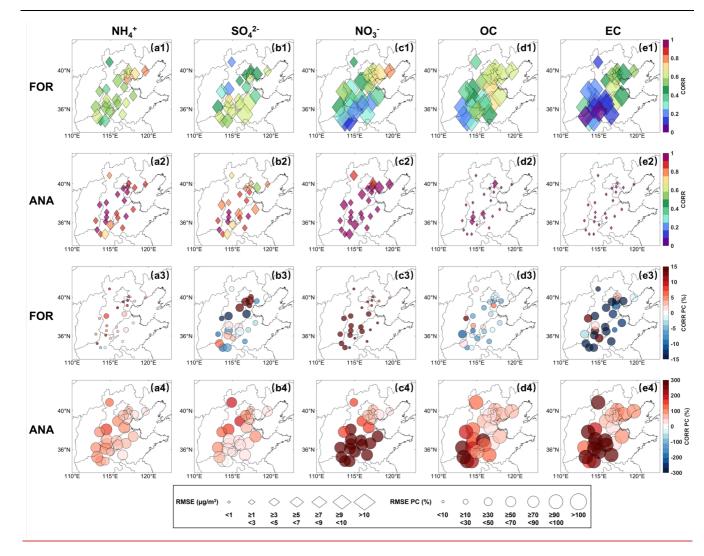
Figure 10: Spatial concentration distribution of site observation (OBS, a1-e1), free-run field (FR, a2-e2), forecast field (FOR, a3-e3),
 analysis field (ANA, a4-e4), and increment (INC) between ANA and FR (a5-e5) for five PM_{2.5} chemical components.



49 Figure 11: Spatial distribution of DA-site bias for five PM_{2.5} chemical components from observation (OBS) for the free-running field

50 (FR, a1-e1), forecast field (FOR, a2-e2) and analysis field (ANA, a3-e3).





52

Figure 12: Spatial distribution of DA-site statistical <u>indictorsindicators</u> for five PM_{2.5} chemical components. (a1-e1) represents the values of RMSE and CORR for the forecast field (FOR), (a2-e2) same as (a1-e1) but for analysis field (ANA), (a3-e3) represents the improvement of RMSE and CORR for the forecast field (FOR), (a4-e4) same as (a3-e3) but for analysis field (ANA). The size represents the value of RMSE in (a1-e2) and the improvement percentage compared to non-assimilation in (a3-e4), respectively.

57 The spatial characteristics of NH_4^+ and NO_3^- are similar. Compared to the OBS (Fig. 10a1 and c1), the FR (Fig. 10a2 and c2) 58 and FOR (Fig. 10a3 and c3) have failed to capture the high-value mass concentrations in the border area between Hebei 59 province, Shanxi province, Henan province, and Shandong province, especially in the northern region of Henan province. The 60 primary reason is the uncertainties in emission inventories in winter heating periods, which results in insufficient emission 61 statistics of gaseous precursors NOx and NH₃ (Aleksankina et al., 2018). After DA, this situation is significantly improved 62 with the ANA (Fig. 10a4 and c4). The INCs in the Beijing-Tianjin-Hebei region, Shanxi province, Henan province, and 63 Shandong province are positive (Fig. 10a5 and c5), indicating varying degrees of improvement in correcting the 64 underestimation of mass concentrations. Specifically, for NH4⁺ and NO3⁻ at DA sites, the biases between the OBS and ANA 65 are significantly reduced compared to the biases between the OBS and FR (Fig. 11), with the mean absolute bias decreasing 66 by 0.93 μ g/m³ and 4.27 μ g/m³, respectively. Moreover, the overall biases at VE sites also decrease (Fig. S5). As for the spatial

67 statistical indicators of NH4⁺ (Fig. 12a1 and a2), the CORR values in FOR and ANA range from 0.39 to 0.79 and 0.70 to 0.97, 68 respectively, and the RMSE values range from 3.16 μ g/m³ to 7.65 μ g/m³ and 1.20 μ g/m³ to 3.49 μ g/m³, respectively. As for 69 the spatial statistical indicators of NO₃⁻ (Fig. 12c1 and c2), the CORR values in FOR and ANA range from 0.09 to 0.76 and 70 0.89 to 0.99, respectively, and the RMSE values range from 4.88 μ g/m³ to 15.69 μ g/m³ and 1.34 μ g/m³ to 5.39 μ g/m³, 71 respectively. For the FOR, the improvement in accuracy for NO₃⁻ is more significant than that for NH₄⁺, with the CORR values 72 of most DA sites increasing by more than 10% and the RMSE of most DA sites decreasing by not less than 10% (Fig. 12a3 73 and c3). For the ANA, NH_4^{++} and NO_3^{-} exhibit significant improvements in CORR and RMSE, as most DA sites show over 74 150% in CORR and over 50% in RMSE (Fig. 12a4 and c4). The improvements Improvements can also be found for INH4⁺ 75 and NO₃⁻ at VE sites (Fig. S6). The spatial consistency of NH₄⁺ and NO₃⁻ indicates that NH₄NO₃ is the primary aerosol chemical 76 component, highlighting the necessity of coordinated control of precursor NOx and NH₃.

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78 Unlike NH4⁺ and NO3⁻, compared to the OBS (Fig. 10b1), the mass concentrations of SO4²⁻ in the FR and FOR (Fig. 10b2 and 79 b3) are significantly overestimated, especially in Shandong province. In contrast, the ANA has dramatically improved (Fig. 80 10b4), with most areas showing negative INCs (Fig. 10b5). The mean absolute biases in DA and VE sites have decreased by 81 1.80 µg/m³ and 2.68 µg/m³, respectively (Fig. 11 and Fig. S5). Specifically, after DA, the CORR values of the FOR and ANA 82 range from 0.22 to 0.71 and 0.58-0.97, and the RMSE values range from 3.42 μ g/m³ to 11.07 μ g/m³ and 1.20 μ g/m³ to 4.30 83 µg/m³, respectively (Fig. 12b1 and b2). The CORR and RMSE values in FOR have significantly improved (Fig. 12b3) at DA 84 sites around Beijing. While the CORR values in ANA have increased by more than 13%, with most DA sites showing an 85 increase of over 50%, and RMSE values have decreased by no less than 30%, with most DA sites showing a decrease of over 86 70% (Fig. 12b4). Besides, half of the VE sites show significant improvement in the CORR and RMSE in the FOR and ANA, 87 mainly due to their proximity to more DA sites (Fig. S6). The OBS and ANA indicate a considerable control in SO₄²⁻ pollution 88 during the winter heating period due to the emission reduction of gaseous precursors (Zhai et al., 2019; Yan et al., 2021).

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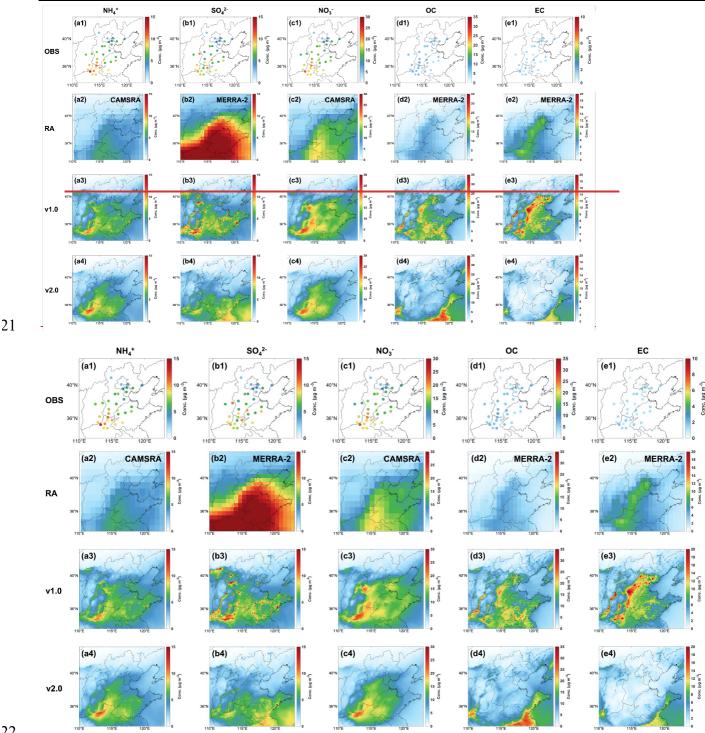
The spatial distributions of OC and EC exhibit similarities (Fig. 10d1 and e1), consistent with the finding of a strong correlation between OC and EC in winter (Cao et al., 2007). Since the low temperature and weakened photochemical reactions in winter reduced secondary OC (SOC) generation, and primary OC (POC) and EC mainly originate from direct anthropogenic emissions, such as combustion (Guo, 2016). Compared to the OBS, the mass concentrations in FR (Fig. 10d2-d3) and FOR (Fig. 10e2-e3) are significantly overestimated over a wide range. Similar overestimations have also been reported in the global reanalysis datasets of CAMS and MERRA-2, likely attributed to the hygroscopic growth scheme of carbonaceous aerosols in the models, poorly constrained semi-volatile species escaping from primary organic aerosols (Soni et al., 2021), and aging

97 mechanisms in the models (Huang et al., 2013). After DA, the spatial distribution of the ANA aligns entirely with that of the 98 OBS (Fig. 10d4 and e4), with the improvements in all overestimations (Fig. 10d5 and e5) and the average biases of OC and 99 EC at DA sites both significantly decreasing to 0.14 μ g/m³ (Fig. 11d3 and e3). The VE sites show similar results to the DA 00 sites, with the average biases of less than 2 µg/m³ (Fig. S5d3 and e3). Specifically, for OC (Fig. 12d1 and d2), the CORR 01 values in FOR and ANA are 0.18-0.71 and 0.92-1.00, respectively, with RMSE values of 7.91 µg/m³-26.27 µg/m³ and 0.16 02 µg/m³-1.45 µg/m³, respectively. For EC (Fig. 12e1 and e2), the CORR values in FOR and ANA are 0.01-0.66 and 0.97-1.00, 03 respectively, with RMSE values of 5.33 µg/m³-16.91 µg/m³ and 0.01 µg/m³-0.26 µg/m³, respectively. Although significant 04 improvements are not observed in FOR at some specific DA sites, the RMSE values at all DA sites decrease by 10%-50% (Fig. 05 12d3 and e3). The CORR values of OC and EC in ANA increase by more than 30%, with most DA sites exceeding 200%, and 06 the RMSE values decrease by more than 90% (Fig. 12d4 and e4). At VE sites (Fig. S6), significant improvements in the CORR 07 are not observed, but the RMSE values in the FOR and ANA decrease, which indicates that DA has limited benefits for whole 08 areas but can effectively reduce biases of whole areasentire regions.

09 3.3 Compared to NAQPMS-PDAF v1.0 and global reanalysis dataset

10 To comprehensively evaluate the competitiveness and superiority of NAQPMS-PDAF v2.0 in generating the reanalysis 11 datasets of the PM2.5 chemical compositions, we assimilated the mass concentrations of the five PM2.5 chemical components 12 from all sites (sum of DA sites and VE sites) in February 2022 to generate a reanalysis dataset. We compared our reanalysis 13 dataset with the global reanalysis (RA) datasets (CAMSRA and MERRA-2) and NAOPMS-PDAF v1.0 output. Figure 13 14 illustrates the spatial distribution of the monthly average mass concentrations for the five chemical components. Compared to 15 the OBS (Fig. 13a1 and c1), CAMSRA underestimates the NH_4^+ and NO_3^- concentrations and fails to capture the high-value 16 concentration in northern Henan Province (Fig. 13a2 and c2). Meanwhile, MERRA-2 overestimates the concentrations of 17 SO₄²⁻, OC, and EC (Fig. 13b2, d2, and e2), particularly SO₄²⁻, exhibiting a large region with inaccurately high concentrations. 18 Besides, CAMSRA (approximately 80*80 km²) and MERRA-2 (55*70 km²) have significantly lower spatial resolutions 19 compared to NAQPMS-PDAF v2.0 (5*5 km²). Therefore, NAQPMS-PDAF v2.0 provides a more detailed description of the

20 pollution characteristics of chemical components in Northern China and surrounding areas compared to RA.



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23 Figure 13: Spatial distribution of the monthly averaged concentration of five PM2.5 chemical components for observations (OBS, a1-24 e1), global reanalysis data (RA, a2-e2), NAQPMS-PDAF v1.0 analysis data (a3-e3) and NAQPMS-PDAF v2.0 analysis data (a4-e4).

25 Although NAQPMS-PDAF v1.0 demonstrates a superior spatial representation of the five chemical components when 26 compared to RA, it fails to capture the high-value concentrations of NH4⁺ in the northwest of Henan Province and correct the 27 high-value concentrations of NH4+ in the central and western areas of Hebei Province (Fig. 13a3). Moreover, the scattered 28 high-value concentrations of SO4²⁻ in the North China Plain do not align with the spatial characteristics of the OBS (Fig. 13b3). 29 Notably, NAQPMS-PDAF v1.0 exhibits poor performance in interpreting OC and EC with significant overestimations in a

wide range (Fig. 13d3 and e3), which indicates that NAQPMS-PDAF v1.0 is weaker than NAQPMS-PDAF v2.0 in terms of DA performance on chemical components, primarily due to insufficient propagation of observations. In NAQPMS-PDAF v2.0, the LKNETF algorithm with an adaptive forgetting factor is more suitable for the nonlinear and non-Gaussian situations compared to EnKFs in NAQPMS-PDAF v1.0, and the ensemble perturbation with non-Gaussian distribution can better represent the reasonable error distribution of model states.

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36 Table 3 presents a quantitative comparison of three reanalysis datasets. Compared to the CORR of NAQPMS-PDAF v2.0 37 (0.86-0.99), the CORR of RA for the five chemical components is significantly lower (0.42-0.55). Moreover, NAQPMS-PDAF 38 v1.0 exhibits significantly poorer consistency in SO₄²⁻, OC, and EC, with CORR values ranging from 0.35 to 0.57. NAQPMS-39 PDAF v2.0 has lower overall RMSE values (0.14 µg/m³-3.18 µg/m³) compared to RA and NAQPMS-PDAF v1.0, with RMSE 40 values ranging from 4.51 μ g/m³ to 12.27 μ g/m³ and 2.46 μ g/m³ to 15.50 μ g/m³, respectively. The characteristics of the R² are 41 likesimilar to those of the CORR and RMSE. For NH4⁺ and NO₃⁻, NAQPMS-PDAF v2.0 (0.85 and 0.93) and v1.0 (0.80 and 42 0.96) are much higher than RA (0.09 and 0.13). Notably, for SO4²⁻, OC, and EC, NAQPMS-PDAF v2.0 (0.74-0.98) is 43 significantly higher than v1.0 (-0.16-0.25) and RA (-0.15-0.25). Overall, NAQPMS-PDAF v2.0 more accurately and 44 consistently interprets the five chemical components, particularly for NH4⁺, SO4²⁻, OC, and EC. The reasons are summarized 45 as follows. (1) The DA frequency of CAMSRA is 12 hours, which is lower than the hourly DA frequency in NAQPMS-PDAF v2.0. (2) CAMSRA only assimilates satellite retrievals (Inness et al., 2019), and MERRA-2 only assimilates aerosol optical 46 47 depth (AOD) from both ground-based and space-based remote sensing platforms (Randles et al., 2017). The aerosol optical 48 information analysis increment cannot be allocated to each chemical component accurately and reasonably due to the lack of 49 a deterministic relationship between aerosol optical information and PM_{2.5} chemical components. (3) NAOPMS-PDAF v1.0 50 has evident DA shortcomings for chemical components due to the limited DA algorithm under the assumption of a linear model 51 or system, inappropriate ensemble perturbation under the assumption of Gaussian distribution, and inadequate observational 52 modules. (4) The state variable structure in NAQPMS-PDAF v1.0 lacks the capacity tocannot effectively mitigate the impact 53 of spurious correlations between chemical component variables, even when using analytical localization.

Table 3: Statistical indicators (CORR, RMSE, R²) of five PM_{2.5} chemical components for global reanalysis data (RA), NAQPMS PDAF v1.0 analysis data and NAQPMS-PDAF v2.0 analysis data.

Components	CORR			RMSE (µg/m ³)			R ²		
	RA	v1.0	v2.0	RA	v1.0	v2.0	RA	v1.0	v2.0
$\mathrm{NH_4}^+$	0.49	0.90	0.92	5.59	2.53	2.22	0.09	0.80	0.85
SO4 ²⁻	0.55	0.57	0.86	12.27	5.45	2.61	0.25	0.25	0.74
NO ₃ -	0.54	0.98	0.96	10.27	2.46	3.18	0.13	0.96	0.93
OC	0.50	0.42	0.97	4.51	12.92	0.93	0.15	-0.09	0.93
EC	0.42	0.35	0.99	7.59	15.50	0.14	-0.15	-0.16	0.98

56 3.4 The uncertainty in NAQPMS-PDAF v2.0

57 In ensemble DA, the ensemble members represent possible values of the model states, and the ensemble sampling can 58 determine the uncertainties of the model states. Therefore, the ensemble generation directly affects the propagation of 59 observations and subsequently impacts the final DA performance. Previous studies generated ensemble members based on the 60 uncertainties of emission species and the Gaussian-distribution assumption to satisfy the requirements of EnKFs algorithms 61 (Kong et al., 2021; Wang et al., 2022). However, the true error probability distribution of emission species is not an ideal 62 Gaussian distribution, and the assumption will introduce errors. In this study, we coupled the hybrid nonlinear DA algorithm 63 (LKNETF) with NAQPMS to handle the nonlinear and non-Gaussian situations, which combines the stability of LETKF with 64 the nonlinearity of LNETF. Therefore, we evaluate the performance of ensemble members with different uncertainties and 65 error probability distributions in NAQPMS-PDAF v2.0 through two groups of sensitivity experiments.

66

67 The first group of experiments (T1-T5) involves controlling the SO₂ uncertainty as a fixed value of 200% and transforming 68 the distribution of the perturbation coefficient matrix. The second group of experiments (M1-M5) focuses on assessing the 69 influence of SO₂ uncertainty on NH₄⁺ and SO₄²⁻ DA based on a fixed non-Gaussian distribution (m3=1, m4=6). Figure 14 70 shows the statistical indicators of the five chemical components under different error probability distributions, including a 71 Gaussian distribution (T1) and four non-Gaussian distributions (T2-T5). The mean CRPS and RMSE in T2 and T4 are lower 72 than those in T1, T3, and T5, and the CORR values in T2 and T4 are higher than those in T1, T3, and T5, indicating that the 73 DA performance of non-Gaussian-distribution assumption is superior to that of Gaussian-distribution assumption. Moreover, 74 positively skewed non-Gaussian distribution performs better than negatively skewed distribution. Except for SO₄²⁻, the 75 performance in T2 outweighs that in T4 for other chemical components, implying that higher kurtosis harms the chemical 76 components DA.

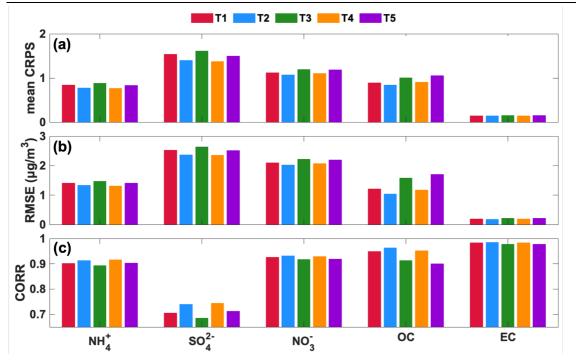


Figure 14: Statistical indicators (mean CRPS (a), RMSE (b), and CORR (c)) of five PM_{2.5} chemical components for five perturb
 experiments based on distribution.

80 SO_2 is a crucial precursor of NH₄⁺ and SO_4^{2-} , and perturbing SO_2 affects the forecast and simulation of NH₄⁺ and SO_4^{2-} . Table 81 4 presents statistical indicators of NH_4^+ and SO_4^{2-} analysis fields based on ensemble perturbations with different SO_2 82 uncertainties (12%-300%). Increasing the uncertainty of SO₂ from 12% to 200% leads to a decrease in the mean CRPS in the 83 SO₄²⁻ analysis field from 2.67 to 1.40, an increase in the CORR from 0.51 to 0.74, and a reduction in the RMSE from 4.10 84 $\mu g/m^3$ to 2.37 $\mu g/m^3$. Similarly, the mean CRPS in the NH₄⁺ analysis field decreases from 0.98 to 0.77, the CORR increases 85 from 0.88 to 0.91, and the RMSE decreases from 1.55 μ g/m³ to 1.33 μ g/m³. It indicates that increasing the uncertainty of SO₂ 86 improves the DA performance on NH_4^+ and SO_4^{2-} because the higher SO_2 uncertainty makes SO_2 perturbed sufficiently, and 87 the estimated error probability distribution is closer to the real distribution, resulting in a sufficient spread of observations. 88 However, when the uncertainty of SO₂ reaches 300%, the statistical indicators do not significantly improve and even worsen 89 because excessively high SO₂ uncertainty causes the estimated error probability distribution to deviate from the true 90 distribution. Thus, selecting appropriate uncertainties for emission species is crucial in aerosol chemical component DA.

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To summarize, the non-Gaussian-_distribution assumption outperforms the Gaussian-_distribution assumption in NAQPMS-PDAF v2.0. Positive skewness performs better than negative skewness, and excessively high kurtosis should be avoided. Additionally, appropriately increasing the uncertainty of SO₂ enhances the DA performance of NH_4^+ and SO_4^{2-} . Future studies should conduct more sensitivity experiments on emission species perturbation to determine the suitable schemes for different aerosol chemical components. 97 98

Table 4: Statistical indicators (mean CRPS (a), RMSE (b), and CORR (c)) of five $PM_{2.5}$ chemical components for five perturb experiments based on SO₂ emission uncertainty.

1		-					
Evenovinant		SO4 ²⁻		$\mathrm{NH_{4}^{+}}$			
Experiment	CRPS	CORR	RMSE	CRPS	CORR	RMSE	
M1	2.67	0.51	4.10	0.98	0.88	1.55	
M2	2.07	0.59	3.24	0.92	0.89	1.48	
M3	1.61	0.69	2.63	0.83	0.91	1.39	
M4	1.40	0.74	2.37	0.77	0.91	1.33	
M5	1.41	0.74	2.39	0.78	0.91	1.33	

99 4 Conclusions

In this paper, we online coupled NAQPMS with PDAF-OMI to develop a novel hybrid nonlinear DA system (NAQPMS-PDAF v2.0) with level-2 parallelization based on a hybrid Kalman-Nonlinear Ensemble Transform Filter (LKNETF) for the first time. Compared to NAQPMS-PDAF v1.0, NAQPMS-PDAF v2.0 with OMI can be applied with multiple component types and nonlinear/non-Gaussian situations in chemical analysis to effectively interpret five PM_{2.5} chemical components (NH₄⁺, SO₄²⁻, NO₃⁻, OC and EC), which is not achieved in previous studies. The background error covariance was calculated by ensemble perturbation based on adaptive uncertainties and non-Gaussian-distribution assumption of emission species. The DA experiments were conducted based on 33 observational sites in Northern China and surrounding areas.

07

08 NAQPMS-PDAF v2.0 with LKNETF can maintain high accuracy and reliability in ensemble DA with an ensemble size of 10, 09 smaller than the traditional minimum of 20 ensemble members, as observed in prior ensemble assimilation studies. The FR 10 (free-run fields without DA) have a poor consistency with the observations, with the CORR values ranging from 0.32-0.56 11 and the R^2 values less than 0.3, showing that SO₄²⁻, OC and EC are significantly overestimated, while NH₄⁺ and NO₃⁻ are 12 underestimated. A significant improvement was observed in the ANA (analysis fields) of at the DA sites. The CORR values are 13 not less than 0.86, the RMSE and MAE values do not exceed 3.23 μ g/m³ and 1.49 μ g/m³, respectively, and R² is not less than 14 0.74. Specifically, the CORR values for NO₃, OC, and EC are not less than 0.96, and R^2 is not less than 0.93. The error 15 distributions of the five chemical components concentrate to 0 with the mean bias ranging from $0\pm0.08 \text{ µg/m}^3$ to 1.02 ± 3.07 16 µg/m³. These improvements are also found in the ANA at VE sites, indicating an excellent DA performance of NAQPMS-17 PDAF v2.0.

18

19 The ability of NAQPMS-PDAF v2.0 to interpret the spatiotemporal characteristics of the five chemical components was 20 examined. For temporal variations, compared to the FR and FOR (forecast fields), the ANA closely aligned with the OBS 21 (observations) and accurately captured the peak concentrations of SO_4^{2-} , NO_3^{-} , and NH_4^+ on specific periods (such as February 22 25th), indicating good consistency and accurate characterization. Specifically, the CORR of the ANA at the six representative 23 sites increased by 13.64%-89.58% and 17.19%-75.00%, respectively, while the RMSE decreased by 56.03%-83.13% and 24 40.74%-72.20%. For spatial distributions, after DA, both NH4⁺ and NO3⁻ with positive analysis increments exhibit significant 25 improvements in CORR and RMSE, as most DA sites show improvements of over 150% in CORR and over 50% in RMSE. 26 SO4²⁻, OC, and EC with negative analysis increments were also improved. Especially for OC and EC, the improvements of 27 CORR and RMSE at most DA sites were over 200% and over 90%, respectively. The improvements at VE sites were also 28 identified. Consequently, DA successfully aligned the spatiotemporal characteristics of the ANA with OBS and significantly 29 reduced the biases of five chemical components.

30

Compared to the global reanalysis datasets (CORR: 0.42-0.55, RMSE: 4.51-12.27 µg/m³) and NAQPMS-PDAF v1.0 (CORR: 0.35-0.98, RMSE: 2.46-15.50 µg/m³), the NAQPMS-PDAF v2.0 (CORR: 0.86-0.99, RMSE: 0.14-3.18 µg/m³) has significant superiority in generating the reanalysis datasets of the PM_{2.5} chemical compositions with high spatiotemporal resolution. Besides, NAQPMS-PDAF v1.0 cannot capture the high-value concentrations and exhibits poor performance when interpreting SO4²⁻, OC, and EC with CORR values ranging from 0.35 to 0.57. In contrast, NAQPMS-PDAF v2.0 interprets the five chemical components more accurately and consistently.

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Finally, the uncertainties of NAQPMS-PDAF v2.0 are examined by identifying the influence of ensemble generation on ensemble DA performance. The non-Gaussian-distribution assumption outperforms the Gaussian-distribution assumption in NAQPMS-PDAF v2.0. Positive skewness performs better than negative skewness, and excessively high kurtosis should be avoided. Additionally, appropriately increasing the uncertainty of SO₂ enhances the DA performance of NH₄⁺ and SO₄²⁻. Future studies should conduct more sensitivity experiments on emission species perturbation to determine the suitable schemes for different aerosol chemical components.

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The novel hybrid nonlinear DA system (NAQPMS-PDAF v2.0) can be effectively applied in the interpretation of chemical components and outperform in generating the reanalysis dataset of the five PM_{2.5} chemical components with high accuracy and high consistency, thus providing the sufficient channel to investigate the spatiotemporal characteristics, identify the regional transport and prevent and control aerosol composition pollution. In future work, we plan to research the vertical DA of chemical components, introduce more vertical information from more observational platforms, and verify the simultaneous DA performance of surface and vertical mass concentrations.

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52 Code and data availability

53 The source codes in our work are available online via Zenodo (https://doi.org/10.5281/zenodo.10886914).

54 Author contributions

HL developed the data assimilation system, performed numerical experiments, carried out the analysis, and wrote the original manuscript. TY provided scientific guidance, designed the paper streutrestructure, and wrote this paper. LN developed PDAF and provided help for the model code. DWZ, DZ, and GT provided PM_{2.5} chemical component data. HW provided help forwith the model code. YS, PF, HS, and ZW did overall supervision. All authors reviewed and revised this paper.

59 Competing interests

50 The contact author has declared that neither they nor their co-authors have any competing interests.

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