

1 Regionalization in global hydrological models and its impact on 2 runoff simulations: A case study using WaterGAP3 3 (v 1.0.0)

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9 **Abstract:**

10 Valid simulation results from global hydrological models (GHMs), such as WaterGAP3, are essential to detecting
11 hotspots or studying patterns in climate change impacts. However, the lack of worldwide monitoring data makes
12 it challenging to adapt GHMs' parameters to enable such valid simulations globally. Therefore, regionalization is
13 necessary to estimate parameters in ungauged basins. This study presents the results of regionalization methods
14 for the first time applied on the GHM WaterGAP3. It aims to provide insights into (1) selecting a suitable region-
15 alization method for a GHM and (2) evaluating its impact on runoff simulation. In this study, four new regionali-
16 zation methods have been identified as appropriate for WaterGAP3. These methods span the full spectrum of
17 methodologies, i.e., regression-based methods, physical similarity, and spatial proximity, using traditional and
18 machine learning-based approaches. Moreover, the methods differ in the descriptors used to achieve optimal re-
19 sults, although all utilize climatic and physiographic descriptors. This demonstrates (1) that different methods use
20 descriptor sets with varying efficiency and (2) that combining climatic and physiographic descriptors is optimal
21 for regionalizing worldwide basins. Additionally, our research indicates that regionalization leads to spatially and
22 temporally varying uncertainty in ungauged regions. For example, regionalization highly affects southern South
23 America, e.g., leading to high uncertainties in the flood simulation of the Río Deseado. The local impact of re-
24 gionalization propagates through the water system, also affecting global estimates, as evidenced by a spread of
25 1,500 km³ yr⁻¹ across an ensemble of five regionalization methods in simulated global runoff to the ocean. This
26 discrepancy is even more pronounced when using a regionalization method deemed unsuitable for WaterGAP3,
27 resulting in a spread of 4,208 km³ yr⁻¹. This significant increase highlights the importance of carefully choosing
28 regionalization methods. Further research is needed to enhance the predictor selection and the understanding of
29 the methods' robustness on a global scale.

30 **1. Introduction**

31 Global hydrological models (GHMs) are developed and applied worldwide, e.g., to detect hotspots and examine
32 patterns of climate change impacts on the terrestrial water cycle (e.g., Barbarossa et al., 2021; Boulange et al.,
33 2021). Valid model results are a prerequisite to draw robust conclusions. For valid modeling results, it is beneficial
34 to adjust the parameter values to adapt the models to different basin processes (Gupta et al., 1998). This adaptation
35 is usually modified and evaluated (in a loop) by comparing the simulated model output, often discharge, with the
36 monitored data. However, this parameter adjustment for GHMs is challenging due to the lack of global monitoring

37 data. Consequently, parameter adjustment for GHMs can be based not only on monitored data (i.e., calibration)
38 but also on estimating parameter values for ungauged basins (i.e., regionalization).

39 Regionalization defines the estimation of model parameters for ungauged basins (Oudin et al., 2008), usually based
40 on information from gauged basins (Oudin et al., 2010). Regionalization methods generally follow the same prin-
41 ciple: basin characteristics (e.g., physiographic and/or climatic) are linked to hydrological characteristics and can
42 thus be used to estimate parameter values. Various regionalization methods exist, and no overall preferred method
43 has been found (Ayzel et al., 2017; Pool et al., 2021). In contrast, the optimal regionalization method may differ,
44 for example, regarding available information (Pagliero et al., 2019) or model structures (Golian et al., 2021).
45 Therefore, different methods should be tested to find an optimal regionalization method for a specific use case
46 (e.g., Qi et al., 2020).

47 Evaluation is needed to assess different regionalization methods. The evaluation of regionalization methods is
48 particularly challenging because they are usually applied when there is a lack of monitoring data. Therefore, re-
49 gionalization studies often treat gauged basins as "ungauged" and perform leave-one-out cross-validation (e.g.,
50 Chaney et al., 2016) or split-sample tests (e.g., Beck et al., 2016; Nijssen et al., 2000; Yoshida et al., 2022). While
51 at the mesoscale, this evaluation is already an integral part (e.g., McIntyre et al., 2005; Parajka et al., 2005; Oudin
52 et al., 2008; Yang et al., 2020), this is sometimes not the case in global or continental studies (e.g., Müller Schmied
53 et al., 2021; Widén-Nilsson et al., 2007). Another reasonable evaluation strategy is the concept of benchmark-to-
54 beat (Schaepli & Gupta, 2007; Seibert, 2001). Applying a benchmark-to-beat supports a comprehensive evaluation
55 of whether a new approach is functional, e.g., better than a straightforward and thus transparent method or better
56 than a predecessor. To the authors' knowledge, such a benchmark-to-beat has never been used to evaluate innova-
57 tions in regionalization at a global scale.

58 In general, regionalization methods can be divided into two categories based on the parameter estimation strategy:
59 (1) regression-based and (2) distance-based (He et al., 2011). Regression-based methods derive the relationship
60 between basin characteristics and model parameters through fitted regression models. These mathematically de-
61 fined relationships are further applied to estimate model parameters of ungauged basins (e.g., Kaspar, 2004; Müller
62 Schmied et al., 2021). A significant drawback of regression-based regionalization is the difficulty of incorporating
63 parameter interdependencies (Poissant et al., 2017), as regression-based approaches often assume that the depend-
64 ent variables, i.e., the model parameters, are not correlated (Wagener et al., 2004). Distance-based approaches
65 transfer complete parameter sets from similar or nearby donor basins to ungauged basins (e.g., Beck et al., 2016;
66 Nijssen et al., 2000; Widén-Nilsson et al., 2007). Using an ensemble of donor basins, e.g., by averaging the pa-
67 rameter values or model outputs, can improve the performance of such methods (e.g., Arsenault & Brissette, 2014).
68 A significant disadvantage of such methods is the clustering problem of ungauged basins, i.e., the unequal distri-
69 bution of gauging stations worldwide (Krabbenhof et al., 2022). Thus, basins exist where distance-based ap-
70 proaches will use incomparable basins to transfer parameter values due to the lack of close basins.

71 Recent advances have implemented machine learning-based techniques in the context of regionalization. For ex-
72 ample, Chaney et al. (2016) used regression trees as an alternative to least squares regression to estimate parameter
73 values in ungauged basins. Pagliero et al. (2019) explored supervised and unsupervised clustering methods to
74 define the similarity of basins to transfer parameter sets. To the authors' knowledge, no study has compared several
75 traditional regionalization methods with machine learning-based methods for a GHM on a global scale.

76 Some regionalization methods do not make a clear distinction between calibration and regionalization. For exam-
77 ple, Arheimer et al. (2020) applied a basin grouping beforehand. Then, they jointly calibrated the group members
78 to define representative parameter sets. Subsequently, the representative parameter sets are transferred to other
79 basins based on grouping rules. Another approach defines so-called transfer functions (Samaniego et al., 2010)
80 and calibrates meta-parameters instead of the model parameter values (Beck et al., 2020; Feigl et al., 2022). These
81 methods, where regionalization is part of the calibration process, often require a change in the calibration process
82 itself, which is challenging for GHMs (Schweppe et al., 2022), for example, due to a lack of code flexibility (e.g.,
83 Cuntz et al., 2016).

84 This study proposes an improved regionalization method for the state-of-the-art GHM WaterGAP3 (Eisner, 2016).
85 It compares traditional regionalization methods with machine learning-based methods and uses a benchmark-to-
86 beat and an ensemble of split-sample tests to evaluate the applied methods. Further, global runoff simulations are
87 compared to analyze the impact of regionalization methods. The overall research topic is evaluating and selecting
88 regionalization methods for a GHM. Specifically, the study has two objectives. It aims

- 89 (1) to propose an improved regionalization method for WaterGAP3 and
- 90 (2) to evaluate the impact of regionalization methods on global runoff simulations.

91 **2. Data and Methods**

92 **2.1 The Model: WaterGAP3**

93 The GHM WaterGAP3 simulates the terrestrial water cycle, including the main water storage components and a
94 simple storage-based routing algorithm. It is a fully distributed model that operates on a five arcmin grid and
95 simulates at a daily time step. A more detailed description of the model can be found in Eisner (2016).

96 In WaterGAP3, most model parameter values are set a priori, e.g., using look-up tables for albedo or rooting depth.
97 Only one parameter, γ , is calibrated, which is part of the soil moisture storage in which runoff generation processes
98 are present. The model equation for γ , which originates from the HBV-96 model (Lindström et al., 1997), is given
99 in Eq. (1) (cf. ll. 1223-4 in daily.cpp of the published model (Flörke et al., 2024)). Generally, higher values of γ
100 lead to lower runoff volumes, while lower values of γ lead to higher runoff volumes. The model parameter is
101 calibrated per basin within the range of 0.1 and 5. The objective function of the calibration is to minimize the
102 deviation between the mean annual simulated and observed river discharge, i.e., the calibration aims to reduce the
103 error in discharge volume. Given the monotonic relationship between the model's parameter and the optimization
104 function, a simple search algorithm is applied: The parameter space is divided into rectangles, which are subse-
105 quently subdivided into smaller rectangles depending on the direction γ should be modified to achieve closer
106 alignment with the optimization target. The calibration results in one calibrated γ value between 0.1 and 5 per
107 basin. After the calibration, a correction is applied to account for high errors in the mass balance, e.g., due to
108 inaccuracies in global meteorological forcing products. This correction is only applicable on gauged basins. It is,
109 therefore, neglected in this study.

$$110 \quad R = P_t \cdot \left(\frac{S_s}{S_{s,max}} \right)^\gamma \quad (1)$$

111 where R is the daily runoff, P_t is the daily throughfall, S_s is the actual soil storage, $S_{s,max}$ is the maximal soil
112 storage (given as a global map in Appendix A), and γ is the calibration parameter.

113 Traditionally, the regionalization process in WaterGAP3 is a simple multiple linear regression (MLR) approach to
114 estimate the calibration parameter γ for ungauged basins (e.g., Döll et al., 2003; Kaspar, 2004). The drawback of
115 MLR regarding parameter interaction can be neglected: As there is only one parameter to estimate, parameter
116 interference does not exist. Instead, the approach offers the advantage of a lightweight, transparent application that
117 can be quickly revised and adapted.

118 2.2 Model Data

119 WaterGAP3 requires various input data, such as soil information, topography, or information on open freshwater
120 bodies. This study uses the same input data as Kupzig et al. (2023). For meteorological forcing, we use the global
121 data set EWEMBI (Lange, 2019). This data product includes daily global forcing data with a spatial resolution of
122 0.5 degrees (latitude and longitude) that covers a period from 1979 to 2016. Specifically, WaterGAP3 uses the
123 following forcing information from the EWEMBI data set as input:

- 124 • daily mean temperature,
- 125 • daily precipitation,
- 126 • daily shortwave downward radiation, and
- 127 • daily longwave downward radiation.

128 The WaterGAP3 calibration requires observed monthly river discharge data. This discharge data is subsequently
129 transformed into annual discharge sums and used as a benchmark in the calibration procedure. In this study, we
130 used discharge data from 1,861 stations that were manually verified (Eisner, 2016). To get the best data available,
131 we have updated all available station data with recent data from The Global Runoff Data Center (GRDC, 2020).
132 All stations have at least five years of complete (monthly) station data between 1979 and 2016. For each station,
133 a contribution area, i.e., a basin, is defined with the gridded flow-direction information obtained from WaterGAP3,
134 based on the HydroSHEDS database (Lehner et al., 2008).

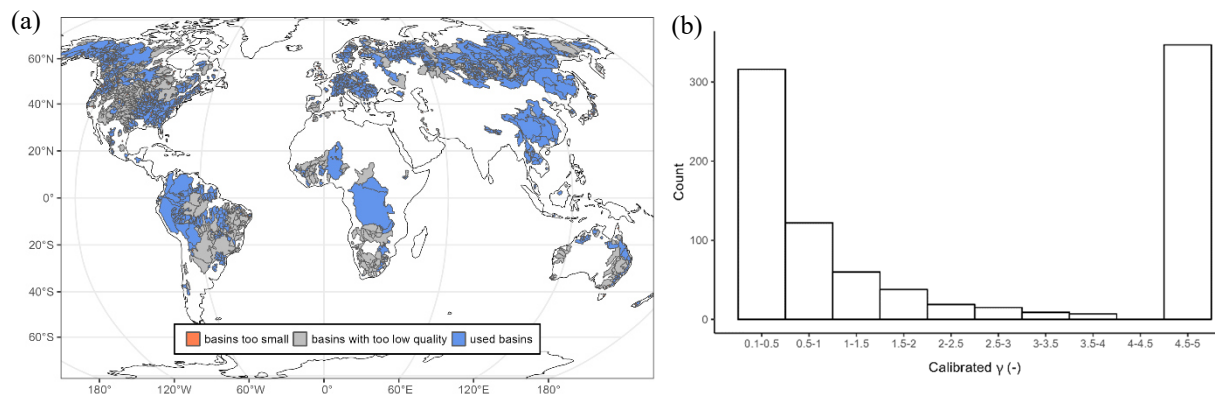
135 The 1,861 basins are calibrated using the above-described standard calibration approach for WaterGAP3. Follow-
136 ing the standard calibration procedure, some basins still have an insufficient model performance. In this context,
137 we define a monthly Kling-Gupta-Efficiency (KGE) (Gupta et al., 2009) below 0.4 or more than 20 % bias in
138 monthly flow as insufficient model performance. The expression for the KGE is given in Eq. (2). We underscore
139 the importance of minimizing the error in discharge volume by defining it as an additional criterion corresponding
140 to the optimization target during calibration. Basins not fulfilling the defined conditions regarding bias and KGE
141 are neglected in further analysis to avoid high parameter uncertainty due to errors in input data, model structure,
142 or discharge data affecting the analysis. Further, we have excluded all basins with less than 5000 km² (inter-) basin
143 size from the next upstream basin. We assume that this inter-basin size is large enough to assume a certain degree
144 of interdependency between nested basins. In total, 933 out of 1,861 basins are selected for regionalization (626
145 are neglected due to insufficient model performance, and 302 are neglected due to inadequate basin size).

$$146 \quad KGE = 1 - \sqrt{(1 - r)^2 + \left(1 - \frac{\sigma_y}{\sigma_x}\right)^2 + \left(1 - \frac{\mu_y}{\mu_x}\right)^2} \quad (2)$$

147 where r is the Pearson correlation coefficient between observed discharge x and simulated discharge y , σ denotes
148 the corresponding standard deviation, and μ the corresponding mean of observed and simulated discharge.

149 Figure 1a depicts the worldwide calibrated basins, highlighting gauged and ungauged regions. Whereas most parts
150 of North and South America are gauged, Africa and Australia remain largely ungauged. A cluster of gauged basins
151 is in Central Europe and in Eastern Asia. Gauged regions with insufficient model performance are mainly in the
152 Mississippi River basin, Southern Africa, Australia, and large parts of Brazil. These regions are known to be chal-
153 lenging for GHMs (e.g., cf. Fig. 8b in Stacke & Hagemann, 2021).

154 Figure 1b shows the calibrated values for γ . It emerges that the calibrated values tend to be at the upper and lower
155 bounds of the parameter space. This behavior is already known (cf. Fig. 4b in Müller Schmied et al., 2021). A
156 brief sensitivity analysis and discussion of the calibration parameter are included in Appendix B. The results of
157 this analysis indicate that the clustering of the calibrated parameter value is not related to an inappropriate selection
158 of the parameter bounds but instead to the absence or an insufficient representation of processes. Thus, the clus-
159 tering of the calibrated values does not indicate an inadequate selection of the parameter bounds but highlights the
160 necessity to improve the model structure and the calibration strategy for WaterGAP3. However, this study focuses
161 solely on analyzing and implementing regionalization methods. It does not aim to enhance the model structure or
162 to change the calibration procedure of WaterGAP3. Future studies are needed to achieve the latter, as WaterGAP3
163 contains many hard-coded parameters or parameters defined by look-up tables that need to be analyzed to identify
164 and adjust sensitive parameters more accurately during calibration. Initial steps in this direction have already been
165 taken for WaterGAP2 in the form of a multivariate and multi-objective case study in the Mississippi River basin
166 (Döll et al., 2024).



167 **Figure 1: a) Map of calibrated basins, highlighting basins not used for regionalization due to insufficient model perfor-**
168 **mance or inadequate basin size and b) the histogram of the calibrated γ values for all used basins showing a cluster of**
169 **parameter values at the parameter bounds.**

170 2.3 Basin Descriptors

171 This study uses basin descriptors as predictors to drive regression-based or distance-based regionalization ap-
172 proaches. These basin descriptors are based on data used within the model simulation (as they are globally avail-
173 able). They are aggregated to basin values using a simple mean method to have the same spatial resolution as the
174 calibrated model parameter. Thus, in the case of nested basins, the inter-basin area is used to define the basin
175 descriptors. The selection of the predictors, i.e., basin descriptors that support the estimation of γ , is crucial for
176 regionalization methods (Arsenault & Brissette, 2014). Typically, this selection aims to obtain the most infor-
177 mation with the least number of predictors to (1) improve the model quality and (2) limit over-parametrization. In
178 this study, we use 12 basin descriptors to develop regionalization methods; nine of these descriptors are physio-
179 graphic, while the remaining three are climatic (see Table 1). Most descriptors are not correlated (see Appendix
180 C), i.e., we minimize redundant information (Wagener et al., 2004).

181 A descriptor subset is selected based on correlation analysis between basin descriptors and calibrated γ value and
182 entropy assessment. Pearson's correlation coefficient detects linear correlation, and Spearman's Rho and Kendall's
183 Tau detect a non-linear correlation. Shannon entropy (Shannon, 1948) measures the information gain of the pre-
184 dictors explaining the calibrated γ value. The higher the information gain, the more valuable the basin descriptor
185 is for explaining the variation in the calibrated γ value. The analysis directly evaluates the relationship between
186 the calibrated parameter and the basin descriptors, as WaterGAP3 uses only one calibration parameter with a clear
187 global optimum within the parameter space. An alternative would be to use flow characteristics to define the basis
188 for regionalization (e.g., Pagliero et al., 2019). We decided to use the calibrated parameter instead of flow charac-
189 teristics as it does not need any further assumption on which flow characteristics determine the model's parameter.

190 Statistical information of the evaluated basin descriptors and the corresponding correlation coefficients and infor-
191 mation gain are listed in Table 1. The basin descriptors demonstrate a considerable degree of variability, e.g., the
192 basin size ranges from 5000 km² to 3,112,480 km² with a median of 13,796 km². The mean temperature varies
193 from -19 °C to 29 °C, and the sum of precipitation ranges from 213 mm to 5,716 mm. Although there is a high
194 degree of variability in the analyzed basin descriptors, the basin descriptors exhibit low correlation coefficients
195 with the calibrated values. For example, the permafrost coverage shows the strongest Pearson correlation of -0.37
196 (and -0.50 for Spearman's Rho). The information gain indicates the same results as the correlation analysis, i.e.,
197 the information gain is generally relatively low, and descriptors with a higher correlation tend to have a higher
198 information gain. For example, the mean temperature exhibits the maximal information gain of 17.6 % and has
199 the second-highest correlation coefficient with a Pearson correlation of 0.34.

200 **Table 1: Basin descriptors: statistical information, correlation, and entropy assessment. Selected physiographic and**
201 **climatic basin descriptors are written in bold.**

	Basin Descriptor	Attribute Information				Entropy & Correlation			
		Min	Max	Mean	Median	IG (%) ¹	Pearson	Spearman	Kendall
physiographic	Soil Storage (mm)	12.405	610.469	220.805	195.778	13.07	-0.21	-0.15	-0.11
	Open Water Bodies (%)	0.000	63.960	5.521	1.812	5.65	-0.01	-0.08	-0.05
	Wetlands (%)	0.000	63.466	4.164	0.547	5.01	-0.02	-0.13	-0.09
	Size (km ²)	5000	3,112,480	37,572	13,796	1.42	-0.04	-0.04	-0.03
	Slope Class (-)	10.057	67.756	38.668	38.364	16.60	-0.31	-0.37	-0.27
	Altitude (m.a.s.l.)	30.239	4765.166	591.024	394.870	9.30	-0.18	-0.28	-0.20
	Sealed Area (%)	0.000	12.3	0.6	0.1	4.49	0.22	0.38	0.29
	Forest (%)	0.000	100.000	35.340	24.002	13.82	-0.25	-0.18	-0.14
	Permafrost & Glacier (%)	0.000	95.000	16.662	0.000	13.12	-0.37	-0.50	-0.40
climate	Mean Temperature(°C)	-18.848	28.823	7.720	7.707	17.56	0.34	0.41	0.30
	Yearly Precipitation (mm)	213.6	5,716.3	996.5	779.5	9.23	0.02	0.21	0.14
	Yearly Shortwave Down-ward Radiation (Wm⁻²)	1,050.6	3,043.2	1,857.9	1,759.7	15.79	0.31	0.33	0.24

¹Information gain is given in percentage of total information content in γ after Shannon (1948)

202 In contrast to the findings of Wagener and Wheater (2006), the correlation coefficients between the basin de-
203 scriptors and the calibrated values are relatively low, indicating a weak relationship. One potential explanation for
204 this discrepancy is that Wagener and Wheater (2006) used a smaller number of basins in southeast England, with
205 limited versatility (e.g., regarding climate and seasonality) compared to the 933 worldwide basins used in this
206 study. Studies using a large number of basins likely tend to find a lower correlation between catchment attributes
207 and model parameters (Merz et al., 2004). Moreover, the clustered calibrated γ values at the bounds of the valid
208 parameter space may disturb the results of this analysis. As the calibrated value masks the effect of multiple sources

209 of errors, such as uncertainty in the input data, model structure, or varying hydrological processes, finding a mean-
210 ingful relationship between catchment characteristics and calibrated values is challenging.

211 Because the basis for the descriptor selection seems uncertain, given the low correlation and the named constraints,
212 we additionally run the regionalization methods with all descriptors to evaluate the descriptor selection. Further
213 on, to ascertain the advantage of integrating climatic descriptors, we run the regionalization methods using either
214 physiographic or climatic descriptors. In total, we used four groups of basin descriptors to implement the region-
215 alization methods:

- 216 • "cl": all three climatic descriptors,
- 217 • "p": all nine physiographic descriptors,
- 218 • "p+cl": all 12 descriptors, and
- 219 • "subset": two correlated climatic descriptors (mean temperature, annual shortwave radiation) & three
220 correlated physiographic descriptors (slope class, forest %, permafrost %).

221 **2.4 Regionalization Methods**

222 In our study, we test several traditional and machine learning-based regionalization methods against each other
223 and a defined benchmark-to-beat to find suitable regionalization methods for WaterGAP3. At the global scale,
224 regionalization is particularly challenging due to (1) the lack of high-quality data, (2) the diversity of dominant
225 hydrological processes in basins, and (3) the high computational demands of the models. Therefore, a robust re-
226 gionalization method that applies to a wide variety of basins and is not computationally demanding should be
227 selected for a global application.

228 We test three common traditional approaches and two machine learning-based approaches using the concepts of
229 spatial proximity, physical similarity, and regression-based methods. As WaterGAP3's model calibration is very
230 rigid and has only one parameter, it is not feasible to implement and test regionalization methods that incorporate
231 regionalization into the calibration process, such as transfer functions. In addition, we avoid high computational
232 demands as all evaluated methods are applicable after the calibration, i.e., without running the model.

233 As the calibration of WaterGAP3 results in a parameter distribution with a cluster of parameter values at the
234 parameter bounds, we implement a so-called "tuning" to introduce information about the parameter space into
235 regionalization. In detail, we apply a simple threshold-based approach to shift the regionalized parameter values
236 to the extremes, i.e., $\gamma_{est} < \gamma_1 \rightarrow \gamma_{reg} = 0.1$ and $\gamma_{est} > \gamma_2 \rightarrow \gamma_{reg} = 5.0$. The thresholds γ_1 and γ_2 are defined
237 by applying the k-means algorithm with three centers to the calibrated parameter values. This clustering results in
238 three clusters: one for low, one for medium, and one for high γ values. Subsequently, γ_1 refers to the highest γ
239 value of the low cluster and γ_2 refers to the lowest γ value of a high cluster.

240 To evaluate the regionalization methods, we implement an ensemble of split-sample tests. Specifically, we ran-
241 domly split the basins into 50 % gauged (for training) and 50 % pseudo-ungauged (for testing). The split has a
242 relatively high percentage of pseudo-ungauged basins, accounting for many missing gauges worldwide and the
243 high importance of generalizability. We fit the methods and apply them to the training and testing data sets. The
244 split-sample test is repeated 100 times by randomly splitting the basins to account for sampling effects.

245 As there is only one calibration parameter, γ , this parameter has a global optimum per basin. Consequently, the
246 quality of training and testing is directly assessed by the deviation between the regionalized and the calibrated

247 value for γ . The closer the regionalized values are to the calibrated ones, the more accurate the prediction. We
 248 assess the prediction accuracy by the logarithmic version of the mean absolute error (logMAE) shown in Eq. (3)
 249 to account for the decreasing sensitivity of γ for higher values (see Appendix B). The lower the logMAE, the better
 250 the prediction; a zero value in logMAE expresses no error. The regionalization method is robust if the prediction
 251 accuracy is similar in training and testing. A generally good performance, i.e., small logMAE values, indicates
 252 that the regionalization method suits WaterGAP3. The comparison of γ values enables applying a wide range of
 253 regionalization methods and sets of descriptors, as no computationally intensive model simulation is required.
 254 However, it assumes that deviations in γ lead, in turn, to deviations in discharge, which is only partially true
 255 because of varying parameter sensitivity in basins (e.g., Kupzig et al., 2023). To validate that the logMAE is a
 256 sufficient approximator for the regionalization performance in WaterGAP3, we use one representative split-sample
 257 from the ensemble to compare the accuracies in simulated discharge for different regionalization methods.

$$258 \quad \log MAE = \frac{1}{n} \sum |\ln(\gamma_{x,i} + 1) - \ln(\gamma_{y,i} + 1)| \quad (3)$$

259 where n is the number of basins in the corresponding sample, $\gamma_{x,i}$ is the calibrated value of γ for the i^{th} basin, and
 260 $\gamma_{y,i}$ is the estimated value of γ for the i^{th} basin. We applied a Box-Cox-type transformation with $\lambda_1=0$ and $\lambda_2=1$
 261 (Box and Cox, 1964) to calculate the logMAE, avoiding negatively transformed values.

262 **Regression-based methods**

263 The traditionally used regionalization approach of WaterGAP3 is a regression-based MLR. As the benchmark-to-
 264 beat, we use the regionalization approach from WaterGAP2.2d defined in Müller Schmied et al. (2021). We con-
 265 sider it a suitable benchmark-to-beat given that WaterGAP2 has a model structure and calibration process that is
 266 very similar to WaterGAP3. The main difference between these models is that WaterGAP2 simulates at 0.5° spatial
 267 resolution. The benchmark-to-beat consists of "a multiple linear regression approach that relates the natural loga-
 268 rithm of γ to basin descriptors (mean annual temperature, mean available soil water capacity, fraction of local and
 269 global lakes and wetlands, mean basin land surface slope, fraction of permanent snow and ice, aquifer-related
 270 groundwater recharge factor)". (Müller Schmied et al., 2021) We fit this regression model to our data and define
 271 the quality of this approach as the benchmark-to-beat. Moreover, we test an independent MLR approach without
 272 using the logarithmic scaling of γ and using the above-defined sets of basin descriptors. For MLR and the bench-
 273 mark-to-beat, we use the `lm()` function of the R package `stats` (R Core Team, 2020). After applying the regression
 274 model, we adjust the estimated parameter values to ensure that the estimated values range between 0.1 and 5.

275 Furthermore, a machine learning-based method, random forest (RF), is tested for regionalization as an alternative
 276 to MLR. Here, we implement the random forest algorithm with the `randomForest()` function from the R package
 277 `randomForest` (Liam & Wiener, 2002), which is based on Breiman (2001). The algorithm uses an ensemble of
 278 decision trees, making the decision human-like. It is relatively robust because it incorporates random effects into
 279 the training process. To implement this randomness, we define the algorithm as one that can choose between two
 280 randomly selected predictors at each node, using an ensemble of 200 trees.

281 **Physical Similarity**

282 As the traditional physical similarity approach, we use Similarity Indices (in the following named with SI), apply-
 283 ing the methodology proposed by Beck et al. (2016). The SI (see Eq. (4)) are derived using the defined basin

284 descriptors sets, and the parameter of the most similar basin is transferred to the pseudo-ungauged basin. Addi-
 285 tionally, we use an ensemble of basins to control whether an ensemble-based approach leads to more robust results.
 286 The optimal number of donor basins may vary between research regions and hydrological models (Guo et al.,
 287 2020). Here, we use ten donor catchments (noted with "ensemble") based on Beck et al. (2016) and McIntyre et
 288 al. (2005). Further, we apply a simple mean method for the ensemble-based prediction to aggregate the ensemble
 289 of γ values into one predicted parameter value.

$$290 \quad S_{i,j} = \sum_{p=1}^n \frac{|Z_{p,i} - Z_{p,j}|}{IQR_p} \quad (4)$$

291 where $S_{i,j}$ is the Similarity Index between basin i and basin j , $Z_{p,j}$ is the basin descriptor p for basin j , IQR_p is the
 292 interquartile range for basin descriptor p among all (gauged) basins, and n is the number of all basin descriptors
 293 used.

294 As an alternative machine learning-based approach, we apply a simple k-means algorithm. We selected the k-
 295 means algorithm because it is one of the most widely used clustering algorithms (Tongal & Sivakumar, 2017). It
 296 is easy to understand and use. The algorithm `kmeans()` is implemented in the R base package `stats`. It aims to
 297 maximize variation between groups and minimize variation within groups. The number of clusters to use is deter-
 298 mined by multiple indices calculated with the R package `NbClust` (Charrad et al., 2014). For all 933 basins and
 299 the defined sets of basin descriptors, most indices defined three as the optimal number of clusters. Accordingly,
 300 we use three clusters to generate the groups of basins. As different scales of the predictor values can affect the
 301 clustering, a rescaling with min-max-normalization (see Eq. (5)) is performed on the training set and applied to
 302 the testing set. After the grouping, the mean γ value is assigned as a representative calibrated value to the corre-
 303 sponding basin group. To estimate the corresponding group for a pseudo-ungauged basin, the `knn` algorithm is
 304 used, and the representative γ value of the group is assigned to the pseudo-ungauged basin. This algorithm is
 305 implemented by the `knn()` function of the R package class (Venables & Ripley, 2002). Since the k-means method
 306 is less flexible than SI, we implement a highly flexible version, using the `knn` algorithm directly to define the donor
 307 basin most similar to each ungauged basin. Using the `knn` algorithm directly, we test how beneficial it is to create
 308 groups of similar basins using the `kmeans` algorithm and regionalize the parameter with a representative mean
 309 value.

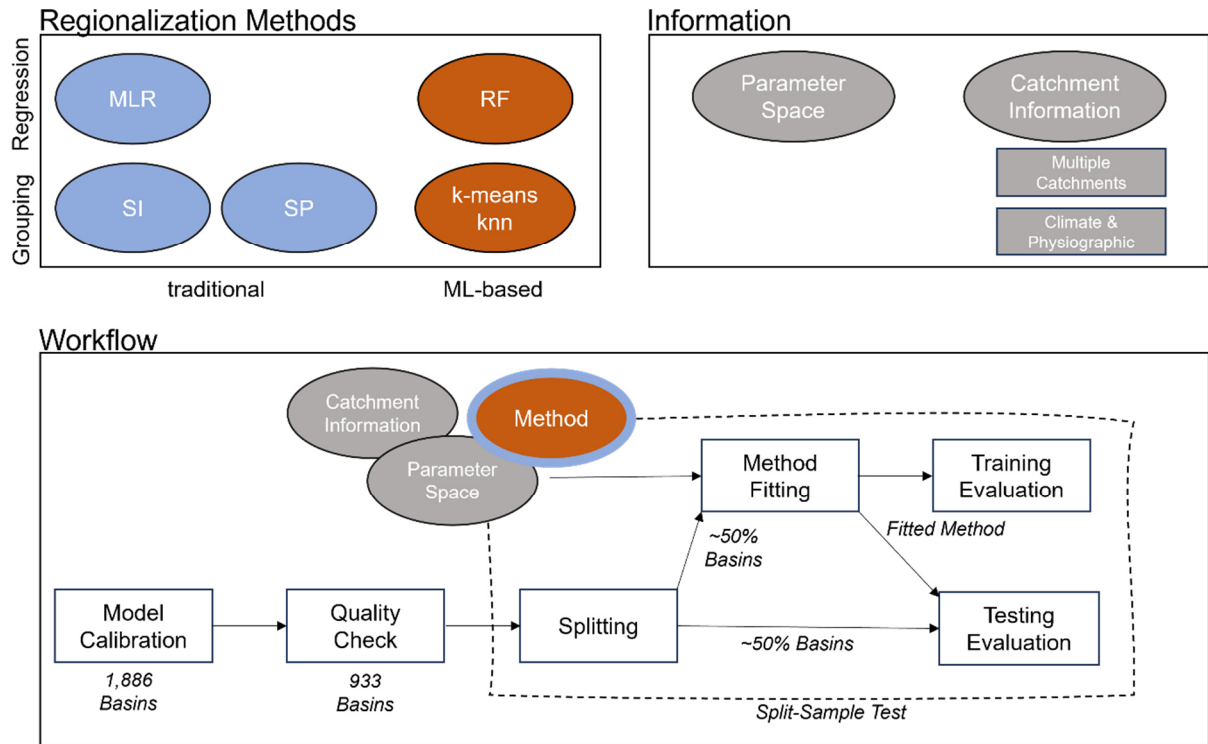
$$310 \quad Z'_{p,j} = \frac{Z_{p,j} - \min_{j \rightarrow m}(Z_{p,j})}{\max_{j \rightarrow m}(Z_{p,j}) - \min_{j \rightarrow m}(Z_{p,j})} \quad (5)$$

311 where $Z'_{p,j}$ is the normalized basin descriptor p for basin j , $Z_{p,j}$ is the basin descriptor p for the basin j , m is the
 312 number of (gauged) basins.

313 **Spatial Proximity**

314 The spatial proximity approach is one of the easiest to regionalize parameter values. However, it is also often
 315 criticized that nearby basins do not necessarily have the same hydrological behavior (Wagener et al., 2004). Fur-
 316 thermore, its performance depends on the density of the network of gauged basins (Lebecherel et al., 2016). The
 317 dependency on network density is particularly challenging for global applications where large parts of the world
 318 are ungauged (e.g., northern Africa). Nevertheless, the approach has been successfully applied in other studies
 319 (e.g., Oudin et al., 2008; Qi et al., 2020), even globally (Widén-Nilsson et al., 2007). Here, we take the distance
 320 between the centroids of the basins as the reference for the spatial distance between basins, as done by others

321 (Oudin et al., 2008; Merz and Blöschl, 2004). We use the abbreviation SP in the text below to refer to the spatial
 322 proximity approach. Figure 2 provides an overview of the applied regionalization methods and information used
 323 for the experimental setup.



324
 325 **Figure 2: Experimental setup of the study: regionalization methods, used modifications and information, and the general workflow (MLR: Multiple Linear Regression, SI: Similarity Indices, SP: Spatial Proximity, RF: RandomForest).**
 326

327 3. Results and Discussion

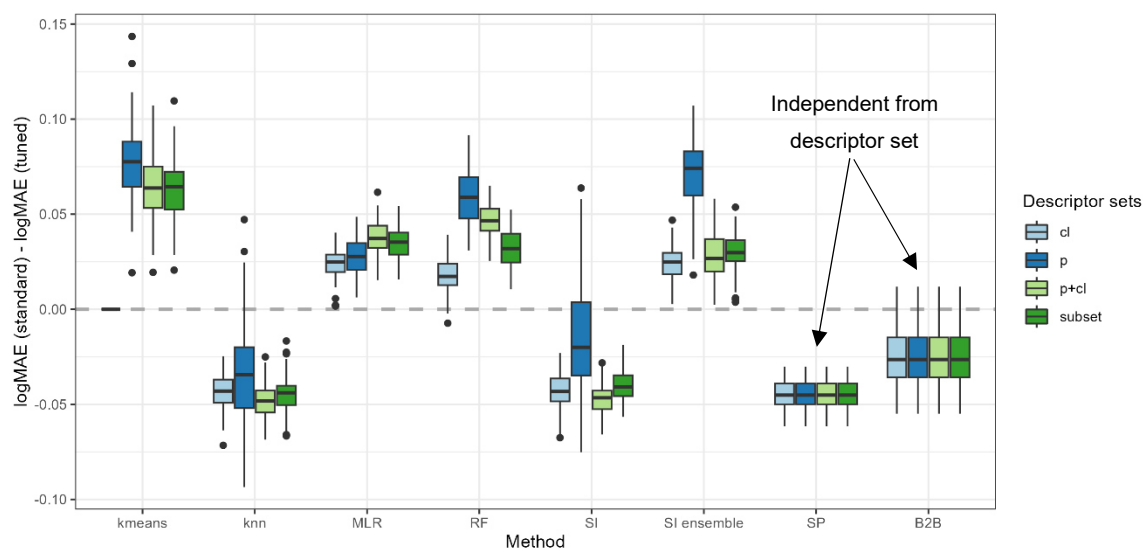
328 3.1 Evaluating the effect of tuning

329 First, the impact of the tuning approach on the regionalization approaches is evaluated. Therefore, Fig. 3 depicts
 330 the differences in logMAE between the standard and tuned approaches in testing, i.e., using the pseudo-ungauged
 331 basins. A positive difference in logMAE indicates an increase in accuracy, whereas a negative difference indicates
 332 a decrease in accuracy due to the tuning.

333 Using the tuning thresholds of about 1.1 and 3.4 for γ_1 and γ_2 , respectively, enhances the predictive accuracy for
 334 kmeans, MLR, RF, and the ensemble approach of SI. The most remarkable improvement for kmeans, RF, and SI
 335 ensemble is achieved when all physiographic descriptors are used as input (mean improvement of 0.077, 0.058,
 336 and 0.071, respectively). MLR shows the most significant improvement when using all available descriptors (mean
 337 improvement of 0.038). In contrast, the tuning decreases the performance for knn, SI, and SP, with a mean degra-
 338 dation between -0.02 and -0.05. Unlike the enhanced regionalization techniques, these methods transfer single-
 339 basin information to ungauged regions. Thus, the tuning disturbs the use of single-basin information yet simulta-
 340 neously enhances the performance of methods that transfer multi-basin information. The disturbance or improve-
 341 ment is probably related to the capability of the methods representing the clustering of parameter values at the
 342 extremes: Whereas the multi-basin information transfer implies a smoothing and thus suffers from a lack of rep-
 343 resenting the extremes, the single-basin information transfer exhibits no such a smoothing.

344 The exception from the above-defined rule is the benchmark-to-beat approach. The benchmark-to-beat is the only
 345 approach that uses logarithmic scaled γ values when fitting the model. This logarithmic transformation leads to an
 346 increase in estimating small values. Thus, when the benchmark-to-beat is tuned, more basins with higher calibrated
 347 γ values receive low estimates. The tuning intensifies this effect, leading to a decrease in the accuracy of the
 348 logMAE from the standard to the tuned version. Thus, for models using logarithmical transformed γ values, the
 349 defined thresholds for the tuning are not appropriate.

350 Applying knowledge of the optimal parameter space enhances the quality of regionalization for methods transfer-
 351 ring multi-basin information in case the tuning thresholds are appropriate. This positive effect is not surprising, as
 352 incorporating a priori information about parameter distribution strengthens parameter estimation (e.g., described
 353 in Tang et al. (2016) using the Bayes Theorem). However, for single-basin transfer, which already represents the
 354 parameter space well, i.e., the clustering of γ at the extremes, the tuning disturbs the performance. This indicates
 355 that such tuning needs to be cautiously introduced as there is the risk of decreasing the accuracy of regionalization.



356
 357 **Figure 3: Changes in performance between standard and tuned versions for all applied regionalization approaches.**
 358 **Positive values indicate an improvement related to the tuning.**

359 3.2 Evaluating descriptor subsets & algorithm selection

360 Different descriptor sets yield different performances in regionalizing γ . Table 2 shows the median of all logMAE
 361 values for the testing. For a complete overview of the results of the split-sample test ensemble, see Appendix D.
 362 Evaluating Table 2 reveals that the selected subset or all descriptors consistently yield the best performance across
 363 all regionalization methods. In both variants of the ensemble approach of SI, the tuned version of the no-ensemble
 364 approach of SI, and the standard version of RF, the selected subset yields the best results. For all other methods,
 365 using all descriptors yields the best results. Hence, all methods perform best when combining climatic and physi-
 366 ographic descriptors. This benefit of using climatic and physiographic descriptors is consistent with others that
 367 often apply a combination of climatic and physiographic descriptors, achieving optimal regionalization results
 368 (e.g., Oudin et al., 2008; Reichl et al., 2009).

369 The machine learning-based approaches seem to benefit most when using more information displaying an im-
 370 provement for all methods (knn, kmeans, and RF) and both variants (standard and tuned) ranging from "cl", "p",
 371 "subset" to "p+cl". This is not surprising as machine learning is developed to deal with big data sets. The traditional

372 methods MLR and SI do not exhibit such a distinct pattern. The (weakly) correlated subset of climatic and physi-
 373 ographic descriptors yields the best results for SI. As utilizing all descriptors decreases the performance slightly,
 374 the results indicate that uncorrelated descriptors may disturb the performance of this approach. For MLR, the
 375 meaning of physiographic information is highest, resulting in the best ("p+cl") and second best ("p") results. The
 376 disparate performance of the regionalization methods when using different descriptor sets indicates that different
 377 methods use descriptor sets with varying efficiency. It also emphasizes that the selection of descriptors impacts
 378 the regionalization method's results, as noted by others (Arsenault & Brissette, 2014). Consequently, the above-
 379 performed analysis defining a descriptor subset lacks universal validity as methods exist where the defined subset
 380 is outperformed. Instead, the validity of this approach is most closely aligned with the SI approaches.

381 Although the algorithms kmeans and knn are similar, they yield considerably different performances in Table 2.
 382 As knn shows a logMAE of 0.432 at best, the kmeans algorithm performs poorly, resulting in the best logMAE of
 383 0.472. This indicates that applying the kmeans clustering algorithm to transfer averaged parameters is inappropriate
 384 for WaterGAP3. This may be attributed to the reduced flexibility of the approach, which entails estimating
 385 only three γ values due to the optimal, though limited, number of centers. The ensemble SI approach consistently
 386 outperforms the no-ensemble SI approach in almost all variants. The positive effect of an ensemble approach for
 387 SI has already been noted (Oudin et al., 2008). Therefore, it is recommended that the number of donor basins
 388 derived from the literature be adopted in future applications to be optimal for WaterGAP3, likely resulting in
 389 higher performance.

390 **Table 2: Median logMAE of 100 split-samples for pseudo-ungauged basins, i.e., in testing, for all regionalization meth-**
 391 **ods applying four sets of descriptors for a) the standard version and b) the tuned version. The bold numbers indicate a**
 392 **better performance than the benchmark-to-beat. Thicker edges mark best-performing variants, which are chosen for**
 393 **further analysis. Grey-shaded cells indicate worst-performing variants, which were taken to validate the assumption**
 394 **that lower logMAE values result in lower KGE values.**

(a)

test (median)	MLR	RF	SI		kmeans	knn	SP	B2B
			no ens.	ensemble				
cl	0.552	0.483	0.496	0.483	0.619	0.501	0.454	0.461
p	0.479	0.465	0.487	0.480	0.551	0.477		
p+cl	0.464	0.464	0.454	0.462	0.534	0.432		
subset	0.488	0.488	0.461	0.439	0.539	0.467		

(b)

test* (median)	MLR	RF	SI		kmeans	knn	SP	B2B
			no ens.	ensemble				
cl	0.529	0.467	0.537	0.459	0.619	0.546	0.502	0.488
p	0.441	0.416	0.532	0.455	0.515	0.521		
p+cl	0.427	0.403	0.503	0.435	0.472	0.480		
subset	0.453	0.408	0.501	0.409	0.477	0.509		

395
 396 Only a few regionalization methods outperform the benchmark-to-beat. The best descriptor sets of tuned MLR,
 397 RF, and SI ensemble approach have a logMAE of 0.427, 0.403, and 0.409, respectively. The standard version of
 398 knn ("p+cl") and SP yield 0.432 and 0.454 in logMAE, respectively. Additionally, two variants of the standard SI
 399 approaches outperform the benchmark-to-beat yet exhibit inferior results compared to the selected tuned approach.

400 All other regionalization methods show higher logMAE values than the benchmark-to-beat. These methods are
401 considered insufficient in terms of performance to regionalize γ in WaterGAP3. As the benchmark-to-beat outper-
402 forms all kmeans approach variants, it is deemed unsuitable for regionalizing γ for WaterGAP3 and, therefore,
403 excluded from further analysis.

404 The well-performing SP on a global scale is surprising as the distances between basins are potentially long, and
405 hydrological processes may strongly vary. It is probably beneficial for the SP approach that γ comprises all kinds
406 of errors, e.g., spatially localized errors in global forcing products (e.g., Beck et al., 2017 reported errors for arid
407 regions in the precipitation product) or inaccurately represented processes for larger regions. Thus, the estimation
408 of γ might be appropriate, but not because of the same hydrological behavior but due to the same kind of errors.

409 The RF approach is outstanding, as it shows a massive loss in performance from training to testing (see Appendix
410 D). In detail, the logMAE in testing is about twice the logMAE in training. In comparison, other methods show
411 values of logMAE in testing ranging from 95.6 % to 101.4 % of logMAE in training. This performance loss indi-
412 cates that RF is not a robust regionalization method for WaterGAP3. Other studies that reported the good perfor-
413 mance of RF for regionalization have not investigated the stability of the performance from training to testing
414 (Golian et al., 2021; Wu et al., 2023). Likely, the mathematical problem of predicting the calibrated parameter for
415 WaterGAP3, with all its challenges (e.g., tailored parameter space, clustered calibrated parameter, and incorpora-
416 tion of many sources of errors), cannot be adequately solved by RF. Thus, although RF is known to be especially
417 robust among other machine learning-based techniques, it shows symptoms of over-parameterization. This indi-
418 cates that the algorithm is too flexible and adjusts to noise in the data, missing the underlying systematic. This lack
419 of robustness is particularly disadvantageous since, for WaterGAP3, regionalization is applied globally, requiring
420 regionalizing large parts of the world. In consequence, the RF approach is left out from further analysis and defined
421 as not suitable to regionalize γ for WaterGAP3.

422 For the tuned MLR approach and the knn approach, the best performing and, therefore, selected variant employs
423 all 12 descriptors. This number of predictors for a regionalization method is among the highest found in the liter-
424 ature (e.g., McIntyre et al., 2013, used three predictors; Beck et al., 2016, used eight predictors; Chaney et al.,
425 2010, used 13 predictors). In general, it is advisable to limit the number of degrees of freedom in a model to reduce
426 the risk of over-parametrization, thus increasing the probability of generalizability (Seibert et al., 2019). As both
427 model variants exhibit a stable model performance during training and testing (see Table D1), using a high pro-
428 portion of the basins for testing, i.e., 50 %, we consider the two variants robust despite the relatively high number
429 of predictors used. Therefore, we consider them appropriate for further model evaluation.

430 Nevertheless, the chosen basin descriptors for knn and tuned MLR could be enhanced in future studies. As the
431 descriptor set "p+cl" was initially considered as a control group to determine the suitability of the selected subset,
432 it is not optimal. To indicate potential enhancements regarding the descriptor set for both methods, we calculated
433 a simple permutation-based feature importance score (cf. Breiman, 2001) by randomly shuffling each predictor
434 within the testing data set and quantifying the loss in logMAE relative to the logMAE of the original testing data
435 set. The higher the loss, the more critical the shuffled predictor for the regionalization method. The resulting feature
436 importance scores are presented in Appendix E, indicating that for the tuned MLR, the subset of (weakly) corre-
437 lated descriptors should be extended by including waterbody information. For the knn approach, the calculated
438 feature importance scores indicate that it should be extended by including information about the soil storage.

3.3 Performance of selected algorithm in pseudo-ungauged basins

To avoid the high risk of sampling effect when applying the split-sample test, we conduct an ensemble of 100 split-sample tests analyzing the median of logMAE between regionalized and calibrated values as an indicator for performance. Directly using the differences in regionalized and calibrated values is only meaningful when the calibrated value represents the global optimum. As this is often not the case, e.g., due to equifinality, the performance of regionalization methods is usually assessed by the accuracy of simulated discharge (e.g., Samaniego et al., 2010; Arsenault & Brissette, 2014). Because WaterGAP3 requires computationally intensive simulations, running WaterGAP3 for all 100 split-sample tests for the selected methods is not feasible. Therefore, we select a single representative split-sample to assess the quality of representing the discharge in the pseudo-ungauged basins using regionalized γ values. The representative split-sample leads to comparable logMAE values to the corresponding median of the ensemble for all regionalization methods. For the evaluation, WaterGAP3 was run for the same period used in calibration (from 1979 to 2016), with the first year simulated ten times to allow for model warm-up. Using this period ensures the availability of sufficient data for the evaluation (see Chapter 2.2). Furthermore, the differences between the monthly simulated and observed discharge are assessed using the KGE.

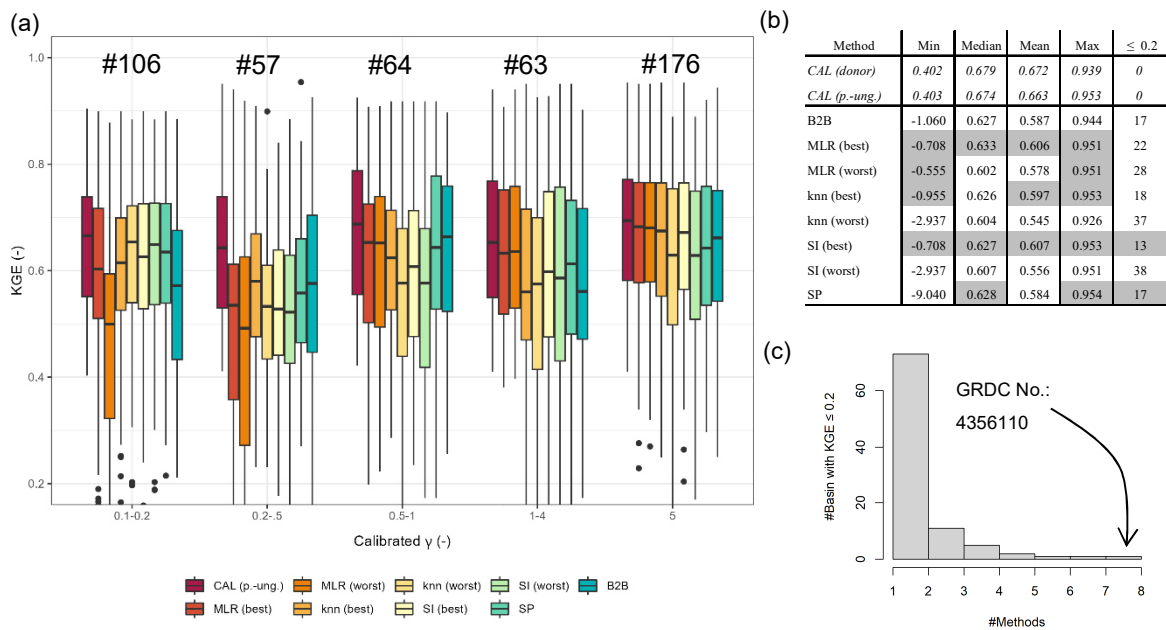


Figure 4: a) KGE values of pseudo-ungauged basins from split-sample test grouped by the range of calibrated γ values, b) selected metrics of KGE values from the pseudo-ungauged basins (better or equal performance to the benchmark-to-beat is highlighted in grey), and c) histogram of the number of pseudo-ungauged basins with a KGE below 0.2 and the corresponding number of methods exhibiting this performance loss.

To evaluate the KGE, we select the best-performing methods that outperform the benchmark-to-beat: tuned MLR "p+cI", knn "p+cI", tuned SI ensemble "subset", and SP (see Table 2). For the sake of simplicity, we further mark them with "(best)". Additionally, we select three poorly performing variants to validate the assumption that methods resulting in higher logMAE values tend to result in lower KGE values, i.e., lower accuracy of simulated discharge. These methods are tuned SI "cI" (logMAE: 0.537), tuned knn "cI" (logMAE: 0.546), and MLR "cI" (logMAE: 0.552). Further, we denote these methods with "worst". Applying the selected methods and the benchmark-to-beat method results in eight estimates of γ for the pseudo-ungauged basins, whose performance is further evaluated in terms of simulated discharge accuracy.

466 Figure 4a shows the resulting KGE values for the evaluated regionalization methods and the calibrated version as
467 grouped boxplots for different ranges of calibrated γ . The methods show different performances for different γ
468 ranges, indicating their strengths and weaknesses. For the smallest γ range, "0.1-0.2", the selected methods that
469 perform well during the split-sample test outperform the benchmark-to-beat. The better result for minimal γ ranges
470 is probably partially related to the advantage of the tuning, which leads to more predictions of 0.1 within the
471 regionalization. The benchmark-to-beat shows the best performance for γ values between 0.2 and 0.5. The good
472 performance for basins with calibrated γ values between 0.2 and 0.5 is probably related to the benefit of using the
473 logarithmical version of γ in the benchmark-to-beat, leading to more estimates of smaller values. However, this
474 affects only 12 % of the basins, as calibrated values between 0.2 and 0.5 are not frequently present in the calibration
475 result. Generally, the differences in KGE appear higher for smaller γ values, probably due to the decreasing pa-
476 rameter sensitivity with higher values (see Appendix B).

477 Given the variability in the performance of the regionalization methods across the depicted γ ranges, it is challeng-
478 ing to identify an overall best regionalization method using Fig. 4a. Therefore, we compare the various metrics of
479 the KGE values depicted in Fig. 4b. The analyzed metrics are the minimum, maximum, mean, and median. Further,
480 we count the number of poorly performing basins, defined as basins with a KGE below 0.2. In Fig. 4b, metrics
481 that exceed the benchmark-to-beat are grey-shaded. Comparing the KGE metrics in Fig. 4b reveals that the meth-
482 ods showing higher logMAE values in our split-sampling test ensemble also show lower performance in simulating
483 discharge. For example, all mean (and median) KGE values of the "worst" methods are below the mean KGE of
484 0.587 from the benchmark-to-beat, ranging from 0.545 to 0.578. This indicates that the used logMAE between
485 regionalized and calibrated values is a valid tool for a preliminary selection of adequate methods for the regional-
486 ization of WaterGAP3. However, for a more comprehensive analysis, we recommend additionally analyzing the
487 accuracy of simulated discharges, as the logMAE of calibrated and regionalized parameter values simplifies the
488 inherent complexity between model parameters and model performance.

489 Moreover, SI (best) outperforms the benchmark-to-beat in all listed metrics, reducing poorly performing basins
490 and enhancing well-performing basins. MLR (best) performs very similarly to SI (best), yet it shows a higher
491 number of basins with KGE values below 0.2. In comparison to the benchmark-to-beat, it outperforms four out of
492 five criteria. The remaining well-performing methods, SP and knn (best), demonstrate superior or equal perfor-
493 mance to the benchmark-to-beat in three out of five criteria. SP results in an equal number of poorly performing
494 basins, and the minimal KGE value is lower than for the benchmark-to-beat. The knn (best) approach has a slightly
495 worse median of KGE, i.e., -0.001, and one additional basin shows a KGE below 0.2.

496 As SI (best) outperforms the benchmark-to-beat in all metrics, we conduct a statistical test to ascertain whether
497 there is a statistically significant difference in KGE results between the methods. To this end, we use a one-sided
498 paired Wilcoxon rank sum test to test the null hypothesis of whether the KGE differs significantly in central ten-
499 dency. A significance level of 0.05 and an adjusted p-value are applied to correct for multiple comparisons (using
500 the correction after Benjamini & Hochberg (1995)). The results (cf. Figure F1c) demonstrate that SI (best) outper-
501 forms all "worst" methods and the benchmark-to-beat. However, the null hypothesis for SP and the "best" options
502 of knn and MLR cannot be rejected. Consequently, rather than identifying a single alternative to the benchmark-
503 to-beat, we have identified four.

504 Notably, all regionalization methods lead to poorly performing basins, as evidenced by the range of basins with a
505 KGE below 0.2, varying from 13 to 37. In Fig. 4c, we examine whether there are basins that all methods cannot

506 regionalize, thereby indicating a general insufficiency of the regionalization methods for these basins. The histo-
507 gram indicates that most poorly performing basins belong to a single regionalization method. The high number of
508 basins, which cannot be estimated well by a single regionalization method, illustrates the diverse shortcomings of
509 the methods. A single basin shows poor performance across all methods. This is a basin of the river El Platanito
510 in Mexico. The calibrated γ value is about 1.5, and the corresponding KGE value in calibration is 0.466. This basin
511 appears to be highly sensitive to γ , with an inaccuracy in the estimated γ having a significant impact on the accuracy
512 of river discharge. For example, the benchmark-to-beat estimates γ to 1.0, which is close to the calibrated value of
513 1.5. However, the KGE value of the simulated discharge using the benchmark-to-beat is -0.158 due to a high
514 overestimation of the variation and mean of the discharge. This high sensitivity seems outstanding and is likely
515 attributable to the absence of waterbodies and snow, supporting a potentially high impact of γ on the model simu-
516 lation (Kupzig et al., 2023) in conjunction with a relatively small basin size (ca. 6,600 km²).

517 Model evaluation is at least partially subjective (Ritter & Muñoz-Carpena, 2013), and the choice of evaluation
518 criteria represents a source of uncertainty in model performance evaluation (Onyutha, 2024). Furthermore, the
519 choice should reflect the intended model use (Janssen & Heuberger, 1995). As GHMs are often applied to evaluate
520 monthly simulated discharge (e.g., Herbert and Döll, 2023; Jones et al., 2023; Tilahun et al., 2024), we assess the
521 model performance using monthly data. Moreover, GHMs are generalists rather than expert models; thus, the
522 model evaluation should encompass a range of aspects related to streamflow to obtain an overall metric. Therefore,
523 we applied the monthly KGE, which comprises information about the streamflow's variability, bias, and timing.
524 As we use monthly values, we expect that outliers, i.e., single flood events, are less influential than in daily data
525 sets. Consequently, we expect the disadvantage of the KGE exhibiting sampling uncertainty to be less significant
526 (cf. Clark et al., 2021).

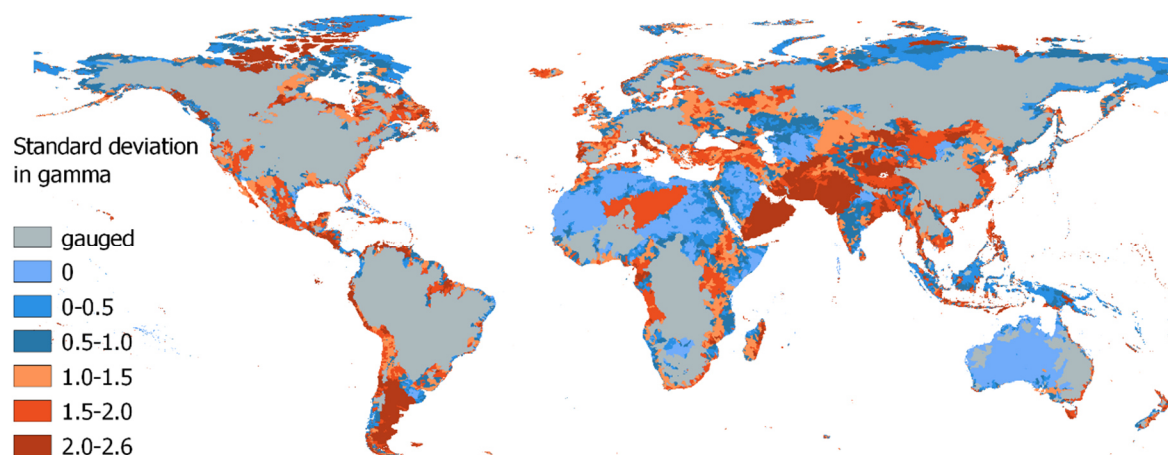
527 Nevertheless, to reduce the risk that disadvantages of the evaluation criteria influence the model evaluation, we
528 conducted an additional model evaluation using a modified version of the Nash-Sutcliffe efficiency (NSE) (Nash
529 & Sutcliffe, 1970). This modified NSE uses absolute differences instead of squared terms, leading to a metric that
530 is especially suitable as an overall measure (Krause et al., 2005). The results of the analysis are in Appendix F.
531 The high boxplot similarity between the modified NSE and the KGE confirms that the monthly KGE represents
532 the overall monthly model quality. Moreover, the statistical metrics of the modified NSE indicate that MLR (best),
533 in particular, outperforms the benchmark-to-beat. Applying the one-sided paired Wilcoxon rank sum test on the
534 modified NSE reveals that knn (best), SI (best), and the benchmark-to-beat deliver no statistically significant dif-
535 ferences in the central tendency to the well-performing MLR (best). These differences in results illustrate that the
536 choice of evaluation criteria can significantly impact the experimental outcome. Moreover, it underpins the use-
537 fulness of evaluating ensemble approaches to account for this inherent uncertainty.

538 **3.4 Impacts on runoff simulations**

539 To evaluate the impact of runoff simulations, we apply an ensemble of regionalization methods generating γ esti-
540 mates for the worldwide ungauged regions. Within the ensemble, we use the four methods SI (best), knn (best),
541 MLR (best), and SP that (1) outperform the benchmark-to-beat regarding the logMAE of regionalized and cali-
542 brated values and (2) perform similarly to each other and better than the benchmark-to-beat in KGE for monthly
543 discharge. Additionally, we use the benchmark-to-beat as the fifth member of our regionalization method ensem-
544 ble, as it shows no significantly weaker performance than the well-performing MLR (best) for the modified NSE.

545 The entire set of 933 gauged basins is used for regionalizing γ , resulting in five distinct worldwide distributions of
546 γ . The spatially distributed standard deviation of the regionalized values is shown in Fig. 5.

547 In particular, the southern parts of South America, the northern and southern parts of North America, and Central
548 Asia reveal differences in γ across the ensemble of regionalization methods (see Fig. 5). In Europe, the highest
549 differences in regionalized values are observed in Italy, Great Britain, and northern Portugal. In Oceania, the high-
550 est values in standard deviation of γ are in Tasmania, New Zealand, and the southwest of Australia's coast. In
551 contrast, a minor variation in γ is apparent in northern Africa, most parts of Australia, and the East of the Dead
552 Sea. Thus, the uncertainty associated with globally regionalizing γ seems to vary across different regions.



553 **Figure 5: Standard deviation in regionalized γ values using the best approaches of MLR (best), SI (best), SP, knn (best),**
554 **and the benchmark-to-beat. Note that dry regions without discharge are set to zero.**
555

556 An example of how these uncertainties in regionalized values propagate through the water system is presented in
557 Fig. 6. This figure displays the coefficient of variation of the mean yearly discharge between 1980 and 2016 based
558 on the five simulation runs. Moreover, we highlight the effect on rivers in ungauged regions by showing the re-
559 sulting seasonal pattern, i.e., the simulated long-term mean of monthly river discharge for three exemplary rivers.
560 These rivers are the Río Bravo in Mexico, the Tiber in Italy, and the Tamar River in Tasmania. Each river is located
561 in an ungauged region, where the standard deviation in γ is high (see Fig. 5).

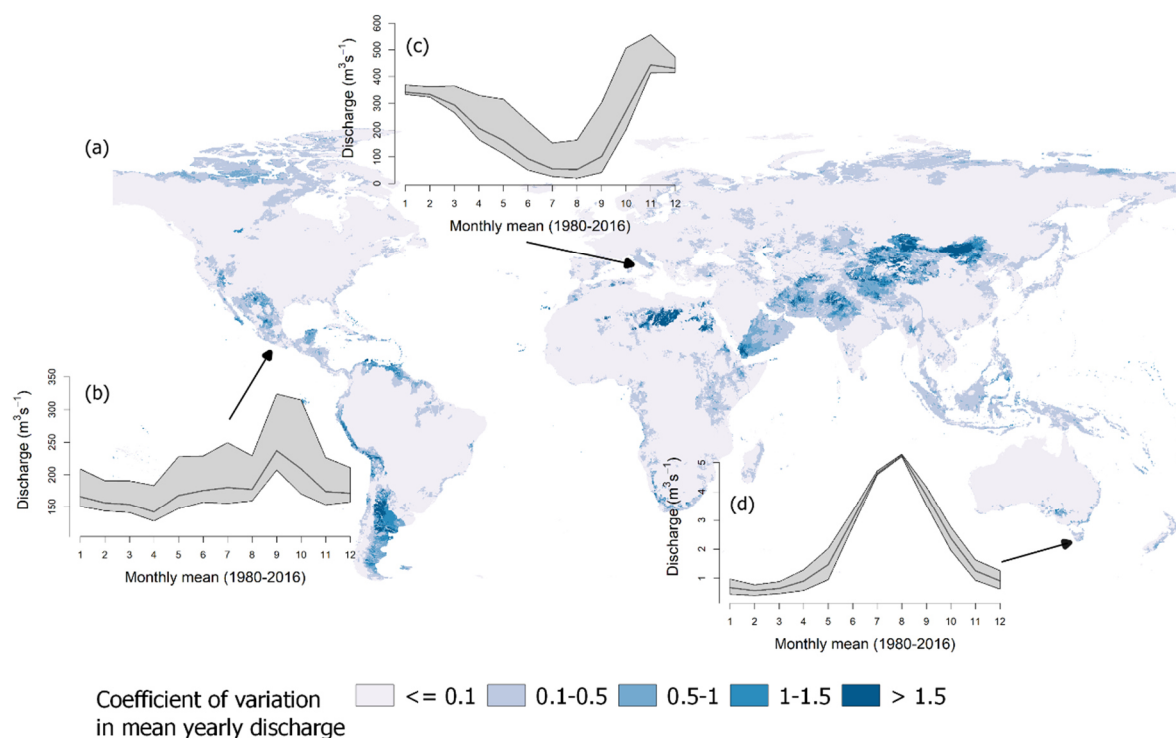
562 Comparing Fig. 5 and Fig. 6 reveals that regions showing variability in γ tend to exhibit variation in mean yearly
563 discharge. However, the impact of variation in γ on the simulated discharge appears to vary spatially. Some regions
564 showing a high degree of variation in γ do not exhibit a correspondingly high degree of variation in discharge. For
565 example, 45 % of all ungauged regions showing a low variation in discharge, i.e., the coefficient of variation is
566 below 0.5, exhibit a standard deviation of more than one in γ . In contrast, about 89 % of the ungauged regions
567 showing a higher discharge variation exhibit a standard deviation of more than one in γ . Thus, variation in γ does
568 not necessarily lead to variation in river discharge, but it increases the likelihood that a region's discharge is af-
569 fected. The spatially varying impact of γ is likely related to varying sensitivity regarding γ in the ungauged regions,
570 which depends on numerous aspects, e.g., snow occurrence or waterbodies (see Kupzig et al., 2023).

571 About 11 % of the ungauged area exhibits variations in yearly river discharge exceeding 50 % of the mean. These
572 regions are primarily in southern South America and Central Asia. A further 62 % of the ungauged area exhibits
573 variations in yearly river discharge between 10 % and 50 % of the mean. These regions are mainly located on the
574 northern coast of Russia and northern Canada, Indonesia, and Tasmania. Other areas, like most ungauged regions

575 of Africa and Australia, show almost no impact, i.e., the variation in yearly discharge is less than 10 % of the
 576 mean. In northern Africa, one region exhibits higher values in the coefficients of variation. These values are at-
 577 tributable to minimal discharge values, resulting in comparatively high coefficients of variation in this region.

578 Considering the variation in the seasonality in the selected ungauged river systems (see Fig. 6b-d), the temporal
 579 impact of regionalization varies across the local landscape. For the Tamar River in Tasmania, as illustrated in Fig.
 580 6d, the variation is higher at the start and end of the dry periods in October/November and April/May, respectively.
 581 The spread in monthly mean discharge is about $0.7 \text{ m}^3\text{s}^{-1}$ to $1 \text{ m}^3\text{s}^{-1}$ in these periods. The Tiber in Italy and the Río
 582 Bravo in Mexico exhibit a similar pattern: using the regionalized γ values of SP leads to much higher discharge
 583 rates than other ensemble members, introducing broad uncertainty bands. For the Tiber, this leads to seasonal
 584 estimates varying between 1.2 % (in January) and 11 % (in October) of the mean yearly sum. The Río Bravo shows
 585 variations in its seasonal pattern, with values ranging from 2.2 % (in February) to 6.8 % (in October) of the mean
 586 yearly sum. Thus, all rivers display a temporally varying impact. Whereas the main variation in the discharge of
 587 the Río Bravo and the Tiber is mainly attributed to the SP regionalization run, for the Tamaris River, all regional-
 588 ization runs contribute to the varying long-term monthly mean in discharge.

589



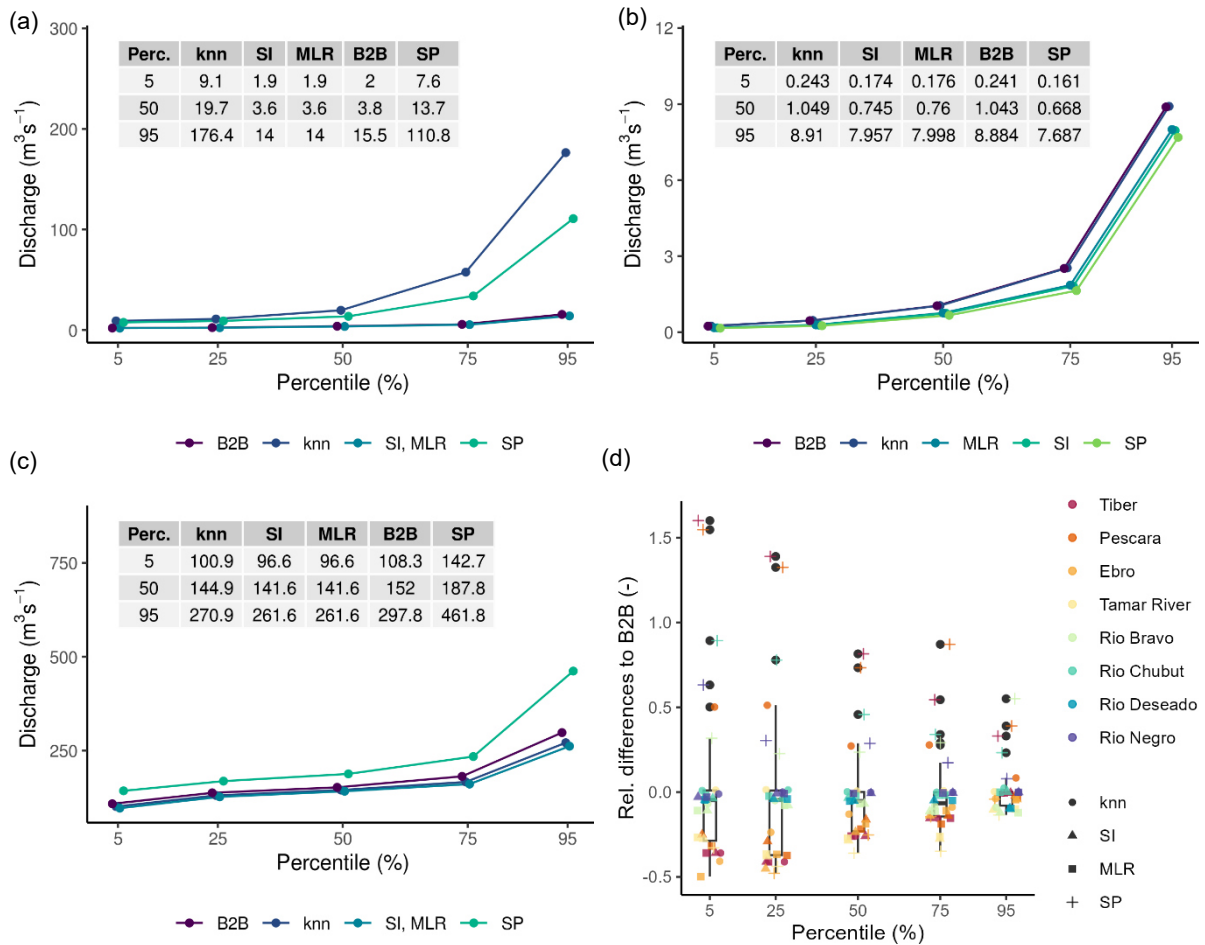
590

591 **Figure 6:** a) Global map of the coefficient of variation in mean yearly discharge for the applied regionalization methods.
 592 Resulting differences in the regionalization ensemble regarding the long-term mean of monthly discharge are depicted
 593 for: b) the Río Bravo in Mexico, c) the Tiber in Italy and d) the Tamar River in Tasmania. The grey-shaded area
 594 indicates the range of the long-term mean of monthly discharge and the black line indicates the mean off all simulation
 595 runs.

596 To gain a deeper understanding of the local impact of regionalization on runoff simulations, we analyze the annual
 597 percentiles from 1980 to 2016 for Río Deseado in Argentina, Río Bravo, and Tamar River, displaying the mean
 598 percentile of all years (see Fig. 7a-c). As the Tiber and Río Bravo display high similarities in the resulting patterns
 599 of percentiles, we demonstrate the impact by showing the percentiles from the Río Bravo. Additionally, we com-
 600 pare the relative differences in the mean for each percentile using eight ungauged river systems (see Fig. 7d), as

601 previously done by Gudmundsson et al. (2012) for nine GHMs. To calculate the relative difference, we subtract
 602 the mean annual percentile of a method from the corresponding mean annual percentile of the reference and divide
 603 the resulting difference by the mean annual percentile of the reference. Instead of using observed flow as a refer-
 604 ence, we use the annual percentiles of our benchmark-to-beat. As river discharge is already spatially aggregated
 605 information, it is unnecessary to spatially aggregate grid cells to create results comparable to those of Gudmunds-
 606 son et al. (2012), who used cell runoff. The evaluated river systems are Río Chubut, Río Deseado, Río Negro, Río
 607 Bravo, Tamar River, Tiber, Pescara, and Ebro.

608



609 **Figure 7: Mean annual percentiles between 1980 and 2016 of simulated discharge using an ensemble of regionalization**
 610 **methods. The rivers are a) Río Deseado, b) Tamar River, and c) Río Bravo. In d), the relative differences in mean annual**
 611 **percentiles to the benchmark-to-beat of eight ungauged river systems are presented. Negative values indicate smaller**
 612 **mean annual percentiles than the benchmark-to-beat. Note that all data points from Río Deseado for knn and SP are**
 613 **excluded as the values are above 2.0.**

614 In Fig. 7a, Río Deseado is highly affected by uncertainties in simulated discharge due to the different regionaliza-
 615 tion methods; all segments of the percentiles show high variations where the absolute spread is increasing with
 616 increasing percentiles. For SP and knn (best), the discharge is highest, e.g., estimating a median discharge of 13.7
 617 $\text{m}^3 \text{s}^{-1}$ and 19.7 $\text{m}^3 \text{s}^{-1}$, respectively. For the other methods, the simulated discharge is low, e.g., SI and MLR result
 618 in an equal median discharge of 3.6 $\text{m}^3 \text{s}^{-1}$. The Tamar River in Fig. 7b also shows increasing absolute differences
 619 between the methods for higher percentiles, with the benchmark-to-beat approach leading to the highest discharge.
 620 For the Río Bravo, the absolute differences between the highest result of SP and the other methods remain almost
 621 constant until the 75th percentile. For the 95th percentile, the absolute differences increase rapidly from about 40

622 m^3s^{-1} (75th percentile) to nearly $200 \text{ m}^3\text{s}^{-1}$ (95th percentile). The exemplary results of Río Deseado and Río Bravo
 623 indicate a potentially high degree of uncertainty regarding the high percentiles in discharge simulation. These
 624 uncertainties put the results of global flood frequency analysis (e.g., Ward et al., 2013) in ungauged regions at risk
 625 as the time series of annual maxima might be even more uncertain. Thus, the results of flood frequency analysis
 626 should be carefully interpreted in ungauged regions as the impact of parameter regionalization may be significant.

627 Upon examination of the relative differences to the benchmark-to-beat for eight ungauged river systems, it be-
 628 comes evident that the impact of regionalization methods varies between ungauged river systems (e.g., Río Negro
 629 exhibits almost no variation, but Ebro does). Moreover, it becomes apparent that some regionalization methods
 630 contribute more to the variation in estimated discharge than others. The methods contributing most are knn (best)
 631 and SP. For knn (best), 10 of the 40 relative differences are higher than |0.3|. For SP, even 29 out of the 40 relative
 632 differences are higher than |0.3|. The results of SI (best) and MLR (best) are very similar, indicating high similarity
 633 in performance. This is consistent with the KGE evaluation (see Chapter 3.3), in which they performed similarly.
 634 The observation in Fig. 7d that higher relative differences of discharge simulations occur in drier percentiles is
 635 also reported in Gudmundsson et al. (2012). Moreover, the relative differences between the five regionalization
 636 runs seem comparable to the inter-model differences depicted in Gudmundsson et al. (2012), indicating the high
 637 impact of regionalization methods on the evaluated ungauged river systems.

638 Finally, Table 3 presents the estimated yearly mean runoff to the ocean for all five ensemble members. All esti-
 639 mates of global "runoff to ocean" range from 45,622 (SI (best)) to 47,069 (SP). Thus, the differences are on the
 640 scale of smaller inter-model differences (see Table 2 in Widen-Nilsson et al., 2007). The impact of regionalization
 641 becomes even more evident using an unsuitable regionalization method for WaterGAP3. For instance, the tuned
 642 kmeans ("subset") approach results in $42,862 \text{ km}^3 \text{ yr}^{-1}$ "runoff to ocean", increasing the spread between the meth-
 643 ods to $4,208 \text{ km}^3 \text{ yr}^{-1}$ being in the scale of inter-model differences. This high impact of regionalization on global
 644 "runoff to ocean" is surprising, given that only 27 % of the world is ungauged, using the GRDC database. From
 645 this 27 %, most regions are in Australia and Africa, where minimal runoff is produced. In studies employing
 646 disparate models, e.g., for inter-model comparison, all regions are simulated in disparate ways.

647 **Table 3: Mean outflow to the ocean and endorheic basins in $\text{km}^3 \text{ yr}^{-1}$ between 1980-2016. The highest continental devi-**
 648 **ation to the benchmark-to-beat is indicated in bold.**

<i>Runoff to ocean¹</i>	B2B	SI (best)	knn (best)	MLR (best)	SP
Oceania	1,127	-1.80 %	-2.20 %	-3.40 %	-6.60 %
Europe	3,098	-2.30 %	-0.10 %	-2.60 %	0.20%
Asia	16,676	3.50 %	0.30 %	1.60 %	5.50 %
Africa	5,203	-1.00 %	0.70 %	-0.30 %	-3.60 %
North America	7,517	0.30 %	1.00 %	-1.70 %	2.20 %
South America	12,032	1.30 %	1.40 %	-0.20 %	4.90 %
global	45,653	46,273	45,953	45,622	47,069

¹including endorheic basin

649
 650 The most significant deviations in the continental sums of "runoff to ocean" in Table 3 are due to SP. Only for
 651 Europe is the highest deviation related to MLR (best), not SP. Interestingly, the estimated sums of SP occasionally
 652 define the lowest and occasionally the highest extremes for the continents, lacking a systematic pattern. The out-
 653 standing role of SP is consistent with previous evaluations in this Chapter, where SP frequently contributes most

654 to the variation in discharge. This suggests that SP may not be suitable for the global scale. Nevertheless, the
655 pseudo-ungauged basins in the split-sample tests may also exhibit considerable distances from the observed basins.
656 Given that SP achieved satisfactory results in both evaluations, using either the logMAE or the KGE, the evaluation
657 indicates the method's suitability on a global scale. Thus, in the future, the split-sample test must be extended to
658 gain deeper insights into the method's robustness and make a definitive statement about the method's suitability
659 on a global scale. For example, the so-called "HDes" approach, recommended by Lebecherel et al. (2016), could
660 be applied for this purpose. In this approach, the closest basin to the corresponding (pseudo-) ungauged basin is
661 excluded from the regionalization process, thereby enabling an assessment of the method's robustness.

662 **3.5 Challenges & Future Directions**

663 Regionalization is an inevitable step when parameterizing GHMs. However, only a few studies exist that conduct
664 regionalization experiments with GHMs, often focusing on a single or two distinct regionalization strategies (e.g.,
665 Beck et al., 2016; Beck et al., 2020; Yoshida et al., 2022). A significant challenge in developing and testing dif-
666 ferent regionalization methods for GHMs is the time-consuming runtime of these models. This extensive runtime
667 impedes comprehensive testing of different regionalization methods, as evaluating the regionalization methods,
668 e.g., by using streamflow, demands a considerable number of simulation runs. This study addressed this challenge
669 using the differences between calibrated and regionalized parameter values as an approximator for the suitability
670 of the regionalization methods. Thereby, we considered the varying sensitivity of the parameter within the param-
671 eter space using the logMAE as the evaluation criterion. Using the differences between calibrated and estimated
672 values is the most straightforward approach, given that WaterGAP3 uses a single calibration parameter, leading to
673 a clear global optimum. However, this approach might not apply to GHMs using multiple calibration parameters
674 due to equifinality. For example, Ayzel et al. (2017) found varying estimated parameter values when regionalizing
675 11 parameters of the SWAP model using different regionalization methods. They concluded that the difference
676 between regionalized and calibrated values cannot be regarded as a performance measure due to parameter com-
677 pensation. Thus, further research is required to tackle the challenge of GHMs' time-consuming runtimes to enable
678 comprehensive testing of regionalization methods, especially for GHMs using multiple calibration parameters.

679 Another challenge in regionalizing hydrological models is the optimal selection of predictors for the regionaliza-
680 tion methods. Various approaches exist regarding the predictor selection for the regionalization methods (Razavi
681 & Coulibaly, 2013), resulting in a lack of consensus. This study used a predictor selection based on correlation
682 coefficients and an entropy assessment. The results indicate that the approach is particularly well-suited to the
683 Similarity Indices. However, further research on predictor selection is needed to find the optimal descriptor set
684 per method, as regionalization methods use predictors with varying efficiency. For example, future studies might
685 integrate feature importance bars, e.g., by using permutation, to identify the most critical descriptors per method.

686 Moreover, future research should explicitly account for the issue of multicollinearity. Multicollinearity can affect
687 MLR (and potentially other techniques), resulting in ungeneralizable predictions. This phenomenon is more
688 likely to occur when the number of predictor variables is large relative to the number of observation units and
689 when the predictor variables are highly collinear (Kiers & Smilde, 2007). To account for the high importance of
690 the generalizability of regionalization methods for GHMs, we used a high proportion of the basins for testing,
691 i.e., 50 %. Moreover, we used a large sample size (50 % of 933 basins) relative to the number of predictors
692 (maximum 12), lowering the risk of multicollinearity interfering with the results. However, future studies might

693 use methods such as Principal Component Analysis (PCA) or Partial Least Square (PLS), explicitly accounting
694 for the issue of multicollinearity (e.g., Kroll & Song, 2013). An alternative approach to using PCA or PLS is ex-
695 plicitly testing for multicollinearity in predictor sets using the variance inflation factor and avoiding using pre-
696 dictors with values exceeding a pre-defined threshold (e.g., Kroll et al., 2004).

697 **4. Conclusion**

698 Valid simulation results from GHMs, such as WaterGAP3, are crucial for detecting hotspots or studying patterns
699 in climate change impacts. However, the lack of worldwide monitoring data makes adapting GHMs' parameters
700 for valid global simulations challenging. Therefore, regionalization is necessary to estimate parameters in un-
701 gauged basins. This study applies regionalization methods for the first time to WaterGAP3, aiming to provide
702 insights into selecting suitable regionalization methods and evaluating their impact on the runoff simulations. Tra-
703 ditional and machine learning-based methods are tested to assess the application of several regionalization tech-
704 niques on a global scale. The concept of benchmark-to-beat and an ensemble of split-sampling tests are employed
705 for a comprehensive evaluation. Moreover, the impact on runoff simulation is assessed using a wide range of
706 temporal and spatial scales, i.e., from the daily to the yearly and from the local to the global scale.

707 In this study, four regionalization methods outperform the benchmark-to-beat in monthly KGE and are thus con-
708 sidered appropriate for WaterGAP3. These methods span the complete range of methodologies, i.e., regression-
709 based methods and methods using the concept of physical similarity and spatial proximity. Moreover, the methods
710 vary in the descriptors used to achieve the highest accuracy. This highlights that different methods use descriptor
711 sets with varying efficiency. All methods perform best when using climatic and physiographic descriptors, indi-
712 cating that combining climatic and physiographic descriptors is optimal for regionalizing worldwide basins.
713 Mainly for two selected regionalization methods (tuned MLR and knn), the suggested descriptor selection based
714 on correlation coefficients and entropy assessment is not optimal. Further research might integrate variable im-
715 portance scores or PCA to enhance the predictor selection. Although random forest is known to be especially
716 robust among other machine learning-based techniques, it shows symptoms of over-parameterization, indicating
717 that the algorithm is too flexible and adjusts to noise in the data, missing the underlying systematic pattern.

718 Our results demonstrate that variation in the regionalized parameter value does not necessarily lead to variation in
719 river discharge. However, it increases the likelihood that a region's runoff is affected. This spatially varying impact
720 of γ is likely related to the varying sensitivity in ungauged regions regarding γ . Southern South America is a region
721 identified to be especially sensitive to variation in γ . Furthermore, local effects on runoff simulations indicate a
722 temporally varying impact. For example, some impacted rivers indicate a high degree of uncertainty regarding the
723 high percentiles in discharge simulation. These uncertainties potentially lead to a significant impact on flood fre-
724 quency analysis on a global scale, where the lack of gauging stations in certain regions calls for regionalization.
725 The global impact of regionalization methods that perform well for WaterGAP3 appears to be in the order of minor
726 inter-model differences. This impact rigorously increases when using a poorly performing method for WaterGAP3,
727 underscoring the importance of carefully selecting regionalization methods.

728 The spatial proximity approach contributes most to the variation in estimated runoff. The outstanding role of this
729 approach suggests that it may not be suitable for the global scale. However, as the pseudo-ungauged basins in the
730 split-sample tests may also have considerable large distances to the observed basins, and the method achieves

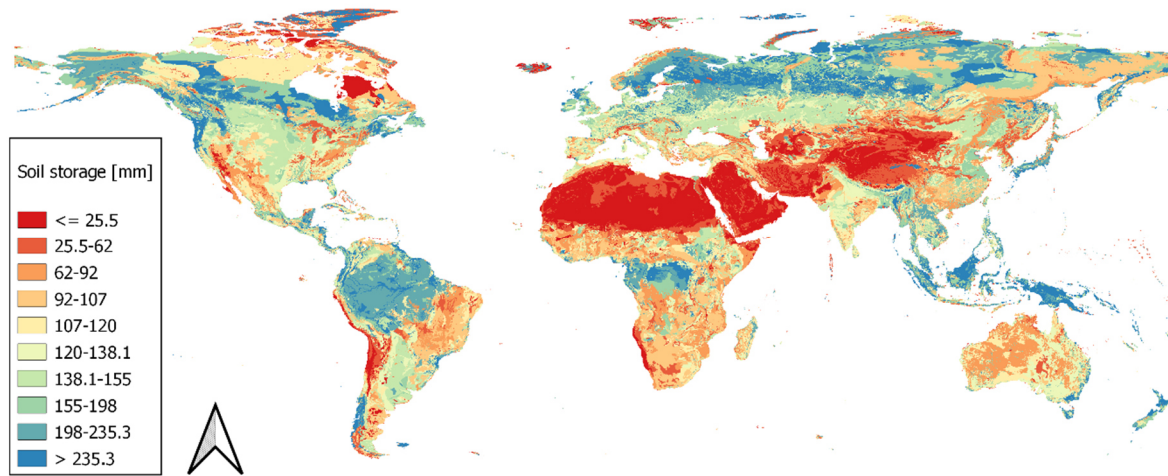
731 satisfactory results in all executed evaluations, it is not possible to make a definite statement about the method's
732 suitability for the global scale. Further research is required to gain deeper insights into the methods' robustness,
733 e.g., by extending the analysis by applying the recommended "HDes" approach (Lebecherel et al., 2016).

734 *Code and data availability.* The data and the supporting R-Code to reproduce this study's findings are available at
735 <https://doi.org/10.5281/zenodo.12808527>.

736 *Authors contribution.* JK developed, designed, and drafted the study. NK helped to design the experiment. MF
737 provided feedback throughout the entire process and supported the writing.

738 *Competing interests.* The authors declare that they have no conflict of interest.

739 **Appendix A: Global Map of derived global soil moisture storage**



740

741 **Figure A1: Global map of the size of soil storage based on Batjes (2012) and land use information (derived from Friedl**
742 **& Sulla-Menashe, 2019)**

743

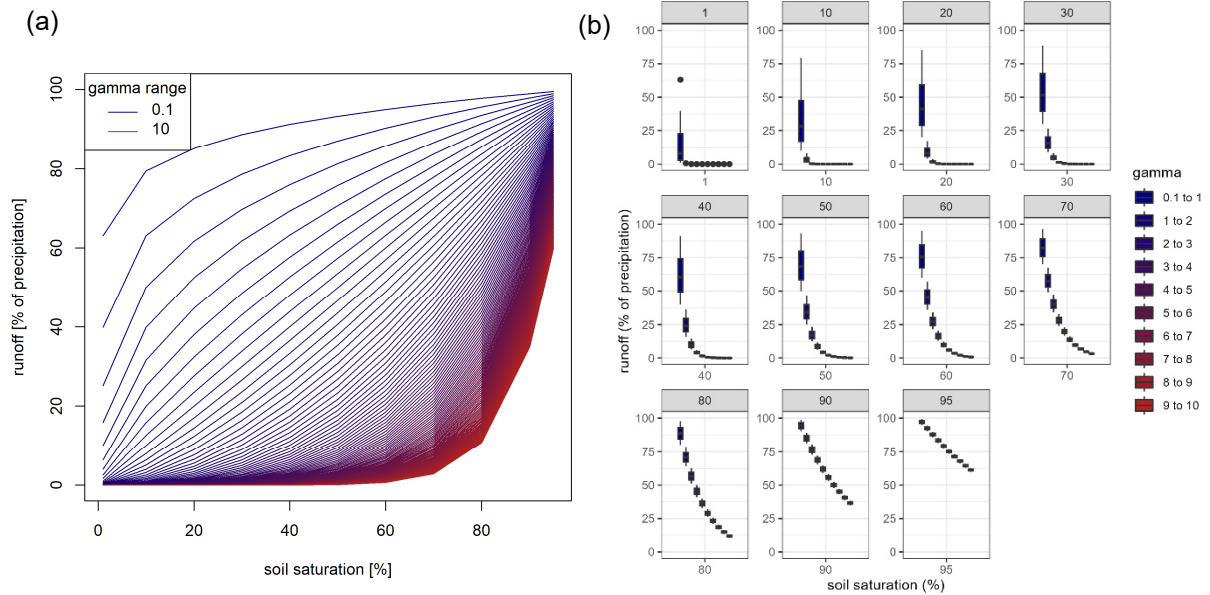
744 **Appendix B: Further analysis regarding the clustering of parameter values at the extremes**

745 The clustered calibrated parameter values at the extremes of the valid parameter space (see Fig. 1b) are a known
 746 problem within the calibration. As the parameter space, i.e., the parameter bounds, is crucial for calibration and,
 747 in consequence, for regionalization, we address this issue by a brief sensitivity analysis to demonstrate that the
 748 clustering of the calibrated parameter values is more an issue of missing processes (or using additional parameter
 749 values) than an issue of inappropriate parameter space. As the lower limit of the calibrated parameter (0.1) is
 750 sufficiently small in comparison to other studies using a similar HBV-based approach for runoff generation pro-
 751 cesses (e.g., see the beta in Table A2 in Jansen et al., 2022), we focus on the sensitivity analysis on the upper limit
 752 of γ (5.0).

753 In the sensitivity analysis regarding the upper limit of γ , we applied the model formula (see equation B1) containing
 754 the model's parameter γ and modified it within the bounds of 0.1 and 10. Additionally, we modified the soil satu-
 755 ration varying from 1 % to 95 %.

$$outflow = precipitation_{effective} \cdot soil\ saturation^{\gamma} \quad (B1)$$

756 The calculated outflow and its relationship to the soil saturation and γ are depicted in Fig. B1 and B2. The incoming
 757 effective precipitation is defined as constant. As it is a factor in equation B1,, the results regarding incoming
 758 effective precipitation are linearly scalable.



759 **Figure B1: a) Runoff generation in the soil layer (neglecting overflow and evapotranspiration) using different values**
 760 **for the calibration parameter and increasing the soil-moisture, b) runoff generation for varying soil moisture grouped**
 761 **in bins of size one.**

762 In the depicted Fig. B1, the runoff generation process differences between differing γ values become more linear
 763 when soil saturation increases. Thus, the non-linear model parameter becomes less critical for high soil moisture.
 764 Generally, the runoff generation process differences for higher γ values are more pronounced for higher soil mois-
 765 ture. For lower soil moisture, the smaller values have higher effects on the generated runoff. For example, for 70 %
 766 soil moisture, the differences for γ values ranging from 5 to 10 are between 3 % and 16 %. For the same soil
 767 moisture, the range in runoff generation varies from 16 % to 70 % for γ values between 1 and 5.

768 High γ values usually occur in dry regions (see Fig. 4b in Müller Schmied et al., 2021). In dry regions, high soil
769 moisture values are not expected to occur frequently (e.g., see Khosa et al., 2020; Oloruntoba et al., 2024 for
770 estimated and measured soil moisture in Africa and Draper et al., 2008 for estimated and measured soil moisture
771 in Australia). It is, therefore, unlikely that higher γ values will significantly enhance the calibration result or de-
772 crease the issue of clustered calibrated parameter values at the higher end of the parameter space. More likely, the
773 clustering of calibrated parameter values will be resolved in dry regions by incorporating additional (missing)
774 model processes, such as evaporation from rivers or inaccurate representation of groundwater processes (Eisner,
775 2016, p. 49). Thus, the parameter bounds of γ (e.g., also used in Eisner 2016, p. 16; Müller Schmied et al., 2021;
776 Müller Schmied et al., 2023) are not changed in this study.

777 **Appendix C: Basin descriptors**

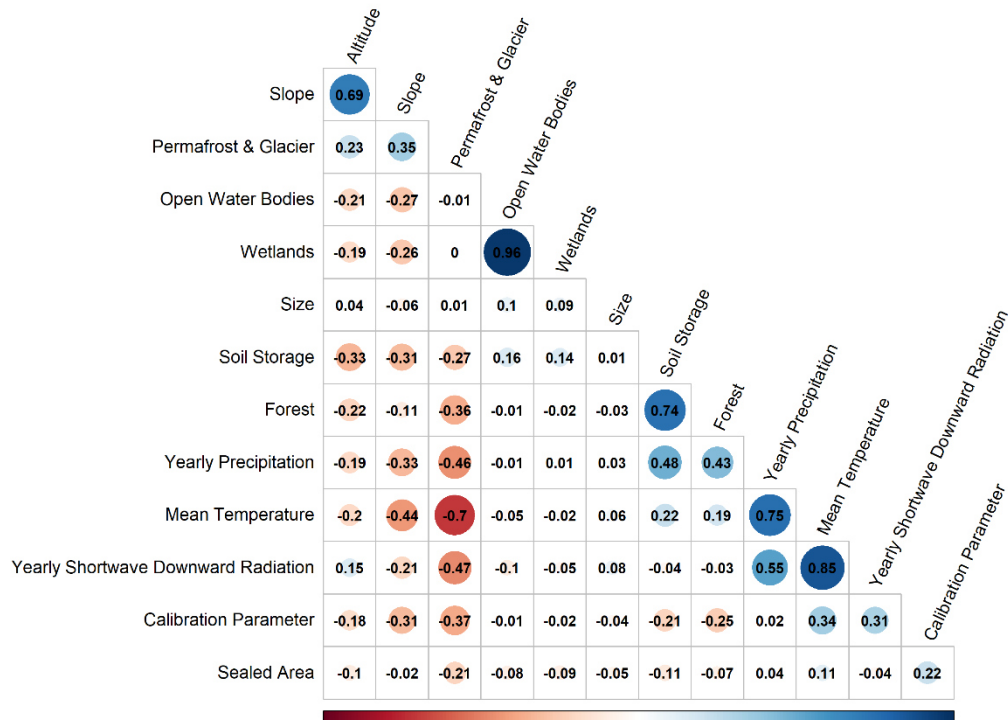
778 Overview of basins descriptors used in this study. All basin descriptors are derived from the original model input
779 and aggregated with a simple mean method to basin values to produce the same spatial resolution as the calibrated
780 model parameter.

- 781 • *Soil Storage*: The size of the soil storage, i.e., the maximal water content in the soil reachable for plants
782 in mm. The information is the product of rooting depth (defined in a look-up table) and the total available
783 water content derived from Batjes (2012).
- 784 • *Open Water Bodies*: The fraction of the area covered with open water bodies in the basin is given as a
785 percentage. The model input is based on the GLWD database (Lehner & Döll, 2004).
- 786 • *Wetlands*: The fraction of area covered with wetlands in a basin is given in percentage. The model input
787 is based on the GLWD database (Lehner & Döll, 2004).
- 788 • *Size*: Size of a basin in km².
- 789 • *Slope*: The mean slope class is calculated as described in Döll & Fiedler (2008) and based on GTOPO30
790 (USGS EROS data centre).
- 791 • *Altitude*: The mean altitude of a basin is given in meters above sea level and based on GTOPO30 (USGS
792 EROS data centre).
- 793 • *Forest*: The mean fraction of the area covered with forest is given in percentage and derived from MODIS
794 data (Friedl & Sulla-Menashe, 2019), where 2001 is used as a reference. All grid cells having a dominant
795 International Geosphere-Biosphere Programme (IGBP) classification between one and five are defined
796 as "forest".
- 797 • *Sealed Area*: The mean fraction of sealed area is given in percentage and derived from MODIS data
798 (Friedl & Sulla-Menashe, 2019), where 2001 is used as a reference. All grid cells having an IGBP clas-
799 sification equal to 13 are defined as they would contain 60% of the sealed area. Note: The different treat-
800 ment of forest and sealed area is based on the required model input; whereas the land cover is a classified
801 value, the sealed area is a floating-point value.
- 802 • *Permafrost & Glacier*: The mean coverage of permafrost and glacier in a basin is given in percentage. It
803 is based on the World Glacier Inventory and the Circum-Arctic Map of Permafrost and Ground-Ice Con-
804 ditions.
- 805 • *Mean Temperature*: The mean air temperature is based on the meteorological forcing used to drive the
806 model (Lange, 2019) covering the period 1979 to 2016 and given in degrees Celsius.
- 807 • *Yearly Precipitation*: The yearly precipitation sum is based on the meteorological forcing used to drive
808 the model (Lange, 2019) covering the period 1979 to 2016 and given in mm.
- 809 • *Yearly Shortwave Downward Radiation*: The yearly shortwave downward radiation is based on the me-
810 teorological forcing used to drive the model (Lange, 2019) covering the period 1979 to 2016 and given
811 in Wm⁻².

812

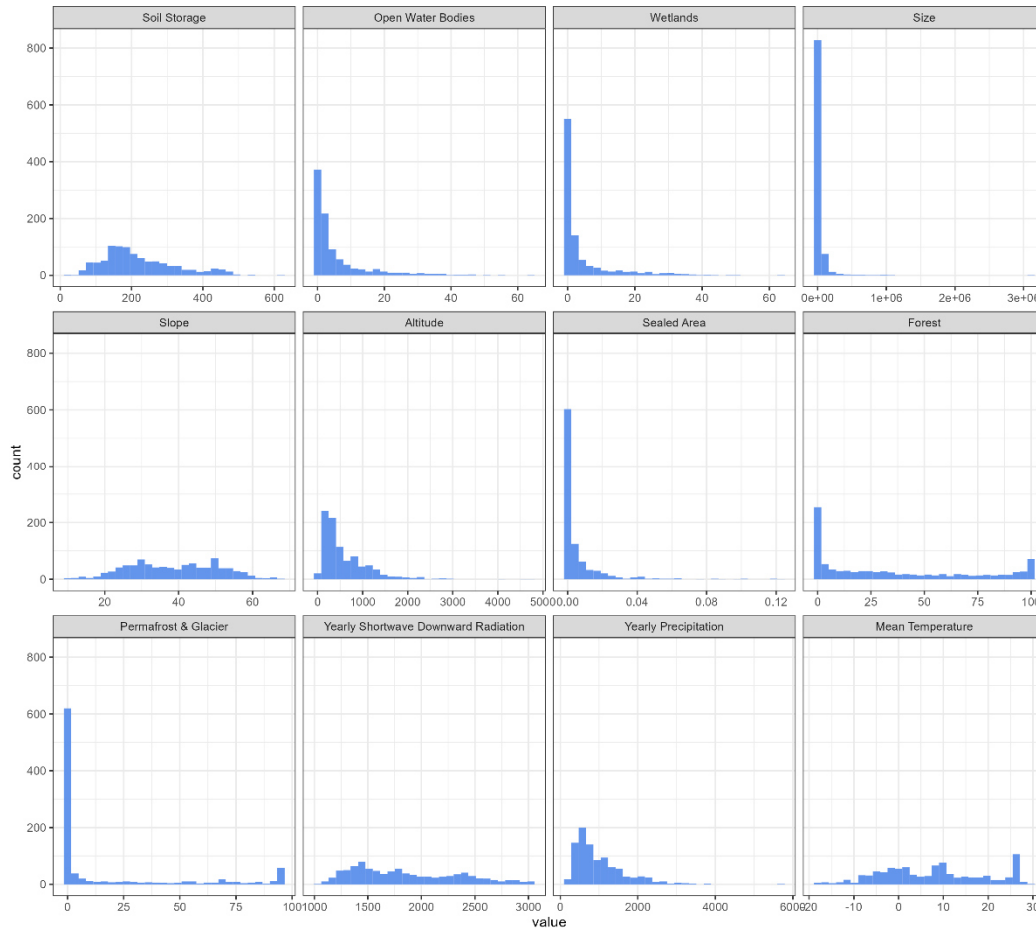
813 The correlation between the defined basin descriptors is shown in Fig. A1. The variation within each basin de-
814 scriptor for basins used for regionalization is shown in Fig. A2.

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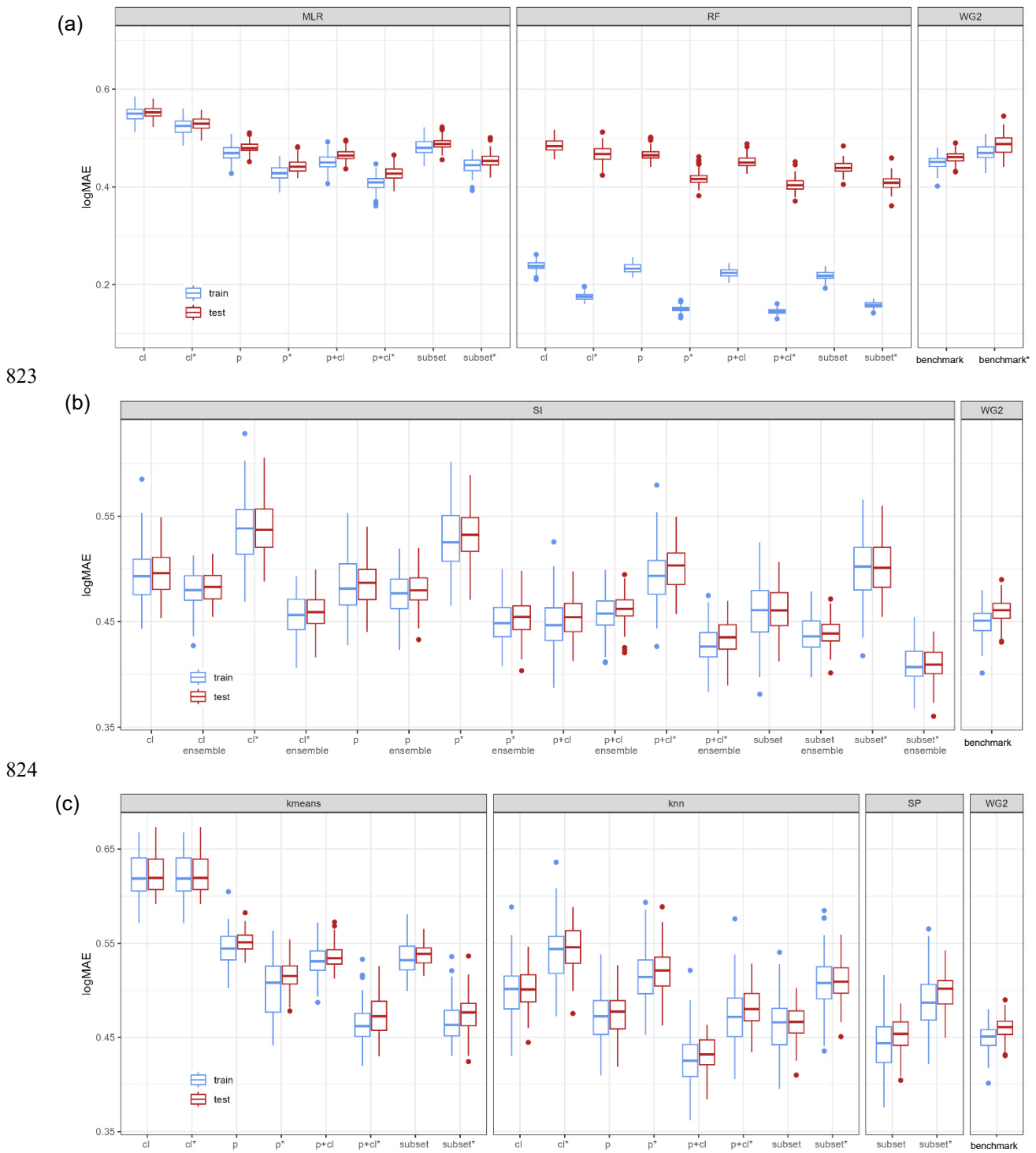
Figure C1: Correlation (using Pearson's correlation) between basins descriptors.



820
821

Figure C2: Distribution of basins descriptors within all basins used for regionalization (n=933)

822 **Appendix D: Results of the ensemble of the split-sample tests**



826 **Figure D1: logMAE values for all 100 split-sampling tests using all variants of a) MLR, RF, and benchmark-to-beat,**
 827 **b) SI, and c) kmeans, knn, and SP. Note that the asterisk * indicates the tuned version of the method.**

828

829 **Table D1: Performance loss in median logMAE of the ensemble of split-sample tests from training to testing expressed**
 830 **in % of logMAE in training.**

test (% train)	MLR	RF	SI		kmeans	knn	SP	B2B
			no ens.	ensem- ble				
cl	100.4	202.9	100.6	100.6	100	100	102.3	102.2
p	102.1	199.6	101.2	100.6	101.3	101.1		
p+cl	103.1	207.1	101.6	100.9	100.6	95.6		
subset	101.7	223.9	100	100.7	101.3	100.2		

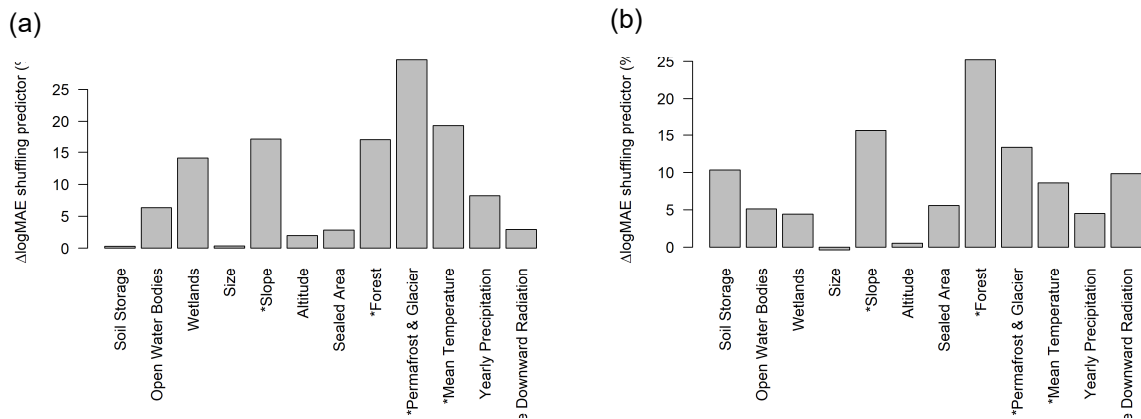
test* (% train*)	MLR	RF	SI		kmeans	knn	SP	B2B
			no ens.	ensem- ble				
cl	100.8	266.9	99.8	100.7	100	100.4	103.1	104.1
p	103	277.3	101.3	101.3	101.4	101.4		
p+cl	104.4	277.9	102	102.1	102.2	101.7		
subset	102	258.2	99.8	100.5	103	100.2		

831

832

833 **Appendix E: Feature importance bars for MLR (best) and knn(best) using the descriptor set "p+c1"**

834



835

836 **Figure E1: Decrease in logMAE for testing using one representative split-sample when randomly shuffling each pre-**
 837 **dictor for a) MLR (best) and b) knn (best). Note that the asterisk indicates the basin descriptors used in the (weakly)**
 838 **correlated subset.**

839

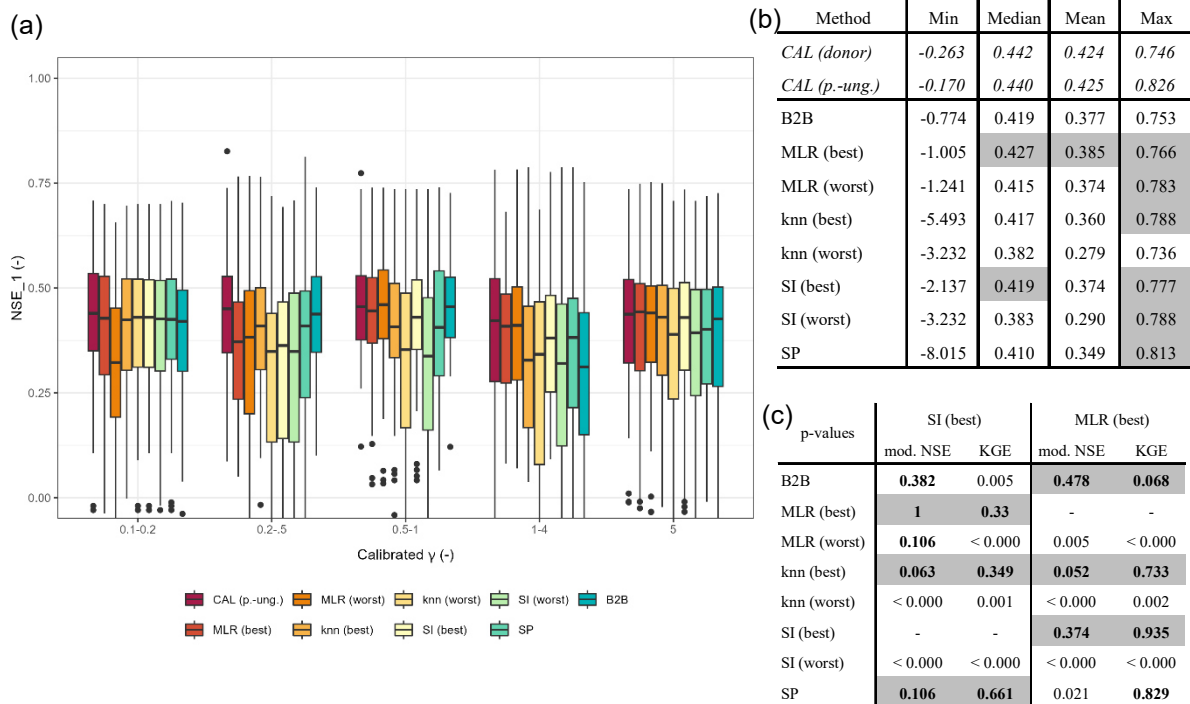
840 **Appendix F: Model performance for pseudo-ungauged basins using a modified version of the NSE**

841 Krause et al. (2005) suggested a modified version of the NSE that is especially suitable as an overall metric, leading
 842 to results between NSE versions focusing on low and high flows. The applied equation for the modified version is
 843 given below (see Eq. F1).

844
$$\text{modified NSE} = 1 - \frac{\sum |y_k - x_k|}{\sum |y_k - \mu_y|} \quad (F1)$$

845 where x_k is the simulated monthly discharge for the timestep k and y_k is the observed discharge for the timestep
 846 k , and μ_y is the mean of the discharge for the evaluated period.

847 The evaluation of the modified NSE for all pseudo-ungauged basins of a representative split-sample are summa-
 848 rized in Figure F1. Note that the figure includes also the results of the applied one-sided paired Wilcoxon rank
 849 sum test for the KGE values, mentioned in Section 3.3.



850 **Figure F1: a) modified NSE values of pseudo-ungauged basins from split-sample test grouped by the range**
 851 **of calibrated γ values, b) selected metrics of modified NSE values from the pseudo-ungauged basins (bet-**
 852 **ter or equal performance to the benchmark-to-beat is highlighted in grey), and c) p-values of the one-sided**
 853 **paired Wilcoxon rank sum test, testing the best performing methods MLR (best) and SI (best) against all**
 854 **other regionalization methods. (Note that p-values greater than 0.05 are highlighted in bold, indicating**
 855 **that the null hypothesis cannot be rejected, thus the difference in central tendency is not statistically sig-**
 856 **nificant; cases where the results of modified NSE and KGE indicate the same are shaded grey.)**

857

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