The authors would like to thank the editor and the referee’s comments on our manuscript. Following the comments, we make the following replies and corresponding revisions to the manuscript. Each item of the original comments from the referee is in green italic, followed by our reply. Moreover, in the marked version of the revised manuscript, the revisions are highlighted with 'REV2'.

REVIEW 2

This manuscript is technically sound, offers a new code likely to be of wide interest within the sea ice modeling community, and presents compelling results to clear up an unresolved question in previous sea ice model intercomparison projects. There were a number of issues left hanging, for example, in the works of Bouchat et al. (2022) and Hutter et al. (2022) for the Sea Ice Rheology Experiment (SIREx). One of the issues was the somewhat nebulous role of the ocean in the modeled sea ice deformation statistics. That remains unresolved in this work, since a simple mixed layer ocean has been used to generate sea ice deformation statistics. The second unresolved issue was the difficulty in consistently accounting for deformation across Lagrangian and Eulerian models, which is a problem this paper addresses. The scientific results are excellent and worthy of publication. The issues I found amount to relatively minor edits and additions: 1) English in this paper needs a thorough proofing; 2) Some math notation should be aligned with existing sea ice literature; 3) I suggest editing the methods section so there can be no doubt this paper concerns a diagnostic tool rather than one influencing the physics of CICE; 4) In the presentation of results, please give consideration to a figure that would convey key climatological circulation features of the Arctic to help provide visual proof that your tool works correctly; and finally 5) perhaps most importantly for GMD, please make sure the Zenodo code base provides everything needed in CICE to reproduce results documented in this paper. I provide further details here:

Reply: we sincerely thank the referee for the comment about our paper addressing the Eulerian and Lagrangian diagnostics for sea ice deformations. Regarding the first aspect of the ocean dynamics’ role in modulating sea ice deformations, we also plan to carry out a detailed study on this issue in the coming future with the Lagrangian tracking framework introduced in this paper.

According to the referee’s suggestions, we revise the paper in several ways. First, an overall for better language usage is carried out. Second, figures and presentation in the methods section are revised to be clear of the role and validity of the Lagrangian tracking framework. Also math notations are re-checked and revised accordingly, so that they are in accordance with what is usually in the community. Third, the whole CESM/CICE version is provided through Zenodo, which is the codebase that the newly developed Lagrangian tracking is based upon, at: https://zenodo.org/records/12200190. The manuscript is revised accordingly.
Lexicon:

Here are examples of the issues I noticed in my reading with English grammar and notation:

- **Sea ice deformation should not be pluralized** (i.e. deformation not deformations)

  **Reply:** corrected.

- **Change:** “Since they drift with the sea ice, their locations are also representative of the sea ice floe they are attached to” to “Since they drift with the sea ice, their locations are also representative of the sea ice floe to which they are attached”. (line 30)

  **Reply:** corrected.

- **Pluralize “sea ice dynamic” to “sea ice dynamics”**.

  **Reply:** corrected.

- **Instead of denoting deformation rates as 's, please use the correct mathematical expression for these rates to be consistent with existing sea ice rheological literature.**

  **Reply:** corrected to $\dot{\epsilon}$ for all relevant cases.

- **Change “…are capable to reproduce certain…” to “…are capable of reproducing certain…”**. (line 55)

  **Reply:** corrected.

- **“It is worth to note…” should be changed to “It is worth noting…”** (line 155)

  **Reply:** corrected.

*Please carefully proof the entire document to address similar English grammar issues.*

**Reply:** we have carried out an overhaul of the manuscript to improve the English language use.
Methods:

The methods section is well explained, and I suggest only needs minor edits:

- For section 2.2.1, please consider a section title more useful than “Basic Support”. “Software implementation” may be more descriptive.

Reply: changed to “Software implementation”.

- In Figure 3, the “Lagrangian Tracking” box would suggest that somehow the tracking is instrumental in the physics of your version of CICE, when it’s actually a diagnostic but not prognostic tool. I suggest the “Lagrangian Tracking” box should be shifted to the side of and outside of the step_dynamics box so that there can be no confusion on this point.

Reply: we would like to clarify the current layout of the schematic plot is to show clearly when the Lagrangian tracking is carried out. According to the referee’s suggestion, we move the step of Lagrangian tracking outside the step_dynamics box to be more clear about the diagnostic nature of the Lagrangian tracking in the model. The updated figure is shown below:

Results:

There are a number of issues that should be addressed in the graphical presentation of your results:

- The color scale in Figure 5 is smooth to the point of deception. It appears that there is a significant problem with your thickness field in that you have near zero thickness in patches surrounding the North Pole. I may have missed it, but you appear to have omitted any comment about this problem. The problem does not preclude publication, and is almost certainly an artifact of your forcing, but please comment on the cause of this.
Reply: we thank the referee for pointing out this issue, and we would like to make the following clarifications over the numerical experiments and corresponding revisions:

First, the modeled sea ice thickness field is highly dependent on the sea ice strength parameterization scheme. The R75 scheme (Rothrock, 1975) is usually shown to simulate poorer sea ice climatology than H79 (Hibler, 1979), although R75 is arguably more physics-based. Both schemes are provided by CICE and used by various studies, and the comparison between them also reported by many [such as Ungermann et al. (2017)], and by our previous study as well [Xu et al. (2021), see also the figure below]. In this study, we choose R75 mainly because it relates the ice strength to the amount of work during ridging, despite the fact that it usually performs poorer than H79 in terms of modeled climatology. One particular apparent shortcoming of R75 in the NYF-based experiments is the hoarding of thick ice in the Beaufort Gyre system and too thin ice in the Nansen Basin (as shown in our Fig. 5 and pointed out by the referee). We consider that this is due to a series of complex issues, including the fact that the CICE model cannot melt away thick, deformed ice effectively as observed (Evgenii et al, 2023). This issue is definitely worth further investigating, especially the role of external factors (i.e., forcing and coupled process) as well as internal processes to CICE (i.e., strength parameterization, etc).

![Figure. Quasi-equilibrium March sea ice thickness with R75 (left) and H79 (right) ice strength parameterization in the CICE simulations based on NYF and slab-ocean. All other model configurations are kept the same. Hoarding of thick ice in the Beaufort Sea is apparent in the run with R75.](image)

Second, although the model simulates different sea ice thickness fields with R75 and H79, the wintertime sea ice extent are both consistent with the satellite-based climatology. During summer, the difference is more pronounced and apparent, due to the sea ice loss in the Atlantic sector and the relatively thinner ice to start with from the
beginning of the melt season. We want to emphasize that: the sea ice drift is mainly
driven by atmospheric forcing (i.e., winds), and the result of this study does depend on
the sea ice strength parameterization. However, which strength scheme simulates better
sea ice deformation is beyond the scope of this study, since the introduction of
Lagrangian tracking is our focus here.

Third, regarding the suggestion to improve the figure’s readability, we have revised the
colormap to make it more readable across all thickness ranges. We apologize for the
inconvenience that might have been caused, and we would like to clarify that it was not
chosen on purpose.

References:


Ungermann, M., Tremblay, L. B., Martin, T., and Losch, M.: Impact of the ice strength

Xu, Shiming, Jialiang Ma, Lu Zhou, Yan Zhang, Jiping Liu, and Bin Wang: Comparison of
sea ice kinematics at different resolutions modeled with a grid hierarchy in the
Community Earth System Model (version 1.2.1), Geosci. Model Dev., 14, 603–628,

• You have a wonderful Lagrangian tracking tool, but at no point in the
manuscript do you make use of it to show streamlines exceeding two weeks
in length. Rather than just a novelty, it is essential to show at least seasonal
tracks for proof that your tracking system is able to perceive the most basic of
circulation features of the Arctic: the Beaufort Gyre and the Transpolar drift. I
recommend including a separate figure accompanying Figure 6 with seasonal
breakdowns of a less dense sub-selection of the tracer points in that figure.
Without this, it is very difficult to make sense of, for example, Figure 6(b).

Reply: according to the referee’s comment, we have included another figure after Figure
6 (now the new Figure 7). This figure shows two-months SLP and Lagrangian points’
tracks for both November-December and February-March. Data are from the same
experiment (specifically, the second year of the G16 simulation under NYF). This new
figure (shown below) should establish the concept that the Lagrangian tracking is
working as intended.
Figure. Sea-level pressure (SLP) and the tracks of Lagrangian points for two bi-monthly periods: November-December (left) and February-March (right) for the NYF-based simulation with the GX1V6 grid. The tracks during the second year of the Lagrangian tracking are shown.

**Code and Model Specifics relevant to GMD:**

Information provided in Appendix A offers far from an exhaustive list of model parameters in CICE, and it's difficult to understand why only some default constants and parameters are listed. Either make the table exhaustive of the model parameter space, or only show parameters you have changed from the default CESM version 2 code base, and state so. Please ensure, that a namelist for the model is available, or make it clear that the CICE namelist remains unchanged from CESM.

**Reply:** we revise the manuscript to include a more exhaustive list of relevant model parameters. Also, a namelist is provided as a supplementary file for the GX1V6 experiment.

It appears that in the Zenodo link you have provided, only the subroutines needed to be switched out in the CESM code are given. However, the CESM code is a GitHub release, and therefore subject to change. My understanding is that GMD, like other journals, now requires a stable and orphaned code base rather than a link subject to institutional change. As your Zenodo link currently stands, one could not take that code and preproduce the results in this paper without reliance on NCAR. That needs to be fixed.

**Reply:** according to the suggestion from the referee, we have archived the CESM codebase on Zenodo, alongside the new code we have added. The link is publicly
available at: https://zenodo.org/records/12200190. The manuscript is also revised to include the updated link.

References


Reply: these 2 references are already cited at relevant locations of the manuscript.