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**Assimilation of snow water equivalent from AMSR2 and IMS
satellite data utilizing the local ensemble transform Kalman filter**

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~~29 July~~ 20 SEP 2024

To be submitted to GMD

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24 **Abstract**

25 Snow Water Equivalent (SWE), as one of the land initial or boundary conditions, plays a
26 crucial role in global or regional energy and water balance, thereby exerting a considerable
27 impact on seasonal and sub-seasonal scale predictions owing to its enduring
28 memory persistence over 1 to 2 months. Despite its importance, most SWE initialization
29 remains challenging due to its reliance on simple approaches based on spatially limited
30 observations. Therefore, this study developed the advanced SWE data assimilation framework
31 with satellite remote-sensing data utilizing the local ensemble transform Kalman filter (LETKF)
32 and the Joint U.K. Land Environment Simulator (JULES) land model. This approach
33 constitutes an objective method that optimally combines two previously unattempted
34 incomplete data sources: the satellite SWE retrieval from the Advanced Microwave Scanning
35 Radiometer 2 (AMSR2) and dynamically-balanced SWE from the JULES land surface model.
36 In this framework, an algorithm is additionally considered to determine the assimilation process
37 based on the presence or absence of snow cover from the Interactive Multisensor Snow and Ice
38 Mapping System (IMS) satellite, renowned for its superior reliability.

39 The baseline model simulation from JULES without satellite data assimilation shows better
40 performance in high-latitude regions with heavy snow accumulation but relatively inferior in
41 the transition regions with less snow and high spatial and temporal variation. Contrastingly, the
42 AMSR2 satellite data exhibit better performance in the transition regions but poorer in the high
43 latitudes, presumably due to the limitation of the satellite data in the penetrating depth. The
44 data assimilation (DA) demonstrates the positive impacts by reducing uncertainty in the JULES
45 model simulations in most areas, particularly in the mid-latitude transition regions. In the
46 transition regions, the model background errors from the ensemble runs are significantly larger
47 than the observation errors, emphasizing great uncertainty in the model simulations. The results
48 of this study highlight the beneficial impact of data assimilation by effectively combining both

49 land surface model and satellite-derived data according to their relative uncertainty, thereby
50 controlling not only transitional regions but also the regions with heavy snow accumulation
51 that are difficult to detect by satellite.

52

53 **1. Introduction**

54 Snow plays a crucial role in regulating the water, energy, and carbon exchange between the
55 land surface and atmosphere (e.g., Dutra et al., 2011; Thomas et al., 2016). A snowpack tends
56 to increase surface albedo and soil moisture as the snow melts (Eagleson,1970), thereby
57 affecting the climate system through changes in water and energy balances. In addition to local
58 impacts, the continental snowpack over Eurasia can influence the large scale atmospheric
59 circulation during winter (e.g., Li and Wang, 2014) or in spring (e.g., Broxton et al., 2017).
60 Especially, the Eurasian autumn snow can affect upward-propagating stationary Rossby-wave
61 activity, leading to stratospheric warming and weakening of stratospheric polar vortex and jet
62 stream, which in turn emerges as a negative Arctic oscillation (AO)-like pattern at the surface
63 during winter due to downward propagation through the troposphere. Its impact is shown in
64 both observation and model experiments (e.g., Allen and Zender 2011; Cohen et al. 2007).
65 Furthermore, the interannual variability of snow melting during the boreal spring season affects
66 surface soil moisture in summer, which has important implications for heatwave development
67 and emphasizing mechanisms through land-atmosphere interactions (Seo et al., 2020).

68 In the subseasonal to seasonal (S2S) timescales, land initial states are crucial components
69 in the S2S timescale predictions due to the inherent memory that changes slowly for 1 to 2
70 months in the climate system (e.g., Derome et al. 2005; Chen et al., 2010; Seo et al., 2019). In
71 particular, the realistic snow initial states contribute to improving S2S prediction skills, as
72 proven in several modeling studies. For example, previous studies (Orsolini et al., 2013; Jeong
73 et al., 2013) demonstrated a considerable enhancement in prediction skill of 2m air temperature
74 up to a lead time of 1-2 months across certain regions of Eurasia and the Arctic during winter,
75 depending on snow initialization. Moreover, other studies (Orsolini et al., 2016; Li et al., 2019)
76 have revealed that wave activity propagating toward the stratosphere, influenced by snow
77 initial conditions in climate models, can induce changes in the polar vortex and contribute to

78 the persistence of the North Atlantic Oscillation (NAO) and the AO. This emphasizes the
79 significance of snow initialization in climate models as an essential process for enhancing
80 prediction performance at the S2S timescales.

81 Snow states, i.e., snow water equivalent (SWE) used directly for hydrological analysis and
82 initial states of the model (Li et al., 2019; Gan et al., 2021), are generally provided from in-situ
83 observations data, remote-sensing retrievals from satellites, or numerical models such as the
84 land surface model (LSM) operated based on the observed atmospheric variables. For the in-
85 situ data snow depth (SD) measurements prevail, largely attributed to the challenges associated
86 with acquiring precise SWE data (Takala et al., 2011; De Rosnay et al., 2014). Surface synoptic
87 observations (SYNOP) serve as the principal source for SD measurements. The in-situ
88 measurements offer the most dependable snow information, yet they are characterized by
89 relatively coarse temporal and spatial resolutions, particularly within limited areas, due to the
90 spatial heterogeneity inherent in snow distribution. (Helmert et al., 2018; Meyal et al., 2020).
91 Satellite-derived observations using conical scanning microwave instruments may provide
92 spatially consistent data coverage across the globe. Cho et al. (2017) showed the SWE retrieval
93 results from two passive microwave sensors, the advanced microwave scanning radiometer 2
94 (AMSR2) and the special sensor microwave imager sounder (SSMIS). However, the
95 algorithms for SWE retrieval exhibit a degree of sensitivity to a variety of parameters such as
96 snow liquid water content and snow grain size distribution (De Rosnay et al., 2014). Hence,
97 satellite-based SWE data still have limitations in accuracy, especially under deep snow
98 conditions due to the limited penetration depth (Gan et al., 2021). On the other hand, satellite
99 retrieval can estimate snow cover accurately under clear sky conditions (Brubaker et al., 2009).
100 Model simulations obtained from LSMs and simple snow models can cover complete
101 spatiotemporal resolution but involve potentially large uncertainties due to the deficiencies in
102 the physical parameterizations and meteorological forcing data (Dirmeyer et al., 2006; Seo et

103 al., 2021).

104 Considering that snow observation dataset has its respective strengths as well as limitations,
105 data assimilation or other data fusion methods can prove to be beneficial for constructing snow
106 states such as reanalysis data (e.g., Brasnett, 1999; Dee et al., 2011; Meng et al., 2012; Pullen
107 et al., 2011; De Rosnay et al., 2014). For example, the snow analysis for the Canadian
108 Meteorological Center (CMC) utilizes a 2-dimensional optimal interpolation (2D-OI) scheme
109 with in-situ observations and the outputs from a simple snow model (Brown et al., 2003). The
110 National Centers for Environmental Prediction (NCEP) climate forecast system reanalysis
111 (CFSR) combines a multi-satellite-based interactive multi-sensor snow and ice mapping
112 system (IMS) as satellite-based snow cover retrieval and the outputs from the global snow
113 model of the Air Force Weather Agency (Meng et al., 2012). At the European Center for
114 Medium Weather Forecast (ECMWF), the ECMWF reanalysis (ERA)-Interim and ERA5 for
115 the snow analysis employ a Cressman interpolation and 2D-OI, respectively, with the IMS, in-
116 situ observation, and the results from a land surface model (Dee et al. 2011; De Rosnay et al.,
117 2014). The Japanese 55-year Reanalysis (JRA55) also utilizes the 2D-OI with in-situ
118 observation, satellite-based snow cover from SSMIS, and the results from an LSM (Kobayashi
119 et al., 2015). Given that the majority of the reanalysis datasets rely on snow depth
120 measurements, the SWE estimation is likely to introduce potential accuracy concerns when the
121 snow depth information is combined with the snow density calculations.

122 Climate prediction systems in operational centers such as the Meteorological Office (Met
123 Office) in the United Kingdom and the Korean Meteorological Administration (KMA) conduct
124 the snow initialization by utilizing the results of the operational global unified model (UM) and
125 the IMS snow cover, which solely indicates the presence of snow (Pullen et al., 2011), lacking
126 in its ability to reflect the physical quantity of it. The initialization at NCEP also performs a
127 similar approach using input data combined from IMS snow cover and results from the global

128 SD model (SNODEP; Meng et al., 2012). Furthermore, the snow initialization of ECMWF
129 employs optimal interpolation with a combination of results from the LSM, IMS snow cover,
130 and in-situ observation from SYNOP and national networks available on the GTS. However,
131 in regions where ground observations are unavailable, large errors may exist in the snow model
132 outputs due to uncertainties in atmospheric forcing and imperfect model parameterization
133 (Boone et al., 2004; Essery et al., 2009). Often, the snow processes parameterized in LSMs
134 rely on observed properties sampled in limited areas (Lim et al., 2022). In addition, as IMS
135 snow cover only identifies the presence of snow, the data assimilation with the satellite snow
136 cover only is not sufficient and inappropriate in constraining water and energy conservation.
137 Alternative methods that consider the physical quantity of snow are required for the snow
138 initialization.

139 One approach to mitigate the spatial discontinuity of ground observations is to use satellite-
140 derived SWE with wide spatial coverage and frequent temporal resolution. However, the SWE
141 retrievals from satellites still have considerable uncertainties (De Lannoy et al., 2010; Dawson
142 et al., 2018), which can arise from vegetation and terrain interference, sensor signal saturation,
143 snowfall amount, and simplifications in the underlying assumptions of the retrieval algorithms
144 (Liu et al., 2015). In particular, a region with heavy snow accumulation leads to a significant
145 underestimation of SWE due to the limitations in penetration depth from satellites (Gan et al.,
146 2021), so that satellite-derived SWE is not employed in the land initialization process. In
147 previous studies, various approaches have been attempted to improve SWE product
148 performance, such as combining satellite-derived SWE with ground observations (Pulliainen
149 et al., 2020), different satellite data sets (Gan et al., 2021), simple snow models (Dziubanski
150 and Franz, 2016), or LSMs (Kwon et al., 2017; Kumar et al., 2019). However, most previous
151 studies have focused on targeted regions with limited ground-based observations. Snow
152 initialization in global coverage using satellite-derived SWE remains a persistently challenging

153 task.

154 Therefore, this study developed an advanced SWE data assimilation framework with satellite
155 remote-sensing data using the local ensemble transform Kalman filter (LETKF) and the Joint
156 U.K. Land Environment Simulator (JULES) land model. While there are existing studies on
157 SWE data assimilation (e.g., Oaida et al., 2019; Smyth et al., 2020; Luo et al., 2021), the
158 use of passive microwave observations based on the LETKF in this context is relatively rare
159 (e.g., Giroto et al., 2020). This approach constitutes an objective method that optimally
160 combines two previously unattempted incomplete data sources: the satellite SWE from the
161 Advanced Microwave Scanning Radiometer 2 (AMSR2) and the dynamically-balanced SWE
162 from the JULES land model forced by observed atmospheric fields. The estimated SWE data
163 exhibit better consistency by additionally using snow cover data from the IMS data. This
164 assimilation framework also enables the assessment of improvement as it provides insights into
165 the reasons behind the performance improvement based on the Kalman gain analysis that
166 measures the relative significance of the input data between the satellite and the land model
167 during the data assimilation cycle. The satellite data have demonstrated high reliability in the
168 transition regions of climatologically-shallow snow conditions (Gan et al., 2021), and these
169 regions are known as "hot spots" of strong atmosphere-land coupling through snow melting
170 and associated surface energy and water balance changes (Koster et al., 2004; Dirmeyer, 2011;
171 Huning and AghaKouchak, 2020). From these perspectives, it would be important to evaluate
172 the impact of satellites on the transition regions as well as on the deep accumulation regions
173 where accurate satellite retrievals are challenging. Furthermore, the benefits of assimilating
174 satellite retrievals in extremely high-temperature events, such as the case in April 2020 over
175 Eurasia, can be elucidated. In this regard, we expect that this snow data assimilation framework
176 with satellite-derived SWE can be significant in providing optimal snow initial states for
177 improving the S2S prediction by global climate models.

179 **2. Data and model**

180 **2.1. Satellite data**

181 The snow information including snow cover and SWE can be derived from satellite
182 measurements offering global coverage and high temporal as well as spatial resolution. For
183 data assimilation, this study uses SWE calculated from brightness temperature measurements
184 obtained by the AMSR2 on board the Japanese Aerospace Exploration Agency (JAXA) global
185 change observation mission-water (GCOM-W) satellite. This AMSR2 Unified Level-3 (L3)
186 dataset offers daily estimation of SWE at 25 km resolutions from July 2012 to the present.
187 AMSR2 has a sensor designed to detect microwave radiation naturally emitted from the surface
188 and atmosphere, employing six frequency bands ranging from 6.9 to 89 GHz. Through this
189 conical scanning mechanism, AMSR2 can acquire day and night datasets with nearly constant
190 spatial resolution over more than 99% of the global coverage every two days. Comprehensive
191 explanations of AMSR2 characteristics are available in Imaoka et al. (2010). AMSR2 is
192 selected for the assimilation because it produces more accurate results by assimilating data
193 from modern sensors (e.g., AMSR2) compared to data from conventional sensors (e.g., AMSR-
194 E) (Cho et al., 2017).

195 The widely used multisensor-derived snow cover is IMS (e.g., Ramsay 1998; Helfrich et
196 al., 2007) produced by NOAA the National Environmental Satellite Data and Information
197 Service (NESDIS) for the Northern Hemisphere from February 2004 to the present at 4 km
198 resolutions. This dataset is generated using various data products, including multi-satellite
199 images and in-situ observations (U.S. National Ice Center, 2008). Since IMS provides binary
200 (0: no snow or 1: snow covered) snow cover information, we transform the IMS snow cover at
201 4 km grids to the snow cover fraction (SCF) within a 50-km LSM grid by counting the snow
202 pixel number with a value of 1. A 50-km LSM grid is declared as snow-covered when more
203 than 50% of the 4km pixels within the grid are covered with snow. In this study, the application

204 of the assimilation process is determined based on IMS-based SCF, renowned for its superior
205 reliability (e.g., Brown et al., 2014). Further details will be described in Section 3.3.

206

207 **2.2. Reference data for SWE and SCF**

208 The CMC daily estimated SWE is used for verification. The SWE data is processed using
209 statistical interpolation between a background field derived from a simple snow model and in-
210 situ daily SD (Brown and Brasnett, 2010). In detail, this dataset utilizes optimal interpolation
211 methods to acquire spatial SD from the in-situ data, involving SYNOP, special aviation reports
212 from the World Meteorological Organization (WMO), and meteorological aviation reports
213 (METAR). In areas with scant in-situ data, a simple snow accumulation and melt model is
214 employed to create an optimal interpolation that estimates snowmelt and snowfall worldwide,
215 assuming the persistence of the snowpack mass between snowfall and melting events
216 (Brasnett, 1999). Although the average elevation of snow measurement stations used in CMC
217 is biased toward low elevations ($< 400\text{m}$), potentially causing relative negative biases at higher
218 elevations with heavy snow accumulation, the CMC dataset is often considered the premier
219 snow analysis accessible in the Northern Hemisphere (Su et al. 2010) and has still been widely
220 used to evaluate model outputs (e.g., Reichle et al., 2011; Reichle et al., 2017; Toure et al,
221 2018). Therefore, the SWE of CMC produced without the satellite-derived data is selected for
222 verification as an independent dataset for evaluating the assimilated analysis with remote
223 sensing snow retrievals. Since only daily SD analysis is provided in CMC, it is converted to
224 daily SWE based on the snow bulk density methods (e.g., Sturm et al., 2010). It is available
225 from 12 March 1998 to the present and offers comprehensive coverage of the entire Northern
226 Hemisphere with a horizontal resolution of 24 km. The SWE of CMC at its native horizontal
227 resolution is interpolated onto the LSM grid through local area averaging.

228

229 **2.3. JULES LSM**

230 This study utilizes the JULES LSM from the Met Office (Best et al., 2011), a component
231 land model of the global seasonal forecasting system version 6 (GloSea6) global, fully-coupled
232 atmosphere, ocean, land, and sea-ice model. The surface types (or snow tiles) in the JULES
233 LSM consist of four non-vegetated types: urban, land-ice, inland water, and bare soil, as well
234 as five vegetation functional types: C3 temperate grass, needleleaf trees, shrubs, C4 tropical
235 grass, and broadleaf trees. For each surface tile, a separate energy balance is computed, and the
236 average energy balance in the grid cells is determined by applying weights to the values of each
237 surface tile. Two schemes are used within JULES to represent surface snow (e.g., Best et al.,
238 2011; Burke et al., 2013). The simple method involves a zero-layer approach, which modifies
239 the top soil level without using explicit model layers to represent snow processes. The other is
240 the multi-layer approach which is more comprehensive, described in Best et al. (2011). In the
241 case of vegetated surfaces, snow can be separated into ground snow and canopy snow or stored
242 in a single effective reservoir. As both the zero-layer and multi-layer snow models provide
243 similar results under various conditions (Best et al., 2011), this study used the zero-layer snow
244 model with constant thermal conductivity and density for snow. Although the heat capacity of
245 snow is ignored, the bulk thermal conductivity in the surface layer is reduced as the thermal
246 conductivity of snow differs from that of the soil and the layer thickness increases. As long as
247 snow persists on the ground, the skin temperature cannot exceed 0°C, yet the heat flux utilized
248 for melting the snow is diagnosed as the residual in the surface energy balance. The melted
249 water is immediately drained from the snow, divided into runoff and soil infiltration, and liquid
250 water is not stored or frozen in the snow. A detailed description of the energy and water cycling
251 in the JULES LSM can be referenced in Best et al. (2011).

252 The prognostic variables (e.g., SWE) in the LSM are determined by meteorological forcing
253 variables such as 2-m air temperature, humidity, 10-m wind speed, precipitation, surface

254 pressure, and radiative fluxes. The 3-hourly, JRA55 reanalysis at 0.56° spatial resolution is
255 employed for the meteorological forcing variables, which is linearly interpolated to a 50 km
256 resolution of the LSM. The model background error needed for data assimilation is estimated
257 by JULES ensemble runs with perturbed initial and boundary conditions. Following the
258 previous studies (Reichle et al., 2008; Seo et al., 2021), meteorological forcing variables are
259 perturbed to account for the uncertainties in these variables, especially precipitation, downward
260 shortwave, and downward longwave. Perturbations are applied using additive adjustments
261 assuming a normal distribution for longwave radiation and multiplicative adjustments
262 following a log-normal distribution for shortwave radiation and precipitation, as guided by
263 previous studies (Seo et al., 2021). Here, the ensemble means of additional and multiplicative
264 perturbations are zero and one, respectively. The relationship between disturbed precipitation
265 and radiative flux ensures the physical consistency among atmospheric forcing variables
266 (Reichle et al., 2008). For instance, a negative anomaly in precipitation and downward
267 longwave-radiation is statistically linked to a positive anomaly of downward shortwave-
268 radiation. Detailed explanations regarding the perturbation of atmospheric forcings can be
269 found in Reichle et al. (2008).

270

271 **3. Methodology**

272 **3.1. Bias correction**

273 The discrepancy in SWE between remote sensing and LSMs often arises due to uncertainties
274 in the model physics and forcing data and satellite retrievals. These uncertainties can lead to a
275 significant discrepancy in SWE between model simulations and satellite remote-sensing
276 retrievals, potentially degrading performance. In previous studies (e.g., Reichle and Koster,
277 2004; Seo et al., 2021), a scaling method of the nonlinear cumulative distribution function
278 (CDF) matching is used to account for the systematic bias of soil moisture in the model
279 backgrounds. However, unlike soil moisture, SWE presents varying characteristics in the CDF
280 distribution across different regions, such as between high and low latitudes, thus requiring the
281 estimation of distribution at each grid point. As a result, the insufficient sample size hinders
282 the clear simulation of the CDF distribution, posing challenges in its application. To address
283 this issue, we attempted to apply a simple and effective standard normal deviation scaling to
284 satellite-derived SWE at each grid point, considering its potential use as initial conditions for
285 JULES LSM-based climate models. Based on the climatology and standard deviation for the
286 model and remote sensing retrievals, the scaled SWE (O_{new}) from the satellite can be derived
287 from the following relation:

288

$$289 \quad O_{new} = \left(\frac{O - \bar{O}}{\sigma_o} \times \sigma_m \right) + \bar{M} \quad (1)$$

290

291 where $\bar{O}(\sigma_o)$ and $\bar{M}(\sigma_m)$ indicate climatology (standard deviation) of remote sensing
292 retrievals and the model, respectively. This approach has been widely utilized in observation-
293 based land initialization and has proven to be effective (e.g., Koster et al., 2011; Jeong et al.,
294 2013).

295

296 **3.2. Data assimilation method**

297 The snow assimilation is conducted based on the LETKF (e.g., Hunt et al., 2007), which is
298 utilized to combine remotely sensed retrievals with the LSM model outputs (a.k.a. backgrounds)
299 at each grid point to produce a snow analysis. Unlike variational data assimilation methods,
300 non-variational approaches (i.e., ensemble-based filters) characterize a probabilistic
301 representation with the spread of the ensemble serving as an estimate of forecast uncertainty.
302 LETKF has several advantages over other data assimilation methods. First, LETKF can
303 efficiently handle large datasets and high-dimensional state variables by localizing the
304 covariance matrix. This offers efficiency in parallel computing, making it suitable for real-time
305 forecasting and high-resolution data assimilation. In this study, the horizontal local patch size
306 and the localization length scale parameters are defined as 150 km and 30 km (Table 1),
307 respectively. This approach involves the weight function for the covariance localization within
308 the local patch centered at the analysis grid (e.g., Houtekamer and Mitchell, 2001; Hamill et
309 al., 2001). This function assigns larger errors to observations located farther away from the
310 center of the local patch, as proposed by Miyoshi and Yamane (2007), depending on the
311 Gaussian function. Secondly, the method utilizes model simulation ensembles to capture the
312 uncertainty in the initial states and background errors, which allows for a better representation
313 of the flow-dependent probability distribution of the state variables that vary in time and space.
314 Third, the LETKF employs an inflation parameter to adjust the ensemble spread, ensuring
315 realistic uncertainty estimation by accounting for background errors. The underestimation of
316 the analysis error covariance is typically issued by spatially and temporally constant boundary
317 conditions and observation errors and limited ensemble members. Based on the standardized
318 LETKF, this study applies a multiplicative covariance inflation of 20% of the spread of 24
319 member ensembles for each data assimilation cycle. Furthermore, the Kalman gain analysis
320 (Seo et al., 2021), which quantifies the ratio of the background error to the total error

321 (equivalent to the sum of the background and the observation error), is conducted. This analysis
322 serves to determine the weights assigned to assimilated observations in the analysis update
323 processes of the LETKF.

324

325 **3.3. Snow data assimilation design**

326 This study conducts the advanced daily cycle snow data assimilation experiment at each
327 ~~grid~~grid point using the LETKF based on the satellite data and the JULES LSM model outputs
328 driven by 3-hourly JRA55 reanalysis atmospheric forcing. The snow assimilation processes are
329 illustrated in Fig. 1, with a more detailed description in Table 1. Since data assimilation is
330 conducted by considering the error of SWE in both the model and the observation, it is
331 important to accurately understand the observation and background errors to improve the
332 performance of data assimilation. The experiment calculates the background error from the 24
333 ensemble member spreads generated by perturbing atmospheric forcings such as longwave
334 radiation, shortwave radiation, and precipitation in JULES LSM, as provided in section 2.3.
335 Due to the absence of precise error estimates for AMSR2 SWE retrievals, the observation error
336 is conservatively prescribed as 10% of AMSR2 SWE for each grid compared to the previous
337 study utilizing AMSR2 SWE data (Lee et al., 2015), considering the general increase in the
338 errors during the snow accumulation period with the development of deep snowpack (Foster et
339 al., 2005; Cho et al., 2017). Here, the bias-corrected AMSR2 satellite data as described in
340 section 3.1 is used as the observation data, and the updated snow analysis state through data
341 assimilation becomes a new initial state for the next integration in JULES LSM (Fig. 1). In
342 addition, the analysis state of this method is calculated based on the IMS snow cover fraction
343 as follows (Fig. 1). If the SCF from IMS is 0, the snow analysis is set to zero; otherwise, it is
344 derived through data assimilation. The reason for this is due to the importance of the presence
345 or absence of snow in the climate system, as well as the high reliability of the IMS data (e.g.,

346 Brown et al., 2014). A background experiment of JULES LSM without satellite data
347 assimilation as a baseline (referred to hereafter as “Openloop”) is also achieved by employing
348 the same ensemble perturbations, thereby measuring the skill improvement from the snow
349 analysis state through the assimilation of satellite-derived SWE and IMS SCF from satellite
350 and surface observations (referred to hereafter as “DA”). All experiments are conducted in
351 April from 2013 to 2020, which is one of the months with low snow performance in the LSM
352 when the snow begins to melt in the Northern Hemisphere (e.g., Toure et al., 2018; You et al.,
353 2020).

354 4. Results

355 4.1. Skill Verification

356 Figure 2 displays the climatological-mean SCF from the IMS multi-satellite data (Brown
357 et al., 2014) and the differences from [IMS for](#) AMSR2, Openloop, JRA55, and DA for April
358 2013-2020. Here, the JRA55 [SWE SCF](#) serves as a reference dataset for comparison with other
359 reanalyses and is associated with meteorological forcing data used in the JULES land surface
360 model. April is a season when the accumulated snow during the cold season begins to melt.
361 This study defines the transitional region with a climatological-mean SWE of less than 16 mm
362 as in previous studies (e.g., Gan et al., 2021), the boundary of these transition regions is
363 represented by the black lines in Fig. 2. The transitional regions exhibit large variability in
364 space and time, and they are mainly located at mid-latitudes. The SCF climatology patterns
365 show negligible differences in high latitudes of heavy snow accumulation but noticeable
366 differences in the transitional mid-latitude regions of less snow. SCF from JRA55 tends to be
367 underestimated compared to IMS, whereas AMSR2 and Openloop tend to overestimate. There
368 is a clear difference in SCF between AMSR2 and IMS satellite data. This study gives more
369 credibility to IMS than AMSR2, as the former is based on multiple satellite data sources (e.g.,
370 Brown et al., 2014). As we used the IMS SCF to define the snow region to be assimilated by
371 AMSR2 SWE, it is natural that DA shows better consistency with IMS and reduces
372 overestimation biases in Openloop. Quantitatively, the root mean square differences (accuracy,
373 defined in supplementary Table 1 as in previous study) for AMSR2, Openloop, JRA55, and
374 DA with (from) IMS are 0.23 (0.91), 0.18 (0.91), 0.13 (0.93), and 0.13 (0.97), respectively,
375 showing the best consistency in DA. The quantitative differences between DA and other
376 experimental results are minor, but noticeable spatial discrepancies exist, particularly around
377 transition regions.

378 The SWE climatology from AMSR2, Openloop, JRA55, and DA is also compared with

379 CMC as a reference in Fig. 3. The SWE derived from AMSR2 shows a significant
380 underestimation compared to CMC, particularly in the regions with heavy snow accumulation
381 at high latitudes. This is presumed to be due to limitations in satellite sensors detecting the
382 depth of snow (Gan et al., 2021). The SWE from JRA55 exhibits characteristics of
383 overestimation in high latitudes and underestimation in transitional regions. On the other hand,
384 the climatological SWEs from Openloop and DA exhibit higher correspondence to CMC, even
385 higher than JRA55. Specifically, DA demonstrates a higher agreement with CMC, despite the
386 marginal difference compared to Openloop. Quantitatively, the pattern correlation coefficients
387 (root mean square differences) for AMSR2, Openloop, JRA55, and DA with (from) CMC are
388 0.63 (80.7 kg/m²), 0.80 (50.1 kg/m²), 0.60 (100.8 kg/m²), and 0.80 (49.9 kg/m²), respectively.
389 Due to the application of standard deviation scaling to the satellite-derived SWE used in data
390 assimilation, the discrepancy in climatological SWE distributions between DA and Openloop
391 is deemed negligible. Despite its similarity to Openloop, DA with snow data assimilation
392 displays the relatively highest correlation and the smallest root mean square difference among
393 the datasets.

394 Next, we compare the temporal variation of SWE as measured by the Spearman rank
395 correlation coefficient with CMC, which is regarded as more appropriate than the Pearson
396 correlation coefficient for describing datasets containing nonlinearity and outliers such as snow
397 in both time and space. Figure 4 compares the distribution of correlation skills from AMSR2,
398 Openloop, JRA55, and DA. Openloop has a high performance in regions with heavy snow
399 accumulation but relatively low performance in transition regions with significant snow
400 changes. In contrast, the results from the AMSR2 satellite data represent poor performance in
401 high-latitude areas with heavy snow accumulation but high performance in transitional regions,
402 consistent with the previous studies (Gan et al., 2021). DA shows high performance not only
403 in high-latitude areas with heavy snow accumulation but also in transition regions. Even

404 compared to JRA55 used as the atmospheric forcing, DA performs better in temporal variation.
405 The quantitative results in the correlation in the Northern Hemisphere over 40°N (the transition
406 region) are 0.41 (0.54) for AMSR2, 0.61 (0.48) for Openloop, 0.58 (0.58) for JRA55, and 0.67
407 (0.61) for DA, respectively. The findings indicate that satellite retrievals offer additional value
408 in capturing temporal variations through data assimilation, indicating the benefit of
409 assimilating the AMSR2 SWE despite the overall lower performance of the satellite data itself.

410 The performance improvement by DA is also evident in the zonally-averaged correlation
411 coefficient shown in Fig. 5. The AMSR2 satellite data shows higher performance than
412 Openloop in the transition region around latitude 45 °N-55 °N, although performance sharply
413 decreases with increasing snow accumulation. Openloop indicates gradually increasing
414 performance as the latitude increases, with the highest performance at around 60°N. DA
415 denotes superior performance across the Northern Hemisphere, especially in the mid-latitude
416 transition region than AMSR2 or JRA55. An exception is for 35-40°N in the Tibetan Plateau,
417 where JRA55 used in-situ observations. The results suggest that the developed snow data
418 assimilation system represents well not only the transitional regions but also the regions with
419 high snow accumulation that are difficult to detect by satellite.

420 Figure 6 presents the Spearman rank correlation depending on the SWE amount in the
421 Northern Hemisphere. AMSR2 exhibits higher performance than Openloop for SWE up to 16
422 mm. However, the performance of AMSR2 sharply declines beyond that threshold, and
423 Openloop shows a better performance. Consistent with the results illustrated in Figs. 4 and 5,
424 DA demonstrates superior performance compared to others. Note that DA performs
425 significantly better in the transition region of less than 16 mm of SWE. Considering that the
426 area below 16 mm of SWE accounts for approximately 53% of the entire area of the Northern
427 Hemisphere(as shown in the pie chart in Fig. 6), the data assimilation impact is identifiable,
428 and it can contribute substantially to the increase in the prediction skill through improving the

429 simulation of the albedo changes and surface energy balance.

430 Consistent with the description in Section 3.3, this study considers an algorithm based on
431 the highly reliable IMS satellite SCF data to identify the presence of snow and determine the
432 assimilation process. Therefore, a further sensitivity test is conducted to investigate the
433 influence of incorporating IMS data in snow assimilation. Figure 7 compares the correlation
434 differences between Openloop and the data assimilation result employing both AMSR2 and
435 IMS (DA), as well as the data assimilation result utilizing solely AMSR2 and excluding IMS
436 (hereafter referred to as DA_AMSR2). The results obtained from the snow assimilation show
437 the improvements in the transitional regions where AMSR2 denotes a better agreement with
438 the observations compared to Openloop. Notably, the skill is enhanced significantly in DA by
439 incorporating the IMS SCF. DA exhibits inferior performance compared to Openloop in certain
440 exceptional cases, which may be attributed to discrepancies in snow identification between the
441 CMC observations used for correlation and the IMS data utilized for data assimilation.
442 Moreover, the performance of SWE improves even when only AMSR2 is used, but
443 incorporating IMS leads to a substantial improvement in the transitional regions. This implies
444 that IMS has a positive influence on the snow data assimilation.

445

446 **4.2 Kalman gain analysis**

447 In order to better understand the skill enhancement through snow assimilation of satellite
448 data, this section examines the Kalman gain. Figure 8 illustrates the spatial distribution of
449 observation error, model background error, and the Kalman gain for SWE. A high value of the
450 Kalman gain denotes that the assimilated result is closer to the AMSR2 observation than the
451 model background. The Kalman gain is large when the background error becomes large, or the
452 observation error is small. As this study specifies the observation error as a conservative 10%
453 of SWE compared to the previous study (Lee et al., 2015), the observation error basically

454 follows the distribution similar to the climatological-mean values. The background errors,
455 originating from the 24 ensemble members, have higher values in high-latitude regions and
456 mid-latitude regions. Data assimilation methods such as LETKF used in this study often face
457 challenges in accurately representing background errors when the ensemble spread is
458 insufficient. Generally, the magnitude of ensemble spread is frequently compared to the root
459 mean square error (RMSE). The ensemble spread in this study demonstrates a sufficiently valid
460 magnitude in comparison with the RMSE, as illustrated in SFig. 1, indicating that it is well
461 estimated. Moreover, the standardized distribution of SWE among the ensemble members
462 exhibits a quasi-Gaussian distribution centered around zero, with the transition region showing
463 a closer resemblance to a standardized Gaussian distribution (SFig. 4). In the spatial
464 distribution of Kalman gain in Fig. 8c, significant performance improvement is observed in
465 transition regions, where Kalman gains exhibit larger values. However, in high-latitude areas
466 with substantial snow accumulation, there is a tendency for Kalman gain to have lower values.
467 These findings agree well with the bar graph in Fig. 9, which illustrates the Kalman gain as a
468 function of SWE amount. In the region encompassing the transition region with SWE amounts
469 below 20 mm, the Kalman gain displays the highest values, particularly exceeding 0.8. As the
470 SWE amount increases, the Kalman gain decreases, with a significant decline observed when
471 the SWE amount reaches 80-100 mm or higher. Furthermore, in the areas where DA denotes
472 improved skill compared to Openloop, the Kalman gain shows values generally above 0.7. In
473 contrast, relatively lower values below 0.5 are observed in the areas with decreased skill. This
474 indicates that in the dominant areas of performance improvement, including the transition
475 region, the background error is significantly larger than the observation error, emphasizing the
476 substantial influence of observations in data assimilation. It is found that accurate remote
477 sensing retrievals are well reflected in regions with high uncertainty in the LSM through the
478 snow data assimilation system, leading to performance improvement.

479 **4.3 Validation of the SWE for the extreme event**

480 In April 2020, Siberia experienced a record-breaking heatwave with the highest observed
481 average temperature. This section investigates the potential benefits of snow assimilation using
482 satellite data for the case of the 2020 Siberian heatwave. Previous studies have identified the
483 strong polar vortex accompanied by the AO amplification during winter as a major cause of
484 the cold Eurasian region (Overland and Wang, 2021). Additionally, it has been revealed that
485 the occurrence of high temperatures in the Siberian region is found to be closely associated
486 with large-scale atmospheric waves in the upper atmosphere over the Eurasian region
487 originating from the Atlantic (De Angelis et al., 2023). As a result, remarkable snow melting
488 occurred due to the high surface temperature over the Siberian region in April 2020, leading to
489 extremely low values of SWE and SCF as depicted in SFig. 2. This is consistent with previous
490 studies reporting a significant snow depletion in 2020 in the region (Gloege et al., 2022).
491 Especially, as shown in Fig. 10, significant negative anomalies in SWE and SCF are
492 predominant over the transition region. Substantial snow melt can contribute to record-
493 breaking heatwaves through albedo feedback and changes in the ratio of the latent and sensible
494 heat fluxes from the exposed surface, coupled with favorable atmospheric circulation patterns
495 (Collow et al., 2022). Collow et al. (2022) demonstrated that the exposed surface contributed
496 to up to 20% of the temperature anomaly over Siberia in spring 2020. This implies the
497 importance of realistic snow initial states in the global coupled model forecasts. For the
498 Siberian region with extreme high-temperature events marked by the red box in Fig. 10, DA
499 shows a better agreement with the extremely dry snow conditions, especially in the transitional
500 region, compared to the Openloop. These results are evident when considering the observation-
501 to-model ratio in that region. The percentage of CMC (IMS) is 83% (78%) for Openloop and
502 93% (89%) for DA, indicating that DA with snow data assimilation based on satellite data
503 effectively replicates the observed snow depletion in comparison with Openloop. Similarly to

504 the 2020 case, we obtained another significant case in 2014 compared to Openloop, as shown
505 in SFig. 3. Such extremely dry snow conditions can provide significant heatwave events in the
506 following months.

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513 **5. Conclusions and discussion**

514 The advanced SWE data assimilation is developed in this study with the LETKF data
515 assimilation method and the JULES LSM. The system assimilates snow water equivalent
516 retrievals from AMSR2 and IMS snow cover. This constitutes an objective way to optimally
517 combine two imperfect data sources for SWE from satellite remote sensing data and the land
518 surface model simulation forced by observed atmospheric data. This study shows that the
519 satellite-derived SWE has limitations in penetrating deep snow and exhibited much
520 discrepancy from the SWE obtained from the Openloop LSM simulations. The SWE
521 assimilation in this study proves the beneficial impacts of using satellite snow data, maintaining
522 better analysis quality by dynamically balancing the errors from the satellite observations and
523 the model background states.

524 It is found that the simulation from Openloop as a baseline shows superior performance in
525 high-latitude regions with heavy snow accumulation but relatively inferior performance in
526 transition regions with much variation of snow in space and time. Contrastingly, the AMSR2
527 satellite data represent poor performance in high-latitude regions but exhibit relatively better
528 performance in the transition regions. The SWE from the LETKF data assimilation consistently
529 exhibits better performance in capturing the climatology and temporal variation compared to
530 other results. It specifically improves the analysis in the mid-latitude transition regions that
531 cover approximately 53% of the entire areas of the Northern Hemisphere. It is found that the
532 model background errors estimated from the ensemble spread are significantly larger than the
533 observation errors, thereby reflecting satellite information more in those regions. The LETKF
534 data assimilation also proves reliable representation in the heavy snow regions due to low
535 ensemble spread and large uncertainty in the satellite retrievals. Moreover, during the record-
536 breaking heatwave in Siberia in April 2020, the remarkable snow depletion observed due to
537 high surface temperatures is more realistically reproduced by our snow analysis compared to

538 the Openloop.

539 This snow data assimilation framework is anticipated to contribute to a more precise
540 prediction of atmospheric conditions by realistically capturing the interaction between the
541 atmosphere and land, given the substantial influence of SWE on energy and water balance at
542 the interface of the atmosphere and land. Specifically, this applies to the transitional regions
543 with high spatial and temporal variability. The long-term analysis of snow manifests a
544 pronounced variability in the continental interior at the interannual timescales, potentially
545 improving the prediction of extreme heatwave events by global climate models. This study
546 used the gridded CMC data from in-situ observations for the validation. Although existing
547 snow data are subject to much uncertainty and limitations, we expect to obtain comparable
548 conclusions and significant benefits of optimally combining satellite SWE data and the LSM
549 model simulations through LETKF data assimilation method.

550 The quality of the observation is crucial in the data assimilation system. Satellite-derived
551 snow cover exhibits a significantly higher accuracy compared to other data sources, while SWE
552 has restricted performance due to the limitations of penetration depth by satellite sensors and
553 relies heavily on estimation algorithms. Due to these problems, most previous studies and
554 operational centers primarily depend on satellite-derived snow cover for snow initialization.
555 However, the findings from this study highlighted the beneficial impacts of using satellite-
556 derived SWE, particularly in the rapidly changing transition areas, to find out which variable
557 is more important in closing surface energy and water balance changed by snow. Nevertheless,
558 areas of significance in large-scale circulation, such as the Tibetan region, which experiences
559 significant uncertainty and degraded performance in satellite data, do not exhibit substantial
560 data assimilation effects. As the performance of SWE derived from various satellites continues
561 to advance, these issues will be discussed more.

562

563 **Key words**

564 Snow data assimilation, AMSR2, LETKF, snow water equivalent, JULES LSM

565

566 ***Data availability.***

567 The AMSR2 SWE and IMS SC were obtained from
568 https://n5eil01u.ecs.nsidc.org/AMSA/AU_DySno.001/ and
569 <https://noadata.apps.nsidc.org/NOAA/G02156/>, respectively. The CMC SWE was collected
570 from https://daacdata.apps.nsidc.org/pub/DATASETS/nsidc0447_CMC_snow_depth_v01/.

571 The snow-assimilated results and land surface variables from the LSM offline simulation may
572 be requested from the authors.

573

574 ***Author contributions.***

575 LJI conceived the project, designed the study, developed the snow assimilation system, wrote
576 the paper, and made the figures. LMI provided advice on the methods, project design, and
577 review and editing of the manuscript. TSL helped with the experiment with the land surface
578 model. SEK helped with the data assimilation method based on LETKF. LYK provided advice
579 on snow satellite data and the sensitivity methods. All authors contributed to the writing of the
580 paper by providing comments and feedback.

581

582 ***Competing interests.***

583 The contact author has declared that none of the authors has any competing interests.

584

585 *Acknowledgements*

586 This work was funded by the Korea Meteorological Administration Research and Development
587 Program under Grant ~~KMI2021-01210~~(RS-2024-00403698). ES was supported by Learning
588 & Academic research institution for Master's·PhD students, and Postdocs (LAMP) Program of
589 the National Research Foundation of Korea (NRF) grant funded by the Ministry of Education
590 (RS-2023-000301702). We thank the supercomputing resources of the UNIST Supercomputing
591 Center.

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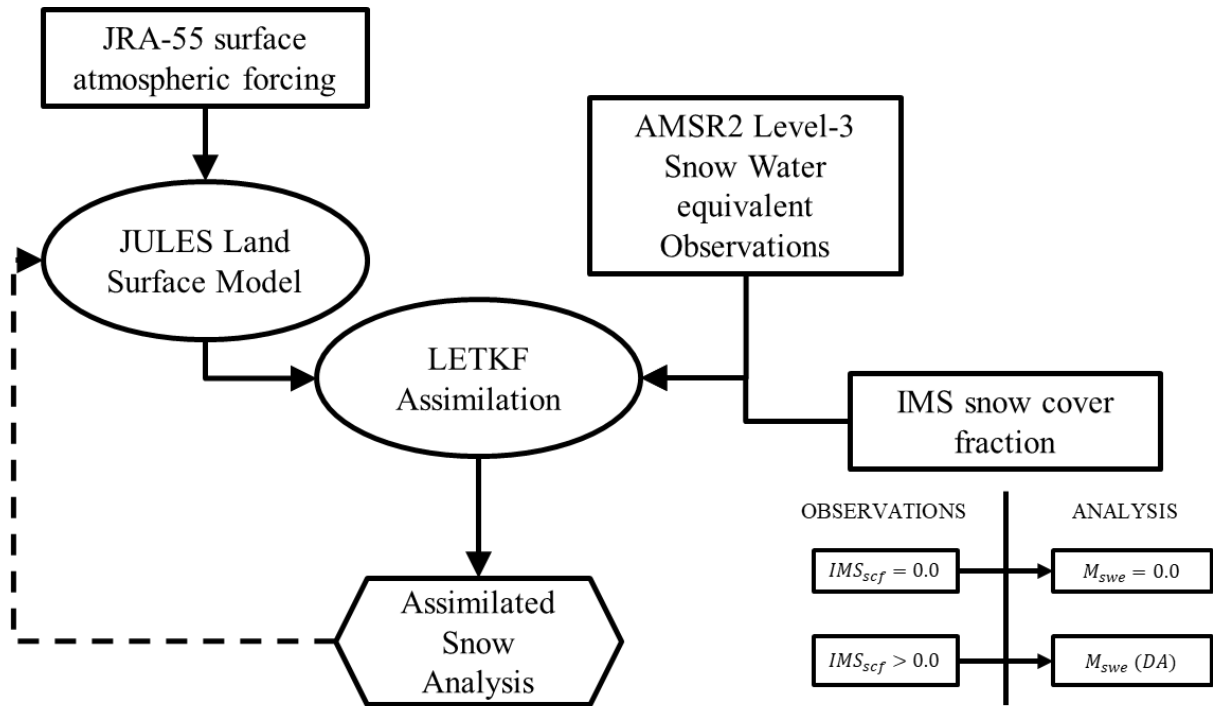
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814 **Table 1.** Description of the land surface model, the data used, and assimilation experiment
 815 designs.

	INFORMATION	REFERENCES
Land Surface Model	JULES	Best et al., (2011)
Atmospheric Forcing	3-hourly JRA-55 reanalysis	Kobayashi et al., (2015)
Snow Observation	AMSR2 & IMS	Imaoka et al., (2010) Ramsay (1998) Helfrich et al., (2007)
Data Assimilation scheme	Local Ensemble Transform Kalman Filter (LETKF)	Hunt et al., (2007) Miyoshi and Yamane, (2007)
Resolution (km)	0.5° × 0.5° (~ 50)	
	1-day DA cycle	
Localization patch size (km)	3×3 (150), $\sigma = 30$	
Ensemble sizes	24	
Experiment period	2013-2020, APR	

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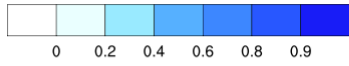
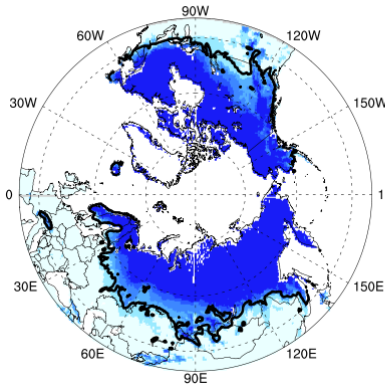
819 **Figure 1.** Schematic diagram of the snow assimilation system with satellite-derived

820 observations and the land surface model outputs.

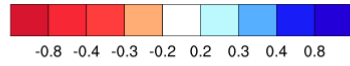
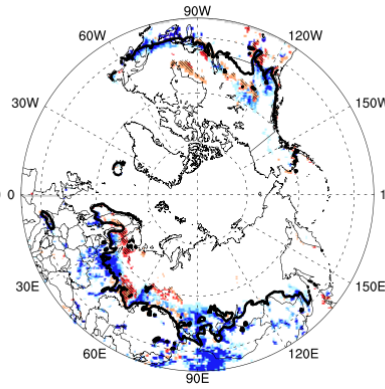
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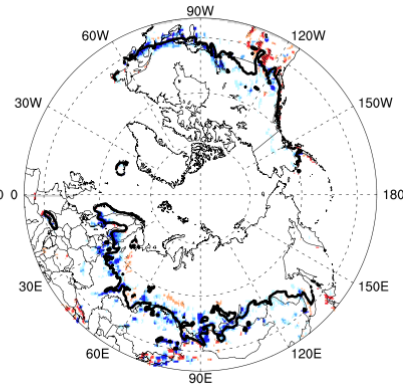
a) IMS



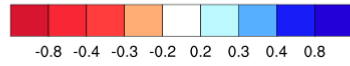
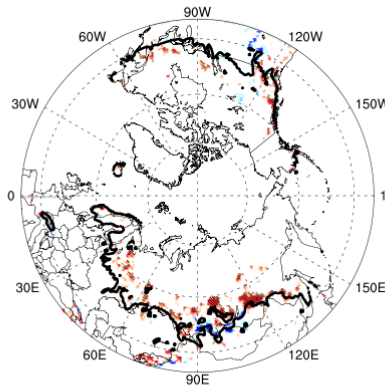
b) AMSR2 0.23 (0.91)



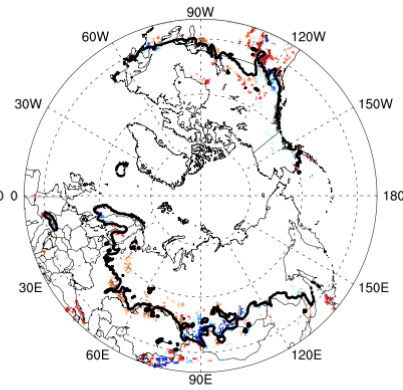
c) Openloop 0.18 (0.91)

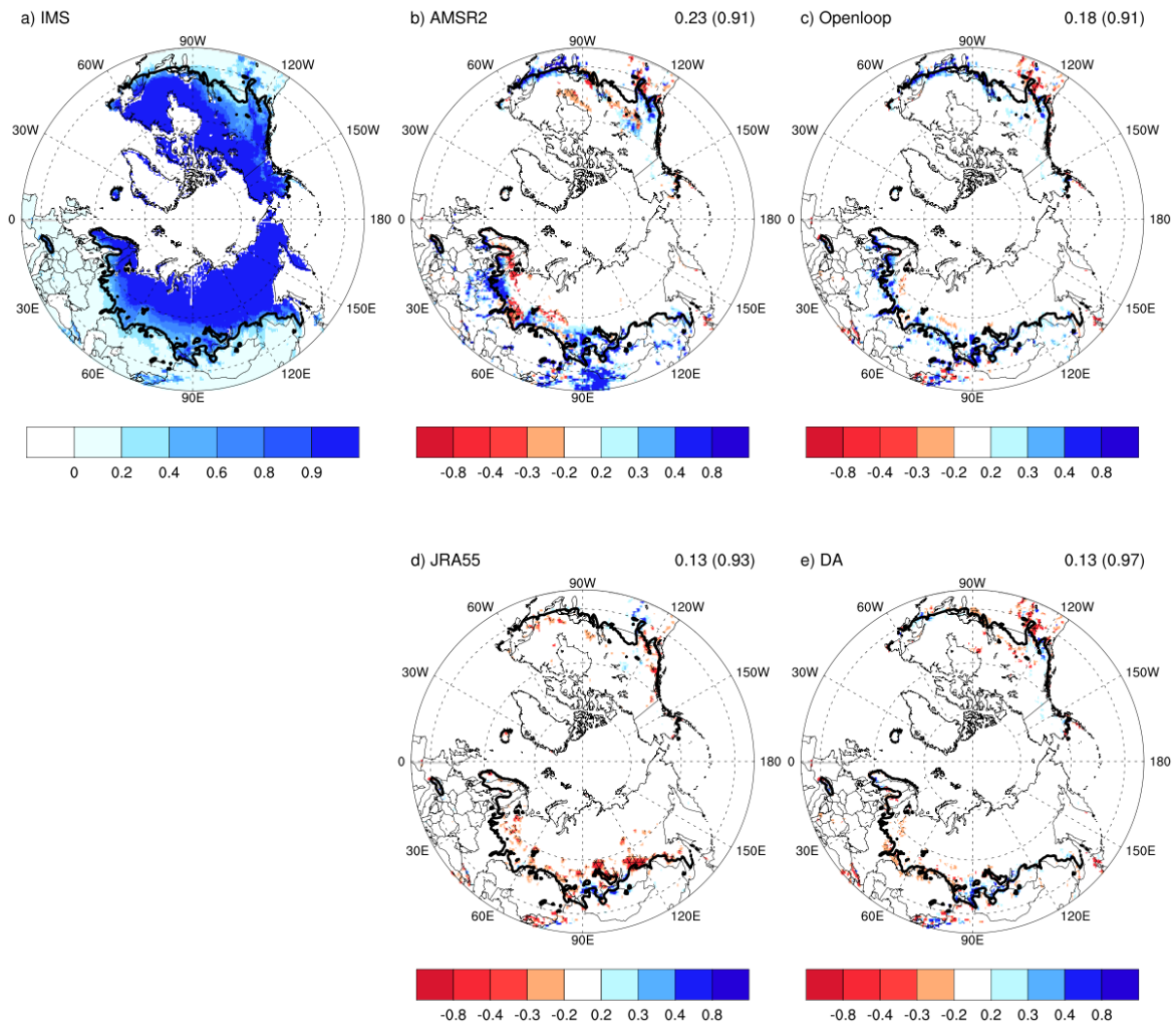


d) JRA55 0.13 (0.93)



e) DA 0.13 (0.97)





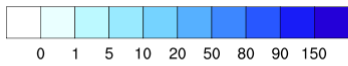
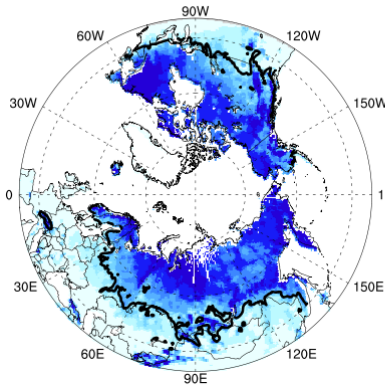
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825 **Figure 2.** (a) Climatology of SCF from IMS used as reference and (b-e) the differences from
 826 IMS for AMSR2, base-line model simulation (Openloop), JRA55, and the data
 827 assimilation results (DA) for April during 2013-2020. The black line represents the
 828 boundary of the transition region, defined as the climatological-mean SWE of less than
 829 16mm. Each value on the top right is the root-mean-squared difference with IMS and
 830 the accuracy from IMS (parenthesis) for 15323 pixels over 40-60°N. The accuracy is
 831 defined in supplementary Table 1 as in previous study (Lee et al., 2015). Negative
 832 values (areas) in red shades are indicated with a diagonal line hatching. Here, SCF is
 833 dimensionless since it represents a proportion rather than a physical measurement with
 834 units.

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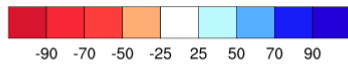
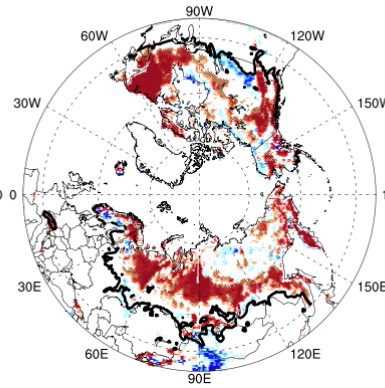
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a) CMC



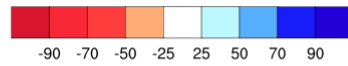
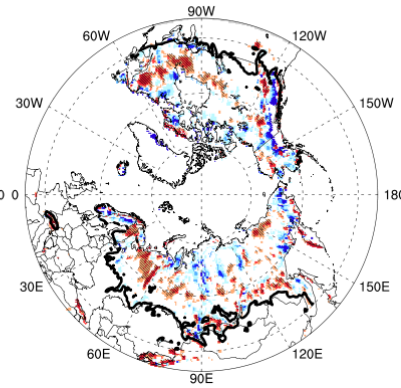
b) AMSR

0.63 (80.7)



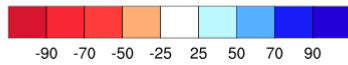
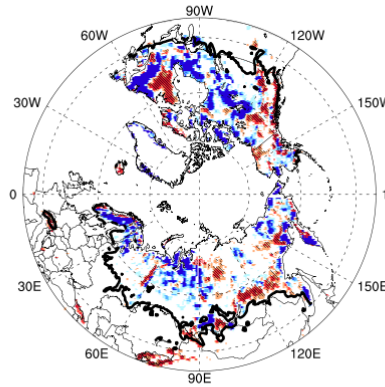
c) Openloop

0.80 (50.1)



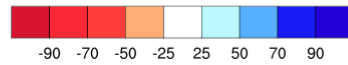
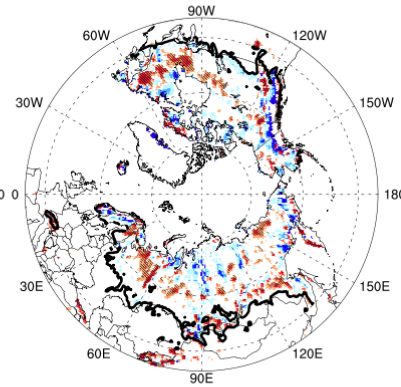
d) JRA55

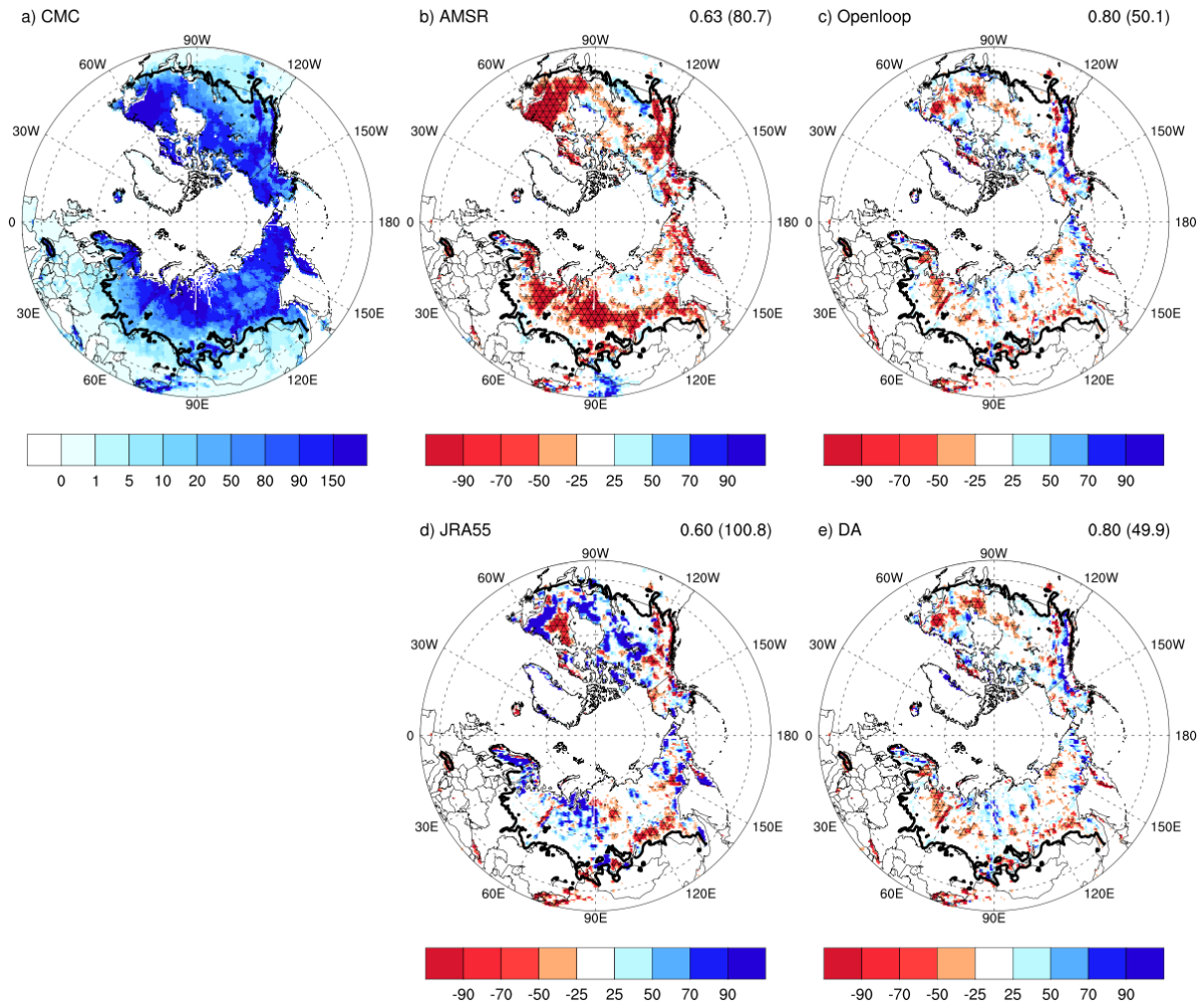
0.60 (100.8)



e) DA

0.80 (49.9)





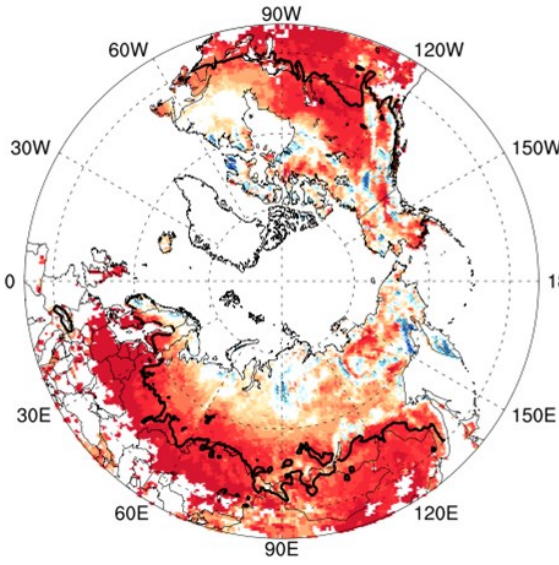
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839 **Figure 3.** (a) Climatology of SWE (unit: kg/m² or mm), from CMC used as reference and (b-
 840 e) the differences from CMC for AMSR2, base-line model simulation (Openloop),
 841 JRA55, and the data assimilation results (DA) for April during 2013-2020. The black
 842 line represents the boundary of the transition region, defined as the climatological-mean
 843 SWE of less than 16mm. Each value on the top right is the pattern correlation with
 844 CMC for 26482 pixels over 40 °N and the root-mean-squared difference (unit: kg/m²
 845 or mm) from CMC (parenthesis) for 15323 pixels over 40-60°N. Negative values (areas)
 846 in red shades are indicated with a diagonal linehatching.

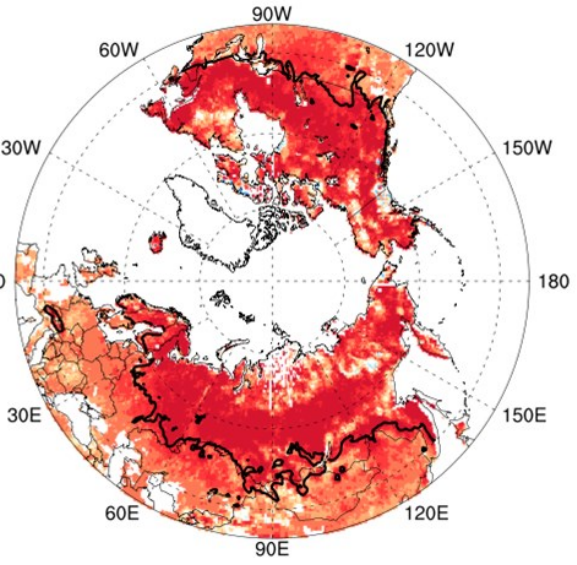
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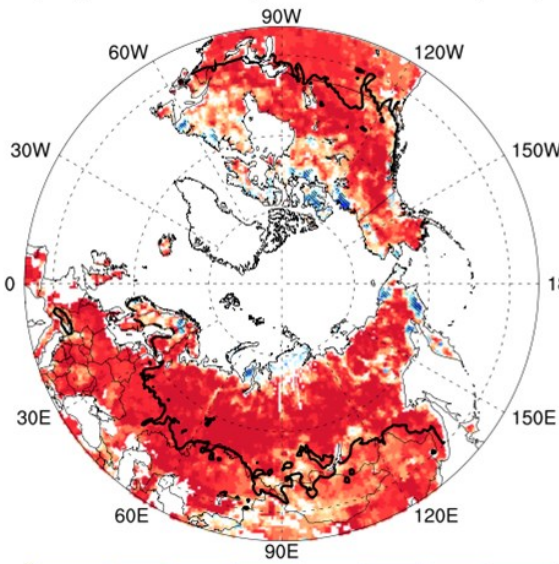
a) R (CMC vs AMSR2) 0.41 (0.54)



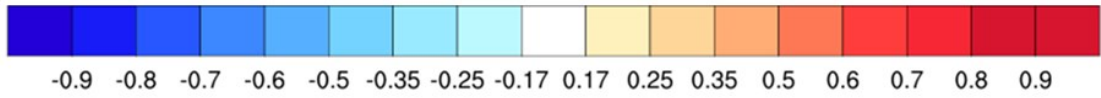
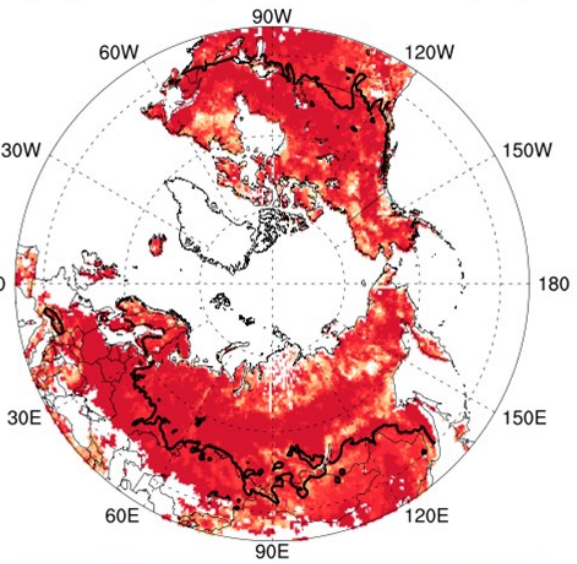
b) R (CMC vs Openloop) 0.61 (0.48)



c) R (CMC vs JRA55) 0.58 (0.58)

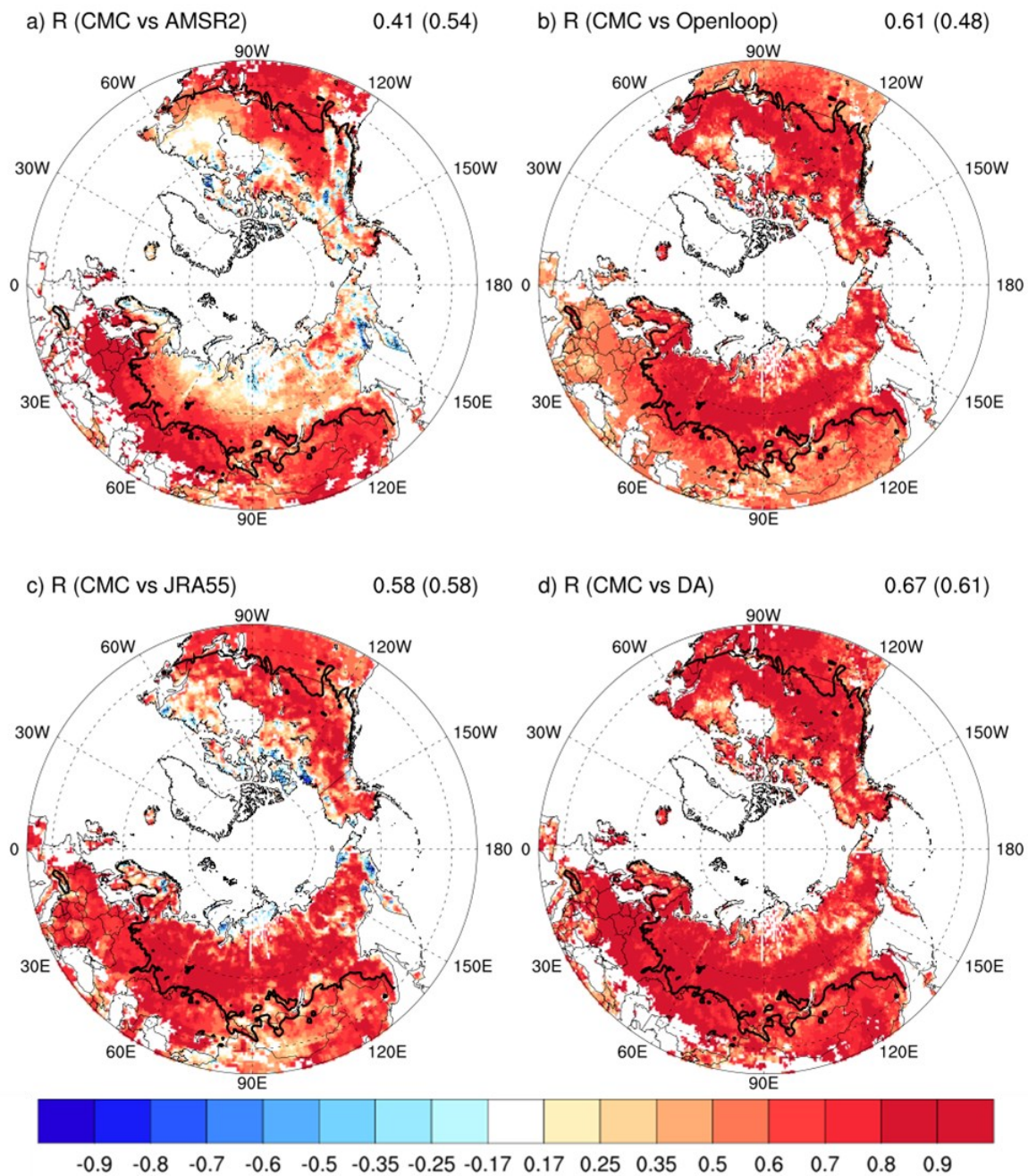


d) R (CMC vs DA) 0.67 (0.61)



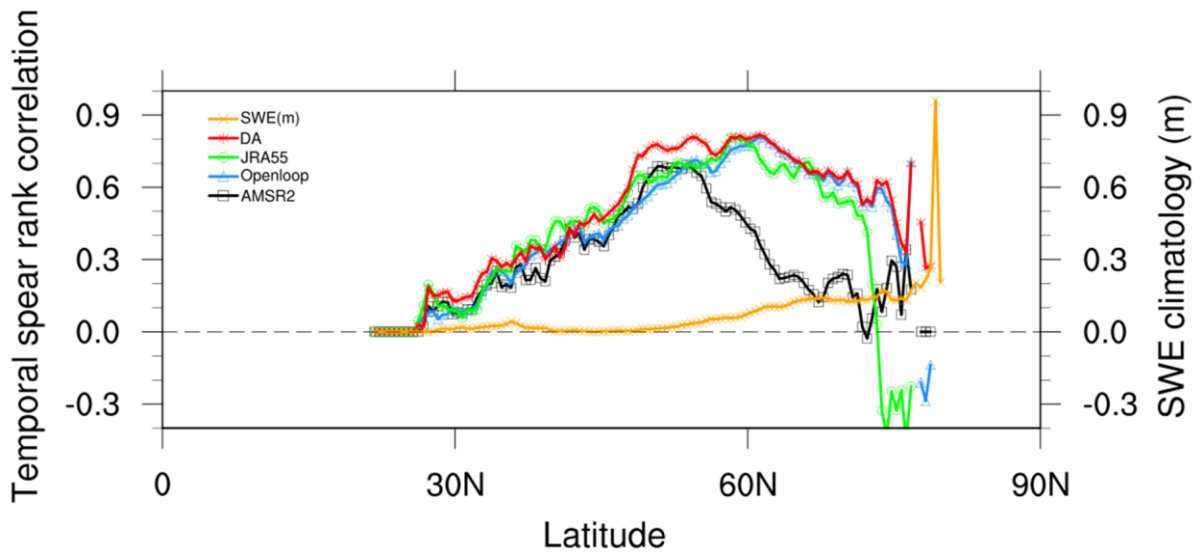
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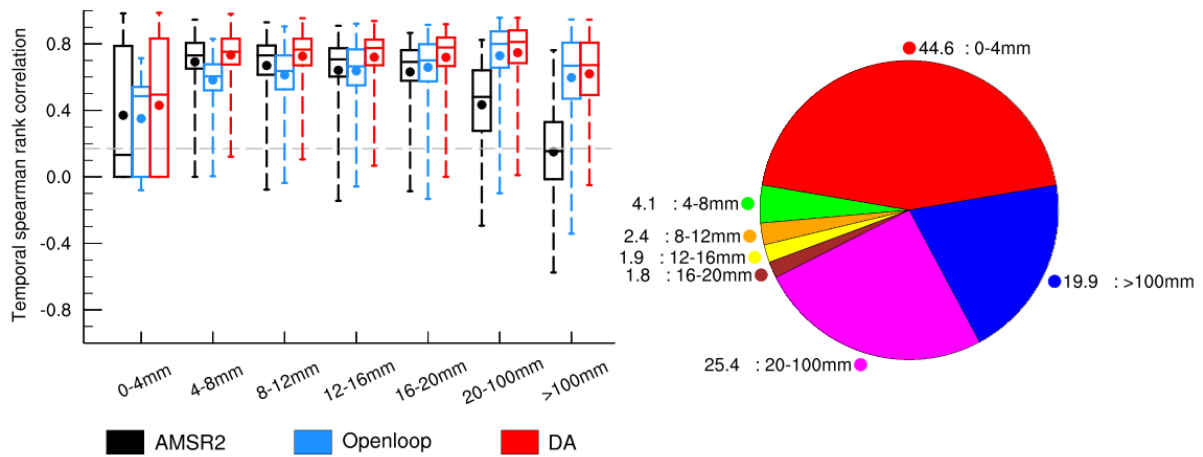
852 **Figure 4.** SWE skill measured as the Spearman rank correlation (R) with the CMC for AMSR2,
 853 base-line model simulation (Openloop), JRA55, and the data assimilation result (DA).
 854 The black line represents the boundary of the transition region, defined as the
 855 climatological-mean SWE of less than 16mm. Each value on the top is the area-average
 856 R of North hemisphere for 26482 pixels over 40°N and for 8801 pixels over the
 857 transition region (parenthesis). Negative values (areas) in red shades are indicated with
 858 a diagonal linehatching.



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860 **Figure 5.** Zonally-averaged Spearman rank correlation (R) along the latitude for SWE. The
 861 yellow line indicates the climatology of SWE, and the black, blue, green, and red lines
 862 denote the values of AMSR2, base-line model simulation (Openloop), JRA55, data
 863 assimilation results (DA), respectively.

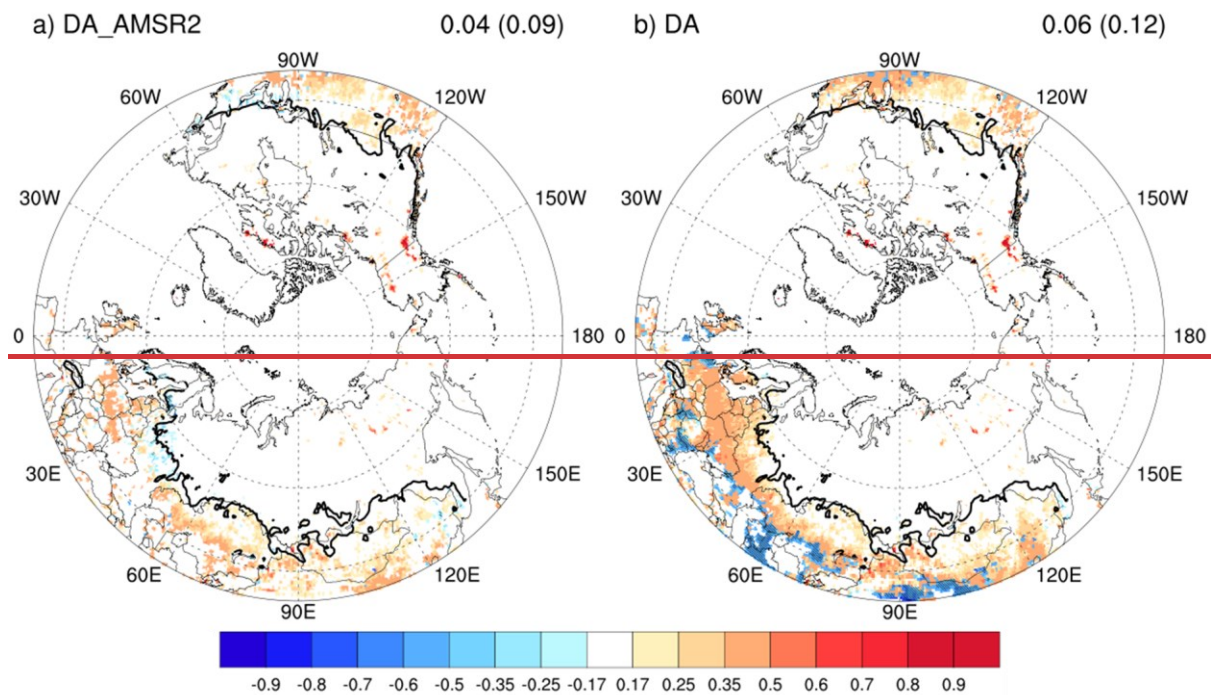
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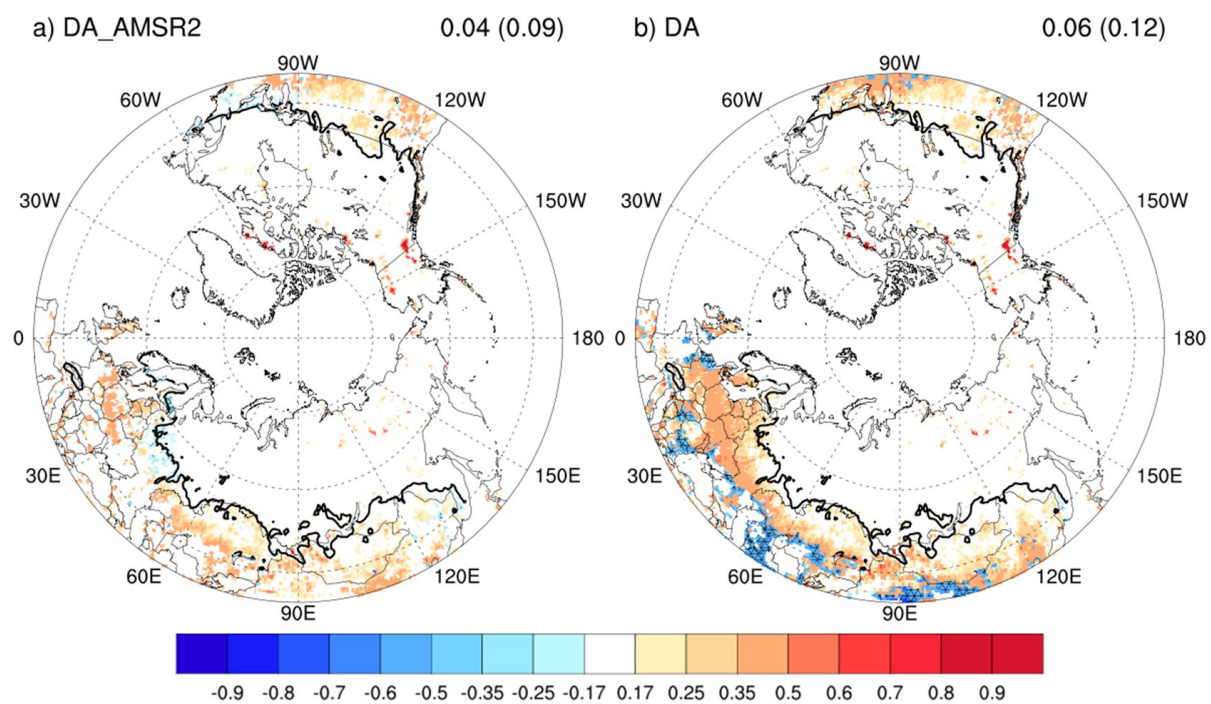
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866 **Figure 6.** Box plots of the Spearman rank correlation (R) according to SWE- (unit: kg/m^2 or
 867 mm). The pie chart shows the total area ratio (%) as a function of SWE amount. The
 868 black, blue, and red boxes denote the AMSR2, base-line model simulation (Openloop),
 869 and the data assimilation results (DA), respectively. The boxes indicate 25 and 75%
 870 percentiles, and the line and point in the boxes shows the median and the mean values.
 871 The upper and lower whiskers denote the 10 and 90% percentiles, respectively.

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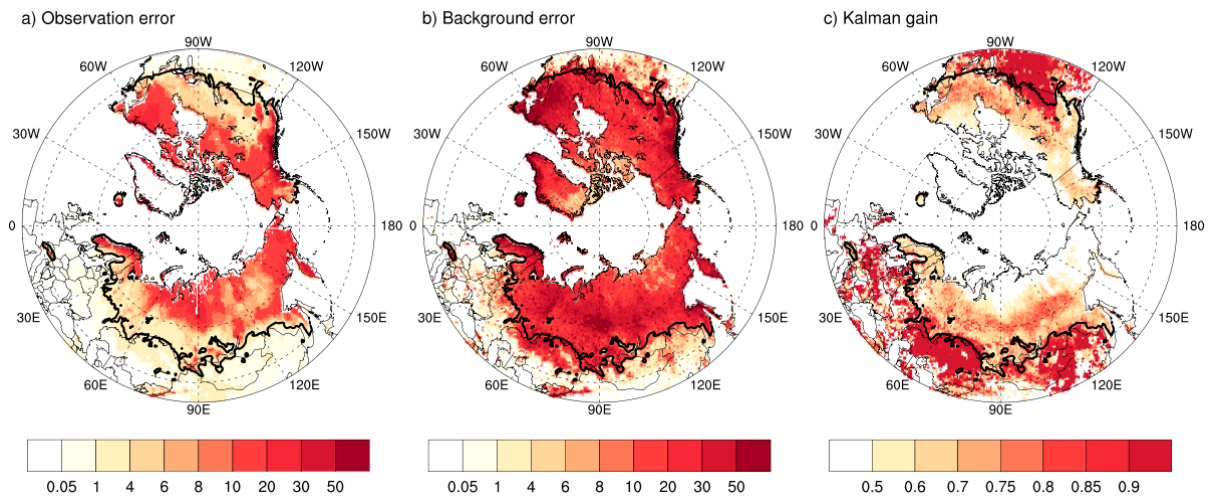


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875 **Figure 7.** The difference in SWE Spearman rank correlation coefficient with CMC between
 876 the Openloop and data assimilation results: DA employing both AMSR2 and IMS and
 877 DA_AMSR2 utilizing solely AMSR2 and excluding IMS, for April during 2013-2020.
 878 The black line represents the boundary of the transition region, defined as the
 879 climatological-mean SWE of less than 16mm. Each value on the top right is the area-

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average over 40°N and the transition region (parenthesis). Negative values (areas) in red shades are indicated with a diagonal linehatching.



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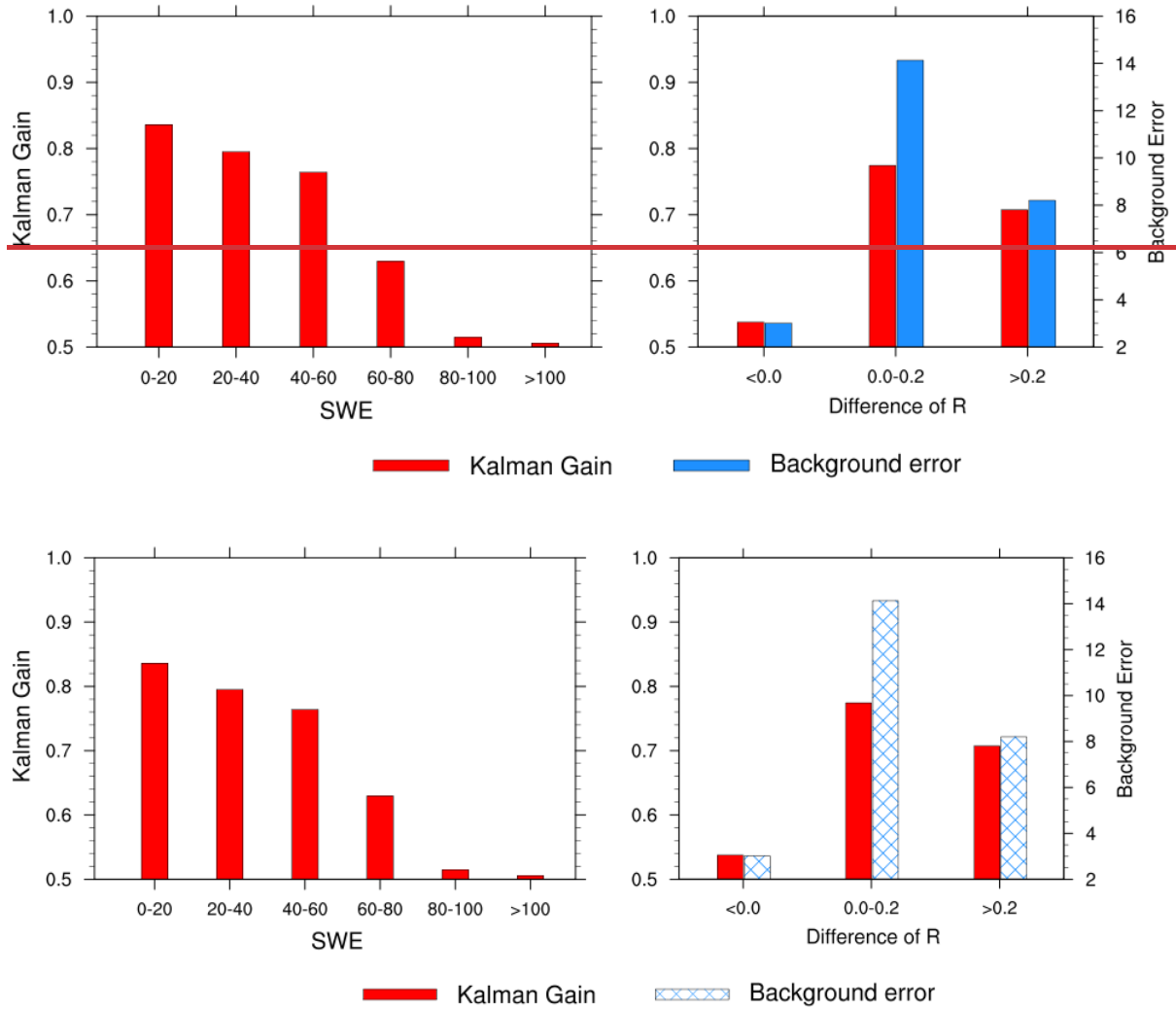
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Figure 8. Spatial distribution of observation error (unit: kg/m^2 or mm), background error (unit: kg/m^2 or mm), and Kalman gain. The black line represents the boundary of the transition region, defined as the climatological-mean SWE of less than 16mm.



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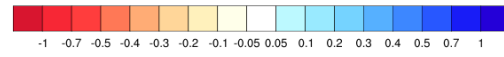
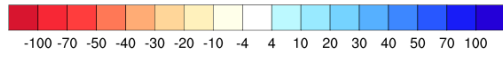
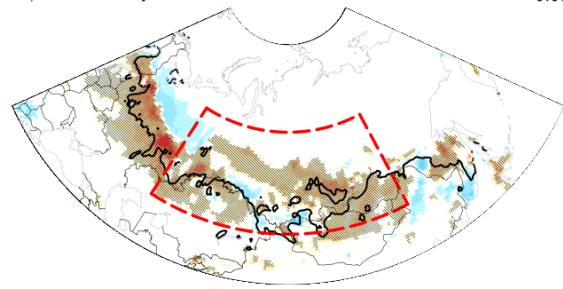
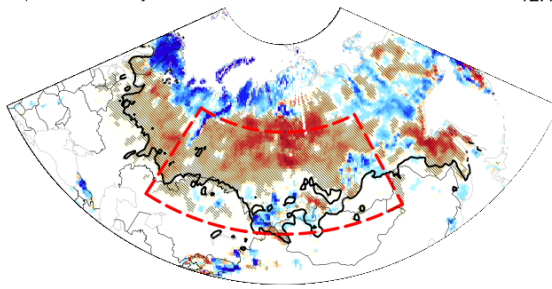
Figure 9. Bar chart of (left) the Kalman gain according to the SWE amount, (unit: kg/m^2 or mm) and (right) the Kalman gain (red line) and background error (blue hatched line) as a function of the difference between Openloop and DA in Spearman rank correlation coefficient (R).

a) SWE anomaly of CMC for 2020

-12.44

b) SCF anomaly of IMS for 2020

-0.08

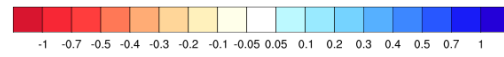
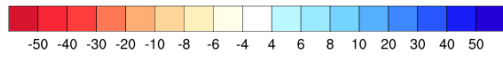
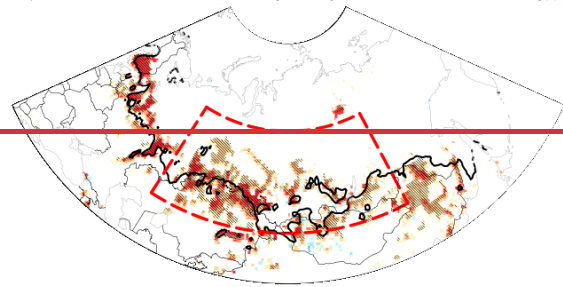
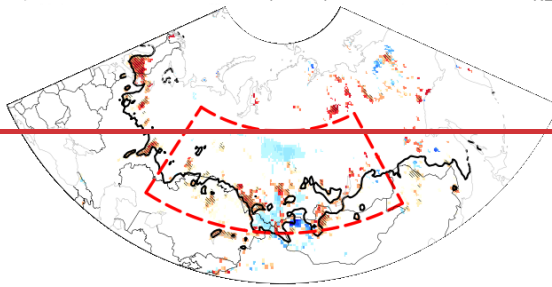


c) Difference between DA and openloop of SWE for 2020

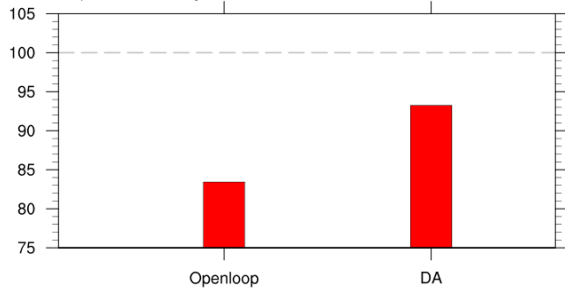
-1.22

d) Difference between DA and openloop of SCF for 2020

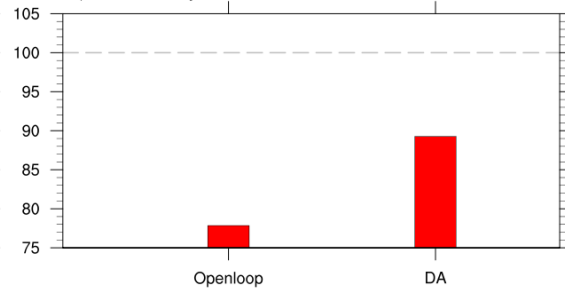
-0.10

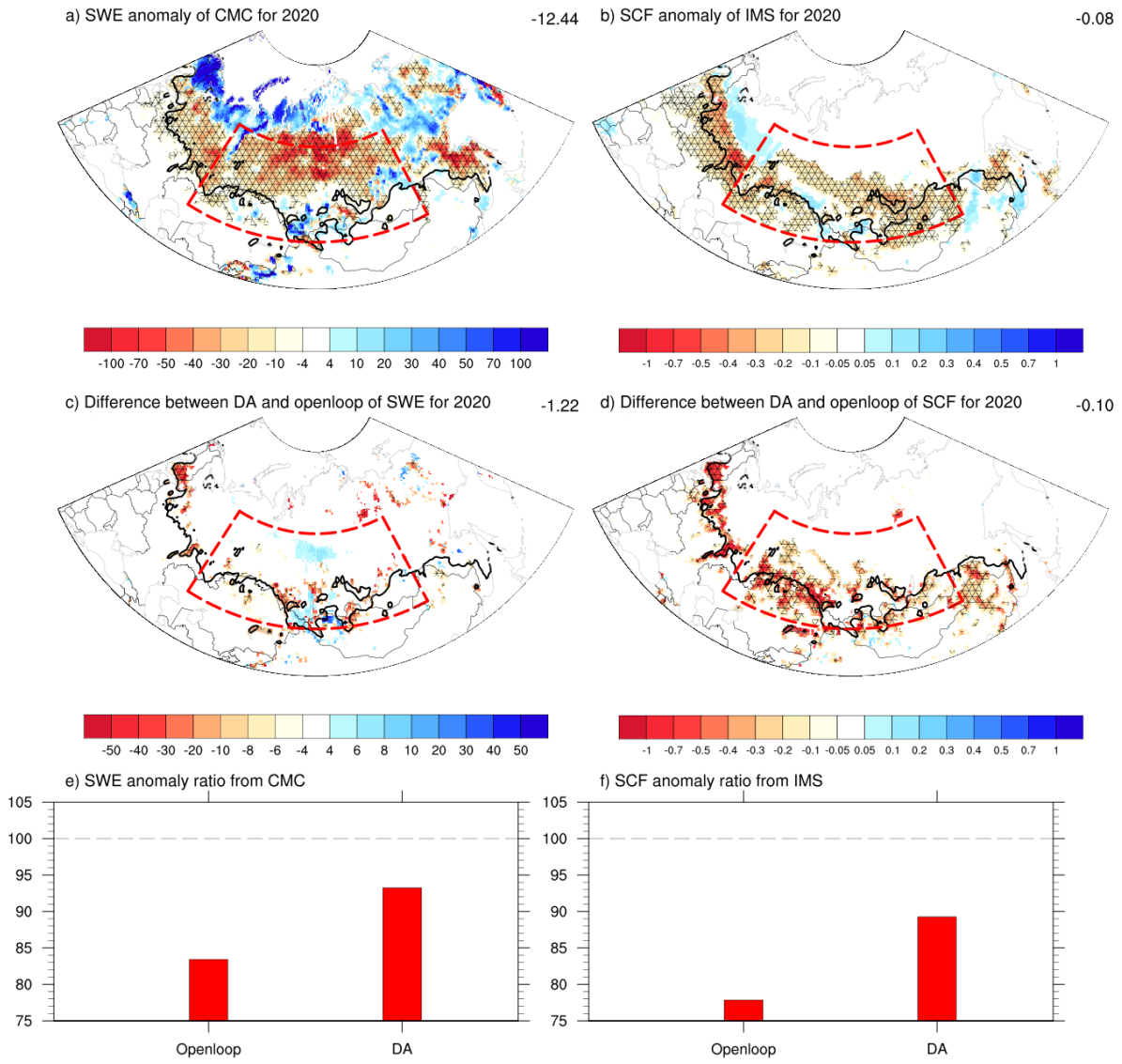


e) SWE anomaly ratio from CMC



f) SCF anomaly ratio from IMS





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Figure 10. Anomalies of a) SWE (unit: kg/m^2 or mm) from CMC and b) SCF from IMS as well as the difference (c, d) of variables between DA and ~~openloop~~Openloop in April 2020. Bar chart (e, f) indicates the ratio of DA and ~~openloop~~Openloop to verification data such as CMC and IMS in the red box ($48\text{--}65^\circ\text{N}$ and $55\text{--}120^\circ\text{E}$), which is the region associated with extreme high-temperature events, focused on this study. Negative values (areas) in red shades are indicated with a diagonal linehatching.