1	Assimilation of snow water equivalent from AMSR2 and IMS
2	satellite data utilizing the local ensemble transform Kalman filter
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26 Abstract

Snow Water Equivalent (SWE), as one of the land initial or boundary conditions, plays a 27 crucial role in global or regional energy and water balance, thereby exerting a considerable 28 29 impact on seasonal and sub-seasonal scale predictions owing to its enduring memory over 1 to 2 months. Despite its importance, most SWE initialization remains challenging due to its 30 reliance on simple approaches based on spatially constrained observation.limited observations. 31 32 Therefore, this study developed the advanced SWE data assimilation framework with satellite remote-sensing data utilizing the local ensemble transform Kalman filter (LETKF) and the 33 34 Joint U.K. Land Environment Simulator (JULES) land model. This approach constitutes a 35 novel approach that has not been previously attempted, as it offers an objective way tomethod that optimally combinecombines two imperfect previously unattempted incomplete data 36 sources: the satellite SWE retrieval from the Advanced Microwave Scanning Radiometer 2 37 (AMSR2) and dynamically-balanced SWE from the JULES land surface model. In this 38 framework, an algorithm is additionally considered to determine the assimilation process based 39 40 on the presence or absence of snow cover from the Interactive Multisensor Snow and Ice Mapping System (IMS) satellite, renowned for its superior reliability. 41

The baseline model simulation from JULES without satellite data assimilation shows 42 43 superiorbetter performance in high-latitude regions with heavy snow accumulation but relatively inferior in the transition regions with less snow and high spatial and temporal 44 variation. Contrastingly, the AMSR2 satellite data exhibit better performance in the transition 45 regions but poorer in the high latitudes, presumably due to the limitation of the satellite data in 46 the penetrating depth. The data assimilation (DA) demonstrates the positive impacts by 47 48 reducing uncertainty in the JULES model simulations in most areas, particularly in the midlatitude transition regions. In the transition regions, the model background errors from the 49 50 ensemble runs are significantly larger than the observation errors, emphasizing great

uncertainty in the model simulations. The results of this study highlight the beneficial impact 51 of data assimilation by effectively combining both land surface model and satellite-derived 52 53 data according to their relative uncertainty, thereby controlling not only transitional regions but also satellite-constrained areas experiencing heavy snow accumulation. This assimilation 54 framework is anticipated to contribute to a more precise prediction of atmospheric conditions 55 by realistically capturing the interaction between the atmosphere and land, given the substantial 56 influence of SWE on energy and water balance at the interface of the atmosphere and land the 57 58 regions with heavy snow accumulation that are difficult to detect by satellite. 59

60 1. Introduction

Snow plays a crucial role in regulating the water, energy, and carbon exchange between the 61 62 land surface and atmosphere (e.g., Dutra et al., 2011; Thomas et al., 2016). A snowpack tends 63 to increase surface albedo and soil moisture as the snow melts (Eagleson, 1970), thereby affecting the climate system through changes in water and energy balances. In addition to local 64 impacts, the continental snowpack over Eurasia can influence the large scale atmospheric 65 66 circulation during winter (e.g., Li and Wang, 2014) or in spring (e.g., Broxton et al., 2017). Especially, the Eurasian autumn snow can affect upward-propagating stationary Rossby-wave 67 68 activity, leading to stratospheric warming and weakening of stratospheric polar vortex and jet 69 stream, which in turn emerges as a negative Arctic oscillation (AO)-like pattern at the surface 70 during winter due to downward propagation through the troposphere. Its impact is shown in both observation and model experiments (e.g., Allen and Zender 2011; Cohen et al. 2007). 71 Furthermore, the interannual variability of snow melting during the boreal spring season affects 72 surface soil moisture in summer, which has important implications for heatwave development 73 74 and emphasizing mechanisms through land-atmosphere interactions (Seo et al., 2020).

In the subseasonal to seasonal (S2S) timescales, land initial states are crucial components 75 in the S2S timescale predictions due to the inherent memory that changes slowly for 1 to 2 76 77 months in the climate system (e.g., Derome et al. 2005; Chen et al., 2010; Seo et al., 2019). In particular, the realistic snow initial states contribute to improving S2S prediction skills, as 78 proven in several modeling studies. For example, previous studies (Orsolini et al., 2013; Jeong 79 et al., 2013) demonstrated a considerable enhancement in prediction skill of 2m air temperature 80 up to a lead time of 1-2 months across certain regions of Eurasia and the Arctic during winter, 81 82 depending on snow initialization. Moreover, other studies (Orsolini et al., 2016; Li et al., 2019) have revealed that wave activity propagating toward the stratosphere, influenced by snow 83 84 initial conditions in climate models, can induce changes in the polar vortex and contribute to the persistence of the North Atlantic Oscillation (NAO) and the AO. This emphasizes the significance of snow initialization in climate models as an essential process for enhancing prediction performance at the S2S timescales.

Snow states, i.e., snow water equivalent (SWE) used directly for hydrological analysis and 88 89 initial states of the model (Li et al., 2019; Gan et al., 2021), are generally provided from in-situ observations data, remote-sensing retrievals from satellites, or numerical models such as the 90 land surface model (LSM) operated based on the observed atmospheric variables. For the in-91 92 situ data snow depth (SD) measurements prevail, largely attributed to the challenges associated with acquiring precise SWE data (Takala et al., 2011; De Rosnay et al., 2014). Surface synoptic 93 observations (SYNOP) serve as the principal source for SD measurements. The in-situ 94 measurements offer the most dependable snow information, yet they are characterized by 95 relatively coarse temporal and spatial resolutions, particularly within limited areas, due to the 96 97 spatial heterogeneity inherent in snow distribution. (Helmert et al., 2018; Meyal et al., 2020). Satellite-derived observations using conical scanning microwave instruments may provide 98 spatially consistent data coverage across the globe. Cho et al. (2017) showed the SWE retrieval 99 100 results from two passive microwave sensors, the advanced microwave scanning radiometer 2 101 (AMSR2) and the special sensor microwave imager sounder (SSMIS). However, the algorithms for SWE retrieval exhibit a degree of sensitivity to a variety of parameters such as 102 103 snow liquid water content and snow grain size distribution (De Rosnay et al., 2014). Hence, 104 satellite-based SWE data still have limitations in accuracy, especially under deep snow conditions due to the limited penetration depth (Gan et al., 2021). On the other hand, satellite 105 106 retrieval can estimate snow cover accurately under clear sky conditions (Brubaker et al., 2009). Model simulations obtained from LSMs and simple snow models can cover complete 107 spatiotemporal resolution but involve potentially large uncertainties due to the deficiencies in 108 the physical parameterizations and meteorological forcing data (Dirmeyer et al., 2006; Seo et 109

110 al., 2021).

111 Considering that snow observation datasets have their dataset has its respective strengths as well as limitations, data assimilation or other data fusion methods can prove to be beneficial 112 for constructing snow states such as reanalysis data (e.g., Brasnett, 1999; Dee et al., 2011; 113 114 Meng et al., 2012; Pullen et al., 2011; De Rosnay et al., 2014). For example, the snow analysis for the Canadian Meteorological Center (CMC) utilizes a 2-dimensional optimal interpolation 115 (2D-OI) scheme with in-situ observations and the outputs from a simple snow model (Brown 116 et al., 2003). The National Centers for Environmental Prediction (NCEP) climate forecast 117 system reanalysis (CFSR) combines a multi-satellite-based interactive multi-sensor snow and 118 ice mapping system (IMS) as satellite-based snow cover retrieval and the outputs from the 119 global snow model of the Air Force Weather Agency (Meng et al., 2012). At the European 120 Center for Medium Weather Forecast (ECMWF), the ECMWF reanalysis (ERA)-Interim and 121 122 ERA5 for the snow analysis employ a Cressman interpolation and 2D-OI, respectively, with the IMS, in-situ observation, and the results from a land surface model (Dee et al. 2011; De 123 Rosnay et al., 2014). The Japanese 55-year Reanalysis (JRA55) also utilizes the 2D-OI with 124 125 in-situ observation, satellite-based snow cover from SSMIS, and the results from an LSM (Kobayashi et al., 2015). Given that the majority of the reanalysis datasets rely on snow depth 126 measurements, the SWE estimation is likely to introduce potential accuracy concerns when the 127 128 snow depth information is combined with the sow density calculations.

129 Climate prediction systems in operational centers such as the Meteorological Office (Met 130 Office) in the United Kingdom and the Korean Meteorological Administration (KMA) conduct 131 the snow initialization by utilizing the results of the operational global unified model (UM) and 132 the IMS snow cover, which solely indicates the presence of snow (Pullen et al., 2011), lacking 133 in its ability to reflect the physical quantity of it. The initialization at NCEP also performs a 134 similar approach using input data combined from IMS snow cover and results from the global

SD model (SNODEP; Meng et al., 2012). Furthermore, the snow initialization of ECMWF 135 employs optimal interpolation with a combination of results from the LSM, IMS snow cover, 136 and in-situ observation from SYNOP and national networks available on the GTS. However, 137 in regions where ground observations are unavailable, large errors may exist in the snow model 138 139 outputs due to uncertainties in atmospheric forcing and imperfect model parameterization (Boone et al., 2004; Essery et al., 2009). Often, the snow processes parameterized in LSMs 140 rely on observed properties sampled in limited areas (Lim et al., 2022). In addition, as IMS 141 snow cover only identifies the presence of snow, the data assimilation with the satellite snow 142 cover only is not sufficient and inappropriate in constraining water and energy conservation. 143 Alternative methods that consider the physical quantity of snow are required for the snow 144 initialization. 145

One approach to mitigate the spatial discontinuity of ground observations is to use satellite-146 derived SWE with wide spatial coverage and frequent temporal resolution. However, the SWE 147 retrievals from satellites still have considerable uncertainties (De Lannoy et al., 2010; Dawson 148 et al., 2018), which can arise from vegetation and terrain interference, sensor signal saturation, 149 150 snowfall amount, and simplifications in the underlying assumptions of the retrieval algorithms (Liu et al., 2015). In particular, a region with heavy snow accumulation leads to a significant 151 underestimation of SWE due to the limitations in penetration depth from satellites (Gan et al., 152 153 2021), so that satellite-derived SWE is not employed in the land initialization process. In previous studies, various approaches have been attempted to improve SWE product 154 performance, such as combining satellite-derived SWE with ground observations (Pulliainen 155 et al., 2020), different satellite data sets (Gan et al., 2021), simple snow models (Dziubanski 156 and Franz, 2016), or LSMs (Kwon et al., 2017; Kumar et al., 2019). However, most previous 157 studies have focused on targeted regions with limited ground-based observations. Snow 158 initialization in global coverage using satellite-derived SWE remains a persistently challenging 159

160 task.

Therefore, this study developed an advanced SWE data assimilation framework with satellite 161 remote-sensing data using the local ensemble transform Kalman filter (LETKF) and the Joint 162 U.K. Land Environment Simulator (JULES) land model. This constitutes a novel approach that 163 164 has not been previously attempted, and it offers an objective way to optimally combine two imperfectWhile there are existing studies on SWE data assimilation (e.g., Oaida et al., 2019; 165 Smyth et al., 2020; Luojus et al., 2021), the use of passive microwave observations based on 166 167 the LETKF in this context is relatively rare (e.g., Girotto et al., 2020). This approach constitutes an objective method that optimally combines two previously unattempted incomplete data 168 sources: the satellite SWE from the Advanced Microwave Scanning Radiometer 2 (AMSR2) 169 and the dynamically-balanced SWE from the JULES land model forced by observed 170 atmospheric fields. The estimated SWE data exhibit better consistence by additionally using 171 snow cover data from the IMS data. This assimilation framework also enables the assessment 172 of improvement as it provides insights into the reasons behind the performance improvement 173 based on the Kalman gain analysis that measures the relative significance of the input data 174 between the satellite and the land model during the data assimilation cycle. The satellite data 175 have demonstrated high reliability in the transition regions of climatologically-shallow snow 176 conditions (Gan et al., 2021), and these regions are known as "hot spots" of strong atmosphere-177 land coupling through snow melting and associated surface energy and water balance changes 178 (Koster et al., 2004; Dirmeyer, 2011; Huning and AghaKouchak, 2020). From these 179 perspectives, it would be important to evaluate the impact of satellites on the transition regions 180 as well as on the deep accumulation regions where accurate satellite retrievals are challenging. 181 Furthermore, the benefits of assimilating satellite retrievals in extremely high-temperature 182 events, such as the case in April 2020 over Eurasia, can be elucidated. In this regard, we expect 183 that this snow data assimilation framework with satellite-derived SWE can be significant in 184

185 providing optimal snow initial states for improving the S2S prediction by global climate models.

187 2. Data and model

188 2.1. Satellite data

189 The snow information including snow cover and SWE can be derived from satellite 190 measurements offering global coverage and high temporal as well as spatial resolution. For data assimilation, this study uses SWE calculated from brightness temperature measurements 191 obtained by the AMSR2 on board the Japanese Aerospace Exploration Agency (JAXA) global 192 193 change observation mission-water (GCOM-W) satellite. This AMSR2 Unified Level-3 (L3) dataset offers daily estimation of SWE at 25 km resolutions from July 2012 to the present. 194 195 AMSR2 has a sensor designed to detect microwave radiation naturally emitted from the surface 196 and atmosphere, employing six frequency bands ranging from 6.9 to 89 GHz. Through this conical scanning mechanism, AMSR2 can acquire day and night datasets with nearly constant 197 spatial resolution over more than 99% of the global coverage every two days. Comprehensive 198 explanations of AMSR2 characteristics are available in Imaoka et al. (2010). AMSR2 is 199 selected for the assimilation because it produces more accurate results by assimilating data 200 201 from modern sensors (e.g., AMSR2) compared to data from conventional sensors (e.g., AMSR-202 E) (Cho et al., 2017).

The widely used multisensor-derived snow cover is IMS (e.g., Ramsay 1998; Helfrich et 203 204 al., 2007) produced by NOAA the National Environmental Satellite Data and Information 205 Service (NESDIS) for the Northern Hemisphere from February 2004 to the present at 4 km resolutions. This dataset is generated using various data products, including multi-satellite 206 207 images and in-situ observations (U.S. National Ice Center, 2008). Since IMS provides binary (0: no snow or 1: snow covered) snow cover information, we transform the IMS snow cover at 208 4 km grids to the snow cover fraction (SCF) within a 50-km LSM grid by counting the snow 209 pixel number with a value of 1. A 50-km LSM grid is declared as snow-covered when more 210 211 than 50% of the 4km pixels within the grid are covered with snow. In this study, the application

of the assimilation process is determined based on IMS-based SCF, renowned for its superior 213 reliability (e.g., Brown et al., 2014). Further details will be described in Section 3.3.

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215 2.2. Reference data for SWE and SCF

216 The CMC daily estimated SWE is used for verification. The SWE data is processed using statistical interpolation between a background field derived from a simple snow model and in-217 situ daily SD (Brown and Brasnett, 2010). In detail, this dataset utilizes optimal interpolation 218 methods to acquire spatial SD from the in-situ data, involving SYNOP, special aviation reports 219 220 from the World Meteorological Organization (WMO), and meteorological aviation reports 221 (METAR). In areas with scant in-situ data, a simple snow accumulation and melt model is employed to create an optimal interpolation that estimates snowmelt and snowfall worldwide, 222 assuming the persistence of the snowpack mass between snowfall and melting events 223 (Brasnett, 1999). Although the average elevation of snow measurement stations used in CMC 224 is biased toward low elevations (< 400m), potentially causing relative negative biases at higher 225 elevations with heavy snow accumulation, the CMC dataset is often considered the premier 226 227 snow analysis accessible in the Northern Hemisphere (Su et al. 2010) and has still been widely used to evaluate model outputs (e.g., Reichle et al., 2011; Reichle et al., 2017; Toure et al, 228 2018). Therefore, the SWE of CMC produced without the satellite-derived data is selected for 229 230 verification as an independent dataset for evaluating the assimilated analysis with remote 231 sensing snow retrievals. Since only daily SD analysis is provided in CMC, it is converted to daily SWE based on the snow bulk density methods (e.g., Sturm et al., 2010). It is available 232 from 12 March 1998 to the present and offers comprehensive coverage of the entire Northern 233 Hemisphere with a horizontal resolution of 24 km. The SWE of CMC at its native horizontal 234 resolution is interpolated onto the LSM grid through local area averaging. 235

237 **2.3. JULES LSM**

This study utilizes the JULES LSM from the Met Office (Best et al., 2011), a component 238 land model of the global seasonal forecasting system version 6 (GloSea6) global, fully-coupled 239 240 atmosphere, ocean, land, and sea-ice model. The surface types (or snow tiles) in the JULES 241 LSM consist of four non-vegetated types: urban, land-ice, inland water, and bare soil, as well as five vegetation functional types: C3 temperate grass, needleleaf trees, shrubs, C4 tropical 242 grass, and broadleaf trees. For each surface tile, a separate energy balance is computed, and the 243 average energy balance in the grid cells is determined by applying weights to the values of each 244 surface tile. Two schemes are used within JULES to represent surface snow (e.g., Best et al., 245 246 2011; Burke et al., 2013). The simple method involves a zero-layer approach, which modifies the top soil level without using explicit model layers to represent snow processes. The other is 247 248 the multi-layer approach which is more comprehensive, described in Best et al. (2011). In the 249 case of vegetated surfaces, snow can be separated into ground snow and canopy snow or stored in a single effective reservoir. As both the zero-layer and multi-layer snow models provide 250 similar results under various conditions (Best et al., 2011), this study used the zero-layer snow 251 252 model with constant thermal conductivity and density for snow. Although the heat capacity of snow is ignored, the bulk thermal conductivity in the surface layer is reduced as the thermal 253 conductivity of snow differs from that of the soil and the layer thickness increases. As long as 254 255 snow persists on the ground, the skin temperature cannot exceed 0°C, yet the heat flux utilized 256 for melting the snow is diagnosed as the residual in the surface energy balance. The melted water is immediately drained from the snow, divided into runoff and soil infiltration, and liquid 257 water is not stored or frozen in the snow. A detailed description of the energy and water cycling 258 in the JULES LSM can be referenced in Best et al. (2011). 259

The prognostic variables (e.g., SWE) in the LSM are determined by meteorological forcing
variables such as 2-m air temperature, humidity, 10-m wind speed, precipitation, surface

pressure, and radiative fluxes. The 3-hourly, JRA55 reanalysis at 0.56° spatial resolution is 262 employed for the meteorological forcing variables, which is linearly interpolated to a 50 km 263 resolution of the LSM. The model background error needed for data assimilation is estimated 264 by JULES ensemble runs with perturbed initial and boundary conditions. Following the 265 previous studies (Reichle et al., 2008; Seo et al., 2021), meteorological forcing variables are 266 perturbed to account for the uncertainties in these variables, especially precipitation, downward 267 268 shortwave, and downward longwave. Perturbations are applied using additive adjustments 269 assuming a normal distribution for longwave radiation and multiplicative adjustments following a log-normal distribution for shortwave radiation and precipitation, as guided by 270 previous studies (Seo et al., 2021). Here, the ensemble means of additional and multiplicative 271 perturbations are zero and one, respectively. The relationship between disturbed precipitation 272 and radiative flux ensures the physical consistency among atmospheric forcing variables 273 (Reichle et al., 2008). For instance, a negative anomaly in precipitation and downward 274 longwave-radiation is statistically linked to a positive anomaly of downward shortwave-275 radiation. Detailed explanations regarding the perturbation of atmospheric forcings can be 276 277 found in Reichle et al. (2008).

279 **3. Methodology**

280 **3.1. Bias correction**

The discrepancy in SWE between remote sensing and LSMs often arises due to uncertainties 281 282 in the model physics and forcing data and satellite retrievals. These uncertainties can lead to a significant discrepancy in SWE between model simulations and satellite remote-sensing 283 retrievals, potentially degrading performance. In previous studies (e.g., Reichle and Koster, 284 2004; Seo et al., 2021), a scaling method of the nonlinear cumulative distribution function 285 (CDF) matching is used to account for the systematic bias of soil moisture in the model 286 backgrounds. However, unlike soil moisture, SWE presents varying characteristics in the CDF 287 distribution across different regions, such as between high and low latitudes, thus requiring the 288 estimation of distribution at each grid point. As a result, the insufficient sample size hinders 289 the clear simulation of the CDF distribution, posing challenges in its application. To address 290 this issue, we attempted to apply a simple and effective standard normal deviation scaling to 291 292 satellite-derived SWE at each grid point, considering its potential use as initial conditions for 293 JULES LSM-based climate models. Based on the climatology and standard deviation for the model and remote sensing retrievals, the scaled SWE (O_{new}) from the satellite can be derived 294 from the following relation: 295

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$$O_{new} = \left(\frac{O-\bar{O}}{\sigma_o} \times \sigma_m\right) + \bar{M}$$
(1)

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where $\overline{O}(\sigma_o)$ and $\overline{M}(\sigma_m)$ indicate climatology (standard deviation) of remote sensing retrievals and the model, respectively. This approach has been widely utilized in observationbased land initialization and has proven to be effective (e.g., Koster et al., 2011; Jeong et al., 2013).

304 3.2. Data assimilation method

The snow assimilation is conducted based on the LETKF (e.g., Hunt et al., 2007), which is 305 306 utilized to combine remotely sensed retrievals with the LSM model outputs (a.k.a. backgrounds) 307 at each grid point to produce a snow analysis. Unlike variational data assimilation methods, non-variational approaches (i.e., ensemble-based filters) characterize a probabilistic 308 309 representation with the spread of the ensemble serving as an estimate of forecast uncertainty. 310 LETKF has several advantages over other data assimilation methods. First, LETKF can efficiently handle large datasets and high-dimensional state variables by localizing the 311 covariance matrix. This offers efficiency in parallel computing, making it suitable for real-time 312 forecasting and high-resolution data assimilation. In this study, the horizontal local patch size 313 314 and the localization length scale parameters are defined as 150 km and 30 km (Table 1), respectively. This approach involves the weight function for the covariance localization within 315 316 the local patch centered at the analysis grid (e.g., Houtekamer and Mitchell, 2001; Hamill et 317 al., 2001). This function assigns larger errors to observations located farther away from the center of the local patch, as proposed by Miyoshi and Yamane (2007), depending on the 318 Gaussian function. Secondly, the method utilizes model simulation ensembles to capture the 319 uncertainty in the initial states and background errors, which allows for a better representation 320 of the flow-dependent probability distribution of the state variables that vary in time and space. 321 Third, the LETKF employs an inflation parameter to adjust the ensemble spread, ensuring 322 realistic uncertainty estimation by accounting for background errors. The underestimation of 323 the analysis error covariance is typically issued by spatially and temporally constant boundary 324 325 conditions and observation errors and limited ensemble members. Based on the standardized LETKF, this study applies a multiplicative covariance inflation of 20% of the spread of 24 326 member ensembles for each data assimilation cycle. Furthermore, the Kalman gain analysis 327 328 (Seo et al., 2021), which quantifies the ratio of the background error to the total error

(equivalent to the sum of the background and the observation error), is conducted. This analysis
serves to determine the weights assigned to assimilated observations in the analysis update
processes of the LETKF.

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3.3. Snow data assimilation design

334 This study conducts the advanced daily cycle snow data assimilation experiment at a daily eycle based on each gird point using the LETKF with based on the satellite data and the JULES 335 LSM model outputs driven by 3-hourly JRA55 reanalysis atmospheric forcing. The snow 336 assimilation processes are illustrated in Fig. 1, with a more detailed description in Table 1. 337 Since data assimilation is conducted by considering the error of SWE in both the model and 338 the observation, it is important to accurately understand the observation and background errors 339 to improve the performance of data assimilation. The experiment calculates the background 340 341 error from the 24 ensemble member spreads generated by perturbing atmospheric forcings such as longwave radiation, shortwave radiation, and precipitation in JULES LSM, as provided in 342 section 2.3. Due to the absence of precise error estimates for AMSR2 SWE retrievals, the 343 observation error is conservatively prescribed as 10% of AMSR2 SWE for each grid compared 344 to the previous study utilizing AMSR2 SWE data (Lee et al., 2015), considering the general 345 increase in the errors during the snow accumulation period with the development of deep 346 snowpack (Foster et al., 2005; Cho et al., 2017). Here, the bias-corrected AMSR2 satellite data 347 as described in section 3.1 is used as the observation data, and the updated snow analysis state 348 through data assimilation becomes a new initial state for the next integration in JULES LSM 349 (Fig. 1). In addition, the analysis state of this method is calculated based on the IMS snow 350 351 cover fraction as a reference in the following wayfollows (Fig. 1); where). If the SCF offrom IMS is zero0, the snow amount analysis is set to zero, and in other cases; otherwise, it is derived 352 353 from through data assimilation. The reason for this is due to the importance of the presence or

354 absence of snow in the climate system, as well as the high reliability of the IMS data (e.g., Brown et al., 2014). A background experiment of JULES LSM without satellite data 355 356 assimilation as a baseline (referred to hereafter as "Openloop") is also achieved by employing the same ensemble perturbations, thereby measuring the skill improvement from the snow 357 analysis state through the assimilation of satellite-derived SWE and IMS SCF from satellite 358 and surface observations (referred to hereafter as "DA"). All experiments are conducted in 359 April from 2013 to 2020, which is one of the months with low snow performance in the LSM 360 361 when the snow begins to melt in the Northern Hemisphere (e.g., Toure et al., 2018; You et al., 2020). 362

363 **4. Results**

364 4.1. Skill Verification

Figure 2 displays the climatological-mean SCF from the IMS multi-satellite data (Brown 365 366 et al., 2014) and the differences from AMSR2, Openloop, JRA55, and DA for April 2013-2020. Here, the JRA55 SWE serves as a reference dataset for comparison with other reanalyses and 367 is associated with meteorological forcing data used in the JULES land surface model. April is 368 a season when the accumulated snow during the cold season begins to melt. This study defines 369 the transitional region with a climatological-mean SWE of less than 16 mm as in previous 370 studies (e.g., Gan et al., 2021), the boundary of these transition regions is represented by the 371 372 black lines in Fig. 2. The transitional regions exhibit large variability in space and time, and they are mainly located at mid-latitudes. The SCF climatology patterns show negligible 373 differences in high latitudes of heavy snow accumulation but noticeable differences in the 374 transitional mid-latitude regions of less snow. SCF from JRA55 tends to be underestimated 375 compared to IMS, whereas AMSR2 and Openloop tend to overestimate. There is a clear 376 377 difference in SCF between AMSR2 and IMS satellite data. This study gives more credibility to IMS than AMSR2, as the former is based on multiple satellite data sources (e.g., Brown et 378 al., 2014). As we used the IMS SCF to define the snow region to be assimilated by AMSR2 379 380 SWE, it is natural that DA shows better consistency with IMS and reduces overestimation biases in Openloop. Quantitatively, the root mean square differences (accuracy, defined in 381 supplementary Table 1 as in previous study) for AMSR2, Openloop, JRA55, and DA with 382 (from) IMS are 0.23 (0.91), 0.18 (0.91), 0.13 (0.93), and 0.13 (0.97), respectively, showing the 383 best consistency in DA. The quantitative differences between DA and other experimental 384 385 results are minor, but noticeable spatial discrepancies exist, particularly around transition regions. 386

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The SWE climatology from AMSR2, Openloop, JRA55, and DA is also compared with

CMC as a reference in Fig. 3. The SWE derived from AMSR2 shows a significant 388 underestimation compared to CMC, particularly in the regions with heavy snow accumulation 389 at high latitudes. This is presumed to be due to limitations in satellite sensors detecting the 390 depth of snow (Gan et al., 2021). The SWE from JRA55 exhibits characteristics of 391 392 overestimation in high latitudes and underestimation in transitional regions. On the other hand, the climatological SWEs from Openloop and DA exhibit higher correspondence to CMC, even 393 higher than JRA55. Specifically, DA demonstrates a higher agreement with CMC, despite the 394 marginal difference compared to Openloop. Quantitatively, the pattern correlation coefficients 395 (root mean square differences) for AMSR2, Openloop, JRA55, and DA with (from) CMC are 396 $0.63 (80.7 \text{ kg/m}^2)$, $0.80 (50.1 \text{ kg/m}^2)$, $0.60 (100.8 \text{ kg/m}^2)$, and $0.80 (49.9 \text{ kg/m}^2)$, respectively. 397 Due to the application of standard deviation scaling to the satellite-derived SWE used in data 398 assimilation, the discrepancy in climatological SWE distributions between DA and Openloop 399 400 is deemed negligible. Despite its similarity to Openloop, DA with snow data assimilation displays the relatively highest correlation and the smallest root mean square difference among 401 the datasets. 402

403 Next, we compare the temporal variation of SWE as measured by the Spearman rank correlation coefficient with CMC, which is regarded as more appropriate than the Pearson 404 correlation coefficient for describing datasets containing nonlinearity and outliers such as snow 405 406 in both time and space. Figure 4 compares the distribution of correlation skills from AMSR2, 407 Openloop, JRA55, and DA. Openloop has a high performance in regions with heavy snow accumulation but relatively low performance in transition regions with significant snow 408 409 changes. In contrast, the results from the AMSR2 satellite data represent poor performance in high-latitude areas with heavy snow accumulation but high performance in transitional regions, 410 consistent with the previous studies (Gan et al., 2021). DA shows high performance not only 411 in high-latitude areas with heavy snow accumulation but also in transition regions. Even 412

compared to JRA55 used as the atmospheric forcing, DA performs better in temporal variation. 413 The quantitative results in the correlation in the Northern Hemisphere over 40°N (the transition 414 region) are 0.41 (0.54) for AMSR2, 0.61 (0.48) for Openloop, 0.58 (0.58) for JRA55, and 0.67 415 (0.61) for DA, respectively. The findings indicate that satellite retrievals offer additional value 416 417 in capturing temporal variations through data assimilation, indicating the benefit of assimilating the AMSR2 SWE despite the overall lower performance of the satellite data itself. 418 The performance improvement by DA is also evident in the zonally-averaged correlation 419 coefficient shown in Fig. 5. The AMSR2 satellite data shows higher performance than 420 Openloop in the transition region around latitude 45 °N-55 °N, although performance sharply 421 decreases with increasing snow accumulation. Openloop indicates gradually increasing 422 performance as the latitude increases, with the highest performance at around 60°N. DA 423 denotes superior performance across the Northern Hemisphere, especially in the mid-latitude 424 transition region than AMSR2 or JRA55. An exception is for 35-40°N in the Tibetan Plateau, 425 where JRA55 used in-situ observations. The results suggest that the developed snow data 426 427 assimilation system represents well not only the transitional regions but also the satellite-428 limited regions with heavyhigh snow accumulation that are difficult to detect by satellite.

429 Figure 6 presents the Spearman rank correlation depending on the SWE amount in the Northern Hemisphere. AMSR2 exhibits higher performance than Openloop for SWE up to 16 430 431 mm. However, the performance of AMSR2 sharply declines beyond that threshold, and 432 Openloop shows a better performance. Consistent with the results illustrated in Figs. 4 and 5, DA demonstrates superior performance compared to others. Note that DA performs 433 significantly better in the transition region of less than 16 mm of SWE. Considering that the 434 area below 16 mm of SWE accounts for approximately 53% of the entire area of the Northern 435 Hemisphere(as shown in the pie chart in Fig. 6), the data assimilation impact is identifiable, 436 and it can contribute substantially to the increase in the prediction skill through improving the 437

438 simulation of the albedo changes and surface energy balance.

Consistent with the description in Section 3.3, this study considers an algorithm based on 439 the highly reliable IMS satellite SCF data to identify the presence of snow and determine the 440 assimilation process. Therefore, a further sensitivity test is conducted to investigate the 441 442 influence of incorporating IMS data in snow assimilation. Figure 7 compares the correlation differences between Openloop and the data assimilation result employing both AMSR2 and 443 IMS (DA), as well as the data assimilation result utilizing solely AMSR2 and excluding IMS 444 (hereafter referred to as DA AMSR2). The results obtained from the snow assimilation show 445 the improvements in the transitional regions where AMSR2 denotes a better agreement with 446 the observations compared to Openloop. Notably, the skill is enhanced significantly in DA by 447 incorporating the IMS SCF. DA exhibits inferior performance compared to Openloop in certain 448 exceptional cases, which may be attributed to discrepancies in snow identification between the 449 CMC observations used for correlation and the IMS data utilized for data assimilation. 450 Moreover, the performance of SWE improves even when only AMSR2 is used, but 451 incorporating IMS leads to a substantial improvement in the transitional regions. This implies 452 that IMS has a positive influence on the snow data assimilation. 453

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455 **4.2 Kalman gain analysis**

In order to better understand the skill enhancement through snow assimilation of satellite data, this section examines the Kalman gain. Figure 8 illustrates the spatial distribution of observation error, model background error, and the Kalman gain<u>for SWE</u>. A high value of the Kalman gain denotes that the assimilated result is closer to the AMSR2 observation than the model background. The Kalman gain is large when the background error becomes large, or the observation error is small. As this study specifies the observation error as a conservative 10% of SWE compared to the previous study (Lee et al., 2015), the observation error basically

follows the distribution similar to the climatological-mean values. The background errors, 463 originating from the 24 ensemble members, have higher values in high-latitude regions and 464 mid-latitude regions. Data assimilation methods such as LETKF used in this study often face 465 challenges in accurately representing background errors when the ensemble spread is 466 467 insufficient. Generally, the magnitude of ensemble spread is frequently compared to the root mean square error (RMSE). The ensemble spread in this study demonstrates a sufficiently valid 468 magnitude in comparison with the RMSE, as illustrated in SFig. 1, indicating that it is well 469 470 estimated. Moreover, the SWE standardized distribution of SWE among the ensemble members 471 consistently exhibited exhibits a quasi-Gaussian distribution centered around zero, with the transition region showing a distinct this closer resemblance to a standardized Gaussian 472 473 distribution particularly evident in transitional regions (SFig. 4). In the spatial distribution of Kalman gain in Fig. 8c, significant performance improvement is observed in transition regions, 474 where Kalman gains exhibit larger values. However, in high-latitude areas with substantial 475 snow accumulation, there is a tendency for Kalman gain to have lower values. These findings 476 agree well with the bar graph in Fig. 9, which illustrates the Kalman gain as a function of SWE 477 amount. In the region encompassing the transition region with SWE amounts below 20 mm, 478 the Kalman gain displays the highest values, particularly exceeding 0.8. As the SWE amount 479 increases, the Kalman gain decreases, with a significant decline observed when the SWE 480 481 amount reaches 80-100 mm or higher. Furthermore, in the areas where DA denotes improved 482 skill compared to Openloop, the Kalman gain shows values generally above 0.7. In contrast, relatively lower values below 0.5 are observed in the areas with decreased skill. This indicates 483 that in the dominant areas of performance improvement, including the transition region, the 484 background error is significantly larger than the observation error, emphasizing the substantial 485 influence of observations in data assimilation. It is found that accurate remote sensing retrievals 486 are well reflected in regions with high uncertainty in the LSM through the snow data 487

488 assimilation system, leading to performance improvement.

489 **4.3 Validation of the SWE for the extreme event**

In April 2020, Siberia experienced a record-breaking heatwave with the highest observed 490 491 average temperature. This section investigates the potential benefits of snow assimilation using 492 satellite data for the case of the 2020 Siberian heatwave. Previous studies have identified the strong polar vortex accompanied by the AO amplification during winter as a major cause of 493 the cold Eurasian region (Overland and Wang, 2021). Additionally, it has been revealed that 494 the occurrence of high temperatures in the Siberian region is found to be closely associated 495 with large-scale atmospheric waves in the upper atmosphere over the Eurasian region 496 originating from the Atlantic (De Angelis et al., 2023). As a result, remarkable snow melting 497 occurred due to the high surface temperature over the Siberian region in April 2020, leading to 498 extremely low values of SWE and SCF as depicted in SFig. 2. This is consistent with previous 499 studies reporting a significant snow depletion in 2020 in the region (Gloege et al., 2022). 500 Especially, as shown in Fig. 10, significant negative anomalies in SWE and SCF are 501 predominant over the transition region. Substantial snow melt can contribute to record-502 503 breaking heatwaves through albedo feedback and changes in the ratio of the latent and sensible heat fluxes from the exposed surface, coupled with favorable atmospheric circulation patterns 504 (Collow et al., 2022). Collow et al. (2022) demonstrated that the exposed surface contributed 505 506 to up to 20% of the temperature anomaly over Siberia in spring 2020. This implies the 507 importance of realistic snow initial states in the global coupled model forecasts. For the Siberian region with extreme high-temperature events marked by the red box in Fig. 10, DA 508 509 shows a better agreement with the extremely dry snow conditions, especially in the transitional region, compared to the Openloop. These results are evident when considering the observation-510 to-model ratio in that region. The percentage of CMC (IMS) is 83% (78%) for Openloop and 511 93% (89%) for DA, indicating that DA with snow data assimilation based on satellite data 512

513	effectively replicates the observed snow depletion in comparison with Openloop. Similarly to
514	the 2020 case, we obtained another significant case in 2014 compared to Openloop, as shown
515	in SFig. 3. Such extremely dry snow conditions can provide significant heatwave events in the
516	following months.
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523 **5. Conclusions and discussion**

The advanced SWE data assimilation is developed in this study with the LETKF data 524 assimilation method and the JULES LSM. The system assimilates snow water equivalent 525 526 retrievals from AMSR2 and IMS snow cover. This constitutes an objective way to optimally combine two imperfect data sources for SWE from satellite remote sensing data and the land 527 surface model simulation forced by observed atmospheric data. This study shows that the 528 satellite-derived SWE has limitations in penetrating deep snow and exhibited much 529 discrepancy from the SWE obtained from the Openloop LSM simulations. The SWE 530 531 assimilation in this study proves the beneficial impacts of using satellite snow data, maintaining 532 better analysis quality by dynamically balancing the errors from the satellite observations and the model background states. 533

It is found that the simulation from Openloop as a baseline shows superior performance in 534 high-latitude regions with heavy snow accumulation but relatively inferior performance in 535 transition regions with much variation of snow in space and time. Contrastingly, the AMSR2 536 537 satellite data represent poor performance in high-latitude regions but exhibit relatively better performance in the transition regions. The SWE from the LETKF data assimilation consistently 538 exhibits better performance in capturing the climatology and temporal variation compared to 539 540 other results. It specifically improves the analysis in the mid-latitude transition regions that cover approximately 53% of the entire areas of the Northern Hemisphere. It is found that the 541 model background errors estimated from the ensemble spread are significantly larger than the 542 observation errors, thereby reflecting satellite information more in those regions. The LETKF 543 data assimilation also proves reliable representation in the heavy snow regions due to low 544 545 ensemble spread and large uncertainty in the satellite retrievals. Moreover, during the recordbreaking heatwave in Siberia in April 2020, the remarkable snow depletion observed due to 546 547 high surface temperatures is more realistically reproduced by our snow analysis compared to

548 the Openloop.

549 This snow data assimilation framework is anticipated to contribute to a more precise prediction of atmospheric conditions by realistically capturing the interaction between the 550 atmosphere and land, given the substantial influence of SWE on energy and water balance at 551 552 the interface of the atmosphere and land. Specifically, this applies to the transitional regions with high spatial and temporal variability. The long-term analysis of snow manifests a 553 pronounced variability in the continental interior at the interannual timescales, potentially 554 improving the prediction of extreme heatwave events by global climate models. This study 555 used the gridded CMC data from in-situ observations for the validation. Although existing 556 snow data are subject to much uncertainty and limitations, we expect to obtain comparable 557 conclusions and significant benefits of optimally combining satellite SWE data and the LSM 558 model simulations through LETKF data assimilation method. 559

The quality of the observation is crucial in the data assimilation system. Satellite-derived 560 snow cover exhibits a significantly higher accuracy compared to other data sources, while SWE 561 has restricted performance due to the limitations of penetration depth by satellite sensors and 562 relies heavily on estimation algorithms. Due to these problems, most previous studies and 563 operational centers primarily depend on satellite-derived snow cover for snow initialization. 564 However, the findings from this study highlighted the beneficial impacts of using satellite-565 derived SWE, particularly in the rapidly changing transition areas, to find out which variable 566 567 is more important in closing surface energy and water balance changed by snow. Nevertheless, areas of significance in large-scale circulation, such as the Tibetan region, which experiences 568 significant uncertainty and degraded performance in satellite data, do not exhibit substantial 569 data assimilation effects. As the performance of SWE derived from various satellites continues 570 to advance, these issues will be discussed more. 571

573	Key	words							
574	Snow data assimilation, AMSR2, LETKF, snow water equivalent, JULES LSM								
575									
576	Data	availability.							
577	The	AMSR2	SWE	and	IMS	SC	were	obtained	from
578	https:/	/n5eil01u.ecs.r	nsidc.org/A	MSA/AU		<u>01/</u>			and
579	<u>https:/</u>	/noaadata.apps	.nsidc.org/l	NOAA/G	<u>02156/</u> , re	spectively	y. The CM	C SWE was c	ollected
580	from	https://daacd	ata.apps.nsi	idc.org/pu	ıb/DATAS	ETS/nsic	lc0447_CN	IC_snow_dept	<u>th_v01/</u> .
581	The sr	now-assimilate	d results an	d land su	rface varia	bles from	the LSM of	offline simulat	ion may
582	be req	uested from the	e authors.						

584 *Author contributions.*

LJL conceived the project, designed the study, developed the snow assimilation system, wrote the paper, and made the figures. LMI provided advice on the methods, project design, and review and editing of the manuscript. TSL helped with the experiment with the land surface model. SEK helped with the data assimilation method based on LETKF. LYK provided advice on snow satellite data and the sensitivity methods. All authors contributed to the writing of the paper by providing comments and feedback.

591

592 *Competing interests.*

593 The contact author has declared that none of the authors has any competing interests.

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825	Table 1. Description	of the	land	surface	model,	the	data	used,	and	assimilation	experime	nt
826	designs.											

	INFORMATION	REFERENCES
Land Surface Model	JULES	Best et al., (2011)
Atmospheric Forcing	3-hourly JRA-55 reanalysis	Kobayashi et al., (2015)
Snow Observation	AMSR2 & IMS	Imaoka et al., (2010)
		Ramsay (1998)
		Helfrich et al., (2007)
Data Assimilation	Local Ensemble Transform	Hunt et al., (2007)
scheme	Kalman Filter (LETKF)	Miyoshi and Yamane, (2007)
Resolution (km)	0.5° ×0.5° (~ 50)	
	1-day DA cycle	
Localization patch size (km)	3×3 (150), σ=30	
Ensemble sizes	24	
Experiment period	2013-2020, APR	



Figure 1. Schematic diagram of the snow assimilation system with satellite-derived
observations and the land surface model outputs.



Figure 2. (a) Climatology of SCF from IMS used as reference and (b-e) the differences from 835 IMS for AMSR2, base-line model simulation (Openloop), JRA55, and the data 836 assimilation results (DA) for April during 2013-2020. The black line represents the 837 boundary of the transition region, defined as the climatological-mean SWE of less than 838 16mm. Each value on the top right is the root-mean-squared difference with IMS and 839 the accuracy from IMS (parenthesis) for 15323 pixels over 40-60°N. The accuracy is 840 defined in supplementary Table 1 as in previous study (Lee et al., 2015). Negative 841 values in red shades are indicated with a diagonal line. 842

834



846	Figure 3. (a) Climatology of SWE from CMC used as reference and (b-e) the differences from
847	CMC for AMSR2, base-line model simulation (Openloop), JRA55, and the data
848	assimilation results (DA) for April during 2013-2020. The black line represents the
849	boundary of the transition region, defined as the climatological-mean SWE of less than
850	16mm. Each value on the top right is the pattern correlation with CMC for 26482 pixels
851	over 40 °N and the root-mean-squared difference (unit: kg/m ²) from CMC (parenthesis)
852	for 15323 pixels over 40-60°N. Negative values in red shades are indicated with a
853	diagonal line.



Figure 4. SWE skill measured as the Spearman rank correlation (R) with the CMC for AMSR2,
base-line model simulation (Openloop), JRA55, and the data assimilation result (DA).
The black line represents the boundary of the transition region, defined as the
climatological-mean SWE of less than 16mm. Each value on the top is the area-average
R of North hemisphere for 26482 pixels over 40°N and for 8801 pixels over the
transition region (parenthesis). Negative values are indicated with a diagonal line.



Figure 5. Zonally-averaged Spearman rank correlation (R) along the latitude for SWE. The
yellow line indicates the climatology of SWE, and the black, blue, green, and red lines
denote the values of AMSR2, base-line model simulation (Openloop), JRA55, data
assimilation results (DA), respectively.



Figure 6. Box plots of the Spearman rank correlation (R) according to SWE. The pie chart
shows the total area ratio (%) as a function of SWE amount. The black, blue, and red
boxes denote the AMSR2, base-line model simulation (Openloop), and the data
assimilation results (DA), respectively. The boxes indicate 25 and 75% percentiles, and
the line and point in the boxes shows the median and the mean values. The upper and
lower whiskers denote the 10 and 90% percentiles, respectively.



Figure 7. The difference in SWE Spearman rank correlation coefficient with CMC between
the Openloop and data assimilation results: DA employing both AMSR2 and IMS and
DA_AMSR2 utilizing solely AMSR2 and excluding IMS, for April during 2013-2020.
The black line represents the boundary of the transition region, defined as the
climatological-mean SWE of less than 16mm. Each value on the top right is the areaaverage over 40°N and the transition region (parenthesis). Negative values are indicated
with a diagonal line.



Figure 8. Spatial distribution of observation error (unit: kg/m²), background error (unit: kg/m²),
and Kalman gain. The black line represents the boundary of the transition region,
defined as the climatological-mean SWE of less than 16mm.



Figure 9. Bar chart of (left) the Kalman gain according to the SWE amount, and (right) the
Kalman gain (red line) and background error (blue line) as a function of the difference
between Openloop and DA in Spearman rank correlation coefficient (R).



Figure 10. Anomalies of a) SWE from CMC and b) SCF from IMS as well as the difference
(c, d) of variables between DA and openloop in April 2020. Bar chart (e, f) indicates
the ratio of DA and openloop to verification data such as CMC and IMS in the red box
(48–65°N and 55–120°E), which is the region associated with extreme high-temperature
events, focused on this study. Negative values are indicated with a diagonal line.