Climate and parameter sensitivity and induced uncertainties in carbon stock projections for European forests (using LPJ-GUESS 4.0)

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15 Abstract

Understanding uncertainties and sensitivities of projected ecosystem dynamics under environmental change is of immense 16 17 value for research and climate change policy. Here, we analyze sensitivities (change in model outputs per unit change in 18 inputs) and uncertainties (changes in model outputs scaled to uncertainty in inputs) of vegetation dynamics under climate change, projected by a state-of-the-art dynamic vegetation model (LPJ-GUESS v4.0) across European forests (the species 19 20 Picea abies, Fagus sylvatica and Pinus sylvestris), considering uncertainties of both model parameters and environmental 21 drivers. We find that projected forest carbon fluxes are most sensitive to photosynthesis-, water- and mortality-related 22 parameters, while predictive uncertainties are dominantly induced by environmental drivers and parameters related to water 23 and mortality. The importance of environmental drivers for predictive uncertainty increases with increasing temperature. Moreover, most of the interactions of model inputs (environmental drivers and parameters) are between environmental 24 25 drivers themselves or between parameters and environmental drivers. In conclusion, our study highlights the importance of 26 environmental drivers not only as contributors to predictive uncertainty in their own right, but also as modifiers of 27 sensitivities and thus uncertainties in other ecosystem processes. Reducing uncertainty in mortality related processes and 28 accounting for environmental influence on processes should therefore be a focus in further model development.

29 1. Introduction

30 Terrestrial ecosystem models have emerged in the last three decades as a central tool for decision making and basic research 31 on vegetation ecosystems (Cramer et al., 2001; Fisher et al., 2018; IPCC, 2014; Smith et al., 2001; Snell et al., 2014). 32 Projections from different vegetation models, however, often disagree on important details, for example regarding the 33 observable past (Bastos et al., 2020) or the future carbon uptake of forest ecosystems (Huntzinger et al., 2017; Krause et al., 34 2019). Among the possible reasons for such differences is the uncertainty in climate scenarios (Saraiva et al., 2019), model 35 structural uncertainty (Bugmann et al., 2019; Oberpriller et al., 2021; Prestele et al., 2016), initial condition uncertainty 36 (Dietze, 2017b) as well as uncertainty about the model parametrization (Grimm, 2005), which in turn make models' 37 projections themselves uncertain (Dietze, 2017a). It is widely appreciated that understanding which exact factors drive these 38 uncertainties is of immense value for directing research (Tomlin, 2013), but also to interpret and understand projections 39 (Dietze et al., 2018). For example, the IPCC started in its Fifth Assessment Report to systematically analyze uncertainties and attribute them to model inputs (IPCC, 2014) similar to other predictive sciences (e.g. nuclear reactor safety (Chauliac et 40 41 al., 2011), energy assessment for buildings (Tian et al., 2018) or policy analysis (Maxim and van der Sluijs, 2011)).

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43 The two main tools to understand how uncertainties in model inputs (drivers, parameters, and model structure) affect model 44 outputs are sensitivity analysis (SA) and uncertainty analysis (UA) (Cariboni et al., 2007; Caswell, 2019; Saltelli, 2002; 45 Saltelli et al., 2008). The key difference between these two methods is that in an UA, the central starting point is the 46 quantification of uncertainty in the model inputs (e.g. parameters, typically determined via expert elicitations and previous 47 studies (Matott et al., 2009)). This uncertainty is then propagated to the model outputs, and back-attributed to the different 48 inputs. An SA, on the other hand, calculates how the model output changes per unit or percentual change of the respective 49 input (Jørgensen and Bendoricchio, 2001). This calculation is primarily independent of the inputs' uncertainties, although 50 local SAs can be affected by the reference point and global SAs by the range over which the sensitivity is calculated. 51 Overall, however, both methods share the goal of identifying inputs with a high influence on model outputs, with the 52 underlying idea that better constraining these will increase robustness and reliability of model projections (Balaman, 2019).

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Although the benefits for understanding model behavior and predictive uncertainties are obvious, relatively few SAs and UAs have been applied to complex ecosystem models and especially the widely used dynamic global vegetation models (DGVMs) that project terrestrial ecosystem responses to climate change or land management (see, e.g., Courbaud et al., 2015; Cui et al., 2019; Huber et al., 2018; Reyer et al., 2016; S. Tian et al., 2014; Wang et al., 2013). A reason for this is arguably the complex structure of most DGVMs (Fer et al., 2018), which makes SAs and UAs computationally demanding and difficult to interpret, especially when performing state-of-the-art global SAs and UAs that compute sensitivities and uncertainties across the entire parameter space (Saltelli et al., 2008) rather than just locally around a reference parameter set 62 (see e.g., Hamby, 1994). Moreover, several studies highlight that sensitivities and uncertainties of DGVMs also exist with 63 respect to environmental drivers (Barman et al., 2014; Wu et al., 2017, 2018), especially solar radiation (Barman et al., 2014; 64 Wu et al., 2018), temperature (Barman et al., 2014) and precipitation (Wu et al., 2017), and it is reasonable to expect that 65 there can be interactions between parameter and environmental sensitivities, meaning that certain parameters are more 66 sensitive in some environments than in others. It therefore seems important to investigate parametric sensitivities in 67 conjunction with their environmental sensitivities in one combined analysis.

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69 In this study, we concentrate on a well-established and widely applied DGVM, the Lund-Potsdam-Jena General Ecosystem 70 Simulator (LPJ-GUESS) (Gerten et al., 2004; Sitch et al., 2003; B. Smith et al., 2001). Three previous SAs or UAs for the LPJ family identified the intrinsic quantum efficiency of CO₂ uptake (alpha C3) and the photosynthesis scaling parameter 71 72 (from leaf to canopy) (alpha a) as the main contributors of sensitivity for net primary production (NPP) (about 50-60% of 73 the overall sensitivity. Zaehle et al., 2005; Pappas et al., 2013) or foliage projective cover (Jiang et al., 2012). Additionally, 74 these previous studies show that LPJ-GUESS projections of NPP and vegetation carbon pools showed high sensitivity to tree 75 structure-related (sapwood to heartwood turnover rate, longevity of trees, Pappas et al., 2013; Wramneby et al., 2008; Zaehle et al., 2005), establishment-related (maximum sapling establishment rate, minimum forest floor photosynthetically active 76 77 radiation for tree establishment, Jiang et al., 2012; Wramneby et al., 2008; Zaehle et al., 2005), mortality-related (threshold 78 for growth suppression mortality, Pappas et al., 2013) and water-related parameters (minimum canopy conductance not 79 associated with photosynthesis, maximum daily transpiration, Pappas et al., 2013; Zaehle et al., 2005). Regarding 80 uncertainties, strong impacts on LPJ-GUESS projections of NPP and vegetation carbon pools (FPC for Jiang et al., 2012) were found for photosynthesis related parameters (Jiang et al., 2012; Zaehle et al., 2005), but also for water-related 81 82 (minimum canopy conductance not associated with photosynthesis, Zaehle et al., 2005) as well as structure-related 83 parameters (tree leaf to sapwood area ratio, crown area to height function Jiang et al., 2012), whereas soil hydrology 84 parameters were not identified as very sensitive in earlier studies (Pappas et al., 2013).

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Since the publication of these studies, however, the structure of the LPJ-GUESS model changed substantially. The most important changes are the inclusion of the nitrogen cycle (Smith et al., 2014) and new management modules (Lindeskog et al., 2021). Since these changes, no study has systematically examined how model sensitivities and uncertainties were affected by the new model structure. Moreover, previous SAs and UAs ignored management parameters, which, however, are expected to have large impacts on carbon pools and fluxes (Lindeskog et al., 2021).

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A further limitation of most previous studies for LPJ-GUESS and other models (e.g. Mäkelä et al., 2020) is that they either analyzed sensitivities and uncertainties to parameter changes, or to changes in the environmental drivers, but not both. As discussed earlier, however, there are good reasons to expect that the sensitivity of parameters will change if environmental drivers change. Given that previous sensitivity analyses used different choices for these boundary conditions (different

96 sensitivities for the climate scenarios and sites in Jiang et al., 2012; for different elevations in Pappas et al., 2013; different 97 sites in Wramneby et al., 2008), this not only limits the comparability between studies, but also questions the generality of 98 the results for all climatic conditions. Only Jiang et al. (2012) combined parameter and driver sensitivities, but used for the latter only a number of fixed climate scenarios instead of a range of possible values, which prohibits a systematic joint 99 analysis. Moreover, it would be interesting to compare the relative importance of drivers and parameters for the predictive 100 101 uncertainty of model simulations and how these change between environmental zones (here we use the classification of 102 Metzger et al., 2005) and thus on an environmental gradient. When sensitivities or uncertainties of parameters belonging to a specific process increase on an environmental gradient, this indicates that the process itself becomes more important on the 103 gradient (Saltelli, 2002). By comparing such changes to existing ecological hypotheses, we can test if model sensitivities and 104 105 thus process descriptions are in line with ecological expectations.

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107 To answer these questions, we analyzed sensitivities and uncertainties in LPJ-GUESS for 200 randomly distributed sites 108 across Europe (see Appendix A1.1). We address the issue of interactions between environmental and parametric sensitivities 109 by simultaneously investigating uncertainty in environmental drivers (precipitation, temperature, solar radiation, CO₂, 110 nitrogen deposition) with parametric uncertainty in the most important processes (photosynthesis, establishment, nitrogen, water cycle, mortality, disturbance/management, and growth) for dynamic climate change from 2001-2100 and steady 111 112 climate from 2100-2200. We simulated the most abundant tree species in Europe (Fagus sylvatica, Pinus sylvestris and 113 *Picea abies*) individually and in mixed stands, as these species are suffering from climate change (e.g. Buras et al., 2018; Walentowski et al., 2017) and could benefit from mixed stands (e.g. Pretzsch et al., 2015). To test climate change impacts, 114 115 we randomly sampled climate projections within the boundaries of RCP2.6 and RCP8.5. Thereby, our key objectives were to understand the sensitivities and uncertainties of LPJ-GUESS due to environmental drivers and parameters. We were 116 117 especially interested in 1) overall sensitivities and uncertainties across European forests, 2) uncertainties per environmental 118 zone and 3) uncertainties on a temperature gradient. Moreover, we investigated, 4) if and how environmental conditions 119 change the uncertainties of environmental processes.

120 2. Methods and Material

121 2.1. The LPJ-GUESS vegetation model

LPJ-GUESS is a process-based ecosystem model that simulates vegetation growth, vegetation dynamics and biogeography as well as biogeochemical (e.g. nitrogen and carbon) and water cycles (Lindeskog et al., 2013; Olin et al., 2015; Smith et al., 2014). Ecosystem dynamic processes in the model include establishment, growth, mortality, and competition for light, space and soil resources. To simulate these processes, the model combines time steps on different scales from daily (e.g. phenological and photosynthesis processes) to yearly (e.g. allocation of net primary production to tree carbon components) 127 basis. LPJ-GUESS includes forest gap dynamics succession of cohorts (each represented by an average individual) of

- 128 different plant functional types (PFTs) or species. Each PFT/species has a unique parameter set.
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In this study, we use a model version that was slightly modified from Lindeskog et al. (2021), which is based on the LPJ-130 GUESS 4.0 version, with a re-parameterization for spruce (*Picea abies*), pine (*Pinus sylvestris*) and beech (*Fagus sylvatica*) 131 132 (see Appendix A1.2 for Pin. syl. and Pic. abi.). To account for the stochastic components of establishment, mortality and 133 patch destroying disturbances, LPJ-GUESS simulates several replicate patches (25 for the simulation with the reference parametrization and 1 for each simulation in the SA and UA) representing "snapshots" of the grid-cell. In this model version, 134 135 fire is based on the BLAZE model (Rabin et al., 2017). Thereby annually burned area is generated based on fire weather and fuel continuity and distributed to monthly intervals based on climatology (Giglio et al., 2010). Tree mortality is then 136 137 estimated by computing firelines based on weather and converted into height-dependent survival probabilities (see Haverd et 138 al., 2014) depending on empirical biome specific parameters.

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A first set of key parameters from our expert elicitation (see below) for **establishment** are the bioclimatic limits (i.e. minimum growing degree days (*gdd5min_est*), minimum 20-year coldest month (*tcmin_est*), maximum 20-year coldest month (*tcmax_est*) and minimum forest photoactive radiation at forest floor (*parff_min*)), which build the environmental envelope for establishment. Given the bioclimatic limits are fulfilled, at regular intervals new PFTs are established (here: 1 year) given enough space, light, soil water and photoactive radiation at forest floor is available for establishment (B. Smith et al., 2001). Moreover, each of our three investigated species has a maximum establishment rate (*est_max*) (B. Smith et al., 2001).

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148 Structure of trees in the model is mainly linked to the simulated growth of trees, which is triggered by allocating all net 149 primary production (NPP) besides a reproduction debt of 10% (reprfrac) to tree components thereby satisfying mechanical balance (e.g. allometric eq. for the relationship between height and diameter with allometric parameters (k allom2, 150 k allom3) (e.g. Huang et al., 1992), the relationship between tree leaf to sapwood area (k latosa) (e.g. Robichaud & 151 Methven, 1992), the relationship between crown area and height (k rp) (packing constraint, Zeide, 1993), the maximum 152 crown area (crownarea max) and leaf longevity (leaflong)) and functional balance as well as demographic constraints (Sitch 153 154 et al., 2003). Each living tissue is assigned a turnover rate transferring sapwood into heartwood (turnover sap) and leaves (turnover leaf) and fine roots (turnover root) to litter. Investment into above and belowground growth is influenced by the 155 156 resource stress as individuals are competing for light, space, nitrogen and water. Competition for light is determined by the photosynthetic response and light extinction in the canopy. Competition for space (self-thinning) is represented in the model 157 158 via allometric equations between crown area and stem diameter (Sitch et al., 2003). Competition for nitrogen and water is 159 determined by tree individual demand for nitrogen and water and soil availability of nitrogen and water and the PFT-specific 160 root profile. Competition between species will favor certain life-history strategies in particular situations, for example shade161 tolerant (e.g. Fagus sylvatica and Picea abies) or intermediate-shade tolerant (e.g. Pinus sylvestris) growth responses, and

162 dynamically changing root-to-shoot ratios.

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Tree mortality (natural or via harvest) in the model responds to growth efficiency (ratio of annual NPP to leaf area) being 164 too low over a 5-year period, e.g. due to light competition, maximum longevity of a PFT or changes in environmental 165 166 conditions (e.g. tolerance to drought *(drought tolerance)* changes water uptake) exceeding the species suitable range. Light 167 competition is modeled using the foliage projective cover (FPC), defined as the area of ground by foliage directly above it, using Beer's Law (B. Smith et al., 2011). The resulting shading mortality is distributed proportional to species' FPC growth 168 169 in the respective year due to their biomass increase. Mortality is modeled inversely proportional to the growth efficiency (with a given species-specific threshold (greff min), e.g. Waring (1983)). Moreover, negative NPP of a species kills all 170 171 individuals of the respective cohort. Background mortality probability increases with tree age, reaching one at the maximum 172 longevity (longevity). Mortality has also a stochastic component. Natural disturbances are implemented in the model as process-based wildfires (with a given fire resistance for each species (*fireresist*)) and as patch-destroying disturbances (e.g. 173 174 windthrow and landslides) with the same yearly occurrence probability for all patches (inverse of *distinterval*). Additional mortality arises from forest management activities, determined by thinning intensity (percentage of all trees cut, 175 176 thinning intensity) and cutting intervals (cut interval), which can be set for each species individually. For a more detailed 177 description of the management module and the additional management parameters see Lindeskog et al. (2021).

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Nitrogen input is implemented in the model through nitrogen deposition (prescribed) and biological nitrogen fixation. The latter is simulated empirically as a linear function with intercept ($nfix_a$) and slope ($nfix_b$) of the five-year averaged actual evapotranspiration (Cleveland et al., 1999). The resulting amount of nitrogen accumulates in the ecosystem equally over the year and directly adds to the available mineral soil nitrogen pool. When nitrogen is in living tissue, a fraction (*nrelocfrac*) is re-translocated before leaf- and root shedding.

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Photosynthesis is modeled as a function of absorbed photosynthetically active radiation, temperature (optimum temperature range for photosynthesis determined by *pstemp_low and pstemp_high*, Larcher, 1983), intercellular CO₂ (i.e. non-water stressed ratio of intercellular to ambient CO₂ (*lambda_max*)), and canopy conductance thereby considering a species-specific respiration coefficient (*respcoeff*) (B. Smith et al., 2001) and nitrogen availability. The photosynthesis scheme is a modified version of the Farquhar photosynthesis model, but instead of prescribed values for the Rubisco capacity it is optimized for maximum net CO₂ assimilation at the canopy level (Smith et al., 2014).

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Water availability for plants is based on precipitation and snowmelt in the two-layer soil hydrology submodule (for details see Hickler et al., 2004; Smith et al., 2001). Vegetation transpiration and evaporation (with a maximum evapotranspiration rate (*emax*)) from bare ground and leaves reduce water availability as well as runoff from saturated soil (Sitch et al., 2003).

Water vapor exchange by the vegetation canopy is calculated on a daily basis within the photosynthesis scheme (e.g. minimum canopy conductance not associated with photosynthesis (*gmin*)). The water supply and transpirative demand are calculated on a daily basis and converted into a drought-stress coefficient. Given this coefficient, the investment in roots at

198 the costs of leaves is calculated.

199 2.2. Simulation setup

We selected 200 study sites (see Appendix A1.1) spatially and environmentally stratified over Europe by applying random stratified sampling (using the R package splitstackshape Mahto, 2019) with longitudinal and latitudinal coordinates as well as mean precipitation, solar radiation and temperature as categories based on IPSL-CM5 Earth System Model CMIP5 (Dufresne et al., 2013) climate data. We chose 200 sites as a compromise between the high computational demand of running LPJ-GUESS multiple times for all sites and a good spatial as well as environmental coverage of Europe. For these sites, we performed simulations for each of the three most common species in Europe (*Fagus sylvatica, Pinus sylvestris* and *Picea abies*) as monospecific stands and additionally all three species together as mixed stands.

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208 The simulation period was from 1861 to 2199. To start the simulations with equilibrium C pools and fluxes, we spun up LPJ-209 GUESS vegetation and soil carbon and nitrogen pools to pre-industrial equilibrium by recycling the 1861 to 1900 climate, 210 the 1861 CO₂ concentration (Meinshausen et al., 2011) and nitrogen deposition. For the transient and future simulation runs, 211 we used the bias-corrected monthly IPSL-CM5 Earth System Model CMIP5 (Dufresne et al., 2013). From this data set, we 212 extracted temperature, precipitation, number of wet days per month, and incoming solar radiation from 1861 to 2099 for RCP4.5 as base scenario and RCP2.6/RCP8.5 as lower/upper boundaries for the climate ranges (see below). In addition to 213 214 these data, monthly nitrogen deposition was extracted from Lamarque et al. (2013) and soil texture data from Baties (2005). 215 All these driving data had a spatial resolution of 0.5°x 0.5°. We recycled detrended data from 2090-2099 for all environmental drivers except CO_2 and nitrogen deposition and used these as potential stable climates for the 2100-2199 216 period. 217

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219 **2.3.** Selection of parameters and drivers and their ranges

The a priori selection of the most influential parameters that can be specified in the parameter file and their ranges was based on our expert knowledge (following the SHELF expert elicitation protocol, see Gosling, 2018) and a literature review. The resulting eleven (= 33%) parameters common for all species and 22 (= 20%) species-specific parameters (see Table 1) were grouped to the specific processes they contribute most to (Table 1, Grouping).

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From the environmental drivers of the model, we selected incoming solar radiation, temperature, precipitation, atmospheric CO₂ and nitrogen deposition for our analysis. To obtain uncertainties for temperature, precipitation and solar radiation, we calculated the mean deviations of RCP8.5/RCP2.6 to our base scenario RCP4.5 plus/minus one standard deviation as maximal/minimal per site. As the CO₂ data is global and not site-specific, we calculated ranges from the global data set (RCP2.6 as minimum, RCP8.5 as maximum) averaged over time and plus/minus a standard deviation. For nitrogen deposition, we used RCP6.0 as maximum and RCP2.6 as minimum with the same procedure as for the other drivers.

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232 2.5. Sensitivity analysis and uncertainty analysis

LPJ-GUESS predicts a substantial number of output variables, which could all be examined regarding their sensitivities and uncertainties. Here, we concentrate on carbon outputs (gross primary production GPP, total standing biomass TSB and net biome productivity NBP), because of forests' role for carbon cycling (Bonan, 2008), their large contribution to the land carbon sink (Pugh et al., 2019) and the economic importance of tree growth for forest owners (Pearce, 2001).

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Sensitivities and uncertainties were calculated by Monte-Carlo sampling from the assumed multivariate parameter and climate uncertainty. For the monospecific / mixed simulations, we drew respectively 10.000 / 50.000 parameter and climate combinations randomly from the prespecified uncertainty ranges, and ran the model based on these combinations for each of the 200 sites. Note, that for mixed simulations, for each simulation we individually drew parameter combinations for each species, i.e. the same parameter could be different for different species. In total, this means that 200 x (50.000 + 3 x 10.000) = 16 million LPJ-GUESS simulations were run.

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245 We quantified sensitivity and uncertainty indices by running multiple linear regressions with the model output averaged over 246 time as response, and parameters and drivers as well as their second order interactions as predictors. With 200 sites, each 247 having three monospecific and one mixed stands setup, we overall ran 200x (3 + 1) = 800 linear regressions. This analysis 248 corresponds to a global SA/UA in the context of regression analysis and has been applied to other system models (e.g. Sobie, 249 2009). The estimated effects from the regression can be interpreted as sensitivities, as the effect of a unit change of the driver 250 on the response (model output) is estimated. By scaling the predictors to the range [-0.5, 0.5], we obtained the corresponding uncertainties. To check whether we missed non-linear effects, we additionally applied a random forest and extracted the 251 252 variable importance (following Augustynczik et al., 2017, see Appendix A1.3.). To calculate mean sensitivities/uncertainties 253 for each species, we averaged site-specific sensitivities over all sites with an average annual biomass production greater than 254 2 tC/ha. We have chosen this threshold because smaller values indicate that the environment is not suitable for the species, 255 however, for each site at least one species was able to establish. For the mixed stands, we first averaged the three species-256 specific sensitivities/uncertainties per site and then averaged over all sites. Mean percentual sensitivities were calculated by 257 dividing by the mean model output, while mean uncertainty contributions were calculated by dividing by the entire uncertainty budget. Thereby, positive values mean that the respective output increases with increasing parameter values, while negative values mean that it decreases.

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It is important to note that uncertainties and sensitivities have different interpretations, and which of these two is more 261 relevant strongly depends on the purpose. The calculated percental sensitivities can be interpreted as percentage change in 262 263 the corresponding output, when changing a parameter value 1% in the prespecified range. The calculated uncertainties per 264 parameter/driver can be interpreted as relative proportion of the overall uncertainty budget coming from environmental drivers and parameters. For scenario-analysis, e.g. comparing different cut intervals of forests, sensitivities provide a direct 265 estimate of the model response, e.g. how much biomass changes when the cut interval is changed. For a comparison of 266 different model forecasts, uncertainties are usually more relevant. If a reduction of uncertainty via a model-data comparison 267 is the purpose, both measures are important, as parameters with high sensitivities can contribute more or less predictive 268 269 uncertainty, depending on their input uncertainty.

270 3. Results

271 3.1. Mean sensitivities over Europe

272 Regardless of the output variable, LPJ-GUESS was most sensitive to photosynthesis-related parameters (respcoeff, *lambda max*), parameters controlling the wood turnover (*turnover sap*) and tree allometry (k rp), water-related parameters 273 274 (*emax*), mortality-related parameters (*greffmin*) and environmental drivers (temperature, CO₂ and solar radiation) (Fig. 1). 275 When looking at differences in the strength of sensitivities for different outputs, TSB was most sensitive to the respiration 276 coefficient (respcoeff), the growth suppression mortality threshold (greff min) and solar radiation while NBP projections 277 showed negative sensitivity to wood turnover rates (turnover sap) and longevity and positive sensitivity to temperature, CO₂ and the ratio of intercellular to ambient CO_2 (*lambda max*). GPP was negatively sensitive to the respiration coefficient 278 279 (respcoeff), growth suppression mortality threshold (greffmin), tree allometry (k rp) and temperature and positive to CO₂, 280 solar radiation and the maximum transpiration rate (*emax*). Establishment and nitrogen showed the smallest sensitivities for 281 all three carbon-related projections (Fig.1). Note also that NBP had higher percentual sensitivities than GPP and TSB.

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Mixed stands were less sensitive to changes in parameters than mono-specific stands (Fig. 1). For monospecific simulations, species sometimes showed different magnitudes and even directions of sensitivities, especially *Fag. syl.* was more strongly affected by bioclimatic limits and *Pin. syl.* showed higher sensitivity to environmental drivers (temperature and solar

radiation) than the other species. Moreover, TSB and GPP are negatively sensitive to temperature except for Fag. syl. For

287 NBP, the direction of sensitivities changes between species for the non-water-stressed ratio of intercellular to ambient CO₂

288 (lambdamax), the respiration coefficient (respcoeff), the root turnover (turnoverroot), an allometric constant (krp) and the

289 maximum evapotranspiration rate (emax).

292 **3.2. Mean uncertainties over Europe**

Looking at uncertainties, we found that environmental drivers contributed most of all processes/drivers to the predictive 293 294 uncertainty (Fig 2), regardless of the considered model output. For TSB projections, CO₂, solar radiation and temperature 295 contributed substantial uncertainty (Fig. 2a). Additionally, large uncertainty contributions arose from growth suppression 296 mortality thresholds (greffmin) and the respiration coefficient (lambda max). Uncertainty in NBP projections was 297 substantially affected by model parameters (longevity (Mortality process), tcmax est (Establishment process), turnover sap 298 (Tree structure process), greffmin (Mortality process) and emax (Water process)), additionally to the high contributions of 299 temperature and CO₂ (Fig. 2b). For GPP projections, solar radiation and CO₂ contributed most to climate induced uncertainty, while the threshold for growth suppression mortality (greffmin) and maximum evaporation rate (emax) 300 301 contributed most to parameter induced uncertainty (Fig. 2c). Notably, also nitrogen-fixation induced uncertainty was 302 substantial (7-9%) for TSB and GPP. Most tree structure related parameters except the sapwood to heartwood turnover rate (turnoversap) and the fraction of NPP allocated to reproduction (repfrac) contributed only small uncertainties (Fig. 2). 303 304 Uncertainty contributions analyzed by a random forest are similar to linear regression results (see Appendix 1.3.).

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306 By analyzing uncertainty contributions on a species level, a more diverse picture emerged. *Fag. syl.* was more affected by 307 temperature and less by solar radiation than the other species. Additionally, we found that uncertainty contributions of 308 environmental drivers were substantially higher for mixed than for mono-specific stands.

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310 **3.3.** Geographic variation in uncertainties of TSB across Europe

To project the uncertainties of TSB (for GPP and NBP see Appendix 1.4.) into the European environmental space, we filtered stands according to environmental zones, then calculated mean uncertainties per environmental zone and aggregated these per process.

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The broad pattern of TSB uncertainty contributions for all three monospecific and mixed stands remains similar in all environmental zones. On average across all environmental zones, stands and species about 45% of the uncertainty was due to environmental drivers, 15% due to mortality-, 14% due to photosynthesis-, 12% due to structure-, 7% due to water- and 7% due to nitrogen-related parameters (Fig. 3).

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For the individual environmental zones, however, there were subtle differences. In the Mediterranean mountain (MDN) and Pannonian (PAN) zone, environmental driver induced uncertainty was higher than on average especially for monospecific 322 stands (Fig. 3). In the Boreal (BOR), Atlantic central (ATC), and Atlantic north (ATN) zone, tree structure- related 323 uncertainty increased compared to the average pattern (Fig. 3). In the Atlantic central (ATC) and Atlantic north (ATN) zones 324 nitrogen related uncertainty increased for all species and stands (Fig. 3).

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To examine this spatial pattern further, we investigated the change of uncertainties across a temperature gradient. To this end, we aggregated the uncertainties per site and process/driver and then fitted a linear regression with the process/driver as predictor and the aggregated uncertainties as dependent variables.

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For TSB, we found that increasing mean annual temperature increased the uncertainty contributions of environmental drivers, water- and establishment-parameters, while the uncertainty due to nitrogen- and tree structure- related parameters decreased (Fig. 4a). Thereby, the uncertainty contributions of environmental drivers ($\approx 0.4\%$ /°C) increased the most (measured in percentage points per °C) and uncertainty contributions of nitrogen fixation decreased most ($\approx -0.5\%$ /°C). Mortality and photosynthesis stayed approximately constant on the gradient (Fig. 4b).

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Looking in more detail at the environmental drivers, temperature (\approx +0.75%/°C) as well as CO₂ (\approx +0.2%/°C) and precipitation (\approx +0.25%/°C) induced uncertainty increased with mean annual temperature, while the uncertainty contribution of solar radiation (\approx -0.75%/°C) decreased with mean annual temperature (Fig. 4c). Nitrogen deposition induced uncertainty contributions stayed approximately constant on a mean annual temperature gradient.

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The above geographical and correlative observations of changing uncertainties across Europe receive further support when looking at the interactions between uncertainties of different drivers/parameters (Fig. 5). Interaction indices were calculated by averaging the interactions found in the linear regression over all sites and species (Fig. 5b). Moreover, to investigate the overall influence on other parameters or drivers we summed the absolute individual interaction indices of each parameter with each other (Fig. 5a).

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We found that environmental drivers (temperature, solar radiation, CO₂ and precipitation) had the highest sum of interactions 347 348 for TSB (Fig. 5a). Moreover, the respiration coefficient (respcoeff), the growth suppression mortality threshold (greffmin), 349 longevity, the sapwood to heartwood turnover rate (turnover sap) and maximum evaporation rate (emax) had a lower, but 350 still high sum of interactions (Fig. 5a). Establishment and nitrogen related parameters had only a few weak interactions (Fig. 351 5). Strong interaction effects occurred mostly with environmental drivers (Fig. 5b). A main part of these interactions was between the different environmental drivers themselves (solar radiation - CO₂ and solar radiation - temperature). 352 Additionally, we found interactions of parameters and environmental drivers (temperature-sapwood to hardwood turnover 353 354 (turnover sap), temperature – threshold for growth suppression mortality (greffmin) and temperature-respiration coefficient 355 (respcoeff) (Fig. 5b)) and moderate parameter-parameter interactions (longevity (Mortality process) - greffmin (Mortality 356 process), respcoeff (Water process) - longevity (Mortality process) (Fig. 5b)). Similar patterns were present for the other two

357 carbon outputs (see Appendix A1.4.).

358 4. Discussion

359 In this study, we analyzed sensitivities and uncertainties of the LPJ-GUESS vegetation model due to environmental driver 360 and parameter variations across European forests. We found that the model is most sensitive to relative (percentage) changes in photosynthesis-related parameters, structure-related parameters controlling the wood turnover and tree allometry, water-361 362 related parameters, mortality-related parameters, and environmental drivers (Fig.1), irrespective of the considered output 363 variable. When considering the different uncertainties (i.e. the entire plausible range) in these parameters and the environmental inputs, we found that environmental drivers and parameters controlling evapotranspiration, background 364 365 mortality and nitrogen cycling contribute most to predictive uncertainty (Fig. 2). When correlated against a temperature gradient and thus geographically from north to south, uncertainty contributions to TSB increased for environmental drivers 366 367 and decreased for tree structure and nitrogen-related parameters (Fig. 3, 4). Interactions between the uncertainty 368 contributions were mainly between different drivers or between model parameters and drivers, whereas only a few 369 parameter-parameter interactions were present (Fig. 5).

370

371 Our finding that average sensitivities of carbon-related projections across European forests were highest for photosynthesis-372 related parameters amplifies the evidence from earlier studies (Pappas et al., 2013; Zaehle et al., 2005), although we have 373 used different parameter ranges. In addition, the finding about high sensitivity of LPJ-GUESS to parameters controlling tree 374 structure and especially carbon turnover (turnover sap) (Fig. 1) is in line with results reported for a previous version of LPJ-375 GUESS (Pappas et al., 2013) and its important role for carbon allocation in trees found in empirical studies (e.g. Herrero de 376 Aza et al., 2011). The finding that carbon-related projections are very sensitive to mortality-related parameters (greffmin) is 377 also supported by previous studies on the sensitivity of vegetation models and underlines the importance of improving 378 mortality submodules for generating precise projections of vegetation dynamics (Bugmann et al., 2019; Hardiman et al., 2011). Moreover, sensitivities in mixed stands were lower than in mono-specific stands for NBP and GPP (Fig. 1) (in line 379 380 Wramneby et al., 2008). The reason for that imbalance may be that other species can dampen and even benefit from non-381 optimal life-history strategies of an individual species (Loehle, 2000). Another reason might be, that for mixed simulations 382 we sampled parameters for each species individually, which reduces the influence of each parameter on stand-level carbon 383 projections.

384

We found that uncertainty contributions of environmental drivers were comparable to the uncertainty contributions of all parameters together (Figs. 2-5, see also Snell et al., 2018 for the FLMs model, but see Petter et al., 2020, who found that most uncertainty is induced by the choice of the forest model). Especially high uncertainty contributions arose from 388 temperature (negative effect for TSB, GPP positive for NBP), CO₂ (positive effect for all variables) and solar radiation 389 (positive effect for all variables). These results are supported by the earlier studies on the effect of environmental drivers in DGVMs (Barman et al., 2014; Wu et al., 2017, 2018). The positive effect of CO₂ could be explained by increased water-use 390 efficiency and the CO₂ fertilization effect (also found for other DGVMs Keenan et al., 2011; Galbraith et al., 2010), which in 391 392 LPJ-GUESS is an emerging property of the formulation of photosynthesis and respiration (see Hickler et al., 2008). 393 However, empirical studies do not find such an effect (Körner, 2006), which could be linked to the fact that LPJ-GUESS 394 does not model phosphor cycling which could be the limiting nutrient (for a DVGM study see Fleischer et al., 2019). We speculate that the negative effect of temperature (also found for multiple DGVMs, see Galbraith et al., 2010) arises from 395 decreased photosynthetic efficiency and increased respiration rates with higher temperatures (see the empirical study of 396 397 Gustafson et al., 2018, here confirmed by the negative relationship between temperature and the respiration coefficient). This 398 effect, however, differed in magnitude and direction between tree species (Fig. 2) - while there was a strong effect for Pic. 399 abi, and Pin, syl., Fag. syl, was less affected, which could be a sign of its higher resistance to increasing drought (Buras and Menzel, 2019; Tegel et al., 2014; but see Charru et al., 2010). From the parameters, especially water-, nitrogen- and 400 mortality-related parameters contributed a substantial amount of uncertainty. The uncertainty contributions from mortality 401 parameters (Bugmann et al., 2019, for a variety of DGVMs) and water (Pappas et al., 2013, with different parameter ranges 402 403 for LPJ-GUESS) were already highlighted by earlier studies.

404

405 4.1. Geographical and environmental patterns in sensitivities and uncertainties

406

407 Several of our results suggest that environmental context influences the sensitivity of LPJ-GUESS model parameters. First, 408 we found changing uncertainties across different vegetation zones (Fig. 3) and on an environmental gradient (Fig. 4) and that 409 most interactions occurred with environmental drivers (Fig. 5). Moreover, uncertainty contributions analyzed by a random 410 forest were similar to the linear regression results, but assign higher importance to environmental drivers (see Appendix 411 A1.3). All these findings indicate that environmental context can change the importance of different processes in the model, 412 which is in line with the biological expectation that the environment affects the physiology of organisms directly and thus indirectly the fitness and biotic interactions (e.g. Seebacher & Franklin, 2012; Tylianakis et al., 2008), and that 413 414 environmental responses can be particularly nonlinear (e.g. Burkett et al., 2005) or show higher order interactions.

415

Interestingly, our results of decreased uncertainty contributions of structure- related parameters and increased contributions of environmental drivers on the temperature gradient (Fig. 4) also seem in line with the stress-gradient hypothesis (Maestre et al., 2009), an empirically-observed pattern which states that in stressful environments, positive interactions should occur more often than in benign environments (e.g. Callaway, 2007). For the ecosystem that we consider, we interpret increasing temperature as increasing stress (e.g. Ruiz-Pérez and Vico, 2020), and structure as the best indicator for competitive interactions as the structure dictates resource allocation (e.g. bigger crown, but identical stem diameter leads to more 422 photosynthesis; more sapwood to heartwood turnover requires less NPP). With this interpretation, one would conclude that 423 under increasing stress, the importance of competition-related parameters decreases in the model, as expected from the 424 stress-gradient hypothesis. We acknowledge that a fair amount of interpretation is needed to arrive at this conclusion, and we 425 do not claim that this result lends evidence to the empirical discussion about the generality of the stress-gradient hypothesis, 426 but we find it noteworthy that such a large-scale pattern emerges in the model from lower-level processes, without having 427 been imposed (see also Levin, 1992).

428

429 4.2. Associated uncertainties of previous changes in model structure and implications for future model development

430

431 The management and the nitrogen cycling module are the most recent improvements of the LPJ-GUESS model (Smith et al., 432 2014; Lindeskog et al., 2021). Compared to previous sensitivity and uncertainty analysis, the high contributions of the 433 nitrogen fixation to the predictive uncertainty of TSB and GPP (Fig. 2 a.c) are novel, though not surprising, as nitrogen is an 434 important factor for the productivity of most temperate and boreal ecosystems (Vitousek and Howarth, 1991). The main 435 reason why few earlier studies report those uncertainties is that vegetation models have only recently begun to integrate 436 nitrogen cycling and limitation (e.g. B. Smith et al., 2014). The management module showed only small uncertainties, which could be due to the narrow parameter ranges for the cut interval and thinning intensity reflecting typical forest owners' 437 438 choices. As forest owners usually try to maximize their profits (Johansson, 1986; but see Brazee and Amacher, 2000) and 439 thus biomass production, low sensitivities of the management module are not surprising. A more suitable and important test 440 case and application of the management module would be a historical reconstruction of foliage projective cover data or 441 similar outputs of the LPJ-GUESS model.

442

443 Our study helps to guide the model application, discussion of uncertainties and model development of LPJ-GUESS and other 444 DGVMs. First, future model applications and model comparisons should focus on mortality as this process contributes high 445 uncertainties for carbon-related projections (see Fig. 1-3, see also Fisher et al., 2018). Thereby, it should be investigated if 446 these uncertainties stem from the intra-specific variability of the parameters itself (Bolnick et al., 2011), parameters are just not identifiable (see Marsili-Libelli et al., 2014), or if a model data comparison could reduce uncertainties in the parameters 447 (e.g. Hartig et al., 2011; Dietze, 2017b). Using time series inventory data might help as it is informative for constraining 448 449 mortality modules (Cailleret et al., 2020). Second, small sensitivities of establishment related parameters are surprising as we 450 know that not all three investigated species can effortlessly establish across all of Europe, e.g. Fag. syl. can only establish on 451 locations with no extreme drought and heat and no extreme winter frosts (Bolte et al., 2007). Thus, either we missed important parameters of this module, or the parametrization of the model needs to be updated. Third, when introducing new 452 453 processes or coupling with other models (e.g. Forrest et al., 2020) calculating interactions helps to get a first impression 454 where these new processes influence other model processes and potentially detect missing links. Moreover, future model

455 applications can interpret their results with regard to the sensitivities in different factors (Saltelli et al., 2019) and discuss 456 uncertainties and the causing factors, when used in policy advice (Laberge, 2013).

457

458 4.3. Limitations

459

460 We caution that our results regarding the importance of different factors for predictive uncertainties (but not sensitivities) 461 depend on the a priori defined uncertainty range of the contributing factors (see Wallach & Genard, 1998), as well as on several other technical choices in our study. For determining uncertainty ranges of the drivers, we used RCP scenarios; 462 however, these were not created as probabilistic min / max ranges. For the model parameters, we relied on expert guesses, 463 464 reducing subjectivity as far as possible by following the SHELF expert elicitation protocol (Gosling, 2018). Future studies could include more experts and their opinion on parameter distributions to reduce variability in this protocol. As the model is 465 sensitive to parameters and environmental drivers, and because these influence each other, we treated them in a combined 466 467 sensitivity and uncertainty analysis (Saltelli et al., 2019), however, when interpreting it should be kept in mind that the one group relates to uncertainties in the model, while the other is external, so the two are conceptually very different (see also 468 469 Dietze, 2017b). A certain ambiguity also arises from the definition of the indicators; here, we calculated sensitivities and uncertainties by capturing only linear components and second-order interactions, and we may therefore miss highly non-470 471 linear (and in particular hump-shaped) responses in LPJ-GUESS (Roux et al., 2021). However, our comparison to 472 uncertainties calculated with random forest variable importance, a method that would also capture nonlinearities, did not reveal any qualitative differences in the ranking of parameter importance (Appendix A1.3). Overall, while we acknowledge 473 474 that a certain amount of subjectivity exists in the choice of input uncertainty and calculation of indices, we believe that our 475 results are quantitatively robust to those choices.

476

477 Moreover, we acknowledge that LPJ-GUESS is known to be sensitive to the scaling parameters alpha a and alpha C3 478 (Pappas et al., 2013; Zaehle et al., 2005), which we have omitted from our analysis. These parameters, however, are not 479 accessible in the parameter input file. Instead, they are hard coded in the model's source code and therefore a normal user would not change them. We argue that these parameters should thus be counted towards the more general and here neglected 480 481 contribution of structural uncertainty (i.e. the uncertainty regarding the functional form of processes or even to entire 482 modules) to the joint model uncertainty. Several previous studies suggest that the sensitivity of vegetation models to structural changes can be large, often larger than to parameters (e.g. Bugmann et al., 2019), and it would certainly be useful 483 484 (although very complicated) to explore these uncertainties together with the here considered factors in a joint analysis. In the present study, however, we considered only the parameters that would be accessible to normal LPJ-GUESS users, and 485 486 neglect structural uncertainty that could be explored by changing the source code.

488 5. Conclusions

489 Our findings highlight the relative importance of parametric uncertainties in different processes and their interactions with 490 uncertainties in environmental drivers for carbon projections with LPJ-GUESS. Our results demonstrate that environmental 491 context changes uncertainty contributions of other processes across the European environmental gradient. The pattern of decreasing importance of competition towards the warmer areas is in line with the stress-gradient hypothesis, which posits 492 493 that the importance of competition decreases with increasing environmental stress. Our findings improve our understanding 494 of forest ecosystem models, enable pathways for future ecosystem model development and thus builds a basis for more 495 realistic projections. In the future, parametric uncertainties could be reduced by model-data fusion (e.g. Trotsiuk et al., 2020) 496 of LPJ-GUESS, concentrating on the parameters contributing most uncertainty in each geographic region (Fig. 3). Reducing 497 uncertainties in the drivers is more difficult. To some extent, environmental drivers are themselves influenced by the 498 vegetation (Strengers et al., 2010), so model-data fusion on a fully coupled model including feedback loops between 499 vegetation and climate, as well as a general improvement of climate models, could reduce driver uncertainty to some degree. Effectively, however, much of the uncertainty in this section arises from potential greenhouse gas emission trajectories, for 500 501 which a probabilistic assignment is difficult due to their dependency on human decision-making.

502

503 Appendix A

504

505 A1.1 Site selection

506 We sampled 200 sites geographically and environmentally stratified over Europe and thereby avoided sites near the sea. The 507 corresponding sites with the average temperature (Fig. A1) covers most of European climates and vegetation zones.

508 A1.2. Re-parametrization for better fit to observed data

There are several technical and methodological reasons requiring a re-parametrization of LPJ-GUESS for our study. First, most of European forests are managed and species are planted far outside of their natural distribution. Second, the introduction of the nitrogen cycle (Smith et al., 2014) changed the model structure and thus parameters require an adjustment. Third, the productivity of trees in managed forests did not fit to the reported inventory data (Fig. A2). To account for all these issues, we adjusted the parametrization of (Hickler et al., 2012) to allow species growing according to their actual (i.e., caused by forest management) distribution instead of their natural distribution.

- 515
- 516

517 Especially Picea abies and Pinus sylvestris are planted far outside their natural distribution (Figure S2). In particular we

518 adjusted bioclimatic limits, drought tolerances, longevity, leaf turnover, disturbance intervals and allometry for these species.

519 A1.3. Random forest results

To check the consistency of the results obtained via linear regressions, we compare them to variable importance of random forest. The variable importance measures additionally non-linear effects and thus, should be able to deal with non-linear models like DGVMs. We calculated the variable importance the same way as we did for the linear regression by fitting a random forest with all parameters against the sum of differences between model outputs with default values and model outputs with sampled parameters. As our parameters were sampled from a uniform distribution with no correlation between the individual parameters, random forest variable importance can be compared to linear regression results.

526

527 The ranking is very similar to the ranking of the parameters and environmental drivers obtained via linear regression (Fig. 528 A3). There is, however, a difference in the magnitude of the uncertainty induced by drivers, which is higher compared to 529 linear regression (Fig A3). The higher uncertainty due to drivers is thus a nonlinear effect and stresses our conclusion that 530 environmental conditions change the uncertainty contributions of other parameters.

531

532 A1.4. Interactions of GPP and NBP

533 Interactions of gross primary production (Fig. A4 a,b) and net biome production (Fig. A4c,d) are similar to the interactions 534 of total standing biomass. These interactions are mostly between environmental drivers and environmental drivers or 535 between environmental drivers and parameters (Fig. A4). Some strong interactions are between parameters and parameters, 536 however, in such interactions there are always parameters included having strong interactions with environmental drivers 537 (Fig. A4).

538

High sums of strong interactions arise from temperature, precipitation, solar radiation, greffmin, emax and respcoeff (Fig. 540 A4a,b).

541 Code and Data Availability

542 LPJ-GUESS development is managed and the code maintained in a permanent repository at Lund University, Sweden.

543 Source code is made available on request. The model version presented in this paper is identified by the permanent revision

544 number r10207 in the code repository. There is no DOI associated with the code. Code to perform the sensitivity and

545 uncertainty analysis can be found on zenodo under https://zenodo.org/record/5873672#.YebgTmAxnYU. Results from the

546 LPJ-GUESS runs are available under https://zenodo.org/record/4670295#.YKIkI-tCRqs.

547 Author contribution

548 JO and FH conceived and designed the study and wrote a first draft. JO implemented the case studies, ran the experiments, 549 and analyzed the results. CH, AK and PA advised regarding running the LPJ-GUESS model. CH, AR and AK determined 550 the prior ranges for the parameters. All authors contributed to discussing and interpreting the results, and to the preparation 551 of the manuscript.

552

553 Competing interests

554 The authors declare that they have no conflict of interest. 555

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- 888 Tables
- 889 Table 1: The model inputs investigated in the sensitivity analysis can be grouped in a) common parameters b) species-specific
- 890 parameters and c) drivers. The ranges for the parameters have been determined from experts and literature, default parameter
- 891 values that changed from Hickler et al. (2012) due to the reparameterization are explained in Appendix A1.2 .* denotes an 892 averaging over sites.

							-4,22E-07*	5,30E-07*	RCP 4.5	g/mm^2/year	RCP 4.5 per site	ndep	Environmental Drivers
							237	-95,4	RCP 4.5	ppm	Mean deviations co2 from standard scenario RCP 4.5 per site	co2	Environmental Drivers
							6,27*	-6,18*	RCP 4.5	mm/month	Mean deviations precipitation from standard scenario RCP 4.5 per site	prec	Environmental Drivers
							5,82*	-5,40*	RCP 4.5	ő	Mean devisions temperature from standard scenario RCP 4.5 per site	temp	Environmental Drivers
							65,2*	-63,9*	RCP 4.5	W/m^2	Mean deviations solar radiation from standard scenario RCP 4.5 per site	insol	Environmental Drivers
							rs	c) Drive					
Pappas et al 2013;	0,58	0,42	0,5	0,38	0,22	0,3	0,38	0,22	0,3	mm/s	minimum canopy conductance not assoc with photosynthesis	gmin	Water
	800	250	600	800	80	100	800	80	100		Coefficient in equation for budburst chiling time requirement	k_chillb	Structure/Phenology
Zhang et al 2014	meters	m common Para	Values from	ameters	om common Para	Values fre	60	15	30		height =kallom2* -diameter /\$kallom3}	k_allom2	Structure/Phenology
	8000	2500	5000	7000	2500	4000	5200	1800	3000		Tree leaf to sapwood xs area ratio	k_latosa	Structure/Phenology
	0,1	0,05	0,085	0,09	0,04	0,065	0,1	0,05	0,085	fraction/year	Folde of sapwood turnover	turnover_sap	Structure/Phenology
Mencuccini, M., Bonosi, L., 2001,; Pallandt-Vermeulen et al. 2015; Xiao et. al. 2006	48,23	28,33	43,08	15,1	8,7	11,52	9,3	7,812	8,56	m^2/kgC	Specific luaf area	8/8	Structure/Phenology
	27,19	22,7	24,06	43,16	31,9	38,37	38,37	27,32	31,90		minimum leaf C/N ratio	cton_leaf_min	Structure/Phenology
Zhang et al 2014	30	20	25	30	16	25	30	16	25	ĉ	Approx higher range of temp optimum for photosynthesis (deg C)	pstemp_high	Photosynthesis/Light
Renwick et al. 2019, Patiendi- Vermeulen et al. 2015	20	8	15	14	6,75	10	15	6,75	10	ĉ	Approx lower range of temp optimum for photosynthesis	pstemp_low	Photosynthesis/Light
-	1,5	0,5	-1	2,2	0,8	-	2,2	0,8	-		Respiration coefficient	respoceff	Photosynthesis/Light
	-	0,55	0,9	-	0,5	0,9	-	0,45	0,9		percentage of treshold crowncoverage that is kept after thinning	thinning_intensit y	Mortality / Management
	0,49	0,2	0,39	0,65	0,2	0,48	0,4	0,1	0,25		Implements drought-limited establishment plus water uptake, from 0: total to 1: not at all drought-limited	drought_toleran ce	Mortality / Management
Pappas et al. 2013	0,13	0,001	0,02	0,19	0,03	0,135	0,26	0,07	0,21	kgC/m^2/yr	Threshold for growth suppression mortality	greff_min	Mortality / Management
	140	80	105	120	60	90	140	40	90	year	Time until trees are cut	cutinterval	Mortality / Management
	0,8	0,05	0,1	0,8	0,05	0,1	0,7	0,05	0,4		fire resistance	fireresist	Mortality / Management
	650	250	400	1000	200	300	900	300	500	year	Expected longevity under lifetime non-stressed conditions (yr)	longevity	Mortality / Management
	5	0.8	2	54	2	4	ъ	4	10	•	Shape parameter for recruitment-juv growth rate relationship	alphar	Establishment
	0,25	0,05	0,2	0,2	0,05	0,1	0,25	0,1	0,2	1/m^2/year	Max sapling establishment rate	est_max	Establishment
Schilbaski et al 2017	8	5	7	6	ŕ.	ω	6	-1.0	5.5	ő	Max 20-year coldest month mean temp for establishment	tcmax_est	Establishment
	άı	å	-6.5	-15	-100	-29	-15	-100	-29	ő	Min 20-year coldest month mean temp for establishment	tcmin_est	Establishment
	1450	1050	1300	700	300	350	700	250	500	"C day	Min GDD on 5 deg C base for establishment	gdd5min_est	Establishment
	1600000	750000	1000000	1600000	750000	1000000	3500000	1500000	2500000	J/m^2/day	Min forest foor PAR for grass growth/tree estab	parff_min	Establishment
	max. value	agus svivatica	Faunt Faunt	max. value	Picea abies	Delaut talue	ITIGA, VOING	Pinus svivestris	Dolarit taine			r arannever	dioth
I taratura entrene	May Valua	Min Valua	Dafault Value	May Value	Min Valua	S Default Value	c Paramater	ecies-specifi	b) Sp	Init	Evalanation	Daramatar	Crown
Köstner 2000	6	2	5	mm/day	Maximum evapotranspiration rate	emax	Water
							1,6	1,3	1,6		crown area = kalom1-*height*(k_rp)	k_rp	Structure/Phenology
							80	30	60		height=kalom2*-diameter ^{kalom3}	k_allom2	Structure/Phenology
							60	20	40	mm^2	maximum crown area	crownarea_max	Structure/Phenology
							0,75	0,65	0,7	1/year	Rate of fine root turnover	turnover_root	Structure/Phenology
-							0,3	0,05	0,1		Fraction of NPP allocated to reproduction	reprfrac	Structure/Phenology
Pappas et al. 2013							0.8	0.6	0,8		Non-water-stressed ratio of intercellular to ambient CO2 pp	lambda_max	Photosynthesis/Light
-							0,8	0,1	0,5		Fraction of N retranslocated prior to leaf and root shedding	nrelocfrac	Nitrogen
Cloveland et. al, 1999							0,624	0,764	0,624		Second term in N Reation ogn	nfix b	Nitrogon
							0.367	0.102	0.102		First term in N fixation eon	nfix a	Nitrogen
							1000	200	920	year	average return time for generic patch-destroying disturbances	distinterval	Mortality / Management
Literature sources							Max. Value	Min. Value	Default Value	Unit	Explanation	Parameter	Grouping
							ramaters	Common Pa	a				



Fig.1: Relative sensitivities (percent output change per percent parameter change) of the individual parameters and environmental drivers regarding a) total standing biomass, b) net biome productivity and c) gross primary production. Sensitivities were not substantially different between *Fag. syl.* (green squares), *Pic. abi.* (blue circles) and *Pin. syl.* (red triangles), but parameter sensitivities were stronger for mono-specific stands than mixed stands (purple asterisks). The height of the bar reflects the mean over mono and mixed stands. Positive values for points and bars indicate a positive and negative values a negative relationship with the corresponding output.



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Fig. 2: Uncertainty contributions in percent of the individual parameters and environmental drivers regarding a) total standing biomass, b) net biome productivity and c) gross primary production showed no strong differences between *Fag. syl.* (green squares), *Pic. abi.* (blue circles) and *Pin. syl.* (red triangles) and were stronger for mono-specific stands than mixed stands (purple asterisks). The height of the bars reflects the mean over mono and mixed stands. Positive values for points and bars indicate a positive and negative values a negative relationship with the corresponding output.



Fig. 3: The aggregated relative uncertainties of total standing biomass per environmental zone (with more than five sites) show a
higher importance of drivers in the south than in the north. The environmental zones are from Metzger et al. (2005): ALN-Alpine
North; ALS - Alpine South; ANA - Anatolian; ATC - Atlantic Central; ATN- Atlantic North; BOR-Boreal; CON-Continental;
LUS - Lusitanian; MDM - Mediterranean Mountains; MDN - Mediterranean North; MDS - Mediterranean South; NEM Nemoral; PAN - Pannonian. In the radar plots of each environmental zone, the color and percentage value of the process label
indicates which simulation setup (monospecific with corresponding species or mixed) has contributed most uncertainty and how
much.



Fig. 4: The uncertainty contributions to total standing biomass projections of parameters and environmental drivers change across a mean annual temperature gradient across Europe from north to south (with p-values and R^2 for the processes/drivers). With increasing temperature, the importance of drivers and establishment became higher for total standing biomass, while the uncertainty contributions from nitrogen and structure declined (4a). The uncertainty contributions due to temperature increased on the temperature gradient and the contributions from solar radiation decreased (4c).



Fig. 5: The induced uncertainty of environmental drivers, mortality- and photosynthesis-related parameters changed the most depending on other parameters (Fig. 5a). Strong individual interactions between parameters and environmental drivers in monospecific projections of total standing biomass were rare (Fig. 5b). If strong interactions occurred, these were mainly between two environmental drivers or environmental drivers and parameters and only rarely between two parameters (Fig. 5b).

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930 Tables Appendix A

- 731 Table A1: Differences in parametrization of Hickler et al. 2012 and our study for the investigated species (Fag. syl.,
- 932 Pic. Abi. and Pin. Syl)

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Parameters	Fag	syl	Pic	abi	Pin	syl
	Hickler et al. 2012	Our study	Hickler et al. 2012	Our study	Hickler et al. 2012	Our study
drought_tolerance	0.3	0.3	0.43	0.48	0.25	0.25
fireresist	0.1	0.1	0.1	0.1	0.2	0.4
leaflong	0.5	0.5	4	7	2	4
turnover_leaf	1	1	0.33	0.1429	0.5	0.25
turnover_sap	0.085	0.085	0.05	0.065	0.065	0.085
est_max	0.05	0.1	0.05	0.1	0.2	0.2
alphar	3	10	2	4	6	10
parff_min	1.250.000	1.000.000	1.250.000	1.000.000	2.500.000	2.500.000
tcmin_surv (minimum 20-year coldest month mean temperature for survival)	-3.5	-7.5	-30	-30	-30	-30
tcmin_est (min. 20-year coldest month mean temperature for establishment)	-3.5	-6.5	-29	-29	-30	-29
tcmax_est (max. 20-year coldest month temperature for establishment)	6	7	-1.5	3	-1	5.5
twmin_est (minimum warmest month mean temperature for establishment)	5	-1000	5	-1000	5	8
k_chillb	600	600	100	100	100	100

sla	43?	43.08	11	11.52	8	8.56
k_allom2	40	60	40	60	40	60
wooddens	200	293	200	185	200	211
longevity	500	400	500	300	500	500
ga (aerodynamic						
conductance)	0.04	0.04	0.14	0.14	0.14	0.14
gdd5min_est	1500	1300	600	350	500	500

938 Figures Appendix A



Fig. A1: Our 200 sampled sites geographically and environmentally stratified over Europe cover the most important countries,
 climate and temperature zones.

Parameterization as in Hickler et al. (2012)

Re-parametrization to fit to actual distribution

a) Picea abies



b) Picea abies



c) Pinus sylvestris

d) Pinus sylvestris



Fig. A2: Simulated (black points), observed (blue) and natural distributions (green) of the adjusted parametrization (b, d)
compared to applying the parametrization from Hickler et al., 2012 (a, c) for Picea abies and Pinus sylvestris. EUFO =
EUFROGEN, 2008 and 2013, Mauri =(Mauri et al., 2017), Caudullo =(Caudullo, 2017). The simulations were run from 1600 to
2010 without management and without competition between species. The plotted biomasses were averages over the last 20 years.



Fig. A3: Results of the random forest uncertainty contributions. The uncertainties due to environmental drivers are higher than
 the uncertainties due parameters compared to linear regression, but the ranking of parameters is similar to linear regression
 results.



- 951 Fig. A4: Interactions of uncertainty contributions of GPP and total standing biomass are similar to net biome productivity with
- 952 most interactions arising from environmental drivers.