

The improvements in the regional South China Sea Operational Oceanography Forecasting System (SCSOFSv2)

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Abstract. ~~The~~ South China Sea Operational Oceanography Forecasting System (SCSOFS), ~~had been~~ constructed and operated ~~by the~~ National Marine Environmental Forecasting Center of China, ~~has been providing to provide~~ daily updated hydrodynamic forecasting in ~~the~~ SCS for the next ~~five~~ days since 2013. This paper presents recent comprehensive updates ~~to~~ of the configurations of the physical model and data assimilation scheme in order to improve ~~the~~ SCSOFS forecasting skill ~~of the~~ SCSOFSs. ~~The~~ paper highlights three of the most sensitive updates, including ~~the~~ sea surface atmospheric forcing method, ~~the discrete tracers advection-discrete~~ scheme, and modification of ~~the~~ data assimilation scheme. Inter-comparison and accuracy assessment among ~~the~~ five versions ~~were performed~~ during the ~~whole entire~~ upgrading processes ~~using are performed by employing the~~ OceanPredict Inter-comparison and Validation Task Team Class4 metrics. The results indicate that remarkable improvements have been ~~made to the~~ ~~achieved in~~ SCSOFSv2 with respect to the original version known as SCSOFSv1. ~~The~~ ~~D~~ domain averaged monthly mean root-mean-square errors ~~of the decrease from 1.21 °C to 0.52 °C for~~ sea surface temperature ~~and, from 21.6cm to 8.5cm for~~ sea level anomaly ~~have decreased from 1.21 °C to 0.52 °C and from 21.6 cm to 8.5 cm,~~ respectively.

25 1. Introduction

The South China Sea (SCS) is located between 2°30'S ~~≈~~ 23°30'N and 99°10'E ~~≈~~ 121°50'E. ~~It is the largest in area and the deepest in depth,~~ a semi-closed marginal sea in the western Pacific ~~and has the largest area and deepest depths.~~ Its area is about 3.5 million km², and its maximum depth is about 5300 m ~~in~~ the central region. It ~~is connected~~ to the East China Sea by the Taiwan Strait to the northeast, to 30 the North Pacific Ocean by the Luzon Strait to the east, ~~and~~ to the Java Sea by the Karimata Strait to the south. Numerous islands, irregular and complex coastal boundaries, and drastic changes in bottom topography all ~~together~~ contribute to the ~~extremely great~~ complex distribution of ~~the~~ topography in the SCS.

The ~~upper layer~~ basin-scale ocean circulations ~~in the upper layer~~ of the SCS are mainly controlled by the 35 East Asian Monsoon (Hellerman and Rosenstein, 1983), ~~result showing~~ a cyclonic gyre in winter and an anti-cyclonic gyre in summer (Mao et al., 1999; Chu and Li, 2000). The ~~dynamic~~ multi-scale oceanic circulation ~~dynamical~~ processes ~~in~~ the SCS are affected by various factors, i.e., the Kuroshio intrusion through the Luzon Strait (Nan et al., 2015; Farris and Wimbush, 1996; Liu et al., 2019), ~~the~~ internal waves (Li et al., 2011; Li et al., 2015) ~~and~~ internal solitary waves (Zhang et al., 2018; Zhao and Alford, 40 2006; Cai et al., 2014) generated in the Luzon Strait and propagated ~~ing westward~~ in the northern SCS, the SCS throughflow as a branch ~~from~~ the Pacific ~~Ocean~~ to ~~the~~ Indian Ocean throughflow (Wei et al., 2019; Wang et al., 2011), and energetic mesoscale eddy activities (Zu et al., 2019; Xu et al., 2019; Zhang et al., 2016; Zheng et al., 2017; Hwang and Chen, 2000; Wang et al., 2020). The multi-scale ~~dynamical~~ mechanisms in the SCS are too complex to understand clearly ~~as yet,~~ ~~it~~ has always been a challenge to 45 simulate or reproduce the ocean circulations, ~~as well as~~ ~~not to mention~~ forecast ~~the~~ future oceanic status ~~using the~~ Operational Oceanography Forecasting System (OOFS).

Within ~~the~~ coordination and leadership of ~~the~~ Global Ocean Data Assimilation Experiment OceanView (GOV, <https://www.godae-oceanview.org>; Tonani et al., 2015; Dombrowsky et al., 2009), in ~~the last recent~~ decade or two, several regional OOFSs have been developed and operated based on the state- 50 of-the-art community numerical ocean models ~~for~~ different regions of the ocean. Tonani et al. (2015)

~~reported~~ ~~summarized~~ that ~~a total of there were~~ 19 regional systems ~~were~~ running operationally ~~in total~~ until 2015.

For instance, ~~the~~ Canadian Operational Network of Coupled Environmental Prediction Systems from Canada was built based on the Nucleus for European Modelling of the Ocean (NEMO) 3.1, ~~and its whose~~

55 domain covered the Arctic and North Atlantic ~~oceans~~ with a $1/12^\circ$ horizontal resolution. ~~‡~~ ~~The~~ Real-Time

Ocean Forecast System ~~of the from~~ US National Oceanic and Atmospheric Administration National Centers for Environmental Prediction (NCEP) was designed based on the HYbrid Coordinate Ocean

Model and ~~was~~ implemented in the North Atlantic on a curvilinear coordinate ~~system~~, with ~~the~~ ~~horizontal~~ resolution ranging from 4 km to 18 km. ~~in horizontal~~; The Meteorological Research Institute

60 (MRI) of ~~the~~ Japan Meteorological Agency developed the Multivariate Ocean Variational Estimation

System/MRI Community Ocean Model (MOVE/MRI.COM) coastal monitoring and forecasting system based on the MRI.COM (T sujino et al., 2006). ~~This~~ model consists of a fine-resolution (2 km) coastal

model around Japan and an eddy-resolving (10 km) Western North Pacific model with one-way nesting. ~~‡~~

~~‡~~ ~~The~~ Chinese Global operational Oceanography Forecasting System was developed and operated based

65 on the Regional Ocean Modelling System (ROMS, Shchepetkin and McWilliams, 2005) and NEMO by

~~the~~ National Marine Environmental Forecasting Center, covering ~~six~~ subdomains from global to polar regions, Indian Ocean, Northwest Pacific, Yellow Sea and East China Sea (Kourafalou et al., 2015), ~~and~~

~~South China Sea~~ (Zhu et al., 2016), with ~~their~~ horizontal resolutions ranging from $1/12^\circ$ to $1/30^\circ$. It

~~is should be noted worth noting~~ that there are considerable differences among ~~the~~ ~~ese~~ systems in many

70 aspects, such as the model codes, area coverage, horizontal ~~and/~~ vertical resolutions, ~~and~~ data assimilation

schemes, ~~which are based on and so on, according to~~ the user needs ~~and/or~~ regional ocean characteristics.

In order to better satisfy ~~the~~ end users' needs, ~~these~~ OOFs ~~has~~ ~~ve~~ been ~~upgraded~~ ~~ing~~ and ~~improved~~ ~~ing~~

constantly since ~~they began~~ operation. In general, most improvements ~~to the of~~ OOFs ~~we~~ ~~are~~

implemented by increasing ~~the~~ horizontal or vertical grid resolution, changing the data assimilation

75 schemes ~~into~~ a more sophisticated level, assimilating more diverse sources of observation data, ~~and~~ by

benefiting from the growth of high-performance computing power and global or regional observation

networks. Initially, the MOVE/MRI.COM was developed based on a three-dimensional variational

analysis scheme and ~~was~~ implemented in 2008 (Usui et al., 2006). ~~Then,~~ it was updated to ~~the~~ four-dimensional variational analysis scheme to provide better representation of mesoscale processes (Usui et al., 2017). ~~The~~ Mercator Ocean International global monitoring and forecasting system had been routinely operated in real time with an intermediate-resolution ~~of~~ $1/4^\circ$ and 50 vertical levels since early 2001. ~~An~~ ~~u~~ ~~p~~ ~~g~~ ~~r~~ ~~a~~ ~~d~~ ~~i~~ ~~n~~ ~~g~~ ~~by~~ ~~of~~ increasing ~~the~~ horizontal resolution was implemented in December 2010, ~~to~~ consisting ~~of~~ a $1/12^\circ$ nested model over the Atlantic and Mediterranean. Real time daily services with ~~a~~ global $1/12^\circ$ high-resolution eddy-resolving analysis and forecasting were delivered by an updated system, ~~since~~ 19 October, 2016. Moreover, Mercator Ocean International also continues to implement regularly updates by increasing ~~the~~ system's complexity, such as expanding the geographical coverage, improving ~~the~~ models, ~~and~~ assimilating schemes, and ~~have~~ ~~developing~~ several versions for the various milestones of the MyOcean project and the Copernicus Marine Environment Monitoring Service (Lellouche et al., 2013, 2018).

As mentioned in the literature of Zhu et al. (2016), the regional SCS Operational Oceanography Forecasting System (SCSOFS, here after named it as SCSOFSv1) has been developed and routinely operated in real time since the beginning of 2013. It has continued to be upgraded by modifying ~~the~~ model settings in many aspects, such as ~~the~~ mesh distributions, surface atmospheric field forcing, ~~and~~ open boundary inputs, and ~~so on, and by~~ improving ~~the~~ data assimilation scheme according to the results of comparisons and validations ~~from~~ ~~conducted~~ ~~by~~ Zhu et al. (2016), in order to provide better services. The primary purpose of this ~~study paper wa-iss~~ to introducing ~~the~~ updates applied to SCSOFS ~~and to~~ ~~determine which update had the great,~~ ~~but only show the highestest~~ impact on the system. The ~~other~~ results ~~offrom~~ routine system updates ~~and/or~~ improvements ~~were~~ ~~will~~ not ~~determined~~ ~~be illustrated~~ or ~~analysed~~ ~~discussed~~ in detail.

This paper is organized as follows. A detailed description of some general/basic updates applied to ~~the~~ SCSOFS ~~is~~ ~~will be~~ provided in Section 2. Some highlights and sensitive updates and their impacts ~~to~~ the performance of ~~the~~ system are ~~described~~ ~~shown~~ in Section 3. ~~The~~ ~~R~~ results of the inter-comparison and assessment ~~of~~ ~~the~~ different SCSOFS versions during the upgrading processes based on the ~~Class~~ 4

metrics² verification framework (Hernandez et al., 2009) ~~are presented~~~~will be shown~~ in Section 4. Section 5 contains a summary of the scientific improvements and future plans for the next step.

2. Physical model description, updates, and input datasets

This section describes ~~several~~~~some~~ general updates applied to the SCSOFSv1 in ~~the last few recent couple~~ years. The newly updated system is ~~referred~~~~named to as~~ SCSOFSv2 ~~in this paper~~~~here~~~~after~~. In order to isolate the contributions of each modification, different simulations were performed for ~~the~~ respective updates. However, some ~~of the~~ updates ~~were~~~~have been~~ implemented directly according to model experiences or ~~theoretically~~ knowledges, without standalone evaluation. The performances ~~off~~~~from~~ a few integrated updates will be shown in Section 4 ~~in~~~~for the~~ different upgrading stages.

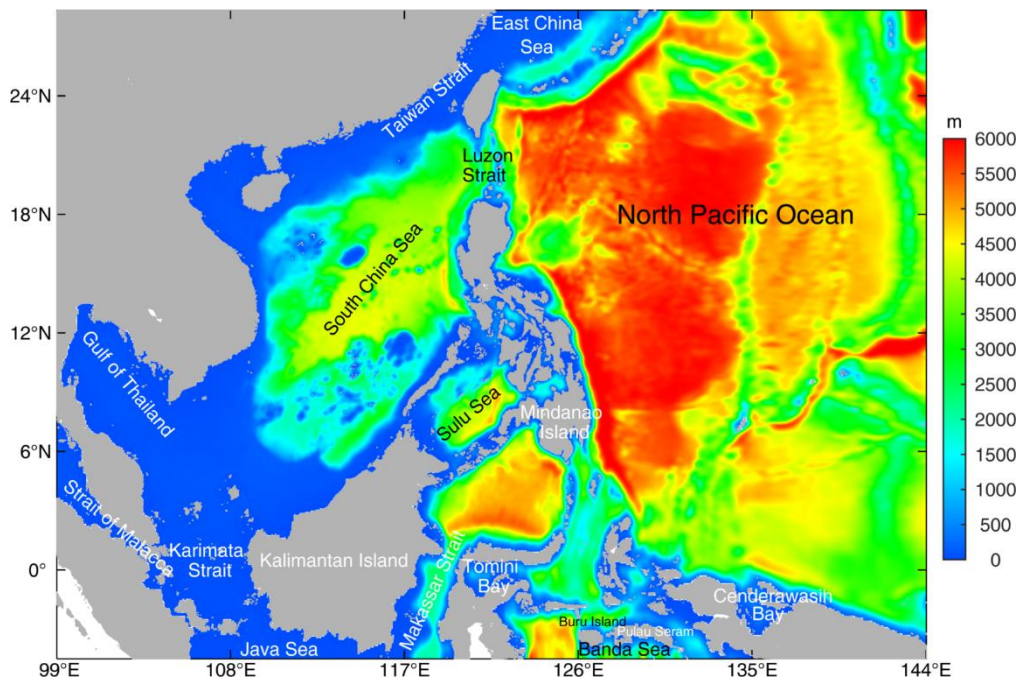


Figure 1: The model domain and bathymetry of SCSOFSv2

The SCSOFSv2 is still built based on ROMS, ~~which~~~~whose version~~ has been updated from v3.5 (svn trunk revision 648 in 2013) to v3.7 (svn trunk revision 874 in 2017). ~~In addition to a~~~~ROMS v3.7~~ ~~incorporates some changes for the model settings, which facilitating the operational running especially,~~ ~~besides of the~~ major overhaul of the nonlinear, tangent linear, representor, multiple-grid nesting, and

adjoint numerical kernels, ROMS v3.7 incorporates several changes to the model settings, which facilitate the operational running.

Firstly, we redistributed the land-sea grid mask layout to enable the systems mesh land boundary to fit the actual coastline better (Fig.1). Based on a comparison with the Fig. 1 infrom Zhu et al. (2016), a few areas have vee been changed from land to sea or vis versa inverse, e.g., along the coast of China mainland, the-Vietnam and the Gulf of Thailand, and around the coasts of the-Kalimantan Island and the Mindanao Island. In addition, the Strait of Malacca had been opened to connect with the Karimata Strait, and the western lateral boundary was treated as an open boundary across the Strait of Malacca along 99°E, instead of as a closed boundary as-in SCSOFSv1. Along the south lateral open boundary, the Java Sea was connected to the Makassar Strait toin the southeast of the Kalimantan Island, the Banda Sea was connected across the southern part of Buru Island and Pulau Seram, and including volved the Tomini Bay and the Cenderawasih Bay. It is obvious that the changes in the land-sea masks changing can-generated significant effects on the sea-water volume of sea water transportation in the model domain, and thus, it would contributes to the better simulation of the ocean circulations.

The bathymetry ETOPO1 dataset used in SCSOFSv1, which has a 1 arc-minute grid resolution from the U.S. National Geophysical Data Center, was-is replaced by the General Bathymetric Chart of the Oceans (GEBCO_2014 Grid) global continuous terrain model for ocean and land, which has is-with 30 arc-second spatial resolution in SCSOFSv2, from ETOPO1 data set in SCSOFSv1, which is with 1 arc-minute grid resolution from U.S. National Geophysical Data Center. It was also merged with the measured topographic data in the coastal areas along China mainland, and was adjusted with the tidal range. Then, it was smoothed by applying a selective filter eight times to reduce the isolated seamounts on the deep ocean, so that the “slope parameter” $r = \Delta h / 2h$ is lower than thea maximum value $r_0 = 0.2$ for each grid (Beckmann and Haidvogel, 1993; Marchesiello et al., 2009), in order to supress the computational errors of the pressure-gradient (Shchepetkin and McWilliams, 2003). Then, the two grid stiffness ratios parameters, i.e., the slope parameter (r) and the Haney number, were changed from 0.22 and 9.78 in SCSOFSv1 to 0.17 and 13.80 in SCSOFSv2, respectively. The maximum depth was isstill

145 set to be 6000_m~~still~~, but the minimum depth was changed from 10_m in SCSOFSv1 to 5_m in SCSOFSv2 (Wang, 1996). The final smoothed bathymetry is shown in Fig.1.

For the vertical terrain-following coordinate, it ~~has been~~ increased from 36 s-coordinate layers in SCSOFSv1 to 50 layers in SCSOFSv2. The transformation equation ~~of from~~ the original formulation was also changed to an improved solution (Shchepetkin and McWilliams, 2005). The original vertical stretching function (Song and Haidvogel, 1994) was replaced with an improved double stretching function (Shchepetkin and McWilliams, 2005); to make it preserve a sufficient resolution in the upper 300_m in order to resolve the thermocline well. In this case, the thinnest layer was changed from 0.16 m in SCSOFSv1 to 0.09_m in SCSOFSv2 near the surface.

150 The new initial temperature and salinity fields in SCSOFSv2 we are extracted from the Generalized Digital Environmental Model version 3.0 (GDEMv3, Carnes, 2009) global climatology monthly mean in January, ~~which replaced~~ to substitute the version 2.2.4 of the Simple Ocean Data Assimilation (SODA, Carton and Giese, 2008) datasets. All four lateral boundaries are open, ~~and the whose~~ temperature, salinity, velocity, and elevation are obtained via ~~prescribed by~~ spatial interpolation ~~of from~~ the new SODA 3.3.1 datasets for the running 2005_–2015 and SODA 3.3.2 datasets for the running 2016_–2018_–~~datasets~~ 160 (Carton et al., 2018), instead of the original SODA 2.2.4. In ~~the current version~~ this present, we use the SODA 3.3.1/2 monthly mean ocean state variables are used, which are mapped onto the regular 1/2°×1/2° Mercator horizontal grid from the original approximately 1/4°×1/4° displaced pole non-Mercator horizontal grid at 50_–z vertical levels.

165 For the surface atmospheric forcing, we replaced the dataset from the NCEP Reanalysis 2 provided by the NOAA/OAR/ESRL PSL, Boulder, Colorado, USA, which is accessible from their website at <https://psl.noaa.gov/> (Kanamitsu et al., 2002), with the six ~~6~~-hourly Climate Forecast System Reanalysis (CFSR, Saha et al., 2010) for 2005_–2011 and the Climate Forecast System version 2 (CFSv2, Saha et al., 2014) for 2011_–2018. Both are archived at the National Center ere for Atmospheric Research, Computational and Information Systems Laboratory, Boulder, Colorado.; ~~Its with a~~ 0.2°_–0.3° horizontal 170 grid is significantly higher ~~horizontal grid~~ than the 2.5°×2.5° resolution ~~of the for~~ NCEP Reanalysis 2.

The net surface heat flux correction ~~is still following~~ Barnier et al. ~~(1995)~~'s ~~(1995)~~ method in SCSOFSv2, but the parameter $dQ/dSST$, ~~i.e., the~~ kinematic surface net heat flux sensitivity to sea surface temperature (SST), is calculated using ~~the~~ SST, sea surface atmospheric temperature, atmospheric density, wind speed, and sea level specific humidity, instead of setting a constant number of ~~30~~ $W\ m^{-2}\ K^{-1}$ for the ~~entire~~ domain as in SCSOFSv1. Therefore, the parameter $dQ/dSST$ varies temporally and spatially. ~~In addition~~ ~~Meanwhile, we use~~ the infrared Advanced Very High Resolution Radiometer (AVHRR) satellite data ~~are used~~ in SCSOFSv2, which is an analysis constructed by combining observations from different platforms on a regular grid via optimum interpolation and ~~is~~ provided by ~~the~~ National Centers for Environmental Information, instead of ~~using~~ the merged satellite's infrared ~~sensors~~ and microwave sensor, and ~~the~~ *in-situ* (buoy and ship) ~~data~~ global daily SST (MGDSST) ~~data~~ obtained from the Office of Marine Prediction of the Japan Meteorological Agency ~~used in the~~ SCSOFSv1.

The North Equatorial Current (NEC) is an interior Sverdrup steady current in the subtropical North Pacific and ~~is~~ located at ~~about~~ $10^{\circ}N$ – $20^{\circ}N$; ~~It~~ and usually bifurcates into two branches after encountering the western boundary along the Philippine coast ~~to~~ the west of $130^{\circ}E$ (Qiu and Chen, 2010). However, the NEC is separated into two branches in ~~the~~ SCSOFSv1 ~~due to~~ ~~affected by the~~ model's eastern lateral boundary setting; ~~its~~ main branch ~~is~~ located at ~~about~~ $9.5^{\circ}N$ – $13^{\circ}N$, ~~and~~ the other branch ~~is~~ located at $14.5^{\circ}N$ – $17^{\circ}N$ (Fig. 2a), which is clearly not in line with the ~~actual locations~~ ~~fact~~. The cause ~~of the~~ ~~for~~ above result is that ~~the~~ Guam Island (~~shown in~~ red circle in Fig. 2, located ~~at~~ about $13^{\circ}26'N$, $144^{\circ}43'E$) is included in SCSOFSv1, ~~and its~~ ~~whose~~ location is too close to the eastern lateral boundary. There is a sudden change ~~in~~ ~~of~~ the bathymetry from over 3500 m to below 500 m, ~~serving~~ as a ~~large~~ ~~big~~ blockade to the NEC ~~that~~ once flow~~ed~~ ~~ing~~ into the model domain from ~~the~~ eastern lateral boundary. To resolve this problem, ~~in~~ SCSOFSv2, the eastern lateral boundary ~~was~~ ~~been~~ moved westward from $145^{\circ}E$ to $144^{\circ}E$ to narrow the model domain and exclude ~~the~~ Guam Island ~~in~~ SCSOFSv2. It ~~was~~ found that ~~in~~ SCSOFSv2, the simulated NEC ~~remains as~~ ~~keeps the form of~~ one main current until $130^{\circ}E$, ~~and~~ then bifurcates into the southward-flowing Mindanao Current and the northward-flowing Kuroshio ~~in~~ SCSOFSv2 (Fig. 2b). ~~Also~~ ~~In addition~~, it ~~has~~ ~~been~~ shown that the Kuroshio ~~current~~ of eastern Philippine Island and ~~the~~ ocean

circulations in the north-eastern SCS grow stronger when the island of Guam was removed. This indicates that the location of the lateral open boundary is very important to the results of the model's simulation, and the results are better when it is set far enough away from the island, especially for the islands located in the major ocean circulations.

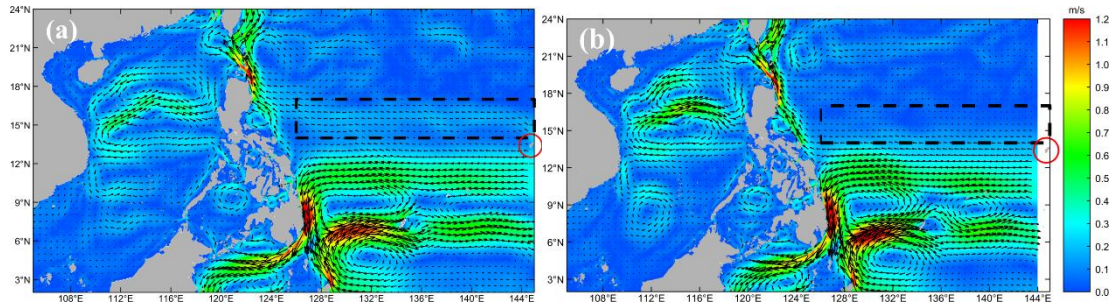


Figure 2: The multi-year monthly mean sea surface currents (the colour shading indicates the current speed (m s^{-1}), and the arrows denote the current direction) with vertical averages of $>100\text{ m}$ in May. The left panel (a) is from SCSOFSv1, with the model domain including the Guam Island, the right panel (b) is from SCSOFSv2, with the eastern lateral boundary moved 1 degree westward.

For the advection schemes of the momentum, third-order upstream and fourth-order centered schemes are used in both the horizontal and vertical directions. A Harmonic mixing scheme was used for both the viscosity for momentum and the diffusion for tracers in the horizontal. The Mellor-Yamada Level-2.5 vertical turbulent mixing closure scheme was used for both the momentum and tracers. In SCSOFSv2, they all in SCSOFSv2 are all set to be the same as in SCSOFSv1. Table 1 summarizes the main differences between SCSOFSv1 and SCSOFSv2 after upgrading.

Table 1 The main differences between SCSOFSv1 and SCSOFSv2

System settings		SCSOFSv1	SCSOFSv2
ROMS version		V3.5	V3.7
Bathymetry		ETOPO1	GEBCO_2014
Initial conditions		SODA2.2.4	GDEMv3
Open boundary conditions		SODA 2.2.4 climatological monthly mean	SODA3.3.1 and SODA 3.3.2 monthly mean
Sea surface atmospheric forcing	Data	NCEP Reanalysis 2	CFSR
	Method	Directly fluxes forcing	COARE3.0 Bulk_Formula
The parameter of $dQ/dSST$		Constant (-60)	Calculated with spatiotemporal variations
Observed SST data used for net surface heat flux correction		MGDSST	AVHRR
The position of eastern lateral boundary		145°E	144°E
Vertical layers		36	50

Horizontal advection scheme of tracers	Third-order upstream	Fourth-order Akima
Vertical advection scheme of tracers	Fourth-order centered	Fourth-order Akima
Horizontal mixing surface	Constant density	Geopotential surfaces
Assimilated observation data	SLA	SLA, AVHRR, Argo profiles

215 The SCSOFSv2 is run using with a 5_s time step for the external mode, and a 150_s time step for the internal mode under all of the new configurations described mentioned above and those that will be introduced in Section 3. The reason for the modification ying of the time step is related to the change in of the discrete schemes, which will be illustrated further in Section 3. First, a 26--years climatology run is conducted for spinning-up-at first, and followed by a hindcast run from 2005 to 2018 (Wang et al., 220 2012). The daily mean of the model results is archived and used for the subsequent evaluation.

3. Highlights, and sensitive updates, and their impacts

Most of the bias and of errors in the operational systems are mainly induced by several some major recurring problems, for example, external forcing, the intrinsic deficiencies of the numerical model (e.g., discrete schemes and sub-grid scale, parameterization schemes for sub-grid scale), initial errors, and the 225 assimilation schemes. In this section, we elaborate upon the solutions to such problems that are applied in SCSOFSv2, which were has not discussed been mentioned in Section 2. All of these solution them have significantly improved the model skills of the SCSOFS from different aspects, such as the SST, the three- dimensional temperature and salinity structures, and the comprehensive simulationg skill, especially for the meso-scale processes.

230 3.1 Sea surface atmospheric forcing

The air--sea interactions are is one of the most essential physical processes that affect the vertical mixing and thermal structure of the upper--ocean. The air--sea fluxes mainly include the momentum flux, fresh water flux, and heat flux. The SST is an important indicator of the ocean circulation, ocean front, upwelling, and sea water mixing, and its whose variations mainly depend ing on the air--sea interactions, 235 and the ocean's thermal and dynamical factors (Bao et al., 2002). Thus, for the OOFS and ocean

numerical modelling, the SST simulation and forecasting accuracy ~~of SST~~ is ~~an~~ important metric ~~for~~ evaluating the modelling and forecasting performance.

The accurate input of the sea surface atmospheric forcing plays a key role ~~to excel in the performance of~~ the model simulation of the SST. The ROMS provides two methods ~~of~~ introducing the sea surface atmospheric forcing: one is directly forcing the ocean model by providing momentum fluxes (wind stress), net fresh water fluxes, net heat fluxes and shortwave radiation fluxes from the atmospheric datasets; the other is employing the COARE3.0 bulk algorithm (Fairall et al., 2003) to calculate the air-sea momentum, fresh-water, and heat turbulent fluxes using the set of atmospheric variables from the atmospheric datasets, including the wind speed at 10_m above the sea surface, the mean sea level air pressure, the air temperature at 2_m above the sea surface, the air relative humidity at 2_m above the sea surface, the downward longwave radiation flux, the precipitation rate, and the shortwave radiation fluxes (Large and Yeager, 2009). The calculations ~~of~~ the air-sea fluxes, sensible heat flux, latent heat flux, and longwave radiation can be referenced to Li et al. (2021). Since the SST used in the calculation of ~~these~~ these three air-sea fluxes is extracted from the ocean model, ~~an~~ the increase ~~in the~~ of SST induces their variations in these fluxes as a result, which then leads to ~~increasing~~ loss of ocean heat, and ~~inhibits~~ further increases in the ~~of~~ SST; and vice versa. ~~Thus, it means that~~ an effective negative feedback mechanism ~~can~~ form between the SST and the SST-related heat fluxes. In this case, it is much easier to maintain the simulated SST at a reasonable level. The first method is employed in SCSOFSv1, and the second method, i.e., the bulk algorithm, is employed in SCSOFSv2.

In order to evaluate the performances of the different sea surface atmospheric forcing methods, we conducted a special experiment by changing the method based on SCSOFSv1, which is referred to as BulkFormula here named the experiment in this paper as BulkFormula. In this experiment, we used the merged satellite SST analysis with a multi-scale optimal interpolation, called the Operational SST and Sea Ice Analysis (OSTIA) system, ~~with~~ globally coverage on a daily basis ~~and~~ a horizontal grid resolution of 1/20° (~6 km), ~~which is~~ and produced by the Met Office (Donlon et al., 2012), to verify the results of the SCSOFS.

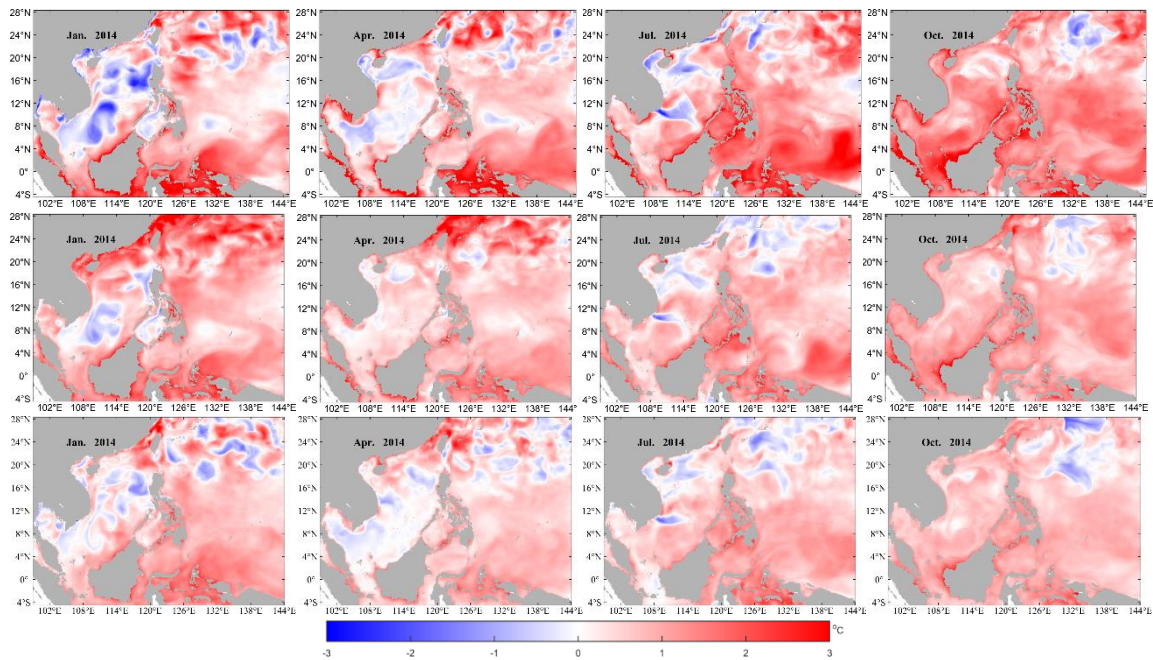


Figure 3: The monthly mean SST differences in January, April, July, and October of 2014: SCSOFSv1 minus OSTIA (upper panels), BulkFormula minus OSTIA (middle panels), SCSOFSv2 minus OSTIA (lower panels)

265 Figure_3 shows the distributions of the monthly mean SST differences in January, April, July, and October of 2014, which represent to stand for Wwinter, Sspring, sSummer, and Aautumn, respectively. The SST differences were calculated usingwith SCSOFSv1, BulkFormula, and SCSOFSv2 minus subtracts the OSTIA, respectively. It was found that the simulated SST were higher than the OSTIA in all three sets of results. The difference from SCSOFSv1 is significantly pronouncedly higher than the differences from the BulkFormula and SCSOFSv2. The maximum differences mainly occur near the coast (Fig.3-upper panels in Fig.3), especially for a few bays embedded into the mainland, which areis nearly impossible to resolve well usingwith 2-3 horizontal grids with at 1/30° resolution and within very shallow water depth in SCSOFSv1. This is because the sea surface atmospheric forcing data areis not accurate enough near the coast, and they provide an abnormally higher amount of heat to the ocean, resulting ineasuring the continuously heating of the coastal water. Thus, the simulated SST is beyond the normal level in SCSOFSv1. This phenomenon can be significantly alleviated significantly by introducing the effective negative feedback mechanism between the model's SST and the air-sea heat flux usingby employing the COARE 3.0 bulk algorithm, which is employed in both the BulkFormula and SCSOFSv2 (Fig.3 middle and lower panels).

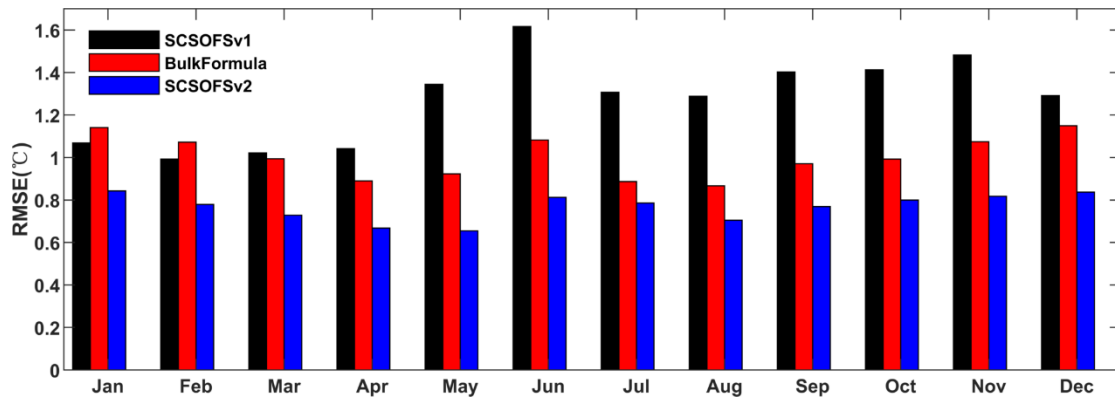


Figure 4: Domain averaged monthly mean SST RMSE comparison of the among SCOSFSv1 (black), BulkFormula (red), and SCOSFSv2 (blue) with the and OSTIA SST in January, April, July, and October of, 2014

Figure 4 shows the bars of the domain averaged Root-Mean-Square Error (RMSE) of the monthly mean SST differences between of SCOSFSv1, BulkFormula, and SCOSFSv2 with respect to the OSTIA datasets for each month in of 2014. It was found that the domain averaged RMSE of the monthly mean SST differences from SCOSFSv1 is about 0.99 °C–1.62 °C, and the annual mean value is about 1.27 °C. The highest (1.62 °C) is in June, and the lowest (0.99 °C) is in February. The Monthly mean RMSE for the BulkFormula run is about 0.87 °C–1.15 °C, and the annual mean value is about 1.00 °C. The maximum value (1.15 °C) is in January and December, and the minimum value (0.87 °C) is in August. The performance of the model's skill for the annual mean SST RMSE is can be improved by about 21% only by changing the method of sea surface atmospheric forcing method from directly forcing to the COARE 3.0 bulk algorithm due to the effective negative feedback mechanism.

However, the domain averaged RMSE of the monthly mean SST differences from the SCOSFSv1 is lower than that from the BulkFormula in January and February, especially in the shallow region around the Taiwan Island. This indicates that the COARE 3.0 bulk algorithm is not necessarily a panacea, even with an effective negative feedback mechanism. This may be dependent on the surface forcing field data dependent, and the use of an accurate dataset for the sea surface atmospheric forcing is more important effective than the selection of the forcing methodology selection (Li et al., 2019). It also may suffer from the complicated air-sea interactions and tidal mixing missed in the model.

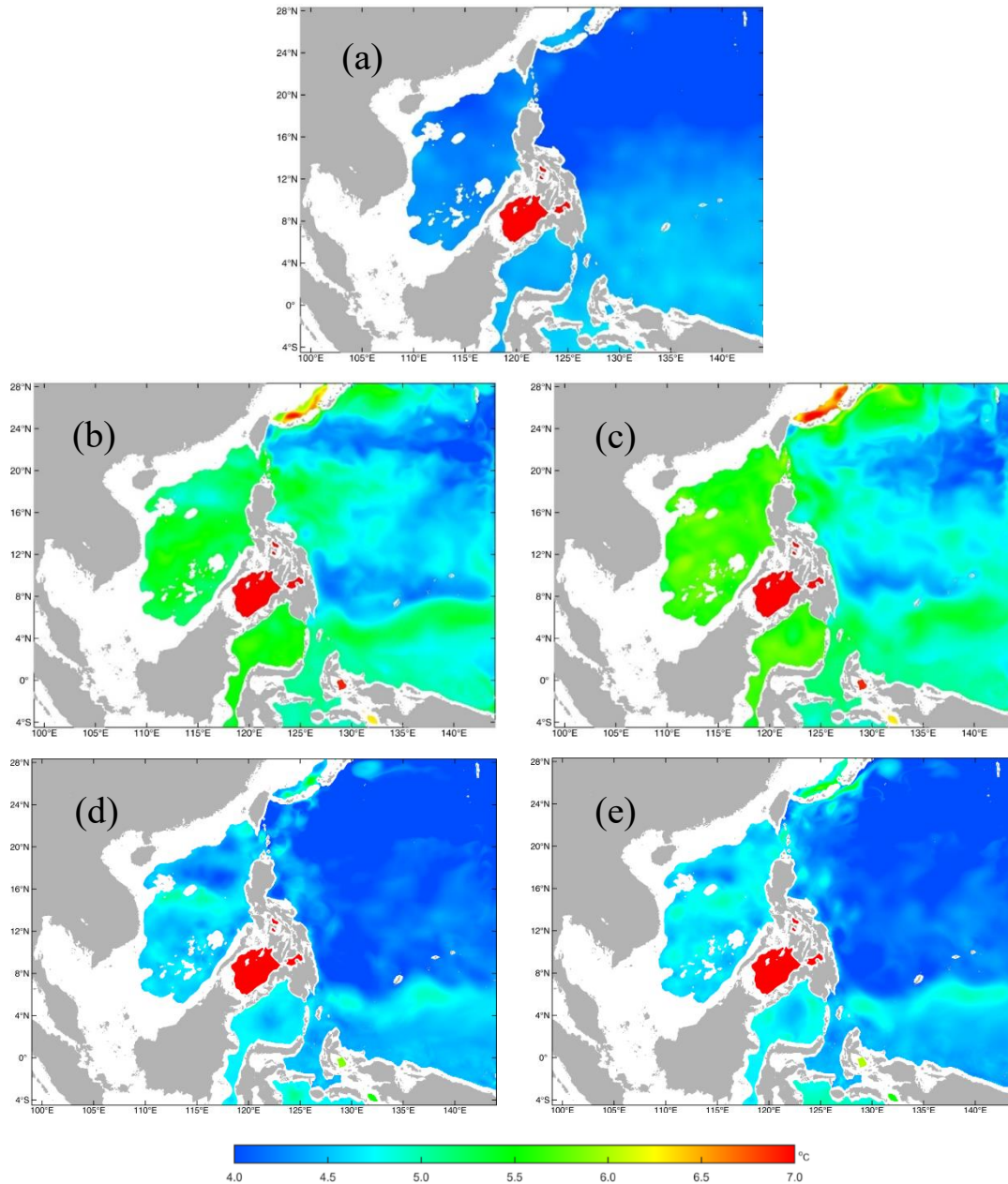
3.2 ~~Discrete~~ Tracers advection term ~~discrete~~ schemes

Spurious diapycnal mixing is one of ~~the~~ traditional errors in state-of-the-art atmospheric and oceanic models, especially for ~~regional~~~~the~~ terrain-following coordinate ~~regional~~ models, including both the continental slope and deep ocean (Marchesiello et al., 2009; Naughten et al., 2017; Barnier et al., 1998).

Marchesiello et al. (2009) identified the problem ~~as~~ the erosion of ~~the~~ salinity from the southwest Pacific model with steep reef slopes and distinct intermediate water masses based on ~~the~~ ROMS. They found that ~~the~~ ROMS cannot preserve the large-scale water masses while using the third-order upstream advection scheme during the spin-up phase of the model, and ~~they~~ proposed a rotated split upstream third-order scheme to decrease ~~the~~ dispersion and diffusion by splitting ~~the~~ diffusion from ~~the~~ advection.

They implemented the rotated split upstream third-order scheme by employing a rotated biharmonic diffusion scheme with flow-dependent hyper diffusivity satisfying the Peclet constraint.

For SCSOFSv1, a third-order upstream horizontal advection scheme, a fourth-order centered vertical advection scheme, and ~~a~~ scheme of



315

Figure 5: The distributions of the monthly mean temperature in the 1000_m layer in January from the (a) GDEMv3 climatology, (b) the fifth and (c) the 11eleventh model year by using the scheme combination of the UCI based on SCSOFSv1 for other model settings, (d) the fifth and (e) the 11eleventh model year by using the scheme combination of the AAG based on SCSOFSv2 for other model settings.

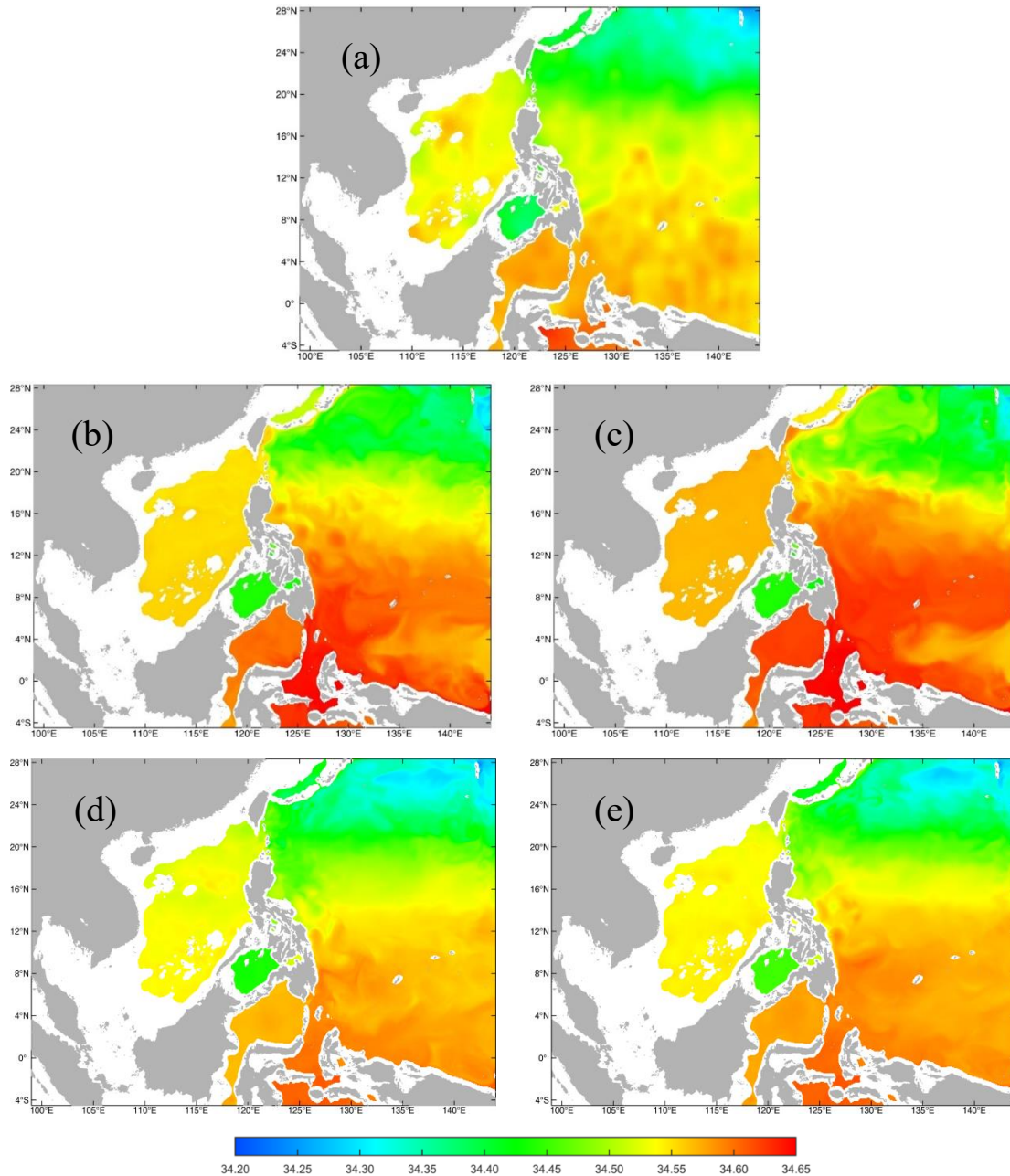
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horizontal mixing on epi-neutral (constant density) surfaces for tracers we are selected (Shchepetkin and McWilliams, 2005). We have encountered same problem with Marchesiello et al.'s (2009) method regarding the temperature (Fig.5b and 5c) and salinity (Fig.6b and 6c) in the deep layer. Figure 5 and 6 show the distributions of the monthly mean temperature and salinity in the 1000_m layer in January

from the GDEMv3 climatological initial fields, ~~as well as~~ the simulated results from the fifth and the
325 ~~11~~^{eleventh} model years by using 1) the scheme combinations of the third-order upstream horizontal
advection, fourth-order centered vertical advection, and horizontal mixing on epi-neutral surfaces
(hereafter referred to as UCI) and 2) the combination of the fourth-order Akima scheme (Shchepetkin
and McWilliams, 2005) for both the horizontal and vertical advection terms and the scheme of horizontal
mixing along Geopotential surfaces (constant Z) for tracers (hereafter referred to as AAG), respectively.
330 ~~The~~ and other settings are identical ~~to those of~~ with SCSOFSv2. Figure 7 shows the comparisons of the
time series of the domain averaged monthly mean temperature and the salinity ~~in the~~ 1000 m layer
simulated using the scheme combinations of the UCI in SCSOFSv1 and the AAG in SCSOFSv2,
~~respectively~~. In order to ~~lower~~ save computation costs, we only ~~ran~~ the model with the scheme
combination of the UCI for over 16 years ~~until~~ it reached a stable states.

335 The fourth-order Akima scheme is a little different from the fourth-order centered scheme ~~because it~~
~~replaces by replacing~~ the simple mid-point average with harmonic averaging in the calculation of the
curvature term. Since the time stepping is done independently ~~of the~~ from-spatial discretization in the
ROMS, the Akima scheme ~~has the~~ represents its advantage of reducing the spurious oscillations, which
arises ~~from with the~~ non-smoothed advected fields, with respect to the fourth-order centered scheme
340 (Shchepetkin and McWilliams, 2003, 2005).

During the spin-up phase of the model from the initial conditions derived from GDEMv3, the temperature
at 1000 m increases from ~~the~~ 3.0-12.0°C by initial settings of 3.0 °C-12.0 °C (Fig.5a) to 3.0 °C-17.2°C
(Fig.5b), and the domain averaged monthly mean value quickly increases from 4.4 °C to 5.1 °C (Fig.7a)
in



345

Figure 6: The same as Fig. 5, but for salinity.

January of the fifth model year. The salinity at 1000 m increases from the initial settings of 34.26–34.62 by initial settings (Fig. 6a) to 34.27–34.68 (Fig. 6b), and the domain averaged monthly mean value increases rapidly from 34.50 to 34.54 (Fig. 7b) in January of the fifth model year. In particular, especially, the increase in the domain averaged monthly mean value is almost linearly for both the temperature and salinity in the first 50 months, indicating a fast rate of increase and strong spurious diapycnal mixing (Fig. 7). These values are even higher in January of the 11th model

350

year, the ranges (minimum and maximum values) reach to 3.0 °C–17.3 °C for temperature (Fig. 5c) and 34.26–34.73 for temperature (Fig. 5c) for and salinity (Fig. 6c), respectively. The domain averaged values are 5.3 °C for temperature and 34.56 for salinity (Fig. 7), respectively. The areas with increasing temperature and salinity are mainly located on the steep slopes and nearby regions, e.g., the central basin of the SCS, the Sulawesi Sea, and the equatorial Pacific Ocean.

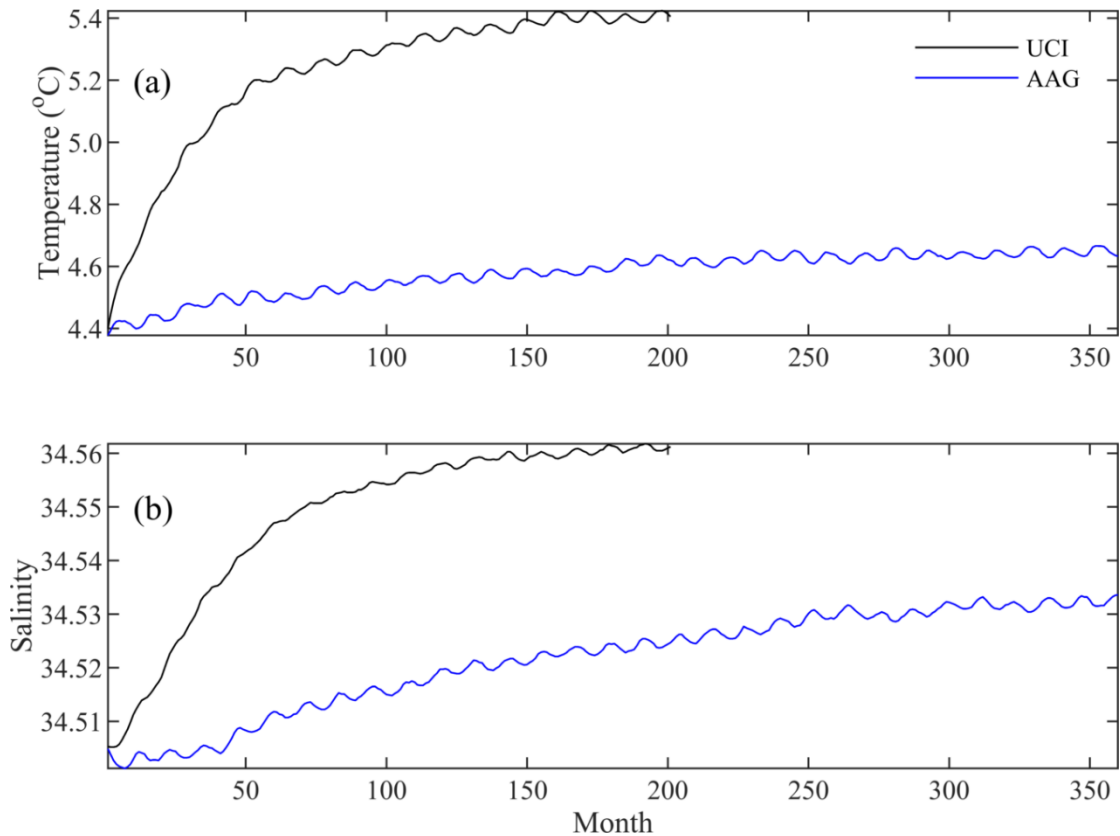


Figure 7: The timeseries of the domain averaged monthly mean (a) temperature (a) and (b) salinity in the (b) at 1000 m layer simulated by using the scheme combinations of UCI (black line) and AAG (blue line), respectively

To fix this problem, we tested various model settings and compiling options available in ROMS, such as increasing the number of vertical levels, changing the advection and diffusion schemes, horizontal mixing surfaces for tracers, and horizontal mixing schemes. The details of how the tested model settings effect on the spurious diapycnal mixing are beyond the scope of this paper, and they which will be discussed in a separate paper.

The monthly mean temperature ~~in the~~ 1000 m layer from ~~for~~ SCSOFSv2 varies from ~~the initial conditions of~~ 3.0 °C–12.0 °C ~~in initial condition~~ to 3.0 °C–11.5 °C (Fig.5d); and the domain averaged monthly mean value increases slightly from ~~the initial value of~~ 4.4 °C ~~in initial~~ to 4.5 °C ~~(Fig.7a)~~ in January ~~in~~ the fifth model year (Fig.7a). The salinity at 1000 m varies from ~~the~~ 34.26–34.62 ~~in initial conditions of~~ 34.26–34.62 to 34.24–34.63 (Fig. 6d); and the domain averaged monthly mean value only ~~slightly~~ varies ~~slightly~~ from ~~the initial value of~~ 34.505 ~~in initial~~ to 34.509 (Fig.7b) in January ~~in~~ the fifth model year (Fig. 7b). These values ~~exhibits~~ show little variation ~~until~~ January of the 11th model year, the ranges are 3.0 °C–11.3 °C for temperature (Fig. 5e) and 34.25–34.63 for salinity (Fig. 6e), and the domain averaged values are 4.6 °C for temperature and 34.52 for salinity (Fig. 7); ~~respectively. For~~ the increment of ~~the~~ domain averaged value ~~for~~; temperature is about 0.2°C and ~~that~~ for salinity is about 0.03, ~~but they~~ yet remaining stable after 20 model years (Fig. 7). ~~This~~ is suggested that ~~the~~ spurious diapycnal mixing ~~is significantly~~ has been suppressed ~~significantly~~ by ~~the~~ AAG scheme combination, which can preserve the characteristics of ~~the~~ water masses in ~~the~~ deep ocean well. ~~In addition~~ Meantime, ~~the~~ temperature and salinity biases in the subsurface layer ~~are~~ have been significantly improved ~~significantly~~, which will be shown in the latter part of this paper.

In addition, it ~~was~~ found that the model skill for ~~the~~ SST ~~has~~ also ~~significantly~~ been improved ~~significantly while using~~ the new AAG scheme ~~employed~~ in SCSOFSv2 (Fig. 3 and Fig.4). The maximum of ~~the~~ monthly mean differences between ~~the simulated~~ SST ~~simulated~~ by SCSOFSv2 and OSTIA is about 3 °C–4 °C, which is obviously smaller than the results ~~of the~~ from BulkFormula. Comparing with the results of SCSOFSv1 and BulkFormula, ~~the results of SCSOFSv2 have a lower~~ less SST hot bias ~~versus OSTIA is found~~ in the central Pacific Ocean ~~relative to OSTIA for the result of SCSOFSv2~~, which ~~is can be~~ attributed to the new ~~scheme~~ combination ~~scheme~~. ~~The~~ For ~~the~~ domain averaged RMSE of ~~the~~ monthly mean SST of SCSOFSv2 is ~~about~~ 0.65 °C–0.84 °C, with an annual mean value of 0.77 °C; ~~†~~ The maximum value (0.84 °C) is in January and December, ~~and~~ the minimum value (0.65 °C) is in May. Comparing with the results of ~~the~~ BulkFormula, the performance of ~~the~~ model skill ~~based on judging from~~ the annual mean SST RMSE is improved by about 23% due to ~~the usage of the employing~~ new combination scheme in SCSOFSv2. ~~†~~ This indicates that ~~the~~ subsurface or deep layer

processes can affect the surface layer significantly due to vertical heat transport, which is induced by the barotropic and baroclinic instabilities that increasing the eddy kinetic energy (Ding et al., 2021).

3.3 Data assimilation scheme

As ~~was reported by~~ mentioned as Zhu et al. (2016), the original SCSOFSv1 ~~used~~ had employed the multivariate Ensemble Optimal Interpolation (EnOI, Evensen, 2003; Oke et al., 2008) method to assimilate the along track altimeter Sea Level Anomaly (SLA) data produced by SSALTO/DUACS and distributed by AVISO with support from the Centre National D'études Spatiales. During this upgrading process, we also improved several of the some functions of the EnOI scheme, and developed a new "Multi-source Ocean data Online Assimilation System" (MOOAS).

Firstly, SCSOFSv1 only assimilated the along track SLA data ~~only~~, while SCSOFSv2 is also additionally able to simultaneously assimilate satellite AVHRR SST and *in-situ* temperature and salinity vertical profiles data from the Argo arrays, ~~simultaneously~~. ~~This~~ It is ~~accomplished~~ conducted by ~~combining~~ constructing the four variables' all innovations (difference between the assimilated observation and the model forecast), background error covariances, and observation errors ~~for four different variables into each one array, respectively~~. It is worth to pointing out that, the SLA data assimilated into the SCSOFS is a nearly real time along-track L3 product for special assimilation specially, which is filtered but not subsampled and ~~the~~ with Dynamic a Atmospheric Correction, ocean tide, long wavelength error correction is applied (CMEMS-SL-QUID-008-032-051, <http://marine.copernicus.eu/documents/QUID/CMEMS-SL-QUID-008-032-051.pdf>). The filtering processing consists ~~of~~ a low-pass filtering with a cut-off wavelength of 65 km and a 20-day period using a Lanczos filter. ~~The~~ Residual noise and small-scale signals are then removed via by filtering. For the measurement errors ~~of the~~ in SCSOFSv2, we set those of the SLA as constants of 3 cm according to the method of Taburet et al. (2018), and directly used the estimated error standard deviation of the analysed AVHRR SST ~~directly, respectively~~, as ~~for~~ those of the Argo profiles, assuming they are ~~represented as~~ a function of water depth (D) following Xie and Zhu (2010), as $ERR_T(D)=0.05+0.45\exp(-0.002D)$, and $ERR_S(D)=0.02+0.10\exp(-0.008D)$.

420 Secondly, we ~~have~~ introduced the method of computing the anomalies of the ensemble numbers used for
constructing the background error covariance following Lellouche et al. (2013). In SCSOFSv1, the
anomalies are computed by subtracting a 10-year average from ~~a~~ long-term (typically 10 years) model
free run snapshots with a five~~5~~-day interval for the ocean state, i.e., the sea surface height and three-
dimensional temperature, salinity, zonal velocity, and meridional velocity. In addition,~~And~~ the ensemble
425 is selected within a 60-~~day~~ window around the target assimilation date from each year, resulting adding
in a total of up to about 130 members ~~in total~~ (Ji et al., 2015; Zhu et al., 2016). However, in SCSOFSv2,
a Hanning low-pass filter is employed to create the running mean according to Lellouche et al. (2013) in
order to obtain~~get the~~ intra-seasonal variability of~~in~~ the ocean state. Thus, the anomalies are computed
by subtracting the running mean with a 20-day time window from ~~the~~ 10-year (2008-2017) free run
430 daily averaged results. In particular,~~Especially,~~ it should be~~is noted~~ ~~pointed out~~ that the daily averaged
free run results are selected within a 60-~~day~~ window, i.e., with 30 days before and after the target
assimilation date from each year ~~in~~ of 2008-~~2017,~~ and are used to compose the ensemble members,
resulting in a total of~~thus totally~~ about 590 members in SCSOFSv2. This~~It~~ means that the background
error covariances rely on a fixed basis and an intra-seasonally variable ensemble of anomalies, which
435 improves the dynamic dependency.

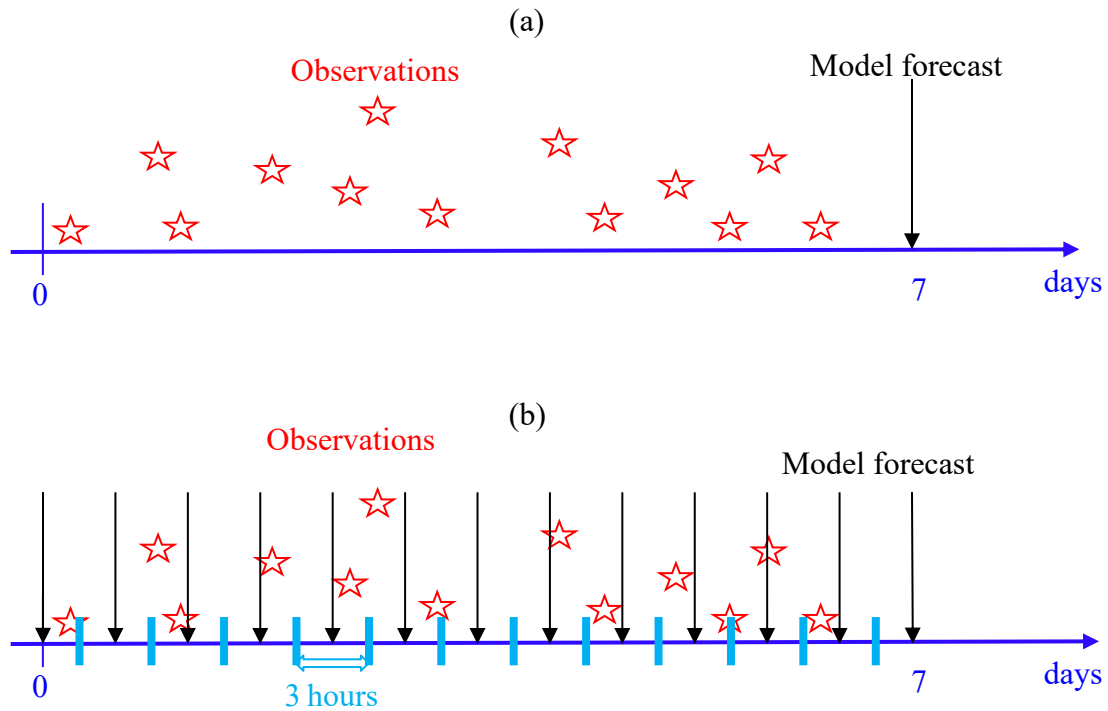


Figure 8: Schematic representation of the FGAT method: (a) not used in SCSOFSv1 and (b) used in SCSOFSv2. Red stars stand for denote the observations, and the black arrows denote the stand for archived snapshots of model forecast

440 Thirdly, for each analysis step with a seven-day assimilation cycle, all of the observations of the SLA within the seven-day time window before the analysis time are treated as being observed at the analysis time in SCSOFSv1, with the assumption that of all of the observations were still valid at the analysis time. The time misfit between the observation and the model forecast would causes non-negligible biases when calculating innovations. Actually, it is inconvenient to calculate all of the synchronous innovations

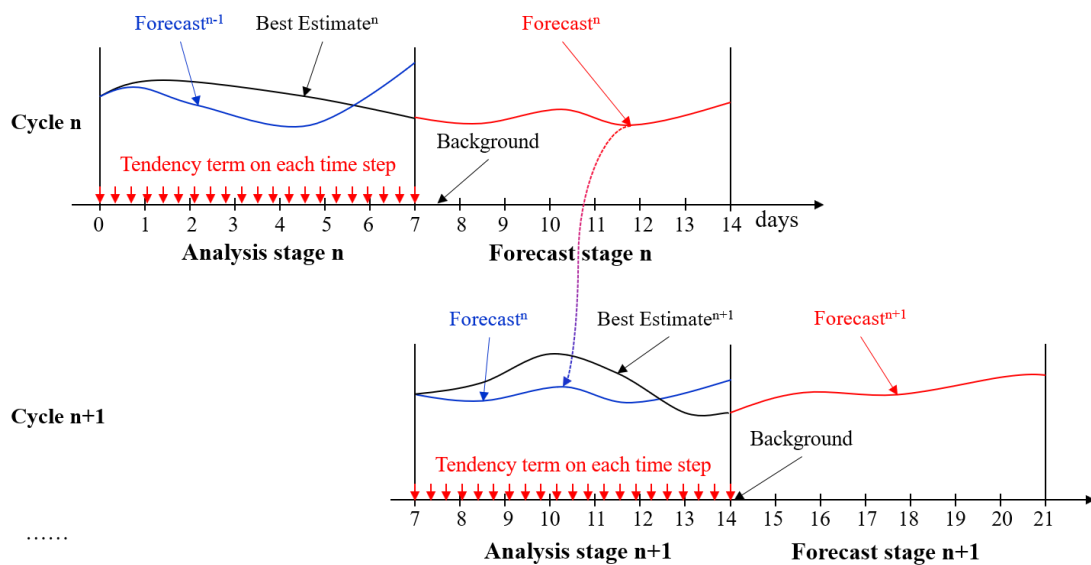
445 between the observation and model forecast entirely, since the spatial and temporal distributions of the along-track SLA and Argo data are irregular and variable in each analysis step. In order to alleviate this deficiency, the First Guess at Appropriate Time (FGAT) method (Lee and Barker, 2005; Cummings, 2005; Lee et al., 2004; Sandery, 2018) was used in SCSOFSv2. Considering the intense computing and storage costs, we have divided the seven-day time window into 56 three-hour time slots (Fig. 8), and

450 archived 57 snapshots with a three-hour interval, while the model forecast was run following the previous analysis run. Then, the innovations were can be calculated within each three-hour time slot by

using the observations ~~minus~~subtracts the nearest model forecast. ~~This~~ means that the maximum temporal misfit of the innovations between the observation and ~~the~~ model forecast ~~would be~~were decreased from ~~seven~~7 days to 1.5 hours by using FGAT. ~~In addition~~Meanwhile, ~~as in~~ SCSOFSv1, the localization ~~was~~is still used with the radius set to ~~be~~ 150 km ~~as in~~ SCSOFSv1.

In SCSOFSv1, the analysis increments of ~~the~~ sea surface height and three-dimensional temperature, ~~the~~ salinity, ~~and the~~ zonal and meridional velocities produced by each analysis of ~~the~~ data assimilation ~~were~~are applied to the model's initial fields at one time step. ~~This inevitably~~It would induced a significant initial shock and spurious high-frequency oscillation ~~into~~ the model due to the imbalance between the increments and the model physics ~~inevitably~~ (Lellouche et al., 2013; Ourmières et al., 2006), and ~~it~~ usually ~~resulted~~causes ~~in a~~ rapid growth of ~~the~~ forecast error and even ~~lead~~ to ~~the~~ model blowing-up after a few assimilation cycles or one or two ~~years~~period after the intermittent assimilation run. ~~This was~~It is a threat to the stability and robustness of ~~the~~ Oofs. Therefore, we introduced the incremental analysis update (IAU) method (Bloom et al., 1996; Ourmières et al., 2006) to apply each analysis increment to

the model integration as a forcing term in a gradual manner in SCSOFSv2 to diminish the negative impact. In ~~this~~our case, we ~~obtained~~get the tendency term by dividing the increments ~~by~~with the total number of time steps within an assimilation cycle, as in most IAU methodologies, in order to make sure the time integral of ~~the~~ tendency term ~~equal~~leds the analysis increment calculated by ~~the~~ EnOI.



470 **Figure 9: Schematic representation of the data assimilation procedure for two consecutive cycles, n and n+1, in SCSOFSv2, while considering the FGAT and IAU methods.**

Once ~~including~~ the FGAT and IAU methods were included in the EnOI scheme, the entire whole system's integral strategy hads to be adjusted by adding one more model integration over the assimilation time window (Lellouche et al., 2013). In SCSOFSv1, only one time model integration is needed ~~only one time~~.
475 ~~This~~ means that once physical ocean model finishes a seven7-day run (does not need to archive snapshot fields) and outputs a restart field, The EnOI data assimilation module starts to calculate the analysis increments at the restart field time and adds it to the restart field, ~~Then~~, the physical ocean model ~~implements~~makes a hot-start from the updated restart field to run the seven7 days ~~of~~ the next cycle.

480 However, in SCSOFSv2, two times model integration ~~are~~is needed ~~twice~~ due to the use of ~~considering~~ the FGAT and IAU methods (Fig.8). ~~This~~ means that the physical ocean model needs to be integrated 14 days in each assimilation cycle, to add the tendency term to the model prognostic equations due to the IAU method used during the first seven7-day~~s~~ run (referred to as the a“Analysis sStage”), to output a restart field at the end of 7th day for hot starting the ocean model in the next cycle, and to output ~~3~~three-
485 hourly snapshot~~s~~ forecast fields during the second ~~7~~seven-day~~s~~ run (referred to as the “Fforecast sStage”) to be used in the next cycle by the FGAT method. The model outputs from the ~~A~~Analysis sStage are referred to as the “~~B~~Best ~~E~~Estimate”, and those from the ~~F~~Fforecast sStage are referred as “the ~~F~~Fforecast”. The analysis increments are defined at the 3.5th day, but not at the end of the seven7th day as in SCSOFSv1, ~~T~~with the observed SLA and Argo vertical profiles data are within the seven7-day time
490 window, and the AVHRR SST data on the 4fourth day are used by the FGAT method.

4. Inter-comparison and accuracy assessment

In order to ~~demonstrate~~show the improvements of the different SCSOFS sub-versions during the upgrading process, the results of the inter-comparison and assessment are ~~presented~~shown and discussed in this section, ~~by~~ using the GOV Inter-comparison and Validation Task Team (IV-TT) Class 4
495 verification framework (Hernandez et al., 2009). Class 4 metrics ~~were originally~~are used for inter-

comparison and validation among different global or regional OOFs or assimilation systems ~~originally~~ (Ryan et al., 2015; Hernandez et al., 2015; Divakaran et al., 2015). ~~They~~ ~~it~~ includes four metrics: ~~the~~, ~~namely~~, bias for ~~assessing the~~ consistency, ~~the~~ RMSE for ~~assessing the~~ quality or accuracy, ~~the~~ anomaly correlation for ~~assessing the~~ pattern of the variability, and ~~the~~ skill scores for ~~assessing the~~ utility of a forecast. They are calculated according to differences between ~~the~~ model values and ~~the~~ reference measurements in observations space for each variable over a given period and spatial domain. The physical variables used in ~~the~~ Class 4 metrics are ~~the~~ SST, SLA, Argo profiles, surface currents, and sea ice. ~~The r~~Reference measurements, providing ~~the~~ ocean “truth”, are selected as follow~~s~~; ~~the~~ SST ~~data~~ from ~~the~~ *in-situ* drifting BUOY, ~~the~~ SLA ~~data~~ from ~~the~~ AVISO along-track data, ~~and the~~ temperature and salinity ~~data~~ from ~~the~~ Argo profiles, ~~respectively~~. They are assembled by GOV IV-TT participating partners on a daily basis (Ryan et al., 2015).

It is virtually impossible to ~~exhaustively~~ test and validate ~~the exhaustively~~ performances of all ~~of the~~ upgrades ~~described~~~~mentioned~~ in Sections 2 and 3. Here, we separate the ~~entire~~~~whole~~ upgrading procedure from SCSOFSv1 to SCSOFSv2 into four stages with three ~~more~~ sub-versions (v1.1, v1.2, ~~and~~ v1.3) according to the reality. ~~By respecting to the previous version,~~ ~~T~~he major upgrades ~~to~~in each new version ~~with respect to the previous version~~ are listed in Table 2.

Table 2 The major upgrades with respect to the previous version

SCSOFS versions	Settings updates
v1→v1.1	ROMS version changed shifting from v3.5 to v3.7; land-sea mask redistribution; bathymetry substitution of ETOPO1 with GEBCO_2014; initial temperature and salinity conditions changed ing from SODA2.2.4 to GDEMv3; open boundary data changed ing from climatological monthly mean to monthly mean from 1990 to 2008 with SODA 2.2.4; sea surface atmospheric forcing data changed ing from NCEP Reanalysis 2 to CFSR; the parameter dQ/dSST changed ing from constant to temporally and spatially varying values; sea surface atmospheric forcing method changed ing from directly fluxes forcing to BulkFormula

v1.1→v1.2	Open boundary data of SODA 2.2.4 monthly mean extended from 2008 to 2010; the eastern lateral boundary moved westward; the observed SST data used for the net surface heat flux correction changed from MGDSST to AVHRR
v1.2→v1.3	Considering Mean sea level atmospheric pressure effect considered, increasing vertical layers increased from 36 to 50; changing the transform and stretching function changed ; tracers advection discrete schemes changed from UCI to AAG; Changing the open boundary data changed from SODA 2.2.4 monthly mean to SODA 3.3.1 and 3.3.2
v1.3→v2	Including The MOOAS included

In this study paper, we used the Class 4 metrics and selected the first four physical variables, (SST, SLA, and Argo profiles), to inter-compare and assess the accuracies of the among different sub-versions of the SCISOFS (Table 3). Since none of all the reference measurements data described above have ~~not~~ been used in these sub-versions of SCISOFS ~~for those sub-versions~~ without data assimilation, they are ~~independent~~ reference observation independent from SCISOFS, except for SCISOFSv2. The inter-comparison and validation of the among those sub-versions without data assimilation we are conducted for the model free-run results in 2013, and the inter-comparison and validation between v1.3 and v2 we are conducted in 2018 to validate the performance of the MOOAS.

Table 3 Mean values of each metric of the four physical variables for the best estimates of each sub-version (T denotes temperature, S denotes salinity, AC denotes anomaly correlation)

Variables	Metrics	v1	v1.1	v1.2	v1.3		v2
SST	AC	0.52	0.56	0.58	0.62	0.64	0.74
	Bias (°C)	0.77	0.88	0.70	0.40	0.34	0.24
	RMSE (°C)	1.21	1.12	0.98	0.76	0.66	0.52
SLA	AC	—	—	—	—	0.67	0.85
	Bias (cm)	<u>-7.0</u>	<u>-5.5</u>	<u>-7.0</u>	<u>-7.4</u>	<u>-5.2</u>	<u>-3.1</u>
	RMSE (cm)	21.6	20.8	16.7	14.8	12.9	8.5
T Profile	AC	0.01	0.04	<u>-0.12</u>	0.48	0.38	0.57
	Bias (°C)	0.98	0.75	0.30	<u>-0.15</u>	<u>-0.08</u>	0.15
	RMSE (°C)	1.75	1.60	1.44	1.03	0.96	0.67
S Profile	AC	<u>-0.01</u>	<u>-0.02</u>	0.02	0.44	0.30	0.51
	Bias	0.06	0.05	0.06	0.02	0.013	0.009
	RMSE	0.14	0.14	0.13	0.10	0.11	0.08
Year		2013			2018		

4.1 SST

The accuracy of the SST is continuously increasing from version v1 to v2, and the anomaly correlation increased from 0.52 in v1 to 0.74 in v2, i.e., a with percentage increase being 29.7% improvement. The RMSE is decreasing from 1.21°C in v1 to 0.52°C in v2, i.e., a with percentage increase being 57.0% improvement, for the annual mean of the entire whole model domain averaged in 2013 (or v1.3 and v2 in 2018) (Table 3). For the versions v1, v1.1, v1.2, and v1.3, their anomaly correlation exhibited shows significant seasonal variations, with high anomaly correlations in summer and low anomaly correlations in winter. It was also found indicated that the accuracy of the SST can be benefited from the sea surface atmospheric forcing method, as well as the usage of more accurate observed SST data for the sea surface heat flux correction, temperature advection discrete scheme, and SST data assimilation.

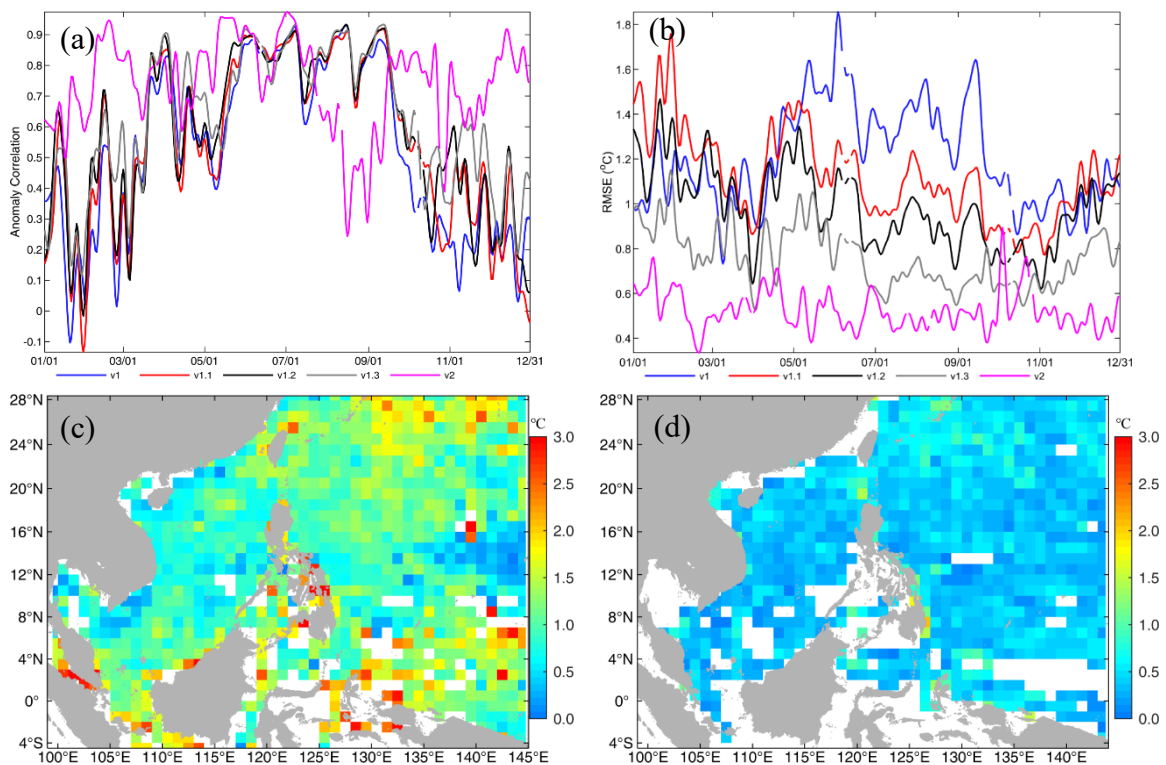


Figure 10: (a) Anomaly correlation (a) and (b) RMSE (b) time-series of the SST best estimates for each version against observations as a function of time (seven-day low-pass filter applied), i.e., v1, v1.1, v1.2, and v1.3 without data assimilation in 2013, and v2 with data assimilation in 2018. Horizontal distribution of the SST

RMSE in a $1^{\circ} \times 1^{\circ}$ bin for the versions (c) v1 and (d) v2. The calculations were performed for year-round in 2013 and 2018, respectively

540 The improvement of the SST due to sea surface atmospheric forcing method changed mainly occurred in summer time, exhibiting the same pattern as the results for the year 2014 in Figs. 3 and 4. However, but using sea surface heat flux correction with more accurate observed SST data for the sea surface heat flux correction improved accuracy of the SST simulation for the whole year-round (v1.2 in Fig. 10b). We also found that the OISST data were closer to the OSTIA than the MGDSST (figure not shown). Due to the benefits obtained from these changes, the maximum and minimum values of the SST RMSE have decreased from 1.92 °C and 0.71 °C for v1 to 1.52 °C and 0.60 °C for v1.2 for the entire year 2013, respectively. It is worth mentioning that the AAG schemes combination not only improved the deep layer temperature, but it also contributed to the improvement of the SST due to the internal baroclinic vertical heat transport. The maximum and minimum values of the SST RMSE were 1.21 °C and 0.52 °C for v1.3. For the results with data assimilation in v2, the maximum and minimum values of the SST RMSE were only 1.13 °C and 0.32 °C, respectively, which are better than the results for v1.3 year-round.

For the horizontal distribution of the SST RMSE, the large values were mainly located in the areas near the equator, coastal areas, and the northern lateral boundary, with most of the values larger than 1.5 °C and a maximum value of about 6.67 °C for v1 (Fig. 10c). For v1.3, due to the contributions of all of the above described model updates, the pattern of the RMSE was similar to that of v1, i.e., basically without significant variations, but the maximum value decreased to 3.91 °C and most of the values were less than 1.2 °C. After applying MOOAS in v2 (Fig. 10d), only a few large RMSE values were located on the eastern coast of Philippine Island, with a maximum value of 2.09 °C, and most of the values were lower than 0.8 °C. This indicates that the performance of the SST in SCSOFSv2 has been improved significantly improved by due to all of the updates described mentioned above.

4.2 SLA

For the ~~entirewhole~~ upgrading process, the accuracy of ~~the~~ SLA ~~is~~ also continuously ~~increas~~ed~~ing~~ from version v1 to v2, with ~~the~~ RMSE ~~decreas~~ed~~ing~~ from 21.6 cm ~~infor~~ v1 to 8.5 cm ~~forin~~ v2, ~~i.e., with~~ ~~percentage increase being a~~ 60.6% ~~improvement~~, for the annual mean of ~~the entirewhole~~ model domain averaged in 2013 (or in 2018 for v1.3 and v2) (Table 3). Since there was an ongoing problem with the SLA climatology variable provided by GOV IV-TT during 2013–2015, we could not calculate ~~the~~ anomaly correlation for ~~the~~ SLA in 2013 and had ~~to provide~~ feedbacked ~~on~~ this issue to GOV IV-TT. ~~However, based on~~~~But from~~ the result of ~~the~~ SLA anomaly correlation in 2018, we ~~can find~~ that it ~~increas~~ed~~s~~ from 0.67 ~~forin~~ v1.3 to 0.85 ~~forin~~ v2, showing significant improvement ~~infor~~ the correlation of ~~the~~ pattern of the variability between the model results and ~~the~~ climatology.

~~As can be seen f~~From Fig. 11(a), there ~~was~~ a slight decrease ~~inof~~ RMSE ~~forin~~ v1.1 with respect to v1, which mainly occurs in winter ~~time~~, and rarely in summer ~~time~~. This may ~~be~~ because ~~there was~~ no direct or intrinsic relationship between ~~these~~ model updates from v1 to v1.1 and ~~the~~ SLA in physics, and ~~these~~ updates mainly focused ~~on~~ ~~the~~ horizontal and temporal resolutions of the datasets. However, the improvement of ~~the~~ SLA accuracy ~~of the SLA is obvious~~ in v1.2 with respect to v1.1 ~~was significant~~, with the minimum and maximum of daily-mean RMSE values ~~decreas~~ing~~change~~ from 0.12 cm and 0.31 cm ~~forin~~ v1.1 to 0.11 cm and 0.23 cm ~~forin~~ v1.2, respectively. Their annual mean value ~~decreas~~ed~~s~~ from 20.8 cm ~~forin~~ v1.1 to 16.7 cm ~~infor~~ v1.2, ~~i.e., with percentage increase of a~~ 19.7% ~~improvement~~. This may be ~~the result of the from~~ well-represent~~ed~~ing~~of~~ NEC pattern due to ~~the~~ change ~~in theof~~ model's eastern lateral boundary. With respect to v1.2, ~~the~~ accuracy of ~~the~~ SLA in v1.3 ~~increas~~ed slightly, ~~increas~~es with ~~an~~ annual mean value ~~of~~ 14.8 cm and ~~a~~percentage increase 11.4% ~~improvement~~. ~~This~~ ~~It~~ may be ~~the result of from~~ the mean sea level air pressure correction and ~~the~~ modification of ~~the~~ temperature and salinity baroclinic structures due to ~~the usage of the~~ AAG ~~being employed~~. In addition,

the most significant improvement ~~in thefor~~ SLA ~~was~~ introduced by ~~the~~ MOOAS, with minimum and maximum ~~of~~ daily-mean RMSE values ~~arofe~~ 6.1 cm and 12.1 cm ~~forin~~ v2, respectively. The annual mean RMSE ~~decreas~~ed~~s~~ to 8.5 cm and ~~the~~ percentage increase reached~~s to~~ 34.1% with respect to v1.3 and to 60.6% with respect to v1. ~~This~~ ~~It~~ ~~significant improvement was~~ is undoubtedly ~~that this significant~~

590

improvement is introduced by the result of the along-track SLA being assimilated into the system by the MOOAS.

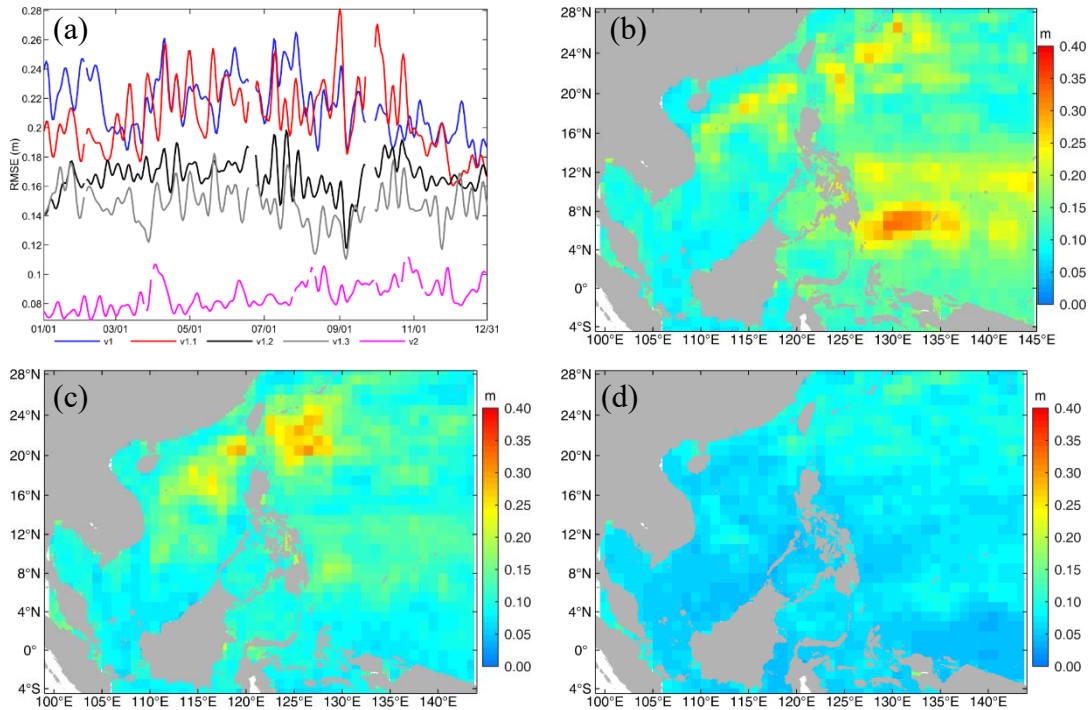


Figure 11: (a) similar to Fig. 10(b) but for the SLA. (b), (c), (d) similar to Fig. 10(c) or (d), but for the SLA of v1, v1.3 (in 2013), and v2, respectively.

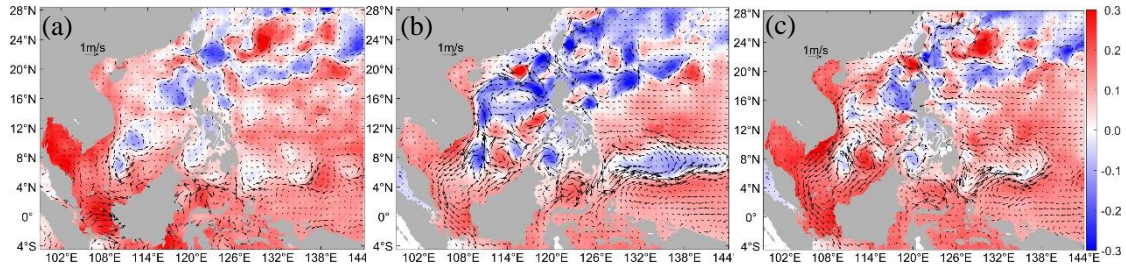
595

For the horizontal distribution of the SLA RMSE, the large values of ~~of >over~~ 20 cm were mainly located in the area of the NEC pathway, the continental shelf of the northeastern SCS, and to the northeast of the Luzon Strait, with a maximum value of 32.7 cm for v1 (Fig. 11b). For v1.3 (Fig. 11c), the large values in the area of the NEC pathway almost disappeared, the maximum RMSE was 30.3 cm and most of the values were less than 20 cm, which can be interpreted as a better representation of the NEC pattern due to amendment of the model's eastern lateral boundary. In comparison with v1.3 or

600

even v1, for v2, the SLA RMSE decreased dramatically for the entire model domain and does not contain areas with obvious large values in v2, and its maximum value was only 18.2 cm, and with most of the values were less than 10 cm. It is well known that abundant mesoscale eddies occur on both sides of the Luzon Strait, in the northeastern SCS, and in the western Pacific Ocean (Fig. 12a). The large SLA RMSEs in Figs. 11b and Fig. 11c indicate that a pure physical ocean model

605 cannot capture these meso-scale processes well without assimilating SLA data ~~assimilated~~ (Fig.12b). However, Fig. 11d shows a significant reduction in the~~with~~ SLA RMSE, indicating that the meso-scale eddies can be represented by SCSOFSv2 due to assimilation of the~~with~~ along-track SLA data, ~~assimilated~~ and the results are in good agreement with the satellite observations ~~well~~ (Fig. 12c).



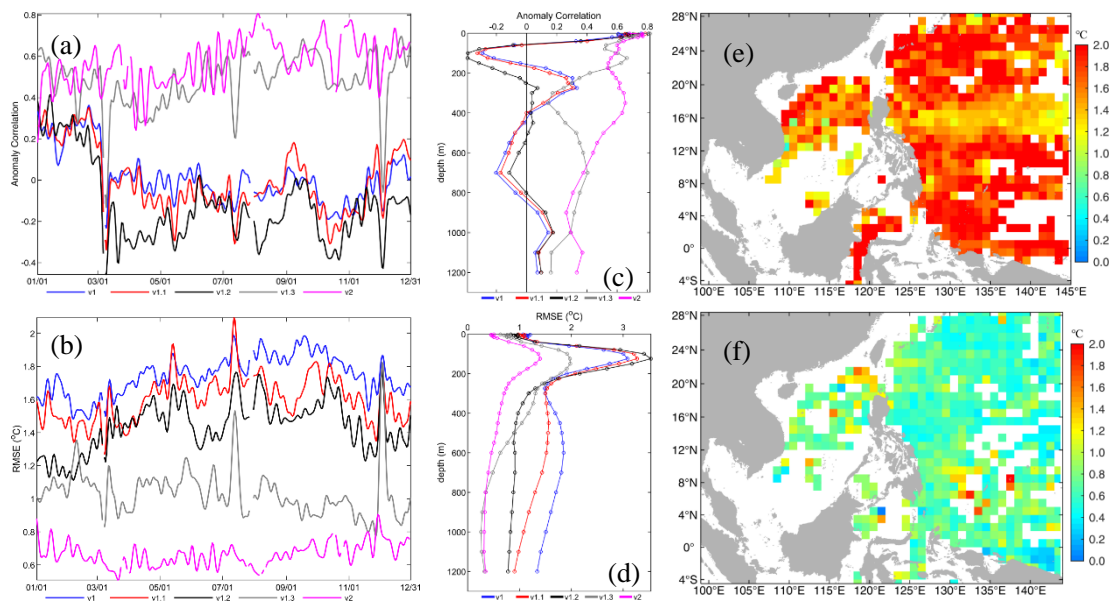
610 **Figure 12: Daily averaged SLA (colour shaded) and surface velocity anomaly (vectors) on January 15, 2018, from AVISO, SCSOFSv1.3, and SCSOFSv2, respectively.**

4.3 Temperature and salinity profiles

615 For the three-dimensional temperature and salinity distribution, by comparing the model results with the climatology temperature and salinity profiles, the results of from first three versions exhibits~~show~~ poor correlations with the observations (Figs. 13a and Fig. 14a) and have large RMSEs (Figs. 13b and Fig. 14b), i.e., 1.44 ~~°C~~–1.75 ~~°C~~ for temperature and 0.13 ~~–~~0.14 for salinity (Table 3), even though~~if~~ they decrease due to the~~with~~ model updates. In particular~~Especially~~, for the vertical distribution, the RMSE can reach to larger than 3°C for temperature and 0.3 for salinity in the thermocline and halocline, respectively, and it remained~~ed~~ larger than 1 °C for temperature in the deep layer and 0.1 for salinity above a depth of 700 m depth (Figs. 13d and Fig. 14d). This may result from the spurious diapycnal mixing caused by the~~due to~~ UCI ~~schemes~~ combination scheme~~employed~~. These updates to~~in~~ v1.1 and v1.2 can only slightly improved the three-dimensional temperature and salinity, and they did ~~can~~not contribute to their intrinsic improvements for, neither ~~for~~ surface forcing nor ~~for~~ the lateral boundary conditions, with the~~an~~ exception of the surface layer with depths of less~~shallower~~ than 100 m.

625 However, once the AAG ~~schemes~~ combination scheme was implemented~~employed~~ in v1.3, the improvements to the three-dimensional temperature and salinity we~~are~~ significant~~obvious~~ with respect to the first three versions (Figs. 13a,b and Fig. 14a,b). The anomaly correlation increased s to 0.38 ~~–~~0.48 for temperature and 0.30 ~~–~~0.44 for salinity, and the RMSE decreased s to 0.96 ~~°C~~–1.03 ~~°C~~ for

630 temperature and 0.10–0.11 for salinity, respectively (Table 3). For the vertical distribution, the anomaly correlation remained at around 0.4 for both temperature and salinity in the entire water column, and it was greater than 0.6 for temperature in the surface layer (Figs. 13c and Fig. 14c). The RMSEs significantly decreased to less than 2 °C for temperature in the thermocline, and 0.25 for salinity in the halocline, and less than 1 °C for temperature and 0.1 for salinity in the deep layer (Figs. 13d and Fig. 14d). For the horizontal distribution of the three-dimensional temperature and salinity RMSEs, the RMSE of the temperature was more likely to being more than ≥ 1.5 °C with maximum and minimum values of being 4.45 °C and 0.49 °C (Fig. 13e), respectively; while the RMSE of salinity was great larger than 0.1, with



640 Figure 13: (a) and (b) similar to Figs. 10(a) and (b) but for the temperature profile, respectively. (c) and (d) vertical distributions of best estimates for each sub-version against observations as a function of depth, v1, v1.1, v1.2, and v1.3 without data assimilation in 2013, and v2 with data assimilation in 2018. (e) and (f) similar to Figs. 10(c) and (d), but for the temperature profile in v1 and v2, respectively.

645 maximum and minimum values of being 0.81 and 0.06 (Fig. 14e), respectively, for in v1. The large values for salinity were mainly located in the SCS and near the equator in the Pacific Ocean. The trend was the same as the with time series of the RMSE. The horizontal distributions of the temperature and salinity RMSEs shows slight decreased slightly from version v1 to v1.2, but they dramatically decreased in v1.3 (Figures not shown). Since it is benefited from the usage of the AAG schemes combination

scheme in v1.3, most of the temperature RMSEs were lower than 1.0 °C, with maximum and minimum values of 1.72 °C and 0.11 °C, respectively; and most of the salinity RMSEs were less than 0.1, with maximum and minimum values of 0.62 and 0.03 in 2013, respectively.

By employing the MOOAS, the accuracies of the three-dimensional temperature and salinity have been improved continuously in v2 compared to v1.3 for all of the metrics in 2018 (Figs. 13 and Fig. 14). The mean anomaly correlation has increased from 0.38 to 0.57 for temperature, and from 0.30 to 0.51 for salinity. The mean RMSEs have decreased from 0.96 °C to 0.67 °C for temperature, and from 0.11 to 0.08 for salinity (Table 3). For the vertical distributions of the anomaly correlation for temperature, it was >0.6 in the surface layer, >0.4 above 600 m, and >0.3 in the deep layer (Fig. 13c). The RMSE of the temperature was less than 1.5 °C for the entire vertical profile, and similar to in other versions, the maximum value was located in the thermocline similar with other versions, but the error decreased dramatically (Fig. 13d). In contrast to temperature, the vertical anomaly correlation of the salinity does not show significantly improve below 200 m in v2 with respect to v1.3 below 200 m, and it was only slightly higher than that of v1.3 in above 200 m. The salinity RMSE was less than 0.25 for the entire vertical profile, with the maximum value located at the surface and decreasing with depth, and decreasing to less than 0.05 below 600 m (Fig. 14d).

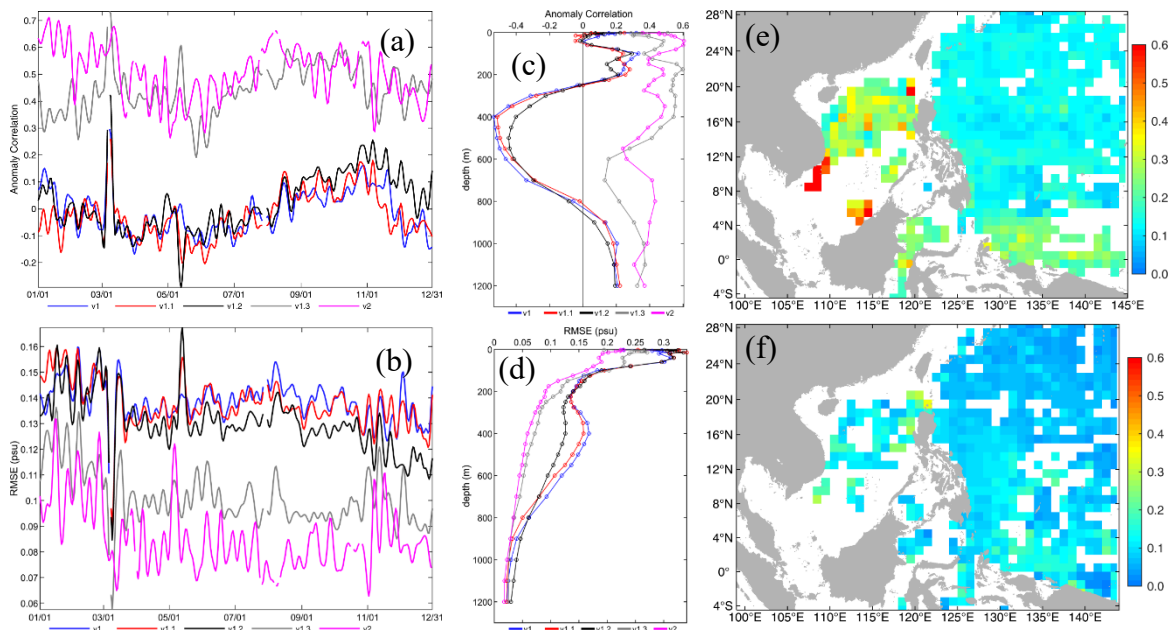


Figure 14: Similar to Fig. 13, but for salinity profile.

For the horizontal RMSE distribution of v2, most of the temperature RMSEs were greater than 0.8 °C with maximum and minimum values of 1.96 °C and 0.03 °C (Fig. 13f), respectively; and most of the salinity RMSEs were greater than 0.1, with maximum and minimum values of 0.35 and 0.01 (Fig. 14f), respectively, in 2018 (Fig. 14f).

5. Conclusions

The results of this study illustrate the major updates applied to SCSOFSv1 in terms of the physical model settings, inputs, and EnOI data assimilation scheme in the last few years following the recommendations of Zhu et al. (2016), such as redistributions of the land-water grid mask, changes in the data sources of the bathymetry, the initial conditions, and the sea surface forcing method; changing the open boundary conditions to higher spatial and temporal resolutions; shifting the eastern lateral boundary westward; and increasing the vertical layers of the model, and so on.

The three most significant updates were highlighted in this paper. Firstly, the sea surface atmospheric forcing method was changed from direct forcing to the BulkFormula to acquire an effective negative feedback mechanism for the air-sea interactions by using the COARE3.0 bulk algorithm. The upgrades lead to more reasonable SST simulations by eliminating abnormal values, significantly decreasing the maximum value of the monthly mean differences between the simulated SST and OSTIA, and decreasing the domain averaged RMSE of the monthly mean SST from 0.99 °C–1.62 °C in SCSOFSv1 to 0.87 °C–1.15 °C in the BulkFormula run. The annual mean value decreased from 1.27 °C to 1.00 °C, indicating that the performance of model's skill has improved by about 21%.

Secondly, the AAG scheme was substituted for the tracers advection term discrete scheme UCI has been substituted with AAG in order to suppress the spurious diapycnal mixing problem. After this substitution, the domain averaged monthly mean temperature in the 1000 m layer decreased from 5.1 °C to 4.5 °C, and that of the salinity decreased from 34.54 to 34.509, in January of the fifth model year, respectively. Even after 20 model years, the domain averaged values of the temperature and salinity

increments were only about 0.2 °C and 0.03, respectively, suggesting that the AAG combination schemes ~~combination~~ can well ~~preserve~~ the characteristics of the water masses in the deep ocean preserve. In addition, the model skill for the SST also ~~can~~ benefited from the AAG combination schemes and ~~the combination with~~ annual mean domain averaged RMSE ~~decreasing~~ from 1.00 °C to 0.77 °C, i.e., ~~showing a~~ 23% ~~improvement in rate for~~ the performance.

Thirdly, the original EnOI method in SCISOFSv1 ~~has been~~ upgraded to the new MOOAS by adding four new functions. The multi-source observation data (SST, SLA, and Argo profiles) ~~were can be~~ simultaneously assimilated, ~~simultaneously~~; The Hanning high-pass filter was applied to the ensemble members from 10 years of free run while calculating the background error covariances to improve the dynamic dependency; The FGAT method with a ~~3~~three-hour time slot was used to calculate the innovations; and the IAU technique with ~~is employed with~~ seven-day time window was used to apply analyses the increment into the model integration in a gradual manner.

Moreover, inter-comparison and accuracy assessment of the among five versions were conducted based on the GOV IV-TT Class 4 metrics for four physical variables, i.e., the SST, SLA, and Argo profiles.

The improvement in the of accuracy of the simulated SST was mainly due attributes to the use of more accurate observed SST data ~~source used for the~~ sea surface heat flux correction, the use of the BulkFormula method for the sea surface atmospheric forcing, and the use of the AAG discrete temperature advection ~~discrete~~ scheme. The improvement of the SLA accuracy of the SLA as mainly due to the benefits from good representations of the NEC pattern ~~obtained caused~~ by ~~modification of the~~ model's eastern lateral boundary, the mean sea level air pressure correction, and the improvement of the three-dimensional temperature and salinity baroclinic structures ~~improvement due to by using the~~ AAG scheme employed. The improvement of the three-dimensional temperature and salinity mainly benefited ds from the use of the AAG non-spurious diapycnal mixing combination schemes ~~combination employed~~.

Finally At last, the remarkable improvements in for all of the above four variables are also benefited from use of the MOOAS application. With respect to v1.3, for the v2 using the MOOAS, the domain averaged annual mean SST RMSE ~~decreaseds~~ from 0.66 °C to 0.52 °C, i.e., a ~~with percentage increase being~~ 21.2% improvement; The SLA RMSE ~~decreaseds~~ from 12.9 cm to 8.5 cm, i.e., a ~~with percentage increase being~~

34.1% ~~improvement.~~ The temperature profile's RMSE decreased from 0.96 °C to 0.67 °C, ~~i.e., a with~~
720 ~~percentage increase being~~ 30.2% ~~improvement.~~ The salinity profile's RMSE decreased from 0.11 to
0.08, ~~i.e., a with percentage increase being~~ 27.3% ~~improvement, in v2 while using MOOAS.~~

Although SCSOFSv2 ~~is greatly~~has improved ~~greatly~~ compared to the previous versions, some biases
still exist, such as the structures of ~~the~~ temperature and salinity ~~profiles in the~~ subsurface, especially ~~in~~
725 the thermocline and halocline. We plan to continue to improve the system in ~~terms of~~ both ~~the~~ physical
model settings and ~~the~~ data assimilation scheme ~~in the~~ next step, ~~including as such as~~ sub-grid
parameterization scheme for ~~the~~ unresolved physical processes, ~~a~~ vertical turbulent mixing scheme to
consider wave mixing, ~~a~~ more accurate input and forcing data source, and assimilation ~~of~~ more or new
types of observations (glider or mooring three-dimensional temperature and salinity profiles, drifting
buoys, *in-situ* velocity ~~data~~ from moorings) into the system.

730 *Code and Data availability.* The latest version of the source code for EnOI and ROMS trunk used to
produce the results in this paper can be accessed via <https://doi.org/10.5281/zenodo.5215783>.
GEBCO_2014 Grid, https://www.bodc.ac.uk/data/open_download/gebco/GEBCO_30_SEC/zip/, last
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735 [3.3.1_mn_download.htm](https://www2.atmos.umd.edu/~ocean/index_files/soda3.3.1_mn_download.htm), last access 3 January 2021; SODA3.3.2, [https://dsrs.atmos.umd.edu/DATA/s](https://dsrs.atmos.umd.edu/DATA/soda3.2/REGRIDED/ocean/)
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last access 3 January 2021; CFSv2, <http://rda.ucar.edu/datasets/ds094.0>, last access 3 January 2021;
NCEP_Reanalysis 2, <https://www.psl.noaa.gov/data/gridded/data.ncep.reanalysis2.html>, last access 3
January 2021; AVHRR, [http://www.ncei.noaa.gov/data/sea-surface-temperature-optimum-interpolation](http://www.ncei.noaa.gov/data/sea-surface-temperature-optimum-interpolation/v2.1/access/avhrr/)
740 [/v2.1/access/avhrr/](http://www.ncei.noaa.gov/data/sea-surface-temperature-optimum-interpolation/v2.1/access/avhrr/), last access 3 January 2021; OSTIA, SST of *in-situ* drifting BUOY, AVISO along-
track SLA, and Argo temperature and salinity profiles, <https://marine.copernicus.eu/>, last access 3
January 2021.

Author Contributions. XZ performed the physical model improvement and free-run simulations,
designed and wrote the paper. XZ and ZZ updated MOOAS and performed the data assimilation
simulations. SR and AL analysed and assessed model results. SR, HW and YZ helped in reading and
745 commenting on the paper. MZ helped in polishing the paper.

Competing interests. The authors declare that they have no conflict of interest.

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