CAPS v1.0: An improved regional coupled modeling system for Arctic sea ice and climate simulation and prediction: a case study for 2018 Chao-Yuan Yang<sup>1</sup>, Jiping Liu<sup>2</sup>, Dake Chen<sup>1</sup> <sup>1</sup>School of Atmospheric Sciences, Sun Yat-sen University, and Southern Marine Science and Engineering Guangdong Laboratory (Zhuhai), Zhuhai, Guangdong, China <sup>2</sup>Department of Atmospheric and Environmental Sciences, University at Albany, State University of New York, Albany, NY, USA Corresponding author: Chao-Yuan Yang (yangchy36@mail.sysu.eu.cn) and Jiping Liu (jliu26@albany.edu) 

#### Abstract

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The improved/updated Coupled Arctic Prediction System (CAPS) is evaluated by a set of Pan-Arctic prediction experiments for the year 2018, which is built on new versions of Weather Research and Forecasting model (WRF), the Regional Ocean Modeling System (ROMS), the Community Ice CodE (CICE), and a data assimilation based on the Local Error Subspace Transform Kalman Filter. A set of Pan-Arctic prediction experiments with We analyze physical process linking improved/changed physical parameterizations in WRF, ROMS, and CICE as well as different configurations are performed for to changes in the year 2018 to assess their impacts on the predictive skill of simulated Arctic sea ice at seasonal timescale. The key improvements of WRF, including cumulus, state. Our results show that the improved convection and boundary layer, and land surface schemes, in WRF result in improved simulation in downward radiative fluxes and near surface air temperature and downward radiation. The major changes of ROMS, including, which influences the predicted ice thickness. The changed tracer advection and vertical mixing schemes, lead in ROMS reduces the bias in sea surface temperature and changes ocean temperature and salinity structure in the surface layer, leading to improved evolution of the predicted total ice extent (particularly correcting the late ice recovery issue in the previous CAPS), and reduced biases in sea surface temperature.). The changes of CICE, that include improved sea ice thermodynamics and assimilation of new sea ice thickness product, in CICE have noticeable influences on the predicted ice thickness and the timing of ice recovery. Results from the prediction experiments suggest that the updated. The updated CAPS can better predict the evolution of total ice

extentArctic sea ice during the melting season compared with its predecessor, though the predictionsprediction still have eertainsome biases at the regional scale. We further show that the updated CAPS can remain skillful beyond the melting season, which may have potential values for stakeholders making decisions for socioeconomical activities in the Arctic.

#### 1. Introduction

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Over the past few decades, the extent of Arctic sea ice has decreased rapidly and entered a thinner/younger regime associated with global climate change (e.g., Kwok, 2018; Serreze and Meier, 2019). The drastiedramatic changes in the properties of Arctic sea ice have captured gained increasing attentions of by a wide range of stakeholders, such as trans-Arctic shipping, natural resource exploration, and activities of coastal communities relying on sea ice (e.g., Newton et al., 2016). This leads to increasing demands on skillful Arctic sea ice prediction, particularly at seasonal timescale (e.g., Jung et al., 2016; Liu et al., 2019; Stroeve et al., 2014). However, Arctic sea ice prediction based on different approaches (e.g., statistical method and dynamical model) submitted to the Sea Ice Outlook, a community effort managed by the Sea Ice Prediction Network (SPIN, https://www.arcus.org/sipn), shows substantial biases in the predicted seasonal minimum of Arctic sea ice extent compared to the observations for most years since 2008 (Liu et al., 2019; Stroeve et al., 2014). Recently, we have developed an atmosphere-ocean-sea ice regional coupled modeling system, for seasonal Arctic sea ice and climate prediction (Yang et al., 2020, hereafter Y20), in which the Los Alamos Sea Ice Model (CICE) is coupled with the Weather Research and Forecasting Model (WRF) and the Regional Ocean Modeling System (ROMS), hereafter called Coupled Arctic Prediction System (CAPS). To improve the accuracy of initial sea ice conditions, CAPS employs an ensemble-based data assimilation system to assimilate satellitebased sea ice observations. Seasonal Pan-Arctic sea ice predictions with improved initial sea ice conditions conducted in Y20 have shown that CAPS has the potential to provide skillful

Arctic sea ice prediction at seasonal timescale.

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We know that the changes of sea ice variables (e.g., ice extent, ice concentration, ice 64 thickness, ice drift) are mainly driven by forcings from the atmosphere and the ocean. 65 Atmospheric cloudiness and related radiation influence surface ice melting (Huang et al., 2019; 66 67 Kapsch et al., 2016; Kay et al., 2008) and the energy stored in the surface mixed layer that determines the seasonal ice melt and growth (e.g., Perovich et al., 2011, 2014). Atmospheric 68 circulation is the primary driver for the transportation of sea ice and partly responsible for the 69 70 variability of Arctic sea ice (e.g., Mallett et al., 2021; Ogi et al., 2010; Zhang et al., 2008). Olonscheck et al. (2019) suggested that atmospheric temperature fluctuations explain a 71 72 majority of Arctic sea ice variability while other drivers (e.g., surface winds, and poleward heat transport) account for about 25% of Arctic sea ice variability. The oceanic heat inputs (as well 73 74 as salt inputs) into the Arctic Ocean include the Atlantic Water (AW; Aagaard, 1989; 75 McLaughlin et al., 2009) through the Barents Sea, and the Pacific Water (PW; Itoh et al., 2013; Woodgate et al., 2005) from the Bering Strait. The oceanic heat inputs from AW and PW are 76 not directly available for sea ice since they are separated from a cold and fresh layer underlying 77 78 sea ice (e.g., Carmack et al., 2015, Fig. 2). Vertical mixing by the internal wave (e.g., Fer, 2014) 79 and double diffusion (e.g., Padman and Dillon, 1987; Turner, 1973) are the principal processes 80 for upward heat transport from the subsurface layer (i.e., AW and PW) to the surface mixed 81 layer in the Arctic Ocean. Sea ice thermodynamics determines how thermal properties of sea 82 ice (e.g., temperature, salinity) change. These changes then influence the thermal structure of underlying ocean through interfacial fluxes (i.e., heat, salt and freshwater fluxes; DuVivier et 83

al., 2021; Kirkman IV and Bitz, 2011) and ice thickness (e.g., Bailey et al., The skills of coupled
climate models (GCMs) in predicting Pan-Arctic sea ice extent have been assessed with suites
of hindcasts, and these studies suggested that GCMs have skill in predicting ice extent 2020).
The CAPS is configured for the Arctic with sufficient flexibility. That means each model
component of CAPS (WRF, ROMS, and CICE) has different physics options for us to choose
and capability to integrate ongoing improvements in physical parameterizations. Recently, the
WRF model has adapted improved convection and boundary layer schemes in the Rapid
Refresh (RAP) model operational at the National Centers for Environmental Prediction (NCEP,
Benjamin et al., 2016). The first question we want to answer in this paper is to what extent
these modifications can improve atmospheric simulations in the Arctic (i.e., radiation,
temperature, humidity, and wind), and then benefit seasonal Arctic sea ice simulation and
prediction. The ROMS model provides several options for tracer advection schemes. These
advection schemes can have different degrees of oscillatory behavior (e.g., Shchepetkin and
McWilliams, 1998). The oscillatory behavior can have impacts on sea ice simulation through
ice-ocean interactions (e.g., Naughten et al., 2017). The second question we want to answer in
this paper is to what extent different advection schemes can change the simulation of upper
ocean thermal structure and then Arctic sea ice prediction. Several recent efforts have
incorporated prognostic salinity into sea ice models. The CICE model has a new mushy-layer
thermodynamics parameterization that includes prognostic salinity and treats sea ice as a two-
phase mushy layer (Turner et al., 2013). Bailey et al. (2020) showed that the mushy-layer
physics has noticeable impacts on Arctic sea ice simulation within the Community Earth

System Model version 2. The third question we want to answer in this paper is whether the
mushy-layer scheme can produce noticeable influence on seasonal Arctic sea ice prediction.
Currently, SIPN focuses on Arctic sea ice predictions during the melting season, particularly
seasonal minimum. It is not clear that how predictive skills of dynamical models participating
in SIPN may change for longer period, i.e., extending into the freezing up period, which also
have significance on socioeconomic aspects. The assessment of the skills of global climate
models (GCMs) in predicting Pan-Arctic sea ice extent with suites of hindcasts suggested that
GCMs may have skill at lead times of 1-6 months (e.g., Blanchard-Wrigglesworth et al., 2015;
Chevallier et al., 2013; Guemas et al., 2016; Merryfield et al., 2013; Msadek et al., 2014;
Peterson et al., 2015; Sigmond et al., 2013; Wang et al., 2013; Zampieri et al., 2018). Moreover,
some studies using a "perfect model" approach, which examines treats one member of an
ensemble as the truth (i.e., assuming the model is prefect without bias) and analyzes the skill
of a model other members in predicting itself, the response of the "truth" member (e.g., Meehl
et al., 2007), suggested that Arctic sea ice cover can be potentially predictable up to two years
in advance (e.g., Blanchard-Wrigglesworth et al., 2011; Blanchard-Wrigglesworth and Bushuk,
2018; Day et al., 2016; Germe et al., 2014; Tietsche et al., 2014). The gap between actual
predictive skill with dynamical models and theoretical predictability suggested by "perfect
model" studies may be related to inaccurate initial conditions and/or inadequate physical
parameterizations in dynamical models (Stroeve et al., 20152014). The last question we want
to answer in this paper is whether CAPS has predictive skill for longer periods (up to 7 months).
Recently, we have developed an atmosphere-ocean-sea ice regional coupled modeling

system, hereafter called Coupled Arctic Prediction System (CAPS), for seasonal Arctic sea ice
and climate prediction (Yang et al., 2020, hereafter Y20). To improve the accuracy of initial
sea ice conditions, CAPS employs an ensemble-based data assimilation system to assimilate
satellite-based sea ice observations. Seasonal Pan-Arctic sea ice predictions with improved
initial sea ice conditions conducted in Y20 have shown that CAPS has potential to provide
skillful Arctic sea ice predictions at seasonal timescale.
With recent improvements in the model components of CAPS, this paper gives a
description of the updated CAPS, and presents the assessment of seasonal Arctic sea ice
predictions associated with improved/changed physical parameterizations. This paper is
structured as follows. Section 2 provides ana brief overview of the CAPS, including major
changes/improvements in the model components compared to its predecessor described in Y20,
as well as the configurations and data assimilation system and the assimilation procedures.
Section 3 describes the designs of the prediction experiments, andfor the year of 2018 based
on major improvements/ changes in the model components compared to its predecessor
described in Y20, examines the performance of the updated CAPS associated with major, and
offers physical links between Arctic sea ice changes/improvements in the model components.
Some discussions and improved/changed physical parameterizations. Section 4 discusses the
predictive skill of CAPS at longer timescale. Discussions and concluding remarks and are given

# 2. Coupled Arctic Prediction System (CAPS)

in section 4 and 5.

As described in Y20, to enhance our ability to predict seasonal Arctic sea ice as well as

climate, we have developed CAPS has been developed by coupling the Community Ice CodE (CICE) with the Weather Research and Forecasting Model (WRF) and the Regional Ocean Modeling System (ROMS) based on the framework of the Coupled Ocean-Atmosphere-Wave-Sediment Transport (COAWST) modeling framework (Warner et al., 2010). The general description of each model component in CAPS is referred to Y20. The advantage of CAPS is its model components have different a variety of physics options for us to choose, and capability to integrate follow-up improvements of physical parameterizations. With recent achievements of community efforts on improving the WRF, ROMS, and CICE models, in this study, we update CAPS based on newly-released WRF, ROMS, and CICE models for further development of our Arctic sea ice. During this update, we focus on the Rapid Refresh (RAP) physics in the WRF model, the oceanic tracer advection scheme in the ROMS model, sea ice thermodynamics in the CICE model (see details in section 3), and investigate physical process linking them to Arctic sea ice simulation and prediction system. Table 1 provides the versions for these model components between this paper and Y20... The same physical parameterizations described in Y20 are used here for the control simulation, but some of them are improved as the WRF, ROMS, and CICE models released their new versions (see Table 2). (see Table 1). Major changes in physics parameterization and physical parameterizations as well as the model infrastructure in the WRF, ROMS, and CICE models are described below. 2.1. Model components and updates WRF: The WRF model (Skamarock et al., 2005) is a non-hydrostatic and quasi-

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compressible model, which uses hybrid vertical coordinate with the top of the model at 50 mb

and the Arakawa C-grid in horizontal. The Rapid Refresh (RAP) system, a high-frequency,
continental scale weather prediction/assimilation modeling system operational at the National
Centers for Environmental Prediction (NCEP), has made some improvements in the WRF
model physics (Benjamin et al., 2016). The official release of WRF model since version 3.9
has adapted these modified physics parameterizations in the RAP system, including the Grell-
Freitas convection scheme (GF) and the Mellor-Yamada-Nakanishi-Niino planetary boundary
layer (PBL) scheme (MYNN) as the replacement of original schemes in the WRF model. For
the GF scheme, the major improvements compared to the original scheme (Grell and Freitas,
2014) include: 1) a beta probability density function used as the normalized mass flux profile
for representing height-dependent entrainment/detrainment rates within statistical-averaged
deep convective plumes, and 2) the European Centre for Medium-Range Weather Forecasts
(ECMWF) approach used for momentum transport due to convection (Biswas et al. in
section 2020; Freitas et al. 2018). For the MYNN scheme, compared to the original scheme
(Nakanishi and Nino, 2009), the RAP system improved the mixing-length formulation and
removed numerical deficiencies to better represent subgrid-scale cloudiness (Benjamin et al.
2016, see Append. B).
For the Noah land surface model (Chen and Dudhia, 2001), some issues including
discontinuous behavior for soil ice melting and negative moisture fluxes over glacial and sea
ice, as well as minor issues associated with snow melting have been fixed since the release of
WRF version 3.9.
ROMS: The ROMS model is a terrain-following and free-surface model, which solves

three-dimensional Reynolds-averaged Navier-Stokes equations with the hydrostatic and Boussinesq approximation (Shchepetkin and McWilliams, 2005; Haidvogel et al., 2008). In the vertical, the equations are discretized over bottom topography with stretching terrain-following coordinates (Song and Haidvodel, 1994). In the horizontal, the ROMS model uses boundaryfitted, orthogonal curvilinear coordinates on a staggered Arakawa C-grid. In the updated CAPS, the major change in the latest ROMS model is associated with surface heat/freshwater fluxes and their coupling to other model components. This change prevents the potentially erroneous results when the ROMS timestep is smaller than the coupling frequency with other model components. Other changes in the ROMS model of the updated CAPS can be found in the ROMS distribution website (https://www.myroms.org/projects/src/report/4 Ticket #654 to #824). CICE: The CICE model is designed to be a sea ice model component for global coupled climate models. Its dynamic core simulates the movement of sea ice based on forces from the atmosphere, the ocean, and Earth's rotation and the material strength of the ice. The new feature of CICE version 6.0.0 contains an independent software package, Icepack, to provide the column physics code for all thermodynamic parameterizations in a single grid-cell. These parameterizations include the MUSHY-layer ice thermodynamics (Turner et al., 2013) that resolves prognostic vertical temperature and salinity profiles. The new version of CICE also includes improvements in sea ice rheology and a new landfast-ice parameterization (Lemieux et al., 2016). More details can be found in the CICE Consortium GitHub page

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(https://github.com/CICE-Consortium).

#### 2.2. Data Assimilation and evaluation data

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As described in Y20, the Parallel Data Assimilation Framework (PDAF, Nerger and Hiller, 2013) was implemented in CAPS for assimilating sea ice observations, which provides a variety of optimized ensemble-based Kalman filters including the Local Ensemble Transform Kalman Filter (LETKF; Hunt et al., 2007), the Localized Singular Evolutive Interpolated Kalman (LSEIK; Nerger et al., 2006), and the. The Local Error Subspace Transform Kalman Filter (LESTKF; Nerger et al., 2012). Following Y20, the LESTKF) is used to assimilate satellite-observed sea ice parameters. The LESTKF projects the ensemble onto the error subspace and then directly computes the ensemble transformation in the error subspace. This results in better assimilation performance compared to the LSEIK filter and higher computational efficiency compared to the LETKFother filters as discussed in Nerger et al. (2012).The initial ensembles are generated by applying the second-order exact sampling (Pham, 2001) to simulated sea ice state vectors (ice concentration and thickness) from an one-month free run, and then assimilating sea ice observations that include, including: 1) the near realtime daily Arctic sea ice concentration processed by the National Aeronautics and Space Administration (NASA) Team algorithm (Maslanik and Stroeve, 1999) obtained from the National Snow and Ice Data Center (NSIDC; \_(https://nsidc.org/data/NSIDC-0081/), and 2) a combined monthly sea ice thickness derived from the CryoSat-2 (Laxon et al., 2013; obtained from http://data.seaiceportal.de), and daily sea ice thickness derived from the Soil Moisture and Ocean Salinity (SMOS; Kaleschke et al., 2012; Tian-Kunze et al., 2014; obtained from https://icdc.cen.uni-hamburg.de/en/l3c-smos-sit.html). To address the issue that sea ice thickness derived from CyroSat-2 and SMOS are unavailable during the melting season, the melting season ice thickness is estimated based on the seasonal cycle of the Pan-Arctic Ice Ocean Modeling and Assimilation System (PIOMAS) daily sea ice thickness (Zhang and Rothrock, 2003) as described in Y20.). In Different from Y20, in this study, compared with Y20, we change the localization radius from 2 to 6 grids during the assimilation procedures. The sea ice component in the updated <u>CAPS experienced</u> to reduce some instability atduring initial <u>Arctic sea ice</u> simulations associated with 2 localization radii. As shown in Supplementary Figure S1, the ice thickness with 2 localization radii but not with 6 localization radii. Figure 1 shows that initial sea ice thickness after the data assimilation with (a) 2 localization radii and 1.5 m uncertainty for assimilating ice thickness and (b) 6 localization radii and 0.75 m uncertainty. The initial ice thickness for both configurations has similar spatial distribution. However, the ice thickness with 2 localization radii and 1.5 m uncertainty shows (used in Y20) shows some discontinuous features (Fig. 1aS1a), which resultstends to result in numerical instability during the initial model integration. Such discontinuous feature is features are obviously corrected with 6 localization radii and 0.75 m uncertainty (Fig. 4bS1b). Following Y20, here we test the 2018 prediction experiment with 2 and 6 localization radii but the same uncertainty for ice thickness (0.75m) for the data assimilation (Y20 and Y20 MOD, see Table 3). The Y20 and Y20 MOD experiments show, which shows very similar temporal evolutions evolution of the total Arctic

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sea ice extent for the July experiment relative to that of Y20, although <del>Y20 MOD</del>it (red solid

252 line) predicts slightly less ice extent than that of Y20 (blue line) for the July experiment 253 ((Supplementary Figure 2S2). In this study, thethis configuration of Y20 MOD is designated 254 as the reference for the following assessment of the updated CAPS- (hereafter Y20 MOD). 255 For the evaluation of Arctic sea ice prediction, Sea Ice Index (Fetterer et al., 2017; 256 obtained from https://nsidc.org/data/G02135) is used as the observed total sea ice extent, and 257 the NSIDC sea ice concentrations (SIC) derived from Special Sensor Microwave Imager/Sounder (SSMIS) with the NASA Team algorithm (Cavalieri et al., 1996; obtained from 258 259 https://nsidc.org/data/nsidc-0051) is employedalso used. For the assessment of the simulated 260 atmospheric and oceanic variables, the ECMWF reanalysis version 5 (ERA5; Hersbach et al., 2020; obtained from https://cds.climate.copernicus.eu) and National Oceanic and Atmospheric 261 Administration (NOAA) Optimum Interpolation (OI) Sea Surface Temperature (SST) 262 (Reynolds 2007; 263 al., obtained from et https://psl.noaa.gov/data/gridded/data.noaa.oisst.v2.highres.html) utilized. For the 264 265 comparison of spatial distribution, SIC, ERA5, and OISST are interpolated to the model grid. 266 **3. Model** Evaluation of updated CAPS 267 3.1. Experiment designs and methodology 268 Following Y20, the The model domain includes 319 (449) x- (y-) grid points with a ~24 km grid spacing for all model components (see Figure 2 in Y20). The WRF model uses 50 269 270 vertical levels, the ROMS model uses 40 vertical levels, and the CICE model uses 7 ice layers,

1 snow layer, and 5 categories of sea ice thickness. The coupling frequency across all model

components is 30 minutes. Initial and boundary conditions for the WRF and ROMS models are

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generated from the Climate Forecast System version 2 (CFSv2, Saha et al., 2014) operational forecast archived at NCEP (http://nomads.ncep.noaa.gov/pub/data/nccf/com/cfs/prod/). Sea ice initial conditions are generated from the data assimilation described in section 2.2. Ensemble predictions with 8 members are conducted. A set of numerical experiments for the Pan-Arctic seasonal sea ice prediction with different configurationsphysics, starting from July 1st to October 1st for the year of 2018, has been conducted. Table 32 provides the details of these experiments that allow us to examine impacts of physical process linking improved/changed physical parameterizations in the updated CAPS onto Arctic sea ice simulation and prediction at seasonal timescale.

#### 3.2.3.1. In this study, sea ice extent Impacts of the RAP physics in the WRF model

To examine the performance the updated CAPS compared to its predecessor in Y20, the Y21\_CTRL experiment uses some updated physics configurations in the WRF model as listed in Table 2. The temporal evolution of the ensemble mean of the predicted Arctic sea ice extent for the Y21\_CTRL and Y20\_MOD experiments along with the NSIDC observations are shown in Figure 3. The ice extent is calculated as the sum of area of all grid cells with ice concentration greater than 15%. Besides the total Arctic sea ice extent, we also calculate the ice extent for the following subregions: 1) Beaufort and Chukchi Seas (120W120°W-180, 60N-80N60°N-80°N), 2) East Siberian and Laptev Seas (90E90°E-180, 60N-80N),60°N-80°N), and 3) Barents, Kara, and Greenland Seas (30W-90E, 60N-80N), 4) Canadian Archipelago and Baffin Bay (30W-120W, 60N-80N),30°W-90°E, 60°N-80°N). To further assess the predictive skill of our Arctic sea ice predictions, here we also show the climatology prediction (CLIM, the period of 1998-

2017) and the damped anomaly persistence prediction (DAMP). Following Van den Dool (2006), the DAMP is generated from the initial sea ice extent anomaly (relative to the 1998-2017 climatology) scaled by the autocorrelation and the ratio of standard deviation between different lead times and initial times (see the DAMP equation in Y20).

In order to understand physical contributors that drive the evolving Arctic sea ice state, the mass budget of Arctic sea ice for all experiments is analyzed in this study as defined in Notz et al. (2016, Append. E), including 1) sea ice growth in supercooled open water (frazil ice formation), 2) basal growth, 3) snow-to-ice conversion, 4) top melt, 5) basal melt, 6) lateral melt, and 7) dynamics process.

### 3.2. Impacts of the RAP physics in the WRF model

To examine the performance of the upgrades of physical parameterization in component models in CAPS one step at a time compared to its predecessor in Y20, we define the Y21 CTRL experiment that uses the RAP physics in the WRF model (see Table 2 for differences between Y21 CTRL and Y20 MOD). Recently, the Rapid Refresh (RAP) model, a high-frequency weather prediction/assimilation modeling system operational at the National Centers for Environmental Prediction (NCEP), has made some improvements in the WRF model physics (Benjamin et al., 2016), including improved Grell-Freitas convection scheme (GF) and Mellor-Yamada-Nakanishi-Niino planetary boundary layer scheme (MYNN). For the GF scheme, the major improvements relative to the original scheme (Grell and Freitas, 2014) include: 1) a beta probability density function used as the normalized mass flux profile for representing height-dependent entrainment/detrainment rates within statistical-averaged deep

convective plumes, which is given as:

$$Z_{u,d}(r_k) = cr_k^{\alpha} - (1 - r_k)^{\beta} - 1$$

where  $Z_{u,d}$  is the mass flux profiles for updrafts and downdrafts, c is a normalization constant,  $r_k$  is the location of the mass flux maximum,  $\alpha$  and  $\beta$  determine the skewness of the beta probability density function, and 2) the ECMWF approach used for momentum transport due to convection (Biswas et al. 2020; Freitas et al. 2018; 2021). For the MYNN scheme, the RAP model improves the mixing-length formulation, which is designed as:

$$\frac{1}{l_m} = \frac{1}{l_s} + \frac{1}{l_t} + \frac{1}{l_b}$$

where  $l_m$  is the mixing length,  $l_s$  is the surface length,  $l_t$  is the turbulent length, and  $l_b$  is the buoyancy length. Compared to the original scheme, the RAP model changed coefficients in the formulation of  $l_s$ ,  $l_t$ , and  $l_b$  for reducing the near-surface turbulent mixing, and the diffusivity of the scheme. The RAP model also removes numerical deficiencies to better represent subgrid-scale cloudiness (Benjamin et al. 2016, see Append. B) compared to the original scheme (Nakanishi and Nino, 2009). In addition, some minor issues in the Noah land surface model (Chen and Dudhia, 2001) have been fixed, including discontinuous behavior for soil ice melting, negative moisture fluxes over glacial, and associated with snow melting.

Apparently, the above RAP physics can have influence on the behavior of simulated atmospheric thermodynamics (i.e., radiation, temperature). Figure 1 and 2 show the spatial distribution of the ERA5 surface downward solar and thermal radiation (SWDN and LWDN), the prediction errors (ensemble mean minuses ERA5) of Y20 MOD, and the difference between Y21 CTRL and Y20 MOD. For July, Y20 MOD (Fig. 1d) results in less SWDN over

most of ocean basins as well as Alaska and northeast US, western Siberia, and eastern Europe,
but more SWDN over southern and eastern Siberia compared with ERA5. For August and
September (Fig. 1e-f), the spatial distribution is generally similar to that of July, except that
eastern Siberia (less SWDN) and northern Canada (more SWDN) in August. It appears that the
magnitude of the prediction errors tends to decrease over the areas with large prediction errors
as the prediction time increases (i.e., July vs. September). Compared with Y20_MOD, the RAP
physics in Y21_CTRL result in large areas with smaller prediction errors in July (e.g., the
positive difference between Y21_CTRL and Y20_MOD reduces the negative prediction errors
in Y20_MOD), except the north Pacific (especially the Sea of Okhotsk) and north Canada (Fig.
1g). For August and September (Fig. 1h, i), encouragingly, there are more areas with smaller
prediction errors.
In contrast to SWDN, the prediction errors of LWDN in Y20_MOD has much smaller
magnitude (up to 100 W/m² in SWDN vs. 50 W/m² in LWDN) for the entire prediction period
(Fig. 2d-f). For July, Y20 MOD (Fig. 2d) simulates less LDWN over most of the model domain
compared with ERA5, except the Atlantic sector and north Greenland. For August, the areas
with negative prediction errors expand and the magnitude of prediction errors increases
(particularly in southeastern Siberia and northeast US) compared to that of July (Fig. 2e). For
September (Fig. 2f), the spatial distribution of LWDN is mostly similar to that of July, except
that north Canada and Canadian Archipelago show positive prediction errors. The Y21_CTRL
experiment with the RAP physics tends to reduce the prediction errors in Y20_MOD, especially
over agetern Sibaria and the Atlantia scoter in July to Sontamber (Fig. 2g. i)

Figure 3 shows the spatial distribution of the ERA5 2m air temperature, the prediction
errors of Y20_MOD, and the difference between Y21_CTRL and Y20_MOD. For Y20_MOD,
the predicted air temperature in July has small cold prediction errors over all ocean basins,
small-to-moderate cold prediction errors (~3-5 degrees) over Canada and Siberia, and
moderate-to-large cold prediction errors (~6-9 degrees) over eastern Europe (Fig. 3d).
Compared to the Y20_MOD experiment, the Y21_CTRL experiment has ~0.5 million km²
more ice extent at the initial, but the ice in Y21_CTRL meltsIn August (Fig. 3e), the cold
prediction errors over most of the model domain are increased, in particular, very large cold
prediction error (over 10 degrees) is located over east Siberia. In September, these cold
prediction errors are decreased relatively, and some warm prediction errors are found in north
of Greenland (Fig. 3f). With the adaptation of the RAP physics in the WRF model, Y21_CTRL,
in general, produces a warmer state in most of the model domain compared to that of
Y20_MOD during the entire prediction period. For July (Fig. 3g), the predicted air temperature
is slightly warmer over the Arctic Ocean, the Pacific, and Atlantic sectors, moderately warmer
(~1-2 degrees) over central and eastern Siberia and Canadian Archipelago, but the slightly
colder over northern Canada than that of Y20_MOD. For August and September (Fig. 3h), most
of the model domain is warmer in Y21_CTRL than that of Y20_MOD, in particular excessive
cold prediction errors shown in Y20_MOD over Siberia are reduced notably (~2.5-4 degrees).
We notice that the RAP physics does not have significant impacts on atmospheric circulation,
given that Y21_CTRL and Y20_MOD have very similar wind pattern (not shown).

ice extent along with the NSIDC observations. In terms of the total ice extent, compared to the
Y20_MOD experiment (blue line), the Y21_CTRL experiment (yellow line) produces ~0.5
million km² more ice extent at the initial. Note that the difference in the initial ice extent is
related to that sea ice fields in Y20_MOD and Y21_CTRL (as well as other experiments listed
in Table 2) are initialized based on one-month free runs (section 2), which use different physical
configurations listed in Table 2. These one-month free runs do not have the same evolution in
sea ice fields and result in different initial ice fields after data assimilation. The ice extent in
Y21_CTRL decreases faster than Y20_MOD during the first 2-week integration. After that,
they track each other closely, and predict nearly the same minimum ice extent (~4.3 million
km²). Like Y20_MOD, Y21_ <u>CTRL</u> still has a delayed ice recovery in late September <u>compared</u>
to the observation. Compared with the CLIM/DAMP predictions (black dashed and dotted
lines), both Y20_MOD and Y21_CTRL have smaller biasesprediction errors in August, but
comparable prediction errors after early August. At the September.
The difference in sea ice extent becomes larger at regional seale, scales, in the East
Siberian-Laptev Seas, Y20_CTRL shows faster ice decline after mid-July than that of
Y21_MOD, whereas in the Beaufort-Chukchi Seas, Y21_CTRL predicts slower ice retreat after
late July than that of Y20_MOD, whereas _ (Fig. 4a, 4b). They are consistent with that
Y21_CTRL predicts warmer (relatively colder) temperature than that of Y20_MOD in the East
Siberian-Laptev ( <u>Beaufort-Chukchi</u> ) Seas <del>, Y20_MOD shows slower ice decline after mid-July</del>
than that of Y21_CTRL (Fig. 3a, 3b) Both Y20_MOD and Y21_CTRL agree well with the
observations in the Barents-Kara-Greenland Seas (Fig. <u>4c</u> ). Compared with the observations,

Y20 MOD performs relatively better in regional ice extents than that of Y21 CTRL. Figure 5
shows the spatial distribution of the NSIDC sea ice concentration and the difference between
the predicted ice concentration and the observations for all grid cells that the predictions and
the observations both have at least 15% ice concentration. The vertical and horizontal lining
areas represent difference of the ice edge location. 3c). In the Baffin Bay-Canadian Archipelago,
both Y20_MOD and Y21_CTRL have similar temporal evolution but show systematic
underestimation of the observed areal extent (~0.3 million km², Fig. Like the regional ice extent
shown in Figure 4, Y21_CTRL predicts lower (higher) ice concentration along the East
Siberian-Laptev (Beaufort-Chukchi) Seas (Fig. 5e <sub>1</sub> -e <sub>3</sub> ). Y21_CTRL also predicts less ice in the
central Arctic Ocean in August and September, which is consistent with warmer temperature
in Y21_CTRL relative to Y20_MOD.3d). This underestimation is partly due to the difference
in land/sea mask (particularly in the Canadian Archipelago) between our model grid and the
NSIDC grid (not shown).
Figure 46 shows the spatial distribution evolution of the NSIDC sea ice concentration and
the difference between the predicted sea ice concentration and the observations for all grid cells
that the predictions and the observations both have at least 15% ice concentration for the mass
budget terms of Y20_MOD and Y21_CTRL-experiments, averaged with cell-area weighting
over the entire model domain. During the entire prediction period, most of the ice loss. The
vertical and horizontal lining areas represent difference of the ice edge location. The
distribution of the predicted ice concentration anomalies resembles in both Y20_MOD and
Y21_CTRL experiments, exceptare caused by basal melting. The surface melting has relatively

small contribution in the total ice loss and mainly occurs in July. However, compared with
Y20_MOD (Fig. 6a), Y21_CTRL predicts relatively higher ice concentration in (Fig. 6b) shows
much of the Beaufort, Chukchi, and East Siberian Seas for the entire period (Fig. 4d-i).
larger magnitude for basal and surface melt. In a fully coupled predictive model, the
changes of sea ice isare determined by the fluxes from the atmosphere above and the ocean
below. The major difference between Y20_MOD and Y21_CTRL is the RAP physics
improvements in the WRF model. The RAP physics improvements can have profound
influence on the behavior of simulated atmospheric variables (i.e., radiation, temperature,
humidity, precipitation, Associated with the increased downward radiation of the above RAP
physics, Y21_CTRL absorbs more shortwave radiation (SWABS, Fig. 7a) and allows more
penetrating solar radiation into the upper ocean below sea ice (SWTHRU, Fig. 7b) than that of
Y20_MOD, especially in July. This explains why Y21_CTRL has larger magnitude of surface
and basal melting terms. Although Y21_CTRL show larger magnitude in surface and basal
melting than that of Y20_MOD, the ice extent in Y21_CTRL and Y20_MOD shown in Figure
4 show similar evolution. The effect of larger surface and wind). Figure 5 shows the spatial
distribution of the ERA5 2m air temperature (T2), the predicted anomalies (ensemble mean
minuses ERA5) of Y20_MOD, and the difference between Y21_CTRL and Y20_MOD. For
Y20_MOD, the predicted air temperature in July has small cold (warm) biases over all ocean
basins (northern Greenland and eastern coastal Siberia), small-to-moderate cold biases (~3-5
degrees) over Canada and Siberia, and moderate-to-large cold biases (~6-9 degrees) over
eastern Europe (Fig. 5d). In August (Fig. 5e), the cold biases over most of the model domain 22

are increased. In particular, very large cold bias (over 10 degrees) are located over east Siberia.
In September, these cold biases are decreased, and warm biases are found in the north of
Greenland and Canada (Fig. 5f). With the adaptation of the RAP physics in the updated WRF
model, Y21_CTRL, in general, produces a warmer statebasal melting in most of the model
domain compared to that of Y20_MOD during the entire prediction period. For July (Fig. 5g),
the predicted air temperature is slightly warmer (< 1 degrees) over the Arctic Ocean, the Pacific,
and Atlantic sectors, moderately warmer (~1-2 degrees) over the Siberia coast and Canadian
Archipelago, but the slightly colder (<1 degrees) over northeastern Europe and northern
Canada than that of Y20_MOD. For August (Fig. 5h), the Arctic Ocean and Atlantic sector (the
Pacific sector and northern Canada) are relatively warmer (colder) than that of Y20_MOD.
Excessive cold biases shown in Y20_MOD over Siberia are reduced notably (~2.5-4 degrees)
in Y21_CTRL.Y21_CTRL is largely reflected in the ice thickness change. As discussed
aboveshown in Figure S3, Y21_CTRL has fasterthinner ice meltingthickness than that of
Y20_MOD, in the East Siberian-Laptev Seas, which can be partly attributed to the changes in
the predicted air temperature. in July and in the much of central Arctic Ocean in August and
September.
Figure 6 and Figure 7 shows the spatial distribution of the ERA5 downward solar and
thermal radiation at the surface (SWDN and LWDN), the predicted anomalies (ensemble mean
minuses ERA5) of Y20_MOD, and the difference between Y20_MOD and Y21_CTRL.
3.3. Impacts of the tracer advection in ROMS model
CurrentlyFor July, Y20_MOD (Fig. 6d) results in less SWDN over most of ocean basins,

southern Canada, western Siberia, and eastern Europe while more SWDN over southern and
eastern Siberia, Canadian Archipelago, and northern Canada compared with ERA5. For August
and September (Fig. 6e-f), the spatial distribution, in general, is similar to that of July, except
that eastern Siberia, Canadian Archipelago and northern Canada have opposite sign. It also
shows that the magnitude of biases decreases as the lead time decreases. With the RAP physics
in the Y21_CTRL experiment, large areas have smaller biases compared with Y20_MOD in
July (i.e., the positive difference between Y21_CTRL and Y20_MOD corresponds to the
negative biases in Y20_MOD), except the north Pacific (especially the Sea of Okhotsk),
southern Canada, and the central coastal Siberia (Fig. 6g). For August (Fig. 6h), there are more
areas with smaller biases, but the north Pacific and southern Canada still have larger biases. In
contrast to SWDN, the biases of LWDN shown in Y20_MOD has smaller magnitude (up to
100 W/m2 in SWDN vs. 50 W/m <sup>2</sup> in LWDN) for the entire prediction period (Fig. 7d-f). For
July, Y20_MOD (Fig. 7d) shows less LDWN over most of the model domain compared with
ERA5, except the Atlantic sector and north of Greenland. For August, areas with negative
biases expand and the magnitude of biases increases (particularly in eastern and southern
Siberia) compared with that of July (Fig. 7e). For September (Fig. 7f), the spatial distribution
of LWDN is mostly similar to that of July, except that northern Canada and Canadian
Archipelago show positive biases. The Y21_CTRL experiment with the RAP physics tends to
reduce the negative biases shown in Y20_MOD, especially the negative biases over Siberia in
August and September (Fig. 7g-i).

483 warmer SST along the ice edge in July, and the warm difference along the ice edge becomes

484 larger (particularly near the east Siberian coast) in August and September. The other areas in

Y21 CTRL are mostly with less than 0.2 degrees difference relative to Y20 MOD (Fig. 10g-

486 <del>i).</del>

#### 3.3. ROMS configuration

As described in section 2, the ROMS model that uses a generalized topography-following

coordinate, but currently has two vertical coordinate transformationstransformation options:

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$$z(x, y, \sigma, t) = S(x, y, \sigma) + \zeta(x, y, t) \left[ 1 + \frac{S(x, y, \sigma)}{h(x, y)} \right]$$
(1) 
$$S(x, y, \sigma) = h_c \sigma + [h(x, y) - h_c] C(\sigma)$$

490 or

$$z(x, y, \sigma, t) = \zeta(x, y, t) + [\zeta(x, y, t) + h(x, y)]S(x, y, \sigma)$$

$$S(x, y, \sigma) = \frac{h_c \sigma + h(x, y)C(\sigma)}{h_c + h(x, y)}$$
(2)

where  $S(x, y, \sigma)$  is a nonlinear vertical transformation function,  $\zeta(x, y, t)$  is the free-surface, h(x, y) is the unperturbed water column thickness,  $C(\sigma)$  is the non-dimensional, monotonic, vertical stretching function, and  $h_c$  controls the behavior of the vertical stretching. In Y20, we used the transformation (1) and the vertical stretching function introduced by Song and Haidvogel (1994) as the setup for seasonal Arctic sea ice prediction. However, the vertical transformation (1) has an inherent limitation for the value of  $h_c$  (expected to be the thermocline depth), which must be less than or equal to the minimum value in h(x, y). As thea result,  $h_c$  was chosen as 10 meters due to the limitation of the minimum value in h(x, y) in Y20. This limitation is removed with the vertical transformation (2) and  $h_c$  can be any positive value. Currently, the vertical transformation (2) and the vertical stretching function

introduced by Shchepetkin (2010), and  $h_c$  can be any positive value., the function in a research version of ROMS developed at University of California, Los Angeles, https://www.myroms.org/wiki/Vertical S-coordinate) are employed. The Here the Y21 VT experiment is designed conducted to examine the impacts impact of the vertical transformation in the ROMS model on seasonal Arctic sea ice simulation and prediction by using, which uses the vertical transformation  $(2)_{52}$  the Shchepetkin stretching function, and 300 meters for  $h_c$ . As shown in Supplementary Figure S4-S5, compared to Y21 CTRL, Y21 VT is less sensitive to the bathymetry and its layers are more evenly-distributed in the upper 300 meters. With the changes of vertical layers of the upper ocean, the Y21 VT experiment has minor SST changes relative to Y21 CTRL. The simulated temporal evolution of total ice extent of Y21 VT (Fig. 4, red line) resembles to that of Y21 CTRL (Fig. 4, yellow line), although some differences are seen at the regional scale in the areas with shallow water (e.g., East Siberian, Laptev, Barents, and Kara Seas). The configuration of Y21 VT is used in the following experiments. In pervious sensitivity experiments to determine the choice of ROMS physical parametrizations listed in Table 2, we noticed It has been recognized that the tracer advection and the vertical mixing schemes have important effects on ocean and sea ice simulation. Thus here (e.g., Liang and Losch, 2018; Naughten et al., 2017). Here the Y21 RP experiment is designated to further explore the influence of these different advection schemes in the updated CAPS, in which ROMS model. Specifically, the tracer advection scheme is changed from the Multidimensional positive definite advection transport algorithm (MPDATA; Smolarkiewicz, 2006) to the third-order upwind horizontal advection (U3H; Rasch, 1994; Shchepetkin, and

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McWilliams, 2005) and the fourth-order centered vertical advection schemes (C4V;
Shchepetkin, and McWilliams, 1998; 2005). The MPDATA scheme applied in Y20_MOD,
Y21_CTRL, and Y21_VT is a non-oscillatory scheme but a sign preserving scheme
(Smolarkiewicz, 2006) that means MPDATA is not suitable for tracer fields having both
positive and negative values (i.e., temperature with degree Celsius in the ROMS model). The
upwind third-order (U3H) scheme used in Y21_RP is an oscillatory scheme but it significantly
reduces oscillations compared to other centered schemes (e.g., Hecht et al., 2000; Naughten et
al., 2017) available in the ROMS model.
The temporal evolutions of the ensemble mean of the predicted Arctic total sea ice extent
(as well as regional ice extent) for Y21_CTRL, Y21_VT, and Y21_RP are shown in Figure 8.
Y21_VT (green line) simulates slightly less areal extent (<0.1 million km²) compared to that
of Y21_CTRL throughout the prediction period. The Y21_RP shows highly similar temporal
evolution of areal extent as Y21_CTRL until near the end of August. After that, the ice melting
slows down and ice extent begins to recover earlier in Y21_RP (red line) compared to both
Y21_CRTL and Y21_VT, which leads to much smaller biases in seasonal minimum ice extent
relative to the observation. This result suggests the delayed ice recovery in late September
shown in Y20, Y20_MOD and Y21_CTRL is partly due to the choice of ocean advection and
vertical mixing schemes that change the behavior of oceanic state. Y21_RP also shows much
better predictive skill after late August compared with the CLIM/DAMP predictions (black
dashed and dotted lines). At the regional scale, changes in both the ocean vertical coordinate
(Y21_VT) and the advection and vertical mixing scheme (Y21_RP) do not significantly affect 27

the evolution of areal extent in the Barents-Kara-Greenland Seas and the Baffin Bay-Canadian Archipelago compared to that of Y21 CTRL (Fig. 8c, d). However, Y21 VT agrees better with the observations in the Beaufort-Chukchi Seas and the East Siberian-Laptev Seas compared to that of Y21 CTRL and the ice extent of Y21 RP stops retreating after mid-September in the Beaufort-Chukchi Seas relative to that of Y21 CTRL (Fig. 8a, b). Spatially, the choice of vertical transformation in Y21 VT does not significantly change the distribution of sea ice biases in Y21\_CTRL (i.e., higher ice concentration in the Pacific sector, and lower ice concentration in the Atlantic sector, (Fig. 9a-c, Fig. 4g-i). The Y21 VT experiment has slightly lower ice concentration compared with that of Y21 CTRL, which corresponds to less areal extent of Y21 VT shown in Figure 8. By using U3H/C4V advection scheme, the Y21 RP experiment has positive anomalies for most ice-covered areas (Fig. 9d-f). For September, the Y21 RP experiment better predicts the ice edge location in the Atlantic sector of the Arctic Ocean (i.e., smaller areas with horizontal/vertical lining) compared to the experiments described above (Fig. 9f). Figure 10 shows that the spatial distribution of the SST changes of Y21 VT and Y21 RP relative to Y21 CTRL (as well as predicted anomalies of Y20 MODthe OI SST and the difference between Y21 CTRL and Y21 MOD). By using different vertical transformation in the ROMS model, the Y21 VT experiment simulates slightly warmer SST in the north Pacific and Atlantic (~0.5 degree), and colder SST in the Bering Sea, Sea of Okhotsk, Barents-Kara, and Greenland Seas (~0.5-1.0 degree). We also note that SST under sea ice cover is warmer than that of Y21 CTRL, especially in the Beaufort-Chukchi Seas, which results in larger

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temperature difference and thus heat fluxes at the ice ocean interface, and then contributes to faster ice retreating in the Beaufort-Chukehi Seas (Fig. 10j l, Fig. 8a). With OISST). In general, Y21\_CTRL shows cold prediction errors in the North Pacific (~2 degrees) and the Atlantic (~3 degrees) compared to that of OISST in July, and these cold prediction errors are enhanced as the prediction time increases (to 3-5 degrees, Fig. 8d-f). With the U3H/C4V tracer advection scheme in Y21\_RP, cold biasesprediction errors shown in Y21\_CTRL (Fig. 10d-i) are reduced significantly in the north Pacific and Atlantic, but SST under sea ice coverin much of the Arctic Ocean is slightly colder than that of Y21\_CTRL (Fig. 10m-08j-l).

#### 3.4. CICE configuration and ice thickness assimilation

Y21\_CTRL (as well as Y21\_VT) until near the end of July. After that, the ice melting slows down (closer to the observation) and the ice extent begins to recover earlier (after the first week of September) in Y21\_RP compared to Y21\_CRTL. This leads to much smaller prediction error in seasonal minimum ice extent relative to the observation. Y21\_RP also shows better predictive skill after late August compared with the CLIM/DAMP predictions (black dashed and dotted lines). This suggests the delayed ice recovery in late September shown in Y20\_MOD, Y21\_CTRL and Y21\_VT is in part due to the choice of ocean advection and vertical mixing schemes, which change the behavior of ocean state. At the regional scale, the slower ice decline after July and earlier recovery of the ice extent in September mainly occur in the Beaufort-Chukchi and Barents-Kara-Greenland Seas compared to that of Y21\_CTRL (Fig. 4a, c). By using U3H/C4V scheme, the Y21\_RP experiment simulates higher sea ice concentration than

that of Y21\_VT (Fig. 5f<sub>1</sub>-f<sub>3</sub>). For September, the Y21\_RP experiment better predicts the ice edge location in the Atlantic sector of the Arctic (i.e., smaller areas with horizontal/vertical lining) compared to the experiments described above (not shown).

Figure 9 shows the evolution of sea ice mass budget terms of Y21\_VT and Y21\_RP.

Relative to Y21\_VT, Y21\_RP (with U3H/C4V scheme) results in increased frazil ice formation

in July, which is partly compensated by increased surface melting. Y21\_RP also leads to

increased basal growth in mid- and late September (Fig. 9a, b).

Figure 10 shows the difference in the vertical profile of ocean temperature and salinity in the upper 150 m averaged for the central Arctic Ocean between Y21\_RP and Y21\_VT. The ocean temperature in the surface layer of Y21\_RP is slightly colder during the prediction period compared to that of Y21\_VT (Fig. 10a), especially in August and September. Moreover, the water in the surface layer (0-20 m) of Y21\_RP is fresher than that of Y21\_VT (Fig. 10b). They reduce the freezing temperature and favor frazil ice formation. In the CAPS, the frazil ice formation is determined by the freezing potential, which is the vertical integral of the difference between temperature in upper ocean layer and the freezing temperature in the upper 5 m-layer. The supercooled water is adjusted based on the freezing potential to form new ice and rejects brine into the ocean that leads to saltier water between 20-50 m in Figure 10. It should be noted that the increased frazil ice formation in July in Y21\_RP might be also partly due to the oscillatory behavior of U3H scheme, which makes the temperature fall below the freezing point and then instantaneously forms new ice (as well as temperature/salinity adjustments).

#### 3.4. Impacts of sea ice thermodynamics in the CICE model

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In Y20, we used thesea ice thermodynamics introduced by Bitz and Lipscomb (1999; hereafter BL99, as the setup of CAPS, which assumes a fixed vertical salinity profile based on observations, as the setup for seasonal Arctic sea ice prediction. Since the release of. The new CICE version 5, it model includes thea MUSHY-layer ice thermodynamics introduced by Turner et al. (2013), which simulates vertically resolved and time-varying prognostic salinity and its associated impact effects on other thermodynamics thermodynamic properties of sea ice. In the Y21 MUSHY experiment, we change the ice thermodynamics from BL99 to MUSHY (Table 32) to examine whether improved ice thermodynamics has noticeable influence on Arctic sea ice simulation and prediction at seasonal timescale. Additionally, in Y20 and Compared to Y21 RP, Y21 MUSHY (Fig. 4, pink line) produces very similar evolution of the total ice extent. However, it simulates relatively larger ice extent near the end of September, which is also reflected by the basin-wide increased ice cover shown in Figure 5h<sub>3</sub>. At the regional scale, compared to Y21 RP, Y21 MUSHY predicts less ice in August in the Beaufort-Chukchi. The opposite is the case for the East Siberian-Laptev Seas (Fig. 4a, b). Figure 11 shows the difference of the ensemble mean of the predicted ice thickness between Y21 MUSHY and Y21 RP. Compared with Y21 RP, Y21 MUSHY simulates thicker ice (from ~0.2m in July to over 0.4m in September) extending from the Canadian Arctic, through the central Arctic Ocean, to the Laptev Sea (Fig. 11a-c). This seems to be consistent with previous studies, which show that the Mushy-layer thermodynamics simulates thicker ice than BL99 thermodynamics in both standalone CICE (Turner and Hunke, 2015) and the fullycoupled (Bailey et al., 2020), but Y21\_MUSHY shows thinner ice (~0.2m) in an arc extending from north of Alaska to north of eastern Siberia compared to Bailey et al. (2020). Note that Y21\_MUSHY focuses the effects of Mushy-thermodynamics on seasonal timescale while the results in Bailey et al. (2020) are based on 50-year simulations.

Compared to Y21\_RP, the mass budget of Y21\_MUSHY (Fig. S6) shows that both surface melting and frazil ice formation terms are increased. This compensation between surface melting and frazil ice formation from the Mushy-layer thermodynamics in the CAPS leads to relatively unchanged total ice extent between Y21\_MUSHY and Y21\_RP (Fig. 4 green and pink lines).

## 4. Prediction skill of CAPS at longer timescale

The design of Arctic sea ice prediction experiments described above follow the protocol of the Sea Ice Prediction Network (SPIN), in which the outlook start from June 1<sup>st</sup>, July 1<sup>st</sup>, and August 1<sup>st</sup> to predict seasonal minimum of the ice extent in September. It is not clear that how predictive skills of dynamical models participating in SIPN may change for longer period. Here we conduct two more experiments to investigate the predictive capability of CAPS beyond the SPIN prediction period. For the prediction experiments discussed above, we use a simple approach to merge CryoSat-2 and SMOS ice thickness by replacing ice thickness less than 1m in CryoSat-2 data with SMOS data for ice thickness assimilation. Ricker et al. (2017) presented a new ice thickness product (CS2SMOS) based on the optimal interpolation to statistically merge CrySat-2 and SMOS data. The Y21\_SIT experiment (Table 3) is designed to

investigateHere we utilize the impacts configuration of assimilating different approaches to merge CyroSat-2 and SMOS data on sea ice prediction. Figure 11 shows the temporal evolutions of the ensemble mean of the predicted Arctic total sea ice extent (as well as regional ice extent) for the Y21 RP, Y21 MUSHY, and but use CS2SMOS SIT for the assimilation (Y21 SIT-experiments. All three experiments predict; Table 2). The predicted total ice extent is almost identical total ice extents during the first 2week integration. After that, Y21 MUSHY (red solid line) produces a slightly more ice extent (~0.2 million km<sup>2</sup>) than that of Y21 RP (blue solid line) for the rest of integration, which mainly due to an increase of sea ice in the East Siberian-Laptev Seas (Fig. 11b). The timing of minimum ice extent occurs early in Y21 MUSHY relative to Y21 RP, resulting in early recovery. In contrast to Y21 RP, Y21 SIT (green solid line) simulates to Y21 RP in July but slightly larger icetotal extent after the first week of August. At the regional scale, compared with Y21 RP, Y21 SIT predicts more ice before the mid-August and less ice after that in the Beaufort-Chukchi Seas (Fig. 11a) and larger ice extent throughout the entire prediction period in the Barents-Kara-Greenland Seas (Fig. 11c). For the spatial distribution of ice concentration anomalies, Y21 MUSHY and Y21 SIT show similar distribution as Y21 RP with slightly higher ice concentration at gridpoint scale (July than that of Y21 RP (not shown). Figure 12 show the ensemble mean of predicted sea ice thickness of the Y21 RP, Y21 MUSHY, and Y21 SIT experiments and the ice thickness changes of Y21 MUSHY and Y21 SIT relative to Y21 RP. All three experiments produce similar ice thickness distribution, that The configuration of Y21 SIT is the thickest ice locates near the Canadian Archipelago

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and the Lincoln Sea, as well as the thickness gradient directs toward the Siberia coast (Fig. 12a-f). Compared with Y21 RP, Y21 MUSHY simulates thicker ice (from ~0.14m in July to over 0.2m in September) in the Canadian Arctic and the central Arctic Ocean, thinner ice (over 0.2m) in the Kara Sea in September, and negligible thickness difference in other areas (Fig. 12g<sub>1</sub>·i<sub>1</sub>). This is consistent with previous studies showing that the Mushy-layer thermodynamics simulates thicker ice than BL99 thermodynamics in both standalone CICE (Turner and Hunke, 2015) and the fully-coupled context (used in the following experiments. Taking advantage of the Bailey et al., 2020). Compared with Y21 RP, Y21 SIT predicts thicker ice most of the ice edge zone and thinner ice in the central Arctic Ocean in July and August. In September, Y21 SIT simulates much thinner ice (over 0.2m) in the Beaufort, Chukchi, East Siberian Seas, and the central Arctic Ocean along with thicker ice in the Barents, Kara, and Laptev Seas (Fig. 12g2-i2). The evolution of predicted ice thickness in Y21 SIT corresponds to that of regional ice extent shown in Figure 11. This result suggests that assimilating the new ice thickness product (CS2SMOS) have significant influences on the predicted ice thickness at the regional scale.

#### 4. Discussions

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Arctic sea ice prediction experiments conducted in this study follow the protocol of Sea Ice Prediction Network (SPIN), in which the outlook start from June 1<sup>st</sup>, July 1<sup>st</sup>, and August 1<sup>st</sup> to predict seasonal minimum of ice extent in September. Due to the socioeconomic impacts of sea ice recovery during the freeze-up period (e.g., trans-Arctic shipping, coastal activities), it is also essential to investigate the predictive capability of CAPS beyond the SPIN prediction

period. Combining the entire prediction period provided by CFS forecasts and the Y21 SIT experiment, (7 months), the Y21 EXT-7 experiment is designed to extend the prediction period to the end of January next year (Table 32). Figure 1312 shows the temporal evolutions of the ensemble mean of the predicted total Arctic total sea ice extent (as well as regional ice extent) for the Y21 EXT-7 experiment. As shown in Figure 13, the predicted. The total ice extent exhibits reasonable evolution in terms of seasonal minimum and timing of recovery compared with the observations until late November. Y21 EXT-7 also performs better than that of the CLIM/DAMP predictions (black dashed and dotted lines) until mid-to-late November. After that, Y21 EXT-7 overestimates the total ice extent compared with relative to the observations, and this such overestimation is largely contributed by more extensive sea ice in the Barents-Kara-Greenland Seas (Fig. 13c). The overestimated ice cover in the Barents-Kara-Greenland Seas may be the results of biases from the CFS data propagated into the model domain through lateral boundary conditions and accumulated effects of biases in model components.12c), which is a result of a sharp increase in the basal growth term after mid-tolate November (not shown).

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A growing number of studies have shown evidences of Arctic sea ice spring predictability barrier, which is defined as a springtime date. It means that predictions initialized prior to this datespring (before May) have much lower predictive skill than predictions initialized after/on that date (e.g., Bonan et al., 2019; Bushuk et al., 2017; 2018; Day et al., 2014). To investigate the predictive capability of CAPS initialized prior to the summer melting season, the Y21\_MAR-7 experiment is initialized on March 1<sup>st</sup>, 2018 and predicts sea ice evolution until

the end of September (Table 32). Figure 1413 shows the temporal evolutions evolution of the ensemble mean of the predicted total Arctic total sea ice extent (as well as regional ice extent) for the Y21 MAR-7 experiment. The evolution of predicted total sea ice extent shows faster ice melting rate than the observations after mid-May, but slower ice retreating after mid-July, and. As a result, the predicted minimum of ice extent has an overestimation (~1.2 million km<sup>2</sup>) compared to the observed minimum. In contrast to Y21 MAR-7, the DAMP prediction (black dotted line) agrees better with the observations throughout the 7-month prediction period. At the regional scale, Y21 MAR-7 shows abrupt ice decline after May in the Beaufort-Chukchi Seas (Fig. 14a13a), and this decline is mainly contributed by ice meltingretreating along the Alaskan coast (not shown). Sea ice in the East Siberian-Laptev Seas exhibits slow melting after July (Fig. 14b13b), and ice cover areas still connect to the Siberian coast, which is different from the observations (not shown). For the Barents-Kara-Greenland Seas (Baffin Bay-Canadian Archipelago), there are systematic overestimations (underestimations) throughout the entire prediction period (Fig. 14e13c-d). Bushuk et al. (2020) suggested that Arctic sea ice predictability prior to the barrier date is mainly limited by synoptic events, which are only predictable for few weeks, whereas the predictability after the barrier date is enhanced by icealbedo feedback with the onset of ice melting.

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### 5. Conclusions and Discussions

This paper presents and evaluates the updated Coupled Arctic Prediction System (CAPS) designated for Arctic sea ice and climate prediction. The CAPS consists of the WRF, ROMS,

and CICE models under the framework of the COAWST system, as well as data assimilation system based on the localized error subspace transform ensemble Kalman filter to assimilate satellite-observed sea ice observations prediction through a case study for the year of 2018. A set of Pan-Arctic prediction experiments with improved/changed physical parameterizations as well as different configurations starting from July 1st to the end of September are performed for the year of 2018 to assess their impacts of the updated CAPS on the predictive skill of Arctic sea ice at seasonal timescale. Specifically, we focus on the Rapid Refresh (RAP) physics in the WRF model, the oceanic tracer advection scheme in the ROMS model, sea ice thermodynamics in the CICE model, and investigate physical process linking them to Arctic sea ice simulation and prediction. The results of prediction experiments show that the updated CAPS with improved physical parameterizations can better predict the evolution of the total ice extent compared with its predecessor described in Yang et al. (2020), though the predictions exhibit biases in regional ice extent. We demonstrate that the (2020), though the predictions exhibit some prediction errors in regional ice extent. The key improvements of WRF, including cumulus, boundary layer, and land surface schemes, result in improved simulations in downward radiative fluxes and near surface air temperature. These improvements mainly influence the predicted ice thickness instead of total ice extent. The difference in the predicted ice thickness can have potential impacts on the icebreakers planning their routes across the ice-covered regions. The major changes of ROMS, including tracer advection and vertical mixing schemes, reduces the

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prediction error in sea surface temperature and changes ocean temperature and salinity

structure in the surface layer, leading to improved evolution of the predicted total ice extent (particularly correcting the late ice recovery issue in the previous CAPS). The change of CICE, including improved ice thermodynamics, have noticeable influences on the predicted ice thickness.

We demonstrate that CAPS can remain skillful beyond the designated period of Sea Ice Prediction Network (SIPN), which has potential values for stakeholders making decisions regarding the socioeconomical activities. Along with the improved Although CAPS shows extended predictive skill to the freeze-up period, the prediction produces extensive ice through

conditions and its accumulated effect influences Arctic sea ice extent, the simulation during the

the basal growth near the end of total prediction. The excessive basal growth may be partly due

to that the bias of the CFS data propagates into the model domain through lateral boundary

freeze-up period.

Keen et al. (2021) analyzed the Arctic mass budget of 15 models participated in the Coupled Model Intercomparison Project Phase 6 (CMIP6). We notice that, first, the top melting and the basal melting terms in CMIP6 models have comparable contributions in July while the top melting term only has ~50% contribution relative to the basal melting term in the CAPS. The updated CAPS also has reduced biases in with the predicted near RAP physics improves the performance of shortwave/longwave radiation at the surface air temperature, downward radiations (Fig. 1 and Fig. 2). The net flux at the surface, and sea surface however, may still be underestimated in the CAPS. Besides, the surface property of sea ice (i.e., the amount of melt ponds, bare ice, and snow) is a factor that influences surface albedo and thus the absorbed

shortwave radiation (e.g., Nicolaus et al., 2012; Nicolaus and Katlein, 2013). The prediction experiments starting at July 1<sup>st</sup> in this study do not consider the initialization of melt ponds (i.e., zero melt pond coverage at the initial). However, melt ponds start to develop in early May based on the satellite observations (e.g., Liu et al., 2015, Fig. 1). The initialization of melt pond based on the observations (e.g., Ding et al., 2020) in the CAPS is a direction to improve the representation of the ice surface properties. Second, the mass budget analysis by both Keen et al. (2021) and this study show that the contribution of lateral melting term is relatively small, which might be due to that CMIP6 models and the CAPS assume constant floe-size (i.e., 300 meters in CICE), which is a critical value to determine the strength of lateral melting (e.g., Horvat et al., 2016; Steele, 1992). Recently, several studies have proposed floe size distribution models (e.g., Bateson et al., 2020; Bennetts et al., 2017; Boutin et al., 2020; Horvat and Tziperman, 2015; Roach et al., 2018, 2019; Zhang et al., 2015, 2016). Incorporating floe size distribution model in the CAPS and understanding its impacts on seasonal Arctic sea ice prediction will be a future direction of developing CAPS. Lastly, the prediction experiments with the upwind advection scheme (i.e., Y21 RP, Y21 EXT-7) shows spurious large frazil ice formation, particularity in July, which is different from the analysis shown in Keen et al. (2021). An approach for reducing spurious frazil ice formation is proposed by Naughten et al. (2017) that they implemented upwind limiter (Leonard and Mokhtari, 1990) to the U3H scheme to further reduce the oscillations. Naughten et al. (2018) also suggested that the oscillatory behaviors can be smoothed out by applying the Akima fourth-order tracer advection scheme combined with Laplacian horizontal diffusion at a level strong enough. Beside of the oscillatory

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behaviors of advection scheme, the ice-ocean heat flux can also play a role in the spurious frazil ice formation. As discussed in section 3.3, the freezing/melting potential not only determines the amount of newly-formed ice, but also limits the amount of energy that can be extracted from the ocean surface layer to melt sea ice. This implies that the ocean surface layer will be close to the freezing temperature if the ice-ocean heat fluxes reach the limit imposed by the melting potential. Shi et al. (2021) discussed the impacts of different ice-ocean heat flux parametrizations on sea ice simulations. Their results suggest that Arctic sea ice will be thicker and ocean temperature in Arctic domain compared to its predecessor. will warmer beneath high-concentration ice with a complex approach proposed by Schmidt et al. (2004) that limits melt rates (heat fluxes) of sea ice through considering a fresh water layer underlying sea ice. The warmer ocean temperature under sea ice with a more complex approach in ice-ocean heat flux may be the solution to reduce the occurrence of local temperature falling below freezing temperature with oscillatory advection schemes. Based on the prediction experiments discussed in thethis paper, the configuration of the with the RAP physics, the U3H/C4V ocean advection, BL99 ice thermodynamics, and CS2SMOS ice thickness assimilation (Table 2, Y21 SIT experiment) is assigned as the finalized CAPS version 1.0. Improving the representation of physical processes in the CAPS version 1.0 for further reducing the model bias will remain the main focus for the development of CAPS version 1.0. \_Since the CAPS version 1.0 is a regional modeling system, it relies on GCMthe forecasts form global climate models as initial and lateral boundary conditions. That is, biases existed in

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GCM simulations (here the CFS forecast) can be propagated into and affect the entire arealimited domain (e.g., Bruyère et al., 2014; Rocheta et al., 2020; Wu et al., 2005). This issue can be a potential source that influences the predictive capability of CAPS version 1.0 for longer timescales. Studies have applied bias correction techniques with different complexities for improving the performance of regional modeling system (e.g., Bruyère et al., 2014; Colette et al., 2012; Rocheta et al., 2017, 2020). Further investigation is needed to address biases inherited from GCM predictions through lateral boundaries for improving the predictive capability of CAPS version 1.0.

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Code and data availability: The COAWST and CICE models are open source and can be downloaded from their developers at <a href="https://github.com/jcwarner-usgs/COAWST">https://github.com/CICE-Consortium/CICE</a>, respectively. PDAF can be obtained from <a href="https://pdaf.awi.de/trac/wiki">https://github.com/CICE-Consortium/CICE</a>, respectively. PDAF can be obtained from <a href="https://pdaf.awi.de/trac/wiki">https://pdaf.awi.de/trac/wiki</a>. CAPS v1.0 described in this paper is permanently archived at <a href="https://doi.org/10.5281/zenodo.5034971">https://doi.org/10.5281/zenodo.5034971</a>. The prediction data analyzed in this paper can be accessed from <a href="https://doi.org/10.5281/zenodo.4911415">https://doi.org/10.5281/zenodo.4911415</a>.

Author contributions: CYY and JL designed the model experiments, developed the updated CAPS model, and wrote the manuscript, CYY conducted the prediction experiments and analyzed the results. DC provided constructive feedback on the manuscript.

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## **7. Tables**

Table 1 Difference in versions for the model components between the original and updated

**CAPS** 

	<del>Yang et al. (2020)</del>	This paper
COAWST	<del>3.1</del>	<del>3.5</del>
WRF	<del>3.6.1</del>	4.1.2
ROMS	3.7 revision 748	3.8 revision 981
CICE	5.1.2	6.0.0

1212 <u>Table 2 Table 1</u> The summary of physic parameterizations used in the Y21\_CRTL experiment

WRF physics			
Cumulus parameterization	Grell-Freitas (Freitas et al. 2018;		
	improved from Y20)		
Microphysics parameterization	Morrison 2-moment (Morrison et al.		
	2009; same as Y20)		
Longwave radiation parameterization	CAM spectral band scheme (Collins et		
	al. 2004; same as Y20)		
Shortwave radiation parameterization	CAM spectral band scheme (Collins et		
	al. 2004; same as Y20)		
Boundary layer physics	MYNN2 (Nakanishi and Niino, 2006;		
	improved from Y20)		
Land surface physics	Unified Noah LSM (Chen and Dudhia,		
	2001; improved from Y20)		
ROMS physics			
Tracer advection scheme	MPDATA (Smolarkiewicz, 2006; same		
	as Y20)		
Tracer vertical mixing scheme	GLS (Umlauf and Burchard, 2003;		
	same as Y20)		
Bottom drag scheme	Quadratic bottom friction (QDRAG;		

	(same as Y20)
CICE physics	
Ice dynamics	EVP (Hunke and Dukowicz, 1997;
	improved from Y20)
Ice thermodynamics	Bitz and Lipscomb (1999; same as
	Y20)
Shortwave albedo	Delta-Eddington (Briegleb and Light,
	2007; same as Y20)

Table 32 The summary of the prediction experiments and details of experiment designs.

Note: All experiments use the CFS operational forecasts as initial and boundary conditions; VT: vertical transformation function; VS: vertical stretching function; SH94: stretching function of Song and Haidvogel (1994); S10: stretching function of Shchepetkin (2010).

Experiment	Physics	Assimilation	ROMS	Simulation
			vertical	period
			coordinate	
¥20	Physics (old version)	2 localization radii	VT 1	2018.07.01-
	listed in Table 2	SSMIS SIC	VS SH94	2018.10.01
		Simply-merged CryoSat-	<i>h</i> € 10m	
		2/SMOS SIT		
Y20_MOD	Physics (old version)	6 localization radii	VT 1	2018.07.01-
	listed in Table 21	SSMIS SIC	VS SH94	2018.10.01
		Simply-merged CryoSat-	$h_c$ 10m	
		2/SMOS SIT		
Y21_CTRL	Physics (new version)	6 localization radii	VT 1	2018.07.01-
	listed in Table 21	SSMIS SIC	VS SH94	2018.10.01
		Simply-merged CryoSat-	$h_c$ 10m	
		2/SMOS SIT		
Y21_VT	Physics (new version)	6 localization radii	VT 2	2018.07.01-

	listed in Table 21	SSMIS SIC	VS S10	2018.10.01
		Simply-merged CryoSat-	$h_c$ 300m	
		2/SMOS SIT		
Y21_RP	Advection: U3H/C4V	6 localization radii	VT 2	2018.07.01-
	Bottom drag:	SSMIS SIC	VS S10	2018.10.01
	LOGDRAG	Simply-merged CryoSat-	$h_c$ 300m	
		2/SMOS SIT		
Y21_MUSHY	Same physics as	6 localization radii	VT 2	2018.07.01-
	Y21_RP	SSMIS SIC	VS S10	2018.10.01
	CICE: Mushy layer	Simply-merged CryoSat-	$h_c$ 300m	
	thermodynamics	2/SMOS SIT		
Y21_SIT	Same physics as	6 localization radii	VT 2	2018.07.01-
	Y21_RP	SSMIS SIC	VS S10	2018.10.01
		OI-merged CryoSat-	$h_c$ 300m	
		2/SMOS SIT		
Y21_EXT-7	Same physics as	6 localization radii	VT 2	2018.07.01-
	Y21_RP	SSMIS SIC	VS S10	2019.01.31
		OI-merged CryoSat-	$h_c$ 300m	
		2/SMOS SIT		
Y21_MAR-7	Same physics as	6 localization radii	VT 2	2018.03.01-

Y21_RP	SSMIS SIC		VS S10	2018.09.30
	OI-merged	CryoSat-	<i>h<sub>c</sub></i> 300m	
	2/SMOS SIT			

## **8. Figures**

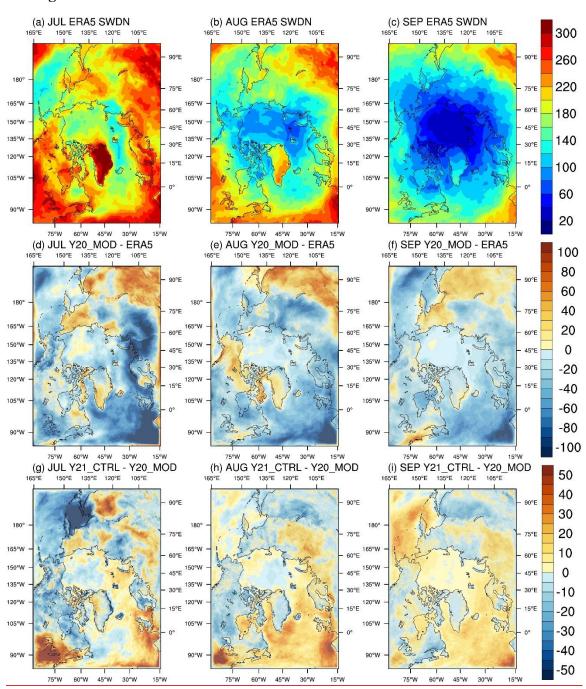


Figure 1 ERA5 monthly mean of downward shortwave radiation at the surface for (a) July, (b)

August, and (c) September, the difference between Y20 MOD and ERA5 for (d) July, (e)

August, (f) September, and the difference between Y21 CTRL and Y20 MOD for (g) July, (h)

August, and (i) September.

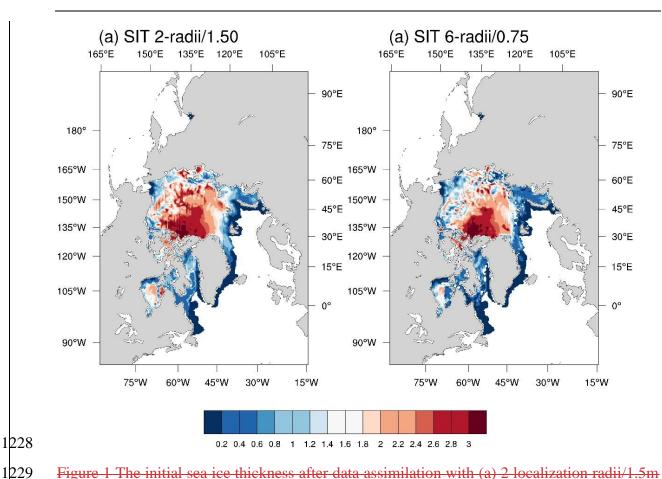


Figure 1 The initial sea ice thickness after data assimilation with (a) 2 localization radii/1.5m ice thickness uncertainty, and (b) 6 localization radii/0.75m ice thickness uncertainty.

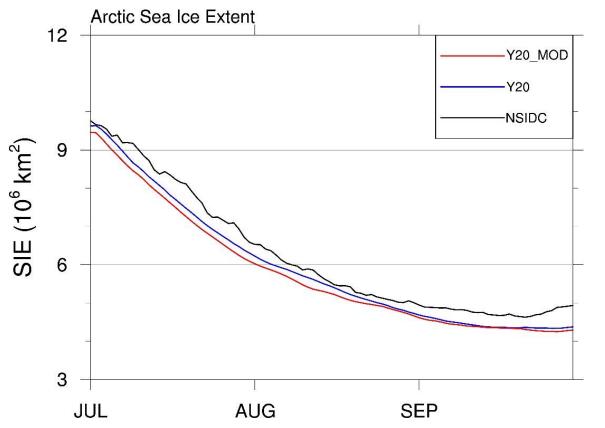
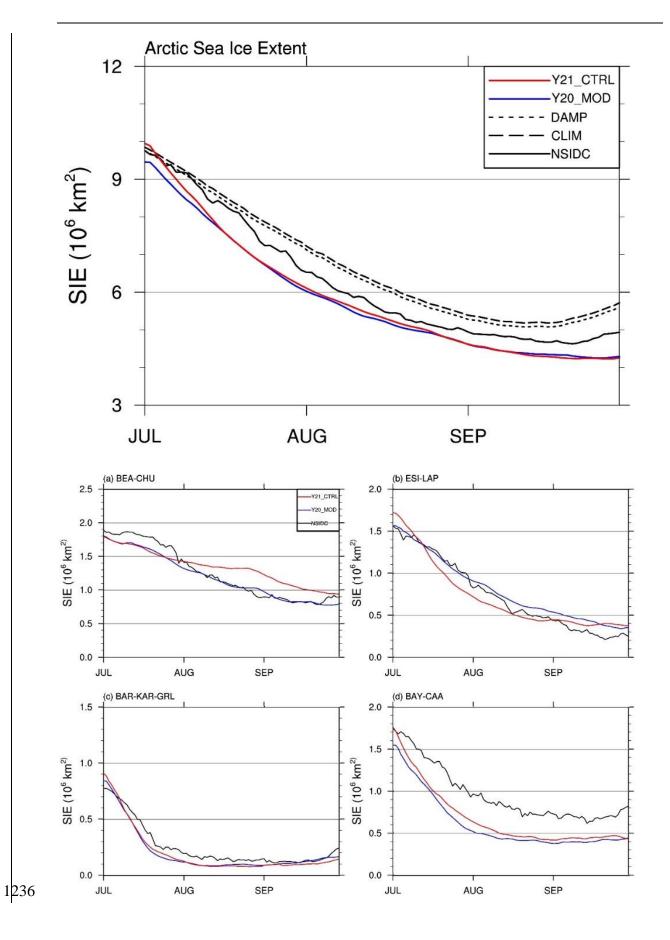


Figure 2 Time-series of Arctic sea ice extent for the observations (black line) and the ensemblemean of Y20 (blue line) and Y20\_MOD (red line).



1237 Figure 3

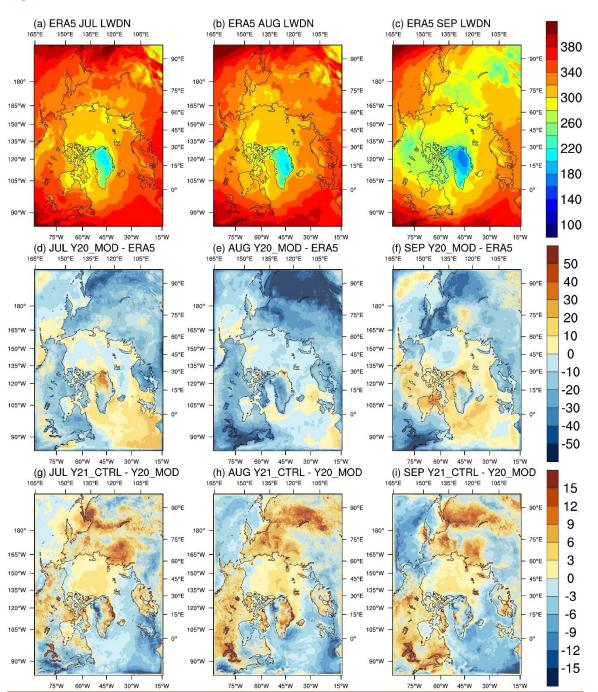


Figure 2 Same as Figure 1, but for downward thermal radiation at the surface.

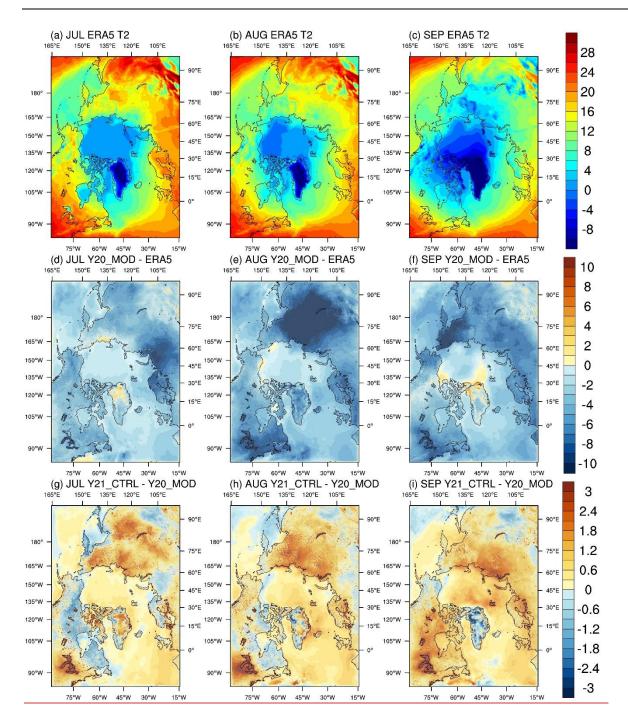


Figure 3 Same as Figure 1, but for near-surface air temperature.

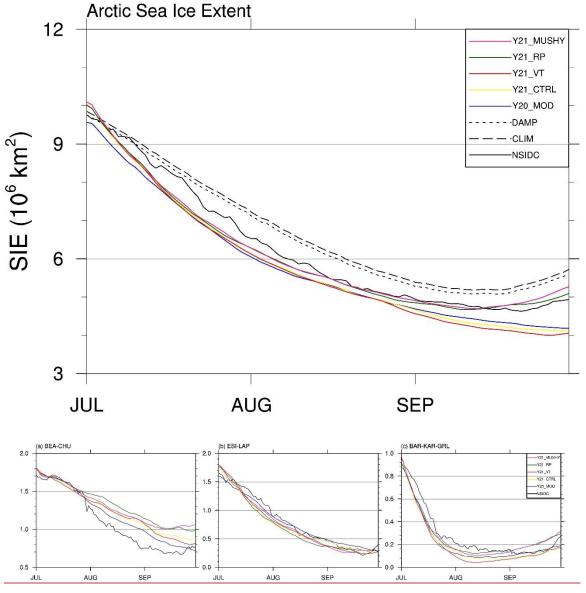
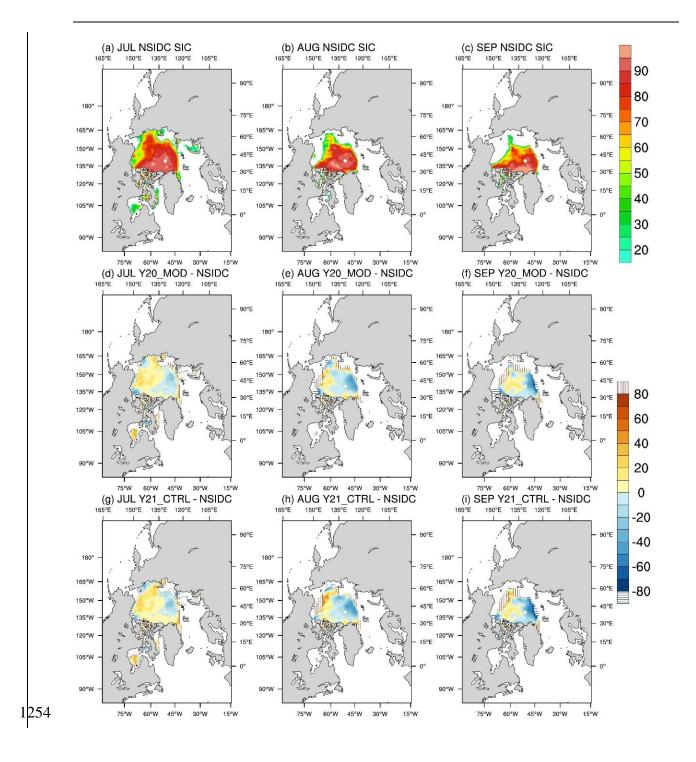


Figure 4 Top panel: Time-series of Arctic sea ice extent for the observations (black line) and the ensemble-mean of Y20\_MOD (blue line) and), Y21\_CTRL (yellow line), Y21\_VT (red line), Y21\_RP (green line), and Y21\_MUSHY (pink line). Dashed and dotted lines are the climatology and the damped anomaly persistence predictions. Bottom panel: Time-series of the observed (black line) and the ensemble-mean of regional sea ice extents for Y20\_MOD (blue line) and), Y21\_CTRL (yellow line), Y21\_VT (red line), Y21\_RP (green line), and Y21\_MUSHY (pink line) for (a) Beaufort-Chukchi Seas, (b) East Siberian-Laptev Seas, and (c) Barents-Kara-Greenland Seas, and (d) Baffin Bay Canadian Archipelago.



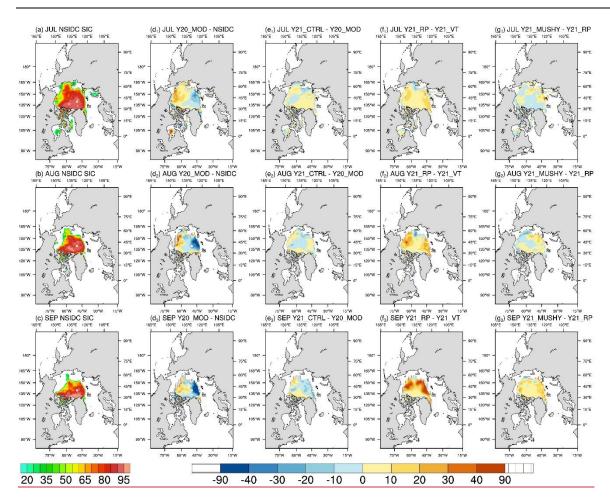


Figure  $4\underline{5}$  Monthly mean of sea ice concentration for (a) July, (b) August, (c) September of the NSIDC observations, and the difference between the <u>predictionsall prediction experiments</u> and the observations for ( $\underline{dd_1}$ - $\underline{g_1}$ ) July, ( $\underline{ed_2}$ - $\underline{g_2}$ ) August, ( $\underline{fd_3}$ - $\underline{g_3}$ ) September of Y20\_MOD, (g) July, (h) August, and (i) September of Y21\_CTRL. Vertical/horizontal-line areas represent the difference of ice edge location (15% concentration).

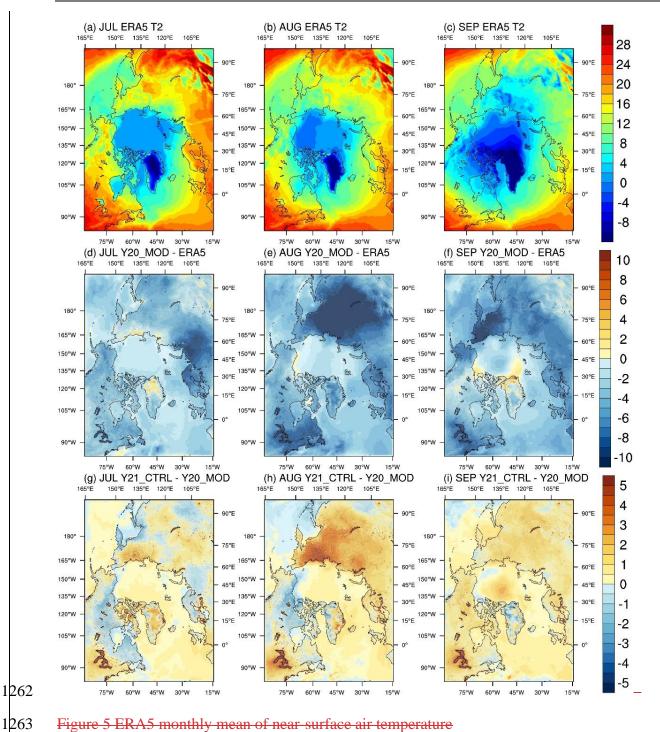
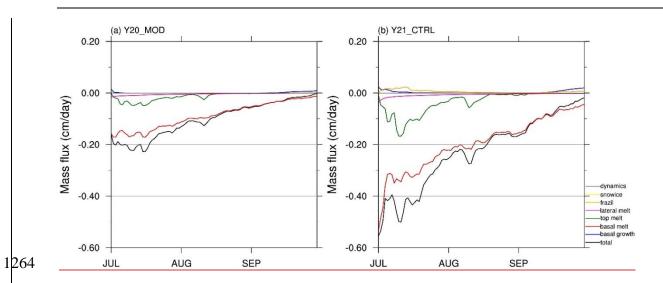


Figure 5 ERA5 monthly mean of near-surface air temperature



for (a) July, (b) August, and (c) September, the difference between Y20\_MOD and ERA5 for (d) July, (e) August, (f) September, and the difference between Y21\_CTRL and Y20\_MOD for (g) July, (h) August, and (i) September.

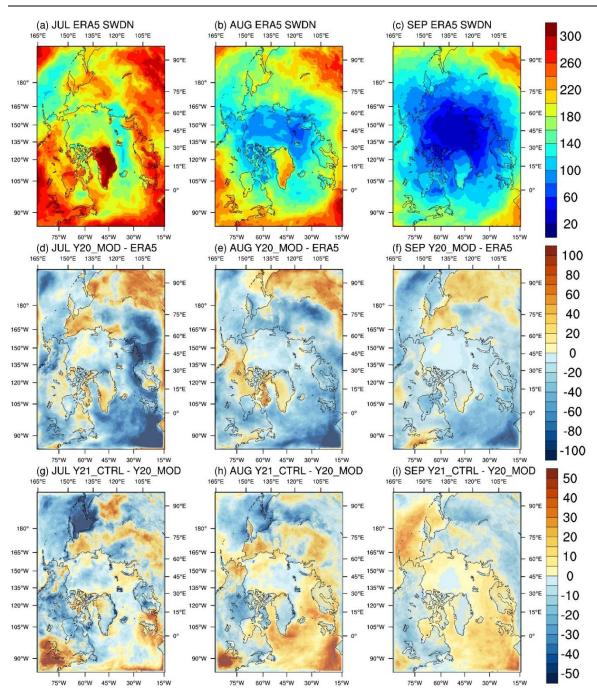


Figure 6 Same as Time-series of sea ice mass budget terms for (a) Y20\_MOD and (b) Y21\_CTRL.

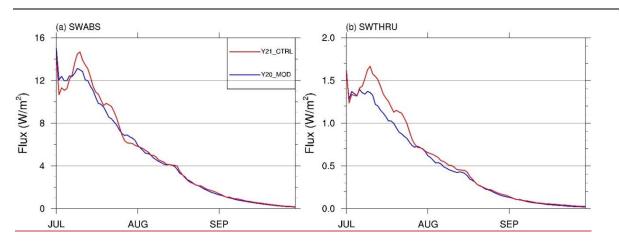


Figure 5, but for downward 7 Time-series of (a) shortwave radiation at the surface. absorbed by ice surface, and (b) penetrating shortwave radiation to the upper ocean averaged over ice-covered grid cells for Y20 MOD (blue line) and Y21 CTRL (red line).

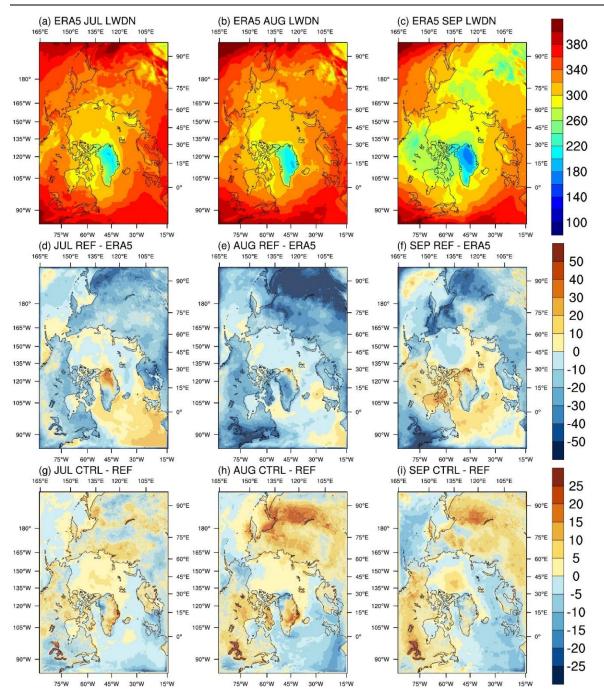
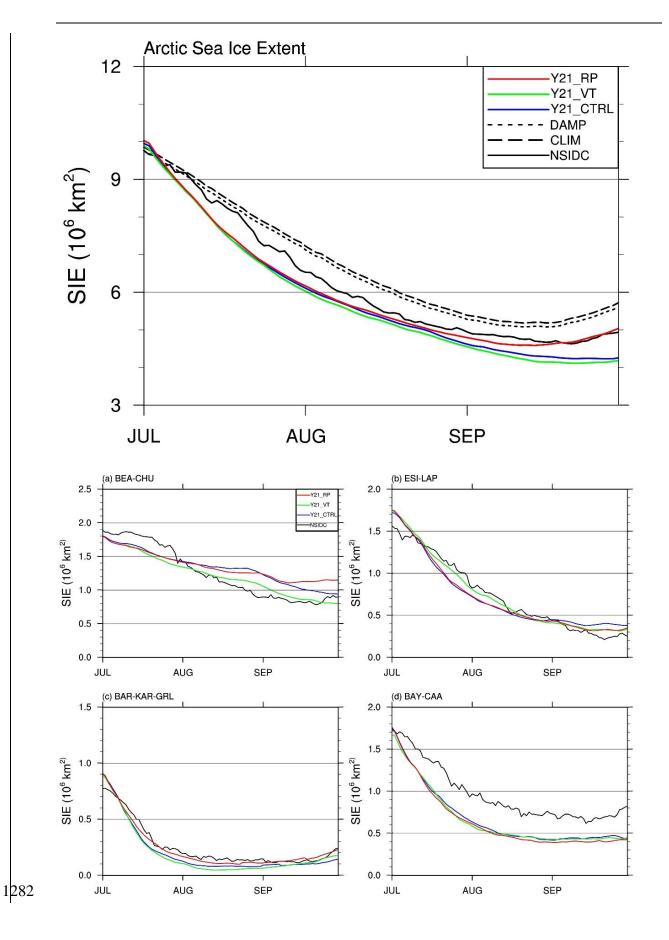


Figure 7 Same as Figure 6, but for downward thermal radiation at the surface.



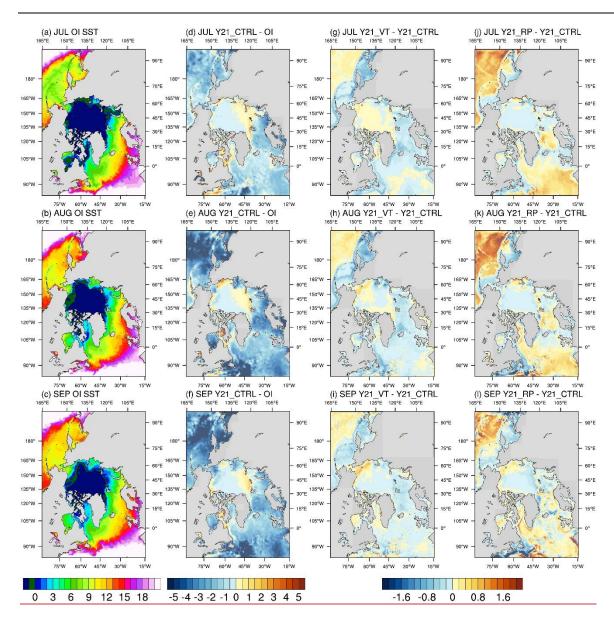


Figure 8 Same as Figure 3, but for Y21\_CTRL (blue line), Y21\_VT (green line), and Y21\_RP (red line).

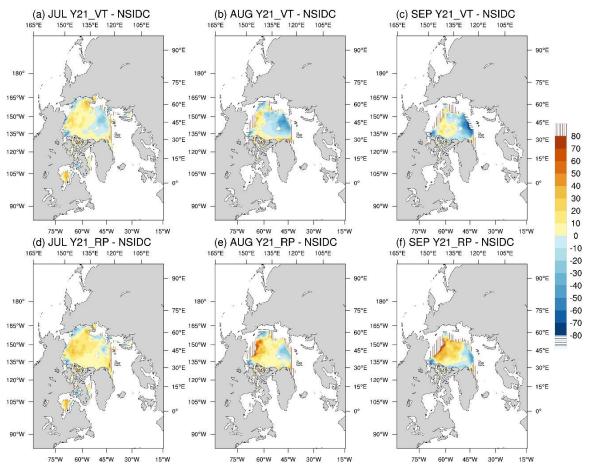


Figure 9 Monthly mean of sea ice concentration difference between the predictions and the observations for (a) July, (b) August, (c) September of Y21\_VT, (d) July, (e) August, and (f) September of Y21\_RP. Vertical/horizontal line areas represent the difference of ice edge location (15% concentration).

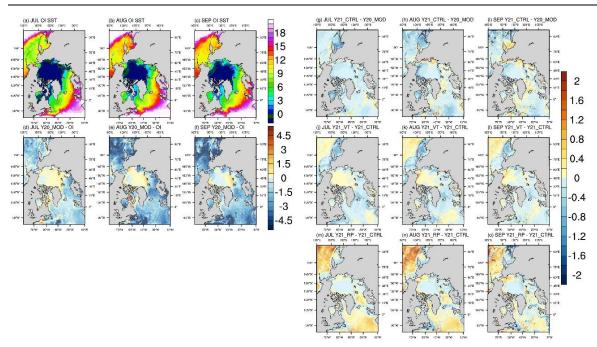
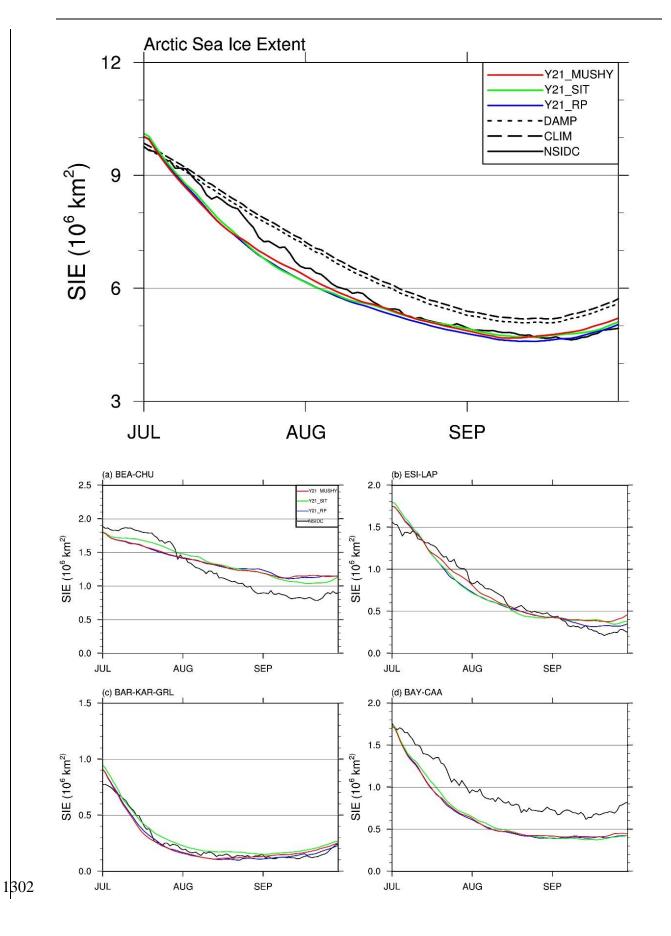


Figure 10 Left panel: MonthlyFirst column: monthly mean of sea surface temperature for (a) July, (b) August, (c) September of the OI SST, and Second column: the difference between the predictions Y21 CTRL and the observations OI SST for (d) July, (e) August, (f) September of Y20\_MOD. Right panel: Monthly mean of sea surface temperature difference between Y21\_CTRL and Y20\_MOD for (g) July, (h) August, (i) September, and the difference between Y21\_VTVT/Y21\_RP and Y21\_CTRL for (g) July, (h) August, (i) September of Y21\_VT, (j) July, (k) August, and (l) September of Y21\_VT, (m) July, (n) August, and (o) September of Y21\_RP.RP.



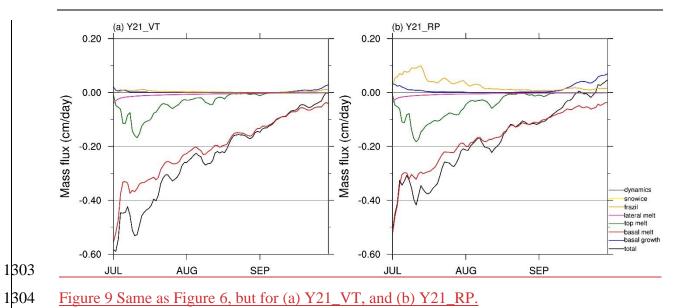


Figure 9 Same as Figure 6, but for (a) Y21\_VT, and (b) Y21\_RP.

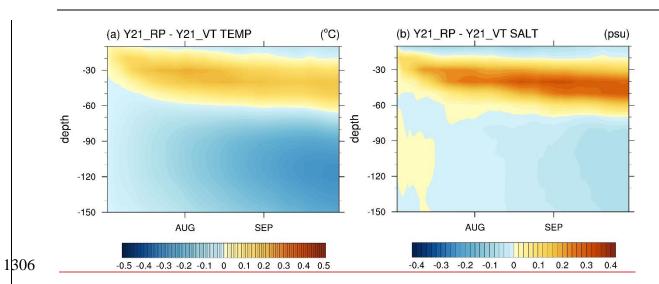


Figure 10 (a) the average temperature profile of upper 150 m under ice-covered areas for the difference between Y21\_RP and Y21\_VT. (b) same as (a), but for the salinity profile.

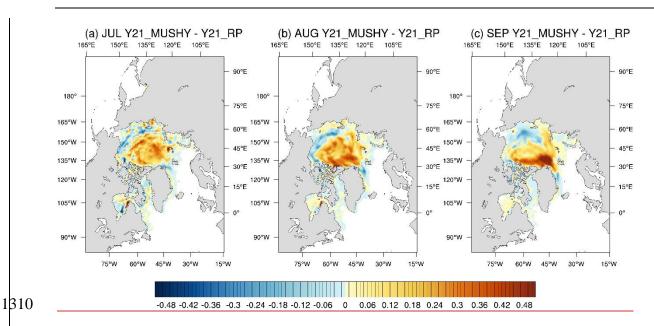


Figure 11 Same as Figure 3, but for Y21\_RP, Y21\_MUSHY, and Y21\_SIT.

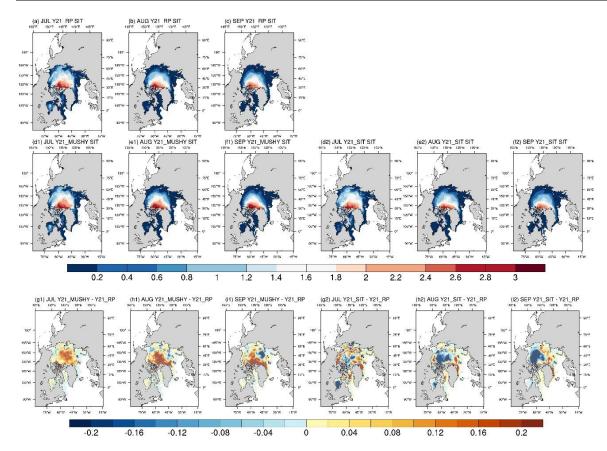
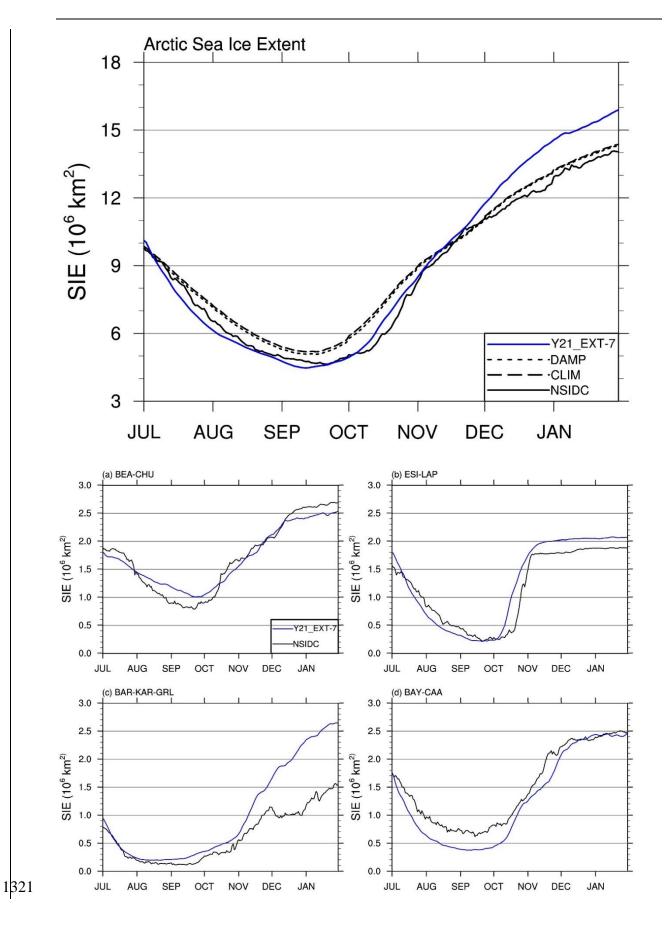


Figure 12 Monthly mean of sea ice thickness for (a) July, (b) August, and (c) September of Y21\_RP, (d<sub>1</sub>) July, (e<sub>1</sub>) August, (f<sub>1</sub>) September of Y21\_MUSHY, (d<sub>2</sub>) July, (e<sub>2</sub>) August, (f<sub>2</sub>) September of Y21\_SIT, the difference between Y21\_MUSHY and Y21\_RP for (g<sub>1</sub>) July, (h<sub>1</sub>) August, and (i<sub>1</sub>) September, and the difference between Y21\_SIT and Y21\_RP for (g<sub>2</sub>) July, (h<sub>2</sub>) August, and (i<sub>2</sub>) September.difference between Y21\_MUSHY and Y21\_RP for (a) July, (b) August, and (c) September.



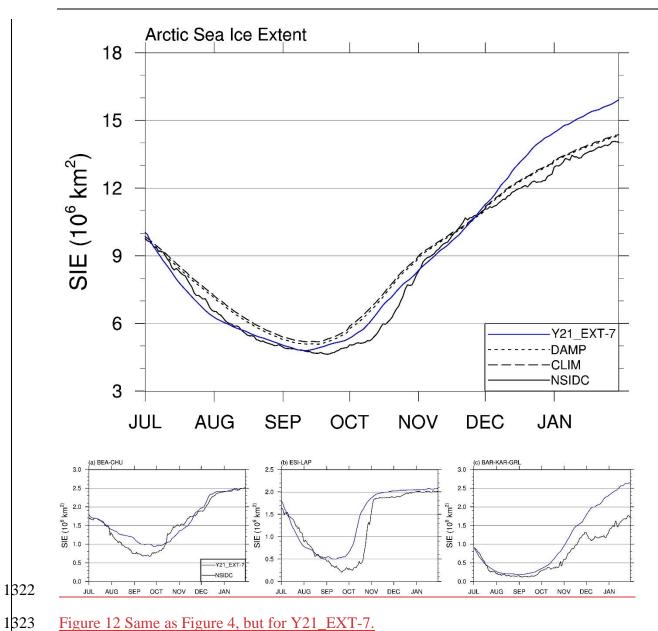


Figure 12 Same as Figure 4, but for Y21\_EXT-7.

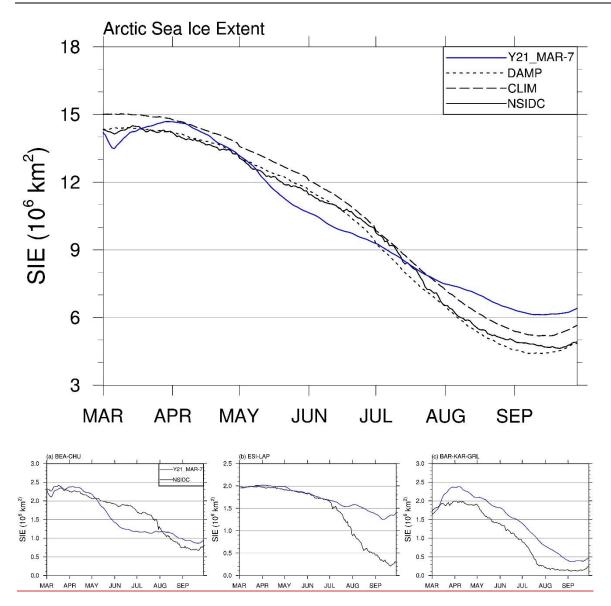


Figure 13 Same as Figure 3, but for Y21\_EXT 7.

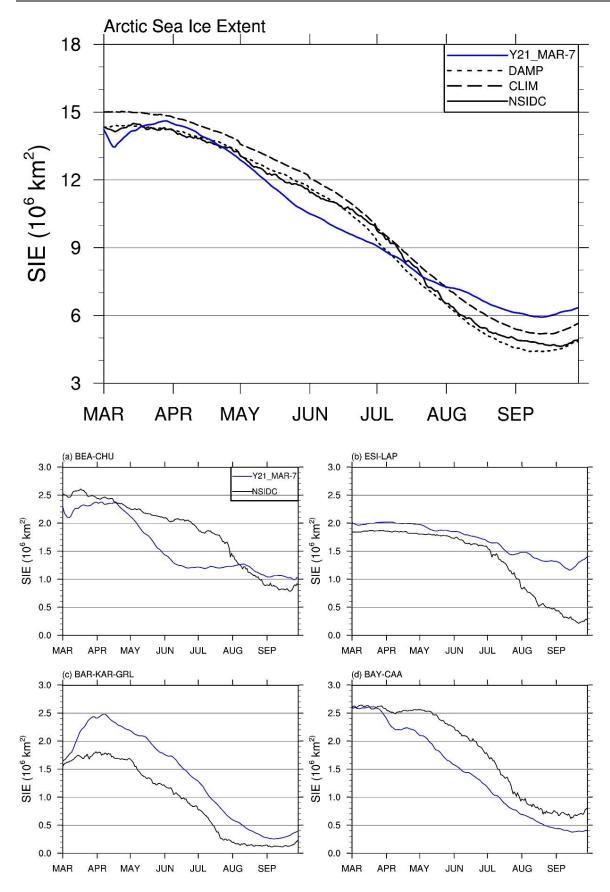


Figure 14 Same as Figure 34, bur for Y21\_MAR-7.