



A new methodological framework by geophysical sensors combinations associated with machine learning algorithms to understand soil attributes

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Abstract. Geophysical sensors combined with machine learning algorithms have been used to understand the pedosphere system, landscape processes and to model soil attributes. In this research, we used parent material, terrain attributes and data from geophysical sensors in different combinations, to test and compare different and novel machine learning algorithms to model soil attributes. Also, we analyzed the importance of pedoenvironmental variables in predictive models. For that, we collected soil physico-chemical and geophysical data (gamma-ray emission from uranium, thorium and potassium, magnetic susceptibility and apparent electric conductivity) by three sensors, gamma-ray spectrometer - RS 230, susceptibilimeter KT10 - Terraplus and Conductivimeter - EM38 Geonics) at 75 points and, we performed soil analysis afterwards. The results showed varying models with the best performance ($R^2 > 0.2$) for clay, sand, Fe₂O₃, TiO₂, SiO₂ and Cation Exchange Capacity prediction. Modeling with selection of covariates at three phases (variance close to zero, removal by correction and removal by importance), demonstrated to be adequate to increase the parsimony. The prediction of soil attributes by machine learning algorithms demonstrated adequate values for field collected data, without any sample preparation, for most of the tested predictors (R² ranging from 0.20 to 0.50). Also, the use of four regression algorithms proved important, since at least one of the predictors used one of the tested algorithms. The performances of the best algorithms for each predictor were higher than the use of a mean value for the entire area comparing the values of Root Mean Square Error (RMSE) and Mean Absolute Error (MAE). The best combination of sensors that reached the best model performance to predict soil attributes were gamma-ray spectrometer and susceptibilimeter. The most important variables were parent material, digital elevation model, standardized height and magnetic susceptibility for most predictions. We concluded that soil attributes can be





efficiently modelled by geophysical data using machine learning techniques and geophysical sensors combinations. The technique can bring light for future soil mapping with gain of time and environment friendly.

1 Introduction

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The pedosphere is composed by soils and their connections with hydrosphere, lithosphere, atmosphere and biosphere (Targulian et al, 2019). Soils are the result of several processes and factors and their interactions, which produces specific soils types or horizons. The main soil processes are weathering and pedogenesis (Breemen and Buurman, 2003; Schaetzl and Anderson, 2005), while the soil-forming factors are parent material, relief, climate, organisms and time (Jenny, 1994). Their interactions during soil genesis results in different soil attributes such as texture, mineralogy, color, structure, base saturation, clay activity and others.

In the last decades, there is a growing demand for soil resource information worldwide (Amundson et al., 2015; Montanarella et al., 2015). Soils are recognized as having a key influence on global issues such as, water availability, food security, sustainable energy, climate change and environmental degradation (Amundson et al., 2015; Pozza and Field, 2020). Understanding the role of spatial variations in surface and subsurface soil is fundamental for its sustainable use as well as other connected environmental resources and monitoring (Agbu et al., 1990). Therefore, it is necessary to increase the acquisition of information on the functional attributes of soils an ever-growing. To achieve this goal, relevant and reliable soil information, applicable from local to global scales is required (Arrouays et al., 2014).

The acquisition of soils data and their attributes are traditionally achieved by traditional soil survey techniques. However, new geotechnologies have emerged in the last decades, allowing the acquisition of data at shorter times, with non-invasive and accurate methods, such as reflectance spectroscopy, satellite imagery and geophysical techniques (Mello et al., 2020; Demattê et al., 2017, 2007; Fioriob, 2013; Fongaro et al., 2018; Mello et al., 2021; Terra et al., 2018a, 2018b). Among these technologies, geophysical sensors have been recently used in pedology to understand pedogenesis and the relationship between these processes and soil attributes (Son et al., 2010; Schuler et al., 2011; Beamish, 2013; McFadden and Scott, 2013; Sarmast et al., 2017; Reinhardt and Herrmann, 2019). Among these geophysical techniques used, we highlight the gamma-spectrometry, magnetic susceptibility (κ) and apparent electrical conductivity (ECa).

Gamma-ray spectrometry can be defined as the measurements of natural gamma radiation emission from natural emitters, such as K⁴⁰, the daughter radionuclides of U²³⁸ and Th²³², and total emissions from all elements in soils, rocks and sediments (Minty, 1988). It is known that weathering and pedogenesis concomitantly with geochemical behavior of each radionuclide determine their distribution and concentration in the pedosphere (Dickson and Scott, 1997; Wilford and Minty, 2006; Mello et al., 2021). Therefore gamma-ray spectrometry can provide important information for comprehension of soil processes and attributes (Reinhardt and Herrmann, 2019), soil texture (Taylor et al., 2002a), mineralogy (Wilford and Minty 2006;

65 Barbuena et al. 2013), pH (Wong and Harper, 1999) and organic carbon (Priori et al., 2016) and others.



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Soil magnetic susceptibility (κ) can be defined as the degree to which soil particles can be magnetized (Rochette et al., 1992). The κ is related to several pedoenvironmental factors, such as soil mineralogy, lithology and geochemistry of ferrimagnetic secondary minerals, mainly magnetite and maghemite (Ayoubi et al., 2018). Also, the κ parameter can be related to other soil secondary minerals, like ferrihydrite and hematite (Valaee et al., 2016). The great potential of this technique is related to geological studies (Shenggao 2000; Correia et al. 2010), soil texture and organic carbon studies (Camargo et al., 2014; Jiménez et al., 2017), soil survey (Grimley et al., 2004) and pedogenesis e pedogeomorphological processes (Viana et al., 2006; Sarmast et al., 2017; Mello et al., 2020).

Apparent electrical conductivity (ECa) is the ability of the soil to conduct electrical current, expressed in *millisiemens* per metre. This soil property is related to the presence/amount of solutes in soil solution, which concentration in 1 dS/m is equivalent to 10 meq/L (Richards, 1954). Concerning the geophysical methods consideration, the ECa is a geotechnology for identifying the soil physicochemical attributes and its spatial variation (Corwin et al., 2003). Many different soil attributes are related to the ECa such as soil salinity (Narjary et al., 2019), soil texture (Domsch and Giebel, 2004), cation exchange capacity (Triantafilis et al., 2009), mineralogy, pore size and distribution, temperature, soil moisture (McNeill, 1992; Rhoades et al., 1999; Bai et al., 2013; Farzamian et al., 2015; Cardoso and Dias, 2017).

Many sensors scan only the soil surface, disregarding the entire soil tridimensional profile (Xu et al., 2019). Therefore, a single sensor may not be able or be the best solution to quantify multiple soil attributes. In this context, the concept and use of multi-sensor data acquisition and analysis in a complementary way to offer more robust and accurate estimations of a number of soil attributes (Xu et al., 2019; Javadi et al., 2021). The analysis of soil data acquired by multiple sensors requires a careful interpretation and a mathematical model, which can be considered the base of observed variation and provides the basis for generalization, prediction and interpretation. (Heuvelink and Webster, 2001).

Recently, many models have been used to estimate soil attributes and their spatial distribution from geophysical data (gamma-ray, κ and ECa) and soil attributes, including machine learning algorithms, such as Support Vector Machine-SVM (Priori et al., 2014; Heggemann et al., 2017; Li et al., 2017; Leng et al., 2018; Zare et al., 2020), Random Forests (Lacoste et al., 2011; Viscarra Rossel et al., 2014; Harris and Grunsky, 2015; Sousa et al., 2020), KNN and artificial neural network (ANN) (Ã and Onjia, 2007) and Cubist (Wilford and Thomas, 2012).

According to Batty and Torrens, (2001), the bests models are those capable of explaining the same phenomena using the smallest number of variables without loss of performance, following the principle of parsimony - Occam's razor. This facilitates the understanding and the faster computer processing (Brungard et al., 2015). In this context, the Recursive Feature Elimination (RFE) algorithm may be used for backward selection of optimal subsets of variables, while maintaining a satisfactory model performance (Vašát et al., 2017; Hounkpatin et al., 2018).

Some of geophysical sensors are able to detect soil attributes in the upper soil layers (0–0.50m for gamma-ray by the RS230 model, 0.02m for magnetic susceptilimeter KT10 Terraplus model and 1.5m for conductivimeter by EM38 model, for example), which are explained by naturally occurring soil processes and soil factor forming (Mello et al., 2020; Mello et al., 2021). However, there is still a gap regarding the identification of the bests covariables and their possible combinations to

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deepen the knowledge of the soil weathering, genesis and their relation to soil attributes. A standard approach to selecting the bests input data to soil prediction models has yet to be developed (Levi and Rasmussen, 2014), mainly for geophysical sensors, little few used in soil science. The identification of such covariates may improve the understanding of the soil processes and attributes interplays, allowing an enhanced comprehension of soils from punctual to landscape scale, supporting digital soil mapping and better soil use and management.

Given this, the research aimed to: *i)* develop a new methodological framework on modelling soil attributes using combined data from three different geophysical sensors in five different sensors combinations; *ii)* using different machine learning algorithms for prediction and selection of suitable models for each soil attribute evaluated; *iii)* evaluating the results and the importance of the variables and relate to pedogeomorphological processes. Our main hypothesis is that the combined use of three geophysical sensors data affords a better prediction of soil attributes by different machine learning algorithms and better model performance. Also, this research can provide an important background for geoscience studies and improving geophysical and soil survey procedures.

2 Material and methods

2.1 Study area

The study area is located on a sugarcane farm of 184 hectares, located in São Paulo State, Brazil (23° 0' 31.37" to 22° 58' 53.97" S and 53° 39' 47.81" to 53° 37' 25.65" W), in the Capivari River catchment, part of the Paulista Peripheric Depression geomorphological unit (Fig. 1). The lithology is mainly composed by Paleozoic sedimentary rocks, dominant by Itararé formation (siltites/meta-siltites) crossed by intrusive diabase dykes of the Serra Geral Formation. The lowlands are covered by Quaternary alluvial sediments deposited by the Capivari River in ancient fluvial terraces (Fig. 2a).



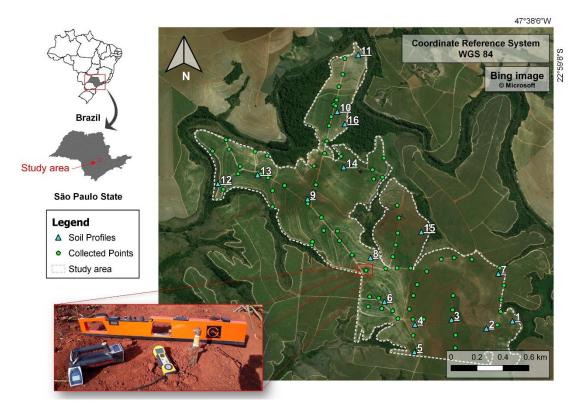


Figure 1. Study area, collected points and geophysical sensors. A - Gamma-ray spectrometer (Radiation Solution - RS 230); B - Susceptibilimeter (KT-10 Terraplus); C - Geonics Ground Conductivity Meter (EM 38).

The heterogeneity of landform and parent materials drove the formation of several soil types (**Fig. 2b**). Previous soil survey and mapping was performed in the study area by expert pedologists (Bazaglia Filho et al., 2013; Nanni and Demattê, 2006), in which the main soil classes mapped were: Cambisols, Phaeozems, Nitisols, Acrisols and Lixisols (IUSS Working Group WRB, 2015). Besides the soil profiles, 75 subsamples from 75 points (0 - 20 cm layer) were collected by augering for physicochemical analyses, according to **Figure 1**.





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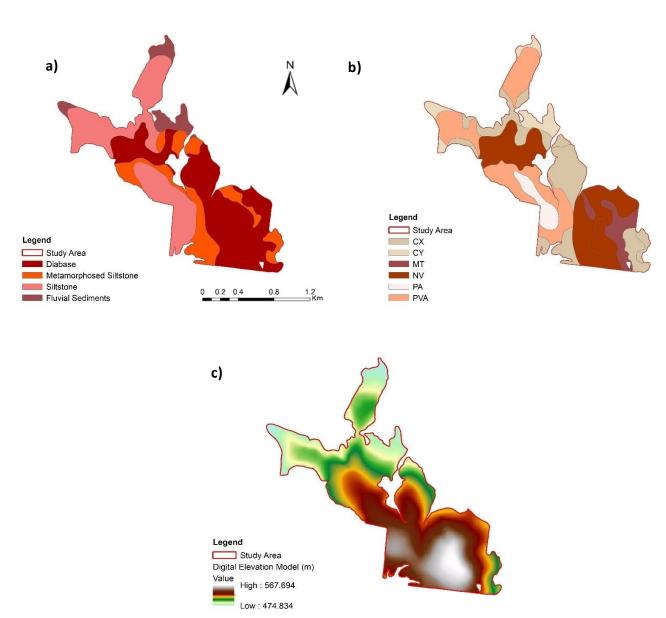


Figure 2. a) Geological compartments of landscape. b) Soil classes: CX: Haplic Cambisols, CY: Fluvic Cambisols, MT: Luvic Phaozem, NV: Rhodic Nitisol: PA: Xanthic Acrisol, PVA: Rhodic Lixisol. The geological and Soil classes maps were adapted from Bazaglia Filho et. al. (2012). d) Slope.c) Digital elevation model.



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According to the Köppen classification the region's climate is subtropical, mesothermal (Cwa), with an average temperature from 18 °C (July - Winter) to 22 °C (February - Summer), and mean annual precipitation between 1100 and 1700 mm (Alvares et al., 2013).

2.2 Laboratory physico-chemical analysis

For soil physical analyses, the soil samples were firstly air-dried, grounded and sieved to 2mm mesh and then, the granulometric analysis were performed. After that, clay, silt and sand contents were determined by the densimeter method (Camargo et al., 1986). Using the granulometry data, the textural groups were determined following EMBRAPA (2011), methodology.

The soil chemical analysis were performed: The exchangeable cations aluminium, calcium and magnesium (Al³⁺, Ca²⁺ and Mg²⁺) were determined by KCl solution (1 mol L⁻¹) and quantified by titration (Teixeira et al., 2017). Mehlich-1 solution were used to extract K⁺, which were quantified by flame photometry. Potential acidity (H⁺ + Al³) were determined using calcium acetate solution (0.5 mol L⁻¹) at pH 7.0 and, for the pH in water determination, the soil:solution ratio of 1:2.5 was used (Teixeira et al., 2017). More details about the analysis methods, can be found in (EMBRAPA, 2017). The determination of soil organic carbon was performed using the Walkley–Black method, by oxidation with potassium the method (EMBRAPA, 2017; Pansu, M., Gautheyrou, J., 2006). Total iron content were determined using selective dissolution by attack with sulfuric acid (EMBRAPA, 2017; Lim, C.H., Jackson, 1986). The resulting extract was used to determine the contents of silicon dioxide (SiO₂) and titanium dioxide (TiO₂) EMBRAPA (2017) methodology. All other chemical parameters such as: Base Sum (BS) Cation Exchange Capacity (CEC), Base Saturation (V%) and Aluminum Saturation (m%) were determined using the analytical data obtained previously, following the methodology (EMBRAPA, 2017). The same methodology for physico-chemical soil analysis was used by Mello et al., (2020); Mello et al., (2021).

2.3.1 Radionuclides and gamma-ray spectrometry data

The radionuclide K^{40} was quantified in total amount, measured by the absorption energy (1.46 MeV). The thorium (Th²³²) and uranium (U²³⁸) are quantified by absorption energy, (approximately 2.62 MeV and 1.76 MeV, respectively). This quantification is indirectly performed through thallium (Tl²⁰⁸) and bismuth (Bi²¹⁴) derived by radioactive decay, respectively for Th²³² and U²³⁸, which are used by expression eTh and eU (equivalent thorium and uranium respectively).

For soil gamma spectrometric characterization, we used the near-gamma-ray spectrometer (GM) model Radiation Solution RS 230 – Radiation Solution INC – Ontario - Canada (**Fig. 1A**). The sensor is able to quantify the radionuclides eTh and eU concentration in parts per million (ppm), while the K⁴⁰ is quantified in % due to its major content in pedosphere. Conventionally, the radionuclides are expressed in mg kg⁻¹ for eU and eTh, while for K⁴⁰ is used %. The GM detect the gamma-ray radiation emission down to 30 - 60cm depth, and varies mainly with soil bulk density and moisture content (Wilford et al., 1997; Taylor et al., 2002; Beamish, 2015).



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Firstly, the GM was automatically calibrated by switching on and leaving the sensor on the ground surface for five minutes until readings of eU, eTh and, K⁴⁰ contents be stabilized (Radiation Solutions, 2009). The measurements of radionuclides were taken in the "assay-mode" of highest precision for quantification, which the GM was kept at the soil surface for two minutes, in each sampling point (79 total collect points) (**Fig. 1**). The geographic position was taken by a GPS coupled in the GM (GPS – Radiation Solution INC – Ontario – Canada – precision of 1m). The collected data in all points were concatenated with their respective information from the soil physico-chemical analyzes for later geoprocessing. The same methodology for gamma-ray spectrometric data acquisition has been applied by Mello et al., (2021).

2.3.2 Magnetic susceptibility (κ)

For soil magneitic susceptibility (κ) characterization, surface readings were recorded at all 79 points using a geophysical susceptibility meter sensor (*KT10 – Terraplus*) (**Fig. 1b**). This sensor is able to measure κ to a depth of 2 cm below the soil surface, with a precision 10⁻⁶ SI units, expressed in m³ kg⁻¹. To perform the readings, the sensor was firstly calibrated by determining the frequency of the outdoor oscillator. Then, we followed the sequence required to obtain the measurements performed in three steps: 1- determine the frequency and amplitude of the oscillator in free air; 2 - The frequency and amplitude of the oscillator were measured with the coil placed directly on the soil surface (sample) outcrop; 3 – We repeated the step 1, and then the results were displayed. More information about the procedures see Sales, (2021). We performed the readings at *scanner mode*, which uses the best geometric correlation to direct κ readings, providing fast and accurate quantification. We performed three readings in triangulation around each augering/collected point and used the mean value of κ in all our analyses. This procedure was adopted to reduce noise. The same methodology for κ readings was performed by Mello et al., (2020).

2.3.3. Apparent electrical conductivity (ECa)

The ECa measurements was performed by the conductivity meter Geonics EM38 (Geonics Ltd., Mississauga, Ontario, Canada) (McNeill, 1986) (**Fig. 1C**). The EM38 provides measurement of the quad-phase (conductivity) without any requirement for soil-to-instrument contact (Geonics, 2002). The ECa measurements units are reported in mSm⁻¹.

Firstly, the EM38 was appropriately calibrated following the instructions of Heil and Schmidhalter, (2019), section 3.1.1. The values of the ECa are a function of calibration, coil orientation, and coil separation (Heil and Schmidhalter, 2019). More details about EM38 operation is discussed in Hendrickx and Kachanoski, (2002).

After calibration, the ECa readings were performed at all 75collection points (**Fig. 1**), using the EM38 at vertical dipole orientation, which provide data from effective soil depth at 1.5 m. The field incursions to collect the data were undertaken in dry season, bare soil and, at same hour interval during the day to reduce environmental variables influence. Also, all metal objects were kept distant from the EM 38 to avoid readings interferences.

Table 1. Terrain variables generated from the digital elevation model





Terrain attributes	Abbreviations	Brief description
Convergence index	CI	Convergence/divergence index in relation to runoff
Cross sectional curvature	CSC	Measures the curvature perpendicular to the down slope direction
Flow line curvature	FLC	Represents the projection of a gradient line to a horizontal plane
General curvature	GC	The combination of both plan and profile curvatures
Hill	НІ	Analytical hill shading
Hill index	HIINDEX	Analytical index hill shading
Longitudinal curvature	LC	Measures the curvature in the down slope direction
Mass balance index	MBI	Balance index between erosion and deposition
Maximal curvature	MAXC	Maximum curvature in local normal section
Mid-slope position	MSP	Represents the distance from the top to the valley, ranging from 0 to 1
Minimal curvature	MINC	Minimum curvature for local normal section
Multiresolution index of ridge top flatness	MRRTF	Indicates flat positions in high altitude areas
Multiresolution index of valley bottom flatness	MRVBF	Indicates flat surfaces at bottom of valley
Normalized height	NH	Vertical distance between base and ridge of normalized slope
Plan curvature	PLANC	Described as the curvature of the hypothetical contour line passing through a specific cell
Profile curvature	PROC	Describes surface curvature in the direction of the steepest incline
Slope	S	Represents local angular slope
Slope height	SH	Vertical distance between base and ridge of slope
Standardized height	STANH	Vertical distance between base and standardized slope index
Surface specific points	SSP	Indicates differences between specific surface shift points
Tangential curvature	TANC	Measured in the normal plane in a direction perpendicular to the gradient
Terrain ruggedness index	TRI	Quantitative index of topography heterogeneity
Terrain surface convexity	TSC	Ratio of the number of cells that have positive curvature to the number of all valid cells within a specified search radius
Terrain surface texture	TST	Splits surface texture into 8, 12, or 16 classes
Total curvature	TC	General measure of surface curvature

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Cont. table 1

Terrain attributes	Abbreviations	Brief description
Topographic position index	TPI	Difference between a point elevation with
Topograpme position maca	111	surrounding elevation
Valley depth	VD	Calculation of vertical distance at drainage
vaney depth	VD	base level
Vallev	VA	Calculation fuzzy valley using the Top Hat
vaney	VA	approach
Volley Index	VA	Calculation fuzzy valley index using the
Valley Index	VA	Top Hat approach
Tono anombio motorosa in Jon	TWI	Describes the tendency of each cell to
Topographic wetness index	TWI	accumulate water in relief

205 **2.3.5.** Modelling processing

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The modeling process is demonstrated in the flowchart (**Fig. 3**). The modeling can be divided into two parts: selection of covariates and training/test of the data. In the selection phase, the algorithm tries to produce the ideal set of covariates, following the principle of parsimony. This is performed by removing highly correlated variables, evaluating the importance of covariables and remove variables that have minor importance in training the model in the prediction process of each algorithm. Darst et al., (2018), considered joint application of the methods of selection of covariates by correlation and importance (RFE), since only the use RFE reduces the effect of highly correlated covariates, but does not eliminate it.





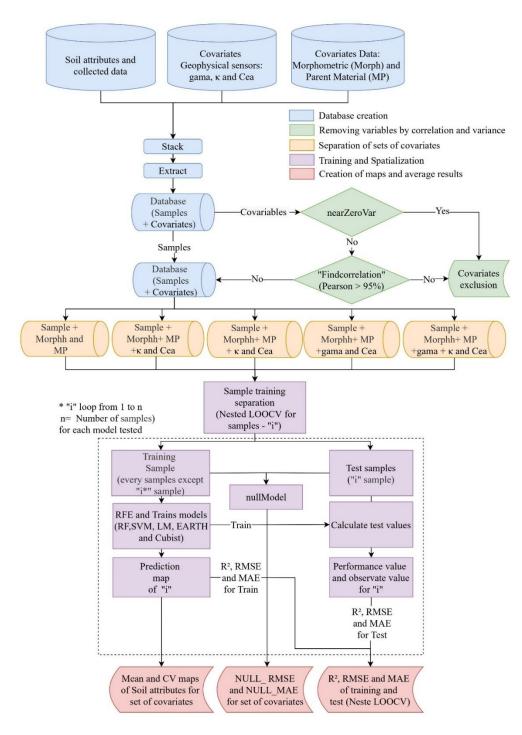


Figure 3. Methodological flowchart showing the sequence of methodologies applied for soil and geophysical attributes prediction. The most accurate model between Cubist, Random Forests (RF), Support Vector Machines (SVM), Earth and Linear Models (LM) was selected to model and map the geophysical and soil attributes maps.



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The correlation selection process was used to calculate the correlation of the set of covariates and covariables, which were evaluated with a correlation greater than the limit (Pearson test > 95%). The pairs that showed higher values are evaluated due to their correlation with the complete set of covariates, eliminating the one with the highest value of the sum of the absolute correlation with the other covariables that started in this process. For this phase we applied the *cor* and *find correlation* functions of the "*stats*" (Hothorn, 2021) and "*caret*" (Kuhn et al., 2020) packages, in *R* software, respectively (Kuhn and Johnson, 2013). In this phase, the covariables: curv_cross_secational and curv_longitudinal were eliminated for all tested sensor sets. The set of covariables that passed this phase joined the samples followed by the separation of samples from training and test.

The separation of training and test was performed using the "nested" leave one out (nested LOOCV) method (Clevers et al., 2007; Honeyborne et al., 2016; Rytky et al., 2020). It is important to highlight that our number of soil samples and readings with geophysical sensors is small (75), due to several difficulties encountered in the field in data collection (high sugar cane size, sloping terrain, dense forest, etc.). In this sense, the nested LOOCV method is indicated for small sample sets (values near 100 samples) to which other validation/test methods (as *holdout* validation) would not be viable due to the low sample set in the test and /or training group (Ferreira et al., 2021). This is one of the main innovations of this research.

The nested LOOCV method is a double loop process, where in the first loop the model is trained with a data set of size n-1, and the test is done in the second loop with the missing sample and used to validate the training performance (Jung et al., 2020; Neogi and Dauwels, 2019). The final result of the performance of the machine learning algorithm will be the mean performance indicators for all points (Training / test). This is a robust method to evaluate the performance of the algorithm and detects possible samples with problems in the collections or outliers. The training set generated in each loop went through the process of selecting covariates for importance and subsequent training.

The selection of covariates by importance is made using the *back forward* method using the Recursive Feature Elimination (RFE) function contained in the "caret" package (Kuhn and Johnson, 2013). The RFE is unique for each algorithm, the result being the set of selected covariates used in the prediction of the final model in the same algorithm. The RFE is a selection method that eliminates the variables that least contribute to the model, based on a measure of importance for each algorithm (Kuhn and Johnson, 2013). The algorithm will be applied to complete sets of data (variable by the set of tested sensors) and 18 more subsets 5,6,7, ... 19, 20 and 30 covariables. Reaching a set of fewer variables (more parsimonious), achieving better prediction performance. The optimization of the ideal covariate subset was based on leave one out (LOOCV), a repetition and 5 values of each of the internal hype parameters of each tested algorithm (*tuneLength*). The hyperparameters of each algorithm are described in the caret package manual in chapter 6. "Models described" available at https://topepo.github.io/caret/train-models-by-tag.html. The metric for choosing the best subset for each model were R². For this work, five algorithms were tested: Random Forests (RF), Cubist (C), Support Vector Machines (SVM), Generalized Linear Models (lm). The choice was made with the use of families of different algorithms in mind, and using linear and non-



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linear algorithms. The algorithms used are commonly used in soil attribute mapping studies. At the end of the selection phase by importance, the most optimized set of covariates for training was generated for each algorithm.

The training was performed with the variables selected in the previous step each tested algorithm by using leave one out (LOOCV) and ten repetitions. Five values of each of the internal hype parameters of each tested algorithm were also tested (tuneLength). At the end of the training phase, a sample prediction was made that was not used in the training and the result was saved for the performance study. The performance of the prediction of the algorithms and set of sensors was performed with a set of samples from the outer loop of the nested LOOCV method. Three evaluation parameters are used: R-square - R2 (Eq. (1)), root mean squared error - RMSE (Eq. (2)), mean absolute error - MAE, (Eq. (3)).

$$R^{2} = \frac{\left[\sum \left(\text{Qpred} - \overline{\text{Qpred}}\right) \times \left(\text{Qobs} - \overline{\text{Qobs}}\right)\right]^{2}}{\left[\sum \left(\text{Qpred} - \overline{\text{Qpred}}\right)^{2}\right] \times \left[\sum \left(\text{Qobs} - \overline{\text{Qobs}}\right)^{2}\right]}$$
(1)

$$RMSE = \sqrt{\frac{1}{n} \times \sum (Qobs - Qpred)^2}$$
 (2)

$$MAE = \frac{1}{n} \times \sum |Qpred - Qobs|$$
(3)

For comparison purposes, null model values (NULL_RMSE and NULL_MAE) were also calculated. The null model considers using the average value quantified by the collected samples (EQ. 4 and EQ. 5). This methodology is widely used and spatialization processes in kriging when the variable in which spatialization is desired has spatial dependence (pure nugget effect).

$$RMSE_NULL = \left[\frac{1}{N}\sum_{i=1}^{N} \left(\underline{Om} - O_i\right)^2\right]^{\frac{1}{2}}$$
 (EQ.4)

$$NULL_MAE = \frac{1}{n} \times \sum \left| Qtrain_i - Qobs_i \right|$$
 (EQ.5)

The NULL_RMSE and NULL_MAE values lower than those observed in the prediction of the algorithm in the validation phase show that the use of mean of the samples of the desired propriety consist with the model created by the algorithms of machine learning. The NULL_RMSE and NULL_MAE were calculated using the nullMode function of the caret package (Kuhn et al., 2020).





The final result of the performance of the algorithms of each attribute was made using the 75 loops, the training results being the average of the performance and the results of the test samples calculated from the 75 external loops results using equations 1, 2 and 3. The importance of the algorithms was calculated by the caret package (Kuhn and Johnson, 2013), each model presents its creation methodology. The final importance for each algorithm and attribute, was created from the importance created in the loop, being the average of the importance of the 75 repetitions.

3 Results

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3.1. Geophysical sensors combinations, models performance, uncertainty and covariates importance

The worst performance in modeling soil attributes occurred excluding the use of geophysical sensors, where only parent material and terrain attributes were used (**Table 2**). In this case, the algorithms selected particular groups of terrain attributes for modelling each soil attributes (**Table 1**).

Table 2. Models' performance for non-use geophysical sensors, for all soil attributes, based on R², RMSE, MAE and NULL_RMSE

Non-use of geophysical sensors										
		Clay	Sand	Fe ₂ O ₃	TiO ₂	SiO ₂	CEC	BS	ОМ	
	Random Forest	0.38	0.284	0.159	0.12	0.12	0.149	0.131	0.000	
R^2	Cubist	0.386	0.292	0.12	0.125	0.174	0.053	0.028	0.001	
К	SVM	0.259	0.278	0.279	0.226	0.128	0.195	0.113	0.004	
	LM	0.285	0.225	0.217	0.16	0.247	0.002	0.003	0.051	
	Random Forest	136.778	185.398	61.686	12.229	41.701	41.3	20.206	8.469	
	Cubist	140.103	192.867	66.432	12.424	41.323	50.065	22.853	8.126	
RMSE ²	SVM	154.406	190.151	59.453	11.621	42.595	41.141	20.396	8.045	
	LM	156.646	215.355	66.357	13.118	38.976	997.529	1189.64	7.702	
	NULL_RMSE	140.885	176.521	53.341	10.239	35.450	36.139	17.142	6.158	
	Random Forest	110.485	149.205	40.742	8.206	31.757	28.931	16.3	6.357	
	Cubist	108.284	148.8	44.028	8.294	31.715	33.168	18.271	4.813	
MAE	SVM	122.397	147.07	36.812	7.051	31.432	27.072	17.012	5.992	
	LM	119.139	169.218	43.673	8.749	29.458	149.114	158.638	5.719	
	NULL_MAE	119.751	153.803	41.578	8.074	29.534	27.187	14.425	4.813	
					Low		М	edium		

The Cubist algorithm showed the best performance to predict soil texture, clay (R^2 of 0.386) and sand (R^2 of 0.292) content, with the highest R^2 and lowest RMSE and MAE, concomitantly (**Table 2**). The importance of covariates to sand content



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prediction showed that minimal curvature, was the most important variable, contributing 100% on the decreasing of the mean accuracy. On the other hand, for clay content the most important variable was parent material. In addition, for clay and sand the tangential curvature and DEM showed importance higher than 50% (**Fig. 4**).

The SVM algorithm presented moderate performance, for Fe_2O_3 (R^2 0.279), TiO_2 (R^2 0.226); whereas for SiO_2 , the LM presented the best result, also with a moderate performance (R^2 0.247) (**Table 2**). The selected models presented the highest R^2 and lowest RMSE and MAE, simultaneously. The most important covariates for Fe_2O_3 and TiO_2 prediction by the SVM model, were parent material (100%) and DEM (more than 50%). For SiO_2 prediction by LM model, the most important covariates were DEM (100%) and standardized height (90%), while parent material contributed with 40% (**Fig. 4**).

For cation exchange capacity (CEC) the model with the best performance, after 75 runs was SVM, (R^2 of 0.223) (**Table 2**). The most important covariates for CEC prediction to mean accuracy were DEM (100%), topographic wetness index (80%) and parent material (75%) (**Fig. 4**).



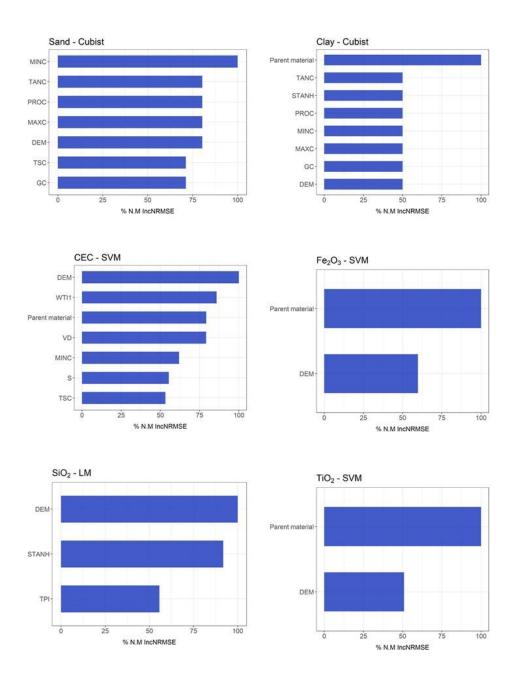


Figure 4. Variable Importance for *Non-use of geophysical sensors* (only variables that contributed more than 50% are presented here (for further details see supplementary material).





In all models, there was a very low performance in the prediction of base saturation (BS) and organic matter (OM), with R² between 0.001 and 0.1 (**Table 2, 3, 4, 5 and 6**).

The different combinations of geophysical sensors that contributed to moderate modeling performance of soil attributes were: Susceptibilimeter + Conductivimeter (S + C), Gamma-ray spectrometer + Conductivimeter (G + C), Combined use of the three geophysical sensors (G + S + C) (**Tables 3, 4 and 6,** respectively). The R^2 values presented some variation between the R^2 of best combination of geophysical sensors and the lowest R^2 values from the without the use geophysical sensors in predictive models (**Tables 3, 4 and 6**). Among all the values of R^2 evaluated for this session, we consider all the highest values and, among the highest values the lowest values we considered the worst result.

Table 3. Models' performance for combined use of susceptibilimeter and conductivimeter, for all soil attributes, based on R², RMSE, MAE and NULL_RMSE

		Su	sceptibili	meter + C	onductivi	meter			
		Clay	Sand	Fe ₂ O ₃	TiO ₂	SiO ₂	CEC	BS	ОМ
R ²	Random Forest	0.444	0.334	0.314	0.316	0.141	0.139	0.138	0.032
	Cubist	0.433	0.365	0.407	0.338	0.25	0.178	0.079	0.077
	SVM	0.484	0.322	0.153	0.263	0.169	0.223	0.065	0.039
	LM	0.394	0.312	0.383	0.262	0.101	0.124	0.002	0.056
	Random Forest	129.619	178.22	55.378	10.531	41.116	41.878	19.821	8.079
	Cubist	136.834	178.253	52.416	10.583	39.138	41.91	21.543	7.494
RMSE ²	SVM	127.598	181.811	64.573	11.052	42.22	40.134	22.307	7.924
	LM	139.463	190.515	54.36	11.622	46.013	48.52	1219.091	8.007
	NULL_RMSE	140.885	176.521	53.341	10.239	35.450	36.139	17.142	6.158
	Random Forest	102.841	145.441	34.357	6.457	30.54	29.354	15.824	5.949
	Cubist	105.12	139.737	32.246	6.593	28.954	28.912	17.372	5.713
MAE	SVM	92.812	146.016	40.303	6.65	31.153	26.689	18.953	6.108
	LM	106.083	153.815	36.79	8.199	33.218	33.024	161.284	6.04
	NULL_RMSE	119.751	153.803	41.578	8.074	29.534	27.187	14.425	4.813

Low Medium High

Clay and sand content in g.kg⁻¹; Fe₂O₃, TiO₂ and SiO₂ in g.kg⁻¹ CEC in mmol_c dm⁻³; Abbreviations: CEC: Cation Exchange Capacity; OM g.dm⁻³; BS: mmolc dm⁻³.

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Table 4. Models' performance for combined use of gamma-ray spectrometer and conductivimeter, for all soil attributes, based on R², RMSE, MAE and NULL_RMSE

	Gamma-ray spectrometer + Conductivimeter									
		Clay	Sand	Fe ₂ O ₃	TiO ₂	SiO ₂	CEC	BS	ОМ	
	Random Forest	0.378	0.318	0.22	0.248	0.16	0.14	0.133	0.001	
R^2	Cubist	0.433	0.265	0.282	0.189	0.163	0.077	0.065	0	
ĸ	SVM	0.406	0.3	0.158	0.048	0.17	0.241	0.068	0.059	
	LM	0.338	0.188	0.249	0.171	0.178	0.002	0.003	0.047	
	Random Forest	137.097	179.808	58.829	11.011	40.256	41.464	19.889	8.567	
	Cubist	134.231	197.657	56.918	12.026	42.209	47.809	21.704	8.356	
RMSE ²	SVM	134.035	182.644	61.758	13.076	40.493	40.463	21.586	7.72	
	LM	146.116	225.909	62.442	13.035	41.555	1499.11	33.64	7.738	
	NULL_RMSE	140.885	176.521	53.341	10.239	35.450	36.139	17.142	6.158	
	Random Forest	108.636	145.511	38.867	7.265	31.095	28.539	15.812	6.443	
	Cubist	105.954	160.722	37.335	8.241	32.419	33.06	17.471	6.07	
MAE	SVM	106.779	148.469	39.185	8.197	32.189	26.449	17.325	5.578	
	LM	117.816	181.07	42.121	9.198	32.035	207.159	24.294	5.806	
	NULL_RMSE	119.751	153.803	41.578	8.074	29.534	27.187	14.425	4.813	
					Low Medium					

Clay and sand content in $g.kg^{-1}$; Fe_2O_3 , TiO_2 and SiO_2 in $g.kg^{-1}CEC$ in $mmol_c dm^{-3}$; Abbreviations: CEC: Cation Exchange Capacity; OM $g.dm^{-3}$; BS: $mmolc dm^{-3}$.

For clay, the model with the best performance was the SVM algorithm (R^2 0.484) by S + C (**Table 3**), while the worst was by the Cubist algorithm (R^2 0.38) by (G + S + C) (**Table 6**). For sand, the best model performance was the Cubist algorithm (R^2 0.365) by S + C (**Table 3**) and the worst also by Cubist (R^2 0.387) by (G + S + C). The most important covariates for clay prediction by the SVM model in S + C sensors combination were magnetic susceptibility (κ) (100%) and parent material (90%) (**Fig. 5**). For clay prediction by the Cubist model in G + S + C sensors combination, the most important covariate was parent material (100%) (**Fig. 6**). With respect to sand prediction, the most important covariates by the Cubist model in S + C were minimal curvature (100%) and magnetic susceptibility (κ) (80%) (**Fig. 5**) On the other hand, for G + S + C, the covariates that most contributed for sand prediction were DEM (100%), general curvature (80%) and minimal curvature (75%) (**Fig. 6**).



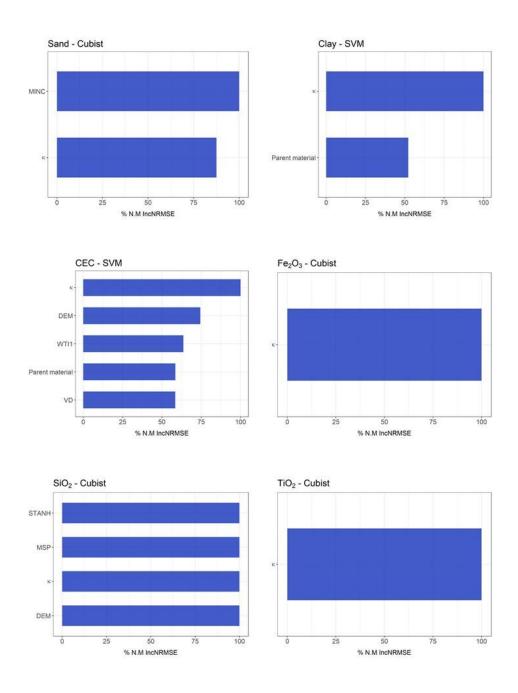


Figure 5. Variable Importance for *Susceptibilimeter + Conductivimeter sensors* (only variables that contributed more than 50% are presented here (for further details see supplementary material).





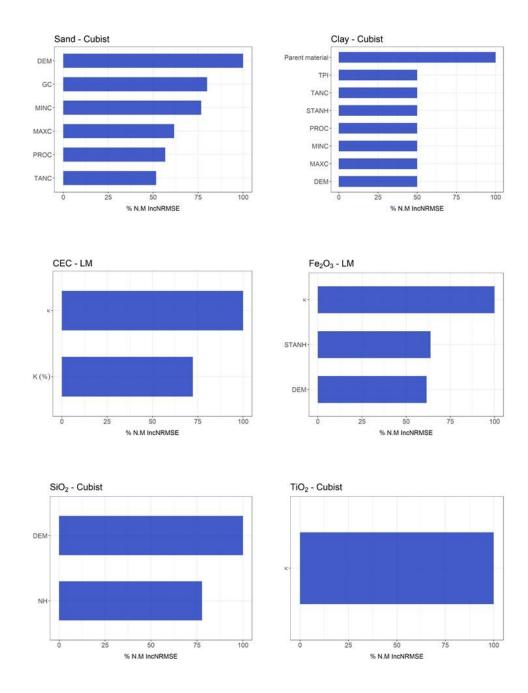


Figure 6. Variable Importance for *Combined use of the three geophysical sensors* (only variables that contributed more than 50% are presented here (for further details see supplementary material).



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For the elemental composition, the models employed greatly variable performance. For Fe₂O₃ the best model performance, was reached by the LM algorithm (R^2 0.441) by G + S + C (**Table 6**), while the worst performance was by the Cubist (R^2 0.282) by G + C (**Table 4**). With respect to TiO₂, the best model performance was by Cubist algorithm (R² 0.358) by G + S 350 + C (Table 6) and the worst was RF (R² 0.248) by G + C (Table 4). For SiO₂, the best model performance was the Cubist algorithm (\mathbb{R}^2 0.250) by S + C (Table 3) and the worst was the LM (\mathbb{R}^2 0.178) by G + C (Table 4). The importance of covariates in predicting Fe₂O₃ by LM in G + S + C, demonstrated that magnetic susceptibility (κ), standardized height and DEM were the most important variables, contributing 100%, 65%, 55%, respectively (Fig. 6). For Fe₂O₃ predicted by the 355 Cubist algorithm by G + C, the most important covariates were standardized height, parent material, ECa and DEM (100%) (Fig. 7). For TiO_2 prediction by the Cubist algorithm by G+S+C the most important covariate was magnetic susceptibility (κ) (100%) (**Fig. 6**), while for the RF algorithm by G + C were parent material (100%) and ECa (75%) (**Fig. 7**). In relation to SiO_2 prediction by the Cubist by S + C, the most important covariates were standardized height, mid-slope position magnetic susceptibility (κ) and DEM (100%) (Fig. 5), while SiO2 predicted by the LM algorithm by G + C were DEM and standardized height (100% and 65%, respectively) to mean accuracy (Fig. 7).



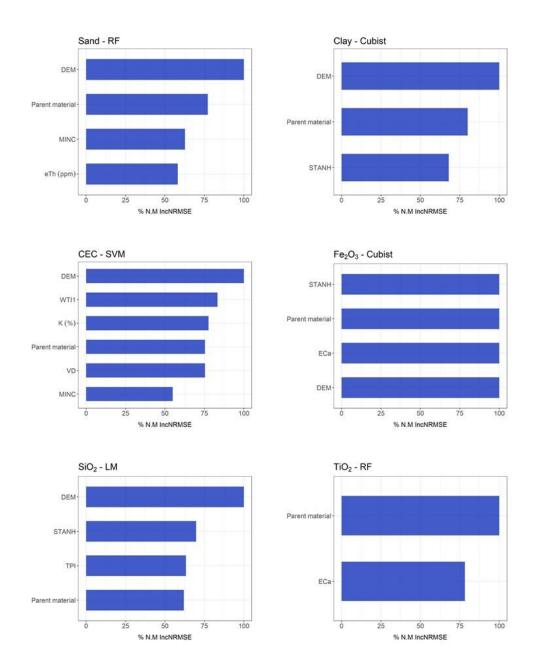


Figure 7. Variable Importance for *Gamma-ray spectrometer* + *Conductivimeter sensors* (only variables that contributed more than 50% are presented here (for further details see supplementary material).





In relation to CEC, the LM algorithm was the best model (R^2 0.317) by G + S + C (**Table 6**) and the worst was the SVM algorithm (R^2 0.223) by S + C (**Table 3**). The most important covariate for prediction of CEC by LM algorithm by G + S + C and by S + C was magnetic susceptibility (κ) (100%) (**Fig. 6 and 5**).

Overall, the best combination of geophysical sensors, which allowed the best model performance for different algorithms in the prediction of soil attributes, was Gamma-ray spectrometer + Susceptibilimeter (G + S) (**Table 5**).

Table 5. Models' performance for combined use of gamma-ray spectrometer and susceptibilimeter, for all soil attributes, based on R², RMSE, MAE and NULL_RMSE

Gamma-ray spectrometer + Susceptibilimeter										
		Clay	Sand	Fe ₂ O ₃	TiO ₂	SiO ₂	CEC	BS	ОМ	
	Random Forest	0.465	0.422	0.36	0.308	0.159	0.147	0.169	0.046	
_2	Cubist	0.441	0.152	0.426	0.282	0.207	0.152	0.082	0.033	
R ²	SVM	0.494	0.367	0.096	0.284	0.169	0.296	0.112	0.028	
	LM	0.366	0.233	0.47	0.328	0.167	0.303	0.002	0.034	
	Random Forest	127.149	165.624	53.418	10.724	40.898	41.902	19.294	7.800	
	Cubist	132.977	244.635	52.737	11.37	40.244	44.296	21.318	7.842	
RMSE ²	SVM	123.84	175.35	67.759	10.846	42.207	38.723	20.856	7.81	
	LM	148.11	202.104	48.513	10.659	42.993	37.645	1024.32	8.131	
	NULL_RMSE	140.885	176.521	53.341	10.239	35.450	36.139	17.142	6.158	
	Random Forest	102.229	134.525	33.284	6.548	30.394	28.977	15.597	5.805	
	Cubist	105.123	168.957	32.411	6.573	29.691	30.945	17.321	5.836	
MAE	SVM	97.173	140.318	42.282	6.447	30.396	25.376	16.96	5.966	
	LM	117.097	166.083	33.124	7.049	32.951	25.815	137.422	6.262	
	NULL_RMSE	119.751	153.803	41.578	8.074	29.534	27.187	14.425	4.813	
					Low		М	edium		

Clay and sand content in g.kg⁻¹; Fe₂O₃, TiO₂ and SiO₂ in g.kg⁻¹ CEC in mmol_c dm⁻³; Abbreviations: CEC: Cation Exchange Capacity; OM g.dm⁻³; BS: mmolc dm⁻³.



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Table 6. Models' performance for all combined use of geophysical sensors, for all soil attributes, based on R², RMSE, MAE and NULL RMSE

Combined use of the three geophysical sensors									
		Clay	Sand	Fe ₂ O ₃	TiO ₂	SiO ₂	CEC	BS	ОМ
	Random Forest	0.356	0.318	0.281	0.322	0.162	0.171	0.122	0.003
R^2	Cubist	0.387	0.322	0.406	0.358	0.212	0.266	0.097	0.073
ĸ	SVM	0.331	0.278	0.309	0.267	0.21	0.246	0.107	0.002
	LM	0.258	0.129	0.441	0.252	0.125	0.317	0.002	0.047
	Random Forest	139.61	180.339	57.225	10.472	40.642	41.451	19.951	8.234
	Cubist	139.41	188.745	52.66	10.547	40.534	39.226	21.749	7.569
RMSE ²	SVM	144.532	189.768	57.589	11.053	40.355	39.815	21.178	8.134
	LM	160.894	256.078	50.038	11.499	43.949	37.134	1045.896	7.752
	NULL_RMSE	140.885	176.521	53.341	10.239	35.450	36.139	17.142	6.158
	Random Forest	112.126	143.98	35.597	6.414	30.215	29.014	15.887	6.223
	Cubist	108.346	145.661	32.751	6.541	30.197	27.169	17.694	5.854
MAE	SVM	117.645	145.187	35.387	6.7	30.001	26.201	17.025	5.945
	LM	120.83	198.059	34.724	8.102	33.649	25.273	140.716	5.798
	NULL_RMSE	119.751	153.803	41.578	8.074	29.534	27.187	14.425	4.813
					Low		M	edium	

Clay and sand content in g.kg⁻¹; Fe₂O₃, TiO₂ and SiO₂ in g.kg⁻¹ CEC in mmol_c dm⁻³; Abbreviations: CEC: Cation Exchange 390 Capacity; OM g.dm⁻³; BS: mmolc dm⁻³.

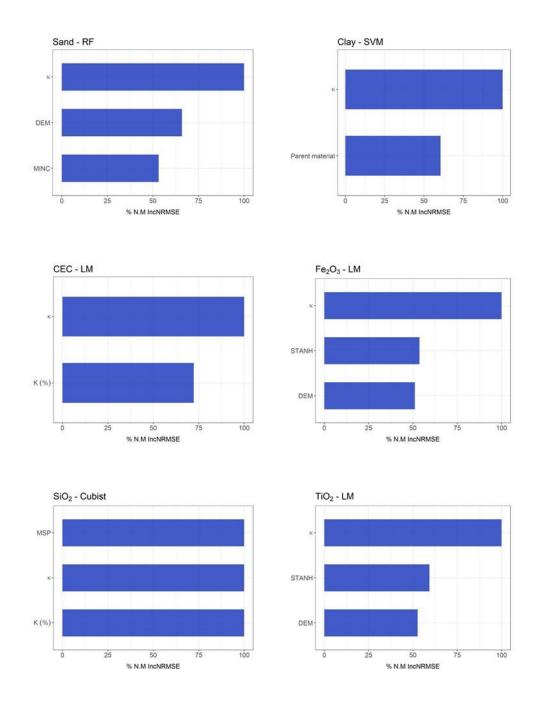
For soil texture, the SVM and RF algorithms, showed the best performance for clay (R^2 0.494) and sand (R^2 0.422), respectively, by G + S, with the highest R^2 and lowest RMSE and MAE, simultaneously (**Table 5**). The importance of covariates in predicting soil texture by the SVM (for clay) and the RF (for sand) demonstrated that, magnetic susceptibility (κ) was the most important covariate (100%). In addition, parent material contributed 60% for clay prediction and DEM 60% for sand prediction (**Fig. 8**).

The LM algorithm presented the best performance for Fe_2O_3 (R^2 0.470) and TiO_2 (R^2 0.328), by G + S, while for SiO_2 was the Cubist algorithm (R^2 0.207), also by G + S (**Table 5**). The most important covariates for Fe_2O_3 and TiO_2 prediction by LM by G + S were magnetic susceptibility (κ) and standardized height (100% and 60%, respectively for both) (**Fig. 8**). For SiO2 prediction by the Cubist by G + S, the most important covariates were mid-slope position and magnetic susceptibility (κ) (100% for both) (**Fig. 8**).

For CEC, the best model performance was the LM algorithm (R^2 0.303) by G + S (**Table 5**). In this case, the covariates that most contributed to model prediction were magnetic susceptibility (κ) (100%) and DEM (60%) (**Fig. 8**).







405 **Figure 8.** Variable Importance for *Gamma-ray spectrometer + Susceptibilimeter sensors* (only variables that contributed more than 50% are presented here (for further details see supplementary material).





4 Discussion

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4.1. Geophysical sensors combinations, models performance and uncertainty

410 The methodological approach optimized the prediction of soil variables by applying different geophysical sensors combination, parent material and terrain attributes for selecting covariates and models, as well as for assessing prediction uncertainty.

In general, without the use of geophysical sensors the poorest results were obtained, in terms of R², RMSE and MAE, for all the prediction algorithms used for modeling soil attributes (**Table 2**). These results are consistent with Frihy et al., (1995) who also compared combined use and the non-use of sensors to model geochemical attributes of soil by the Cubist algorithm and obtained the worst result without using the sensors. The worst performance of the models can be attributed to a very complex interaction between soil forming factors and processes, determining soil attributes (Jenny, 1994).

The moderate performance of the models can be attributed to the different combinations of the geophysical sensors pairwise, and the different data presented by the sensors contributed in different ways to the modelling process. In this concern, O'Rourke et al., (2016) also demonstrated a moderate performance of the models (R² ranging from 0.21 to 0.94) when using data from the VisNir and, with R² ranging from 0.61 to 0.94, when using XRF sensor, to model soil attributes. The explanation can be related to correlations of different data provided by different sensors and, their relation with soil attributes.

The best combination of geophysical sensors was Gamma-ray spectrometer + Susceptibilimeter (G+S), with the highest values of R² and lowest values of RMSE and MAE, concomitantly, among all combinations of geophysical sensors and algorithms used in the modeling processes (**Table 5**). Probably the explanation lies in the fact that the gamma-ray spectrometer and susceptibilimeter are more closely associated with pedogenesis, pedogeomorphology and soil attributes, as recently demonstrated by Mello et al. (2020); Mello et al. (2021), who modeled soil attributes such as texture, Fe₂O₃, TiO₂, SiO₂ and CEC in relation to Thorium, Uranium and Potassium (K⁴⁰) levels and magnetic susceptibility.

In general, the Cubist algorithm was the best model for clay and sand content prediction, (**Table 7**). Similar results were found by Greve and Malone, (2013); Ballabio et al., (2016); Nawar et al., (2016) and Silva, (2019) who used the Cubist and Earth algorithm to predict soil texture using different data source (3D imagery, Land Use and Cover Area frame Statistical survey and reflectance spectroscopy), reaching satisfactory performance. In all of these models the R² was not greater than 0.5 in all cases. The probable explanation is the small variation or limited distribution of the data set, which caused a poor prediction in the modeling. Zhang and Hartemink, (2020), states that textural classes with fewer samples presented more unstable prediction performances than those with more samples, which agree with our results.



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Table 7. Number of times that each model achieved the best performance for each soil attribute

C -: 1 44: 14	R^2							
Soil attributes	Random Forest	Cubist	SVM	LM				
Clay		3	2					
Sand	2	3						
Fe_2O_3		2	1	2				
TiO_2	1	2	1	2				
${f SiO_2}$		3		1				
CEC			3	2				

Clay and sand content in g.kg⁻¹; Fe₂O₃, TiO₂ and SiO₂ in g.kg⁻¹CEC in mmol_c dm⁻³; Abbreviations: CEC: Cation Exchange Capacity

The better model performance for elemental composition (Fe₂O₃, TiO₂ and SiO₂) was the Cubist (**Table 7**) with a R² (0.2 – 0.47). This is contrasting with results obtained by Henrique et al., (2018), who showed that the best models for predicting soil mineralogy Fe₂O₃ and TiO₂ (R² 0.89 and 0.96, respectively) and RF only for Fe₂O₃ (R² 0.95) by pXRF was the simple linear regression. The R² variation in our results for G + S combination is probably related to low correlation with parent material and consequently with soil mineralogy, or to the low representativeness by the limited number of samples, and high soil variability (Fiorio, 2013). However, it is important to highlight that in-situ have many intrinsic environmental influences that can interfere in modelling processes. It can justify the low R² values obtained. For soil mineralogical attributes predicted by machine learning algorithms, results can be classified as satisfactory from 0.2 to 0.5, as for preliminary evaluation, since these values present more informative results (Beckett, 1971; Dobos, 2003; Malone et al., 2009). According to Nanni and Demattê (2006), the R² may be explained by standardized laboratory conditions during their determination, which have less environmental interference compared with direct field methods.

For CEC the best model performance was SVM (R² 0.296) (**Table 5**). This results is corroborated by Liao et al., (2014), who compared the models performance of multiple stepwise regression, artificial neural network models and SVM for CEC prediction, and attributed their results to a nonlinear relationship between CEC and soil physicochemical properties. In addition, other study (Jafarzadeh et al., 2016) demonstrated that, despite of the ability of SVM to predict CEC in acceptable limits, there is a poor performance in extrapolating the maximum and minimum values of CEC data. Despite this, uncertainties estimated for SVM predictions may not be associated with an incorrect classification. As pointed out by Cracknell and Reading, (2013).

Even for the best combination of sensors (G + S) and the overall models' performance, the R^2 values were not greater than 0.5 (**Table 5**). Models generated by field data, without sample preparation, R^2 values varying between 0.20 - 0.50 can be considered satisfactory and reliable results (Dobos, 2003; Malone et al., 2009). In our study, low R^2 values can be related to



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the limited number of collecting points or field distribution, which does not represent the spatial variation of soil attributes, in agreement with Johnston et al. (1997) and Lesch et al. (1992), who evaluated soil salinity.

The best results for predictors of soil attributes through geophysical data, have the lowest values when compared to the values of NULL_RMSE and NULL_MAE. This demonstrates that the use of machine learning models has lesser errors than the use of means values for the entire area (**Table 5**) so that it shows better performance and accuracy.

There are little studies using NULL_RMSE and NULL_MAE as parameters for model evaluation and decision making. These values can be used to evaluate the performance of the models. Algorithms that have RMSE and MAE values greater than the values found in the NULL method, perform less than the use of the mean value for the entire area. The values of NULL_RMSE and NULL_MAE can be used concurrently with kriging to evaluate the performance of the models. However, we could not apply ordinary kriging in our case because the most predictors did not have spatial dependence (pure nugget effect), as demonstrated by Mello et al., (2021).

4.1.2 Variables importance, models performance and pedogeomorphology

In general, for all geophysical sensor combinations, the majority of terrain attributes used did influence significatively sand and clay content prediction (**Fig. 4, 5, 6 and 8**). However, in most cases parent material and magnetic susceptibility strongly influences clay content prediction, except for G + C (**Fig. 7**). Ließ et al. (2012) found that the best performance was by the RF model with altitude and overland flow distance strongly affecting the model performance. According to Bauer (2010), the greater relation sand/clay ratio upslope is explained by selective transport of fine material downslope, whereas in the present study, clay content increased by the influence of parent material (diabase) as demonstrated by Mello et al. (2020).

The magnetic susceptibility (κ), followed by DEM and parent material were key the variables that contributed to sand and clay content prediction by RF and SVM, respectively for G + S (**Fig. 8**). Siqueira et al. (2010) and Mello et al. (2020) found a positive correlation between soil magnetic susceptibility and clay content and a negative correlation between magnetic susceptibility and sand content. In fact, the mineralogical composition of parent material strongly affects soil magnetic susceptibility (Ayoubi et al., 2018), mainly in tropical soils under top of basalt spills (Da Costa et al., 1999), where our study was undertaken.

In general, for Fe_2O_3 and TiO_2 the most important variables were parent material, magnetic susceptibility and DEM, which in most cases contributed 100% (**Fig. 4, 5, 6, 7 and 8**). In fact, the mineralogical composition of the parent material and pedoenvironmental conditions strongly influences the amount of Fe/Ti oxides in soils (Schwertmann and Taylor, 1989; Kämpf and Curi, 2000; Bigham et al., 2002), and faster redistributed by erosion downslope (Mello et al., 2020). Also, the mineralogical composition of parent material (Mullins, 1977; Ayoubi et al., 2018) and landform evolution (Blundell et al., 2009; Sarmast et al., 2017) controls the magnetic susceptibility of soil. Since the sensors used record the surface response and topography effect, it is expected that the most important variables indicated by the models would be related to surface processes. For the best combination of sensors (G + S), magnetic susceptibility and standardized height were more important variables in the prediction of Fe₂O₃ (100%) and TiO₂ (55%) contents (**Fig. 8**), corroborating the expected surface processes



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and materials in the magnetic susceptibility of the soil (Shenggao, 2000; Damaceno et al., 2017) and the relief in the distribution of these materials (De Jong et al., 2000).

For SiO_2 , the most important variable was DEM which in most of cases contributed 100% (**Fig. 4, 5, 6 and 7**). The levels of SiO_2 in soil is directly related to the nature of parent material and erosion processes at different topographic positions at the landscape (Bockheim et al., 2014; Breemen and Buurman, 2003). This can explain the greater contribution of the DEM in the prediction models. For the best sensor combination (G + S), the variable that most contributed was mid-slope position, which also is related to topographic features.

For CEC, the variables DEM and magnetic susceptibility were the most important, contributing 100% in most of cases (**Fig. 4, 5, 6, 7 and 8**). This can be explained by the high correlation between magnetic susceptibility and clay content, and that with CEC (Siqueira et al., 2010; de Souza Bahia et al., 2017; Mello et al., 2020). They vary with parent material and surface geomorphic processes, concentrating the rich ferrimagnetic minerals (Frihy et al., 1995; Mello et al., 2020).

Considering that the gamma spectrometer sensor is composed of three channels (eU, eTh and K^{40}), we can call it "three sensors". Thus, considering the combination of sensors used, it is possible to create a performance graph of the modeling by the number of sensors used through learning curves (**Fig. 9**). A learning curve shows a measure of predictive performance of a given domain as a function of some measure of varying amounts of learning effort (Perlich, 2010). In our case, the varying amounts were the number of sensors: non-use of geophysical sensors (0 sensors), S + C (2 sensors), G + S (4 sensors) and G + C (5 sensors). In this analysis, the combination of G + C sensors will not be used because they present the same number of G + S sensors (4 sensors). However, the combination G + C presented lower results than those for G + S.

The results show that for 5 soil properties (clay, sand, CEC, Fe₂O₃ and SiO₃), the best results did not occur with a greater number of sensors, showing that increasing number of covariables can lead to lower performance (**Fig. 9**). This fact is associated with the addition of a new sensor as a covariate that may be leading to conflicting information to the set of other sensors found, where the ECa may have presented conflicting values with the sensors generated by the gamma spectrometry channels, which generates a loss of performance when with sensor sets together. The application of the RFE importance selection method was able to amortize this, being a reliable method to reduce this effect.



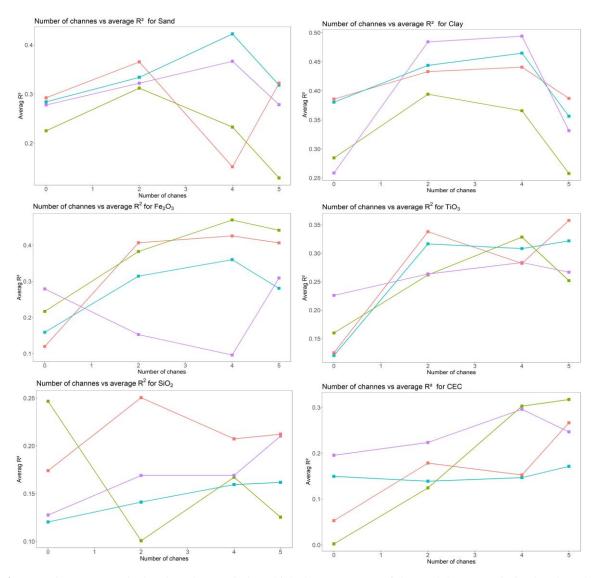


Figure 9. Learning curves calculated on the metric by which the parameters of the model were optimized and on the metric by which the model was evaluated and selected. The most common form of learning curves in the general field of machine learning shows predictive accuracy on the test examples as a function of the number of training examples (Perlich, 2010).

4.1.3 General evaluation

For this study, the independent RMQS data set was not large enough (75 sites). So, validation using 74 sites provided erratic and inconsistent results, mainly when compared different pedoenvironmental indicators, even considering that this dataset, in theory, provide "unbiased" estimates of forecast performance (Loiseau et al., 2020). Similarly, Lagacherie et al., (2019) showed that the location and number of samples used for independent assessment can significantly impact the value of these indicators. This indicates the greatest variations were observed for evaluation sets with less than 100 samples.





Modeling soil attributes using relief and geophysical data presented promising results for geosciences studies and soil scientists. The use of several algorithms from different "families", the training and validation method also made the study more robust and more reliable. In addition, machine learning models allowed to define the importance of covariates, which are, sometimes, not possible use ordinary spatialization methods, such as kriging and the inverse square of distance.

The "nested leave-one-out validation" method was usefulness with small samples, being a potential tool to be used in geosciences studies. However, still there is a poor knowledge in the academic community on the potential applicability of machine learning techniques.

5. Conclusions

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It is possible to model soil attributes satisfactorily, with easily acquired input data (parent material + DEM) combined with data set from different geophysical sensors. In addition, geophysical data from proximal sensors coupled with Cubist algorithms can provide accurate estimates for several soil attributes. This may assist soil survey programs to reduce the need for new soil samples and wet chemistry.

The combination of geophysical sensors with the best model performance (higher R^2 and lower RMSE and MAE, concomitantly) for the prediction of soil attributes, was Gamma-ray spectrometer + Susceptibilimeter (G + S). The use of three equipment in simultaneous did not optimize model's performance. On the other hand, the Non-use of geophysical sensors, presented the lower performance of soil attributes prediction by machine learning algorithms.

In general, the algorithms showed varying performances. In general, the Cubist was the best one for clay, sand, Fe_2O_3 , TiO_2 , SiO_2 . For CEC the best performance was by SVM. The second-best algorithm performance was SVM for clay, RF for sand and LM for Fe_2O_3 , TiO_2 , SiO_2 and CEC.

The prediction performance for most soil attributes showed R² greater than 0.2, considered satisfactory for machine learning algorithms applied to field data without expensive laboratory analysis, especially when compared with data from fieldwork with the use of remote sensing covariates. All soil attributes obtained superior performance considering an average value for the entire area.

The use of the null model methodology provided a way of comparing those generated by machine learning, when it is not possible to use other methods. The use of four algorithms proved necessary since at least one of the soils attributes performed better in each of the tested algorithms.

The final model was more parsimonious with an ideal number of covariates with a three steps selection. This reduced the effect of overfitting by the use of a large number of covariates. Also, the nested leave-one-out validation methodology proved to be appropriate for small number of samples when compared to the hold-out validation and cross-validation.

The covariables that most contributed to the prediction of soil attributes (clay, sand, Fe₂O₃, TiO₂, SiO₂ and CEC), in the most of algorithms used and sensors combinations were DEM, magnetic susceptibility, parent material and standardized height.

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For each study area, a conceptual pedogeomorphological and geophysical model must be created due to the complex interaction between environmental variables, pedogenesis and soil attributes. These factors affect geophysical variables which are detected and quantified by the sensors and will later serve as input data for the modeling processes.

The machine learning technique is a potential tool for modelling soil attributes with geophysical data, when only field data with proximal sensors are available. The combined use of gamma-ray spectrometer and susceptibilimeter, allowed for an optimization of the models.

6. Declaration of non-availability of relevant model code for the manuscript

☑ The authors declare that they have no code or data relevant to the paper.

☑ The authors declare that they have used basic R software packages, described in details in material

580 7. Authors contribution

Danilo César de Mello: conceived of the presented idea, carried out the experiment, developed the theoretical formalism, contributed to the design and implementation of the research, to the analysis of the results and to the writing of the manuscript. He provided critical feedback and helped shape the research, analysis and manuscript.

Gustavo Vieira Veloso: designed the model and the computational framework and analysed the data, planned and carried out the simulations, performed the analytic calculations and performed the numerical simulations, modelling processing, evaluate algorithms performance, variables importance and statistical analyses.

Marcos Guedes de Lana: contributed to the interpretation of the results, took the lead in writing the manuscript. Devised the project, the main conceptual ideas and proof outline. He worked out almost all of the technical details. All authors provided critical feedback and helped shape the research, analysis and manuscript.

Fellipe Alcantara de Oliveira Mello: contributed to the interpretation of the results, took the lead in writing the manuscript. All authors provided critical feedback and helped shape the research, analysis and manuscript.

Raul Roberto Poppiel: contributed to the interpretation of the results, took the lead in writing the manuscript. All authors provided critical feedback and helped shape the research, analysis and manuscript.

Diego Ribeiro Oquendo Cabrero: performed the analysis, drafted the manuscript and designed the figure. All authors provided critical feedback and helped shape the research, analysis and manuscript.

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Geoscientific Model Development

Discussions EGU

Luis Augusto Di Loreto Di Raimo: performed the analysis, drafted the manuscript and designed the figure. All authors

provided critical feedback and helped shape the research, analysis and manuscript.

605 Carlos Ernesto Gonçalves Reynaud Schaefer: Critical revision of the article. All authors discussed the results and

commented on the manuscript. He contributed to the interpretation of the results and verified the analytical methods.

Elpídio Inácio Fernandes Filho: Critical revision of the article. He designed the model and the computational framework

and analysed the data. He contributed to the interpretation of the results and verified the analytical methods. All authors

610 discussed the results and commented on the manuscript.

Emilson Pereira Leite: Critical revision of the article. He contributed to the interpretation of the results and verified the

analytical methods. All authors discussed the results and commented on the manuscript.

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