# A physically based distributed karst hydrological model (QMG

- 2 model-V1.0) for flood simulations imulation
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- 13 Abstract Karst trough valleys and valley landforms are prone to flooding, primarily
- because of the unique hydrogeological features of karst landformlandforms, which are
- conducive to the spread of rapid runoff. Hydrological models that represent the complicated
- 16 hydrological processes in karst regions are effective for predicting karst flooding, but their
- application has been hampered by their complex model structures and associated parameter
- 18 setsets, especially-so for distributed hydrological models, which require large amounts of
- 19 hydrogeological data. Distributed hydrological models for predicting the Karst flooding
- 20 isare highly dependent on distributed structrues modeling modelling processes, complicated
- 21 boundary parameters settingparameter settings, and tremendousextensive hydrogeological
- 22 data processing that is bothsteps, which are time and computational power consuming-

Proposed here is and computationally expensive. In this study, a distributed physicallybased karst hydrological model, known as called the QMG (Qingmuguan) model is proposed. The structural design of this model is relatively simple, and it is generally divided into surface and underground double-layered structures. The parameters that represent the structural functions of each layer have clear physical meanings, and thefewer parameters are lessrequired than those of the currentare need for other distributed models. This approach allows modeling in karst areas to be modelled with only a small amount of necessary hydrogeological data. 18Eighteen flood processes aerossassociated with the karst underground river in the Qingmuguan karst trough valley are simulated by the QMG model, and the simulated values agree well with observations, for which the average value of the Nash-Sutcliffe coefficient wasis 0.92. A sensitivity analysis shows that the infiltration coefficient, permeability coefficient, and rock porosity are the most important parameters that require the most attention in model calibration and optimization. The improved predictability predictions of karst flooding by obtained with the proposed QMG model promotes a better enhance the mechanistic depicting understanding of runoff generation and confluence flow in karst trough valleys.

**Keywords:** Simulation and forecasting of karst floods; Karst trough valleys; QMG (Qingmuguan) model; Parametric optimization; Parameter sensitivity analysis

#### 1 Introduction

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Karst trough valleysand valley landforms are very common in China, especially in the southwest. In general, these karst areas are water scarce during most of the year because their surfaces store very little rainfall, but they are also potential birthplaces for sources of floods because the local trough and valley landforms and topographic features facilitate the

formation and propagation of floods (White, 2002; Li et al., 2021). Taking the The coexistence of drought and flood is a typical phenomenon in these karst trough and valley areas. For example of, in the present study area, i.e. the Qingmuguan karst trough valley, floods used to happen here constantly were historically prevalent during the rainy season. In recent years, with more extreme rainfall events and the increased area of construction land in the region, rainfall infiltration has decreased, and rapid runoff over impervious surfaces has increased, resulting in frequent catastrophic flooding in the basin (Liu et al., 2009). Excess water overflows flows from karst sinkholes and underground river outlets often occur during floods; (Jourde et al., 2007, 2014; Martinotti et al., 2017), flooding large areas of farmland and residential areas and causing serious economic losses (Gutierrez, 2010; Parise, 2010; Yu et al., 2020). Therefore, it is both important and urgent to simulate and predict karst flooding events in karst trough valleys and valley regions, such as the study area.

Hydrological models can be effective for forecasting floods and evaluating water resources in karst areas (Bonacci et al., 2006; Ford and Williams, 2007; Williams, 2008, 2009). However, modelling floods in karst regions is extremely difficult because of the complex hydrogeological structure.structures of these regions. Karst water-bearing systems consist of multiple media under the influence of and are influenced by complex karst development dynamics (Worthington et al., 2000; Kovács and Perrochet, 2008; Gutierrez, 2010), such as karst caves, conduits, fissures and pores, and; thus, such systems are usually highly spatially heterogeneous (Chang and Liu, 2015; Mario Teixeiraparente et al., 2019). In addition, the intricate complex surface hydrogeological conditions and the hydrodynamic conditions inside the karst water-bearing mediummedia result in significant temporal and spatial differences in the hydrological processes in karst areas (Geyer et al., 2008; Bittner et al., 2020).

In early studies of flood forecasting in karst regions, simplified lumped hydrological models were commonly used to describe the rainfall–discharge relationship (e.g., Kovács and Sauter, 2007; Fleury et al., 2007b; Jukić and Denić, 2009; Hartmann et al., 2014a). With the development of physical exploration technology and the progress made in mathematics, computing and other interdisciplinary disciplines, the level of modelling has gradually

improved (Hartmann and Baker, 2017; Hartmann, 2018; Petrie et al., 2021), and). Subsequently, distributed hydrological models have subsequently becomebeen widely used in karst areas. The main difference between lumped and distributed hydrological models is that the latter divide the entire basin into many sub-basinssubbasins to calculate the simulate runoff generation and confluence characteristics, thereby bettereffectively describing the physical properties of the hydrological processes inside the that occur in karst water-bearing system (systems (Jourde et al., 2007; Hartmann, 2018; Epting et al., 2018).

Because of their simple structure and littlelow demand for modelling data, lumped hydrological models have been used widely in karst areas (Kurtulus and Razack, 2007; Ladouche et al., 2014). In a lumped model, thea river basin is considered as a whole to calculate thewhen simulating runoff generation and confluenceflow paths, and there is no division running into sub-basinssubbasins (Dewandel et al., 2003; Bittner et al., 2020). Lumped models usually consider the inputs and outputs of the modelstudy area (Liedl and Sauter, 2003; Hartmann and Bake, 2013, 2017). In addition, most of the model parameters are not optimized in a lumped model, and the physical meaning of each parameter ismay be unclear (Chen, 2009; Bittner et al., 2020).

Distributed hydrological models are of activehigh interest in flood simulation and forecasting research (Ambroise et al., 1996; Beven and Binley, 2006; Zhu and Li, 2014). Compared with a-lumped model, amodels, distributed model has a more definitemodels provide clear physical significance formcaning regarding the model structure in terms of its mechanismand mechanisms (Meng and Wang, 2010; Epting et al., 2018). In a distributed hydrological model, an entire karst basin can be divided into many sub-basinssubbasins (Birk et al., 2005) using high-resolution digital elevation map (DEM) data. In the rainfall-runoff algorithm of thea model, the hydrogeological conditions and karst aquifer characteristics can be fully considered fully to simulate precisely thesimulate runoff generation and confluence (flow processes (Martinotti et al., 2017; Gang et al., 2019). The commonly usedAdditionally, some basin-scale distributed hydrological models (i.e. not a specialspecific groundwater numerical modelmodels, such as MODFLOW) have also been applied widely in karst areas, and they include the SHE/MIKE SHE model (Abbott et al.,

1986a,b; Doummar et al., 2012), the SWMM model (Peterson and Wicks, 2006; Blansett and Hamlett, 2010; Blansett, 2011), TOPMODEL (Ambroise et al., 1996; Suo et al., 2007; Lu et al., 2013; Pan, 2014) and the SWAT model (Peterson and Hamlett, 1998; Ren, 2006).

The commonly used distributed hydrological models have multiplevarious structures and numerous parameters (Lu et al., 2013; Pan, 2014), which means that and a distributed model may needrequire vast amounts of data to build its framework for simulations in karst regions. For example, the distributed groundwater model MODFLOW-CFPM1 requires detailed data regarding the distribution of karst conduits in a study area (Reimann et al., 2009). Another example is the Karst–Liuxihe model (Li et al., 2019), which has ); notably, there are fifteen parameters and five underground vertical layers structures in the model. Such a complex structure and has 15 parameters, thereby making it difficult to modelincreases the data demand, and modelling in karst areas is extremely difficult. In addition, a special borehole pumping test may be required to obtain the rock permeability coefficient.

To overcome the difficulty of the large modelling data demands forof distributed hydrological models in karst areas, a new physically based distributed hydrological model—known as the QMG (Qingmuguan) model-V1.0—was developed in the present study. Other commonly used karst groundwater models with complex structures and parameters—, such as the aforementioned MODFLOW-CFPM1 model—, require a lot of considerable hydrogeological data for modelling in karst areas (Qin and Jiang, 2014). The new QMG model has a high potential for application in karst hydrological simulation and forecasting. It; it has certain advantages included to its framework and structural design, havingsuch as a double-layer structure and fewerfew parameters. The horizontal structure is divided into river channel units and slope units, and the vertical structure below the surface is divided into a shallow karst aquifer and a deep karst aquifer systemsystems. This relatively simple model structure reduces the demand for modelling data in karst areas, and only a small amount of limited hydrogeological data is are needed for modelling.—

To ensure that the QMG model work well in karst flood simulation and prediction in the

case of relatively simple structure and parameters. We carefully designed the algorithms of runoff generation and confluence in the model. To ensure that the QMG model works well in karst flood simulation and prediction despite its relatively simple structure and <a href="mailto:few">few</a>
parameters, we carefully designed the algorithms for runoff generation and <a href="mailto:confluenceflow">confluenceflow</a>
in the model. <a href="mailto:Also\_Additionally">Also\_Additionally</a>, to verify the applicability of the QMG model <a href="mailto:toin">toin</a> flood simulation in karst basins, we selected the Qingmuguan karst trough valley in Chongqing, China, as the study area for a flood simulation and uncertainty analysis. In particular, we analysed the sensitivity of the model parameters.

## 2 Study area and data

## 2.1 Landform and topography

The Qingmuguan karst trough valley is located in the southeastern part of the Sichuan Basin, China, at the junction of the Beibei and Shapingba districts in Chongqing, with the coordinates of 29°40′N–29°47′N, and 106°17′E–106°20′E. The basin covers an area of 13.4 km² and is part of the southern extension of the anticline at Wintang Gorge in the Jinyun Mountains, with the anticlinal axis of Qingmuguan located in a parallel valley in eastern Sichuan (Yang et al., 2008). The surface of the anticline is heavily fragmented, and faults are extremely well developed with large areas of exposed Triassic carbonate rocks exposed. Under the long-term erosion of karst water, a typical karst trough landform pattern of 'three mountains and two troughs' has formed, which looks like a pen-holder structure, means 'three ridges with two troughs' (Liu et al., 2009). This karst trough landform provides convenientideal conditions for flood propagation, and the development of karst landforms is extremely common in thethis karst region of southwestSouthwest China, especially in the karst region of Chongqing. Similar regions include the karst trough valley of the Zhongliang Mountains and the Laolongdong karst basin in Nanshan, Chongqing.

The basin is oriented north north east and south south west in a narrow band of slightly curved arcs and is ~12 km long from north to south. The direction of the mountains in the region is basically generally consistent with the same as that direction of the tectonic line. The

difference in relative elevation is 200 300 m. The map in Fig.Figure 1 gives an overview of the Qingmuguan karst basin.

Figure 1. The Qingmuguan karst basin.

# 2.2 Hydrogeological conditions

The Qingmuguan basin is located within the subtropical humid monsoon climate zone, with an average temperature of 16.5°C and an average precipitation of 1250 mm that is concentrated mainly infrom May—September. An underground river system has developed in the karst trough valley, with a length of 7.4 km, and the water supply of the underground river is mainly rainfall recharge (Zhang, 2012). Most of the precipitation is collected along the hill slopecollects in hillslope areas and flows into the karst depressions at the bottom of the trough valley, where it is rechargedprovides recharge to the underground river through the dispersed infiltration of via surface karst fissures and concentrated injection from sinkholes (Fig. 1a). An upstream surface river collects forms in a gentle valley and enters the underground river through the Yankou sinkhole (elevation 524 m). Surface water in the middle and lower reaches of the river system enters the underground river system mainly through catenuliform cover-collapse sinkholes of (Gutierrez et al., 2014) and fissures.

The stratigraphic and lithological characteristics of the basin are dominated largely by carbonate rocks of the Lower Triassic Jialingjiang Group ( $T_{1j}$ ) and Middle Triassic Leikou Slope Group ( $T_{2l}$ ) on both sides of the slope, with some quartz sandstone and mudstone outcrops of the Upper Triassic Xujiahe Group ( $T_{3xj}$ ) (Zhang, 2012). The topography of the basin presents a general anticline (Fig. 1b), where carbonate rocks on the surface are corroded and fragmented, with a large and have high permeability coefficient. Compared with the core of the anticline, the rocks of the two wingsshale of the anticline areis less eroded and formforms a good waterproof layer.

To investigate the distribution of karst conduits in the underground river system, we conducted a tracer test in the study area. The tracer was placed into the Yankou sinkhole and recovered in the Jiangjia spring (Fig. 1a,c). According to the tracer test results (Gou et al.,

2010), the karst water-bearing medium in the aquifer was anisotropic, whereas the soluble carbonate rocks were extremely permeable. The the karst conduits in the underground river were extremely well developed, and there was a large single-channel underground river-approximately five metres wide. The response of the underground river to rainfall was very fast, with the peak flow observed at the outlet of Jiangjia spring 6–8 h after rainfall. based on the tracer test results. The flood peak rose quickly, and the duration of the peak flow was short. The underground river system in the study area is dominated by large karst conduits, which isare not conducive to water storage in water-bearing media, but isare very conducive to the propagation of floods.

#### 2.3 Data

To build the QMG model to simulate the karst flood events, the necessary modelling baseline data had to be collected, including:and they included 1) high-resolution DEM data and hydrogeological data (e.g., the thickness of the epikarst zone, rainfall infiltration coefficient on for different karst landforms, and permeability coefficient of rock); 2) landuse and soil type data; and 3) rainfall data in the basin and water flow data of the underground river. The DEM data waswere downloaded from a free internet database on the public Internet, withand had an initial spatial resolution of 30 × 30 m. The spatial resolution of landusethe land use and soil types were type data was 1000 × 1000 m, and theythese data were also downloaded from the Internetinternet. After considering the applicability of modelling and computational strength of the model, as well as the size of the basin in the study area (13.4 km²), the spatial resolution of the three types of data was resampled uniformly in the QMG model and downscaled to 15 × 15 m based on other spatial discrete method proposed by Berry et al. (2010).

The hydrogeological data necessary for modelling waswere obtained in three simple ways. 1) A basin survey was conducted to obtain the thickness of the epikarst zone, which was achieved by observing the rock formations on hillsides following cutting for road construction. Information was collected regarding the location, general shape, and size of karst depressions and sinkholes, which had a significant impact on compiling the DEM data

and determining the convergence process of surface runoff and these data were combined with DEM data and used to determine the convergence process of surface runoff. The sinkholes in the basin are cover-collapse sinkholes (Gutierrez et al., 2014) according to the basin survey. There are 3 large sinkholes (more than 3 metres in diameter) and 12 small sinkholes (less than 1 metre in diameter). The rest of the sinkholes, 5 in total, are between 1 and 3 metres in diameter. The confluence calculations for sinkholes in the model were based on the results of a previous study (Meng et al., 2009). 2) Empirical equations developed for similar basins were used to obtain the rainfall infiltration coefficient for different karst landforms and the permeability coefficient of rock. For example, the rock permeability coefficient was calculated based on an empirical equation from stablished based on a pumping test in a coal mine in the study area (Li et al., 2019, 2022). 3) A tracer experiment was conducted in the study area (Gou et al., 2010) to obtain information on the underground river direction and flow velocity flow direction and flow velocity; for instance, underground karst conduits are well developed in the area, and an underground river approximately five metres wide is present. There is no hydraulic connection between the underground river system in the area and the adjacent basin, which means that there is no overflow recharge.

Rainfall and flood data are important model inputs; and represent the driving factors that allowof hydrological models to operate. In the study area, rainfall data waswere acquired bywith two rain gauges located in the basin (Fig. 1a). Point rainfall was then spatially interpolated intoto obtain basin-level rainfall (for such a small basin area, the rainfall results obtained from two rain gauges waswere considered representative). There were 18 karst flood events in the period offrom 14 April 2017 to 10 June 2019. We built a rectangular open channel at the underground river outlet and set up a river gauge on it in the channel (Fig. 1a) to record the water level and flow data every 15 minutes.

#### 3 Methodology

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# 3.1 Hydrological model framework and algorithms

The hydrological model developed in this study was named the QMG model after the basin for which it was developed and to which it was first applied, i.e-, the Qingmuguan basin.

The QMG model proposed in this study has a two-layer structure, including a surface part and an underground part, with the former. The surface part mainly performing the calculation of runoff generation and surface routing calculations, and the underground part performs the confluence of the surface river, while the latter performs the confluence calculation of routing calculations for the underground river system.

The structure of the QMG model is divided into a two-layer structure, both horizontally with horizontal and verticallyvertical components. The horizontal structure of the model is divided into river channel units and slope units. The vertical structure below the surface is divided into a shallow karst aquifer (including soil layers, karst fissures and conduit systems in the epikarst zone) and a deep karst aquifer system (rock stratumbedrock and underground river system). This With this relatively simple model structure means that, only a small amount of hydrogeological data is needed when modelling in karst regions. Figure 2 shows a flowchart of the modelling and calculation procedures required for the QMG model.

**Figure 2.** Modelling flow chart of the QMG (Qingmuguan) model.

To describe accurately show the runoff generation and confluence on a routing processes at the grid scale, thesethe karst sub-basinssubbasins are further divided into many karst hydrological response units (KHRUs).) based on the high-resolution (15 × 15 m) DEM data in the model. The specific steps involved in the division were adopted by referring to studies a study of hydrological response units (HRUs) in TOPMODEL by Pan (2014). As the smallest basin units for computing units, the, KHRUs can effectively ignoremitigate the spatial differences of a karst development within the units and reduce the uncertainty in the classification of model units. Figure 3 shows the spatial structure of the KHRUs.

**Figure 3.** Spatial structure of karst hydrological response units (KHRUs) (Li et al., 2021).

The right-hand side of Fig.Figure 3 shows a three-dimensional spatial model of KHRUs established in the laboratory to reflect visually reflect the storage and movement of water in thea karst water-bearing medium with each spatial anisotropy, and to provide technical support for establishing the hydrological model.

The modelling and operation of the QMG model consists of involve three main stages: 1)

spatial interpolation, and the retention establishment of rainfall and evaporation calculations;

271 2) runoff generation and confluence calculation routing calculations for the surface river; and

3) confluence calculation calculations for the underground runoff, including the

confluence in the shallow karst aquifer and the underground river system.

(Fig. 1a) was interpolated spatially into areal rainfall for the entire basin.

# 3.1.1 Rainfall and evaporation **calculation** calculations

In the QMG model, the spatial interpolation of rainfall is accomplished bywith a kriging method using the ArcGIS 10.2 software. The TysonIn some cases, the Thiessen polygon method may be a simpler method for rainfall interpolation if the number of rainfall gauges in the basin is sufficient. The point rainfall observed bywith the two rainfall gauges in the basin

Basin evapotranspiration in the KHRUs was mainly vegetal, from vegetation, the soil evaporation—and water surface evaporation. They surfaces. These evapotranspiration

282 <u>components</u> were calculated using the following equations (modified from Li et al., 2020):–

$$\begin{cases}
E_{v} = V^{t+\Delta t} - V^{t} - P_{v} \\
E_{s} = \lambda E_{p}, & \text{if } F = F_{c} \\
E_{s} = \lambda E_{p} \frac{F}{F_{c}}, & \text{if } F < F_{\text{sat}} \\
E_{w} = \Delta e \cdot \left[ 1.12 + 0.62 \left( \Delta T \right)^{0.9} \right] \cdot \left[ 0.084 + 0.24 \left( 1 - \gamma^{2} \right)^{1/2} \right] \cdot \left[ 0.348 + 0.5 \omega^{1.8-1.137} \omega^{0.05} \right]
\end{cases}$$
(1)

Here, where  $E_{\nu}$  [mm] is the vegetal discharge,  $V^{\ell + \Delta} - V^{\ell}$  [mm] is the rainfall variation by due to vegetation interception,  $P_{\nu}$  [mm] is the vegetation interception of rainfall by vegetation and  $E_s$  [mm] is the actual soil evaporation. The term  $\lambda$  is the evaporation coefficient. The term  $E_p$  [mm] is the potential evaporation—capability, which can be measured experimentally or estimated by the with a water surface evaporation equation for  $E_{\nu}$ . The term F [mm] is the actual soil moisture,  $F_{sat}$  [mm] is the saturation moisture content,  $F_c$  [mm] is the field capacity,  $E_{\nu}$  [mm/d] is the evaporation of the from a water surface and  $\Delta e \Delta e = e_0 - e_{150}$  [hPa] is the draught head between the saturation vapour pressure of thea water surface and the air vapour pressure 150 m above the water

surface (150 m above the water surface was selected here because the altitude for temperature and humidity observations in the southwestern karst regions of China is usually set at 150 200 m). The term  $\Delta T = t_0 - T_{150}$  [°C] is the temperature difference between thea water surface and the temperaturea location 150 m above the water surface,  $\frac{\gamma}{2}$  is the relative humidity 150 m above the water surface and  $\frac{\omega}{2}$  [m/s] is the wind speed 150 m above the water surface.

# 3.1.2 Runoff generation

In the QMG model, the surface runoff generation in river channel units means associated with the rainfall in the basin that enters the river system after deducting subtracting evaporation losses. This portion of the runoff will participate directly involved in the confluence routing process directly through the river system, rather than undergoing infiltration. In contrast, the process of runoff generation in slope units is more complex, and its classification is related to the developmental characteristics of the surface karst features in the basin, the rainfall intensity and soil moisture. For example, when the soil moisture content is already is saturated, there is the potential for excess infiltration-based surface runoff in exposed karst slope units. The surface Surface runoff generation of the KHRUs in the river channel units and slope units in KHRUs can be described by the following equations (modified from Chen, 2009, 2018; Li et al., 2020):

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$$\begin{cases}
P_{r}(t) = \left[P_{i}(t) - E_{p}\right] \frac{L \cdot W_{\text{max}}}{A} \\
R_{\text{si}} = (P_{i} - f_{i}), P_{i} > f_{\text{max}} \\
R_{\text{si}} = 0, P_{i} < f_{\text{max}} \\
f_{\text{max}} = \alpha (F_{c} - F)^{\beta} + F_{s}
\end{cases}$$

$$\begin{cases}
P_{r}(t) = \left[P_{i}(t) - E_{p}\right] \frac{L \cdot W_{\text{max}}}{A} \\
R_{\text{si}} = (P_{i} - f_{i}), P_{i} \geq f_{\text{max}} \\
R_{\text{si}} = 0, P_{i} < f_{\text{max}} \\
f_{\text{max}} = \alpha (F_{c} - F)^{\beta} + F_{s}
\end{cases}$$
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312 (2)

Here, where  $P_r(t)$  [mm] is the net rainfall (deducting subtracting evaporation losses) in the river channel units at time t [h],  $P_i(t)$  [mm] is the rainfall in the river channel units, L [m] is the length of the river channel,  $W_{\text{max}}$  [m] is the maximum width of the river channel selected and A [m<sup>2</sup>] is the cross-sectional area of the river channel.  $R_{\text{si}}$  [mm] is termed the excess infiltration runoff in the QMG model, when the vadose zone is short of water and has

not been filled. The nonsaturated. Notably, the infiltration capacity  $f_{\text{max}}$  is different varies in different karst landform units,  $\alpha_{\overline{1}}$  and  $\beta$  are the parameters of the Holtan model, and  $F_s$  [mm] is the stable depth of soil water infiltration.

In the KHRUs (Fig. 3), underground runoff is generated primarily from the infiltration of rainwater and direct confluence recharge from sinkholes or skylights.karst windows. In the QMG model, the underground runoff is calculated by the following equations (modified from Chen, 2018):

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$$\frac{\int R_g = R_0 \exp(-pt^m)}{\left[R_e = v_e \cdot I_w \cdot z\right]} \begin{cases} R_g = R_0 \exp(-pt^m) \\ R_e = v_e \cdot I_w \cdot z \end{cases}$$
(3)

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$$\begin{cases} \frac{\partial R_{e}}{\partial x} + I_{w} \cdot z \cdot \frac{\partial F}{\partial t} = R_{r} - R_{epi} \\ v_{e} = K \cdot \tan(\alpha), \quad F > F_{c} \\ v_{e} = 0, \quad F \leq F_{c} \end{cases}$$
 (4)

Here,  $R_g$  [mm] is the underground runoff depth (this part of the underground runoff is mainly directly from the direct confluence supply of the karst sinkholes or skylightskarst windows in the study area),  $R_0$  [mm] is the average depth of the underground runoff, p and m are attenuation coefficients that were calculated by conducting a tracer test in the study area,  $R_e$  [L/s] is the underground runoff generated from rainfall infiltration in the epikarst zone,  $I_w$  [mm] is the width of the underground runoff enzone in the KHRUs, z [mm] is the thickness of the epikarst zone,  $R_r$  [mm²/s] is the runoff-based recharge enin the KHRUs during period t,  $R_{\rm epi}$  [mm²/s] is the water infiltration from rainfall,  $v_e$  [mm/s] is the flow velocity of the underground runoff, K [mm/s] is the eurrent permeability coefficient and  $\alpha$ - $\alpha$  is the hydraulic gradient of the underground runoff. If the eurrent soil moisture level is less than the field capacity, i.e.  $F \leq F_c$ , then  $F \leq F_c$ , and the vadose zone is not yet full, there will be no underground runoff generation, and rainfall infiltration at this time will continue to compensate for the lack of water infill the vadose zone until it is full and before it becomes

saturated, at which point runoff is generated.

## 3.1.3 Channel routing and confluenceconvergence

In the QMG model, the calculation of runoff confluence on the routing in KHRUs includes the confluence of the surface river channel and underground runoff. There are already many mature and classical classic algorithms available for calculating the performing runoff confluence routing calculations in river channel units and slope units, such as the Saint-Venant equations and Muskingum convergence model. In this study, the Saint-Venant equations were adopted to describe the confluence in assess flow routing for the surface river and in hill slope units, for which and a wave movement equation was adopted to calculate confluence for convergence calculations in slope units (Chen, 2009):

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$$\frac{\int \frac{\partial Q}{\partial x} + L \frac{\partial h}{\partial t} = q}{\left\{ S_f - S_0 = 0 \right\}} \begin{cases} \frac{\partial Q}{\partial x} + L \frac{\partial h}{\partial t} = q \\ S_f - S_0 = 0 \end{cases}$$
 (5)

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$$Q = vhL = \frac{L}{n}h^{\frac{5}{3}}S_0^{\frac{1}{2}}.$$
 (6)

Here, we customized two variables a and b:

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$$\frac{\int a = (\frac{n}{L}S_0^{-\frac{1}{2}})^{\frac{3}{5}}}{b = \frac{3}{5}} \begin{cases} a = (\frac{n}{L}S_0^{-\frac{1}{2}})^{\frac{3}{5}} \\ b = \frac{3}{5} \end{cases}$$
 (7)

Equation (7) was substituted into Eq.-\_(5) and discretized bywith a finite-difference method, giving-yielding

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$$\frac{\int \frac{\partial Q}{\partial x} + abQ^{(b-1)} \frac{\partial Q}{\partial t} - q = 0}{\left[\frac{\Delta t}{\Delta x} Q_{i+1}^{t+1} + a(Q_{i+1}^{t+1})^b = \frac{\Delta t}{\Delta x} Q_i^{t+1} + a(Q_{i+1}^t)^b + q_{i+1}^{t+1} \Delta t\right]}$$

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$$\begin{cases} \frac{\partial Q}{\partial x} + abQ^{(b-1)} \frac{\partial Q}{\partial t} - q = 0\\ \frac{\Delta t}{\Delta x} Q_{i+1}^{t+1} + a(Q_{i+1}^{t+1})^b = \frac{\Delta t}{\Delta x} Q_i^{t+1} + a(Q_{i+1}^t)^b + q_{i+1}^{t+1} \Delta t \end{cases}$$
(8)

The Newton–Raphson method was used for the iterative calculation using Eq.-\_(8):

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$$\frac{\left[Q_{i+1}^{t+1}\right]^{k+1}}{\left[Q_{i+1}^{t+1}\right]^{k}} = \left[Q_{i+1}^{t+1}\right]^{k} \frac{\Delta t}{\Delta x} \left[Q_{i+1}^{t+1}\right]^{k} + a\left(\left[Q_{i+1}^{t+1}\right]^{k}\right)^{b} - \frac{\Delta t}{\Delta x} Q_{i}^{t+1} - a\left(Q_{i+1}^{t}\right)^{b} - q_{i+1}^{t+1} \Delta t}{\frac{\Delta t}{\Delta x}} + ab\left(\left[Q_{i+1}^{t+1}\right]^{k}\right)^{b-1}$$

362 
$$\left[ Q_{i+1}^{t+1} \right]^{k+1} = \left[ Q_{i+1}^{t+1} \right]^k - \frac{\frac{\Delta t}{\Delta x} \left[ Q_{i+1}^{t+1} \right]^k + a \left( \left[ Q_{i+1}^{t+1} \right]^k \right)^b - \frac{\Delta t}{\Delta x} Q_i^{t+1} - a \left( Q_{i+1}^t \right)^b - q_{i+1}^{t+1} \Delta t}{\frac{\Delta t}{\Delta x} + ab \left( \left[ Q_{i+1}^{t+1} \right]^k \right)^{b-1}} \right]$$

- where Q [L/s] is the confluenceconvergence of water flow in slope units, L [dm] is its—the width of the runoff widthzone in a slope unit, h [dm] is the runoff depth and q [dm²/s] is the lateral inflow onin the KHRUs. Here, the friction slope  $S_f$   $S_f$  equals the hill slope  $S_0$   $S_0$ , and the inertia term and the pressure term in the motion equation of the Saint-Venant equationsequation set were ignored. The term v [dm/s] is the flow velocity of surface runoff in the slope units, as calculated by the Manning equation. Additionally, n is the roughness coefficient of the slope units,  $Q_i^{t+1}$  [L/s] is the slope inflow in thea KHRU at time t+1 and  $Q_{i+1}^{t+1}$  [L/s] is the slope discharge in the upper adjacent KHRU at time t+1.
- Similarly, the surface river channel confluence convergence was described based on the Saint-Venant equation, where equations, and a diffusion wave movement equation was adopted, meaning that; therefore, the inertia term in the motion equation was ignored:—

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$$\frac{\left|\frac{\partial Q}{\partial x} + \frac{\partial A}{\partial t} = q\right|}{\left|S_f = S_0 - \frac{\partial h}{\partial x}\right|} \left|\frac{\partial Q}{\partial x} + \frac{\partial A}{\partial t} = q\right|$$

$$\left|S_f = S_0 - \frac{\partial h}{\partial x}\right|$$

A finite-difference method and the Newton–Raphson method were used for the iterative calculation of to iteratively solve the above equation:

$$\begin{cases}
\left[Q_{i+1}^{t+1}\right]^{k+1} = \left[Q_{i+1}^{t+1}\right]^{k} - \frac{\Delta t}{\Delta x} \left[Q_{i+1}^{t+1}\right]^{k} + c\left(\left[Q_{i+1}^{t+1}\right]^{k}\right)^{b} - \frac{\Delta t}{\Delta x} Q_{i}^{t+1} - c\left(Q_{i+1}^{t}\right)^{b} - q_{i+1}^{t+1} \Delta t \\
\frac{\Delta t}{\Delta x} + cb\left(\left[Q_{i+1}^{t+1}\right]^{k}\right)^{b-1}
\end{cases} (11)$$

where Q [L/s] is the water flow in surface river channel units, A [dm<sup>2</sup>] is the <u>cross-sectional</u> <u>area of discharge section area</u>, c is a custom intermediate variable and  $\mathcal{X}$  [dm] is the wetted perimeter of the discharge <u>cross-section area</u>.

The underground runoff area in the model includes the confluence convergence region of the epikarst zone and underground river. In the epikarst zone, the karst water-bearing media are highly heterogeneous. (Williams, 2008). For example, the crisscrossedanisotropic karst fissure systems and conduit systems consist of large corrosion fractures. When rainfall infiltrates into the epikarst zone, water moves slowly through the small (less than 10 cm in this study) karst fissure systems, while and it flows rapidly in larger (more than 10 cm) conduits. The key to determining stimating the confluence flow velocity lies in determining the width of karst fractures. In the KHRUs (Fig. 3), the 10 cm fracture width of the fracture 10 cm was used as a threshold value (Atkinson, 1977), meaning that) based on a borehole pumping test in the basin. Thus, if the fracture width exceeded 10 cm, then the water movement into it in the fracture was defined as rapid flow; otherwise, it was defined as slow flow. The confluence flow in the epikarst zone was calculated by the following equation (modified from Beven and Binley, 2006):

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$$\frac{Q(t)_{ijk} = b_{ijk} \cdot \frac{\Delta h}{\Delta l} R_i C_j \cdot T(t)_{slow/rapid}}{Q(t)_{ijk} = b_{ijk} \cdot \frac{\Delta h}{\Delta l} R_i C_j \cdot T(t)_{slow/rapid}}$$
396 (12)

397 where

$$\begin{cases}
T(t)_{\text{slow}} = nr \frac{\rho g R_i C_j L_k}{12\nu} \\
T(t)_{\text{rapid}} = \frac{K_{ij} \left(e^{-f_{ij}h_{ij}} - e^{-f_{ij}z_{ij}}\right)}{f_{ij}}
\end{cases}$$
(13)

Here,  $Q(t)_{ijk} Q(t)_{ijk}$  [L/s] is the flow confluence in the epikarst zone at time t,  $b_{ijk} b_{ijk}$ 

[dm] is the <u>width of the runoff widthzone</u>,  $\frac{\Delta h}{\Delta l} \frac{\Delta h}{\Delta l}$  is the dimensionless hydraulic gradient,

401  $T(t)_{\text{slow/rapid}}$  is the dimensionless hydraulic conductivity,  $\rho \rho \rho$  [g/L] is the density of the

water-flow, g [m/s<sup>2</sup>] is gravitational acceleration, n is the <u>number of</u> valid computational

units,  $\frac{R_i C_j L_k}{R_i C_j L_k}$  [L] is the volume of the *ijk*-th KHRU, v is the kinematic viscosity

coefficient,  $f_{ij}$  is the attenuation coefficient in the epikarst zone,  $h_{ij}$  [dm] is the depth of

shallow groundwater and  $z_{ij}$  [dm] is the thickness of the epikarst zone.

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The distinction between rapid and slow flows in the epikarst zone is not absolute. The 10 cm width of a karstNotably, the established fracture as the dividing threshold also has some subjectivity.of 10 cm may be unrepresentative because pumping tests were conducted in only five boreholes in the region. In fact, there is usually water exchange between the rapid and slow flowsflow zones at the junctionjunctions of large and small fissures in karst aquifers. In the QMG model, this water exchange can be described with thisthe following equation (modified formfrom Li et al., 2021):

$$\frac{Q = \alpha_{i,j,k} \left( h_n - h_{i,j,k} \right)}{\alpha_{i,j,k} = \sum_{ip=1}^{np} \frac{\left( K_w \right)_{i,j,k} \pi d_{ip} \frac{1}{2} \left( \Delta l_{ip} \tau_{ip} \right)}{r_{ip}}} \underbrace{\begin{cases} Q = \alpha_{i,j,k} \left( h_n - h_{i,j,k} \right) \\ \alpha_{i,j,k} = \sum_{ip=1}^{np} \frac{\left( K_w \right)_{i,j,k} \pi d_{ip} \frac{1}{2} \left( \Delta l_{ip} \tau_{ip} \right)}{r_{ip}} \end{cases}}_{q_{i,j,k}}$$

$$\frac{\left( A_{i,j,k} = \sum_{ip=1}^{np} \frac{\left( K_w \right)_{i,j,k} \pi d_{ip} \frac{1}{2} \left( \Delta l_{ip} \tau_{ip} \right)}{r_{ip}} \right)}{r_{ip}} = \frac{1}{2} \left( \frac{1}{2} \left( \Delta l_{ip} \tau_{ip} \right) \right)}_{q_{i,j,k}}$$

$$\frac{\left( A_{i,j,k} = \sum_{ip=1}^{np} \frac{\left( K_w \right)_{i,j,k} \pi d_{ip} \frac{1}{2} \left( \Delta l_{ip} \tau_{ip} \right)}{r_{ip}} \right)}{r_{ip}} = \frac{1}{2} \left( \frac{1}{2} \left( \Delta l_{ip} \tau_{ip} \right) \right)}_{q_{i,j,k}}$$

$$\frac{\left( A_{i,j,k} = \sum_{ip=1}^{np} \frac{\left( K_w \right)_{i,j,k} \pi d_{ip} \frac{1}{2} \left( \Delta l_{ip} \tau_{ip} \right)}{r_{ip}} \right)}{r_{ip}} = \frac{1}{2} \left( \frac{1}{2} \left( \Delta l_{ip} \tau_{ip} \right) \right)}_{q_{i,j,k}}$$

Here,  $\alpha_{i,j,k}$  [dm<sup>2</sup>/s] is the water exchange coefficient in the *ijk*-th KHRU,  $(h_n - h_{i,j,k})$ 

6  $\left(h_n - h_{i,j,k}\right)$  [dm] is the water head difference between the rapid and slow flows flow zones

at the junction of large and small fissures in KHRUs, np is the number of fissure systems

connected to the adjacent conduit systems,  $\frac{(K_w)_{i,j,k}}{(K_w)_{i,j,k}}$  [dm/s] is the permeability

coefficient at the junction of a fissure and conduit,  $\underline{d_{ip}} \underline{d_{ip}}$  and  $\underline{\tau_{ip}} \underline{r_{ip}}$  [dm] are the conduit diameter and radius, respectively,  $\underline{\Delta l_{ip}} \underline{\Delta l_{ip}}$  [dm] is the length of the connection between conduits i and p, and  $\underline{\tau_{ip}} \underline{\tau_{ip}}$  is the conduit curvature. Some of the parameters in this equation, such as  $(K_w)_{i,j,k} \underline{(K_w)_{i,j,k}}$  and  $\underline{(h_n - h_{i,j,k})} \underline{(h_n - h_{i,j,k})}$ , were obtained by conducting an infiltration test in the study area.

The confluence of convergence patterns in the underground river system playshave an important role for influence on the confluence flow regime at the basin outlet. To facilitate the calculation of confluence routing calculations in the QMG model, the underground river systems system can be generalized into large multiple—conduit systems. During floods, these conduit systems are mostly under pressure. Whether the water flow is laminar or turbulent depends on the flow regime at that time. The water flow into these conduits is calculated by based on the Hagen—Poiseuille equation and the Darcy—Weisbach equation (Shoemaker et al., 2008):

$$Q_{\text{laminar}} = -A \frac{gd^2 \partial h}{32\nu \partial x} = -A \frac{\rho gd^2 \Delta h}{32\mu \tau \Delta l}$$

$$Q_{\text{turbulent}} = -2A \sqrt{\frac{2gd |\Delta h|}{\Delta l \tau}} \log \left( \frac{H_c}{3.71d} + \frac{2.51\nu}{d\sqrt{\frac{2gd^3 |\Delta h|}{\Delta l \tau}}} \right) \frac{\Delta h}{|\Delta h|}$$

$$\begin{cases}
Q_{\text{laminar}} = -A \frac{gd^2 \partial h}{32\nu \partial x} = -A \frac{\rho gd^2 \Delta h}{32\mu \tau \Delta l} \\
Q_{\text{turbulent}} = -2A \sqrt{\frac{2gd |\Delta h|}{\Delta l \tau}} \log \left( \frac{H_c}{3.71d} + \frac{2.51\nu}{d\sqrt{\frac{2gd^3 |\Delta h|}{\Delta l \tau}}} \right) \frac{\Delta h}{|\Delta h|}
\end{cases} (15)$$

Here,  $Q_{\text{laminar}} Q_{\text{laminar}}$  [L/s] is the water flow of the laminar flow in the conduit systems, A [dm<sup>2</sup>] is the conduit cross-sectional area, d [dm] is the conduit diameter, P P [kg/dm<sup>3</sup>] is the density of the underground riverwater,  $v = \mu / \rho$  is the coefficient of

kinematic viscosity,  $\frac{\Delta h/\tau\Delta l}{\Delta h/\tau\Delta l}$  is the hydraulic slope of the conduits,  $\frac{\tau}{\tau}$  is the dimensionless conduit curvature,  $\frac{Q_{\text{turbulent}}}{Q_{\text{turbulent}}}$  [L/s] is the turbulent flow in the conduit systems and  $H_c$  [dm] is the average conduit wall height.

## 3.2 Parameter optimization

In total, the QMG model has 12 parameters, of which flow direction and slope are topographic parameters that can be determined from the DEM without parametric optimization, whileand the remaining 10 parameters require calibration. Other distributed hydrological models with multiple structures usually have many parameters. For example, the Karst–Liuxihe model (Li et al., 2021) has 15 parameters that must be calibrated. In the QMG model, each parameter is normalized as

$$x_{i} = x_{i}^{*} / x_{i0}, (16)$$

where  $x_i$  is the dimensionless parameter value <u>for</u> i after it is normalized,  $x^*_i$  is the parameter value <u>for</u> i in actual physical units, and  $x_{i0}$   $x_{i0}$  is the initial or final value of  $x_i$ . Through the processing of Eq.-\_(16), the value range of the model parameters is limited to a hypercube  $K_n = (X \mid 0 \le x_i \le 1, i = 1, 2, ..., n)$ , <u>and</u> K is a dimensionless value. This normalized treatment normalization process ignores the influence of the spatiotemporal variation <u>of in</u> the underlying surface attributes on the parameters, while also simplifying the parameter classification and <u>the</u> number of <u>the</u> model parameters to a certain extent. Accordingly, the model parameters can be <u>further</u> divided <u>further</u> into rainfall-evaporation <u>onesparameters</u>, epikarst-\_zone <u>onesparameters</u> and underground-\_river <u>onesparameters</u>. Table 1 lists the parameters of the QMG model.

# **Table 1.** Parameters of <u>the QMG</u> model.

Because the QMG model has relatively few parameters, it is possible to calibrate them manually, which has the advantage that the operation is easy to implement is easy and does not require a special program for parameter optimization. However, the disadvantage is that itthis manual approach is subjective, which can lead to great uncertainty in the manual parameter calibration process. To compare the effects of parameter optimization on model

performance, this study used both manual parameter calibration and the improved chaotic particle swarm optimization algorithm (IPSO) were used for the automatic calibration of model parameters, and compared the effects of both on flood simulation were compared.

In general, the structure and parameters of a standard particle swarm optimization algorithm (PSO) are simple, with the initial parameter values obtained at random. For parameter optimization in high-dimensional multi-peakmultipeak hydrological models, the standard PSO is easily limited to a-local convergence and cannot achieve the optimal effect, whileand the late evolution of the algorithm may also cause problems, such as precocity and premature convergence or stagnant evolution, due to the 'inert' aggregation of particles, which seriously affects the efficiency of parameter selection. It is necessary to overcome the above problems and makeso that the algorithm can converge to the global optimal solution with a high probability. In parameter optimization for the QMG model, we improved the standard PSO algorithm by adding chaos theory, and developed the IPSO, where method; notably, 10 cycles of chaotic disturbances were added to improve the activity of the particles. The inverse mapping equation offor the chaotic variable is

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$$\begin{cases} X_{ij} = X_{\min} + (X_{\max} - X_{\min}) * Z_{ij} \\ Z_{ij}^{\cdot} = (1 - \alpha) Z^{*} + \alpha Z_{ij} \end{cases}$$
 (17)

where  $X_{ij}$  is the optimization variable for the model parameters,  $(X_{\text{max}} - X_{\text{min}})$  is the difference between itsthe maximum and its-minimum values of  $X_{ij}$ ,  $Z_{ij}$  is the variable before the disturbance is added-and,  $Z_{ij}$  represents the chaotic variables variable after a disturbance is added,  $\alpha - \alpha$  is a variable determined by the adaptive algorithm,  $(0 \le \alpha \le 1_{5})$ , and  $Z^{*}$  is the chaotic variable formed when the optimal particle maps mapped to the interval [0,1]. In parameter optimization, the The flowchart of the IPSO is shown in Fig. Figure 4.

Figure 4. Algorithm flow chart of IPSO.

### 3.3 Uncertainty analysis

Uncertainties in hydrological model simulation results usually originate from three aspects: factors: the input data, the model structure and the model parameters (Krzysztofowicz, 2014). In the present study, the input data (e.g., rainfall, flood events and some hydrogeological data) were first validated and pre-processed throughpreprocessed based on observations to reduce their uncertainties uncertainty.

Second, we simplified the structure of the QMG model to reduce the structural uncertainty. As a mathematical and physical model, a hydrological model hasis characterized by some uncertainty in flood simulation and forecasting because of the errors in the system structure and theselected algorithm (Krzysztofowicz and Kelly, 2000). The model in this study was designed with full consideration of the relationship between the amount of data required to build the model and itsmodel performance forin flood simulation and forecasting in karst regions, and the model's. The entire model framework was integrated through simple structures and easy-to-implement algorithms, using based on the concept of distributed hydrological modelling. Conventionally, the extentlevel of uncertainty is increased increases with the growing complexity of the model structure. We therefore ensured that the structure of the QMG model was simple when it was designed, and the double-layer model was divided into surface and underground double layer structures to reduce its structural uncertainty.

Third, we <u>focus</u> on analysing the uncertainty and sensitivity of <u>the</u>-model parameters and <u>theirthe applied</u> optimization method, <u>for which</u>; <u>specifically</u>, a <u>multi-parametric multiparametric</u> sensitivity analysis method (Choi et al., 1999; Li et al., 2020) was used to analyse the sensitivity of the parameters in the QMG model. The steps in the parameter sensitivity analysis are as follows.

# 1) Selection of <u>the</u> appropriate objective function

The Nash-Sutcliffe coefficient is widely used as the objective function to evaluate the performance of hydrological models (Li et al., 2020, 2021). It was); therefore, it was used to assess the QMG model in this study. Because the most important factor in flood forecasting

is the peak discharge, it is used in the Nash coefficient equation:

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$$NSC = 1 - \frac{\sum_{i=1}^{n} (Q_i - Q_i)^2}{\sum_{i=1}^{n} (Q_i - \overline{Q})^2},$$
 -(18)

where NSC is the Nash–Sutcliffe coefficient,  $Q_i$  [L/s] are is the observed flow discharges discharge,  $Q_i'$  [L/s] are is the simulated discharges discharge,  $\overline{Q}$  [L/s] is the average observed discharge and n [h] is the observation period.

### 2) Parameter sequence sampling

The Monte Carlo sampling method was used to sample 8000 groups of parameter sequences. The parametric sensitivity of the QMG model was analysed and evaluated by comparing the differences between the a priori and a posteriori distributions of the parameters.

### 3) Parameter sensitivity assessment

The a priori distribution of a model parameter means is its probability distribution, while and the a posteriori distribution refers to the conditional distribution calculated after sampling, which can be calculated based on the simulation result results of the parametric parameter optimization. If there is a significant difference between them the a priori distribution and the a posteriori distribution of a parameter, then the parameter being tested has a characterized by high sensitivity, whereas; conversely, if there is no obvious difference, then the parameter is insensitive. The parametrical priori distribution of a parametrical priori distribution of a parameter is calculated as

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$$\begin{cases} P_{i,j}(NSC_{i,j} \ge 0.85) = \frac{n}{N+1} \times 100 \\ \sigma_i = \sum_{j=1}^n \left(P_{i,j} - \overline{P_{i,j}}\right)^2 \end{cases}$$
 (19)

where  $P_{i,j}$  is the a priori distribution's probability associated with a given a priori distribution when  $NSC_{i,j} \ge 0.85 \cdot NSC_{i,j} \ge 0.85$ . We used a simulated Nash coefficient of 0.85 as the

threshold value, and n was the number of occurrences of a Nash coefficient greater than 0.85

in flood simulations. In each simulation, only a certain parameter was changed, while and the remaining parameters remained unchanged. If the Nash coefficient of this a simulation exceeded 0.85, then the flood simulation results were considered acceptable. The term  $\sigma_i$  is the difference between the an acceptable value and its the overall mean, which represents the parametric sensitivity (0 <  $\sigma_i$  < 1). The higher the  $\sigma_i$  value is, the more sensitive the parameter. N is In this study, N denotes the 8000 parameter sequences, and  $\overline{P_{i,j}}$   $\overline{P_{i,j}}$  is the average value of the a priori distribution.

### 3.4 –Model Settingsettings

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Once After the model was built and before it was run, some of the initial conditions had to be set before running it to simulate and forecast floods, such as the basin division scheme, the setting of initial soil moisture levels, and the assumption of the initial parameter rangeranges, were set. 1) In the study area, the entire Qingmuguan karst basin was divided into 893 KHRUs, including 65 surface river units, 466 hill slope units, and 362 underground river units. The division of these units formed the basis for calculating the process of runoff generation and convergence-calculations. 2) The initial soil moisture level was set to 0–100% of the saturationsaturated moisture content in the basin, and the specific soil moisture level before each flood had to bewas determined bythrough a trial calculation. 3) The waterheadhydraulic head boundary conditions offor the groundwater zone were determined by a tracer test in the basin, whereand a perennial stable water level in area adjacent to the groundwater- divide was used as the fixed waterheadhead value at the model boundary. The base flow of the underground river was determined to be 35 L/s frombased on the perennial average dry season runoff. 4) The rangeranges of initial parameters and the convergence conditions were assumedset before parameter optimization (Figure 4). 5) Parameter optimization and flood simulation validatedwere performed to validate the performance of the QMG model in karst basins.

#### 4 Results and discussion

# 4.1 Parameter Sensitivity Results sensitivity results

The number of parameters in a distributed hydrological model is generally large, and it is important to perform a sensitivity analysis of each parameter to quantitatively assess the impact of the different parameters on model performance. In the QMG model, each parameter was divided into four categories according to its sensitivity: (i) highly sensitive, (ii) sensitive, (iii) moderately sensitive, and (v) insensitive. In the calibration of model parameters, insensitive onesparameters do not need to be calibrated, which can greatly reduce the amountnumber of calculationcalculations and improve the efficiency of model operationoperations.

The flow process in the calibration period (14 April to 10 May 2017) was adopted to calculate the sensitivity of the model parameters, for which the calculation principle was and calculations were based on equation (19), and the). The parameter sensitivity results are calculated in Table 2.

Table 2 Parametric sensitivity results infor the QMG model.

In Table 2, the value of  $\sigma_i \sigma_i$  [equation (19)] represents a parameter's sensitivity, and the higher the value is, the more sensitive the parameter is. From the . The results in Table 2, it was found indicate that the rainfall infiltration coefficient, rock permeability coefficient, rock porosity, –and the related parameters of related to the soil water content, such as the saturated water content, and field capacity, were are sensitive parameters. The order of parameter sensitivity wasis as follows: infiltration coefficient > permeability coefficient > rock porosity > specific yield > saturated water content > field capacity > flow direction > thickness > slope > Soilsoil coefficient > channel roughness > evaporation coefficient.

In the QMG model, parameters are classified as highly sensitive, sensitive, moderately sensitive, and insensitive according to their influence on the flood simulation results. In Table 4, we <u>divideddivide</u> the sensitivity of model parameters into four levels based on the  $\sigma_i \sigma_i$  value: 1) highly sensitive parameters,  $0.8 < \sigma_i \sigma_i < 1$ ; 2) sensitive parameters,

 $0.65 < \sigma_i \ \sigma_i < 0.8; 3$ ) moderately sensitive parameters,  $0.45 < \sigma_i \ \sigma_i < 0.65;$  and 4) insensitive parameters,  $0 < \sigma_i \ \sigma_i < 0.45$ . The highly sensitive parameters were are the infiltration coefficient, permeability coefficient, rock porosity, and specific yield. The sensitive parameters were are the saturated water content, field capacity, and thickness of the epikarst zone. The moderately sensitive parameters were are the flow direction, slope, and soil coefficient. The insensitive parameters were channel roughness and the evaporation coefficient.

# 4.2 Parametric Optimization optimization

In total, the QMG model <u>hasincludes</u> 12 parameters, of which only eight need to be optimized, which is relatively few for distributed models. The <u>parameters of flow</u> direction and slope as well as the insensitive parameters of, as channel roughness and the evaporation coefficient, which are insensitive parameters, need not be calibrated, which; this approach can improve the convergence efficiency of the model parameter optimization process.

In the study area, 18 karst floods during the period of from 14 April 2017 to 10 June 2019 were recorded at the underground river outlet to validate the effects of the QMG model in karst hydrological simulations. The calibration period was 14 April to 10 May 2017 at the beginning of the flow process, with the remainder of the time being period used as the validation period. In the QMG model, the IPSO algorithm was used to optimize the model parameters. To showdemonstrate the necessity of need for parameter optimization for the distributed hydrological model, the study specifically compared the flood simulations simulation results obtained using the initial parameters of the model (without parameter calibration) and the optimized parameters. Fig. were compared. Figure 5 shows the iteration process of iterative parameter optimization process for the QMG model.

Figure 5 Iteration process of parametric Iterative parameter optimization process.

Fig.Figure 5 shows that almost all parameters fluctuated widely considerably fluctuate at the beginning of the optimization, and then after about approximately 15 iterations of the iterative optimization calculations, most of the linear fluctuations become significantly less volatile variable, which indicated indicates that the algorithm tended tends to

converge (possibly only locally). When the number of iterations exceeded 25, all parameters remainedremain essentially unchanged, meaningsuggesting that the algorithm had converged (at this point there was, global convergence was achieved). It took only 25 iterations to reach aachieve definite convergence of for parameters in the parameter rates with this applied IPSO algorithm, which; thus, this approach is extremely efficient in terms of the parameter optimization of distributed hydrological models. In previous studies of the parametric optimization for of the parameters of the Karst-Liuxihe model in similar basin areas, 50 automatic parameter optimization iterations iterative steps were required to reach convergence in automatic parameter optimization (Li et al., 2021), demonstrating the effectiveness of the IPSO algorithm.

To evaluate the effect of parameter optimization, the convergence efficiency of the algorithm, and, more importantly, the parameters after calibration were used to simulate floods. Fig.assessed in flood simulation cases. Figure 6 shows the flood simulation effects results.

Figure 6 Flow simulation results of the QMG model based on parameter optimization.

Fig.Figure 6 shows that the flows simulated byfollowing parameter optimization were better than those simulated byobtained with the initial model parameters. The simulated flow processes values based on the initial parameters were relatively small, with the simulated peak flows in particular being notably smaller than the observed values, and; additionally, there were large errors between the twosimulated and observed values. In contrast, the simulated flows produced by the QMG model after parameter optimization were very similar to the observed values, which indicates that calibration of the model parameters is was necessary and that there was an improvement in parameter optimization achieved through the use of the IPSO algorithm in this study. In addition, it was found that the flow simulation effect was better in the calibration periods than in the validation periods (Fig. 6).

To compare the results of the flow processes simulation with the initial model parameters and the optimized parameters, six evaluation indices (Nash–Sutcliffe coefficient, correlation coefficient, relative flow process error, flood peak error,

water balance coefficient, and peak time error) were applied in this study, and the results are presented in Table 3.

Table 3 Flood simulation evaluation index through indices following parametric optimization.

Table 3 shows that the evaluation indices of the flood simulations after parametric parameter optimization were better than those of obtained with the initial model parameters. The average values of the initial parameters for these six indices were 0.81, 0.74, 27%, 31%, 0.80, and 5 h, respectively. For the optimized parameters, the average values were 0.90, 0.91, 16%, 14%, 0.94, and 3 h, respectively. The flood simulation effects after parameter optimization clearly improved, implying that parameter optimization for the QMG model is necessary, and that the IPSO algorithm for parameter optimization is an effective approach that can greatly improve the convergence efficiency of parameter optimization, and also ensure that the model performs well in flood simulations.

# 4.3 Model Validation in Flood Simulations flood simulations

Following parameter optimization, we simulated the whole flow process (14 April 2017 to 10 June 2019-) based on the optimized and initial parameters of the QMG model (Fig. 6), which enabled a visual reflection of the model used in the simulation of 6). This approach allowed us to visually assess a long series of flow processes obtained with the model. To reflect the simulation effect of the model for different flood events, we divided the whole flow process into 18 flood events, and then used the initial parameters of the model and the optimized parameters, respectively, to verify the model performance in flood simulations. Fig. Figure 7 and Table 4 show the flood simulation effects and theirthe calculated evaluation indices using both the initial and the optimized parameters.

Figure 7 Flood simulation effects based on <u>the</u> initial and optimized parameters.

Table 4 Flood simulation indices for model validation.

Fig.Figure 7 shows that the flood simulation results values obtained using the initial parameters were smaller than the observed values, and the model performance improved in flood simulations after parameter optimization. The simulated flood processes were in good

agreement with observations, and <u>flood peak flows</u> were especially <u>effective for simulating</u> <u>flood peak flows.well simulated</u>. From <u>the</u> flood simulation indices in Table 4, the average water balance coefficient based on the initial parameters was 0.69, i.e., much less than 1, indicating that the simulated water in the model was unbalanced. After parameter optimization, the average value was 0.92, indicating that parameter optimization had a significant impact on the <u>model</u> water balance calculation.

Table 4 shows that the average values of the six indices (Nash–Sutcliffe coefficient, correlation coefficient, relative flow process error, flood peak error, water balance coefficient, and peak time error) for the initial parameters were 0.79, 0.74, 26%, 25%, 0.69, and 5 h, respectively, while for the optimized parameters, the average values were 0.92, 0.90, 10%, 11%, 0.92, and 2 h, respectively. All evaluation indices improved after parameter optimization, with the average values of the Nash coefficient, correlation coefficient, and water balance coefficient increasing by 0.13, 0.16, and 0.23, respectively. TheAdditionally, the average values of the relative flow process error, flood peak error, and peak time error decreased by 15%, 14%, and 3 h, respectively. These reasonable flood simulation results confirmed that parameter optimization bywith the IPSO algorithm was necessary and effective for the QMG model.

Compared with the overall flow process simulation shown in Figure 6, each flood process was better simulated by the QMG model (Fig. 7). This was because Notably, in the function of the QMG model and itsthe applied algorithm design, the main consideration was the calculation of the is flood process, but calculations, and the correlation algorithm of the for dry—season runoff was not sufficiently described—well enough. For example, equations (12)—(15) are used in the flood convergence algorithm. As a result Consequently, the model is not good at simulating other flow processes, such as dry—season runoff, leading to a-low accuracy in simulations of the overall flow process. The next phase of our research will focus on refining the algorithm related to dry—season runoff and improving the comprehensive performance of the model.

### 4.4 Uncertainty analysis

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# 4.4.1 Assessment and reduction of uncertainty

In general, the uncertainty in model simulation is due mainly to three aspects of the model factors: (i) the uncertainty of its input data, (ii) the uncertainty of its model structure and algorithm and (iii) the uncertainty of its model parameters. In the practical application of a hydrological model, these three uncertainties are usually interwoven, which leads to the overall uncertainty of the final simulation results (Krzysztofowicz, 2014). Therefore, the presentthis study focused on the uncertainties in the input data, the model structure and the parameters to reduce the overall uncertainty of the simulation results.

First, the input data—mainly rainfall-runoff data and hydrogeological data—were pre-processed, preprocessed, which substantially reduced their uncertainty. Second, we simplified the structure of the OMG model, which is reflected in the fact that it has with only two structural layers of spatial structure in the horizontal and vertical directions. This relatively simple structure greatly reduced greatly the modelling uncertainty due to the model structure. In contrast, the underground structure of our previous Karst-Liuxihe model (Li et al., 2021) hasincluded five layers, which leadsled to greatconsiderably uncertainty. Third, appropriate algorithms for runoff generation and confluence were selected. Different In general, different models were designed for different purposes, which leads to greatnotable differences in the algorithms used. In the QMG model, most of the rainfall-runoff algorithms used have been validated by the research results of others, and some of them were improved to suitfor karst flood simulation and forecasting by with the QMG model. For example, the algorithm for the generation of excess infiltration runoff [Eq.-\_(2)] was an improvement of the version used in the Liuxihe model (Chen, 2009, 2018; Li et al., 2020). Finally, the algorithm for parameter optimization was improved. Considering the shortcomings of the standard PSO algorithm-that, which tends to converge locally, this study developed the IPSO for parameter optimization was developed in this study by adding chaotic perturbation factors. The flood simulation results after parameter optimization were much better than those efobtained with the initial model parameters (Figs. 6 and 7 and Tables 2 and 3), which indicates that parameter optimization is necessary

for a-distributed hydrological modelmodels and can reduce the uncertainty of the model parameters.

# 4.4.2 Parameter sensitivity Sensitivity analysis

The parameter\_sensitivity results in Table 2 show that the rainfall\_infiltration coefficient in the QMG model was the most sensitive parameter. It and was the key to determining the generation of excess infiltration surface runoff and separatingthe separation of surface runoff from subsurface runoff. If the rainfall infiltration coefficient wasis greater than the infiltration capacity, excess infiltration surface runoff waswill be generated on the exposed karst landforms; otherwise, all rainfall wouldwill infiltrate to meet the water deficit ininto the vadose zone; and then continue to seep—down into the underground river system, eventually flowing out of the basin through the underground river outlet. The confluenceflow modes of surface runoff and underground runoff were completely different, resulting in a large difference in the simulated flow results. Therefore, the rainfall infiltration coefficient had the greatest impact on the final flood simulation results.

Other highly sensitive parameters, such as the rock permeability coefficient, rock porosity and specific yield, were used as the basis for dividing between slow flow in karst fissures and rapid flow in conduits. The division of slow and rapid flows also had a greatconsiderable impact on the discharge at the outlet of the basin. Slow flow plays an important role in water storage in a karst aquiferaquifers and is very important for the replenishment of river base flow in the dry season. Rapid flow in large conduit systems dominates the flood runoff and is the main component of the flood water volume in the flood season.

Parameters related to the soil water content, including the saturated water content, field capacity and thickness, were sensitive parameters and had a large influence on the flood simulation results. This is because Notably, the soil moisture content prior to flooding affects how flood flows rise and when peaks occur. If the soil is already very wet or even saturated before the flooding, thea flood will rise quickly to and reach a peak, and the process line of the flood peak flow will be sharp and thin short. This type of flood process forms can easily

occur and can lead to <u>a</u> disaster-causing flood <u>eventsevent</u>. In contrast, if the soil in the basin is very dry before <u>the</u>-flooding, the rainfall will first <u>meet the water shortage of saturate</u> the vadose zone, <u>and after it is replenished; then</u>, the rainfall will infiltrate into the underground river. The flood peak <u>of at</u> the river basin outlet is therefore delayed.

The moderately sensitive parameters were the flow direction, slope and the soil coefficient. They; they had a specific influence on the flood simulation results, but the influence was not as great as that of the highly sensitive and sensitive parameters. The insensitive parameters were channel roughness and the evaporation coefficient. The amount of water lost byvia evapotranspiration is very small incompared to the total volume of flood water, and itevapotranspiration was therefore the least—sensitive parameter in the QMG model.

#### 5 Conclusions

This In this study proposed, a new distributed physically based hydrological model, i.e., the QMG model, was proposed to accurately simulate floods accurately in karst trough and valley landforms. The main conclusions of this paper are as follows.

ThisThe QMG model has—a high application potential in karst hydrology simulations. Other distributed hydrological models usually have multiple structures, resulting in the need for a large amount of data to build models in karst areas (Kraller et al., 2014). The QMG model has only a double-layer structure, with a-clear physical meaning, and a small amount of basic data—is needed to build the model in karst areas, such as some necessary hydrogeological data—is needed to build the model in karst areas. For example, the distribution and flow direction of underground rivers is required, whichmust be known and can be inferred from a-tracer test, leading to atests at low modelling—cost. There were are fewer parameters in the QMG model than in other distributed hydrological models, with only 10 parameters that neededneed to be calibrated.

The flood <u>simulation simulations</u> after parameter optimization <u>waswere</u> much better than <u>the simulation usingthose based on</u> the initial model parameters. After parameter optimization, the average values of the Nash coefficient, correlation coefficient and water

balance coefficient increased by 0.13, 0.16 and 0.23, respectively, whileand the average relative flow process error, flood peak error and peak time error decreased by 15%, 14% and 3 h, respectively. Parameter optimization is necessary for a distributed hydrological modelmodels, and the improvement of the improved IPSO algorithm in this study was an effective way to achieve this.

In the QMG model, the rainfall infiltration coefficient  $I_c$ , the rock permeability coefficient K, the rock porosity  $R_p$  and the parameters related to the soil water content were sensitive parameters. The order of parameter sensitivity was infiltration coefficient > permeability coefficient > rock porosity > specific yield > saturated water content > field capacity > flow direction > thickness > slope > soil coefficient > channel roughness > evaporation coefficient.

This QMG model is suitable for karst trough <u>and valley basinslandforms</u>, <u>such as those in the study area</u>, where the topography is conducive to the spread of flood water. Whether In the future, it must be verified whether this model is applicable to other karst areas in non-trough valley regions still needs to be verified in the future studies. and landforms. In addition, <u>although the studied</u> basin area is very small, where but the hydrological similarity between among different small basin areas varies greatly (Kong and Rui, 2003). The size of the area to be modelled has a great influence on the choice of model spatial resolution for modelling (Chen et al., 2017). Therefore, it must be determined whether the QMG model is suitable for flood forecasting in large karst basins needs to be determined.

#### Model development.

This The QMG model presented in this study uses—the Visual Basic language programming. The general framework of the model and the algorithm consist of three parts: the modelingmodelling approach, the algorithm of rainfall-runoff generation and confluenceconvergence algorithm, and the parameter optimization algorithm. As a free and open—source hydrological modelingmodelling program (QMG model-V1.0), we provide all modelingmodelling packages, including the model code, installation package, simulation data package and user manual, free of charge. It is important to note that the model we provide areis for scientific research purposes only and should not be used for any commercial purposes—(Creative Commons Attribution 4.0 International-).

Model The model installation program can be downloaded from ZENODO, citeZenodo and

16). QMG model-V1.0.

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819	http://doi.org/10.5281/zenodo.4964701, and http://doi.org/10.5281/zenodo.4964697)
820	(registration required).  User The user manual can be downloaded from
821	http://doi.org/10.5281/zenodo.4964754.—
822	Code availability.
823	All eodecodes for the QMG model-V1.0 in this paper are available and free, and the code
824	can be downloaded from ZENODO, Cite as JI LI. (2021, June 16). QMG model-V1.0 code
825	(Version v1.0).—Zenodo- at http://doi.org/10.5281/zenodo.4964709 (registration required)
826	(Cite as JI LI. (2021, June 16). QMG model-V1.0 code (Version v1.0). Zenodo).
827	Data availability.—
828	All data used in this paper are available, findable, accessible, interoperable, and reusable.
829	The simulation data and modelling data package can be downloaded from
830	http://doi.org/10.5281/zenodo.4964727. The DEM was downloaded from the Shuttle Radar
831	Topography Mission database at <a href="http://srtm.csi.cgiar.org">http://srtm.csi.cgiar.org</a> . The land use-type data were
832	downloaded from <a href="http://landcover.usgs.gov">http://landcover.usgs.gov</a> , -and the soil-type data were downloaded from
833	http://www.isric.org. These data were last accessed on 15 October 2020.
834	Author contributions. JIL was responsible for the calculations and writing of the whole
835	paper. DY helped conceive the structure of the model. ZF and JL provided significant
836	assistance in the English translation of the paper. MM provided flow data offrom the study
837	area.—
838	Competing interests.
839	The authors declare that they have no conflicts of interest.
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851	Guangxi 202009, KDL & Guangxi 202012).

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## 1070 **Tables**

1074

1071 Table 1 Parameters of the QMG model.

Parameters-	Variable name	Physical property
Infiltration coefficient	$I_c$	<b>Meteorology</b> Meteorological
Evaporation coefficient	λ	Vegetation cover
Soil thickness	h	Karst aquifer
Soil coefficient	$S_b$	Soil type
Saturated water content	$S_c$	Soil type
Rock porosity	$R_p$	Karst aquifer
Field capacity	$F_c$	Soil type
Permeability coefficient	K	Karst aquifer
Flow direction	$F_d$	Landform
Slope	$S_{O}$	Landform
Specific yield	$S_{y}$	Karst aquifer
Channel roughness	n	Landform–

Table 2 Parametric sensitivity results in the QMG model

$I_c$	λ	h	$S_b$	$S_c$	$S_{y}$	$F_d$	$S_0$	$R_p$	$F_c$	K	n
0.92	0.24	0.71	0.58	0.8	0.83	0.74	0.68	0.86	0.78	0.89	0.36

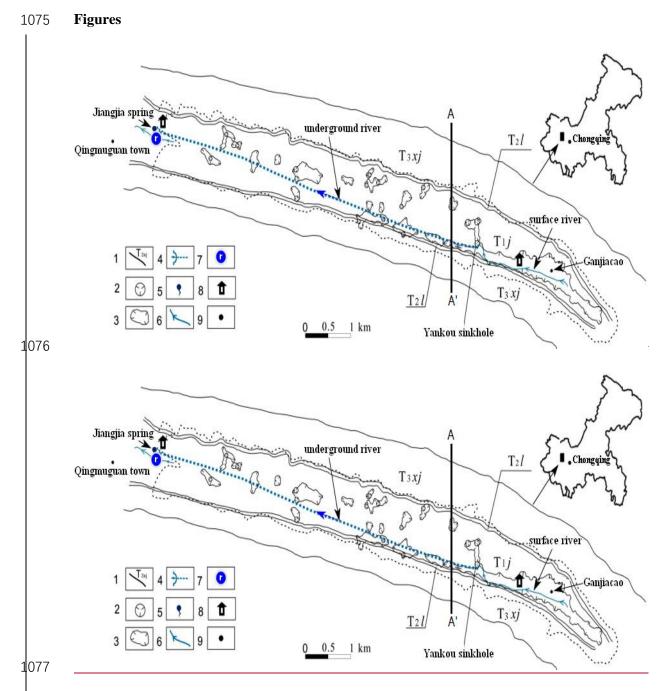
Table 3 Flood simulation evaluation index through parametric optimization.

Parameter	Parameter types	Nash	Correlation	Relative	Flood	Water	]
optimization		coefficient	coefficient	flow	peak	balance	
				process	error/%	coefficient	•
				error/%			(ł
calibration Calibration	<del>initial</del> <u>Initial</u>	0.82	0.77	24	29	0.82	
periods	optimized Optimized	0.91	0.94	14	12	0.95	
validation Validation	<del>initial</del> <u>Initial</u>	0.79	0.71	29	32	0.77	
periods	optimized Optimized	0.88	0.87	18	16	0.92	
average Average	<del>initial</del> <u>Initial</u>	0.81	0.74	27	31	0.8	
value	optimized Optimized	0.9	0.91	16	14	0.94	

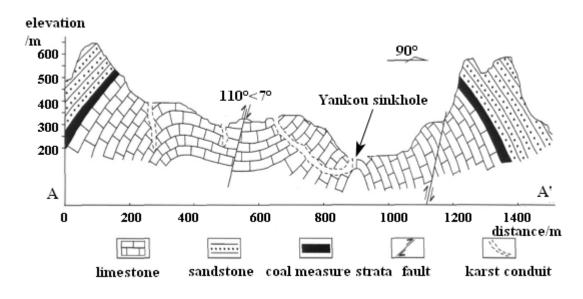
Table 4 Flood simulation indices for model validation.

Floods	Parameter types	Nash coefficient	Correlation coefficient	Relative flow process error/%	Flood peak error/%	Water balance coefficient	Peak time error, (/(hour
2017042408-	<del>initial</del> <u>Initial</u>	0.77	0.7	28	29	0.71	-5
2017042406-	optimized Optimized	0.95	0.89	11	15	0.88	-2
2017050816-	<del>initial</del> Initial	0.78	0.71	19	19	0.76	-4
201/030810-	optimized Optimized	0.92	0.88	11	9	0.94	-2
2017061518-	<del>initial</del> Initial	0.76	0.6	25	32	0.63	-5

	optimized Optimized	0.91	0.93	12	11	0.95	-3
2017071015-	<del>initial</del> Initial	0.78	0.82	25	37	0.64	-4
2017071013-	optimized Optimized	0.92	0.87	8	7	0.94	-2
2017091512-	<del>initial</del> <u>Initial</u>	0.81	0.62	21	16	0.78	-5
2017091312-	optimized Optimized	0.9	0.92	13	10	0.9	-4
2017100815-	<del>initial</del> <u>Initial</u>	0.75	0.68	30	26	0.62	-2
2017100813-	optimized Optimized	0.94	0.86	11	15	0.92	-1
2018052016-	<del>initial</del> <u>Initial</u>	0.78	0.68	25	21	0.67	5
2018032010-	optimized Optimized	0.91	0.93	10	13	0.94	2
2018060815-	<del>initial</del> <u>Initial</u>	0.82	0.79	27	22	0.69	-6
2018000813-	optimized Optimized	0.9	0.92	11	12	0.93	-4
2018071212-	<del>initial</del> <u>Initial</u>	0.84	0.75	26	24	0.61	5
20160/1212-	optimized Optimized	0.91	0.88	8	15	0.92	3
2018081512-	<del>initial</del> <u>Initial</u>	0.71	0.78	26	24	0.78	-4
2010001312-	optimized Optimized	0.89	0.94	12	11	0.89	-3
2018090516-	<del>initial</del> <u>Initial</u>	0.85	0.68	28	23	0.68	-5
2018090310-	optimized Optimized	0.93	0.87	12	10	0.92	-2
2018092514-	<del>initial</del> <u>Initial</u>	0.79	0.78	23	19	0.59	5
2016092314-	optimized Optimized	0.88	0.88	9	11	0.89	2
2018101208-	<del>initial</del> <u>Initial</u>	0.78	0.81	28	25	0.63	5
2010101200-	optimized Optimized	0.92	0.94	11	10	0.94	2
2018111208-	<del>initial</del> <u>Initial</u>	0.79	0.81	25	24	0.65	-6
2010111200-	optimized Optimized	0.94	0.86	13	12	0.92	-2
2019042512-	<del>initial</del> <u>Initial</u>	0.78	0.8	26	36	0.8	5
2019042312-	optimized Optimized	0.89	0.94	9	16	0.93	2
2019051513-	<del>initial</del> <u>Initial</u>	0.84	0.77	32	27	0.79	4
2019031313-	optimized Optimized	0.91	0.88	9	13	0.95	2
2019052516-	<del>initial</del> <u>Initial</u>	0.74	0.75	29	26	0.63	-5
2019032316-	optimized Optimized	0.92	0.86	7	15	0.96	-2
2010070710	<del>initial</del> <u>Initial</u>	0.85	0.83	28	25	0.78	-4
2019060518-	optimized Optimized	0.95	0.96	10	12	0.92	-2
average Average	<del>initial</del> <u>Initial</u>	0.79	0.74	26	25	0.69	5
value	optimized Optimized	0.92	0.9	10	11	0.92	2



1- stratigraphic boundary, 2-sinkhole, 3- karst depression, 4- underground river, 5-karst spring, 6-surface river, 7-river gauge, 8- rain gauge, and 9- geographical name
a. Qingmuguan karst basin (modified from Yu et al., 2016)



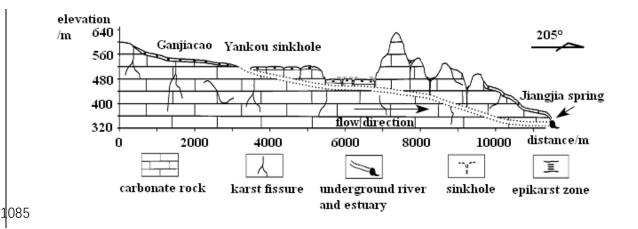
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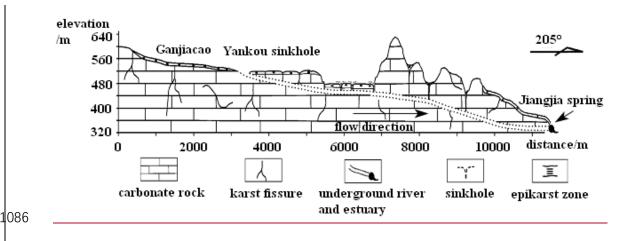
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elevation /m 90° 600 500 110°<7° Yankou sinkhole 400 300 200 A' Α 0 200 600 1000 400 800 1200 1400 distance/m ..... sandstone coal measure strata fault karst conduit limestone

b. Lithologic cross section AA' of the Yankou sinkhole/AA' (modified from Zhang,\_ 2012)





c. Longitudinal profile of the study area (modified from Yang et al.,2008)

Figure 1 The Qingmuguan karst basin.

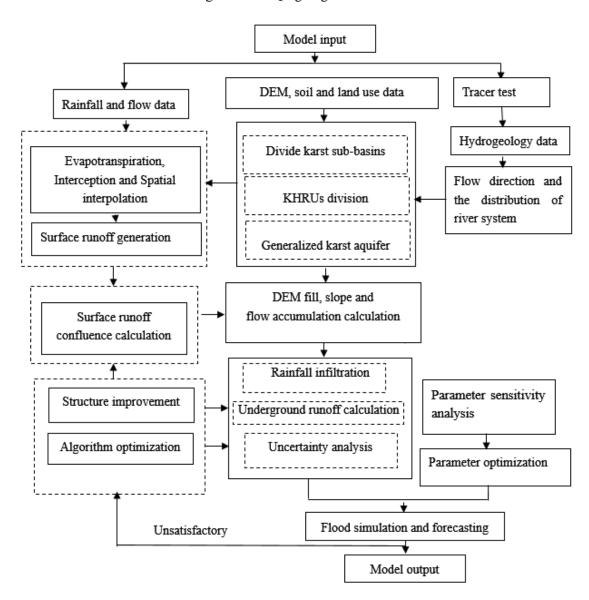


Figure 2 Modeling flow chart Modelling flowchart of the QMG (Qingmuguan) model.

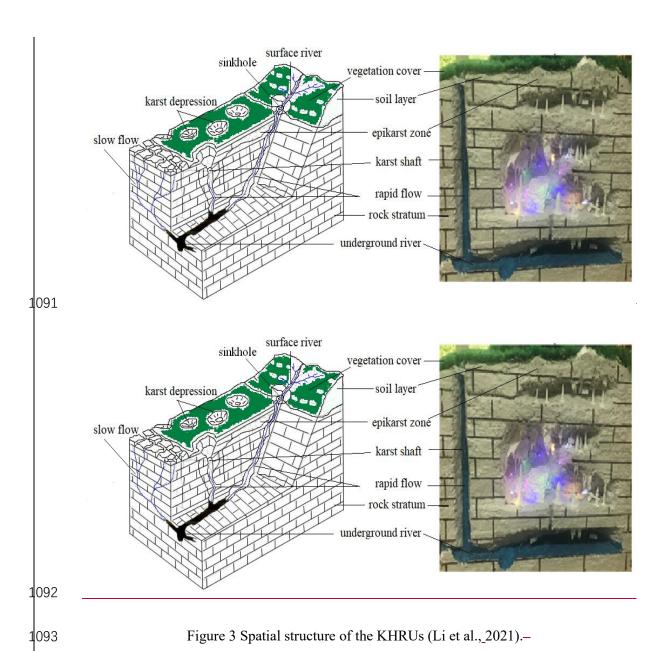
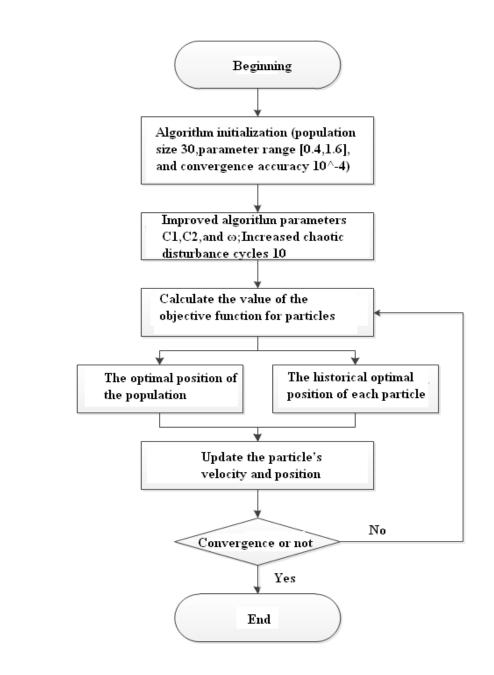
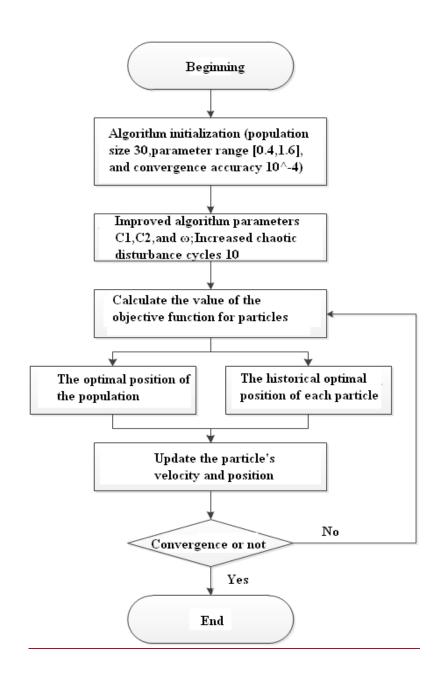


Figure 3 Spatial structure of the KHRUs (Li et al., 2021).—





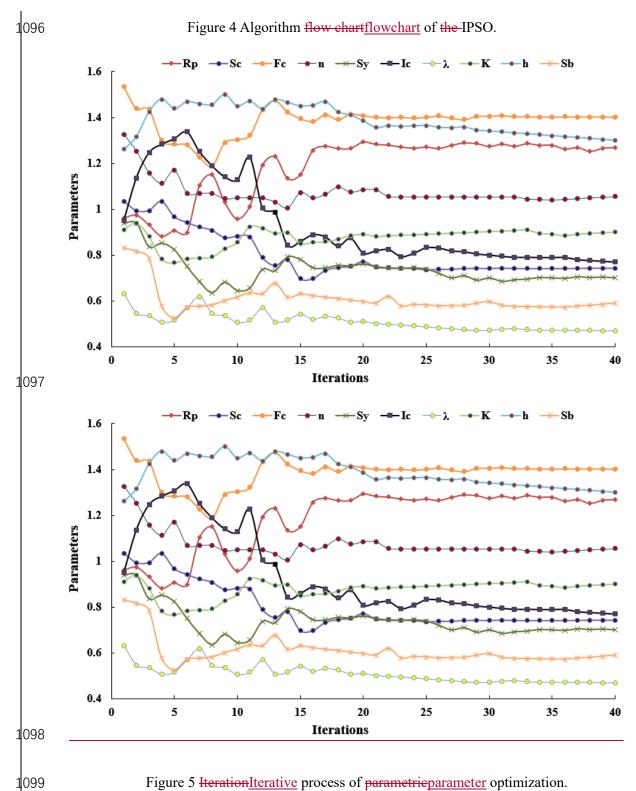


Figure 5 <u>Iteration Iterative</u> process of <u>parametric parameter</u> optimization.

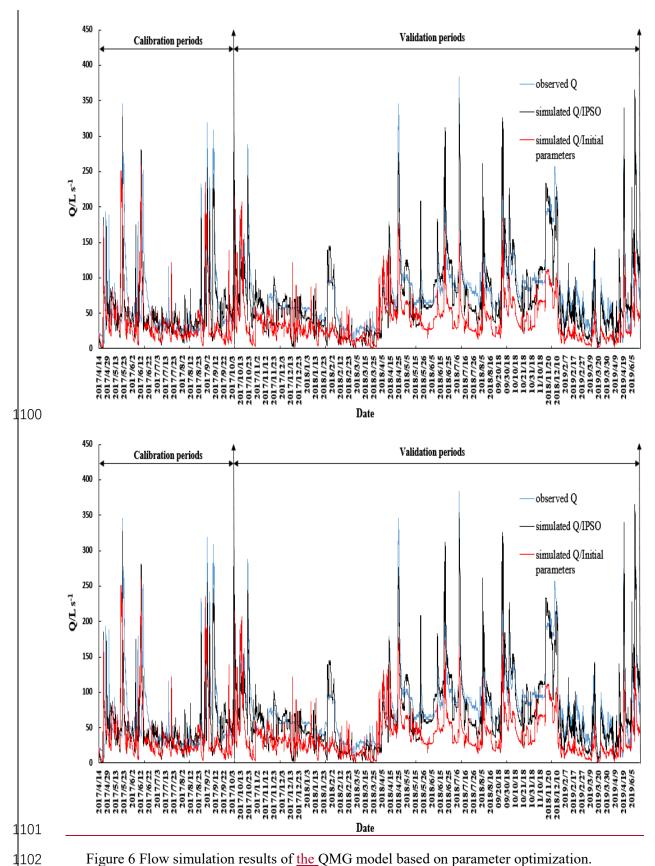
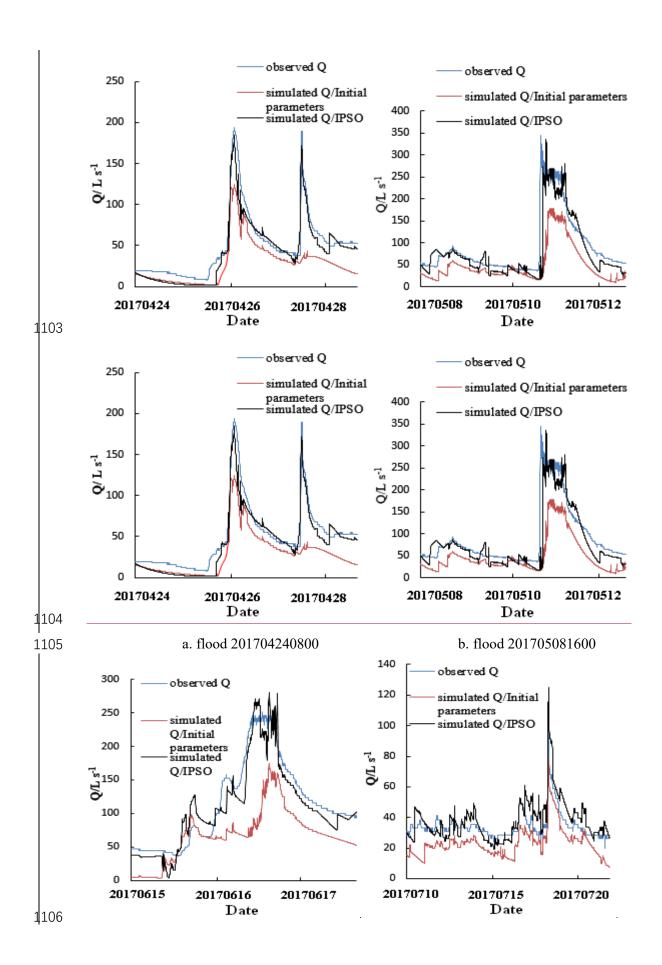
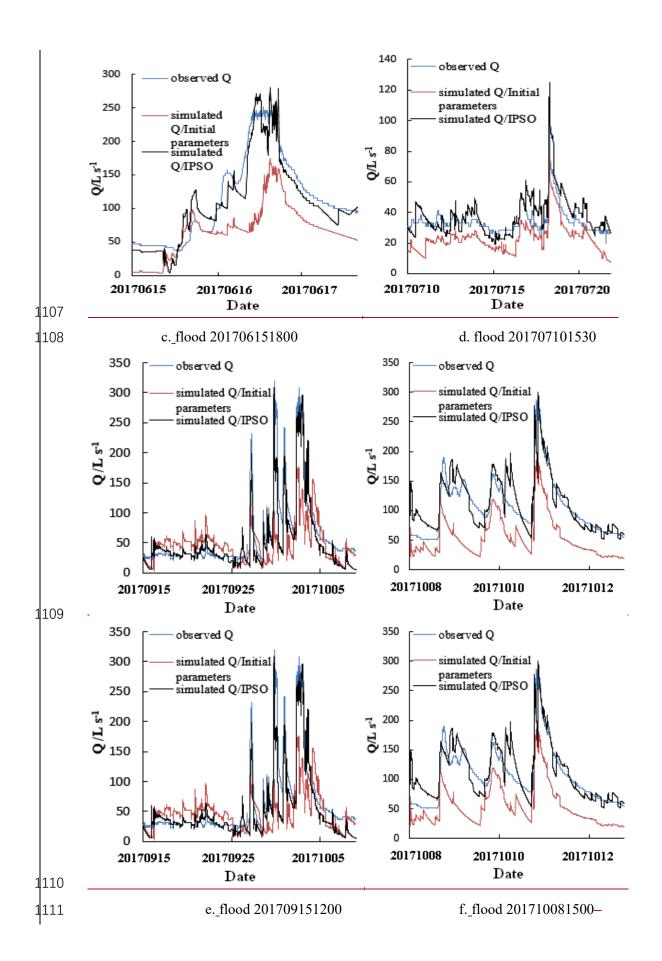
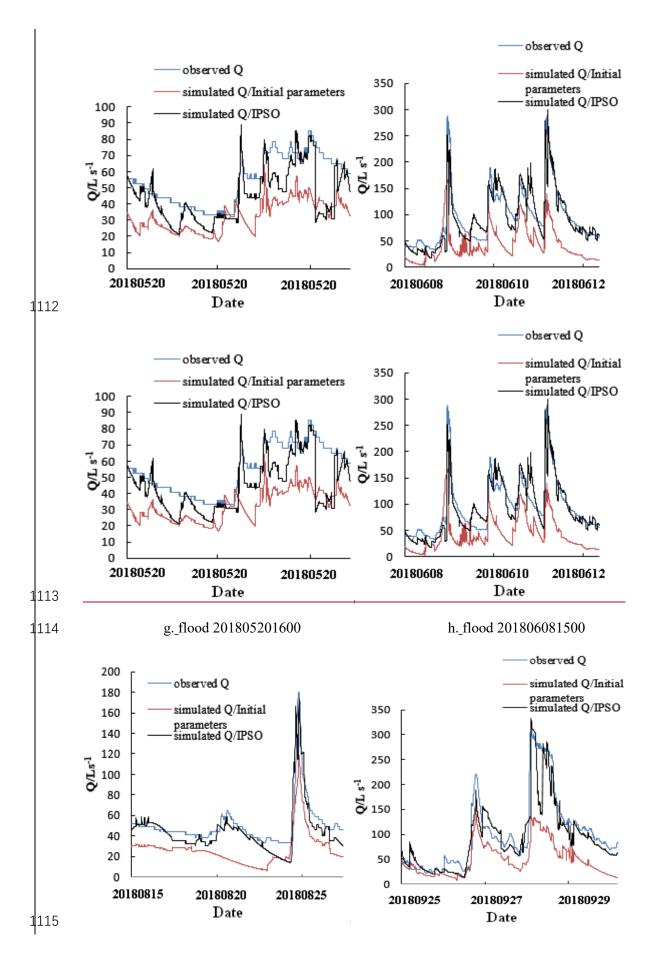


Figure 6 Flow simulation results of the QMG model based on parameter optimization.







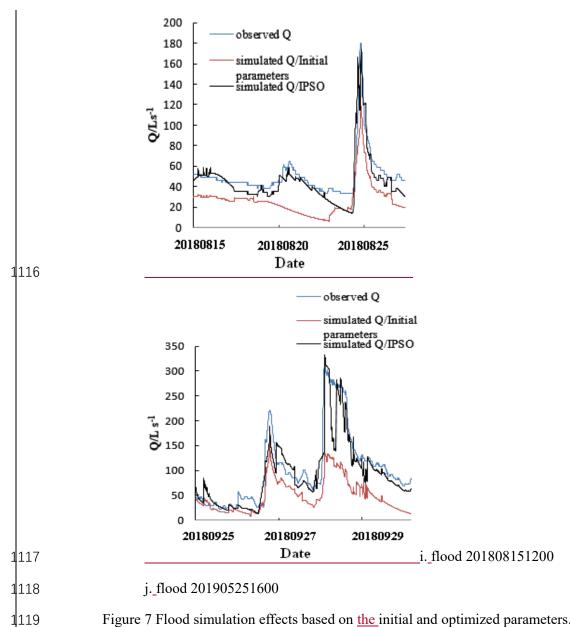


Figure 7 Flood simulation effects based on the initial and optimized parameters.