

# The Community Inversion Framework v1.0: a unified system for atmospheric inversion studies: Supplement

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Table S1: Plugin types in pyCIF

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★ obsoperator:	<ul style="list-style-type: none"> <li>- purpose: maps data from the control space to the observation space and conversely</li> <li>- inheritance: <ul style="list-style-type: none"> <li>- controlvect</li> <li>- obsvect</li> <li>- model</li> </ul> </li> <li>- metadata none</li> <li>- data none</li> <li>- methods: <ul style="list-style-type: none"> <li>- obsoper: <math>\mathbf{x} \rightarrow \mathcal{H}(\mathbf{x})</math> <math>\mathcal{H}^*(\mathbf{y}^*) \leftarrow \mathbf{y}^*</math></li> </ul> </li> <li>- calls: <ul style="list-style-type: none"> <li>- controlvect.<math>\Pi_{\chi}^{\delta}</math>: <math>\mathbf{x} \leftrightarrow \mathbf{x}_{\text{model}}</math></li> <li>- model.<math>\Pi_{\mathcal{F}}^{\mathcal{F}}</math>: <math>\mathbf{x}_{\text{model}} \leftrightarrow \text{model inputs}</math></li> <li>- model.run: model inputs <math>\leftrightarrow</math> model outputs</li> <li>- model.<math>\Pi_{\mathcal{C}}^{\mathcal{M}}</math>: model outputs <math>\leftrightarrow \mathbf{y}_{\text{model}}</math></li> <li>- obsvect.<math>\Pi_{\mathcal{M}}^{\mathcal{Y}}</math>: <math>\mathbf{y}_{\text{model}} \leftrightarrow \mathbf{y}^{\circ}</math></li> </ul> </li> </ul>
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★ controlvect:	<ul style="list-style-type: none"> <li>- purpose: initializes the control vector (including metadata) and uncertainties and computes projections from and to the control space</li> <li>- comments: needs metadata from the model (e.g., resolution) and the domain to carry out projections</li> <li>- inheritance: <ul style="list-style-type: none"> <li>- domain</li> <li>- model</li> </ul> </li> <li>- metadata: <ul style="list-style-type: none"> <li>- components (e.g., fluxes, initial conditions, etc.)</li> <li>- dimension</li> <li>- correlation patterns</li> </ul> </li> <li>- data: <ul style="list-style-type: none"> <li>- <math>\mathbf{x}_b</math></li> <li>- <math>\mathbf{B}</math> if stored, main components otherwise</li> </ul> </li> <li>- methods: <ul style="list-style-type: none"> <li>- <math>\Pi_{\chi}^{\delta}</math>: <math>\mathbf{x} \leftrightarrow \mathbf{x}_{\text{model}}</math></li> <li>- <math>\Pi_{\chi}^{\mathcal{M}}</math>: <math>\mathbf{x} \rightarrow \chi \equiv \mathbf{B}_{1/2}\mathbf{x}</math></li> <li>- <math>\Pi_{\mathcal{M}}^{\mathcal{X}}</math>: <math>\chi \rightarrow \mathbf{x} \equiv \mathbf{B}_{1/2}\chi</math></li> <li>- init_<math>\mathbf{B}</math>: some data <math>\rightarrow \mathbf{B}</math></li> </ul> </li> <li>- calls: <ul style="list-style-type: none"> <li>- domain.resolution</li> </ul> </li> </ul>
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★ obsvect:	<ul style="list-style-type: none"> <li>- purpose: initializes the observation vector (including metadata) from the measurements and computes projections from and to the observation space</li> <li>- inheritance: <ul style="list-style-type: none"> <li>- domain</li> <li>- measurements</li> </ul> </li> </ul>
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- metadata	- species		
	- observation type (in situ, satellite, etc.)		
	- correlations if any		
- data	- $\mathbf{y}^o$		
	- $\mathbf{R}$ if stored, main components otherwise		
- methods:	- $\mathbf{\Pi}_{\mathcal{M}}^{\mathcal{Y}}$ :	$\mathbf{y}_{\text{model}}$	$\leftrightarrow \mathbf{y}^o$
	- $\mathbf{\Pi}_{\mathcal{O}}^{\mathcal{Y}}$ :	$\mathbf{y}_{\text{meas}}$	$\leftrightarrow \mathbf{y}^o$
	- $\mathbf{R}^{-1} \cdot ()$ :	$\mathbf{y}$	$\rightarrow \mathbf{y} = \mathbf{R}^{-1}\mathbf{y}$
- calls:	- domain.resolution		

* model:	- purpose:	drives the transport model, prepares inputs and extracts outputs to CIF-compatible structures	
	- inheritance:	none	
	- metadata	- resolution	
		- computation mode	
		- sub-periods if any	
		- chemistry if any	
		- model-specific configuration	
		- path to fixed inputs (e.g., meteo data)	
	- data	none	
	- methods:	- run:	model inputs $\rightarrow$ model outputs
		- $\mathbf{\Pi}_{\mathcal{F}}^{\mathcal{C}}$ :	$\mathbf{x}_{\text{model}}$ $\leftrightarrow$ model inputs
		- $\mathbf{\Pi}_{\mathcal{C}}^{\mathcal{M}}$ :	model output $\leftrightarrow \mathbf{y}_{\text{model}}$
	- calls:	none	

* simulator:	- purpose:	computes the cost function and its gradient	
	- inheritance:	observation operator	
	- metadata	none	
	- data	none	
	- methods:	simul:	$\chi \rightarrow (J(\chi), \nabla_{\chi} J)$
	- calls:	- obsoperator.obsoper:	$\mathbf{x} \rightarrow \mathcal{H}(\mathbf{x})$
			$\delta \mathbf{y} \rightarrow \mathbf{H}^* \delta \mathbf{y}$

* minimizer:	- purpose:	minimizes a function starting from a given point	
	- inheritance:	observation operator	
	- metadata	none	
	- data	none	
	- methods:	minimize:	$(\chi, J) \rightarrow \chi_{\text{opt}}$

- calls:

- simulator.simul:

$$\chi \rightarrow (J(\chi), \nabla_{\chi} J)$$