

# ATAT 1.1, an Automated Timing Accordance Tool for comparing ice-sheet model output with geochronological data

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**Abstract.** Earth's extant ice sheets are of great societal importance given their ongoing and potential future contributions to sea-level rise. Numerical models of ice sheets are designed to simulate ice sheet behaviour in response to climate changes, but to be improved require validation against observations. The direct observational record of extant ice sheets is limited to a few recent decades, but there is a large and growing body of geochronological evidence spanning millennia constraining the behaviour of palaeo-ice sheets. Hindcasts can be used to improve model formulations and study interactions between ice sheets, the climate system and landscape. However, ice-sheet modelling results have inherent quantitative errors stemming from parameter uncertainty and their internal dynamics, leading many modellers to perform ensemble simulations, while uncertainty in geochronological evidence necessitates expert interpretation. Quantitative tools are essential to examine which members of an ice-sheet model ensemble best fit the constraints provided by geochronological data. We present an Automated Timing Accordance Tool (ATAT version 1.1) used to quantify differences between model results and geochronological-data on the timing of ice sheet advance and/or retreat. To demonstrate its utility, we perform three simplified ice-sheet modelling experiments of the former British-Irish Ice Sheet. These illustrate how ATAT can be used to quantify model performance, either by using the discrete locations where the data originated together with dating constraints or by comparing model outputs with empirically-derived reconstructions that have used these data along with wider expert knowledge. The ATAT code is made available and can be used by ice-sheet modellers to quantify the goodness of fit of hindcasts. ATAT may also be useful for highlighting data inconsistent with glaciological principles or reconstructions that cannot be replicated by an ice sheet model.

## 1 Introduction

Numerical models have been developed which simulate ice sheets under a given climate forcing (e.g. Greve, 1995; Rutt et al., 2009; Pollard and DeConto, 2009; Winkelmann et al., 2011; Gudmundsson et al., 2012; Cornford et al., 2013; Pattyn, 2017). When driven by future climate scenarios, these models are used to forecast the fate of the Antarctic and Greenland ice sheets (e.g. Seddik et al., 2012; DeConto and Pollard, 2016), providing predictions of their potential contribution to future sea level rise. However, incomplete knowledge of ice physics, boundary conditions (e.g. basal topography) and parameterisations of physical processes (e.g. basal sliding, calving), as well as the difficulty of predicting future climate, lead to model-based uncertainty in these predictions (Applegate et al., 2012; Briggs et al., 2014; Ritz et al., 2015). Observations of ice marginal fluctuations (decades) and the processes of ice calving, flow or melting (subaerial or submarine) that facilitate or drive such variations, provide a powerful means to understand the processes leading to the possibility of deriving new formulations that improve

37 the realism of modelling. However, the short-time span (decades) of these observations limits their being used to  
38 constrain, initialise or validate modelling experiments (Bamber and Aspinall, 2013). Conversely, palaeo-ice  
39 sheets, especially from the last glaciation (~21,000 years ago), left behind evidence which provides the  
40 opportunity to study ice sheet variations across timescales of centuries to millennia, albeit with increased  
41 uncertainty in exact timing.

42 Numerous modelling studies have aimed to simulate the growth and decay of palaeo-ice sheets, producing  
43 hindcasts of ice-sheet behaviour (e.g. Boulton and Hagdorn, 2006; Hubbard et al., 2009; Tarasov et al., 2012;  
44 Gasson et al., 2016; Patton et al., 2016). Results from these hindcasts may be compared with empirical data  
45 recording ice sheet activity, so as to discern which parameter combinations produce results that best replicate the  
46 evidence of palaeo-ice sheet activity. Three classes of data are of particular use for constraining palaeo-ice sheets;  
47 (i) geomorphological data, (ii) geophysical data, and (iii) geochronological data. Ideally, all three classes of data  
48 should be used to quantify the goodness of fit of a hindcast.

49 Geomorphological evidence comprises the landforms created by the action of ice upon the landscape, and can  
50 typically provide data on ice extent, recorded by moraines and other ice marginal landforms and on ice-flow  
51 directions recorded by subglacial landforms such as drumlins. Such landforms can be used to decipher the pattern  
52 of glaciation (e.g. Kleman et al., 2006; Clark et al., 2012; Hughes et al., 2014). Two tools, namely Automated  
53 Proximity and Conformity Analysis (APCA) and Automated Flow Direction Analysis (AFDA), have already been  
54 developed which can compare modelled ice margins (APCA) and flow directions (AFDA) to the  
55 geomorphological evidence base (Napieralski et al., 2007).

56 Geophysical data, in the form of relative sea level measurements and present day uplift rates, provide information  
57 regarding the mass-loading history of an ice sheet. Palaeo-ice-sheet model output is often evaluated against such  
58 data by use of glacio-isostatic adjustment models (e.g. Tushingham and Peltier, 1992; Simpson et al., 2009;  
59 Tarasov et al., 2012; Auriac et al., 2016).

60 Geochronological evidence attempts to ascertain the absolute timing of ice advance and retreat using dated  
61 material (e.g. organic remains dated by radiocarbon measurement) found in sedimentary contexts interpreted as  
62 indicating ice presence or absence nearby. It enables reconstruction of the chronology of palaeo-ice sheet growth  
63 and decay (Small et al., 2017) and is the underpinning basis for empirically-based ice sheet margin reconstructions  
64 (e.g. Dyke, 2004; Clark et al., 2012; Hughes et al., 2016). Although widely used in empirical reconstruction of  
65 palaeo-ice sheets, geochronological data has rarely been directly compared with ice sheet model output (although  
66 see Briggs and Tarasov, 2013). Such a comparison could be useful both for constraining ice-sheet model  
67 uncertainty and for identifying problems with the geochronological record. For example, a poor fit between model  
68 output and empirical data on timing could inform on the validity of a numerical model (or its parameterisation),  
69 or it could provide a physical basis for questioning the plausibility of empirically-driven interpretations or specific  
70 lines/data points of evidence given that they are associated with inherent uncertainties. In order to maximise the  
71 benefit to all users, any comparisons between palaeo-ice sheet model output and empirical data should ideally  
72 consider the inherent uncertainties of both.

73 Given the wide availability of compilations of geochronological data (e.g. Dyke, 2004; Hughes et al., 2011;  
74 Hughes et al., 2016), as well as the proliferation of ice sheet models (e.g. Greve, 1995; Rutt et al., 2009; Pollard  
75 and DeConto, 2009; Winkelmann et al., 2011; Gudmundsson et al., 2012; Cornford et al., 2013; Pattyn, 2017), a  
76 convenient, reproducible and consistent procedure for comparison should be of great utility to the palaeo-ice sheet

77 community. The typical volume of geochronological constraints (several thousands) for a palaeo ice sheet and the  
78 number of ensemble runs (several hundreds) from an ice sheet model make a visual matching of data and model  
79 output nearly impossible to accomplish, which is likely to explain the rarity of such comparisons. Here, we present  
80 an Automated Timing Accordance Tool (ATAT, version 1.1). ATAT a systematic means for comparing ice-sheet  
81 model output with geochronological data, which quantifies the degree of fit between the two. To separate model  
82 uncertainty from data error, a single run of ATAT focuses on the error in geochronological data. This is achieved  
83 by comparing geochronological data and its associated error to predictions of ice cover from single ice sheet model  
84 output. However, through multiple comparisons against all members from an ensemble ice-sheet modelling  
85 experiment, parameter uncertainty can be considered by assessing the degree of fit to the various input parameter  
86 combinations. Therefore, ATAT could be used as a basis for examining whether model-data mismatch is a  
87 consequence of inadequacies in either the model or data. The tool is in the form of a Python script and requires  
88 the installation of open-source libraries. ATAT is written to handle NETCDF data as an input, a format commonly  
89 used in ice sheet modelling and is also accessible from many GIS packages in which geochronological data can  
90 be stored and manipulated.

## 91 **2 Background**

92 Geochronological evidence and ice sheet model outputs are often independently used to reconstruct the timing of  
93 glaciological events. The two approaches are fundamentally different in nature and consequently produce  
94 contrasting data outputs. Thus, before describing our approach to comparing the two sets of data (ATAT), we first  
95 briefly consider the nature of both geochronological data and ice-sheet model output to highlight the issues and  
96 potential difficulties associated with comparing the two and conceptualise a comparison procedure. More  
97 extensive descriptions of the nature, uncertainties and limitations of glacial geochronological (Hughes et al., 2016;  
98 Small et al., 2017) and model-based (Rougier, 2007; Tarasov et al., 2012; Briggs and Tarasov, 2013) data are  
99 considered elsewhere. Given the complex nature of both, those seeking to compare geochronological data and  
100 ice-sheet model output should ideally collaborate with those who understand the limitations and uncertainties  
101 involved with both forms of data.

### 102 **2.1 Geochronological data**

103 The timing of palaeo-ice sheet activity has primarily been dated using three techniques: (i) radiocarbon dating;  
104 (ii) cosmogenic nuclide exposure dating, and (iii) luminescence dating (Figure 1). The utility of each method for  
105 determining the timing of palaeo-ice sheet activity has been extensively reviewed elsewhere (e.g. Fuchs and  
106 Owen, 2008; Balco, 2011; Small et al., 2017) and only a brief description is provided here. Radiocarbon dating  
107 uses the known rate of the radioactive decay of  $^{14}\text{C}$  to determine the time elapsed since the death of organic  
108 material (Libby et al., 1949; Arnold and Libby, 1951; Figure 1). For palaeo-glaciological purposes, the dated  
109 organic material (e.g. shells, mosses, plant remains) is usually taken from basal sediments overlying and closely  
110 associated with a glacial deposit in order to determine a minimum deglaciation age (e.g. Heroy and Anderson,  
111 2007; Lowell et al., 2009); ice is interpreted to have retreated from this site some short time prior to this age.  
112 Where organic matter is either reworked within or is located directly beneath a glacial deposit, it can be used to  
113 constrain the maximum age of glacial advance (e.g. Brown et al., 2007; Ó Cofaigh and Evans, 2007); advance

114 happened sometime after this age. Cosmogenic nuclides (e.g.  $^{10}\text{Be}$ ,  $^{26}\text{Al}$  and,  $^{36}\text{Cl}$ ) are produced by the  
115 interaction of secondary cosmic radiation in minerals, such as quartz, within materials exposed at the Earth's  
116 surface (Figure 1). Samples are generally taken from glacially-transported boulders, morainic boulders and  
117 glacially modified bedrock, all of which have ideally had signals from any previous exposure history removed by  
118 glacial erosion. Cosmogenic nuclide dating is thus used to determine the duration of time a sample has been  
119 exposed at the Earth's surface by determination of the concentration of cosmogenic nuclides within that sample.  
120 Luminescence dating can determine the age of a deposit by measuring the charge accumulated within minerals.  
121 This charge accumulates in light-sensitive traps within the crystal lattice due to ionizing radiation produced by  
122 naturally occurring radioactive elements (e.g. U, Th, K). Luminescence dating determines the time elapsed since  
123 the last exposure of the mineral to sunlight; this exposure acts to reset the signal (Figure 1). As subglacial deposits  
124 are unlikely to have been exposed to light before burial, and therefore contain signals accumulated prior to  
125 deposition, luminescence dating within palaeo-glaciology is typically applied to ice marginal sediments, or those  
126 which overly glacial sediments (e.g. Duller, 2006; Smedley et al., 2016; Bateman et al., 2018). All  
127 geochronological techniques record the absence of grounded ice. They therefore provide either maximum or  
128 minimum ages of a glaciological event, depending upon the stratigraphic setting. Table 1 outlines a commonly  
129 used system used to classify geochronological data by stratigraphic setting (Hughes et al., 2011; 2016).  
130 The retreat/advance (ice-free) ages provided by the three geochronometric techniques are all affected by  
131 systematic and geological uncertainties (Small et al., 2017). Systematic uncertainties originate from the tools and  
132 techniques used to derive the date, such as laboratory instruments and sample preparation, and are accounted for  
133 in the quoted errors that accompany a date. Geological uncertainties are caused by the geological history of a  
134 sample, before, during and after a glacial event (e.g. Lowe and Walker, 2000; Lukas et al., 2007; Heyman et al.,  
135 2011). Such influences may leave little or no evidence of their effect upon a sample and are thus hard to quantify.  
136 The relationship between a dated sample and the glacial event it indicates is the largest potential source of  
137 uncertainty in geochronological data and is primarily bounded by the ability of the investigator to find and  
138 associate dateable material to the glacial event of interest. Since all geochronological techniques measure the  
139 absence of ice, expert inference must be made, and are influenced by the availability of information (stratigraphic  
140 or otherwise) at a study site; they may be open to change (e.g. new radiocarbon calibrations, new cosmogenic  
141 isotope production rates). Furthermore, in the cases of luminescence and radiocarbon dating, there can be an  
142 unknown duration since glacial occupation of an area and the deposition of dateable material. These factors mean  
143 it is necessary to consider the quality of dates for ascertaining the timing of the glacial event in question (Small et  
144 al., 2017).  
145 Numerous geochronological studies have sought to ascertain the timing of palaeo-ice sheet activity at sites, leading  
146 to compilations of geochronological data which bring together hundreds to thousands of published dates (e.g.  
147 Dyke et al., 2002; Livingstone et al., 2012; Hughes et al., 2011; 2016). Despite the growing number of reported  
148 dates, they are still insufficient in number and spatial spread to define, on their own, the time-space envelope of  
149 the shrinking ice sheet. Techniques to interpolate geochronological information between sites are required. The  
150 most commonly used technique is empirical ice sheet reconstruction (e.g. Dyke, 2004; Clark et al., 2012), whereby  
151 expert assessments of the geochronological and geomorphological record are used together to create ice-sheet  
152 wide isochrones of ice-sheet margin position and flow configuration. A recent advance in this method has been  
153 the inclusion of confidence envelopes for each isochrone, documenting possible maximum, likely and minimum

154 extents (Hughes et al., 2016). Further techniques for spatiotemporally interpolating geochronological data include  
155 Bayesian sequence modelling (e.g. Chiverrell et al., 2013; Smedley et al., 2017), in which collections of deglacial  
156 ages are arranged in spatial order determined by a priori knowledge of geomorphologically-informed ice flow and  
157 retreat patterns (e.g. Gowan, 2013). Such techniques provide viable methods for producing ice-sheet wide  
158 chronologies, filling in information in locations where geochronological data may be sparse.

## 159 **2.2 Ice sheet model output**

160 Ice-sheet models solve equations for ice flow over a computational domain, for a given set of input parameters  
161 and boundary conditions, to determine the likely flow geometry and extent of an ice sheet. Typically, ice-sheet  
162 models run using finite difference techniques on regular grids (e.g. Rutt et al., 2009; Winkelmann et al., 2011).  
163 Ice-sheet models that utilise adaptive meshes (e.g. Cornford et al., 2013) and unstructured meshes also exist (e.g.  
164 Larour et al., 2012) and the results from such models can be interpolated onto spatially regular grids. The spatial  
165 resolution of an ice-sheet model depends upon the computational resources available, and the spatial resolution  
166 of available boundary conditions. Continental-scale models of palaeo-ice sheets have typical spatial resolution of  
167 tens of kilometres (e.g. Briggs and Tarasov, 2013; DeConto and Pollard, 2016; Patton et al., 2016), though parallel,  
168 high-performance computing means higher resolutions are possible (e.g. 5 km in Golledge et al., 2013 and  
169 Seguinot et al., 2016). The temporal resolution of ice sheet model output is ultimately limited by the time-steps  
170 imposed by the stability properties of the numerical schemes solving the ice-flow equations. Given that these  
171 stable time-steps can be sub-annual, output frequency is mostly predetermined by the user (typically decades to  
172 centuries), and as such is constrained by available disk-storage. Ice-sheet models therefore produce spatially  
173 connected predictions of ice-sheet behaviour such as advance and deglaciation (e.g. Table 1) across gridded  
174 domains at various temporal and spatial resolutions.

175 The stress fields imposed upon ice can be fully described by solving the Stokes equations. Indeed, ‘full Stokes’  
176 models which do so have been tested (Pattyn et al., 2008) and used to simulate ice sheets (e.g. Seddik et al., 2012).  
177 However, fully solving the Stokes equations over the spatio-temporal scales relevant to palaeo-ice sheet  
178 researchers remains beyond the limit of currently available computational power. This problem is exacerbated by  
179 the need to run multi-parameter valued ensemble simulations to account for model uncertainty over multi-  
180 millennial and continental-scale domains. This means that palaeo-ice sheet modelling experiments rely upon  
181 approximations of the Stokes equations (see Kirchner et al., 2011 for a discussion), such as the shallow ice  
182 approximation (SIA) and shallow shelf approximation (SSA). The choice of ice-flow approximation used within  
183 a model has implications for the capability of models to realistically capture aspects of ice sheet flow (Hindmarsh,  
184 2009; Kirchner et al., 2011; 2016), and in turn influences the nature of the model output produced. For instance,  
185 the SIA is not applicable for ice shelves, therefore SIA-based models do not produce modelled ice shelves (e.g.  
186 Glimmer; Rutt et al., 2009). Therefore, the timing of deglaciation in an SIA model can be determined as the point  
187 at which ice thickness in a cell becomes zero or thinner than the flotation thickness, whereas in a SSA or higher-  
188 order model the location and movement of the grounding line must be determined.

189 Though ice sheet models produce output which is consistent with model physics, like all numerical models of  
190 physical systems (e.g. Rougier, 2007) there are many sources of uncertainty involved with ice sheet modelling.  
191 Three broad sources of model-based uncertainty can be distinguished: (i) down-scaling; (ii) parametric  
192 uncertainty; (iii) structural uncertainty. These are defined and discussed below.

193 Down-scaling uncertainties arise due to an ice-sheet models computation over space which has a coarser resolution  
194 than reality. This means that a characteristic which can be measured to a high level of accuracy and precision for  
195 a real ice-sheet (e.g. the position of a calving front), has a larger uncertainty in an ice-sheet model. This is  
196 especially pertinent for data-model comparisons, as most observations of ice-sheet activity have a sub-model  
197 resolution.

198 Parametric uncertainty has two main sources: (i) parameterisations, and (ii) boundary conditions. Where a process  
199 is too complex (e.g. calving) or occurs at too small a scale (e.g. regelation) to be captured by an ice sheet model,  
200 it is often simplified and parameterised. Associated with each parameterisation are a set of parameters, the values  
201 of which are either unknown, or thought to vary within some plausible bounds, and which can either be constant  
202 or spatially and temporally variable across a domain. An example of a process which is often parameterised is  
203 basal sliding. This parameterisation is often done through the implementation of a sliding law (e.g. Fowler, 1986;  
204 Bueler and Brown, 2009; Schoof, 2010), which relates the basal shear stress to the basal velocity (Fowler, 1986).  
205 Parameters used to determine this relationship are often assigned or incorporated within a parameter, or prescribed  
206 by another model parameterisation (e.g. a subglacial hydrology model). Adding to the uncertainty in the absence  
207 of a single preferable sliding law, ice-sheet models often allow the user to choose between different sliding law  
208 implementations.

209 Boundary conditions, the values prescribed at the edge of the modelled domain, also introduce uncertainty into  
210 ice-sheet models. For contemporary ice sheets, there is a large uncertainty in the basal topography (e.g. Fretwell  
211 et al., 2013). This is less of a problem for the more accessible beds of palaeo-ice sheets. However, accurately  
212 accounting for the evolution of this bed topography over the course of a glaciation requires a model of isostatic  
213 adjustment (Lingle and Clark, 1985; Gomez et al., 2013).

214 A very large source of uncertainty for modelling palaeo-ice sheets is the climate used to drive them (Stokes et al.,  
215 2015), as indeed is the case for forecasts of contemporary ice sheets (e.g. Edwards et al., 2014). Owing to the  
216 computational resources required and technical challenges, few palaeo-ice sheet models are coupled with climate  
217 models. This uncertainty over past climate is reflected in the large range of outputs produced by global circulation  
218 models which have tried to simulate the last glacial cycle (e.g. Braconnot et al., 2012). Palaeo-ice sheet modellers  
219 have used a range of methods to force their models, including simple parameterisations (Boulton and Hagdorn,  
220 2006), applying offsets derived from ice core records to contemporary climate (e.g. Huybrechts, 1990; Hubbard  
221 et al., 2009) and scaling between present-day conditions and uncoupled global-circulation-model simulations at  
222 maximum glacial conditions (e.g. Greve et al., 1999; Gregoire et al., 2012; Gasson et al., 2016). Each approach is  
223 associated with an inherent uncertainty. When this uncertainty is accounted for in an ensemble experiment, the  
224 range of possible climates produces numerous ice sheet outputs.

225 Structural uncertainty is related to parametric uncertainty, but has a broader remit, and is defined as uncertainty  
226 which occurs due to differences in model coding and design (Collins, 2007; Tebaldi and Knutti, 2007). This  
227 encompasses differences in which processes are included in different models, and also the manner in which they  
228 are implemented. Structural uncertainty is difficult to quantify, but can be explored by multi-model comparison  
229 (Murphy et al., 2004; Collins et al., 2011). Such comparisons are not currently routine in palaeo-ice sheet  
230 modelling. Differences in model coding (i.e. structural uncertainty), arise due to a lack of understanding regarding  
231 the physical system in question. This points to a broader uncertainty with a similar remit, that no models can

232 include processes that are as yet unknown to science. Reducing this source of uncertainty is an ongoing challenge  
233 for glaciology.

234

235 There is another uncertainty which hinders ice-sheet models from being able to accurately predict the evolution  
236 of ice-sheets, which is the presence of instabilities – we use this term in the technical sense of a small perturbation  
237 that leads to the whole ice-sheet system amplifying this small perturbation to the extent it can leave a mark in the  
238 geological record. A classic example of this in ice-sheet dynamics is the marine ice-sheet instability (MISI), first  
239 discussed in the 1970s (Hughes, 1973; Weertman, 1974, Mercer, 1978) and more recently put on a sounder  
240 mathematical footing (Schoof 2007, 2012).

241 The MISI actually refers to an instability in grounding-line (GL) position on a reverse slope, where the water  
242 depth is shallowing in the direction of ice flow. Since ice flux increases with ice thickness, a straightforward  
243 argument leads to the conclusion that if the GL advances into shallower water, the efflux will decrease, the ice  
244 sheet will gain mass and the advance continue. If, on the other hand, the GL retreats, the flux will increase, the  
245 ice-sheet will lose mass and the retreat continue. In principle, given the right parameterisations and basal  
246 topography, ice-sheet models should be able to predict the ‘trajectory’ of GL migration arising as a consequence  
247 of the MISI. However, the MISI is one of the class of instabilities that lead to poor predictability; certain small  
248 variations of parameters and specifications will lead to large-scale changes in the ‘trajectory’, in this case the  
249 retreat history. A well-known analogy is the ‘butterfly effect’, which originated in atmospheric modelling work  
250 (Lorenz, 1963); the butterfly effect is concerned with the consequences of the statement “small causes can have  
251 larger effects”. Recent work has also shown that additional physical processes, such as ice-shelf buttressing  
252 (Gudmunsson, 2012) and the effect that the gravitational pull of ice-sheets has on sea level (Gomez et al., 2012)  
253 have additional effects on grounding line stability. Given that most of the palaeo-ice sheets during the last glacial  
254 cycle had extensive marine margins and overdeepened basins, with isostatic adjustment creating further zones of  
255 reverse slope, capturing grounding line processes is important for simulating these ice-sheets.

### 256 **2.3 Considerations when comparing geochronological data and ice-sheet model output**

257 Sections 2.1 and 2.2 make it clear that several factors must be considered in order to satisfactorily compare  
258 geochronological data and ice-sheet model output (Table 2). Most critically, the two datasets involved in any  
259 comparison have varying spatial properties. Raw geochronological data is unevenly distributed and located at  
260 specific points, with horizontal position accurate to a metre or so; such data may be used to plot ice-margin  
261 fluctuations of the order of tens of kilometres (Figure 2C). Ice-sheet models typically produce results on evenly-  
262 spaced points (at ~5 km to 20 km resolution) that are distributed over and beyond the maximum area of the palaeo-  
263 ice sheet (Table 2; Figure 2B). Consequently, in comparing the two, a choice must be made; either  
264 geochronological data should be gridded (coarsened) to the resolution of the ice-sheet model, or the ice-sheet  
265 model results must be interpolated to a higher resolution. Both options have drawbacks, as the former removes  
266 spatial accuracy from geochronological data while the latter relies upon interpolation beyond model resolution  
267 and, more seriously, model physics. A second problem lies in the spatial organisation of the data (Table 2). Ice-  
268 sheet models produce a regular grid of data (Figure 2B), meaning that no location is more significant than any  
269 other when comparing the modelled deglacial chronology with that inferred from geological data. Conversely,  
270 owing to the uneven distribution of raw geochronological data, some regions of a palaeo-ice sheet may be better

271 constrained than others (Figure 2C). As noted by Briggs and Tarasov (2013), any comparison that does not treat  
272 the uneven spatial distribution of geochronological data may favour sites where numerous dates exist over more  
273 isolated locations. One approach to overcoming these disparities is to use an interpolation scheme (e.g. empirical  
274 reconstruction, Bayesian sequence) on the raw geochronological data. This produces a geochronological  
275 framework by combining evidence on pattern and timing to yield a distribution that is spatially more uniform and  
276 a spatial resolution similar to that of palaeo-ice sheet model output (Figure 2D).

277 The temporal intervals between and precision of geochronological data and ice sheet model output also vary  
278 (Table 2). The time intervals between geochronometric data are determined by the number of available  
279 observations, and precision determined by sources of uncertainty. Conversely, ice sheet models produce output at  
280 regular intervals and are temporally exact, which is to be contrasted with ‘correct’. Since the output interval of an  
281 ice-sheet model is generally determined by the user (see Section 2.2) it is pertinent to consider an appropriate  
282 time-interval of ice-sheet model output for comparison with geochronological data. For example, radiocarbon  
283 dates have precision typically in the order of hundreds of years but do not directly constrain ice extent, whilst  
284 empirically reconstructed isochrones are typically produced for thousand-year time-slices (e.g. Hughes et al.,  
285 2016). In reality, ice-sheets may respond to events at faster time-scales than this, but in the absence of internal  
286 instabilities (e.g. MISI) palaeo-ice sheet models are ultimately limited by the temporal resolution of the available  
287 climate forcing data. Thus, to gain insight into controls on palaeo-ice sheet behaviour, it may be necessary to  
288 create model output with a greater (centurial) temporal resolution than the uncertainty associated with  
289 geochronology.

290 Both geochronological data and ice-sheet model output have sources of uncertainty which must also be considered  
291 when comparing the two. For geochronological data, uncertainty is typically expressed as a standard deviation  
292 from the reported age, and are therefore easy to consider when comparing to an ice sheet model. For ice-sheet  
293 models, individual model runs do not currently express uncertainty, and it is only when multiple, ensemble, runs  
294 which systematically vary parameters and boundary conditions are conducted that uncertainty in all output  
295 variables can be expressed. Therefore, any comparison between geochronological data and model simulations  
296 must either compare to all members of an ensemble experiment in turn, or against amalgamated output from an  
297 ensemble which considers model uncertainty. Having said this, statistical techniques exist to derive probability  
298 distribution functions for individual quantities (e.g. Ritz et al., 2015). Such ensemble runs typical comprise  
299 hundreds to thousands of individual runs (Tarasov and Peltier, 2004; Robinson et al., 2011). Given the volume of  
300 data this produces, one appealing application of a quantitative comparison between geochronological data and ice  
301 sheet model output would be to act as a filter for scoring ice-sheet model runs and reducing predictive uncertainty  
302 by only using the parameter combinations that were successful. However, if all possible parameters have been  
303 modelled, (i.e. the full ‘phase-space’ of the model has been explored (cf. Briggs and Tarasov, 2013)), and very  
304 few (or no) model runs conform to a certain set of geochronological data or an empirical reconstruction, this may  
305 provide a basis to question aspects of the evidence (e.g. re-examining the stratigraphic context of a dated sample  
306 site or questioning the basis of the reconstructed isochrone). Of course, a third possibility that both data and model  
307 are incorrect cannot be excluded.

308 We therefore suggest that any comparison between ice-sheet model experiments and geochronological data should  
309 consider:

310 i) That both ice-sheet models and geochronological data have inherent uncertainties;



311 ii) That geochronological data typically provide a constraint on just the absence of ice; such that ice must have  
312 withdrawn from a site sometime (50 years? 500 years? 5000 years?) prior to the date (which can be any point  
313 within the full range of the stated uncertainty). It is thus a limit in time and not a direct measure of glacial activity.  
314 Figure 3 illustrates this for advance and retreat constraints. It is most often the case that dated material is taken  
315 close to the stratigraphic boundary or landform representing ice presence, in which case a date might be considered  
316 as a ‘tight constraint’ (e.g. the ice withdrew and very soon afterwards (50 years) marine fauna colonised the area  
317 and deposited the shells used in dating). Sometimes however there may have been a large (centuries to millennia)  
318 interval of time between the withdrawal and the age of the shell chosen as a sample, in which case the date will  
319 provide a ‘loose’ limiting constraint; it might be much younger than ice retreat (Figure 3).

320 iii) There is inherent value to the expert interpretation of stratigraphic and geomorphological information, meaning  
321 an ice-free age reported for a site is likely as close as possible (tight constraint) to a glacial event. However, this  
322 interpretation could be subject to change;

323 iv) Geochronological data exist as spatially distributed dated sites (e.g. Figure 2C) which can be built into a  
324 spatially coherent reconstruction (e.g. Figure 2D);

325 v) A great input uncertainty in a palaeo-ice sheet model is the climate, which can lead to changes in the spatial  
326 extent and timing of ice sheet activity.

327 vi) A factor which requires further investigation is the relationship between the operation of a physical instability  
328 (e.g. the MISI) and the practical ability of models to predict retreat or advance rates; the presence of an instability  
329 can result in extreme sensitivity to parameter ignorance or over-simplified model physics.

330 vii) Other uncertainties can also lead to variations in ice-sheet model results; these can be accounted for in an  
331 ensemble of hundreds to thousands of simulations.

332 Given the above, it is unlikely that a single procedure could capture model-data conformity. ATAT therefore  
333 implements several ways of measuring data-model discrepancies and produces output maps (described in the  
334 following two sections) to help a user assess which model runs best agree with the available geochronological  
335 data. One approach is to transform the geochronological data points (x,y,t) to a gridded field (raster) that define  
336 age constraints of ice advance and another grid for retreat . Both of these data types also require an associated grid  
337 that reports the uncertainty range as error (Figure 4). These age grids may then be quantitatively compared to  
338 equivalent grids (age of advance grid and age of retreat grid) derived from the ice sheet model outputs.  
339 Alternatively, one might prefer to compare model runs against the geochronological data (points) combined with  
340 expert-sourced interpretive geomorphological and geological data, in which age constraints from dated sites have  
341 been spatially extrapolated using moraines and the wider retreat pattern. In this case ATAT allows the model  
342 outputs to be compared to the ‘lines on maps’ type of reconstruction subsequent to conversion from age isolines  
343 to a grid of ages (Figure 4).

### 344 **3. Description of tool**

345 ATAT is written in Python, and utilises several freely available modules. Access to these modules may require a  
346 Python package manager, such as ‘pip’ or ‘anaconda’. ATAT can therefore be run from the command line on any  
347 operating system, or by using a Python interface such as IDLE.

### 348 **3.1 Required data and processing**

349 ATAT requires two datasets as an input: (i) an ice-sheet model output; and (ii) gridded geochronological data.  
350 Table 3 provides the required variables and standard names for each dataset. In order to determine the advance  
351 age or deglacial age predicted by the ice sheet model, ATAT requires either an ice thickness (where the model  
352 does not produce ice shelves) or a grounded ice-mask variable (where ice shelves are modelled). In the latter case,  
353 the user is asked to define the value which represents grounded ice.

354 Empirical advance and deglacial geochronological data (Table 1) require separate input files (NETCDF format),  
355 as model-data comparison for these two scenarios are run separately in ATAT. Table 1 and further references  
356 (Hughes et al., 2011; 2016; Small et al., 2017), provide information regarding identification of the stratigraphic  
357 setting of these two glaciological events as considered by ATAT. ATAT requires that geochronological data  
358 (advance or deglacial) are interpolated onto the same grid projection and resolution as the ice-sheet model before  
359 use. Though an imperfect solution to the problem of comparing grids of different resolution, (Section 2.3; Table  
360 2), this was preferred to the alternative solution of regridding an ice sheet model onto a higher resolution grid, as  
361 this may introduce the false impression of high resolution modelling sensitive to boundary conditions (e.g.  
362 topography) beyond the actual model resolution.

363 Preparation of the geochronological data to be the same format and grid resolution as the ice sheet model output  
364 requires use of a GIS software package such as ESRI ArcMap or QGIS. Users must define deglacial/advance ages  
365 based either upon the availability of geochronological data in a cell, or based upon an empirical reconstruction  
366 (Figure 4). These ages must be calibrated to a calendar which is the same as that output by the ice-sheet model (in  
367 our case the 365-day calendar in units of seconds since 1-1-1). Where there are no data (i.e. outside the ice-sheet  
368 limit), the grid value must be kept at 0. When multiple dates are contained within a cell, expert judgement is  
369 required to ascertain which date is most representative of the deglaciation of a region. This assessment should be  
370 based upon the quality of sample taken; criteria for establishing this quality are considered in Small et al. (2017).  
371 In the case where a profile of dates has been collected (for example up a vertical section at the side of a valley, or  
372 from multiple depths of a marine core) the date which most closely defines the timing of final deglaciation of an  
373 area should be chosen, as this is the focus of ATAT. The assembly of this geochronological database input into  
374 ATAT should consider the reliability of ages, removing outliers and unreliable ages (see Small et al. (2017) for a  
375 discussion of this issue). In particular, loose constraints, such as cosmogenic dates which display inheritance or  
376 radiocarbon dates effected by a depositional hiatus, should be removed as this have the potential to bias results.  
377 In a comparable manner, the attribution of error to each cell is also reliant upon expert interpretation. The  
378 magnitude of error may vary between the source of geochronological data (radiocarbon, cosmogenic nuclide or  
379 luminescence) and user choice for experimental design (e.g. 1, 2 or 3 sigma). A single error value must be given  
380 for each dated cell, corresponding to the maximum threshold beyond which the user deems it is unacceptable for  
381 a model prediction to occur (Figure 3). Given that creating this input data may involve many expert decisions (e.g.  
382 which date has the relevant stratigraphic setting, which date(s) are most reliable?), this part of the process is not  
383 yet automated within ATAT. This data preparation stage is therefore the most time-consuming and user-intensive  
384 part of the process. However, users only need to define the data-based advance/deglacial grid once to compare to  
385 multiple model outputs. Future work should consider alternatives means of choosing dates and identifying outliers,  
386 such as Bayesian age modelling (e.g. Chivverell et al., 2013). The input data NetCDF file should also contain the

387 variables latitude, longitude, base topography (the topography that the ice-sheet modelling is conducted on and  
388 the elevation of the geochronological sample (Table 3).

389 ATAT is called from a suitable python command-line environment, using several system arguments to define  
390 input variables (Table 1; Figure 5). Users must define whether they are testing a deglacial or advance scenario.  
391 ATAT only considers the last time that ice advances over an area. Therefore, caution must be undertaken when  
392 defining advance data in regions where multiple readvances occur, and users should consider limiting the time  
393 interval of the ice sheet model tested when examining specific events (e.g. a well-dated readvance or ice sheet  
394 build-up). The location of the file containing the geochronological data grid (e.g. Figure 5) is then required. From  
395 this file, the age and error grids are converted to arrays. For the age data, null values are masked out using the  
396 `numpys` masked array function. A second array that accounts for error is then created, the properties of which  
397 depends upon whether a deglacial or advance scenario is being tested. For a deglacial scenario, a model prediction  
398 will be unacceptable if the cell is ice-covered after the range of the date error is accounted for, but the cell may  
399 become deglaciaded any time before this. Therefore, the associated error value is added onto the cell date, to create  
400 a maximum age at which a cell must be deglaciaded by to conform to the ice sheet model (Figure 3). The opposite  
401 is true for advance ages; ice can cover a cell any time after the date and associated error, but cannot cover the cell  
402 before the date of the advance. In order to allow for advances which occur after the date and its error, associated  
403 error is therefore subtracted from the date cell (Figure 3). To account for the uneven spatial distribution of dates,  
404 a weighting for each date is then calculated based upon their spatial proximity. This weighting is used later when  
405 comparing the data to the model output. To calculate this weighting ( $w_i$ ), ATAT defines a local spatial density of  
406 dated values based upon a kernel search of 10 neighbouring cells.

407 The user must define the path to the ice sheet model output, from which the modelled deglacial age will be  
408 calculated and eventually compared to the data (Figure 4). The user must also define whether to base deglacial  
409 timing on an ice thickness or grounded extent mask variable (Table 2). If the user selects thickness, the margin is  
410 defined by an increase from 0 ice thickness. For the mask, the user is also asked to supply the number which refers  
411 to grounded ice extent. The timing of advance is then determined by the change of a cell to this number (Figure  
412 5). The margin position recreated by the ice-sheet model has a spatial uncertainty due to downscaling issues and  
413 fluctuations which may occur between recorded outputs. To account for this, ATAT calculates a second set of  
414 modelled deglacial ages, whereby the deglaciaded region at each modelled time output is expanded to all cells  
415 which neighbour the originally identified deglaciaded or advanced over cells. Furthermore, the spatial resolution  
416 of ice-sheet models typically means that the emergence of ice-free topography at the edge or within an ice-sheet  
417 (e.g. in situations such as steep-sided valleys or nuntaks) are poorly represented. To account for this, ATAT firstly  
418 calculates the modelled ice-sheet surface at each time output by adding ice thickness to the input base topography.  
419 Where the modelled surface elevation is below that of the sample elevation, these cells are identified as being  
420 deglaciaded (Figure 5). The downscaling of topography onto ice-sheet model grids also introduces a vertical  
421 uncertainty. This is accounted for in ATAT through calculating the difference between sample elevation and the  
422 reference elevation. A second metric which identifies cells as having been deglaciaded if they are also within this  
423 vertical uncertainty is also calculated (Figure 5).

### 424 3.2 Model-data comparison

425 Once the required variables have been retrieved from the NETCDF data and manipulated, ATAT compares the  
426 geochronological age and modelled age at each location (Figure 4). Firstly, the grid cells which have data are  
427 categorised as to whether there is model-data agreement, based on the criteria shown in Figure 3. Since all dating  
428 techniques only record the absence of ice, geochronological data provides only a one-way constraint on palaeo-  
429 ice sheet activity. For deglacial ages, deglaciation could occur any time before the geochronological data provided  
430 and within the error of the date (i.e. deglacial ages are minimum constraints), but deglaciation must not occur after  
431 the error of the date is considered (Figure 3). For advance ages, advance must have happened after the date or  
432 within error beforehand (i.e. advance ages are maximum constraints), but palaeo-ice sheet advance cannot occur  
433 in the time period before that dated error (Figure 3). Once ATAT has determined whether each cell conforms to  
434 these criteria, a map is produced identifying at which locations the ice sheet model agrees with the  
435 geochronological data.

436 Though the criteria described above and illustrated in Figure 3 allow for the identification of dates which conform  
437 to the predictions of an ice sheet model, they provide little insight into how close the timing of the model prediction  
438 is to the geochronological data. If these were the only criteria on which a model-data comparison was made, it  
439 could prove problematic. In an extreme case, one could envisage that all retreat dates are adhered to by a model  
440 run that deglaciates from a maximum extent implausibly rapidly (say 50 years!), and, given that we only have  
441 one-way (minimum) constraints on deglaciation (Figure 3), this model run would conform to all modelled dates.  
442 Whilst the nature of geochronological data (being only able to determine the absence of ice) does not preclude  
443 such a scenario, this assumes that there is no inherent value to the expert judgement and stratigraphic interpretation  
444 of each date as being close to palaeo-ice sheet timing (cf. Small et al. 2017). Therefore, ATAT also determines  
445 the temporal proximity of the geochronological data and the model prediction. Firstly, a map of the difference  
446 between modelled and empirical ages is created (Figure 5). This enables the identification of dates which are a  
447 large distance away from the model prediction. Secondly, the route-mean square error (RMSE) is calculated using  
448 the Eq. (2):

$$449 \quad RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^n (g_i - m_i)^2},$$

450 (1)

451 where  $n$  is the number of cells which contain empirical geochronological information,  $g_i$  is the associated  
452 geochronological date, and  $m_i$  is the model predicted age. The RMSE works well when the geochronological  
453 data is evenly spatially distributed, either from a reconstruction (i.e. isochrones) or a wealth of dates. ATAT also  
454 calculates a weighted RMSE (wRMSE), for situations where this is not the case (i.e. there is a paucity of dates  
455 that are not distributed evenly across the domain) using Eq. (3):

$$456 \quad wRMSE = \sqrt{\frac{1}{n} \sum_{i=1}^n ((g_i - m_i)/w_i)^2},$$

457 (2)

458 where  $w_i$  is the spatial weighting factor. Results of the RMSE and wRMSE calculations are separated by the  
459 degree to which included dates agree with model output. This creates an array of metrics with varying levels of  
460 consideration of model and data uncertainty (Figure 5). Both the RMSE and wRMSE are calculated for all dates,

461 to create a metric that doesn't account for dating error but may give an indication of how close a model-run gets  
462 to dated cells. Dated locations are also categorised according to whether model-data agreement occurs within  
463 dating error, and whether the addition of horizontal (ice margin) and vertical (ice surface) downscaling uncertainty  
464 means that model-data agreement occurs. The RMSE and wRMSE are calculated for these categories to create a  
465 metric which accounts for data and model uncertainty (Figure 5). ATAT then produces a .csv file containing all  
466 calculated statistics per ice-sheet model output file. We suggest that the most rigorous metric, the wRMSE of  
467 dates which conform within geochronological data and model downscaling uncertainty (Figure 5), should most  
468 frequently used. However, other metrics, such as the RMSE of all dates, may give an indication of performance  
469 earlier in the modelling process. For example, initial results may reveal that no or very few dates conform to a set  
470 of model simulations within model and data uncertainty, but the RMSE of all dates may give an indication of  
471 models and associated parameters to be explored further. Given the complexity of data-model comparison,  
472 different statistics may have different uses. For instance, the percentage of covered dates may prove useful to  
473 identify the worst performing model runs (i.e. the bottom 50%), whilst the wRMSE of dates within error may be  
474 more convenient for choosing between model runs. However, given the uncertainty in ice-sheet modelling it is  
475 likely that in an ensemble there will be no single model run which has significantly better metrics than others, so  
476 ATAT may best be used to choose members which pass a user-defined threshold of combined metrics.  
477 Pragmatically, we envisage that ATAT could be used in the following ways, though others may exist. In sensitivity  
478 experiments (e.g. Huybrechts, 1990; Hubbard et al., 2009; Patton et al., 2016), ATAT could be used to quantify  
479 how the alteration of a parameter influences the fit of a model to geochronological data. In ensemble experiments,  
480 ATAT could be used to rank the performance of individual ensemble member simulations with respect to  
481 geochronological constraints, either as a means of ruling out simulations with the poorest performance (e.g.  
482 Gregoire et al., 2012) or calibrating input parameters for further experiments (e.g. Tarasov et al., 2012). Where  
483 the results of an ensemble experiment have been amalgamated (i.e. where each cell has a distribution of ice-free  
484 ages), ATAT could be compared to measures of average modelled deglaciation/advance age and against standard  
485 deviations of these. Such comparisons could reveal areas of persistent model-data mismatch. If this is the case,  
486 this may form the basis of identifying regions of significant model uncertainty (does this site not match due to  
487 poor implementation of processes in the model?) or form the basis for re-examination of the geological evidence  
488 (are there reasons why this site is consistently an outlier?). Furthermore, ATAT could be used to explore how  
489 incorporating additional processes into a model alter the fit to data. Here, we envisage two sets of model  
490 experiments, one which includes a new implementation of a process in a model and another which does not  
491 implement this process, whilst holding all other things equal between the two experiments. ATAT could then be  
492 used to distinguish whether a better fit to geochronological data can be made when the new process is accounted  
493 for.

#### 494 **4. Application of tool**

##### 495 **4.1 Ice Sheet Model**

496 To trial ATAT we used geochronological data and ice sheet modelling experiments from the former British-Irish  
497 Ice Sheet (BIIS). A vast quantity of previous research has produced a high density of dates (Hughes et al., 2011)  
498 which are being substantially augmented by the BRITICE-CHRONO project ([13](http://www.britice-</a></p></div><div data-bbox=)

499 chrono.group.shef.ac.uk/). Along with an abundance of well documented landforms (Clark et al., 2017), this  
500 makes the BIIS a data-rich study area for empirical reconstructions and ice sheet modelling. Ongoing modelling  
501 work aims to capture the behaviour of the BIIS inferred from the geomorphological and geochronological record  
502 (see Clark et al., 2012 for a recent reconstruction). We do not expect our model to capture these specific details.  
503 Instead, the purpose of modelling in this paper is merely to illustrate the use of ATAT. We therefore restrict  
504 ourselves to simplified modelling experiments and show only three model runs (Experiments A, B and C), whereas  
505 a full ensemble experiment would contain hundreds or thousands of simulations.

506 Ice sheet modelling experiments were conducted using the Parallel Ice Sheet Model (PISM; Winkelmann et al.,  
507 2011). This is a hybrid SIA-SSA model, with an implementation of grounding line physics. It is therefore suited  
508 to modelling both the marine-based portions of the BIIS and the terrestrial realm. The model simulates the history  
509 of the BIIS from 40 ka to present. The model is run at 5 km resolution, with basal topography derived from the  
510 General Bathymetric chart of the Oceans ([www.gebco.net](http://www.gebco.net)). This is updated to account for isostatic adjustment  
511 using a viscoelastic Earth model (Bueler et al., 2007) and a scalar eustatic sea level offset based on the SPECMAP  
512 data (Imbrie et al., 1984). All three model runs, labelled A-C, had the same input parameters and boundary  
513 conditions, apart from climate forcing. We take a similar approach to Seguinot et al. (2016) in computing a climate  
514 forcing. Modern values of temperature and precipitation are perturbed by a proxy temperature record, in this case  
515 the GRIP ice core record (Johnsen et al., 1995). These are input into a positive degree day model to calculate mass  
516 balance (Calov and Greve, 2005). Input precipitation values are the same between experiments. To introduce  
517 variation between the experiments, temperature varies such that Experiment A is the equivalent of modern day  
518 values, Experiment B has values uniformly reduced by 1°C and Experiment C has values uniformly reduced by  
519 2°C. All other parameters and forcings are equal between experiments. This simple approach to climate forcing  
520 here used for demonstration purposes only, and does not capture the changes to atmospheric and oceanic  
521 circulation patterns that occur during a glacial cycle.

522 The maximum extent of ice for each experiment is shown in Figure 6 and the timing of advance and retreat is  
523 shown in Figure 7. Potentially unrealistic ice sheets occur in the North Sea, perhaps due to the choice of domain  
524 not including the influence of the Fennoscandian ice sheet in this area. As noted above, we do not expect these  
525 model runs to fully replicate the reconstructed characteristics of the BIIS (e.g. Clark et al., 2012). However, it is  
526 worth noting general, visually-derived, observations regarding the outputs shown in Figure 6. For larger  
527 temperature offsets, the ice sheet gets bigger, the timing of maximum extent gets progressively later and the  
528 modelled ice sheet gets thicker (Figure 6). In all experiments, there is generally a gradual advance toward the  
529 maximum extent followed by retreat (Figure 7). This pattern is interrupted by a later readvance that corresponds  
530 to the timing of the Younger Dryas in the GRIP record; this causes ice to regrow over high elevation areas such  
531 as Scotland and central Wales. The extent of this readvance increases with decreased temperature offsets between  
532 experiments (Figure 7). Smaller readvances, occurring around 16.5 ka also occur (Figure 7).

#### 533 **4.2 Geochronological data**

534 Ice-sheet advance dates were taken from the compilation of Hughes et al. (2016) and gridded to the ice sheet  
535 model domain (Figure 4). In total, 61 cells were represented with advance dates (Figure 8A). Considering now  
536 ice-sheet retreat (Figure 8B), dates deemed reliable or probably reliable by Small et al. (2017) were used (i.e.  
537 those given a ‘traffic light rating’ of green or amber). For the dated advance and retreat locations, the

538 geochronological data in each cell was assigned an error corresponding to that which was reported in the literature.  
539 We also compared our results to the ‘likely’ empirical reconstruction of Hughes et al. (2016), based on that of  
540 Clark et al. (2012) (Figure 8C), using the minimum and maximum bounding envelopes to assign an error to each  
541 cell of the ice sheet grid (Figure 8D). The largest errors occur in the North Sea region, where there is a lack of  
542 empirical data (e.g. Figures 8A and B).

### 543 **4.3 Results**

544 Table 4 shows selected statistics derived by ATAT when comparing the three ice-sheet modelling experiments  
545 (Figures 6 and 7) against the three categories of data (Advance, Retreat, Isochrones; Figure 8). wRMSE was not  
546 calculated for the DATED isochrone reconstruction, as grid points are distributed evenly and therefore have equal  
547 spatial weighting (Table 4). Experiment C produces modelled ice-sheets with the greatest areal extent, and  
548 therefore performs best at correctly covering the dated areas (Table 4). However, none of the three experiments  
549 perform particularly well when compared with the data or the empirical reconstruction regarding timing and  
550 results in high (>2000 year) RMSEs (Table 4). The application of ATAT and the results from these simplified  
551 experiments allow us to suggest directions for analysing future experiments.

552 All three experiments produced large RMSEs, in the order of thousands of years, when compared to all three  
553 categories of data (Table 4). For advance ages, the three simulations conform to a large number of dated locations  
554 (e.g. 72% of ages in Experiments B and C; Table 4). However, the RMSEs of advance ages are high (Table 4).  
555 This shows that, while the models perform well at matching the constraint of covering an area in ice after an  
556 advance age (Figure 3), the models often glaciates a region much later than required. Advance dates are particularly  
557 difficult to obtain from the stratigraphic record, and often there may be a long hiatus between the initial deposition  
558 of datable material and the subsequent advance of a glacier. Future experiments with large ensembles should  
559 therefore consider the number of advance dates conformed to (rather than the RMSE) as a more robust guide for  
560 model performance during ice advance.

561 For the retreat comparisons, the three modelling experiments conform to a larger percentage of sites, seemingly  
562 outperforming the empirically-derived DATED reconstruction (Table 4). However, where model-data agreement  
563 occurs, the RMSE produced are much higher when the model is compared to the DATED reconstruction. This is  
564 due to the reconstruction containing large uncertainties in regions which lack geochronological control (for  
565 example in the North Sea, Figure 8). These uncertainties, a product of spatial interpolation across regions with  
566 sparse information, are much greater than those associated with individual dates. Figure 9A shows examples of  
567 output maps from ATAT which display the spatial pattern of agreement and the magnitude of the difference  
568 between Experiment C and the DATED reconstruction. This shows that due to the uncertainty associated with  
569 North Sea glaciation, even where the model produces an unrealistic artefact, there is data-model agreement.  
570 Furthermore, ATAT produces a map which displays the number of years between data-based and modelled retreat  
571 and/or advance (e.g. Figure 9B). Figure 9B, which compares Experiment C to the DATED isochrones, shows that  
572 the timing of model-data disagreement is spatially variable. If more modelling simulations were conducted, such  
573 maps may reveal regions of reconstruction or particular dates which are difficult to simulate in the model. In such  
574 cases, data or model re-evaluation may be required and herein lies the potential utility of this ATAT tool in making  
575 sense of ensemble model runs. However, such model-data comparison awaits a full-ensemble simulation which  
576 accounts for model uncertainty (e.g. Hubbard et al., 2009).

577 **5. Summary and concluding remarks**

578 Here we present ATAT, an automated timing-accordance tool for comparing ice-sheet model output with  
579 geochronological data and empirical ice sheet reconstructions. We demonstrate the utility of ATAT through three  
580 simplified simulations of the former British-Irish Ice Sheet. Note that a larger ensemble model of hundreds to  
581 thousands of runs is required for model evaluation (e.g. Hubbard et al., 2009). ATAT enables users to quantify  
582 the difference between the simulated timing of ice sheet advance and retreat and those from a chosen dataset, and  
583 allows production of cumulative ice coverage agreement maps that should help distinguish between less and more  
584 promising runs. We envisage that this tool will be especially useful for ice-sheet modellers through justifying  
585 model choice from an ensemble, quantifying error and tuning ice-sheet model experiments to fit geochronological  
586 data. Ideally, this tool should be used in combination with other evaluation methods, such as fit to relative sea-  
587 level records. In the case where locations or regions of data cannot be fit by a model, and all model uncertainty  
588 has been accounted for in an ensemble simulation, the comparisons made in ATAT may also highlight that data  
589 re-evaluation is necessary. ATAT is supplied as supplementary material to this article.

590 **6. Code Availability**

591 ATAT 1.1 source code is freely distributed under a GNU GPL licence as supplementary material to this paper. It  
592 can also be downloaded with example input grids from <https://figshare.com/s/6c8f885e9d10558ed359>. An example  
593 geochronological data grid and ice-sheet model grid can also be downloaded from this link. The ice sheet  
594 modelling experiments shown here were conducted using the Parallel Ice Sheet Model (<http://pism-docs.org/>).  
595 Development of PISM is supported by NASA grant NNX17AG65G and NSF grants PLR-1603799 and PLR-  
596 1644277. The geochronological data used is freely available from  
597 <https://www.sciencedirect.com/science/article/pii/S0012825216304408#s0105> and  
598 <https://doi.pangaea.de/10.1594/PANGAEA.848117>.

599 **6.1. General Instructions**

600 ATAT is written in python, and distributed as both .py script, for use in Python 2, and a .py3 script, for use with  
601 Python 3. The tool requires installation of Python and the following freely available Python packages:

- 602 • netCDF4 (<https://pypi.python.org/pypi/netCDF4>)
- 603 • numpy (<http://www.numpy.org/>)
- 604 • scipy (<https://www.scipy.org/>)
- 605 • matplotlib (<https://matplotlib.org/>)
- 606 • matplotlib toolkit basemap (<https://matplotlib.org/basemap/>)

607 ATAT can be run from any Python enabled environment (e.g. IDLE, BASH). Here we provide the following  
608 simple instructions for running ATAT in a BASH shell. For numerous runs, a shell script should be created.

609 From the command line, launch the ATAT script using python (“python ATATv1.1.py”). Eight command-line  
610 arguments (A1 - A8), separated by a space should then follow.

611 A1 dictates whether deglacial or advance ages are being tested. Type “DEGLACIAL” or “ADVANCE”  
612 accordingly.

613 A2 is the path to the geochronological data file (e.g. “/home/ATAT/geochron.nc”)



614 A3 defines whether the model extent is based on thickness or a mask. Type THK or MSK accordingly.  
615 A4 is the path to the ice-sheet model output file (e.g. “/home/ATAT/icesheetmodel1.nc”)  
616 A5 is the value of the ice-sheet output mask. A value is required even if A3 = THK, but can be any value as it will  
617 be ignored.  
618 A6 to A8 control output maps. A6 defines whether the output map should consider margin uncertainty, with a  
619 value of BORDER or NONE.  
620 A7 defines whether the model-data offset map displaces RMSE (option “NONE”) or wRMSE (“WEIGHTED”).  
621 A8 specifies which dates are plotted on the difference map, and can be “ALL” for all dates, “COVERED” for  
622 those which at some point were covered by ice and “INERROR” to display only those dates where model-data  
623 agreement within dating error occurred.  
624 An example command would be “python ATATv1.1.py DEGLACIAL /home/ATAT/dated\_recon.nc MSK  
625 /home/ATAT/experiment1.nc 2 BORDER WEIGHTED INERROR”. ATAT then outputs the two maps and a csv  
626 table containing all derived statistics.  
627 Input geochronological data can be created in a GIS environment such as ArcMap or QGIS. Here, the user must  
628 discern the appropriate geochronological data for each grid cell. Since geochronological data is usually stored as  
629 point data, this must be gridded to single grid points as positive values, with surrounding areas of no data assigned  
630 a value of 0. When comparing to a reconstruction (e.g. Hughes et al., 2016), cells outside the reconstruction  
631 should be assigned a value of 0. Those within the reconstruction should be assigned a value corresponding to the  
632 reconstructed age of retreat. The gridded data must be converted to NetCDF format, the details of which are shown  
633 in Table 3. We emphasise that the quality of geochronological data used must be considered, and an example of  
634 how to filter geochronological data is documented in Small et al. (2017). Ice thickness grids can be created using  
635 ice sheet modelling software such as PISM (Winkelmann et al., 2011). The two grids (data and model) must be  
636 aligned and have the same size dimensions for use in ATAT. Examples are included as supplementary material,  
637 including a model output from Ely et al. (in review).

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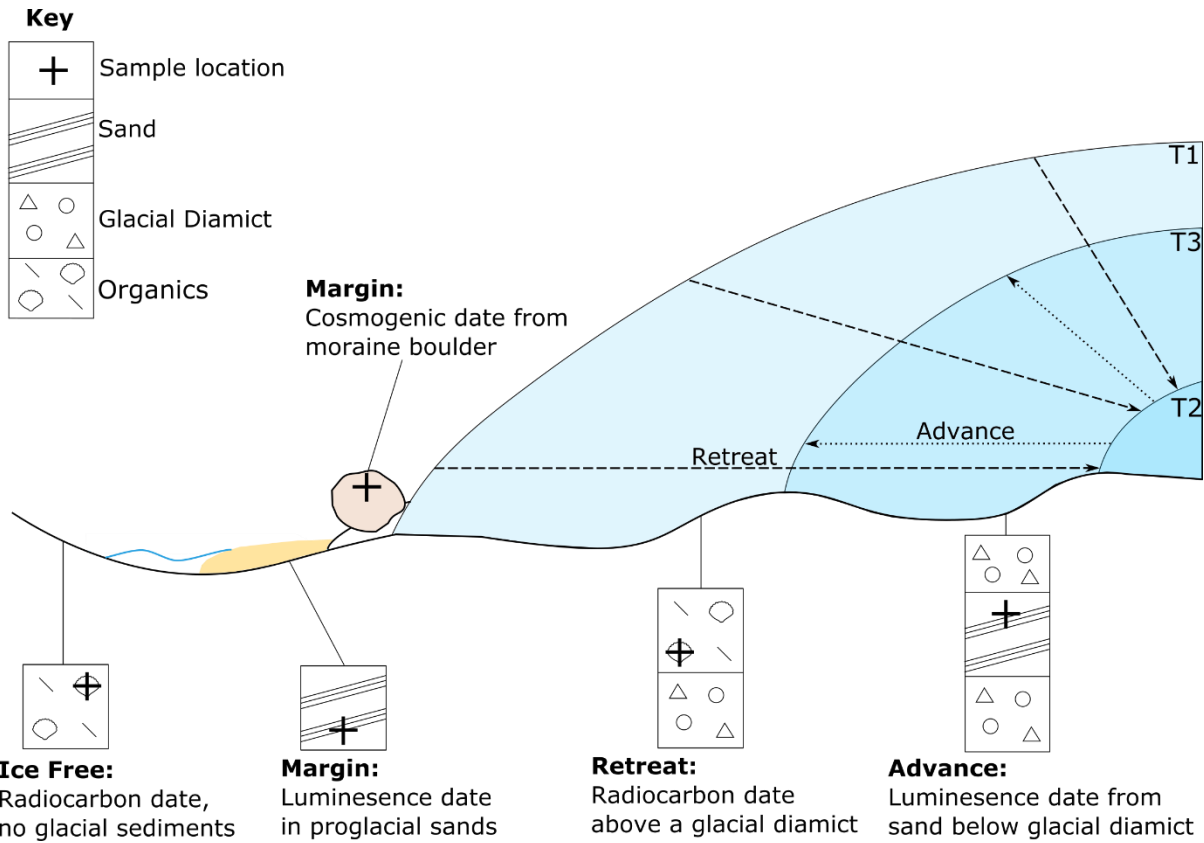
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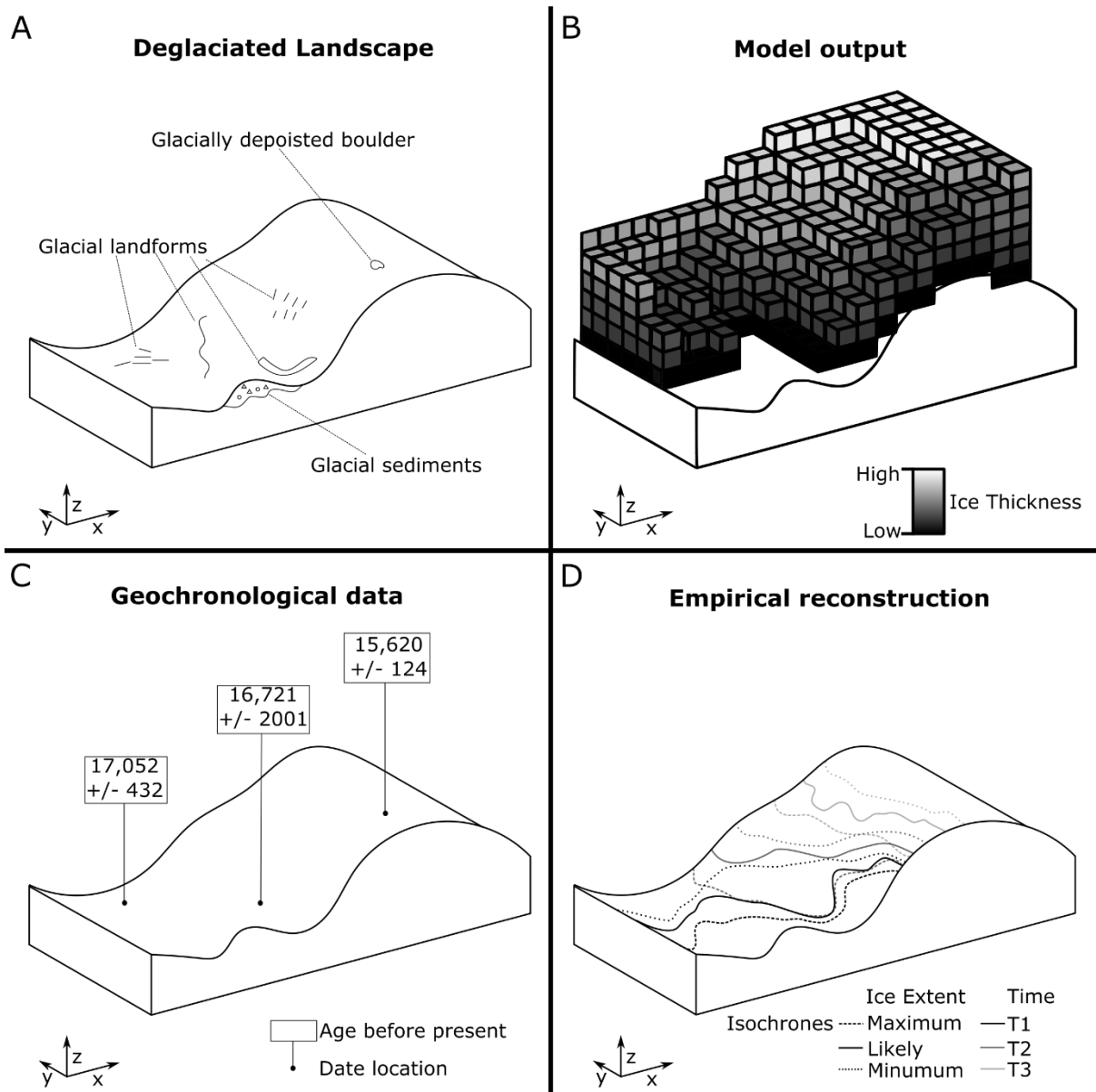


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**Figure 1: Schematic illustration of stratigraphic and inferred glaciological context of geochronological data. Note that at T1 the ice sheet is at its most advanced. It then retreats to a minimum at T2, before re-advancing to T3.**



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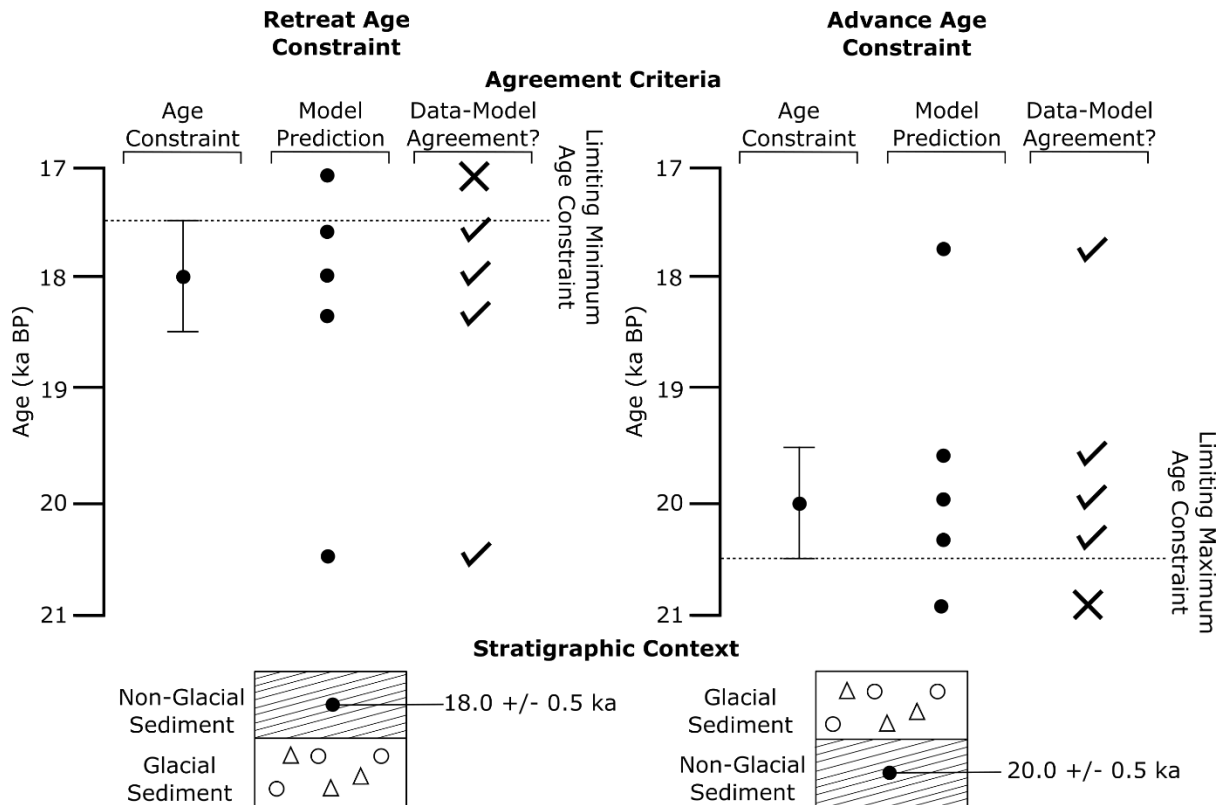
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**Figure 2. Schematic of geochronological data and ice-sheet model output. A) A deglaciaded landscape, demonstrating some of the features used by palaeo-glaciologists when empirically reconstructing an ice sheet. B) Ice-sheet model output, displaying modelled ice-sheet thickness, in this case at a specific time. C) Geochronological data. D) Empirical reconstruction. Note how the nature of these data vary between source.**





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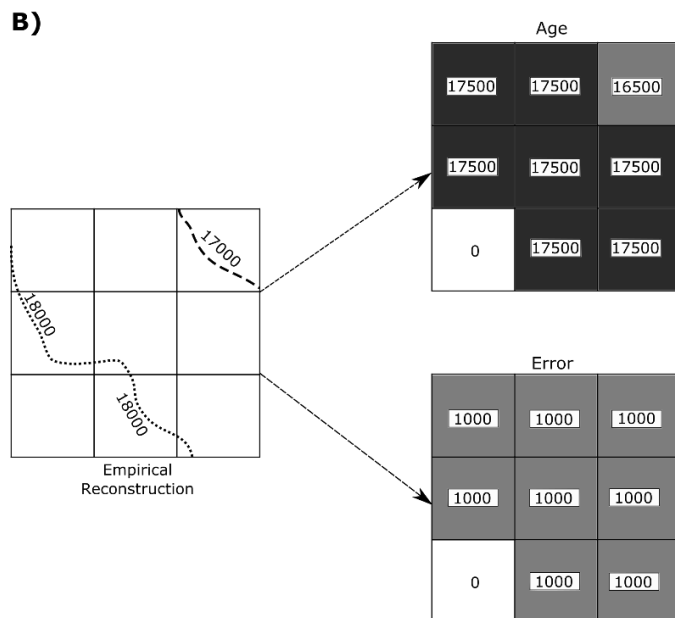
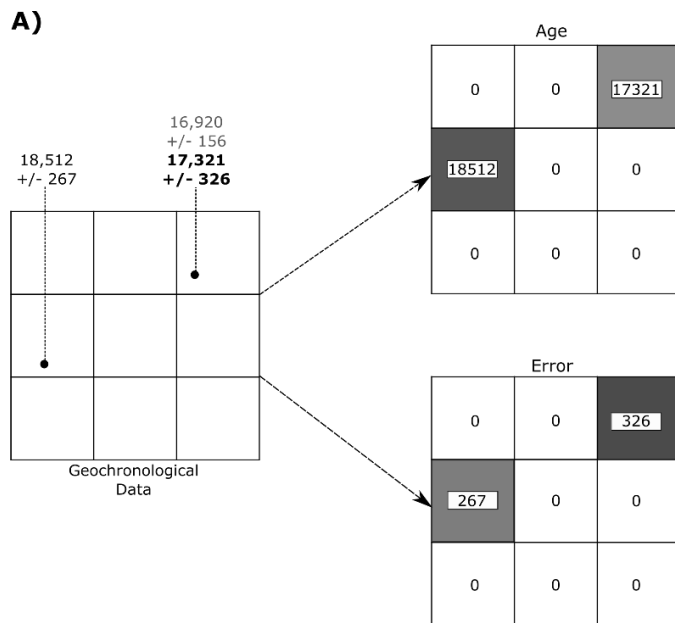
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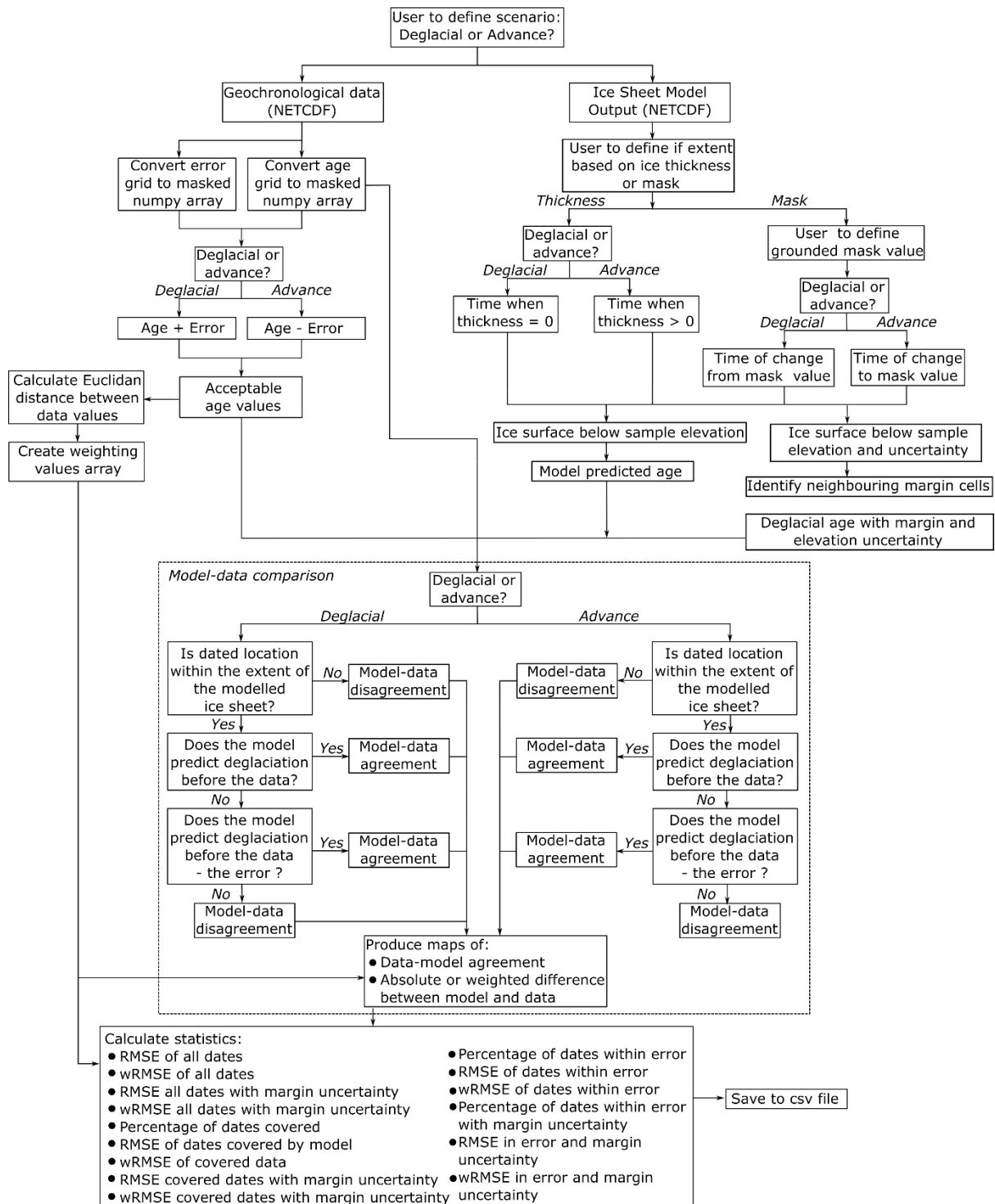
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**Figure 3. Schematic of the identification of data-model agreement with consideration of error by ATAT for retreat (left) and advance (right) data. If a model predicts ice free conditions before an ice-free age, or during the associated error, there is data-model agreement. If deglaciation occurs at this location after the error, the model disagrees with the data. If a model predicts ice advance and cover before the advance age and its associated error, there is model-data disagreement. Agreement between the model and data occurs if ice advances over the location after the date, or before the date within the range of the error. This is used by ATAT to categorise sites as to whether agreement or disagreement between the model and data occurs.**



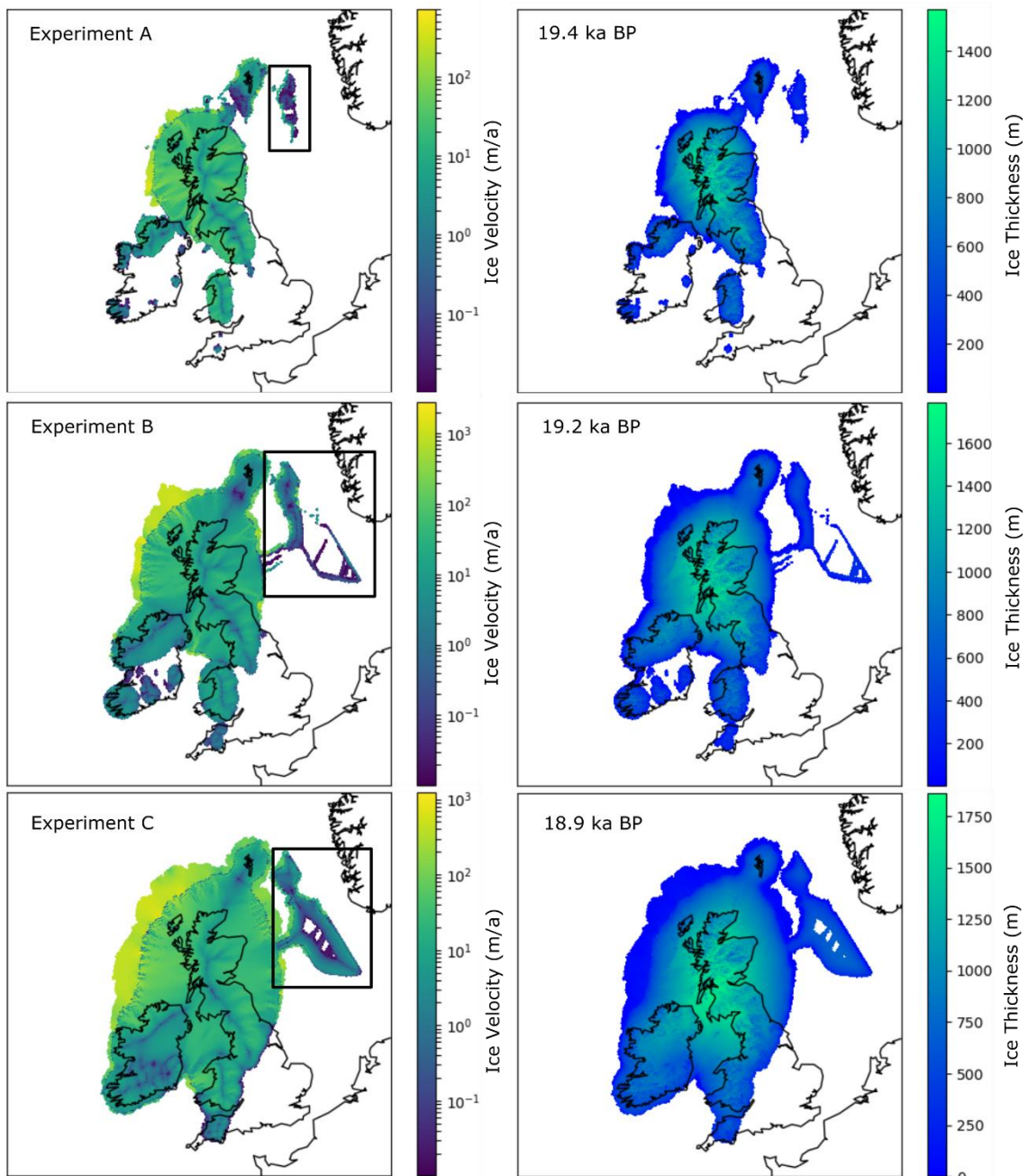
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868 **Figure 4. Examples of empirical data preparation for ATAT. (A) Conversion of geochronological data into**  
 869 **a grid for ATAT. In this example the user has made a judgement based on a priori knowledge that the date**  
 870 **of  $17,321 \pm 326$  is most representative of the event of interest. Note that age and error are split into separate**  
 871 **grids, and that no data regions are assigned a value of 0. (B) Conversion of an empirical reconstruction**  
 872 **(margin isochrones) into a grid for ATAT. Here we simply assume that the area between isochrones became**  
 873 **deglaciated between at the age between the two isochrones, and that associated error is 1000 years. More**  
 874 **complex reconstructions (e.g. Hughes et al., 2016) may require different user-defined rules.**



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876 **Figure 5. Flow chart of ATAT procedure. See text for further description.**



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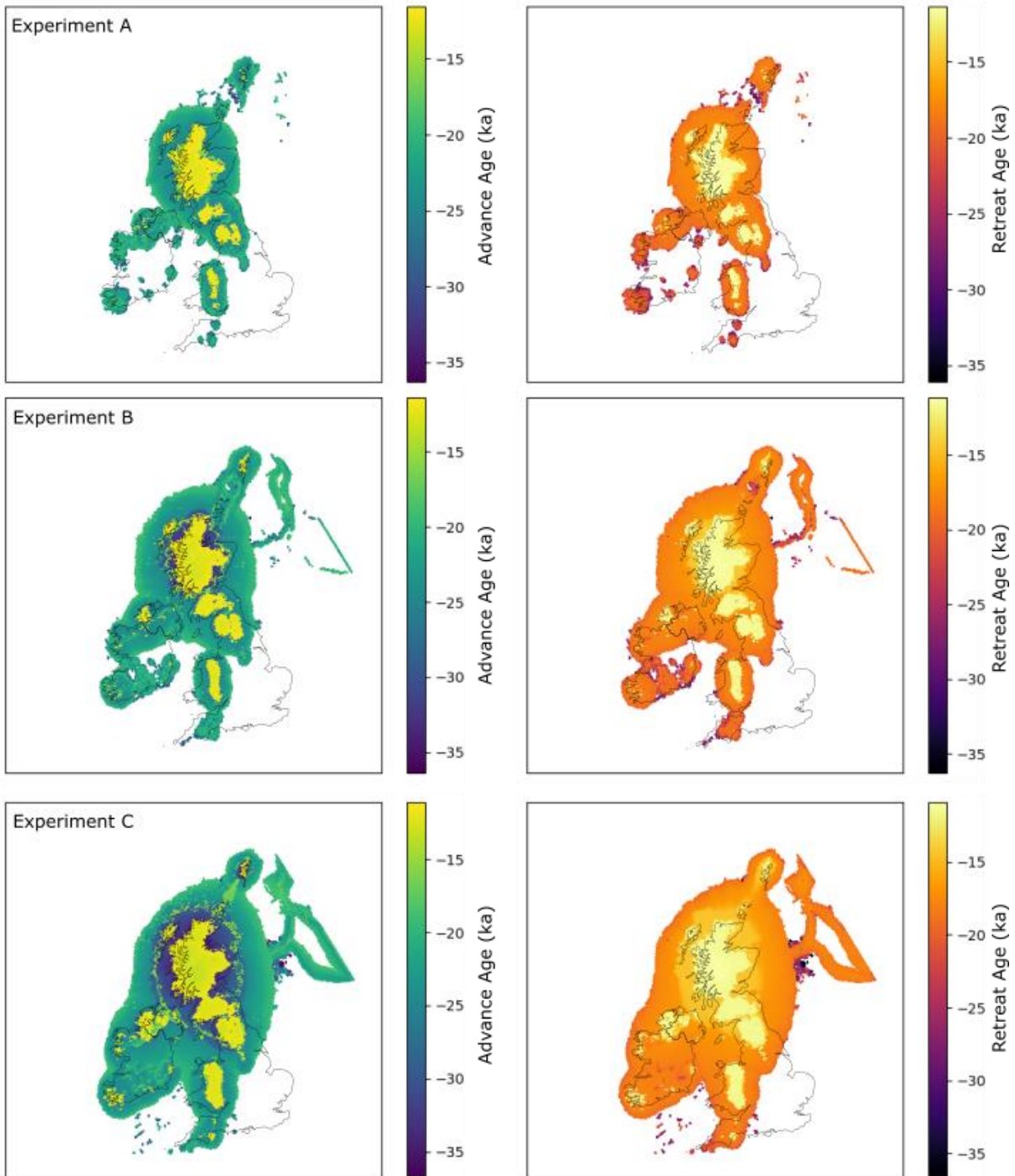
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**Figure 6. Maximum extent of produced ice sheet for the three experiments. Experiment B is  $1^{\circ}\text{C}$  colder than A, and experiment C is  $2^{\circ}\text{C}$  colder than A. Left panel shows ice velocity, right is ice thickness. The box on the left panel highlights likely erroneous output in the North Sea, likely a consequence of model domain, discussed further in the text.**

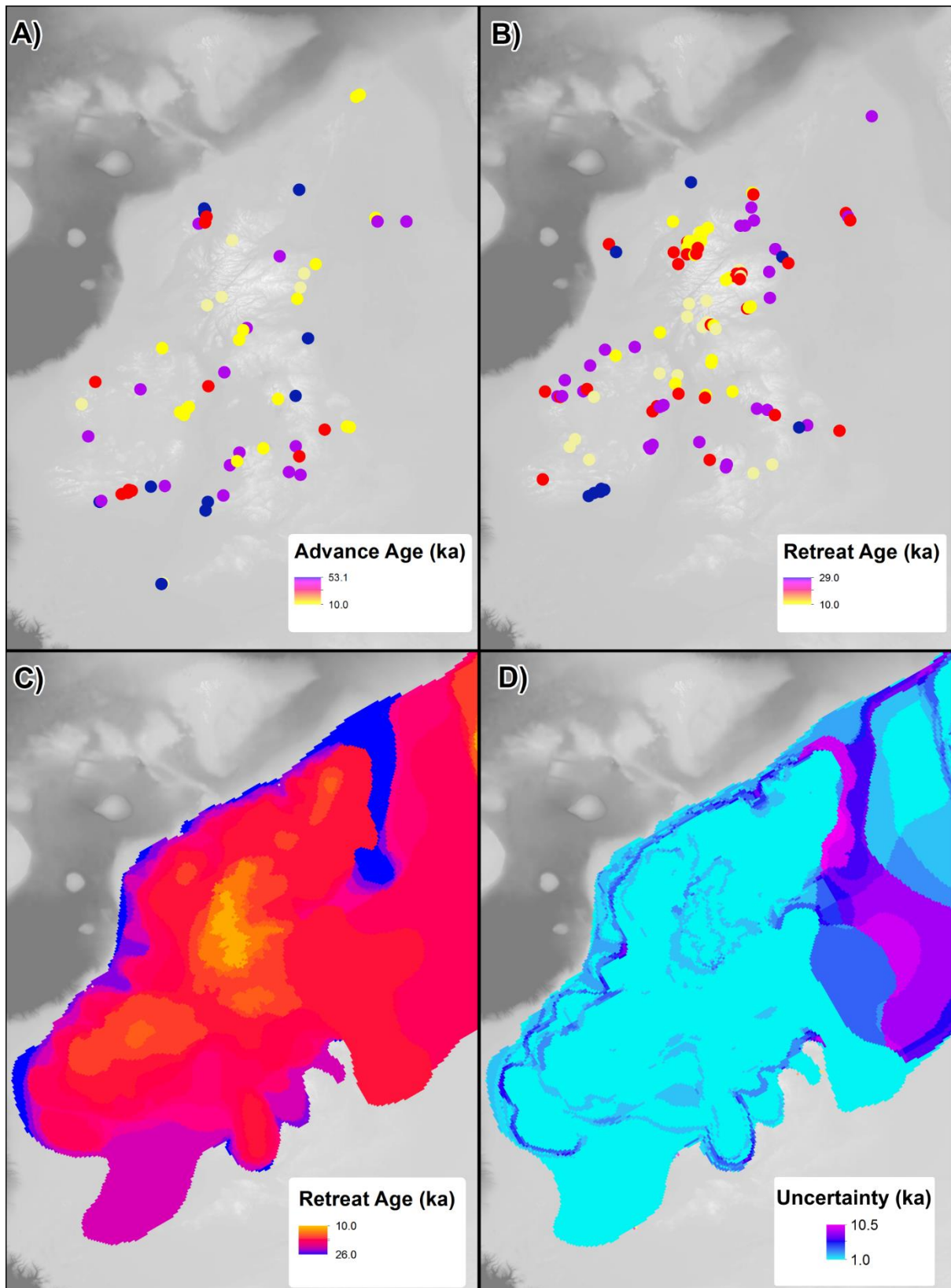


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883 **Figure 7. Timing of advance (left) and retreat (right) from the three ice sheet modelling experiments.**

884 **Experiments are the same as in Figure 6. The early ages toward the centre of the model, and centred over**

885 **higher topography, represent the modelled extent of the Younger Dryas readvance.**



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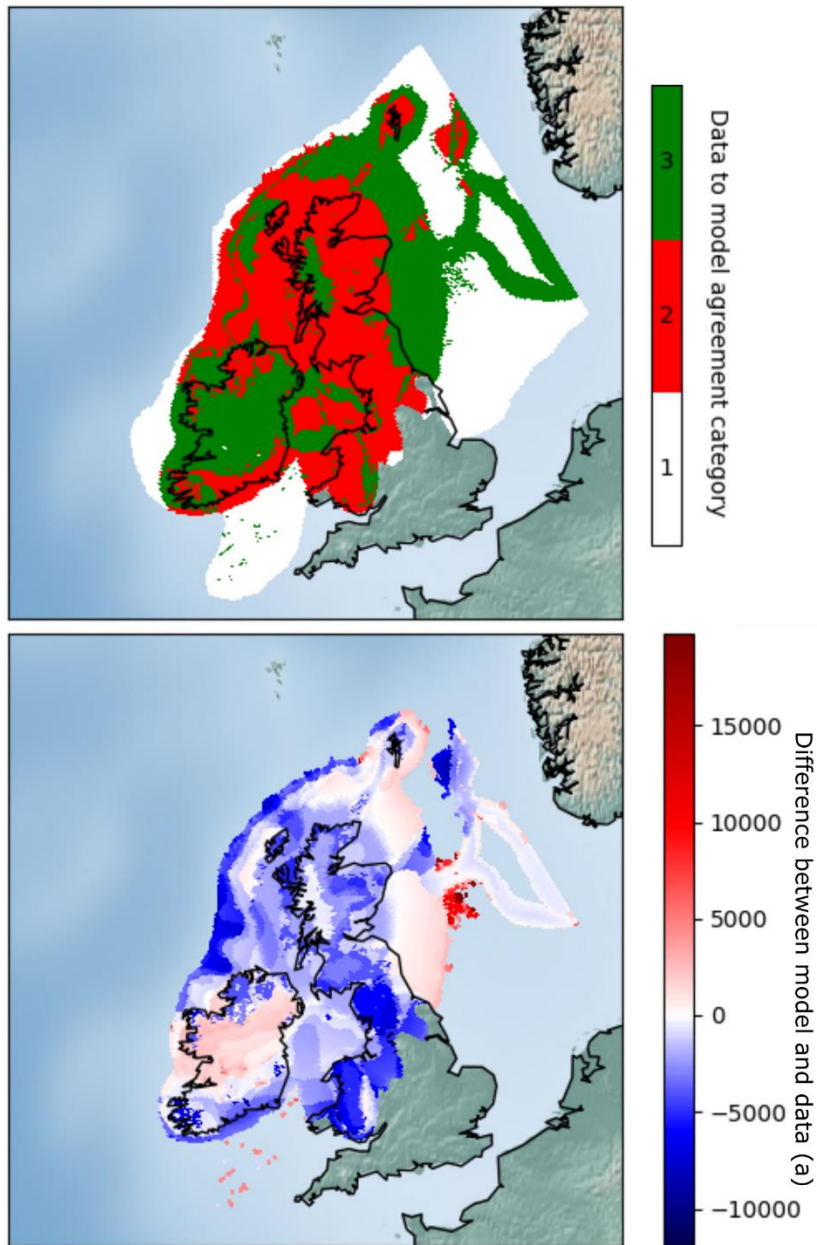
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**Figure 8.** Example of geochronological data projected onto model raster grids; as point-data in A and B and from an empirical reconstruction in C and D. (A). Advance ages from Hughes et al. (2016). (B) Retreat ages from Small et al. (2017). (C) Retreat age derived from DATED isochrone reconstruction (Hughes et al., 2016). (D) Error associated with reconstruction in C.





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 892 **Figure 9.** Example mapped outputs from ATAT. In this case, experiment C was compared with the DATED  
 893 reconstruction. Top map (cumulative agreement) shows categories of data-model agreement across the  
 894 domain, where 1 = not covered by model, 2 = no agreement and 3 = data-model agreement within error.  
 895 The lower map (model-data offset) shows magnitude of difference between model and data; negative values  
 896 show a modelled retreat of ice later than the DATED isochrones, and positive values show a modelled  
 897 retreat of ice before the DATED isochrones.

898 Table 1. Classification of geochronological data (after Hughes et al., 2011) and its use in ATAT.

<b>Class</b>	<b>Glaciological context</b>	<b>Stratigraphic context</b>	<b>Example</b>	<b>Use in ATAT</b>
Advance	Ice-sheet build up	Material directly below or incorporated within glacial diamict	Luminescence date from a sand below a glacial diamict	Ice cover a short time after this date
Retreat	Ice-free after ice cover	Dated material above glacial diamict	Radiocarbon date of a shell above a glacial diamict	Ice-free conditions from this date onwards (note deglaciation could have occurred a long time before)
Ice Free	Ice-free, but lacking direct information regarding ice	Dated material which indicates ice-free conditions but has no relation to ice cover. It may be much younger and not provide much useful constraint.	Radiocarbon date of organic sediments without underlying glacial sediments	
Margin	Proximal to an ice sheet margin	Dated material with information that ties it to an ice margin	Luminescence date in proglacial sands	
Exposure time (cumulative)	Length of time since sample exposed	N/A	Cosmogenic isotope on erratic boulder above a trimline	Not used

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Table 2. Comparison of attributes between geochronological data and ice sheet model output.

	<b>Nature of data produced</b>	<b>Spatial resolution</b>	<b>Spatial continuity</b>	<b>Temporal frequency and resolution</b>	<b>Sources of uncertainty</b>	<b>Main limitation</b>
<b>Geochronological data</b>	Timing of the absence of ice at a location	Point location	Point location, unevenly distributed in space, but can be interpolated	Determined by data availability and associated error	Instrumental, environmental and stratigraphic factors	Reliant upon correct stratigraphic interpretation to tie to glaciological events
<b>Ice-sheet model output</b>	Simulation of physically plausible ice sheet conditions	Various, ranging from tens to unit kilometres.	Spatially even, regularly-spaced across entire domain	Continuous in time. Precise subannual resolution possible, but not recorded in practice	Parameterisations, boundary conditions	Based upon mathematical and physical approximations of ice flow

<b>Data source</b>	<b>NetCDF Variable</b>	<b>Units</b>	<b>Dimensions</b>	<b>Description</b>	<b>Notes</b>
		Time	unit x, y	Calendar years before present	
		before reference calendar date			
<b>Ice sheet model output</b>	thk	m	time, x,y	Ice thickness	Either “thk” or “msk” required by ATAT.
	msk	Integers	time, x,y	Grounded/floating/icefree mask	Either “thk” or “msk” required by ATAT. User defines value referring to the location of grounded ice
	lat	Decimal degrees	x, y	Latitude	
<b>Both</b>	lon	Decimal degrees	x, y	Longitude	
<b>Geochronological data</b>	age	Time unit before reference calendar date	x, y	Timing of deglaciated conditions	Deglacial and advance ages must be in separate files.
	error	Seconds	x, y	Error associated with deglaciated conditions	Error associated with either deglacial and advance age must be in associated separate file.
	topg	m	x,y	Modern elevation at resolution of ice-sheet model	

elevation            m            x,y            Elevation of collected sample

Table 3. Required input variables for ATAT NetCDF files.

Table 4: Example statistics from ATAT. Note that the RMSE is often altered by applying the spatial weighting to create wRMSE.

Ice Sheet Modelling Experiment	Advance			Retreat			Empirical Reconstruction; DATED		
	A	B	C	A	B	C	A	B	C
Percentage of dates covered	52.5	72.1	88.5	76.1	91.7	96.3	32.9	52.6	69.8
Percentage that agree within error	65.6	72.7	72.2	22.0	22.0	12.8	23.2	27.0	17.8
RMSE dates covered by model	11075.9	12732.7	13490.3	3879.0	4180.9	4945.4	2972.5	2678.0	2920.8
wRMSE dates covered by model	13357.3	13994.7	14849.7	4073.4	4450.3	5165.8	N/A	N/A	N/A
RMSE dates within error	655.7	478.6	289.3	403.6	259.7	236.2	12023.4	10638.7	8777.6
wRMSE dates within error	615.4	395.0	223.6	422.1	276.9	248.9	N/A	N/A	N/A