

1    **Supplementary Material**

2    **Supplement S1: Further Details of the Partial Least Squares approach**

3    PLS operates by projecting  $\mathbf{X}$  and  $\mathbf{Y}$  into new spaces, determined by maximising the covariance  
4    between the projections of  $\mathbf{X}$  and  $\mathbf{Y}$ . The transformations of  $\mathbf{X}$  and  $\mathbf{Y}$  are given by  $\mathbf{X} = \mathbf{TP}^T + \mathbf{E}$   
5    and  $\mathbf{Y} = \mathbf{UQ}^T + \mathbf{F}$ , where  $\mathbf{T}$  and  $\mathbf{U}$  are the projections of  $\mathbf{X}$  and  $\mathbf{Y}$  respectively,  $\mathbf{P}$  and  $\mathbf{Q}$  are  
6    orthogonal matrices, and  $\mathbf{E}$  and  $\mathbf{F}$  are independent and identically distributed error terms. It is  
7    straightforward to show that  $\mathbf{Y} = \mathbf{XB} + \mathbf{G}$ , where  $\mathbf{B} = \mathbf{X}^{-1}\mathbf{TQ}^T$  and  $\mathbf{G} = (\mathbf{U} - \mathbf{T})\mathbf{Q}^T + \mathbf{F}$ . The  
8     $\mathbf{B}$  matrix stores the PLS-regression coefficients, which can be interpreted as sensitivity indices  
9    (Chang et al., 2015; Sobie, 2009).

10    **Supplement S2: Calculating first order and total sensitivity indices using the Sobol method**

11    **without dimension reduction**

12    We run the following R script file:

```
13 X=read.csv('InputsNorm_TrainingData.csv', header=FALSE)
14 yALL =read.csv('Outputs_TrainingData.csv', header=FALSE)
15 SI = matrix(-9999,nrow=dim(inputs)[2],ncol= dim(outputs)[2])
16 SI.total = matrix(-9999,nrow=dim(inputs)[2],ncol= dim(outputs)[2])
17 for (j in 1: dim(outputs)[2]) {y = as.matrix(yALL[,j],rownames.force=NA)
18 m = km(~ ., design = X, response = y, covtype = "matern3_2")
19 AB = randomLHS(N,16); A = AB[,1: dim(X)[2]]; B = AB[, (dim(X)[2]+1):(dim(X)[2]*2)]
20 yA = predict.km(m, A, "UK", se.compute = FALSE, checkNames = FALSE)$mean
21 yB = predict.km(m, B, "UK", se.compute = FALSE, checkNames = FALSE)$mean
22 yA_sum = mean(yA); yB_sum = mean(yB); yAyA_sum = mean(yA^2); yByB_sum = mean(yB^2)
```

```

1  for (i in 1: dim(X)[2]) {print(c(j,i)); Ci=B; Ci[,i]=A[,i]; Di=A; Di[,i]=B[,i]
2  yCi = predict.km(m, Ci, "UK", se.compute = FALSE, checkNames = FALSE)$mean
3  yDi = predict.km(m, Di, "UK", se.compute = FALSE, checkNames = FALSE)$mean
4  yCi_sum = mean(yCi); yDi_sum = mean(yDi); yCiyCi_sum = mean(yCi^2);
5  yDiyDi_sum = mean(yDi^2); yAyCi_sum = mean(yA*yCi);
6  yAyDi_sum = mean(yA*yDi); yByCi_sum = mean(yB*yCi);
7  yByDi_sum = mean(yB*yDi); SI_temp = rep(-9999, 8)
8  SI_temp[1] = (yAyCi_sum - (yA_sum*yB_sum))/(yAyA_sum - (yA_sum*yB_sum))
9  SI_temp[2] = (yByDi_sum - (yA_sum*yB_sum))/(yByB_sum - (yA_sum*yB_sum))
10 SI_temp[3] = (yAyCi_sum - (yA_sum*yB_sum))/(yByB_sum - (yA_sum*yB_sum))
11 SI_temp[4] = (yAyCi_sum - (yCi_sum*yDi_sum))/(yCiyCi_sum - (yCi_sum*yDi_sum))
12 SI_temp[5] = (yAyCi_sum - (yCi_sum*yDi_sum))/(yDiyDi_sum - (yCi_sum*yDi_sum))
13 SI_temp[6] = (yByDi_sum - (yA_sum*yB_sum))/(yAyA_sum - (yA_sum*yB_sum))
14 SI_temp[7] = (yByDi_sum - (yCi_sum*yDi_sum))/(yCiyCi_sum - (yCi_sum*yDi_sum))
15 SI_temp[8] = (yByDi_sum - (yCi_sum*yDi_sum))/(yDiyDi_sum - (yCi_sum*yDi_sum))
16 SI[i,j] = mean(SI_temp)}}
17 write.table(SI*100, "SIs_Sobol_EmulatorOnly.csv", row.names=F, col.names=F, sep=", ")

```

18 To compute the total indices, the eight SI\_temp lines can be replaced with the following:

```

19 SI_temp[1] = (yAyDi_sum - (yA_sum*yB_sum))/(yAyA_sum - (yA_sum*yB_sum))
20 SI_temp[2] = (yByCi_sum - (yA_sum*yB_sum))/(yByB_sum - (yA_sum*yB_sum))
21 SI_temp[3] = (yAyDi_sum - (yCi_sum*yDi_sum))/(yAyA_sum - (yCi_sum*yDi_sum))
22 SI_temp[4] = (yByCi_sum - (yCi_sum*yDi_sum))/(yByB_sum - (yCi_sum*yDi_sum))

```

1   **Supplement S3: Calculating first order and total sensitivity indices using the Sobol method,  
2   using principal component analysis to reduce the dimensionality of the output**

3   We run the following R script file to compute the sensitivity indices for the emulator-PCA  
4   hybrid approach. The R script below can be modified to ensure that the number of principal  
5   components included accounts for a specified proportion of the variance (chosen here to be  
6   99%).

```
7 X=read.csv('InputsNorm_TrainingData.csv', header=FALSE)
8 yALL =read.csv('Outputs_TrainingData.csv', header=FALSE)
9 S = var(Y); S.eig = eigen(S)
10 eig.value.cumul = cumsum((S.eig$values/sum(S.eig$values))*100)
11 yALL.dim.index = c(1:dim(yALL)[2]); Npca=min(yALL.dim.index[eig.value.cumul>99])
12 ptm <- proc.time()
13 AB <- randomLHS(N,(dim(X)[2]^2))
14 A <- AB[,1:dim(X)[2]]; B <- AB[, (dim(X)[2]+1):(dim(X)[2]^2)]
15 yA_PCA=matrix(-9999,N,Npixels); yB_PCA=matrix(-9999,N,Npixels)
16 for (j in 1:Npc){
17   PC <- matrix(rep(S.eig$vectors[,j],dim(X)[1]),nrow=dim(X)[1],ncol=Npixels,byrow=TRUE)
18   y_PCj <- as.matrix(rowSums(PC*Y),rownames.force=NA)
19   assign(paste("m",j, sep=""),km(~ ., design = X, response = y_PCj, covtype = "matern5_2"))
20   yA_PCA[,j] <- predict.km(eval(as.symbol(paste("m",j,sep="))), A, "UK", se.compute =
21   FALSE, checkNames = FALSE)$mean
22   yB_PCA[,j] <- predict.km(eval(as.symbol(paste("m",j,sep="))), B, "UK", se.compute =
23   FALSE, checkNames = FALSE)$mean
```

```

1   }
2   for (j in (Npc+1):Npixels){
3     yA_PCA[j]=matrix(0,nrow=N,ncol=1); yB_PCA[j]=matrix(0,nrow=N,ncol=1)
4   }
5   PCs.inv <- solve(S.eig$vectors); yA <- yA_PCA%*%PCs.inv; yB <- yB_PCA%*%PCs.inv
6   yCi <- matrix(-9999,nrow=N,ncol=Npixels*dim(X)[2])
7   yDi <- matrix(-9999,nrow=N,ncol=Npixels*dim(X)[2])
8   for (i in 1:dim(X)[2]){
9     print(c(i)); Ci=B; Ci[i]=A[i]; Di=A; Di[i]=B[i]
10    yCj_PCA <- matrix(-9999,nrow=N,ncol=Npixels)
11    yDj_PCA <- matrix(-9999,nrow=N,ncol=Npixels)
12    for (j in 1:Npc){
13      yCj_PCA[j] <- predict.km(eval(as.symbol(paste("m",j,sep=""))), Ci, "UK", se.compute =
14      FALSE, checkNames = FALSE)$mean
15      yDj_PCA[j] <- predict.km(eval(as.symbol(paste("m",j,sep=""))), Di, "UK", se.compute =
16      FALSE, checkNames = FALSE)$mean
17    }
18    for (j in (Npc+1):Npixels){
19      yCj_PCA[j] <- matrix(0,nrow=N,ncol=1); yDj_PCA[j] <- matrix(0,nrow=N,ncol=1)
20    }
21    i2 <- i*Npixels; i1 <- i2 - (Npixels-1)
22    yCi[,i1:i2] <- yCj_PCA%*%PCs.inv; yDi[,i1:i2] <- yDj_PCA%*%PCs.inv
23  }

```

```

1  SI <- matrix(-9999,nrow=8,ncol=Npixels)
2  for (i in 1:Npixels){
3    yA_sum <- mean(yA[,i]); yB_sum <- mean(yB[,i]);
4    yAyA_sum <- mean(yA[,i]^2); yByB_sum <- mean(yB[,i]^2)
5    SI_temp <- rep(-9999,8)
6    for (j in 1:8){
7      z <- ((j-1)*Npixels) + I; yCi_sum <- mean(yCi[,z]); yDi_sum <- mean(yDi[,z])
8      yCiyCi_sum <- mean(yCi[,z]^2); yDiyDi_sum <- mean(yDi[,z]^2)
9      yAyCi_sum <- mean(yA[,i]*yCi[,z]); yAyDi_sum <- mean(yA[,i]*yDi[,z])
10     yByCi_sum <- mean(yB[,i]*yCi[,z]); yByDi_sum <- mean(yB[,i]*yDi[,z])
11     SI_temp[1] <- (yAyCi_sum - (yA_sum*yB_sum))/(yAyA_sum - (yA_sum*yB_sum))
12     SI_temp[2] <- (yByDi_sum - (yA_sum*yB_sum))/(yByB_sum - (yA_sum*yB_sum))
13     SI_temp[3] <- (yAyCi_sum - (yA_sum*yB_sum))/(yByB_sum - (yA_sum*yB_sum))
14     SI_temp[4] <- (yAyCi_sum - (yCi_sum*yDi_sum))/(yCiyCi_sum - (yCi_sum*yDi_sum))
15     SI_temp[5] <- (yAyCi_sum - (yCi_sum*yDi_sum))/(yDiyDi_sum - (yCi_sum*yDi_sum))
16     SI_temp[6] <- (yByDi_sum - (yA_sum*yB_sum))/(yAyA_sum - (yA_sum*yB_sum))
17     SI_temp[7] <- (yByDi_sum - (yCi_sum*yDi_sum))/(yCiyCi_sum - (yCi_sum*yDi_sum))
18     SI_temp[8] <- (yByDi_sum - (yCi_sum*yDi_sum))/(yDiyDi_sum - (yCi_sum*yDi_sum))
19     SI[j,i] <- mean(SI_temp)
20   }
21 }
22 proc.time() - ptm  #Stop the clock

```

```

1 write.csv(data.frame(SI*100), file =
2 paste("SIs_Sobol_EmulatorPCA_",modelN,"_N",N,".csv",sep=""), row.names=FALSE)

```

3 **Supplement S4: Basic emulator diagnostic checks**

4 We run the following R script file:

```

5 library(sensitivity); library(DiceKriging); library(DiceOptim); library(lhs);
6 X=read.csv('InputsNorm_TrainingData.csv', header=FALSE)
7 inputs_val_norm = maximinLHS(30,dim(X)[2])
8 write.table(inputs_val_norm,"InputsNorm_TrainingData.csv", row.names=F, col.names=F,
9 sep=", ")
10 inputs_val = matrix(-9999,nrow=30,ncol=dim(X)[2])
11 for (i in 1:dim(X)[2]) {inputs[,i] = (inputs_val_norm[,i]*(max(X[,i])-min(X[,i])) + min(X[,i])
12 write.table(inputs_val,"Inputs_ValidationRuns.csv", row.names=F, col.names=F, sep=", ")

```

13 Each row of the *Inputs\_ValidationRuns.csv* file provides the input values for a given model  
14 simulation, and we write the output to a corresponding row in the output file  
15 *Outputs\_ValidationRuns.csv*. The diagnostic check compares the outputs of the simulator at the  
16 validation inputs with those predicted by the emulator. We run the following R script file to  
17 carry out this diagnostic check:

```

18 X=read.csv('InputsNorm_TrainingData.csv', header=FALSE)
19 yALL =read.csv('Outputs_TrainingData.csv', header=FALSE)
20 X_val=read.csv('InputsNorm_ValidationRuns.csv', header=FALSE)
21 yALL_val =read.csv('Outputs_ValidationRuns.csv', header=FALSE)
22 for (j in 1: dim(yALL)[2]) {y = as.matrix(yALL[,j],rownames.force=NA)

```

```

1  m = km(~ ., design = X, response = y, covtype = "matern5_2")
2  yALL_val_emul[j] = as.matrix(predict.km(m, X_val, "UK", se.compute=FALSE,
3  checkNames=FALSE)$mean)
4  plot(c(yALL_val),c(yALL_val_emul),main="Emulator versus Simulator predictions at validation
5  inputs",xlab="simulator", ylab="emulator").
6  print(cor(c(x),c(y))^2)*100

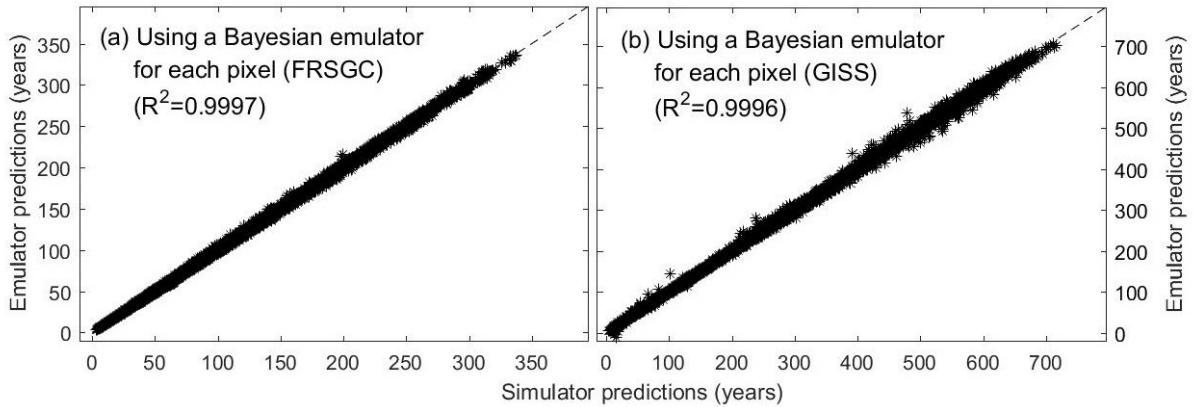
```

7 This prints the value of the coefficient of determination, R<sup>2</sup>.

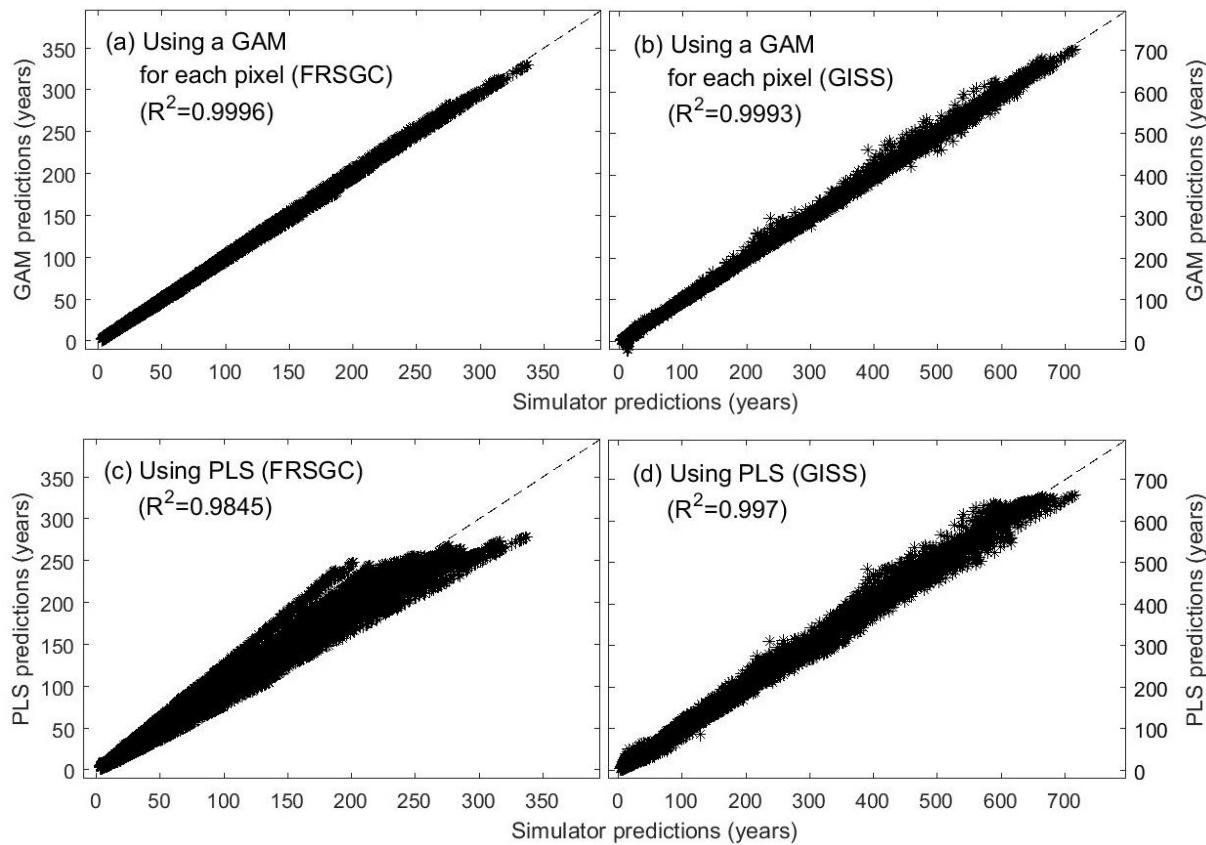
```

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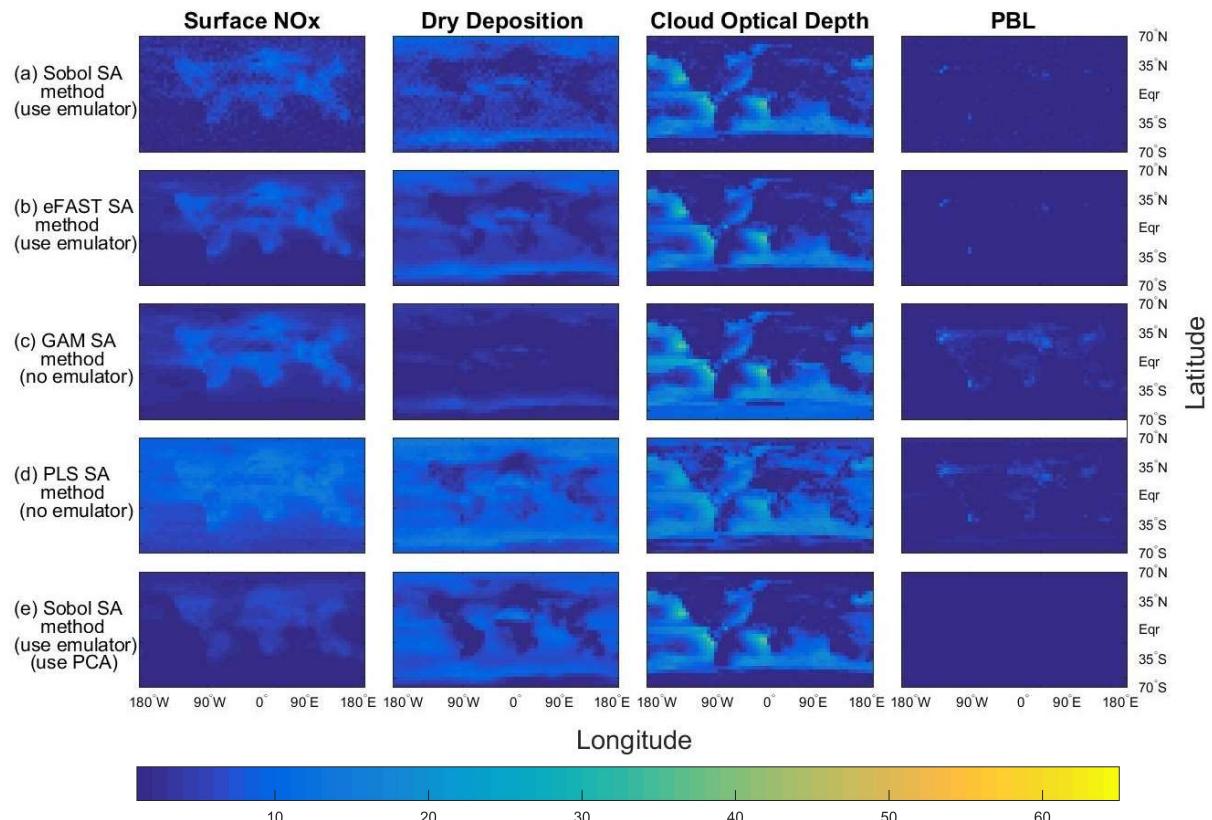
```



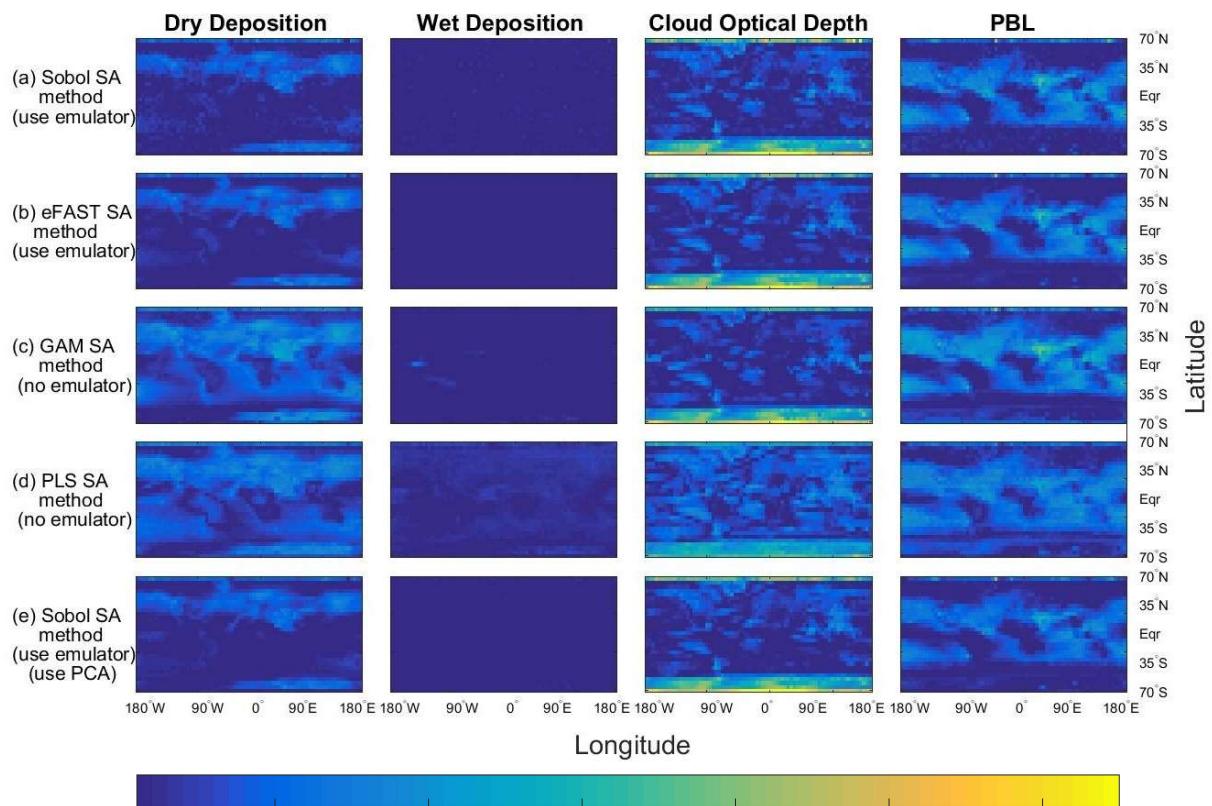
**Figure S1.** Annual column mean CH<sub>4</sub> lifetime calculated by the FRSGC and GISS chemistry models (x-axis) versus predicted by the Gaussian Process emulator (y-axis).



**Figure S2.** Annual column mean CH<sub>4</sub> lifetime calculated by the FRSGC and GISS chemistry models (x-axis) versus predictions by a separate generalized additive model (panels a and b) or partial least squares model (panels c and d) for each pixel (y-axis).



**Figure S3.** Sensitivity indices for the four minor inputs for the FRSGC chemistry transport model showing the inputs not already included in Figure 3.



**Figure S4.** Sensitivity indices for the four minor inputs for the GISS chemistry transport model showing the inputs not already included in Figure 4.