

Dear GMD editor,

First, we would like to thank the associate editor and reviewers for handling our manuscript. Enclosed to this letter, a revised version of our manuscript GMD-2016-162 can be found. We believe we have addressed all comments raised by the reviewers and modified the manuscript accordingly. The most important changes can be found in Sect. 4, where the results of statistical significance tests are added and discussed. In addition, some textual issues have been fixed and the information from the original Tables 1 and 2 has been merged. Finally, we would also like to highlight that the v3a GLEAM dataset has been extended until 2015, and that the in situ validation data has been updated to their latest versions. Although this only resulted in minor changes in the validation statistics, the relevant figures have been updated accordingly. Below, a list of the comments per reviewer is provided, together with our reply and how we modified things in the manuscript. We hope that this revised version of the manuscript is eligible for publication in GMD.

Brecht Martens,

On behalf of all co-authors.

RC1 (published online: 30/11/2016):

1. MAJOR: In several Tables and Figures, the comparison between the three versions of v3 dataset, and against v2 dataset, is shown. In terms of soil moisture, it is highlighted that v3 performs better than v2 and that v03a is performing the best. However, I am wondering if the differences in the correlations between datasets are statistically significant. For instance, I believe that the differences reported in Table 3 for the overlap period between the three v3 datasets are not significant (median values between 0.61 and 0.65 for surface soil moisture). Therefore, I wouldn't stress too much that the new dataset is performing the best in terms of soil moisture, as the differences in the performance are quite small.

We thank the referee for this comment and agree that we need to support the results with statistical significance tests. Therefore, in the revised version of the manuscript we have included the results from a statistical test to verify whether differences in correlations are significant or not.

Changes in manuscript

Statistical significance tests have been performed to analyse the differences in correlations against in situ measurements between different datasets and/or experiments. The test used here is described at P11-L8-11. The results of these tests are discussed throughout Sect. 4: 'Results and Discussion'.

2. MODERATE: It is underlined several times that v03b and v03c are 'fully satellite-based' datasets. It is not correct. The satellite rainfall product used as input is the gauge-corrected version of TMPA. As it is well-known, in TMPA 3B42v7 dataset ground observations are used for correcting the monthly totals month-by-month. They are not used for correcting the long-term bias, as it reads at lines 1-2, page 12). Therefore, in the gauge-corrected product the contribution of ground observations is significant (note that it could happen that the seasonal cycle is inverted between the real-time and the gauge-corrected version). I suggest removing the definition of these datasets as 'fully satellite-based'.

We agree with the reviewer that the TMPA 3B42v7 product is not 'fully' satellite-based and that monthly totals are bias-corrected using gauge data (if gauges are in close proximity). This is in clear contrast with the MSWEP dataset, where gauge-based products (e.g. the CPC-Unified dataset) are not used in a bias-correction step, but directly combined with other datasets using appropriate weights. We note however that the TMPA 3B42v7 product is described in the NASA website as a 'satellite precipitation product'. We have opted therefore to avoid referring to GLEAM v3b and c as 'solely based

on satellite data', and referred to the fact that 'they are driven by satellite-based data only'. We hope the reviewer can agree with this change.

Changes in manuscript

The data set descriptions have been updated and the use of 'solely based on satellite data' or 'fully satellite-based' have been avoided throughout the manuscript. In addition, at P8-L19-21 we clearly acknowledge now that the TMPA dataset is bias-corrected at the monthly scale using gauge data.

3. MODERATE: It would be interesting to show a version 'd' of the v3 dataset in which SMOS observations are assimilated in the product using MSWEP as rainfall input. It would allow to disentangle the impact of rainfall forcing and the assimilated soil moisture product on the final quality of GLEAM datasets.

This is indeed an interesting experiment, which we have already done in the past to confirm our results about the quality of the different input datasets and the performance of the assimilation. Replacing for instance the TMPA 3B42v7 for MSWEP in the v3.0c dataset increases the average open loop correlation (i.e. without data assimilation) of the first layer soil moisture against the in situ measurements from 0.61 to 0.66. This clearly reflects the higher quality of the MSWEP dataset in reference to the TMPA 3B42v7. If SMOS soil moisture observations are assimilated, both soil moisture datasets consistently improve over the CONUS, resulting in a slight increase of the same statistics to 0.62 and 0.67, respectively. These results highlight the high quality of the SMOS soil moisture dataset and the efficiency of the simple Newtonian Nudging algorithm.

Changes in manuscript

Given that the paper is already quite extensive, we believe that including these results would not contribute to increasing the clarity of the manuscript. However, at P11-L24-26 a brief note about the above-mentioned experiments can be found.

4. P5, L2: I missed how snowmelt is computed. Can the authors add some details?

This module of GLEAM is indeed not described in the paper. However, as this component of the model was not modified in reference to the original version, we would like to point readers to the first description of GLEAM in Miralles et al. (2011).

Changes in manuscript

A reference to the latter has been added at P4-L18-19 of the revised manuscript. In addition, at P4-L23-25, readers are pointed to the original papers for more detailed descriptions of the model baseline.

5. P6, L10: The paper by Lievens et al. (2016) is under review. As it is mentioned in the paper several times, and the readers do not have access to it, I believe some additional details should be included in this paper.

The paper by Lievens et al. (2017) has recently been accepted and has been published now.

Changes in manuscript

An updated citation for Lievens et al. (2017) has been added to the revised manuscript.

6. P6, L17-18: This sentence is also repeated below, I suggest removing.

We thank the referee for this comment.

Changes in manuscript

The sentence at P6-L26-27 of the original paper has been removed.

7. P8, L12: I believe it should be specified that for $w > w_c$ $S=1$ and for $w < w_r$ $S=0$. Also for equation (5).

We agree, yet this was already described in the original manuscript (P8-L1-4).

Changes in manuscript

As this is already described in the paper, no changes have been made.

8. P10, L15-22: It is the third time in the paper that the three versions of v_3 are described. Please try to avoid repetitions.

We agree with the reviewer on this point.

Changes in manuscript

The description of the three datasets in the introduction has been removed (P3-L16-24 of the original manuscript).

9. P11, L23-24: Why for a thicker model layer the representativeness of soil moisture measurements is lower? It should be explained.

As the in situ soil moisture measurement is essentially a point measurement, it becomes less representative for the model if the volume to which it is compared gets larger (i.e. if the model layer is thicker). When dealing with a 2D surface, the equivalent would be to think of the spatial representativeness of two different spatial resolutions (a coarse and a fine) and how they compare against a point measurement.

Changes in manuscript

This information has not been added to the manuscript, as we believe this is clear from the context of the statement.

10. P11, L32: Likely, it should be stressed also in the abstract that the quality assessment of root-zone soil moisture products is mostly carried out in CONUS region.

We believe this is already well highlighted in the manuscript (e.g. P11-L26-27, P12-L3-4, P12-L20 etc.). In addition, we did an effort to make the validation as global as possible, and also note that several hundred of soil moisture sites (approximately 500) are located outside the CONUS.

Changes in manuscript

This information has not been added to the abstract of the manuscript.

11. P12, L8-9: Strictly speaking, also the first model layer (10 cm) is thicker than the sensing depth of SMOS and ESA CCI soil moisture products. It should be acknowledged.

This is true and the resulting mismatch should be partly mitigated by the bias removal. However, this is indeed not acknowledged in the paper and has been added to the revised version of the manuscript. We also acknowledge that the penetration depth of these sensors is variable, and can easily exceed 10 cm as well (see e.g.: *'de Jeu, R.A.M and Holmes, T. Derivation of soil moisture sensing depth from microwave satellite sensors, Poster Presentation at the European Geosciences Union General Assembly 2015'*).

Changes in manuscript

It has been acknowledged at P5-L28-29 of the revised version of the manuscript that microwave-based soil moisture datasets are typically only representative of the first few centimetres of the soil.

12. P13, L17: Figure 6 is not described in the text. Remove or add more details.

The results in Figure 6 were referred to at P13-L17-18 of the original paper.

Changes in manuscript

As the conclusions drawn from Figure 6 are analogous to the ones that may be drawn from Figure 5, we have decided not to further elaborate on these results.

13. P13, L34: The possibility to correct for irrigation that is not modelled in GLEAM is highly interesting. However, it is not shown in the paper and, hence, the sentence should be smoothed.

The effects of irrigation on soil moisture should be partly captured by satellite-derived soil moisture datasets. As a result, a temporary increase in observed satellite soil moisture will likely result in an increase of the modelled soil moisture after data assimilation. However, since with the current validation data we are unable to detect this effect, we agree with the referee that this statement should be softened.

Changes in manuscript

We have smoothed this sentence by adding the word 'assumed' at P13-L25-27: 'Nevertheless, our simple Newtonian Nudging data assimilation system is still assumed to correct for random forcing errors, and potential other effects such as irrigation, that are not explicitly modelled in GLEAM.'

14. Figure 3: Specify explicitly which plot refers to tall and short vegetation.

We would like to emphasize that the same stress function for short and tall vegetation is implemented in GLEAM v3. Therefore, the panels in Figure 3 do not necessarily refer to either short or tall vegetation, but rather show the effect of the VOD on the stress (a large range in VOD vs. a small range in VOD).

Changes in manuscript

To make things clearer, the caption of Figure 3 has been slightly updated. In addition, the sentence at P7-L12-14 has been modified to make clear that there is only one stress function (no plural).

RC2 (published online: 14/02/2016):

1. In the introduction, the author's argue that GLEAM is unique in that it is 'primarily driven by microwave remote sensing observations.' So the novelty here really seems to spring from 1) the assimilation of microwave-based soil moisture and 2) the use of microwave-based vegetation optical depth in the canopy stress formulation. If you take away these two aspects, the approach really just collapses down into a basic rain-driven soil water balance approach (which is relatively simple compared to the combined water/energy balance land surface already being run globally in e.g. GLDAS).

We thank the referee for this comment. We would like to emphasize that (a) not only the soil moisture and vegetation optical depth datasets are based on satellite observations, but that the entire dynamic forcing dataset of the GLEAM v3b and c is based on satellite observations, and (b) another important feature of the model is the detailed estimation of interception loss via the modified Gash's analytical model (Miralles et al., 2010), which was (for instance) used to benchmark the MERRA reanalysis and correct its interception estimates in new releases (Reichle et al., 2017). Therefore, we claim that the model can be primarily driven by satellite observations, being in their vast majority of microwave

nature (soil moisture, precipitation, vegetation optical depth); thus available also during cloudy conditions, which is unique for this type of models dedicated to estimate terrestrial evaporation from remotely-sensed data, since other models (such as e.g. Zhang et al., 2010; Fisher et al., 2008; Mu et al., 2007) are forced to rely on reanalysis meteorology due to the requirements of atmospheric humidity and/or wind speed, and on optical greenness data.

In addition, we fully agree with the referee that the approach is simpler than land-surface models such as GLDAS, which provide a more detailed representation of land processes. The added value of GLEAM is that it is specifically designed to estimate terrestrial evaporation and that it has been thoroughly evaluated and validated in regards to its skill to perform this very specific task. Needless to say that the uncertainty in the representation of evaporation in more complex models is actually very large (Jiménez et al., 2011), mostly due to the fact that these models are not specifically developed to estimate the evaporation flux accurately. Nonetheless, it should be noted that it is not our intention to present these features of GLEAM as innovative, as the core of the model was developed in 2011 based on this same rationale. Consequently, we have done an effort to incorporate these points in the revised version of the manuscript (see below).

So it would strengthen the paper if there were more support for the assertion that GLEAM is driven 'primarily' by surface microwave observations. Figure 5 and 6 are clearly an attempt to do this... but the results are not very compelling. The second and third columns of Figure 5 show that the background water balance model is generally superior to the assimilated observations. So naturally, more weight is (generally) placed on the water balance model background. This is ok... but it is really consistent with GLEAM being 'primarily' driven by the microwave surface observations? Instead, it seems more accurate to say that GLEAM is being 'primarily' driven by water balance considerations and these balance considerations are being nudged by 'secondary' considerations derived from microwave DA.

We would first like to stress that the water balance is primarily driven by microwave-based precipitation, and evaporation estimates based on microwave-based precipitation, microwave-based vegetation optical depth and satellite-based (or reanalysis) meteorology. In addition, microwave-based soil moisture is assimilated as stated by the referee. We agree nonetheless that the text should state clearly that GLEAM is mostly 'driven by satellite data', which are 'primarily derived from microwave sensors'. While Figures 5 and 6 mainly show that the impact of the DA on the modelled surface soil moisture strongly depends on the quality of the model open loop soil moisture, the latter is highly impacted by the quality of the precipitation forcing which is largely microwave-based as well.

No comparable results are shown for either root-zone soil moisture or ET... presumably because the impact of microwave DA is even less for these outputs.

The impact of the data assimilation system on the estimated evaporation is indeed limited and not discussed here. For a more detailed discussion about the impact of the data assimilation on evaporation, we would like to point the referee to the study by Martens et al. (2016).

I realize that some of this is just semantics (i.e. what constitutes 'primary' versus 'secondary')... but I do think that the authors should either: 1) present better evidence for the 'primary' role of the microwave observations in GLEAM or 2) be more objective in describing the novelty of their approach... particularly the impact of their novel methodological elements relative to approaches (like a classical soil water balance model) which have been around for quite some time.

We agree, yet we note again that the precipitation is also microwave-based (to the largest extent). In the revised version of the manuscript.

Changes in manuscript

We have tried to clarify the points raised by the reviewer throughout the manuscript: (a) we do not claim anymore that GLEAM is only driven by microwave remote sensing observations, and (b) we have tried to clarify which aspects of the model are novel or not. These changes can be found throughout the manuscript. For instance, at P2-L32-33 we clearly state that the model is designed 'to be driven' by remote sensing observations, which are 'primarily' derived from microwave data (not only). Around the same lines, we also list the two key features of the model, and at P3-L7-14 and P15-L27-29, we clearly list the novel aspects/new algorithms implemented in GLEAM.

2. Some type of statistical significance analysis is needed to assess the noted version-to-version differences. I do not think that 'statistically-significant' differences should be a requirement for publication. Nevertheless, the reader should be given a sense as to how large the stated performance differences are relative to expected levels of sampling noise.

We agree with the reviewer that we need to support the results with statistical significance tests. Therefore, in the revision, we have included tests to verify whether differences in correlations are significant. The discussion of the results throughout Sect. 4: 'Results and Discussion' incorporates the results of these tests. We note, nevertheless, that the two versions are similar on their estimates, and that the rationale for updating the method has been to make it more physically realistic while keeping the simplicity of the algorithm, as well as extending substantially the dataset temporal record based on the adoption of a new range of forcing data.

Changes in manuscript

Statistical significance tests have been performed to analyse the differences in correlation against *in situ* measurements between different datasets and/or experiments. The test used here is described at P11-L8-11. The results of these tests are discussed throughout Sect. 4.

3. Page 1, Line 7... I'd stay away from subjective statements like 'most of these variables can be relatively easily observed at different spatial scales'... it is a stretch to call the remote estimation of rainfall (for example) 'easy'... much safer to say from the remote retrieval of ET is difficult relative to other water balance components.

Changes in manuscript

The reference to the observability of the other hydrological variables has been removed and this sentence has been changed to: 'Unfortunately, the large-scale observation of terrestrial evaporation is hampered by the inability to sense this flux directly from satellites.' (P2-L7-8).

4. Figure 6 does not seem to be references in the manuscript. Also, unclear why case 3c is dropped when moving from Fig. 5 to Fig. 6.

The results in Figure 6 were only briefly referred to at P13-L17-18 of the original paper, since the conclusions were analogous to the ones that may be drawn from Figure 5. Anomaly correlations are not calculated for the GLEAMv3c (and thus not shown) as the period covered by this product is only 5 years (2011–2015). Given that none of the *in situ* stations fully covers this period with measurements (without any data gaps), it is believed that this period is too short to calculate a robust climatology.

Changes in manuscript

As the conclusions drawn from Figure 6 are analogous to the ones that may be drawn from Figure 5, we have decided not to further elaborate on the results related to this figure. Regarding the anomaly correlations, the justification for not including the v3c dataset in this analysis, has been added to the manuscript at P12-L10-12.

GLEAM v3: satellite-based land evaporation and root-zone soil moisture

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Abstract.

The Global Land Evaporation Amsterdam Model (GLEAM) is a set of algorithms dedicated to the estimation of terrestrial evaporation and root-zone soil moisture from satellite data. Ever since its development in 2011, the model has been regularly revised aiming at the optimal incorporation of new satellite-observed geophysical variables, and improving the representation of physical processes. In this study, the next version of this model (v3) is presented. Key changes relative to the previous version include: (1) a revised formulation of the evaporative stress, (2) an optimized drainage algorithm, and (3) a new soil moisture data assimilation system. GLEAM v3 is used to produce three new data sets of terrestrial evaporation and root-zone soil moisture, including a ~~35-year~~ 36-year data set spanning ~~the period 1980–2014~~ 1980–2015, referred to as v3a (~~v3.0a~~, based on satellite-observed soil moisture, vegetation optical depth and snow water ~~equivalent~~ equivalent, reanalysis air temperature and radiation, and a multi-source precipitation product), and two ~~fully~~ fully-satellite-based data sets. The latter ~~two~~ share most of their forcing, except for the vegetation optical depth and soil moisture ~~products~~, which are based on observations from different passive and active C- and L-band microwave sensors (European Space Agency Climate Change Initiative ~~data sets~~, ESA CCI) for the ~~first~~ v3b data set (~~v3.0b, spanning the period~~ spanning 2003–2015) and observations from the Soil Moisture and Ocean Salinity (SMOS) satellite in the ~~second~~ v3c data set (~~v3.0c, spanning the period~~ spanning 2011–2015). ~~These~~ Here, these three data sets are described in detail, compared against analogous data sets generated using the previous version of GLEAM (v2), and validated against measurements from ~~64–91~~ 64–91 eddy-covariance towers and ~~2338–2325~~ 2338–2325 soil moisture sensors across a broad range of ecosystems. Results indicate that the quality of the v3 soil moisture is consistently better than the one from v2: average correlations against in situ surface soil moisture measurements increase from 0.61 to 0.64 in case of the ~~v3.0a~~ v3a data set and the representation of soil moisture in the second layer improves as well, with correlations increasing from 0.47 to 0.53. Similar improvements are observed for the ~~two fully satellite-based~~ tv3b and c data sets. Despite regional differences, the quality of the evaporation fluxes remains overall similar as the one obtained using the previous version of GLEAM, with average correlations against eddy-covariance measurements ranging between 0.78 and ~~0.80 for the three~~ 0.81 for the different data sets. These global

data sets of terrestrial evaporation and root-zone soil moisture are now openly available at www.GLEAM.eu and may be used for large-scale hydrological applications, climate studies and, or research on land–atmosphere feedbacks.

1 Introduction

Climate change alters the complex interplay between land and atmosphere, significantly impacting different processes in the global hydrological cycle (Huntington, 2006; Wild et al., 2008; Miralles et al., 2014b). Analysing these impacts requires long-term, observational and consistent data sets of essential hydrological variables, such as soil moisture, precipitation and terrestrial evaporation (or “*evapotranspiration*”). ~~While most of these variables can be relatively easily observed at different spatial scales~~ Unfortunately, the large-scale observation of terrestrial evaporation is hampered by the inability to sense this flux directly from satellites. Consequently, this crucial return flow of water from land into the atmosphere remains one of the most elusive and uncertain components of the global hydrological cycle (~~Dolman et al., 2014; Miralles et al., 2016b~~) ([Dolman et al., 2014](#); [Miralles et al., 2016a](#)).

However, the climate community is becoming increasingly aware of the crucial role that terrestrial evaporation plays in the Earth system, acting as a link in hydrological and biogeochemical cycles, and being a driver of air humidity, cloud formation, temperature or precipitation (Seneviratne et al., 2010; Taylor et al., 2012; Miralles et al., 2012). Consequently, past decades have seen significant efforts to enhance our understanding of the global magnitude and variability of this flux. Some of these efforts have mainly concentrated on routinely measuring evaporation in the field (~~Wang and Dickinson, 2012~~), ([Wang and Dickinson \(2012\)](#), and references therein), resulting in the increased availability of in situ observations from different climatic regions across the globe (Baldocchi et al., 2001; Jung et al., 2009). In addition, acknowledging the sparseness of current in situ networks and their inability to meet the spatio-temporal requirements for climatological studies, the potential of satellite remote sensing to ~~understand~~ enhance our understanding on terrestrial evaporation dynamics has been intensively explored. While ~~nowadays evaporation still remains in the near future, evaporation will remain~~ undetectable from space, several models that combine remotely-observable drivers of this flux (e.g. radiation, air temperature, soil moisture) have been developed and are being intensively used in recent years (Wang and Dickinson, 2012; McCabe et al., 2016).

Existing algorithms share the overarching objective of producing consistent, long-term, ~~and~~ global data sets of terrestrial evaporation, but the methods and input data sets used in these models ~~markedly differ~~ differ markedly (e.g., Mu et al., 2007; Fisher et al., 2008; Zhang et al., 2010; Miralles et al., 2011; Loew et al., 2015). Recently, McCabe et al. (2016), Michel et al. (2016) and Miralles et al. (2016a) evaluated the relative value of four of these evaporation models using standardized satellite- and in situ based forcing data sets. ~~Results~~ As expected, results highlighted substantial differences in model performance, especially under conditions of water stress. In addition, these studies found pronounced deficiencies in the way evaporation is partitioned into its different components (i.e. transpiration, ~~bare-soil~~ bare soil evaporation, open-water evaporation, interception loss and sublimation). Miralles et al. (2016a) and Fisher et al. (2017) also highlighted the importance to advance the physical representation of evaporation in these simple models, and the need to incorporate new technological advances in remote sensing science.

The Global Land Evaporation Amsterdam Model ~~, GLEAM (Miralles et al., 2011) is the only global evaporation model that is primarily driven by microwave~~ GLEAM (Miralles et al., 2011), is arguably the only one of these global evaporation models that is designed to be driven by remote sensing observations ~~, and that uses satellite soil moisture as a constraint on only~~. These observations are primarily derived from microwave sensors, including soil moisture and vegetation optical depth used ~~in GLEAM to constraint the~~ potential evaporation rates. ~~Additional key features~~ Another key feature of the approach ~~are is~~ the independent and detailed modelling of forest interception loss based on Gash's analytical model (Gash, 1979; Valente et al., 1997; Miralles et al., 2010), ~~and the use of microwave vegetation optical depth (VOD) as a proxy for the vegetation water content (Liu et al., 2013) in the calculation of the evaporative stress (Miralles et al., 2011, 2014b; Martens et al., 2016).~~ Evaporation and root-zone soil moisture data sets from GLEAM have been widely used in the past to study spatial variability and trends in the water cycle (e.g., Jasechko et al., 2013; Greve et al., 2014; Miralles et al., 2014a; Zhang et al., 2016), as well as land-atmosphere feedbacks (e.g., Miralles et al., 2014b; Guillod et al., 2015). The first version (v1) of the model was developed ~~in 2011 (Miralles et al., 2011) by Miralles et al. (2011) and further refined in 2014 (v2; Miralles et al. (2014b))~~ by Miralles et al. (2014b); the present paper presents the third version (v3) of the methodology. In this new version, ~~each of the key components of the methodology has~~ most components of GLEAM have been updated, except for the interception loss algorithm ~~and the potential evaporation module~~. First, aiming at a more realistic representation of evaporative stress, observations of microwave VOD and root-zone soil moisture have been ~~optimally~~ combined to represent the non-linear response of soil and vegetation to the drying of land (e.g., Colello et al., 1998; Serraj et al., 1999; Ronda et al., 2002; Combe et al., 2016). Second, the soil module has been adapted to represent the continuous drainage of precipitation through the vertical profile. Finally, the soil moisture data assimilation system – recently updated and validated for Australia (Martens et al., 2016) – has been optimized to work at the global scale and to integrate different datasets of satellite soil moisture observations. These changes have respected the ~~rationale-minimalistic approach~~ of GLEAM of targeting only the fundamental processes controlling large-scale evaporation rates, while keeping the overall simplicity and observational nature of the model.

~~The new v3 has been used to produce three new data sets of terrestrial evaporation and root-zone soil moisture: v3.0a, v3.0b and v3.0c. The v3.0a data set is a 35-year (spanning the period 1980–2014) global record based on satellite-based soil moisture, VOD and snow water equivalents, reanalysis air temperature and radiation, and a multi-source precipitation product. The v3.0b (spanning the period 2003–2015) and v3.0c (spanning the period 2011–2015) are fully satellite-based, quasi-global (50°N–50°S) data sets, which share most of their forcing database, except for the VOD and soil moisture observations. In case of the v3.0b data set, these are based on a merge of observations from different passive and active C- and L-band microwave sensors (Liu et al., 2011, 2012; Wagner et al., 2012). The v3.0c data set on the other hand relies on observations of the Soil Moisture and Ocean Salinity (SMOS) satellite, the first L-band mission dedicated to the observation of surface soil moisture (Kerr et al., 2001).~~

The main goal of this study is to present the new version of GLEAM and the ~~corresponding~~ resulting evaporation and root-zone soil moisture data sets, including a global validation using a large database of ~~in situ soil moisture~~ soil moisture measurements from 2325 in situ sensors, and evaporation measurements from 91 eddy-covariance towers. In addition, the quality of these data sets is compared against analogous datasets generated using the former version of GLEAM, allowing to

evaluate the added value of the new formulations. The paper is organized as follows: Sect. 2 describes the new algorithms, highlighting the main changes upon the previous version. The forcing data and the in situ validation data are described in Sect. 3. Section 4 analyzes the quality of the GLEAM data sets and discusses the results, while the main conclusions are summarized in Sect. 5.

5 2 Methodology

2.1 Baseline description of GLEAM

GLEAM (see Fig. 1) is a set of algorithms designed to estimate evaporation from satellite observations. It separately derives the different components of terrestrial evaporation, i.e. transpiration, bare-soil bare soil evaporation, open-water evaporation, interception loss and sublimation (Miralles et al., 2011). (Miralles et al. (2011), see Fig. 1). Each grid cell is considered to comprise comprises four different land-cover types: (1) bare soil, (2) low vegetation (e.g. grass), (3) tall vegetation (e.g. trees) and (4) open water. These (e.g. lakes). Except for the fraction of open water, these fractions are sourced from the Global Vegetation Continuous Fields product (MOD44B), based on observations from the Moderate Resolution Image Spectroradiometer (MODIS). For the fraction of open water, the product of Tuanmu and Jetz (2014) is used. The evaporative flux is calculated for each of these fractions separately and then aggregated to the scale of the pixel based on the fractional cover of each land-cover type. First, the Priestley and Taylor (1972) equation is used to calculate the cover-dependent potential evaporation rate E_p (mm/day) based on air temperature and net radiation:

$$\lambda E_p = \alpha \frac{\Delta}{\Delta + \psi} (R_n - G) \quad (1)$$

where λ (MJ kg⁻¹) is the latent heat of vaporization and Δ (kPa K⁻¹) is the slope of the saturated water vapour-temperature curve. Both variables can be estimated using empirical relationships to the air temperature (Henderson-Sellers, 1984; Maidment, 1993). ψ (kPa K⁻¹) is the psychrometric constant, α (dimensionless) is the Priestley and Taylor coefficient, R_n (W m⁻²) is the net radiation and G (W m⁻²) is the ground heat flux. G is calculated as a constant fraction of R_n depending on the cover type (Miralles et al., 2011). For α , a value of 1.26 has been reported by Priestley and Taylor (1972) for well-watered grasslands, and has been used in numerous studies for a variety of ecosystems. However, empirical studies have highlighted the more conservative nature of tree stomata, generally often resulting in lower rates of potential evaporation in forested areas (Shuttleworth and Calder, 1979; Kelliher et al., 1993; Teuling et al., 2010). Therefore, the α for tall vegetation is defined after the findings by McNaughton and Black (1973), Shuttleworth et al. (1984), Viswanadham et al. (1991), Diawara et al. (1991) and Eaton et al. (2001), that report an average value of 0.97 (with a 0.08 standard deviation over the different studies) for forests during various forests during unstressed and precipitation-free periods (i.e. no rainfall interception) and no evaporative stress.

Estimates of E_p are converted into actual evaporation E (mm/day) — i.e. transpiration or bare-soil evaporation transpiration or bare soil evaporation (depending on the land-cover type) —, using a cover-dependent, multiplicative stress factor S (dimensionless) ranging from 1 to 0. S is calculated as a function of microwave VOD and root-zone soil moisture — (see Sect. 2.2.3). The latter

is calculated using a multi-layer water-balance algorithm considering net precipitation (precipitation minus interception loss) and snowmelt as inputs, and evaporation and drainage as outputs (Miralles et al., 2011). The depth of the root zone is a function of the land-cover type and comprises three model layers for the fraction of tall vegetation (0–10, 10–100 and 100–250 cm), two for the fraction of low vegetation (0–10, 10–100 cm), and only one for the fraction of bare soil (0–10 cm). Forest rainfall interception loss is estimated independently using the analytical model introduced by Gash (1979) and further refined by Valente et al. (1997), forced with precipitation and considering both the characteristics of precipitation and vegetation (Miralles et al., 2010). We refer to Miralles et al. (2011), Miralles et al. (2014b), and Martens et al. (2016) for detailed descriptions of the four modules. In the next section, we focus on the changes relative to the previous model version (Miralles et al., 2014b), and we refer to Miralles et al. (2011), Miralles et al. (2014b), and Martens et al. (2016) for more detailed descriptions of the model baseline.

2.2 Recent advances in GLEAM

2.2.1 Soil module

Figure 2 shows a schematic of the conceptual root zone for the fraction of tall vegetation in a pixel. Each soil layer is subdivided in three different compartments. The first zone-compartment (bottom) represents the water retained below wilting-point-the wilting point, w_{wp} ($\text{m}^3 \text{m}^{-3}$), and which is not available for root uptake. For the bare-soil; for the bare soil fraction, the residual soil moisture, w_r ($\text{m}^3 \text{m}^{-3}$), is used instead. The second compartment of the layer is bounded by w_{wp} and the porosity of the soil matrix, w_p ($\text{m}^3 \text{m}^{-3}$), and represents the maximum volume of water available for drainage-and-evaporation. Finally, the third compartment represents the solid phase of the soil column and thus cannot hold any water. The soil properties used in GLEAM come from the database of Global Gridded Surfaces of Selected Soil Characteristics generated by the International Geosphere-Biosphere Programme Data and Information System (IGBP-DIS, Global Soil Data Task Group (2000)).

At every (daily-)daily time step i , the state of any layer l is characterized by its water content $w_i^{(l)}$ ($\text{m}^3 \text{m}^{-3}$), which is updated using:

$$w_i^{(l)} = w_{i-1}^{(l)} + \frac{(F_{s,i}^{(l-1)} + F_{f,i}^{(l-1)} - E_{i-1}^{(l)} - F_{s,i}^{(l)}) \Delta t}{\Delta z^{(l)}} \quad (2)$$

where $w_{i-1}^{(l)}$ is the volumetric soil moisture content of layer l at the previous time step ($i-1$), $F_{s,i}^{(l-1)}$ (mm/day) is the volume of water slowly draining into the layer (slow draining flux), $F_{f,i}^{(l-1)}$ (mm/day) is the volume of water directly reaching the layer (fast draining flux), $E_{i-1}^{(l)}$ (mm/day) is the evaporative flux from the previous day, $F_{s,i}^{(l)}$ (mm/day) is the slow drainage of water out of the reservoir, Δt is the temporal resolution (one day) and $\Delta z^{(l)}$ (mm) is the depth of the soil layer. Note that for the first layer ($l=1$), only $F_{f,i}^0$ is considered as an input, as there is no draining layer on top.

In the previous model versions, the entire volume of net precipitation (i.e. precipitation minus interception loss, plus snowmelt) was first stored in the top layer, which subsequently drained to field capacity into the next soil layer (Miralles et al., 2011). (Miralles et al., 2011) the same process was used to calculate the vertical flow from the remaining layers. As a result, the soil moisture could not ex-

ceed field capacity, nor was drainage allowed to occur below that threshold. In GLEAM v3, net precipitation is first partitioned between the different soil layers based on the relative saturation at the beginning of the daily time step, in order to estimate the fast draining flux $F_{f,i}^{(l)}$. Next, the volume of water that slowly drains to the next layer ($F_{s,i}^{(l)}$) is estimated using a simplified representation of Darcy's law, in which a fraction of the available water above wilting point is drained to the next layer based on (1) the relative saturation of each layer, and (2) the difference in soil moisture content between both layers.

The rationale behind this simple drainage algorithm is that the downward flux of water is expected to increase if (1) the relative soil moisture content is higher (physically resulting in increased hydraulic conductivities), and (2) the difference in soil moisture between source and sink is larger (~~arising~~ resulting in higher differences in soil-water potential). This empirical drainage algorithm is preferred over well-known alternatives such as the Richards equation (Richards, 1931), Brooks-Corey (Brooks and Corey, 1964) or Clapp-Hornberger (Clapp and Hornberger, 1978), due to its simplicity and the fact that it does not require the use of additional largely-unconstrained ancillary data on soil properties at the global scale.

2.2.2 Data assimilation system

The original Kalman filter approach to assimilate microwave soil moisture observations ~~into the first soil layer (Miralles et al., 2011)~~ typically sensitive to the first few centimeters of the soil – into GLEAM was replaced in favour of a simple Newtonian Nudging algorithm (~~Miralles et al., 2014b~~) in the v2 (Miralles et al., 2014b), which was ~~further optimized by Martens et al. (2016)~~ recently further optimized (Martens et al., 2016). This Newtonian Nudging scheme minimizes the computational demands and fits well within the ~~concept~~ rationale of GLEAM of keeping the model as simple and ~~observation-based~~ observation-driven as possible. While more complex algorithms like the ensemble Kalman ~~Filter~~ filter have also been applied in GLEAM, the added value has shown to be marginal (~~Lievens et al., 2017~~) (Miralles et al., 2014b). Therefore, in this new version, we adopt a similar approach to the ~~one implemented by Martens et al. (2016) – in which the soil moisture content of the first layer is updated using a Newtonian Nudging scheme – is adopted~~ implemented by Martens et al. (2016):

$$w_i^{(1)+} = w_i^{(1)-} + K\gamma \left(\hat{w}_i^o - \hat{w}_i^{(1)-} \right) \quad (3)$$

where $w_i^{(1)+}$ is the a posteriori soil moisture state at the first model layer (i.e. after application of the data assimilation algorithm), $w_i^{(1)-}$ is the a priori soil moisture state at the same layer (i.e. before assimilation of the observed soil moisture), K (~~dimensionless~~) is the nudging factor (a value of 1 is used to maximize the impact of the assimilation algorithm as in Martens et al. (2016)), γ (~~dimensionless~~) is the quality factor, and \hat{w}_i^o ($\text{m}^3 \text{ m}^{-3}$) and $\hat{w}_i^{(1)-}$ ($\text{m}^3 \text{ m}^{-3}$) are the observed and modelled soil moisture ~~anomaly~~ anomalies, respectively. The latter ~~two~~ represent deviations relative to the seasonal climatology of soil moisture – calculated ~~similar to as in~~ De Lannoy and Reichle (2016) and Lievens et al. (2017) – as opposed to ~~Martens et al. (2016), in which the~~ absolute values of soil moisture ~~were assimilated~~ assimilated by Martens et al. (2016).

As most assimilation algorithms require bias-free observations in reference to the modelled states, a bias removal algorithm prior to ~~or during~~ (or during) the assimilation step has to be applied. However, no standard procedure exist to correct these constant or seasonally varying biases (Lievens et al., 2015; De Lannoy and Reichle, 2016), thus the choice of the bias-removal

algorithm remains to some degree subjective. As indicated by Martens et al. (2016), the use of a classical CDF-matching approach prior to the assimilation step clearly introduced seasonal biases in the GLEAM soil moisture and evaporative fluxes. As a result, in GLEAM v3, soil moisture anomalies are assimilated instead, as this approach allows the correction of potential seasonal biases between the modelled and observed soil moisture states (De Lannoy and Reichle, 2016). ~~A similar approach to that by De Lannoy and Reichle (2016) and Lievens et al. (2017) is followed to obtain the soil moisture anomalies.~~ As a Triple Collocation Analysis (TCA, Scipal et al. (2008); Miralles et al. (2010); Gruber et al. (2016)) is applied here to obtain the observation and model errors, the anomaly time series of the observations are scaled towards the modelled soil moisture anomalies using a linear regression model prior to the assimilation (Yilmaz and Crow, 2013). We note that for applying a TCA, a third independent data set of the same geophysical variable is required. For this purpose, soil moisture fields from the Noah model in the Global Land Data Assimilation System (GLDAS) (Rodell et al., 2004) are used. The three independent and rescaled anomaly time series of surface soil moisture are used in the TCA to estimate both the model and observation errors on a yearly basis. The latter two are then adopted to calculate the quality factor (γ) as in Martens et al. (2016):

$$\gamma = \frac{\sigma_{\text{mod}}^{(1)}}{\sigma_{\text{mod}}^{(1)} + \sigma_{\text{obs}}} \quad (4)$$

where $\sigma_{\text{mod}}^{(1)}$ ($\text{m}^3 \text{m}^{-3}$) and σ_{obs} ($\text{m}^3 \text{m}^{-3}$) are the standard deviations of the random model and observation errors, respectively. Finally, in contrast to the assimilation of soil moisture observations in all model layers in GLEAM v2 (Miralles et al., 2014b; Martens et al., 2016), only the first model layer is updated in the new version. The latter choice is motivated by the slower dynamics of the deeper model ~~layer, which may be~~ layers, which are strongly perturbed when soil moisture observations are directly assimilated into these layers using ~~this the~~ simple Newtonian Nudging scheme. The impact of the soil moisture update in this GLEAM v3 is thus propagated towards deeper layers by drainage processes only, which ensures a smooth transition of water through the vertical profile.

2.2.3 Stress module

~~The limiting effects of environmental factors such as water availability or~~ Water availability, heat stress, ~~and or~~ phenological constraints acting on evaporation, are generally combined in a single empirical stress factor accounting for the decrease in potential evaporation (Sellers et al., 2007). In GLEAM, a multiplicative stress factor S ranging between 0 (maximum stress and thus no evaporation) and 1 (no stress and thus potential evaporation) is defined.

In the first version (Miralles et al., 2011), S was parameterized separately for the fractions of tall and short vegetation using non-linear relationships between S and the soil moisture of the wettest layer. To account for changes in vegetation phenology of ~~the (more dynamic)~~ short vegetation, the VOD was also used in the calculation of S for this fraction. These functions were linearized in the second version, and the VOD was also introduced for the calculation of the stress for the fraction of tall vegetation ~~(Miralles et al., 2014b; Martens et al., 2016)~~ (Miralles et al., 2014b). However, based on experimental evidence, a non-linear response of S to soil moisture is expected for most vegetation types (e.g., Colello et al., 1998; Serraj et al., 1999;

Ronda et al., 2002; Combe et al., 2016). As a consequence, ~~a non-linear stress functions are re-introduced in GLEAM v3~~
~~function~~ for both tall and short vegetation ~~is re-introduced in GLEAM v3~~:

$$S = \sqrt{\frac{\text{VOD}}{\text{VOD}_{\max}}} \left(1 - \left(\frac{w_c - w^{(w)}}{w_c - w_{\text{wp}}} \right)^2 \right) \quad (5)$$

where VOD_{\max} (~~dimensionless~~) is the maximum VOD for a specific pixel, w_c ($\text{m}^3 \text{m}^{-3}$) is the critical soil moisture and $w^{(w)}$ ($\text{m}^3 \text{m}^{-3}$) is the soil moisture content of the wettest layer, assuming that plants withdraw water from the ~~zone-layer~~ in which it is more easily accessible. As soil moisture decreases, S decreases (i.e. increased evaporative stress), since water becomes less easily available for the roots. As vegetation phenology is not explicitly ~~modelled~~accounted for, the VOD – closely linked to the vegetation water content (Liu et al., 2013) – is used to account for the effect of (seasonal or occasional) phenological constraints on evaporation (e.g. leaf-out, fires, pests etc.), with decreasing VOD resulting in lower values for S and thus higher
 10 evaporative stress. As seen from Eq. 5 and Fig. 3, the stress function is thus defined by both the soil moisture content in the wettest soil layer and the VOD. If $w^{(w)}$ reaches w_{wp} , Eq. 5 implies that the vegetation is incapable to retrieve water from the soil and S equals zero (and so does actual transpiration). On the other hand, for soil moisture values exceeding w_c ~~and the~~
~~VOD reaching its maximum value~~, it is assumed that the ~~water availability is not a limiting factor~~ vegetation is unstressed (i.e. $S=1$ ~~and,~~ thus transpiration equals potential transpiration).

15 Figure 3 illustrates the shape of the stress function in Eq. 5 for a pixel dominated by a strong seasonality in VOD (left-hand side, ~~e.g. a savannah~~) and a site with a limited variability in VOD (right-hand side, ~~e.g. a tropical rain forest~~). For illustrative purposes only, it is assumed that the soil properties (w_c and w_{wp}) are the same for both sites. As can be seen, where the range in VOD is ~~expected to be~~ low given the absence of a marked seasonality, S ~~would mainly depend~~ mainly depends on soil moisture. Conversely, if a large seasonality in the VOD is present (see left-hand side figure), the VOD becomes ~~relatively~~ more
 20 important for the calculation of S .

Finally, for the ~~bare-soil~~ bare soil fraction, S is linearly related to the soil moisture state using the critical and residual soil moisture content as upper and lower boundary conditions, respectively:

$$S = 1 - \frac{w_c - w^{(1)}}{w_c - w_r} \quad (6)$$

Since only the top layer is considered for the fraction of bare soil, S is fully driven by surface soil moisture ($w^{(1)}$).

25 3 Data

3.1 Input data sets

Table 1 gives an overview of the selected forcing data sets ~~for in~~ GLEAM v3. All input data sets have a daily resolution and ~~have~~
~~been are~~ linearly re-sampled from their original spatial resolution (~~see Table 1~~) to a common 0.25° global grid. Given the aim

to extract all valuable information on terrestrial evaporation from existing satellite records, forcing data sets are preferentially derived from satellite observations. However, since a key application of the GLEAM data sets is to analyze the impact of climate change on terrestrial hydrology, we also explore the use of alternative forcing data sets (~~e.g. reanalysis data~~), such as reanalysis data, to yield multi-decadal records of terrestrial evaporation and root-zone soil moisture.

5 Radiation inputs are based on measurements from the Clouds and Earth's Radiant Energy System (CERES) onboard Terra and Aqua (Wielicki, 1996), which are available globally from the year 2001 onwards on a 1° regular grid. Additionally, radiation fluxes from the current reanalysis of the European Centre for Medium-Range Weather Forecasts (ECMWF), ERA-Interim (Dee et al., 2011), are also processed. ERA-Interim data are available globally from 1979 to present, with a temporal resolution of 3 hours and a spatial resolution of approximately 0.75° .

10 For the precipitation forcing, the Tropical Rainfall Measurement Mission (TRMM) Multi-satellite Precipitation Analysis (TMPA) 3B42v7 product (Huffman et al., 2007) and the Multi-Source Weighted-Ensemble Precipitation (MSWEP) data set (Beck et al., 2016) are selected. The TMPA 3B42v7 data set combines measurements from several satellites and is bias corrected on a monthly time scale using ground-based measurements of precipitation. The product is available for the period 1998–2015 and covers 50°N – 50°S based on a 0.25° grid. MSWEP on the other hand is based on a merger of selected satellite-,
15 reanalysis- and gauge-based products, and is available from 1979 until ~~2014~~2015 at a 0.25° spatial resolution.

Air temperatures are derived from measurements of the Atmospheric Infrared Sounder (AIRS, Aumann et al. (2003)), which are available from 2003 onwards on a global 1° regular grid. Air temperature estimates from ERA-Interim are also ~~used in this study~~selected for the long-term GLEAM data set. As for the radiation, data are available globally from 1979 until near present at 3-hourly intervals.

20 To estimate sublimation, observations of snow-water ~~equivalents~~equivalent from the European Space Agency (ESA) GLOB-SNOW product (Luoju et al., 2013) are used. This data set is mainly based on retrievals from the Scanning Multichannel Microwave Radiometer (SMMR), Special Sensor Microwave/Imager (SSM/I), and the Advanced Microwave Scanning Radiometer (AMSR-E), and is available from 1980 onwards. The GLOB-SNOW product only covers the Northern hemisphere and is therefore merged with the National Snow and Ice Data Center (NSIDC) monthly snow-water equivalent climatology
25 product (Armstrong et al., 2005) for the Southern hemisphere. The latter is also based on measurements from SSMR and SSM/I.

As discussed in Sect. 2.2.3, the phenological controls on transpiration are derived from observations of microwave VOD. Here, the 0.25° product from Liu et al. (2011) is used, which is based on retrievals from several passive microwave sensors using the Land Parameter Retrieval Model (LPRM, Owe et al. (2008)). The product is available at the global scale and spans the
30 period 1980–2012.~~In~~in order to cover the period 1980–2015, ~~the product~~it is merged with LPRM-based VOD retrievals from SMOS (van der Schalie et al., 2015, 2016) using a similar CDF-matching approach as ~~in the one used by~~ Liu et al. (2011). The resulting data set contains gaps due to the repeating cycle of the satellites, the requirement of non-frozen conditions for parameter retrieval, and the presence of Radio Frequency Interference (RFI). In order to obtain smooth and continuous time series, the VOD data set is gap-filled using a moving average filter with a 7-day window. Remaining gaps, generally
35 occurring in winter time due to freezing temperatures and snow covers, are linearly interpolated between the last and next

available retrieval. We note however that in periods for which the land is covered by snow, the VOD is not used as the entire evaporation flux is assumed to ~~correspond to~~ be sublimation. Finally, if any gaps remain, these are ~~gap-filled~~ filled using nearest neighbour interpolation. It should be noted here that microwave sensors operating at different frequencies might be sensitive to diverse components of vegetation, varying at different time scales (e.g. Guglielmetti et al., 2007; Liu et al., 2011). Despite
5 the CDF-matching, which corrects for differences in long-term statistics, the use of different microwave sensors might impact the temporal dynamics of the VOD data set used here.

Finally, for the assimilation of microwave ~~soil moisture in GLEAM~~ surface soil moisture, the SMOS Level 3 soil moisture product (Jacquette et al., 2010) and the ESA Climate Change Initiative soil moisture (ESA CCI SM v2.3) data set (Liu et al., 2012; Wagner et al., 2012) ~~have been~~ are selected. The latter is a blended product of soil moisture retrievals from several active
10 and passive microwave sensors, available for the period 1978–2015 at the global scale. In addition, surface soil moisture fields from the Noah model in GLDAS (Rodell et al., 2004) are used as a third independent data set in the TCA (see Sect. 2.2.2). Despite fundamental differences between GLEAM and Noah, some degree of dependency between their soil moisture estimates might be present due to the presence of common precipitation observations embedded within MSWEP, TMPA 3B42 and the forcing of GLDAS Noah. However, the merging schemes used to produce the precipitation data sets are ultimately different
15 (Rodell et al., 2004; Huffman et al., 2007; Beck et al., 2016). Such a dependency ~~may~~ could penalize the satellite-based soil moisture in the TCA (Yilmaz and Crow, 2014), which would result in a lower quality factor γ (see Eq. 4) applied in the data assimilation system and, subsequently, in a more conservative soil moisture update.

As discussed in Sect. 2, GLEAM also requires several static data sets describing the soil properties, land cover and average rainfall climatology. For the land cover fractions, the MODIS Global Vegetation Continuous Fields product (MOD44B) –
20 ~~based on observations from MODIS~~ – is selected (Hansen et al., 2005). The high-resolution product at 250 m is ~~chosen here and is~~ up-scaled to the required grid size of 0.25° (note that in previous model versions, the low resolution 0.25° product produced by the MODIS team was used ~~directly~~). Note that for the fraction of open water, the product produced by Tuanmu and Jetz (2014) is combined with the MODIS-based product. Soil properties such as wilting point, soil porosity, field capacity and critical soil moisture are derived from the database of Global Gridded Surfaces of Selected Soil Characteristics,
25 IGBP-DIS (Global Soil Data Task Group, 2000). Finally, as in Miralles et al. (2010), a monthly rainfall intensity climatology is inferred from the Combined Global Lightning Flash Rate Density monthly product (Mach et al., 2007) produced by the National Aeronautics and Space Administration (NASA) agency.

Using various combinations of the forcing data ~~described in Table 1~~, three different data sets of terrestrial evaporation and root-zone soil moisture are produced using GLEAM v3 (see ~~Table ??~~ also Table 1). The inputs of snow water equivalent, the
30 third independent data set used in the TCA, and the static fields are shared by all data sets ~~and are therefore not listed in Table ??~~. The first GLEAM data set (hereafter referred to as v3.0a v3a) is a ~~35-year~~ 36-year data set (~~1980–2014~~ 1980–2015) covering the entire globe and is based on satellite-observed soil moisture, vegetation optical depth and snow water ~~equivalents~~ equivalent, reanalysis air temperature and radiation, and the MSWEP dataset for precipitation. Given the multi-decadal coverage of this data set, it is intended to foster climatological research. The remaining data sets (~~v3.0b and v3.0c~~) ~~are fully~~ v3b and v3c are
35 driven by satellite-based data only, and span a ~~significantly~~ shorter period. In addition, these data sets only cover 50°N–50°S

due to the use of the ~~satellite-based~~ TMPA 3B42v7 product. The differences between both satellite-based data sets are the VOD and soil moisture forcing, which are retrieved from SMOS only in the ~~v3.0e-v3c~~ data set, and from multiple active and passive microwave sensors in the ~~v3.0b-v3b~~ data set. This also implies a different record length of 13 (2003–2015) and 5 years (2011–2015) for the ~~v3.0b-and-v3.0e-v3b and v3c~~ data sets, respectively.

5 3.2 Validation data sets

For validation purposes, in situ soil moisture and evaporation measurements from different global networks are processed. Soil moisture measurements are sourced from the database of the International Soil Moisture Network (ISMN, Dorigo et al. (2011, 2013)), whereas the FLUXNET 2015 synthesis data set (<http://fluxnet.fluxdata.org/>) is used to obtain the in situ measurements of evaporation (see Table A1 for an overview of the selected sites). ~~Several~~ Note that several studies have already highlighted the lack of closure in the energy balance at eddy-covariance sites and a consequential tendency to underestimate latent heat fluxes (Wilson et al., 2002). ~~Therefore, the corrected measurements of the~~ latent heat flux ~~using the Bowen-ratio are used here~~ (Wilson et al., 2002). All available measurements for 1980–2015 are considered for inclusion in the validation set. Measurements are masked using the quality flags provided in the corresponding data set archives and aggregated from their native temporal resolution (generally 30 minutes or 1 hour) to the required daily scale. For the evaporation data sets, only days with less than 25 % ~~of~~ missing data are processed. ~~Next~~ As in Martens et al. (2016), the resulting daily time series are screened for extreme outliers and repetitive ~~measurements~~ recorded values. Soil moisture measurements are subsequently masked for snow and air temperatures below 0°C using the snow water ~~equivalents~~ equivalent from GLOBSNOW and the ~~ERA-Interim~~ air temperature data ~~set~~ sets, respectively (see Table 1). As eddy-covariance measurements are generally less reliable during precipitation, rainy intervals are masked from the data sets of in situ evaporation. Finally, only sites with at least 365 daily measurements after masking are included in the validation data set. This yields a total of ~~64~~ 91 quality-checked eddy-covariance sites (see Table A1) and a total of ~~2338~~ 2325 soil moisture sensors covering various ecosystems across the globe. Note that the soil moisture sensors are installed at different depths below the soil surface and used to validate both the first (0–10 cm, 1119 sensors) and second ~~model layer~~ (10–100 cm, ~~1219 sensors~~) 1216 sensors ~~model layer~~, depending on the installation depth. Sensors located in the same GLEAM grid cell (horizontally or vertically) are not combined, but treated separately in the validation to avoid problems with potential artifacts resulting from merging sensors with different absolute values and gaps in their ~~records~~ record. For the location of the in situ sites selected in this study, we refer to Figs. 4 and 7 (see ~~further~~ Sect. 4).

4 Results and discussion

4.1 Validation of soil moisture

4.1.1 ~~Inter-product differences in~~ Accuracy of soil moisture ~~accuracy estimates~~

Table 2 summarizes the average correlation (R) and unbiased root mean square difference (ubRMSD) for the v3 soil moisture data sets (~~see also Table ??~~) against the in situ measurements. Validation statistics are calculated using all available in situ mea-

surements within the spatio-temporal domain of each of the data sets, as well as using a common set of soil moisture sites and an overlapping period for the three data sets (i.e. ~~2011–2014~~2011–2015). Statistics for ~~the same analogous~~ data sets obtained using GLEAM v2 (same input data, except for the MODIS land cover fractions) are shown between brackets for comparison. Differences in correlations for the three products are statistically tested for significance using a Student’s t-test (at the 10% level), after applying a Fisher Z transformation on the time series. The autocorrelation of the daily time series was taken into account by reducing the degrees of freedom using an effective sampling size (De Lannoy and Reichle, 2016; Lievens et al., 2017). Note that the first year of each of the data sets is not taken into account for this validation exercise to avoid the effects of ~~the~~ model initialization on ~~the~~-validation statistics.

As indicated by the statistics in Table 2, all data sets compare reasonably well against the in situ measured soil moisture, with correlations for the first model layer ($w^{(1)}$) of 0.64, 0.61 and 0.63 for the ~~v3.0a, v3.0b and v3.0e~~v3a, v3b and v3c data sets, respectively. For the second model layer ($w^{(2)}$), correlations are lower (ranging from 0.49 to 0.53~~for the satellite-based and long-term data set, respectively~~), which can be expected given the lower representativeness of a single in situ measurement over the thicker model layer (10–100 cm). The ubRMSD yields mean values of approximately $0.06 \text{ m}^3 \text{ m}^{-3}$ and $0.05 \text{ m}^3 \text{ m}^{-3}$ for the first and second model layer, respectively.

~~The Overall, the~~ validation statistics shown in Table 2 point to a higher quality of the ~~v3.0a-v3a~~ soil moisture data set ~~as compared to the fully satellite-based data sets (i.e. v3.0b and v3.0e)~~compared to v3b and v3c. This is also confirmed by the statistics obtained for the common validation ~~set, which makes an objective comparison of the quality possible. It is shown that period:~~ for both model layers and in terms of correlations, the ~~v3.0a-v3a~~ soil moisture is ~~superior to the fully satellite-based data sets, with correlation coefficients for $w^{(1)}$ being significantly higher in approximately 20 % of the sites (the opposite is true in 2 % of the sites only).~~ Due to the high autocorrelation in the second layer soil moisture – strongly reducing the degrees of freedom in the statistical test – correlations for the v3a dataset are only higher at approximately 3 % of the individual sites. Permutations of the precipitation forcing amongst the different data sets indicate that the higher quality of the soil moisture in ~~v3.0a-v3a~~ is primarily due to the precipitation forcing used in each data set (not shown), and suggests an overall high accuracy of the MSWEP ~~forcing data~~ as indicated by Beck et al. (2016). We note, however, that more than 75 % of the soil moisture probes are located in the CONUS (Continental United States), where gauge-based precipitation data sets are known to overperform satellite-based products (Beck et al., 2016). ~~Recall that the TMPA 3B42v7 product is only bias-corrected using gauges; while MSWEP incorporates gauge measurements~~These findings should thus not be extrapolated to other regions. Finally, the difference in quality between ~~both satellite-based data sets (v3.0b and v3.0e)~~v3b and v3c is relatively small, with slightly better statistics for the ~~v3.0e-v3c~~ data set, which integrates SMOS data.

For comparison, Table 2 also reports the validation statistics for the same data sets obtained using GLEAM v2. Both the ubRMSD and the correlations suggest that the v3 soil moisture data sets have a higher quality. ~~This is more pronounced for the second model layer, mainly as a result of both the improved drainage formulation and the optimized data assimilation algorithm. In contrast to the assimilation of soil moisture observations in all model layers in the previous version (Miralles et al., 2014b; Martens et al., only the first model layer is updated in the new version. The latter choice is motivated by the slower dynamics of the thick (90-cm) second model layer:~~ at 26 %, 19 % and 12 % of the in situ soil moisture sites, the correlations significantly improve

in case of the v3a, which are strongly perturbed when soil moisture observations are assimilated into this layer. The impact of v3b and v3c datasets, respectively (statistically significant deterioration only occurs in a small number of sites). Although for the second layer significant improvements of R only occur in around 8 % of the individual sites and for all three data sets, overall differences in R are more pronounced for this layer, mainly as a result of both the improved drainage formulation and the soil moisture update is thus propagated towards deeper layers by drainage processes only, which ensures a smooth and natural transition of water through the profile.

optimized data assimilation algorithm. Figure 4 shows maps of the difference in R against in situ measured surface soil moisture for the v3 and v2 data sets. Since most in situ sites are located in the CONUS domain, also a detailed view of the results over this area is presented. As illustrated in these maps, the quality of the soil moisture data sets improves in most regions and for the majority of sites (blue colour). It could be argued that in the Great Plains, the performance of GLEAM v3 is lower than for v2, yet only a limited number of sites are available in this area.

To

Finally, to better evaluate the skill of GLEAM v3 to capture the effect of specific precipitation events on the estimated soil moisture – without the influence of the seasonal cycle – correlations between the anomaly time series of GLEAM soil moisture and the anomaly time series of in situ measured soil moisture are also calculated (R_{an} in Table 3). Note that to calculate a robust climatology, only in situ sites with at least 5 years of data were used, resulting in a lower subset of stations (see Table 3) and no anomaly-based evaluation for the v3c dataset. As expected, correlations decay after the removal of the seasonal cycle, but remain in the range of 0.48–0.53–.54 for the first layer and 0.41–0.43–0.47–.49 for the second layer. In addition, results shown in Table 3 confirm the higher-high accuracy of the v3.0a–v3a soil moisture as compared to the fully-satellite-based v3.0b data set–v3b data set (significantly better correlations are obtained in 55 % of the individual sites), and the higher performance of GLEAM v3 over the previous version (v2), with the number of significantly better correlations being similar as for the regular correlations.

4.1.2 Impact of the data assimilation system

The left-hand side panel in Fig. 5 shows the differences in the correlations against the in situ measurements when data assimilation of satellite soil moisture is included in GLEAM v3 versus when it is not (i.e. model open loop). As more than 75% of soil moisture validation sites are located in the CONUS, only the results for this region are shown here. For the v3.0a–v3a data set, the assimilation of the CCI soil moisture has a rather neutral to negative impact on the modelled soil moisture states of the first model layer. Generally, correlations are decreasing (red colour) after assimilation in very dry (e.g. West Coast of the CONUS) and forested regions (e.g. East Coast of the CONUS). This decrease is statistically significant in about 10 % of the in situ soil moisture sites, while a neutral effect is obtained at the majority of the sites (89 %). In regions of limited topography and dominated by sparse vegetation (e.g. Great Plains), the quality of the modelled soil moisture is slightly improving (blue colour). For the v3.0b–and–v3.0e–v3b and v3c datasets, the assimilation of satellite-derived soil moisture (ESA CCI v2.3 in v3.0b–v3b and SMOS L3 in v3.0e–v3c) has – in general – a more pronounced and positive impact (blue colour) on the modelled

soil moisture, especially in ~~sparsely-vegetated areas~~ areas such as the Great Plains. The latter can be expected given the higher quality of microwave soil moisture retrievals in regions with low vegetation cover (Dorigo et al., 2015).

The negative impact of assimilating satellite observations of surface soil moisture in the ~~v3.0a-v3a~~ data set is partly explained by the ~~relatively low-high~~ quality of the ~~satellite-soil moisture~~ GLEAM open-loop soil moisture compared to the quality of the
5 satellite-based soil moisture data set (ESA CCI SM v2.3) ~~compared to the GLEAM open-loop soil moisture, which is of high~~
~~quality-; correlations are significantly better for the open loop in 73 % of the individual sites. The high quality of the model~~
open loop in these regions is largely due to the accuracy of the MSWEP precipitation forcing in the CONUS domain. ~~This-;~~
this is illustrated in the central panel in Fig. 5, where difference maps between the correlations against in situ measurements of
10 the satellite soil moisture observations and the three open-loop data sets are shown. ~~The~~ A clearly higher quality of the model
open-loop soil moisture in terms of correlations is highlighted for ~~some regions-; including regions such as~~ the East and West
coasts of the CONUS (red colour) ~~;-;~~ and similar patterns are obtained for the ubRMSD (not shown). In those regions, the
assimilation of satellite soil moisture may decrease ~~the model performance~~ model performance, especially in case of the v3a,
where differences are more pronounced (see correspondence to left panel in Fig. 5). ~~For the v3.0b and v3.0e~~ For the v3b and
v3c data sets, the difference in ~~correlations quality~~ between satellite soil moisture and open loop is less pronounced and lower
15 (the model open loop is significantly better in 55 % and 25 % of the in situ sites for the v3b and v3c datasets, respectively).
Moreover, the difference in correlations becomes even positive in regions with low vegetation (see central panels in Fig. 5),
pointing to the higher quality of the satellite-based soil moisture observations as compared to the model estimates in those
areas (e.g. ~~Central part of the CONUS~~ the Great Plains). These maps point again to the above-mentioned lower quality of the
~~v3.0b and v3.0e v3b and v3c~~ precipitation forcing in those regions (TMPA 3B42v7 ~~as opposed compared to~~ MSWEP). The
20 subtle differences between the validation results for the ~~v3.0b and v3.0e v3b and v3c~~ data sets relate to the different quality
of the CCI and SMOS soil moisture observations, respectively. ~~However, caution should be taken given-;~~ bearing in mind the
different study period and number of in situ stations used in ~~these figures~~ their validation. Analogous results for anomaly time
series are summarised in Fig. 6 and point to the same conclusions as drawn from Fig. 5.

Finally, it may be argued that differences in quality between the satellite-derived and modelled soil moisture should reflect
25 in the TCA-based quality factor (γ) used in the data assimilation algorithm (see Sect. 2.2.2). As outlined in Sect. 2.2.2, the
quality factor used in the Newtonian Nudging algorithm is estimated on a yearly basis by applying a TCA on the soil moisture
anomalies of three independent data sets. Based on Eq. 4 it can be seen that values of γ below (above) 0.5 point to a lower
(higher) model error relative to the observation error. The multi-year average quality factor for each of the three data sets is
shown in the right-hand side panel in Fig. 5. Spatial patterns in these maps agree well with the ones observed in the central maps,
30 reflecting the ability of the TCA to capture the relative errors of modelled and observed surface soil moisture. Nonetheless,
despite the overall low quality factors for the ~~v3.0a-v3a~~ data set (i.e. γ rarely exceeds 0.3) – which reflects the higher error of
the observed soil moisture relative to the model open loop – a decrease in quality is often observed when this soil moisture data
set is assimilated into GLEAM ~~v3.0a~~ (see discussion above v3a (see above discussion)). As expected, the quality factors for the
~~v3.0b and v3.0e v3b and v3c~~ data sets are higher and exceed 0.5 in some low-vegetated regions, indicating again the higher

quality of the satellite-based soil moisture observations as compared to the model open loop in these areas(see discussion above).-

Therefore, the inability of the assimilation algorithm to consistently improve the v3.0a soil moisture in regions such as the East and West coasts of the CONUS is mainly explained by the substantially higher quality of the model open loop. Nevertheless, our simple Newtonian Nudging data assimilation system ~~will still be assumed to~~ correct for random forcing errors and other, and other potential effects such as irrigation, that are not explicitly modelled in GLEAM. Moreover, the Newtonian Nudging scheme minimizes the computational costs and, as shown by Miralles et al. (2014b) and Lievens et al. (2017), the use of more complex Kalman filters does not significantly improve the model performance.

4.2 Validation of evaporation

4.2.1 Inter-product differences in Accuracy of evaporation accuracy estimates

Table 4 lists the validation statistics for the different evaporation data sets. In contrast to the results of the soil moisture validation exercise (see Table 2 Tables 2 and 3), differences between the three data sets are less pronounced when diagnosing the quality of their evaporation estimates. For the overlapping period 2011–2014 2011–2015 and the common sample of sites, an average correlation of approximately 0.78 , and a similar ubRMSD of approximately 0.730.71 mm day⁻¹ is obtained for all three data sets.

In addition, differences are only significant at the 10% significance level in two in situ stations. Analogous statistical inferences for the validation of GLEAM v2 are shown between brackets and differ only slightly from the ones calculated for the data sets obtained using the new model version. At the majority of sites, no statistical significant difference in R is obtained. Figure 7 shows maps of the differences in correlation against the in situ measurements for the v3 and v2 data sets. It can be seen from the maps for the v3.0a and v3.0b data sets that GLEAM v2 performs generally better along the Eastern part of the CONUS, which may be attributed to a lower performance of the stress functions implemented in the new v3, since the v3 soil moisture is consistently improved in this region (see Fig. 4). However, given the low number of in situ sites, no clear conclusions on geographical patterns can be drawn until the foreseen extension of the FLUXNET 2015 synthesis database (-). Over Continental Australia, GLEAM v3 performs generally better, except for the v3.0e–v3c data set, where for some sites a deterioration of the results is shown when compared to the corresponding v2c. However, as the validation database for the latter data set contains a significantly lower number of measurements, due to the shorter time period, it may be less representative of the overall quality of the data set. Also, note that the results obtained for the three data sets do not necessarily agree at each in situ site, suggesting an impact of the validation period. Correlations for the anomaly time series are listed in Table 5 and confirm the above conclusions.

As an example, Fig. 8 shows time series of GLEAM and in situ measured evaporation for two validation sites, i.e. US-Ne3 (Central part of the CONUS Great Plains, see Table A1) at the left-hand side and AU-ASM (Central-central Australia, see Table A1) at the right-hand side. While for the first site the performance of GLEAM v3 tends to be lower, statistics are improving for the second site with respect to the previous version of the model. However Overall, time series show an

overall a good correspondence between model and in situ measurements. For US-Ne3, correlations drop from 0.82 (~~v2.0a~~v2a) and 0.83 (~~v2.0b~~v2b) to 0.78 (~~v3.0a~~v3a) and 0.77 (~~v3.0b~~v3b); on the other hand, for the SMOS-based data sets (~~v2.0e~~ and ~~v3.0e~~v2c and v3c), correlations increase from 0.73 to 0.76. Analogous differences are obtained in terms of ubRMSD. Despite the apparent decrease in quality for the v3 data sets, the time series shown in Fig. 8 for US-Ne3 illustrate that the estimates of evaporation are realistic and have no systematic errors. For AU-ASM, correlations consistently improve for all three data sets from 0.84 (~~v2.0a~~v2a), 0.84 (~~v2.0b~~v2b) and 0.78 (~~v2.0e~~v2c) to 0.88 (~~v3.0a~~v3a), 0.88 (~~v3.0b~~v3b) and 0.84 (~~v3.0e~~v3c), and similar improvements are obtained for the ubRMSD. Time series at the right-hand side of Fig. 8 show that the better results are mainly explained by the improved estimates of the evaporative flux during the dry season. For these periods, GLEAM v3 estimates lower volumes of evaporation, resulting in a closer agreement with the in situ measurements; although most of these differences are not statistically significant. This is mainly related to the new drainage formulation, which allows a faster dry-out during precipitation-free periods, leading to an increase in the evaporative stress. Additionally, the new drainage algorithm also yields less extreme evaporation peaks after precipitation events, since the faster drainage implies that the soil profile requires stronger precipitation events to saturate. Results for ~~the Australian site~~ AU-ASM indicate that these evaporation patterns are realistic under conditions of water stress, yet caution may be taken when extrapolating these findings to other climatic and ecological regimes.

4.2.2 Global magnitude and variability of terrestrial evaporation

The top row in Fig. 9 presents the mean annual evaporation from the ~~v3.0a data set~~ v3a (left) and a difference map with ~~the v2.0a data set~~ v2a (right). Analogous results are obtained for the ~~v3.0b and v3.0e~~ v3b and v3c data sets, but are ~~not shown here~~ excluded for simplicity. As expected, the general climatic patterns of evaporation ~~are captured well by both data sets~~. ~~Compared to the numbers and patterns reported in Miralles et al. (2016a) appear realistic, and are comparable to those reported by Miralles et al. (2016a) and McCabe et al. (2016), based on five a range models and different forcing data, the maps shown in Fig. 9 appear realistic.~~ Differences in the annual totals between ~~v3.0a and v2.0a~~ v3a and v2a amount to 100 mm y^{-1} in several regions, with overall less evaporation in areas covered by short vegetation and more evaporation in ~~desert-like deserts~~ and tropical regions ~~for the new version~~. The total continental evaporation (excluding inland water bodies) amounts to $66 \cdot 10^3 \text{ km}^3$ (~~v3.0a~~v3a) versus the $68 \cdot 10^3 \text{ km}^3$ from the previous version (~~v2.0a~~v2a); these numbers agree well with previously reported values from a range of independent sources (~~← see Miralles et al. (2016a) and references therein~~).

The remaining maps in Fig. 9 show the partitioning of GLEAM evaporation ~~in~~ into its different components: ~~;~~ i.e. forest interception loss, transpiration and ~~bare-soil~~ bare soil evaporation. Note that for illustrative purposes only and to ease comparison to previous literature (Miralles et al., 2016a), the estimated sublimation is added to the ~~bare-soil~~ bare soil flux and the evaporation from inland waters (open-water evaporation) is not considered here. Averaged over the entire land surface, approximately 74% of the total flux of water from land into the atmosphere is coming from transpiration, 15% comes from ~~bare-soil~~ bare soil evaporation and about 11% is the result of interception loss; for the ~~v2.0a~~ v2a data set, 80%, 8% and 12% are obtained, respectively. These discrepancies are also evidenced in the difference maps shown in the right-hand side panel in Fig. 9. It can be seen that almost across the entire globe the ~~bare-soil~~ bare soil evaporation is higher in the ~~v3.0a~~ v3a data set; only for some

drier regions such as the Namibian desert, central Australia and parts of Chile, the ~~bare-soil-bare soil~~ evaporation is decreased. In contrast, transpiration typically increases in these areas. As shown, the total flux of interception loss is generally lower in the new version, except for some parts of Amazonia, Eastern China and ~~the~~-CONUS where a clear increase may be observed. All these differences are the result of the modified stress functions, but – more importantly – of the new (high-resolution) land cover fractions used in GLEAM v3 which report an overall larger ~~portion-fraction~~ of bare soils over the continents(~~see Seet.—3).~~. The higher contribution of ~~bare-soil-bare soil~~ evaporation and the lower volumes of transpiration, especially in semi-arid regions like the Sahel, result in closer agreement with the partitioning obtained from other data sets ~~; especially in semi-arid regions like the Sahel~~ (Wang et al., 2014; Schlesinger and Jasechko, 2014; Miralles et al., 2016a; Good et al., 2015). ~~However~~(Wang et al., 2014; Schlesinger and Jasechko, 2014; Miralles et al., 2016a; Good et al., 2015). Nonetheless, Miralles et al. (2016a) recently raised awareness about the use of satellite-based evaporation algorithms to assess the contribution from different evaporation components, and suggested to avoid the use of any single model in isolation due to the large differences found in inter-model comparisons.

5 Conclusions

The available ~~stack-of-satellite-derived-geophysical-variables-related~~ range of satellite-observable geophysical variables that ~~relate~~ to the process of evaporation – such as soil moisture, air temperature and net radiation – is continuously growing and the quality of these datasets is constantly improving. As a result, models aiming at the accurate estimation of terrestrial evaporation from satellite observations need to be updated to optimally incorporate these new data. Concurrently, as our knowledge of the relevant physical processes advances based on new experimental evidence, these simple retrieval models ~~can-should aim to~~ increase their realism. With the overarching goal of improving our understanding of continental evaporation, a next version of the Global Land Evaporation Amsterdam Model (GLEAM v3) – a set of algorithms dedicated to the estimation of global terrestrial evaporation from satellite data – is presented in this paper.

Three major modifications are included~~in this new version~~: (1) a revised representation of the evaporative stress, (2) an optimized water-balance module, and (3) a new soil moisture data assimilation strategy. Using GLEAM v3~~and different forcing data sets~~, three novel data sets of root-zone soil moisture and terrestrial evaporation are presented. The first data set (~~v3.0a~~v3a) spans the ~~35-year period 1980–2014~~36-year period 1980–2015, has a global coverage, and is produced using satellite-observed soil moisture, vegetation optical depth and snow water ~~equivalents~~equivalent, reanalysis air temperature and radiation, and a multi-source precipitation product. The remaining two data sets (~~v3.0b and v3.0c~~) ~~are based on satellite forcing exclusively, with the only difference~~ v3b and v3c are produced using satellite-based forcing only, with their difference being the use of SMOS-based VOD and soil moisture ~~in the v3.0c data set~~(v3c), as opposed to the ~~use of the~~ corresponding CCI forcing ~~in the v3.0b data set. Both satellite-based~~(v3b). Both data sets are quasi-global (50°N–50°S) and span ~~a significantly shorter period~~ (2003–2015 for v3.0b-v3b, and 2011–2015 for v3.0c-v3c).

Results based on the validation of these three data sets against an extensive set of in situ measured evaporation and soil moisture point to a slightly higher quality of the ~~v3.0a-v3a~~ soil moisture data set as compared to the other two data sets, while

the quality of the modelled evaporation is rather similar across all three. The higher accuracy of the ~~v3.0a-v3a~~ soil moisture is explained by the high quality of the MSWEP precipitation forcing over the regions where soil moisture probes are located, compared to the satellite-based forcing in the ~~v3.0b and v3.0c-v3b and v3c~~ data sets. Results, however, might be biased given that the vast majority (i.e. more than 75%) of the in situ soil moisture sites are located in the CONUS, where gauge-based precipitation products are ~~known to perform better (Beck et al., 2016).~~

~~The known to outperform satellite products (Beck et al., 2016).~~ Finally, the quality of the new v3 data sets is also compared to analogous data sets obtained using GLEAM v2. ~~It is shown that for~~ For the soil moisture, the modifications in GLEAM result in a consistent improvement ~~of soil moisture~~ across the vertical profile. These improvements mainly relate to the optimized drainage algorithm and the new data assimilation system, which allow a more realistic representation of the downward flux of water through the soil profile. On the other hand, the increased quality of the evaporation data is not ~~clear from revealed unambiguously by~~ the in situ validation, likely hampered by the low availability of validation sites. It is illustrated that, on average, the performance of GLEAM v3 is comparable to that of the former version.

~~On top of the modifications in the algorithms, the static data set describing the land cover fractions per pixel is also updated. The effect of this change is investigated through the analysis of the~~ The partitioning of terrestrial evaporation into its different components ~~, which shows an increase in bare-soil bare soil~~ bare soil evaporation almost in every continental region, while interception loss generally decreases. ~~An increase in transpiration can be observed,~~ and transpiration increases for some dry regions such as the Namibian desert and Central Australia. These results are related to the static data set describing the land cover fractions per pixel, which is also updated in GLEAM v3.

Based on the results in this study, it can be concluded that the modifications in GLEAM have led to a more realistic representation of physical processes and an overall increased quality of the data sets, particullary in the case of the root-zone soil moisture. Following the advances in satellite technology and the increased availability of ~~these new~~ data, GLEAM will be further optimized in coming years. ~~Future activities may Current activities~~ concentrate on the incorporation of ~~novel data sets (e.g. high-resolution microwave VOD and surface soil moisture, solar-induced fluorescence, land-surface temperature); new constraints on evaporation,~~ the application of GLEAM to higher resolutions and ~~in~~ near-real time, and the improved partitioning of evaporation into its different components. Meanwhile, ~~all the novel the~~ data sets of ~~observation-based~~ terrestrial evaporation and root-zone soil moisture presented in this study ~~are now have been made~~ available for studies of hydrological cycle dynamics and climate model benchmarking using www.GLEAM.eu as gateway.

6 Code and data availability

The model code of GLEAM v3 is available upon request from the corresponding author. Datasets described in this paper can be freely accessed ~~using from~~ www.GLEAM.eu as gateway.

Appendix A: *In situ* eddy-covariance sites

Table A1. List of the FLUXNET sites used in this study together with their [FLUXNET code \(ID\)](#), IGBP land cover [\(LC\)](#) and official reference (or principal investigator (PI)).

ID	LC	Reference/PI	ID	LC	Reference/PI	ID	LC	Reference/PI
AT-Neu	GRA	George Wohlfahrt	CN-HaM	GRA	Kato et al. (2006)	US-ARM	CRO	Fischer et al. (2007)
AU-ASM	ENF	Cleverly (2011)	CN-Qia	ENF	Huimin Wang	US-ARb	GRA	Margaret Torn
AU-Cpr	SAV	Calperum Tech (2013)	CZ-BK1	ENF	Marian Pavelka	US-ARc	GRA	Margaret Torn
AU-DaP	GRA	Beringer (2013a)	CZ-BK2	GRA	Marian Pavelka	US-Blo	ENF	Goldstein et al. (2000)
AU-DaS	SAV	Beringer (2013c)	CZ-wet	WET	Marian Pavelka	US-Cop	GRA	David Bowling
AU-Dry	SAV	Beringer (2013b)	DE-Geb	CRO	Antje Moffat	US-GLE	ENF	Arain and Restrepo-Coupe (2005)
AU-Emr	GRA	Schroder (2014)	DE-Gri	GRA	Christian Bernhofer	US-Goo	GRA	Tilden Meyers
AU-GWW	SAV	Macfarlane (2013)	DE-Hai	DBF	Knohl et al. (2003)	US-Ha1	DBF	Goulden et al. (1996)
AU-RDF	WSA	Beringer (2014b)	DE-Kli	CRO	Christian Bernhofer	US-Ivo	WET	McEwing et al. (2015)
AU-Rig	GRA	Beringer (2014a)	DE-Lkb	ENF	Rainer Steinbrecher	US-LWW	GRA	Twine et al. (2000)
AU-Stp	GRA	Jason Beringer	DE-Lnf	DBF	Alexander Knohl	US-MMS	DBF	Schmid et al. (2000)
AU-TTE	OSH	Jason Beringer	DE-Obe	ENF	Christian Bernhofer	US-Me2	ENF	Campbell and Law (2005)
AU-Ync	GRA	Beringer (2013d)	DE-RuR	GRA	Borchard et al. (2015)	US-Me3	ENF	Bond-Lamberty et al. (2004)
BE-Bra	MF	Ivan Janssens	DE-Seh	CRO	Karl Schneider	US-Me5	ENF	Irvine et al. (2004)
BE-Lon	CRO	Moureaux et al. (2006)	DE-Tha	ENF	Christian Bernhofer	US-Me6	ENF	Ruehr et al. (2012)
BE-Vie	MF	Aubinet et al. (2001)	FI-Hyy	ENF	Timo Vesala	US-NR1	ENF	Arain and Restrepo-Coupe (2005)
BR-Sa3	EBF	Steininger (2004)	FI-Sod	ENF	Tuomas Laurila	US-Ne1	CRO	Simbahan et al. (2006)
CA-Gro	MF	McCaughey et al. (2006)	FR-Fon	DBF	Bazot et al. (2013)	US-Ne2	CRO	Amos et al. (2005)
CA-NS7	OSH	Bond-Lamberty et al. (2004)	FR-Gri	CRO	Pierre Cellier	US-Ne3	CRO	Verma et al. (2005)
CA-Obs	ENF	Bond-Lamberty et al. (2004)	IT-Col	DBF	Giorgio Matteucci	US-Oho	DBF	Noormets et al. (2008)
CH-Cha	GRA	Shijie Han	IT-La2	ENF	Alessandro Cescatti	US-PFa	MF	Richardson et al. (2006)
CH-Dav	ENF	Lukas Hoertnagl	IT-Lav	ENF	Damiano Gianelle	US-SRC	OSH	Shirley Kurc
CH-Fru	GRA	Zeeman et al. (2010)	IT-MBo	GRA	Damiano Gianelle	US-SRG	GRA	Biederman et al. (2016)
CH-Oe1	GRA	Christof Ammann	IT-PT1	DBF	Günther Seufert	US-SRM	WSA	Scott et al. (2009)
CH-Oe2	CRO	Christof Ammann	IT-Ren	ENF	Stefano Minerbi	US-Ton	WSA	Chen et al. (2007)
CN-Cha	MF	Shijie Han	IT-Tor	GRA	Galvagno et al. (2013)	US-Var	GRA	Ma et al. (2007)
CN-Cng	GRA	Gang Dong	RU-Fyo	ENF	Milyukova et al. (2002)	US-WCr	DBF	Cook et al. (2004)
CN-Dan	GRA	Shi Peili	SD-Dem	SAV	Ardö et al. (2008)	US-Whs	OSH	Scott (2010)
CN-Din	EBF	Guoyi Zhou	US-AR1	GRA	David Billesbach	US-Wkg	GRA	Scott et al. (2010)
CN-Du2	GRA	Chen Shiping	US-AR2	GRA	David Billesbach	ZA-Kru	SAV	Bob Scholes
CN-Ha2	WET	Yingnian Li						

Author contributions. All authors have been involved in interpreting the results, discussing the findings, and editing the manuscript. B.M., H.L., D.G.M. and N.E.C.V. designed the modifications in GLEAM v3. B.M., R.v.d.S., H.E.B and W.A.D. processed the forcing and validation data. B.M. did the analyses. B.M. and D.G.M. designed the lay-out of the paper and wrote the draft of the manuscript.

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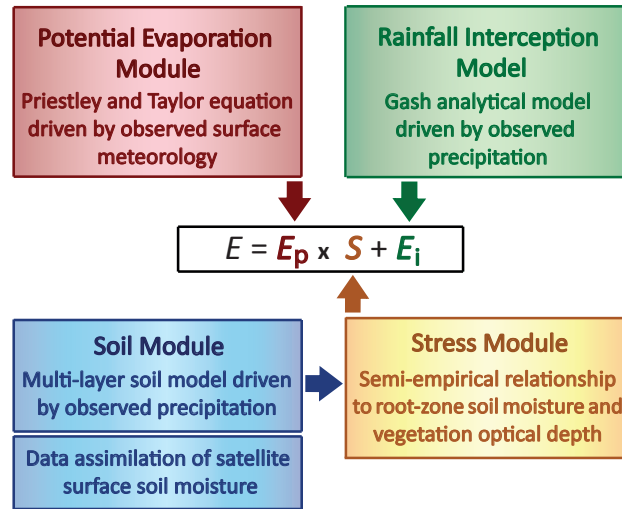


Figure 1. Schematic of the four modules of GLEAM.

Table 1. List of the selected forcing data sets together with their references, the original spatial resolution and period of availability. [The first column indicates the use of these data in GLEAM.](#)

<u>Data set</u>	<u>Variable</u>	<u>Data set</u>	<u>Type</u>	<u>Resolution</u>	<u>Period</u>
Radiation Components v3b,c	Radiation	CERES L3SYN1DEG	Satellite	1°	2001–2015
v3a		ERA-Interim	Reanalysis	0.75°	1979–2015
v3b,c	Precipitation	TMPA 3B42v7	Merge	0.25°	1998–2015
v3a		MSWEP v1.0	Merge	0.25°	1979–2014 1979–2015
v3b,c	Air Temperature	AIRS L3RetStdv6.0	Satellite	1°	2003–2015
v3a		ERA-Interim	Reanalysis	0.75°	1979–2015
Snow Water Equivalent v3a,b,c	Snow Water Equivalent	GLOBSNOW L3av2 + NSIDC v0.1 NSIDC v0.1	Satellite	0.25°	1980–2015
v3c	VOD	SMOS-LPRM	Satellite	25 km	2011–2015
v3a,b		CCI-LPRM	Satellite	0.25°	1980–2012
v3c	Soil Moisture	SMOS L3	Satellite	25 km	2010–2015
v3a,b		ESA CCI SM v2.3	Satellite	0.25°	1978–2015
v3a,b,c		GLDAS Noah	Reanalysis	1°	1980–2015
v3a,b,c	Cover Fractions	MOD44B v51	Satellite	250 m	static
v3a,b,c	Soil Properties	IGBP-DIS	Survey	0.25°	static
v3a,b,c	Lightning Frequency	LIS/OTD	Satellite	5 km	static

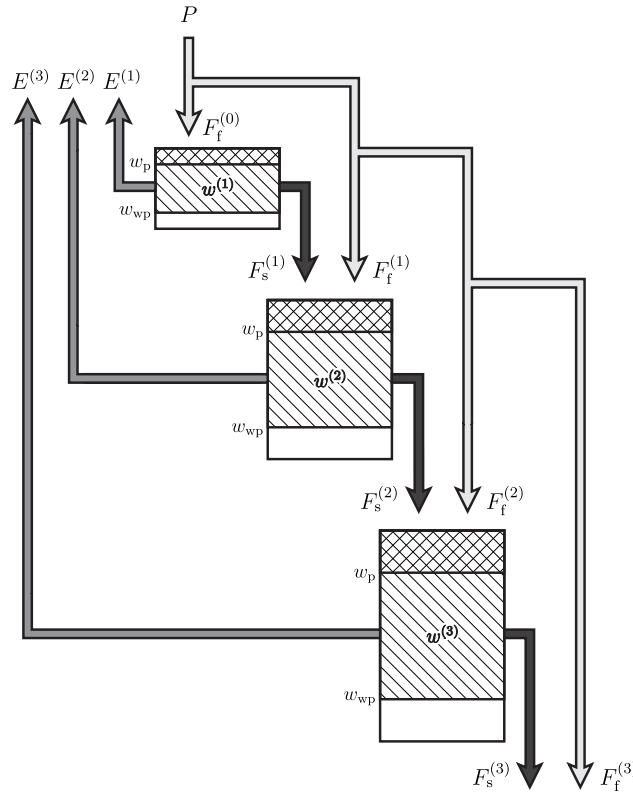


Figure 2. Schematic of the water-balance module implemented in GLEAM v3 for the fraction of tall vegetation. $w^{(l)}$ ($\text{m}^3 \text{m}^{-3}$) is the volumetric soil moisture content of layer l , $F_s^{(l)}$ (mm/day) is the slow draining volume of water, $F_f^{(l)}$ (mm/day) is the fast draining volume of water, $E^{(l)}$ (mm/day) is the evaporative flux, P (mm/day) is the net precipitation, w_{wp} ($\text{m}^3 \text{m}^{-3}$) is the wilting point and w_p ($\text{m}^3 \text{m}^{-3}$) is the porosity.

Overview of the forcing data used to produce the three GLEAM data sets of terrestrial evaporation and root-zone soil moisture: **Data set Coverage Period Radiation Precipitation Air Temperature VOD Soil Moisture** v3.0a-Global-1980-2014 ERA-Interim-MSWEP ERA-Interim-CCI/SMOS-LPRM ESA-CCI-SM v3.0b-50°N-50°S-2003-2015 AIRS-TMPA AIRS-CCI/SMOS-LPRM ESA-CCI-SM v3.0c-50°N-50°S-2011-2015 AIRS-TMPA AIRS-SMOS-LPRM-SMOS-L3-

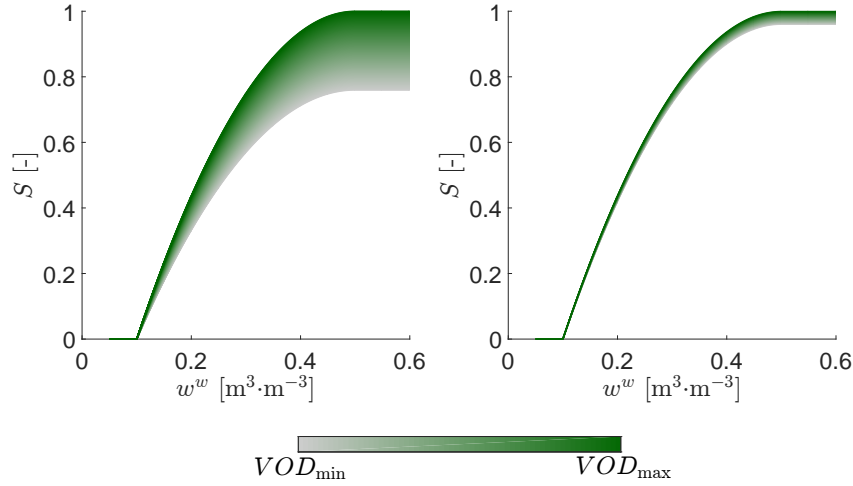


Figure 3. Illustration of the stress function implemented in GLEAM v3 for the fractions of ~~short~~ and ~~tall~~ vegetation (colours relate to the VOD). Left-hand side: ~~pixel with~~ high range in VOD ($VOD_{\max} = 0.47$, $VOD_{\min} = 0.27$); right-hand side: ~~low-pixel with small~~ range in VOD ($VOD_{\max} = 0.40$, $VOD_{\min} = 0.38$). For illustrative purposes only, the wilting point and the critical soil moisture for both figures were set to 0.1 and $0.5 \text{ m}^3 \text{ m}^{-3}$, respectively.

Table 2. Average validation statistics for the different soil moisture data sets (~~v3.0a-v3a~~, ~~v3.0b-v3b~~ and ~~v3.0e-v3c~~) and for the first two model layers ($w^{(1)}$ and $w^{(2)}$) against in situ measurements: ubRMSD is the unbiased root mean square difference, R is the correlation and N is the number of sites included in the sample. The first part of the table reports the averaged statistics over all available sites and the entire study period (see also Table ??), while the second part shows the same statistics for a common sample of sites, and an overlapping study period (~~2011–2014~~~~2011–2015~~) for the three data sets. The same statistics for the data sets produced using GLEAM v2 are reported between brackets.

Data set	Layer	Complete record			Overlap period		
		N	ubRMSD	R	N	ubRMSD	R
		[–]	$[\text{m}^3 \text{ m}^{-3}]$	[–]	[–]	$[\text{m}^3 \text{ m}^{-3}]$	[–]
v3.0a-v3a	$w^{(1)}$	1119	0.059 (0.060)	0.64 (0.61)	782-777	0.059-0.057 (0.062)	0.65-(0.61)0.67 (0.62)
	$w^{(2)}$	1219-1216	0.048 (0.051)	0.53 (0.47)	748-746	0.048 (0.054)	0.51 (0.430.44)
v3.0b-v3b	$w^{(1)}$	1038	0.061 (0.0620.063)	0.61 (0.58)	782-777	0.061-0.060 (0.063)	0.61-0.62 (0.58)
	$w^{(2)}$	1127-1129	0.049 (0.052)	0.49 (0.42)	748-746	0.049 (0.054)	0.48-(0.41)0.49 (0.42)
v3.0e-v3c	$w^{(1)}$	784-785	0.059 (0.063)	0.63 (0.58)	782-777	0.059-(0.063)0.060 (0.062)	0.63 (0.580.59)
	$w^{(2)}$	754	0.048 (0.052)	0.49 (0.42)	748-746	0.048-(0.053)0.049 (0.052)	0.49 (0.420.44)

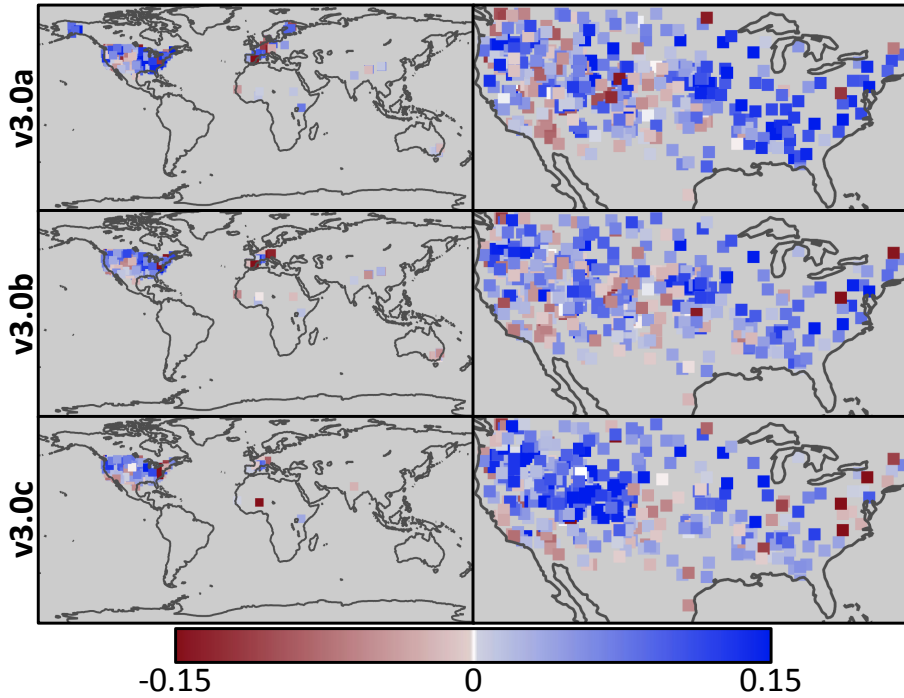


Figure 4. Difference in quality between the v3 and v2 data sets of surface soil moisture ($R(\text{GLEAM v3, in situ}) - R(\text{GLEAM v2, in situ})$). Colours relate to the difference in correlations against in situ measurements for the v3 and v2 surface soil moisture data sets. Statistics are calculated based on all available sites reporting measurements falling within the spatio-temporal domain of the different data sets. Maps at the right show a detailed overview of the results for the CONUS.

Table 3. Average anomaly correlations for different soil moisture data sets (~~v3.0a~~-v3a and ~~v3.0b~~-v3b) and for the first two model layers ($w^{(1)}$ and $w^{(2)}$) against in situ measurements: R_{an} is the anomaly correlation and N is the number of sites included in the sample. The first part of the table reports the averaged statistics over all available sites and the entire study period(~~see also Table ??~~), while the second part shows the same statistics for a common sample of sites, and an overlapping study period (~~2004–2014~~2004–2015) for the two data sets. The same statistics for the data sets produced using GLEAM v2 are reported between brackets.

Data set	Layer	Complete record		Overlap period	
		N	R_{an}	N	R_{an}
		[–]	[–]	[–]	[–]
v3.0a - <u>v3a</u>	$w^{(1)}$	515	0.53 (0.50 <u>0.54</u> (<u>0.52</u>))	455	0.54 (0.52 <u>0.55</u> (<u>0.53</u>))
	$w^{(2)}$	714	0.47 (0.42 <u>0.49</u> (<u>0.45</u>))	622	0.46 (0.43 <u>0.48</u> (<u>0.45</u>))
v3.0b - <u>v3b</u>	$w^{(1)}$	455	0.48 (0.47)	455	0.48 (0.47 <u>0.48</u>)
	$w^{(2)}$	623	0.41 (0.39 <u>0.43</u> (<u>0.40</u>))	622	0.41 (0.39 <u>0.42</u> (<u>0.40</u>))

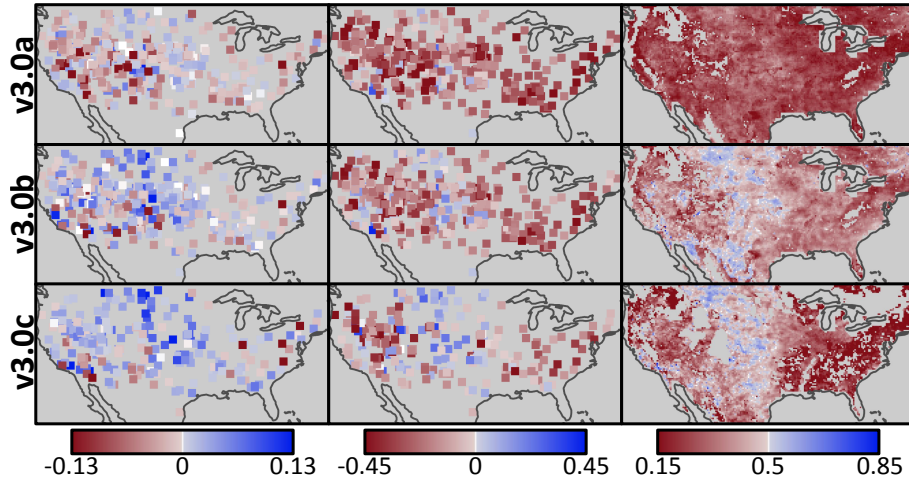


Figure 5. Impact of the data assimilation system in GLEAM v3 on the surface soil moisture for the CONUS. Left-hand side figures show the difference in correlations against in situ measurements for the GLEAM v3 surface soil moisture data sets with and without (open loop) the assimilation of satellite-derived soil moisture ($R(\text{DA}, \text{in situ}) - R(\text{OL}, \text{in situ})$). Maps in the central panel show the difference in correlations against in situ measurements for the satellite-derived soil moisture data sets and the v3 soil moisture data sets without data assimilation ($R(\text{SAT}, \text{in situ}) - R(\text{OL}, \text{in situ})$). Maps at the right show the quality factor γ calculated in the data assimilation system. The latter balances both the model and observation errors, with values above (below) 0.5 indicating a lower (higher) error in the observations relative to GLEAM.

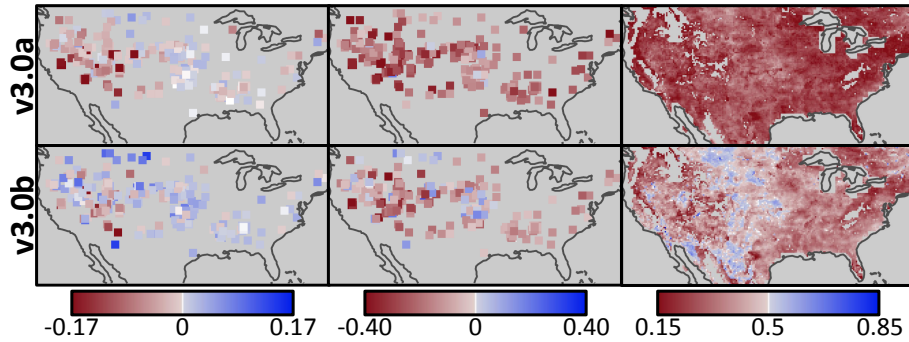


Figure 6. Impact of the data assimilation system in GLEAM v3 on the surface soil moisture for the CONUS. Left-hand side figures show the difference in anomaly correlations against in situ measurements for the GLEAM v3 surface soil moisture data sets with and without (open loop) the assimilation of satellite-derived soil moisture ($R_{\text{an}}(\text{DA}, \text{in situ}) - R_{\text{an}}(\text{OL}, \text{in situ})$). Maps in the central panel show the difference in anomaly correlations against in situ measurements for the satellite-derived soil moisture data sets and the GLEAM v3 soil moisture data sets without data assimilation ($R_{\text{an}}(\text{SAT}, \text{in situ}) - R_{\text{an}}(\text{OL}, \text{in situ})$). Maps at the right show the quality factor γ calculated in the data assimilation system. The latter balances both the model and observations errors, with values above (below) 0.5 indicating a lower (higher) error in the observations relative to GLEAM.

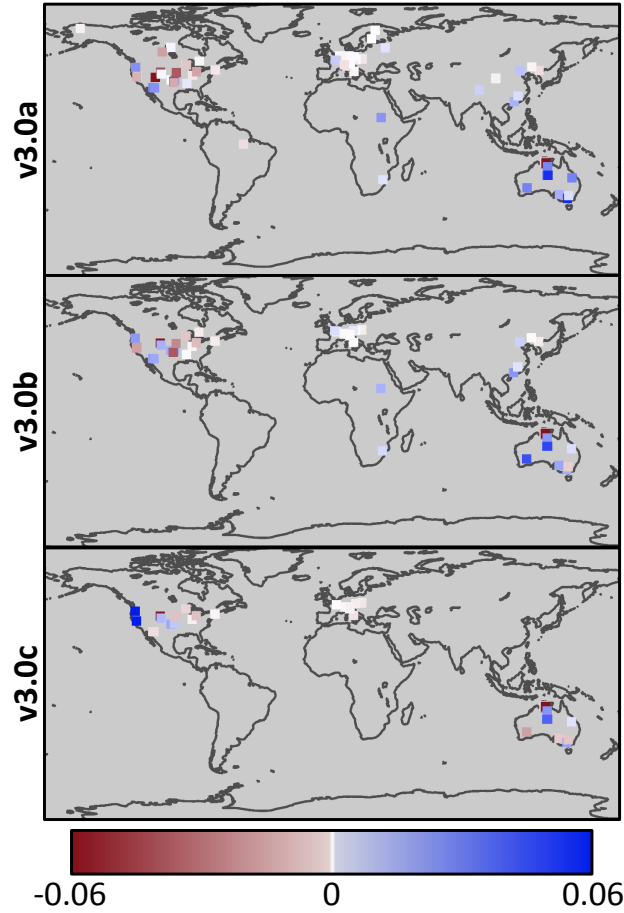


Figure 7. Difference in quality between the v3 and v2 data sets of terrestrial evaporation ($R(\text{GLEAM v3, in situ}) - R(\text{GLEAM v2, in situ})$). Colours relate to the difference in correlations against in situ measurements for the v3 and v2 evaporation data sets. Statistics are calculated based on all available sites reporting measurements falling within the spatio-temporal domain of the different data sets.

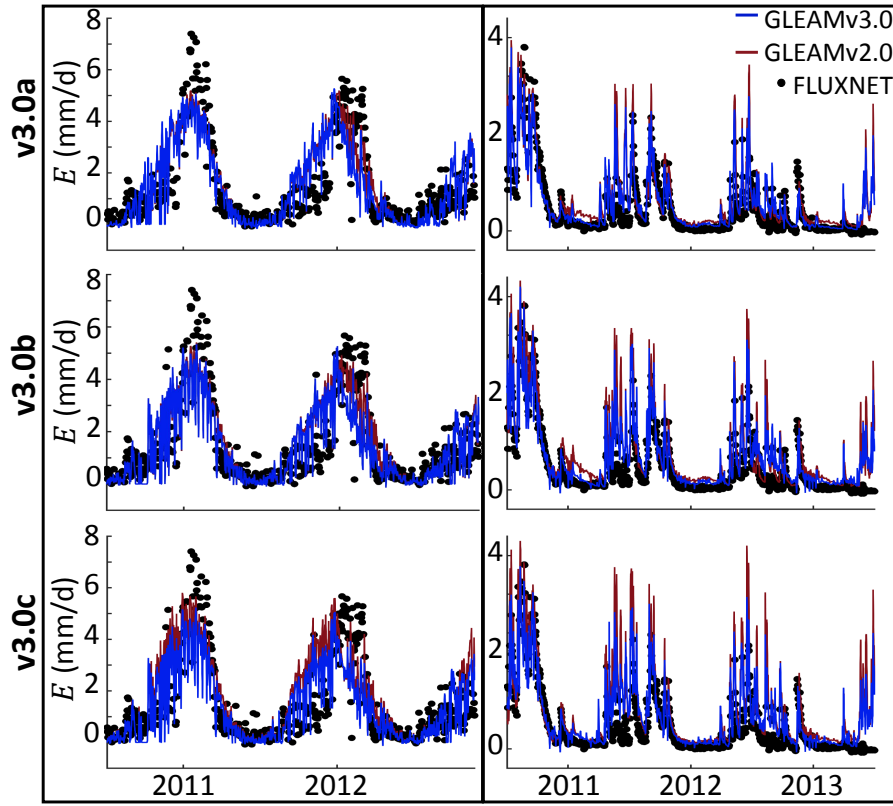


Figure 8. Time series of GLEAM and in situ measured evaporation for two in situ validation sites: US-Ne3 (left) and AU-ASM (right).

Table 4. Average validation statistics for the different evaporation data sets (~~v3.0a~~v3a, ~~v3.0b~~v3b and ~~v3.0e~~v3c) against in situ measurements: ubRMSD is the unbiased root mean square difference, R is the correlation and N is the number of sites included in the sample. The first part of the table reports the averaged statistics over all available sites and the entire study period(see also Table ??), while the second part shows the same statistics for a common sample of sites, and an overlapping study period (~~2011–2014~~2011–2015) for the three data sets. The same statistics for the data sets produced using GLEAM v2 are reported between brackets.

Data set	Complete record			Overlap period		
	N	ubRMSD	R	N	ubRMSD	R
	[–]	[mm day ^{−1}]	[–]	[–]	[mm day ^{−1}]	[–]
v3.0a v3a	65 91	0.73 (0.79 0.72 (0.73))	0.79 (0.80 0.81 (0.81))	29 41	0.72 (0.72 0.71 (0.71))	0.78 0.79 (0.78)
v3.0b v3b	46 63	0.77 (0.77 0.75 (0.76))	0.80 (0.79 0.80)	29 41	0.74 (0.74 0.71 (0.72))	0.78 (0.78)
v3.0e v3c	30 44	0.74 (0.79 0.75)	0.78 (0.78)	29 41	0.73 (0.78 0.71 (0.73))	0.78 (0.78)

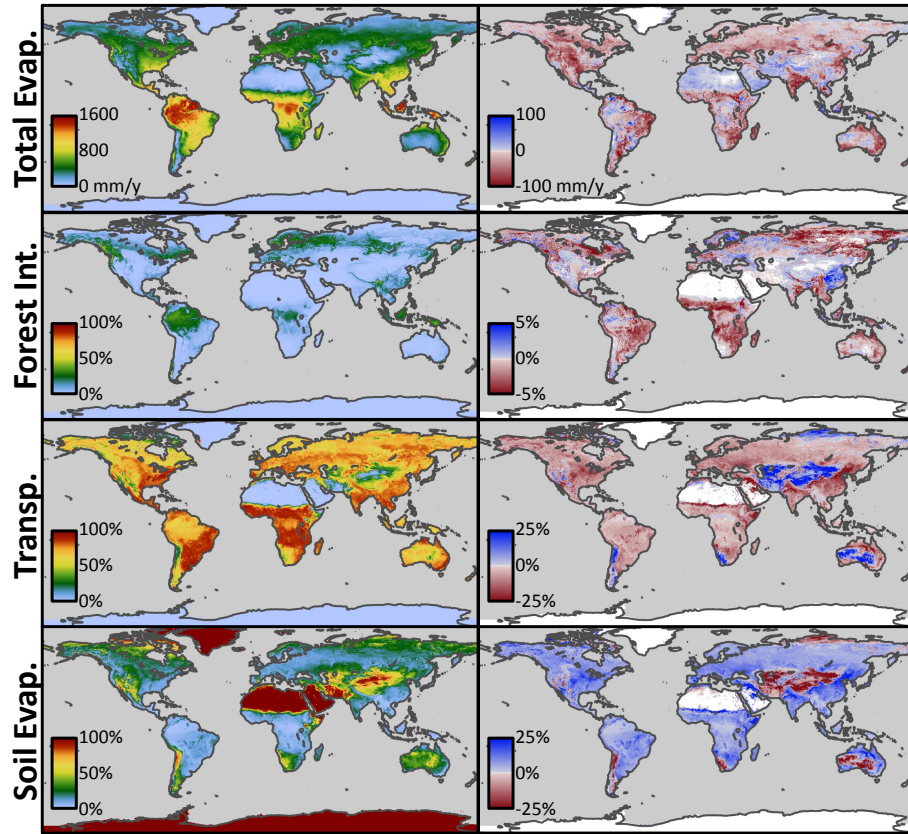


Figure 9. Global maps of terrestrial evaporation (top row) and the partitioning in its different components, i.e. forest interception loss (second row), transpiration (third row) and ~~bare-soil~~ bare soil evaporation (bottom row) for the ~~v3.0a~~ v3a data set. On top, the multi-annual total flux of evaporation for the ~~v3.0a~~ v3a data set (left) and the difference with the ~~v2.0a~~ v2a data set (right) are shown. The other maps show the percentage of the total flux in the ~~v3.0a~~ v3a data set coming from the different components (left) and the difference with the same maps for the ~~v2.0a~~ v2a data set (right).

Table 5. Average anomaly correlations for different evaporation data sets (~~v3.0a~~-v3a and ~~v3.0b~~v3b) against in situ measurements: R_{an} is the anomaly correlation and N is the number of sites included in the sample. The first part of the table reports the averaged statistics over all available sites and the entire study period(~~see also Table ??~~), while the second part shows the same statistics for a common sample of sites, and an overlapping study period (~~2004–2014~~2004–2015) for the two data sets. The same statistics for the data sets produced using GLEAM v2 are reported between brackets.

Data set	Complete record		Overlap period	
	N	R_{an}	N	R_{an}
	[–]	[–]	[–]	[–]
v3.0a -v3a	34 <u>53</u>	0.40 (0.39) <u>0.42 (0.41)</u>	24 <u>34</u>	0.42 (0.42) <u>0.41 (0.40)</u>
v3.0b -v3b	24 <u>35</u>	0.48 (0.49) <u>0.46 (0.45)</u>	24 <u>34</u>	0.48 (0.49) <u>0.43 (0.43)</u>