

1 GMD 2016-16

2 Reply to editor:

3
4
5 1) Abstract, line 3 -- replace "produces synthetic radiance data from any global
6 meteorological model output" with "produces a 'simulated radiance' product from any
7 high resolution general circulation model with interactive aerosol".

8
9 We have made the suggested change. Thank you very much.

10
11 2) Abstract, page 19 lines 15-16 -- replace "thus potentially improving model skill" with
12 "allowing to assess model skill consistently with the retrieval algorithm".

13
14 We have made the suggested change. Thank you very much.

15
16 3) Abstract, page 19 lines 17-19 (up to "be controlled.") These two sentences need
17 to be moved up to be the final 2 sentences of the previous paragraph.

18
19 We have made the suggested change. Thank you very much.

20
21 4) Abstract, page 19 line 19 -- with item 3) the sentence currently beginning "The aerosol
22 properties used in MCARS are directly ingested..." will begin this paragraph -- that's better
23 to re-organise the text this way because I think this sentence should be re-worded to
24 instead begin like a new para as "In this paper, we illustrate the operation of MCARS by
25 deriving simulated radiances from the MERRA re-analysis of the Goddard Earth Observing
26 system 5 (GEOS-5)". Then replace the existing text starting the next sentence from "They
27 are prepared using the..." with "The model aerosol fields are translated into simulated
28 radiances using the ..."

29
30 We are not using the MERRA re-analysis, but rather the direct GEOS-5 v5.9.1 model
31 analysis. Otherwise we have made the suggested clarifications. Thank you very much.

32
33 5) Abstract page 19 line 25 -- insert the word "model" between "computed" and
34 "radiances" so that is now says "MCARS computed model radiances".

35
36 In the implementation we are using MCARS is calculating MODIS radiances, they are
37 modeled sensor radiances, if that makes sense. We have inserted a clarification to that
38 effect. Thank you very much.

39
40 6) Abstract page 20 lines 4-5 -- The sentence beginning "Any operational algorithm..."
41 seems strangely worded -- avoid the phrase "can be executed transparently" -- it's not
42 obvious what you mean -- replace instead with "can be implemented equivalently" -- I think
43 that's rather what you mean.. Similarly the phrase "without being explicitly aware of the
44 specific input source" also seems inappropriately worded -- suggest to instead finish this
45 sentence as ", the module being coded flexibly to enable other approaches to be potentially
46 added in future". Or something like this.

47
48 We changed the text in question to read as follows.

1 ...The resulting MCARS output can be directly provided to MODAPS (MODIS Adaptive
2 Processing System) as input to various operational atmospheric retrieval algorithms.
3 Thus the operational algorithms can be tested directly without needing to make any
4 software changes to accommodate an alternative input source.....

5
6 Hopefully this text better describes the “operationally transparent” bit.

7
8 7) Introduction, page 22, line 6 -- the two references here should be reversed with the
9 Ackermann et al., 2008 put first (papers should be in chronological order) -- and move full-
10 stop to be after the citations.

11
12 We made the suggested change. Thank you very much.

13
14 8) Introduction, page 22, line 11 -- replace "could" with "can".

15
16 We made the suggested change. Thank you very much.

17
18 9) Introduction, page 23, lines 12-13 -- replace "includes outputs of clouds and aerosols
19 above a surface" with "simulates clouds and aerosols interactively" and replace "with
20 simulations" with "with the simulated radiance product derived from the model" or
21 similar.

22
23 We made the suggested change. Thank you very much.

24
25 10) Introduction, page 24, line 1 -- delete the sentence "In sections that follow we will
26 describe the improved MCARS system" -- that text is not needed and the rest of the para is
27 fine on its own as is.

28
29 We made the suggested change. Thank you very much.

30
31 11) Introduction, page 24, line 23 -- delete the text ", and, where applicable, chemistry" and
32 re-word slightly so that part of the sentence instead just reads "treats the sources and sinks
33 of dust, sulfate, sea salt and black and organic carbon aerosols". The author rightly
34 identified that there was no dust chemistry included in this model so it is not appropriate
35 to refer to that here.

36
37 We made the suggested change. Thank you very much.

38
39 12) Page 25, line 7 -- give reference for this database of volcanic SO2 emissions -- is this the
40 Diehl et al. (2012) ACPD, see below?

41
42 It is indeed. Thank you very much. We have included an additional reference.

43
44 13) Page 25, lines 22-24 -- This sentence is incorrect I think. As far as
45 I am aware, the aerosol re-analysis only assimilates MODIS aerosol
46 optical depth measurements. The MISR and AERONET measurements
47 in that Buchard et al. (2015) are used as independent
48 observations against which to assess the aerosol re-analysis.

1 Please re-word as "The aerosol re-analysis is produced at three-hour
2 intervals, with assimilation of bias-corrected aerosol optical depth
3 from MODIS, and has been evaluated against ground-base sun
4 photometer measurements (Holben et al., 1998)
5 and against the Multi-angle Imaging Spectroradiometer (MISR)
6 satellite instrument (give appropriate reference here -- I'd
7 suggest Kahn et al., JGR, 2007, see below).

8
9 We have made the suggested change and added the reference. Thank you very much.

10
11 14) page 45 -- correct "J. Q. R. Meteorol. Soc." to "Q. J. R. Meteorol. Soc."

12
13 We have made the suggested change. We also updated the status of that reference as it
14 has now been accepted. Thank you very much.

15
16

1

2 **Multi-sensor cloud and aerosol retrieval simulator and**
3 **remote sensing from model parameters – Part 2: Aerosols**

4

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13

1 **Abstract**

2 The Multi-sensor Cloud Retrieval Simulator (MCRS) produces a 'simulated radiance'
3 product from any high resolution general circulation model with interactive aerosol as if a
4 specific sensor such as the Moderate Resolution Imaging Spectroradiometer (MODIS) were
5 viewing a combination of the atmospheric column and land/ocean surface at a specific
6 location. Previously the MCRS code only included contributions from atmosphere and clouds
7 in its radiance calculations and did not incorporate properties of aerosols. In this paper we
8 added a new aerosol properties module to the MCRS code that allows user to insert a mixture
9 of up to 15 different aerosol species in any of 36 vertical layers.

10 This new MCRS code is now known as MCARS (Multi-sensor Cloud and Aerosol
11 Retrieval Simulator). Inclusion of an aerosol module into MCARS not only allows for
12 extensive, tightly controlled testing of various aspects of satellite operational cloud and
13 aerosol properties retrieval algorithms; but also provides a platform for comparing cloud and
14 aerosol models against satellite measurements. This kind of two-way platform can improve
15 the efficacy of model parameterizations of measured satellite radiances, allowing to assess
16 model skill consistently with the retrieval algorithm. The MCARS code provides dynamic
17 controls for appearance of cloud and aerosol layers. Thereby detailed quantitative studies of
18 the impacts of various atmospheric components can be controlled.

19 In this paper we illustrate the operation of MCARS by deriving simulated radiances from
20 various data fields output by the Goddard Earth Observing System version 5 (GEOS-5)
21 model. The model aerosol fields are prepared for translation to simulated radiance using the
22 same model subgrid variability parameterizations as are used for cloud and atmospheric
23 properties profiles, namely the Independent Column Approximation (ICA) technique. After
24 MCARS computes modeled sensor radiances equivalent to their observed counterparts, these
25 radiances are presented as input to operational remote sensing algorithms.

1 Specifically, the MCARS computed radiances are input into the processing chain used to
2 produce the MODIS Data Collection 6 aerosol product (M{O/Y}D04). The M{O/Y}D04
3 product is of course normally produced from M{O/Y}D021KM MODIS Level-1B radiance
4 product directly acquired by the MODIS instrument. MCARS matches the format and
5 metadata of a M{O/Y}D021KM product. The resulting MCARS output can be directly
6 provided to MODAPS (MODIS Adaptive Processing System) as input to various operational
7 atmospheric retrieval algorithms. Thus the operational algorithms can be tested directly
8 without needing to make any software changes to accommodate an alternative input source.

9 We show direct application of this synthetic product in analysis of the performance of the
10 MOD04 operational algorithm. We use biomass burning case studies over Amazonia
11 employed in a recent Working Group on Numerical Experimentation (WGNE) -sponsored
12 study of aerosol impacts on Numerical Weather Prediction (Freitas et al. 2016). We
13 demonstrate that a known low bias in retrieved MODIS aerosol optical depth appears to be
14 due to a disconnect between actual column relative humidity and the value assumed by the
15 MODIS aerosol product.

16

17

1 **1 Introduction**

2 Aerosols in the atmospheric column are a significant source of uncertainty for passive
3 remote-sensing (e.g. from a satellite) retrievals of cloud optical and microphysical properties.
4 Thick aerosol layers can be wrongly identified as clouds, and aerosols above clouds will lead
5 to biases in cloud retrievals (Meyer et al. 2013). Biases in cloud detection and retrievals of
6 cloud microphysics will lead to uncertainties in properties important for quantifying Earth's
7 radiative budget. On the other hand, clouds wrongly identified and retrieved as aerosol may
8 have similar impacts on estimates of aerosol radiative forcing and effects on climate and
9 clouds. The Moderate-resolution Imaging Spectroradiometer (MODIS; Barnes et al. 1998) has
10 been flying on the polar orbiting (at 705 km altitude) satellites known as Terra (since 2000)
11 and Aqua (since 2002). Viewing a 2300 km swath, split into 5-minute granules, MODIS
12 measures radiance (or reflectance) in 36 spectral channels, of which 19 are in reflective solar
13 bands, with the other 17 being terrestrial infrared emission. All bands are in at least 1 km
14 spatial resolution. Based on MODIS observations, separate teams have created high-quality
15 retrievals of both cloud (e.g. the M{O/Y}D06_L2 (MxD06); Platnick et al, 2003) and aerosol
16 (M{O/Y}D04_L2 (MxD04; Levy et al., 2013) properties. Current operational cloud retrieval
17 includes methods for clearing the aerosols mis-identified as clouds from retrieval attempts.
18 (Zhang and Platnick 2011; Pincus et al. 2012). Similarly for aerosol retrievals, much effort is
19 made to reclassify as “not cloudy” scenes that are in fact, heavy dust or smoke. Therefore, for
20 both teams, uncertainty whether a particular sample is cloud-covered or contains primarily
21 aerosols, and how to propagate this uncertainty into retrieval products, remains a topic of
22 great interest. A major problem is that there is no absolute ground-truth to confirm or deny
23 these decisions in all cases. Ground based instrumentation such as sun photometers (Holben et
24 al 1998) may not be able to accurately distinguish between aerosol and thin clouds due to
25 limited spectral range, generally reaching only up to a wavelength of 1.024 μ m. Newer sun

1 photometers do provide information up to 1.64 μm , but they are not present at every ground
2 site. The ground sites in Brazil that fall within the area we studied in this paper carry the older
3 instrumentation. The best wavelengths for detecting cirrus clouds are located around 1.38 and
4 1.8 μm . There are also efforts to retrieve aerosol optical depth above cloud layers (Meyer and
5 Platnick 2015, Meyer et al. 2013). Validation for such algorithms is often done using lidar and
6 radar data (Ackerman, et al. 2008, Notarnicola, et al. 2011). However as current spaceborne
7 lidar and radar instruments have fixed nadir view, the amount of such data acquired in tandem
8 with an instrument like MODIS is rather limited.

9 While a global meteorological model cannot be directly used to validate observations and
10 retrievals due to the many assumptions and simplifications commonly made in the dynamic
11 core and physics parameterizations (Rienecker et al. 2008), one can use such a model to learn
12 about sensitivities of retrieval algorithms. As global models such as the Goddard Earth
13 Observing System Model, Version 5 (GEOS-5; Rienecker et al. 2008, Molod et al. 2012),
14 become increasingly realistic when simulating aerosols and clouds over complex surface
15 terrain, we can apply detailed radiative transfer (RT) to simulate how these scenes would
16 appear to a satellite such as MODIS, and how operational algorithms would in turn retrieve
17 the specified conditions. Since the specified model aerosol and cloud properties of the scene
18 are known, one can then characterize the ability (and uncertainties) of standard (e.g. MxD04
19 or MxD06) retrievals in these scenes. Thus, one can evaluate the current (and possibly
20 historical) performance of cloud and aerosol properties retrievals. Application and evaluation
21 of these simulation capabilities for known instruments is also an important step in
22 development of Observing System Simulation Experiments for future observing missions.

23 The Multi-Sensor Cloud and Aerosol Retrieval Simulator (MCARS; Wind et al., 2013) is
24 a modular, flexible tool, in which model output is coupled with a radiative transfer code in

1 order to simulate Top Of Atmosphere (TOA) radiances that may be measured by a remote
2 sensing instrument if it were passing over the model fields. In principle, MCARS can be
3 [applied to any model / visible-IR radiometer combination](#). The simulation complexity is only
4 limited by computer power. However, in this paper, the MCARS continues to use the
5 combination of GEOS-5 model and Discrete Ordinate Radiative Transfer (DISORT) code
6 (Stamnes et al. 1988) to simulate MODIS radiances. In Wind et al. (2013), the MCARS
7 simulated only clouds; here we add microphysical properties of aerosols present in scenes we
8 examine.

9 The approach we take is to populate the operational MODIS Level 1B calibrated radiance
10 files with TOA radiances simulated from GEOS-5 model output and DISORT. For a given
11 time and location, MODIS provides a particular geometry of observation. Since GEOS-5
12 [simulates clouds and aerosols interactively](#), we can replace the MODIS-observed reflectance
13 data with [the simulated radiance product derived from the model](#). Then we run the standard
14 aerosol (MxD04_L2) and cloud (MxD06_L2) retrieval codes and compare retrieval result to
15 the known GEOS-5 source data. The discrepancies diagnosed by this device can then be
16 contrasted to discrepancies obtained by comparing the real operational retrievals to
17 independent, trusted observations (e.g., AOD from [AErosol RObotic NETwork](#)
18 [\(AERONET\)](#)). To the extent that simulated and real statistical comparisons match, we can use
19 capabilities of the MCARS code to examine the causes for such discrepancies, and hopefully
20 identify opportunities for algorithm improvement. Since the aerosol retrieval is under-
21 determined (Levy et al. 2013) and a number of assumptions must be made, the MCARS
22 simulation approach is highly valuable as individual assumptions can be tested in isolation.
23 The MCARS code has sufficient flexibility to test impacts of settings of single operational
24 retrieval code parameters without interference from other components.

1 Section 2 describes the GEOS-5 aerosol properties and their addition into MCARS.
2 Section 3 describes the MODIS aerosol product. Section 4 discusses case selection for the
3 current analysis. It shows the selected scenes simulated by MCARS and describes other
4 special simulation settings available that provide additional analysis capabilities. This section
5 also presents analysis of retrieved aerosol properties as compared to the specified “ground”
6 truth that served as input to the simulations. Finally, section 5 discusses next steps in the
7 continuing MCARS development.

8

9 **2 GEOS-5 aerosol model and data assimilation systems**

10 **2.1 System Description**

11 Global aerosol, cloud, surface and atmospheric column fields from the GEOS-5 model
12 and data assimilation system serve as the starting point for radiance simulations. The GEOS-5
13 system contains components for atmospheric circulation and composition (including aerosol
14 and meteorological data assimilation), ocean circulation and biogeochemistry, and land
15 surface processes. Components and individual parameterizations within components are
16 coupled under the Earth System Modeling Framework (ESMF, Hill et al. 2004). This study is
17 based on the near real-time (NRT) configuration of GEOS-5 where sea surface temperature
18 and sea ice are specified from observations (Molod et al. 2012). The [Goddard Chemistry](#)
19 [Aerosol Radiation and Transport \(GOCART, Colarco et al. 2010, Chin et al. 2002\)](#) bulk
20 aerosol scheme [is](#) used in the GEOS-5 NRT aerosol forecasting system in this paper. A
21 version of [GOCART](#) is run online and [affects atmospheric radiative heating and budget](#) in
22 GEOS-5. [GOCART treats the sources and sinks of dust, sulfate, sea salt and black](#)
23 [and organic carbon aerosols](#). Total mass of sulfate, and hydrophobic and hydrophilic modes
24 of carbonaceous aerosols are tracked. Dust and sea salt have an explicit particle size

1 distribution with five non-interacting size bins for each constituent. Emission functions of
2 both dust and sea salt depend on wind speed. Sulfate and carbonaceous species have
3 contributions primarily from fossil fuel combustion, biomass burning, and biofuel
4 consumption, with additional biogenic sources of organic carbon. Sulfate has additional
5 chemical production from oxidation of SO₂ and dimethyl sulfide (DMS). We additionally
6 include a database of volcanic SO₂ emissions and injection heights ([Diehl et al. 2012](#)). For all
7 aerosol species, optical properties are obtained primarily from the commonly used Optical
8 Properties of Aerosols and Clouds (OPAC) data set (Hess et al. 1998). We have recently
9 updated our dust optical properties data set to incorporate non-spherical dust properties based
10 on the work of Meng et al. (2010), Colarco et al. (2013) and Buchard et al. (2014). The
11 [aerosol](#) transport is consistent with the underlying atmospheric dynamics and physical
12 parameterizations (e.g., moist convection and turbulent mixing) of the model.

13 The GEOS-5 meteorological data assimilation is based on the Grid-point Statistical
14 Interpolation (GSI) analysis scheme, jointly developed with National Oceanic and
15 Atmospheric Administration National Center for Environmental Prediction (NOAA/NCEP)
16 (Wu et al. 2002; Kleist et al. 2009). While the current GEOS-5 operational algorithm is based
17 on a hybrid ensemble-variational scheme, the results reported here are based on the original
18 3D-Var implementation (Rienecker et al 2008). [The aerosol re-analysis is produced at three-](#)
19 [hour intervals, with assimilation of bias-corrected aerosol optical depth from MODIS, and has](#)
20 [been evaluated against ground-base sun photometer measurements \(Holben et al., 1998\)](#)
21 [and against the Multi-angle Imaging Spectroradiometer \(MISR\) satellite instrument \(Kahn et](#)
22 [al, 2007\).](#)

1 **2.2 Fire Emissions**

2 The fire emissions used in our simulations come from the Quick Fire Emission Dataset
3 (QFED) Version 2.4 (Darmenov and da Silva, 2015). The QFED emissions are based on a
4 top-down approach relating satellite retrieved Fire Radiative Power (FRP) at the top of the
5 atmosphere to the amount of gases and particulate matter being emitted at the burning surface.
6 The QFED emission factors are tuned so as to promote agreement among modeled and
7 observed AOD. Another unique feature of QFED is how it handles areas obstructed by
8 clouds when estimating grid-box mean emission rates. A sequential, minimum-variance
9 algorithm keeps track of the fractional obscured area of given grid box. Emissions under the
10 obscured area are then obtained by means of damped persistency model. Details can be found
11 in Darmenov and da Silva (2015).

12 **2.3 Case study selection**

13 The WMO's Working Group on Numerical Experimentation (WGNE) has organized an
14 exercise to evaluate the impact of aerosols on Numerical Weather Prediction (NWP) (Freitas
15 et al. 2015.) This exercise involves testing of regional and global models currently used for
16 weather forecasting by operational centers worldwide. The authors of this exercise selected 3
17 strong or persistent events of aerosol pollution worldwide that could be fairly represented by
18 current NWP models. These cases were specifically selected to facilitate evaluation of the
19 aerosol impact on weather prediction. We chose one of the specified WGNE events: an
20 extreme case of biomass burning smoke in Brazil, as the focus of this paper.

21 **3 MODIS aerosol product**

22 The MODIS "dark-target" (DT) aerosol product is described in detail in Levy, et al.
23 (2013) and references therein. In this section we will give a brief overview of the DT
24 algorithm as applied to MODIS observations.

1 The standard MODIS aerosol properties retrieval algorithm is a 10 km resolution product
2 calculated from a detailed analysis of 10x10 boxes of 1km MODIS pixels. A necessary
3 constraint for the algorithm is that the underlying surface is dark in visible and shortwave-IR
4 wavelengths. There are two separate algorithm paths for ocean and land.

5 Pixels that are suspected to be cloudy or too bright or too noisy are discarded using
6 conditions described in (Levy et al, 2007). Once the data sample is prepared, a spectral profile
7 of average TOA spectral reflectance is created and compared against a lookup table. If a
8 match is found, values for aerosol optical depth (AOD) and fine-mode aerosol weighting
9 (FMW) are then returned.

10 In this paper we will focus on the land algorithm. Full description of the ocean algorithm
11 can be found in Levy, et al (2013). Over land, even though there is greater variability of
12 underlying surface than over ocean and thus greater uncertainty in retrieved aerosol
13 properties, aerosol retrieval is still achievable. Over vegetated and dark-soiled surfaces,
14 Kaufman et al. (1997) found that surface reflectance values for red (e.g. 0.65 μm) and blue
15 (0.47 μm) wavelengths are correlated with the surface reflectance in a short-wave infrared
16 (SWIR) band (e.g. 2.13 μm). The land algorithm uses 0.47, 0.65 and 2.13 μm channels for the
17 main retrieval and 0.55, 0.86 and 1.24 μm channels to give additional surface constraints.

18 The aerosol LUT is calculated for black surfaces and sea-level pressure. There are three
19 fine particle model types and one coarse particle model type of aerosols used for dust based
20 on climatology of AERONET inversion data (Dubovik et al, 2002). Each model type is multi-
21 lognormal and is represented by size distribution, particle shape and complex refractive
22 indices. The three fine-dominated models are differentiated primarily by single scattering
23 albedo (SSA) in mid-visible wavelengths: urban/industrial type (SSA~0.95), near-source
24 biomass burning (SSA~0.85) and a moderately absorbing type (SSA~0.90) to cover all other
25 cases. For each aerosol type, the LUT includes TOA reflectance for a variety of angles and

1 | AOD referenced to 0.55 μ m.

2 | Even with the constraints on surface reflectance, the aerosol retrieval does not have
3 | enough information to select between different aerosol types. Therefore, the relative
4 | proportion of fine-mode and coarse-mode aerosols must be prescribed so that, coupled with
5 | surface constraints, a best match can be found in the LUT for TOA spectral reflectance in the
6 | blue, red and SWIR wavelengths. The difference between TOA and nearest LUT reflectance
7 | is the fitting error.

8 | With Levy et al., (2013) and previous studies, the primary validation of the MODIS
9 | product is by detailed co-location with ground-based sun photometer data, especially the
10 | Aerosol Robotic Network (AERONET; Holben et al., 1998). In this way, Levy et al., (2013)
11 | have defined the expected error (EE) envelope for the 0.55 μ m AOD as $\pm(0.05 + 15\%)$.
12 | While spectral surface reflectance is also retrieved, it does not tend to compare well with
13 | values obtained from the sun photometers. Note that the EE is defined upon mutually
14 | retrieved data. This means that satellite and sun photometer both observe enough clear-sky to
15 | retrieve AOD.

16 | Also, while AERONET is well distributed about the globe, there are many situations for
17 | which MODIS retrieves aerosol, but there are no AERONET data available to compare with.
18 | Thus, there is no way to determine whether the MODIS aerosol retrieval has made reasonable
19 | choices, either for pixel selection, for cloud screening, or for aerosol model type and surface
20 | reflectance assumptions.

21 | This motivates our use of the MCARS. Having full knowledge of underlying
22 | atmospheric, cloud, aerosol and surface parameters MCARS allows us to see deeper than
23 | AERONET would and over a much wider spatial area.

1 **4 MCARS simulations**

2 **4.1 The MCARS software**

3 We produced the simulation input data in accordance with the methods outlined in Wind
4 et al. (2013). The GEOS-5 model output is split into 1-km subcolumns using the [ICA](#) method
5 as described in [detail in](#) Wind et al. (2013). [Here we give a brief summary of the model data](#)
6 [preparation methodology.](#)

7 [Sampling of model cloud-related fields to the MODIS pixel scale is not straightforward](#)
8 [because cloud properties typically vary on scales not adequately resolved by the operational](#)
9 [0.25° GEOS-5 resolution. To sample cloud fields, 1 km MODIS pixels for each GEOS-5](#)
10 [gridcolumn are collected and the same number of pixel-like sub-columns are generated using](#)
11 [a statistical model of sub-gridcolumn moisture variability. The general approach of Norris et](#)
12 [al. \(2008\) is followed, namely using a parameterized probability density function \(PDF\) of](#)
13 [total water content for each model layer and a Gaussian copula to correlate these PDFs in the](#)
14 [vertical. Full details of the calculation of this PDF are described fully in Norris and da Silva](#)
15 [\(2016\).](#)

16 [The subcolumns generated in this way are horizontally independent, but are subsequently](#)
17 [“clumped,” or rearranged, to give horizontal spatial coherence, by using a horizontal Gaussian](#)
18 [copula applied to condensed water path. This clumping acts to give the generated clouds a](#)
19 [reasonable horizontal structure, such that the cloudy pixels in a gridcolumn are actually](#)
20 [grouped into reasonable looking clouds, rather than being randomly distributed. This is](#)
21 [important because the MODIS cloud optical and microphysical properties retrieval algorithm](#)
22 [has some spatial variance tests for potentially partially-cloudy pixels, removing cloud edges](#)
23 [by the so-called “clear-sky restoral” \(Zhang and Platnick 2011; Pincus et al. 2012\). If](#)
24 [clumping is not used, then individual points generated by ICA stand an exceptionally high](#)

1 chance of being eliminated by the clear sky restoral unless a model grid box has a nearly
2 100% cloud fraction.

3 The layer aerosol properties are obtained using the independent column approximation
4 with the same PDF of total water content as used for clouds. The MCARS code uses a species
5 file, produced from the GEOS-5 model output, which for each simulated MODIS pixel gives
6 individual aerosol optical depths by aerosol type. The OPAC database (Hess et al, 1998) is
7 then queried in order to obtain the aerosol phase function for each of the 15 aerosol species
8 and the properties such as single-scattering albedo are then augmented by profile of
9 subcolumn relative humidity. The result of this query is a set of Legendre coefficients and a
10 single-scattering albedo that correspond to the combined effect of all 15 aerosol species.

11 Model parameters such as profiles of temperature, pressure, ozone and water vapor
12 together with layer information about clouds (and now aerosols) are combined with solar and
13 view geometry of the MODIS instrument. Surface information is also a combination of
14 GEOS-5 information of surface temperature, snow and sea ice cover and MODIS-derived
15 spectral surface albedo (Moody et al. 2007, 2008). All these parameters are transferred to the
16 DISORT-5 radiative transfer code and reflectances and radiances in 24 MODIS channels are
17 produced. They are output into a standard MODIS L1B file that corresponds to the source
18 MODIS geolocation file we used to sample the model output with. All metadata is preserved
19 in this process and so the MCARS output is indistinguishable from a real MODIS granule
20 except in how it may appear to the user's eye. These synthetic reflectances and radiances are
21 completely transparent to any operational or research-level retrieval algorithm code and can
22 be used for any purpose that real sensor data can.

23 In order to produce these simulations we use the NASA Center for Climate Simulations
24 (NCCS) supercomputer Discover. It takes 5.5 hours of wall clock time on 144 processors to
25 produce one complete simulation. The performance can be improved if the user limits the

1 simulation scope to fit a particular investigation they are working on. For example, an aerosol
2 researcher would not likely need to simulate the MODIS channels that they would not use and
3 thus reduce execution time by at least half. Because these simulations are simultaneously used
4 for both cloud and aerosol work, we simulate all the channels that would be used by both
5 cloud and aerosol disciplines.

6 **4.2 Granule selection**

7 In order to perform tests of the MCARS aerosol module we have selected Aqua MODIS
8 granules from time period corresponding to WGNE selection for biomass burning in Brazil.
9 In this paper we specifically present results from simulations based on two granules of smoke
10 in Brazil 2012 day 252 17:30 UTC and day 254 17:20 UTC subsequently referred as “Brazil
11 1” and “Brazil 2”.

12 **5 Analysis**

13 For each granule, we ran the simulations in several modes with varied run-time option
14 settings. For example, the cloud-only mode corresponds to a clean atmosphere with no
15 aerosols; this mode was the only one considered in Wind et al. (2013). In the current paper we
16 consider additional options afforded by the implementation of the aerosol effect. The cloud-
17 free option runs atmosphere and aerosols without any clouds. When clouds are turned off, we
18 do not alter the humidity profiles to dry the atmosphere out; because of the high relative
19 humidity conditions where clouds are present, aerosol hygroscopic effects are pronounced
20 there as well. The full simulation option includes atmosphere (temperature, humidity and
21 ozone profiles), all clouds and all aerosols. There is also an additional option where the user
22 can remove both clouds and aerosols and be left with just the atmosphere itself. Rayleigh
23 scattering is always included by default but user also has control over whether or not to turn it
24 off. While this no-cloud/no-aerosol mode could be useful for studies of atmospheric

1 correction methods, we do not exercise it here, as our primary goal here is to investigate the
2 performance of the MODIS aerosol algorithms.

3 The cloud-free mode of operation is convenient when complex cloud and aerosol scenes
4 are being investigated and one wishes to quantify or remove possible impacts of cloud
5 contamination on the retrieval. Figure 1 shows RGB images constructed from simulated
6 MODIS L1B for the different modes of execution for the “Brazil 1” case. MODIS aerosol
7 retrievals were produced for radiance simulations including atmosphere, cloud and aerosols
8 (Figure 1c) and for radiance simulations excluding clouds (Figure 1d). [Rayleigh scattering is](#)
9 [included in these simulations.](#)

10 These Brazil cases came from source MODIS Aqua granules and had been processed
11 using the MODIS Aqua aerosol properties retrieval algorithm. Therefore in this section we
12 will use MYD04 designation for the MODIS aerosol properties retrieval result. There are
13 some slight differences between the MODIS Terra (MOD04) and MODIS Aqua (MYD04)
14 algorithms due to calibration differences between the two instruments (Levy et al, 2013).

15 The scatter diagrams in Figure 2 compare AOD retrieved using the MYD04 algorithm to
16 the specified GEOS-5 AOD, which is considered the ground truth in this case. [MODIS](#)
17 [aerosol retrievals are commonly compared to co-located](#) AERONET AOD measurements
18 (Correia and Pires 2006, Levy, et al. 2007, Remer et al. 2005) [for validation.](#) Unlike
19 comparisons of actual MODIS data with AERONET, the match ups in Figure 2 did not
20 require any temporal averaging or aggregation because for every MYD04 retrieval there is a
21 directly corresponding input data point with all aerosol, cloud and atmospheric properties
22 readily available. The overall shape of resulting scatter plots turned out to be quite similar to
23 existing MYD04 – AERONET comparisons for this region such as those that appear in
24 Correia and Pires (2006) and Figure 3. Figure 3 shows [an actual](#) comparison for AERONET
25 observations for months of July and August [and](#) all available Aqua MODIS collocated

1 observations from year 2002 through 2015. The chosen AERONET sites:
2 Campo_Grande_SONDA, Sao_Paulo and CUIABA-MIRANDA fall in the general area of the
3 two Brazil cases selected for study. They of course represent a tiny sample of the
4 geographical area covered by the MCARS data, just three points out of 2.7 million collocated
5 samples that MCARS provides, but they display a similar shape of the relationship between
6 ground truth and MYD04 retrieval.

7 MCARS is a fully configurable system where source input for all synthetic radiances can
8 be controlled at all times, so that any resulting retrieval can be examined in great detail
9 insofar as the particular setup of model input and radiative transfer core allows. For these
10 smoke cases we used these capabilities to investigate further the specific reasons why the
11 MYD04 retrievals tend to underestimate AOD for smoke aerosol.

12 The first test we made was to examine the performance of MYD04 cloud mask, which is
13 an aerosol specific product (Remer et al, 2005), different from the operational MODIS cloud
14 mask product (Ackerman et al, 2006). The main purpose of this analysis was to ascertain
15 whether cloud contamination could account for some of the discrepancies. Individual panels
16 in Figure 2 show the results of retrievals run with and without the cloud layers. Panels a) and
17 b) show result for “Brazil 1” and panels c) and d) are for “Brazil 2”. “Brazil 1” case does not
18 show any significant cloud contamination. The MYD04 cloud mask does a very good job of
19 avoiding cloud. “Brazil 2” does show some very minor cloud contamination as evident by a
20 small cluster of high MYD04 AOD and low GEOS-5 AOD that disappears when clouds are
21 removed from simulation. However the overall shape of the scatter plot when clouds are
22 removed remains unchanged.

23 The aerosol models used in the MYD04 retrievals make assumptions about the smoke
24 aerosol optical properties, which may not match the aerosol optical assumptions in GEOS-5
25 (Levy et al, 2007). In cases of complex aerosol mixtures or if the model selected by the

1 MYD04 algorithm does not correspond to the aerosols provided by GEOS-5, large retrieval
2 errors should result. Figure 4 shows the species mixture for “Brazil 1” (a) and “Brazil 2” (b)
3 cases. They are both dominated by carbon, organic carbon from smoke in particular, with
4 very little, if any contribution from other species. Therefore these particular cases can be
5 treated as having a single aerosol type present without significant error. MYD04 retrieval
6 output indicates that either moderately or strongly absorbing smoke had been selected, which
7 is very appropriate for the selected granules. Thus any discrepancy in selection of aerosol
8 model does not explain the scatter plot shape.

9 Another candidate source of retrieval error is any difference between the phase functions
10 assumed by MYD04 and GEOS-5. We ran the initial simulations simply using the Henyey-
11 Greenstein (HG) phase function approximation and then repeated the same simulation using
12 the phase functions provided by the OPAC database described in section 2. Figure 5 shows
13 the result for “Brazil 1” and “Brazil 2” cases using the cloud-free run with HG phase function
14 versus OPAC phase function. For the smoke aerosol cases studied, the specific phase
15 function shape does not appear to have a significant impact on the differences seen between
16 MYD04 and GEOS-5.

17 An additional potential source of error for aerosol retrievals over land is the surface
18 albedo and its variation over a 10x10 km area. We performed a simulation where we selected
19 a single surface albedo profile from a successful MYD04 retrieval and fixed the surface
20 albedo to that particular surface albedo profile for the entire granule. The test albedo profile
21 used is listed in Table 1. The profile corresponds to a very dark vegetated surface, the ideal
22 conditions for the MYD04 land algorithm. Figure 6 shows the effect of using a constant
23 surface albedo for “Brazil 1” and “Brazil 2” cases. Whereas use of constant surface albedo
24 reduces the scatterplot spread and so allows us to potentially quantify the effect of surface
25 inhomogeneity on MYD04 land retrievals, it does not alter the overall bias characteristics of

1 scatter plots.

2 With all the factors of model selection, surface parameters and cloud contamination taken
3 into account, we now turn our attention to the aerosol scattering properties, the spectral single
4 scattering albedo (SSA) in particular. Figures 7 and 8 show the spectral profile of aerosol SSA
5 for “Brazil 1” and “Brazil 2” cases respectively for the first seven MODIS channels. This
6 aerosol SSA is a bulk quantity, integrated over all layers and combines all 15 available
7 aerosol species. However the cases under consideration are heavily dominated by carbon with
8 negligible amounts of dust and sulfate. In this particular case the additional uncertainties that
9 would arise from a mixture of aerosols with different scattering properties do not present an
10 issue. The single scattering albedo remains quite high until we reach the 1.2 μ m channel,
11 MODIS band 5, and beyond. Then it drops precipitously. AERONET is only able to provide
12 direct inversion retrievals of single scattering albedo for four wavelengths out to a maximum
13 wavelength of 1.024 μ m (Dubovik and King, 2000; Dubovik et al., 2002). The rapid change
14 in single scattering albedo for smoke aerosol modeled in GEOS-5 is related to aerosol
15 humidification effects, both dilution effects and hygroscopic growth (Colarco et al. 2010,
16 2013). The net effect is that when humidity decreases, so does the single scattering albedo.
17 Figure 9 shows a plot of OPAC single scattering albedo for a variety of column relative
18 humidity values as a function of wavelength. (Colarco, et al 2013) The operational MODIS
19 aerosol code assumes a constant 80% relative humidity when the lookup tables are generated
20 (Levy et al, 2007). It is a reasonable assumption as long as one does not attempt to use
21 channels with wavelengths that are longer than 0.8 μ m. The MYD04 algorithm however does
22 use the 2.1 μ m MODIS channel in retrieval, a channel that is sensitive to humidity. MCARS is
23 particularly well suited to test for humidity impact on the retrieval accuracy. We made another
24 experiment with fixed surface albedo, OPAC aerosol phase function shape but we used the
25 constant single scattering albedo values from the MODIS aerosol algorithm in the reflectance

1 calculation that serves as input to the retrieval algorithm. The result is shown in figure 10.
2 When humidification effects are not taken in consideration in the SSA calculation, MYD04
3 retrieval results closely line up with synthetic GEOS-5 source data. The underestimate of
4 aerosol optical depth disappears, with “Brazil 2” showing the most dramatic improvement. It
5 appears that if MYD04 were to take into account humidification effects and implement a
6 correction for single scattering albedo value as a function of column relative humidity, the
7 result of comparison between MODIS and AERONET could be significantly improved for
8 biomass burning cases in Brazil and other locations with similar synoptic conditions.

9 The improvement is limited however to AOD higher than about 0.5. Relative humidity
10 does not appear to have an effect on retrieved low AOD values. MYD04 product does not
11 provide pixel-level retrieval uncertainty estimates. It is possible that the inherent uncertainty
12 in performing retrieval using such small signal is so high that it drowns out other effects.
13 More studies may be conducted as to attempt to create a pixel-level estimate of retrieval
14 uncertainty for aerosol optical properties retrievals.

15 The MODIS aerosol product performs a simultaneous retrieval of land surface
16 reflectance and aerosol optical depth. After looking at the behavior of aerosol optical depth
17 and making a recommendation for a possible improvement in the retrieval algorithm, we
18 examined the retrieval of land surface reflectance. The MODIS aerosol product provides
19 retrieved land surface reflectance in the 0.47, 0.65 and 2.1 μ m channels. We looked at the land
20 surface reflectance for the simulation of figure 10 panels c) and d) that now matched the
21 source aerosol optical depth reasonably well. The simulation was run under constant surface
22 albedo conditions and we would have expected to see a result, with some degree of
23 uncertainty of course, that would match the given constant surface albedo. However the
24 retrieved land surface reflectance appeared to be a near-linear function of aerosol optical
25 depth. One possible explanation for this behavior may involve the assumed fraction of coarse-

1 mode aerosol in the aerosol model mixture. To examine this hypothesis we performed a
2 MYD04 retrieval using an aerosol model setting so that MYD04 retrieval only used fine mode
3 particles. The retrieval results, depicted in figure 11 confirm that the near co-linearity of
4 surface reflectance and AOD was indeed directly related to fraction of coarse mode particles,
5 such as dust, in the assumed aerosol mixture. Of course there is no way to know exactly what
6 fraction of coarse mode particles may be present in the mixture as the MODIS [DT](#) algorithm
7 does not have enough information content to constraint the fine/coarse mode fraction over
8 land (Levy et al, 2007). However, it can be noted that if such co-linearity is seen during a
9 specific local aerosol study maybe during a field campaign, it may be suggested that the
10 coarse mode fraction assumed operationally for that particular region may be too high. An
11 analysis of MODIS operational retrievals to identify locations and times where this co-
12 linearity exists may be useful to identify regions where the assumed coarse/fine mode fraction
13 might need to be adjusted. Figure 11 illustrates the impact of coarse-mode fraction selection
14 on [land surface reflectance retrievals for](#) “Brazil 1” and “Brazil 2” cases. The fine-to-coarse
15 mode ratio does not appear to have an impact on the [low bias](#) of MYD04 [AOD retrieval](#) vs.
16 “ground truth” comparisons [presented in the earlier figures](#).

17 **6 Conclusions and future directions**

18 This paper is a continuation of work started in Wind et al, (2013). The multi-sensor cloud
19 retrieval simulator code (MCRS) had been extended to add aerosol effects to radiance
20 simulations. The current implementation of the MCARS code generates synthetic radiances
21 by sending GEOS-5 model fields and MODIS sensor geometry and location information to
22 [the](#) DISORT-5 radiative transfer core. The radiance and reflectance data [are](#) output in a
23 standard MODIS Level 1B format that can be transparently ingested by any retrieval or
24 analysis code that reads data from the MODIS instrument.

25 After the aerosol properties module had been added to the MCARS code we used the

1 simulator to perform detailed analysis of performance of the operational MODIS dark target
2 aerosol properties retrieval product for the Aqua MODIS instrument (MYD04). We found the
3 cause of known low bias in MYD04 retrieved AOD for smoke when compared to in-situ
4 measurements. We suggest that the MYD04 retrieval might consider using column relative
5 humidity from ancillary data when performing retrievals in regions that are defined to be
6 dominated by smoke aerosols. The mismatch between the aerosol single scattering albedo
7 assumed by MYD04 and the given synthetic single scattering albedo is the cause of the low
8 bias at higher AODs. The impact of surface inhomogeneity is also quantifiable. Whereas it
9 may not be possible to make an operationally actionable item from retrieval behavior when
10 surface is made homogeneous, it may be possible to deduce an estimate of retrieval
11 uncertainty due to land surface effects.

12 This study is a good example of capabilities of the MCARS code. We are planning many
13 more studies of retrieval algorithm performance.

14 The MCARS results give a relationship between aerosol single scattering albedo, bias in
15 retrieved aerosol optical depth and column relative humidity. One of our future directions is
16 to examine further this relationship and possibly establish a solid parameterization that could
17 be used by the modeling community to reduce biases in assimilated observations that might
18 display a similar low bias when compared to in-situ measurements.

19 The MCARS simulator is currently being extended to calculate synthetic radiances for
20 the Meteosat Second Generation Spinning Enhanced Visible Infrared Radiometer Imager
21 (MSG-SEVIRI).

22 **7 Code and Data Availability**

23 The MCARS code and any datasets produced, including all data shown (GEOS-5 input
24 in netCDF4 and all MODIS output in HDF4 file format) and discussed in this paper, are
25 available to users free of charge by contacting the authors and becoming a registered user of

1 this software package so that any updates to code or datasets can be issued directly. There
2 may be additional, wider distribution means in the future as needed. We have not deemed it
3 practical up to this time to release the MCARS source code into general-purpose source
4 repositories. The data files are quite large with source input data being on the order of 20 Gb
5 for each MODIS-like granule created. The GEOS-5 model source code is publicly available
6 and we may release the MCARS code under the same NASA Open Source Agreement and
7 the same repository in the coming year.

8

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8 [Program through the NASA Center for Climate Simulation \(NCCS\) at the Goddard Space](#)
9 [Flight Center.](#)

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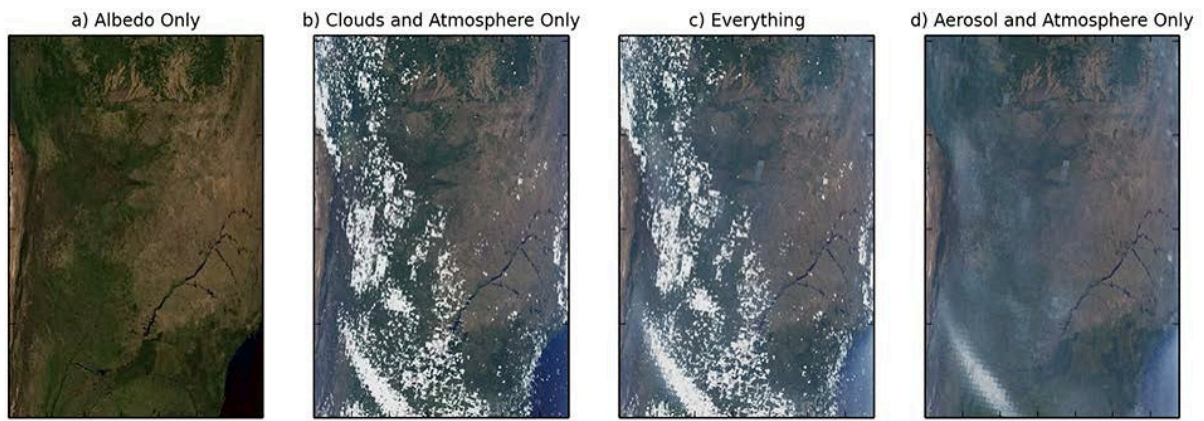
15

1

2 Table 1: Constant surface albedo setting used in smoke AOD retrieval investigation

MODIS channel	<u>Central Wavelength</u> (μm)	Surface Albedo
1	<u>0.65</u>	0.027
2	<u>0.86</u>	0.288
3	<u>0.47</u>	0.017
4	<u>0.55</u>	0.037
5	<u>1.24</u>	0.252
6	<u>1.63</u>	0.146
7	<u>2.13</u>	0.054
8	<u>0.41</u>	0.014
9	<u>0.44</u>	0.022
17	<u>0.91</u>	0.283
18	<u>0.94</u>	0.280
19	<u>0.94</u>	0.280
20	<u>3.7</u>	0.038
22	<u>3.9</u>	0.038
26	<u>1.38</u>	0.216

3



1

2 Figure 1. Example of various execution modes of the MCARS code using the “Brazil 1” case

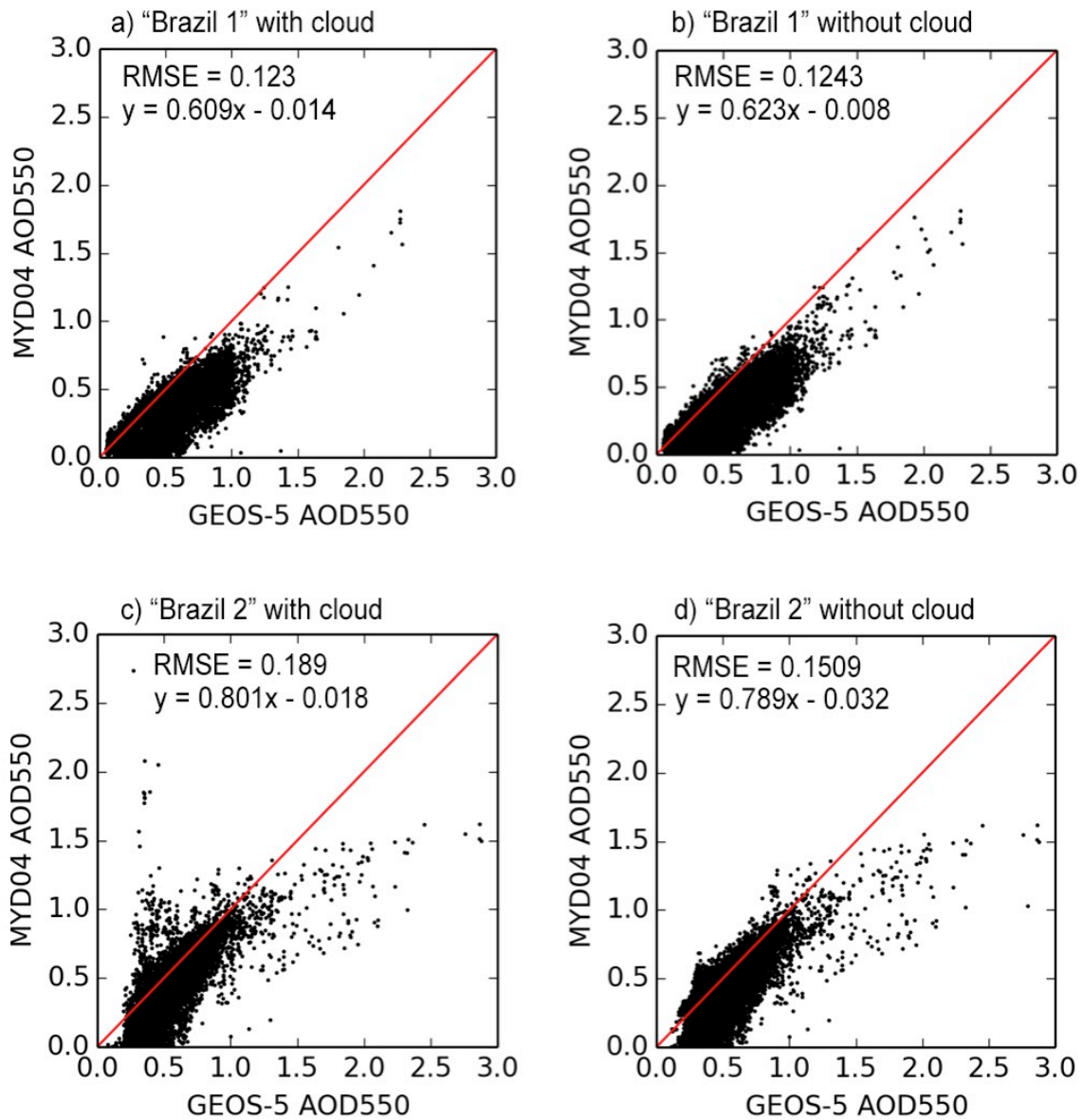
3 | 2012 day 252 17:30UTC. Panel a) shows the atmosphere-free image, just the surface albedo.

4 | Panel b) shows the clouds-only simulation with no aerosols. Panel c) has both clouds and

5 | aerosols and panel d) shows the cloud-free mode, where cloud layers have been removed

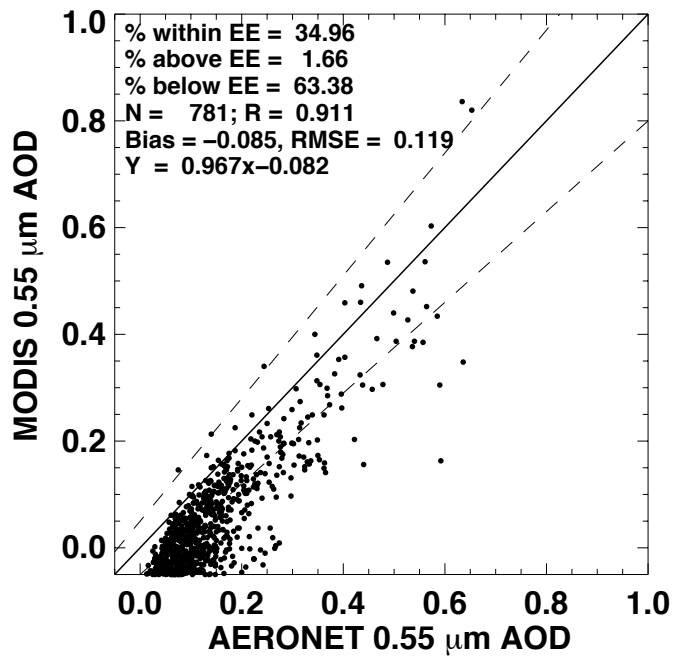
6 | from the scene. Panels b), c) and d) all include Rayleigh scattering.

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Figure 2. MYD04 retrieval of 550 nm aerosol optical depth vs ground "truth" of GEOS-5 550 nm aerosol optical depth. Panel a) shows the scatterplot for retrieval from simulation in figure 1c and panel b) shows retrieval from simulation in figure 1d for "Brazil 1" case. Panels c) and d) show same information for "Brazil 2" case.



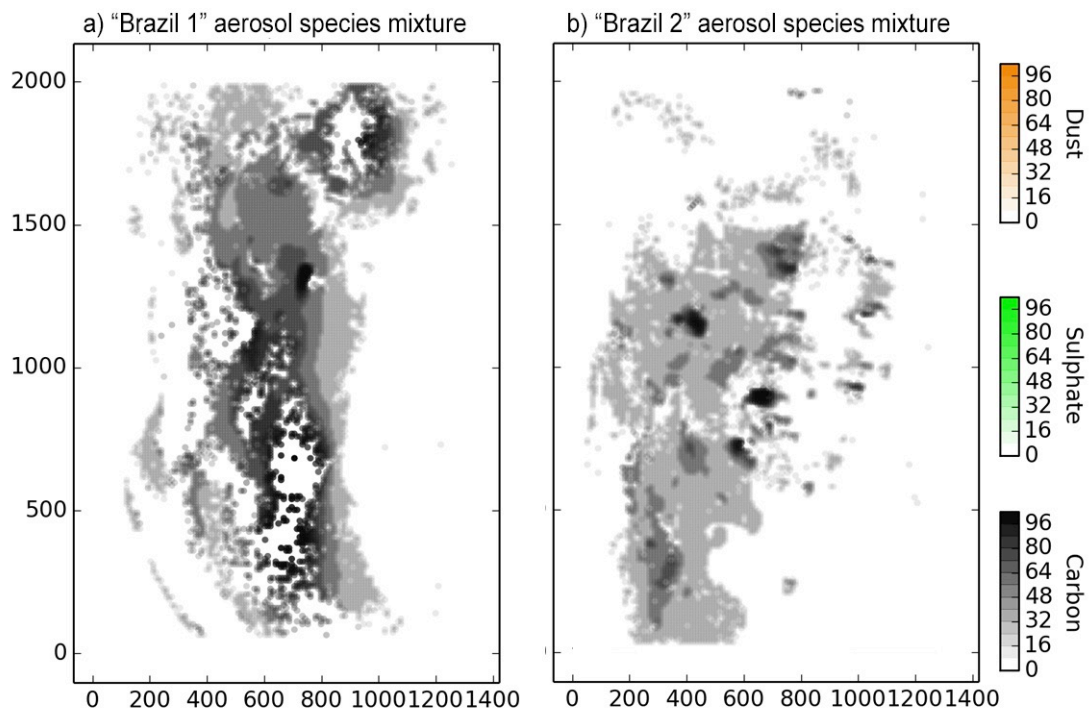
1

2 Figure 3. Comparison of actual AERONET measurements and operational Aqua MODIS

3 Collection 6 aerosol product for Brazil sites Campo_Grande_SONDA, Sao_Paulo and

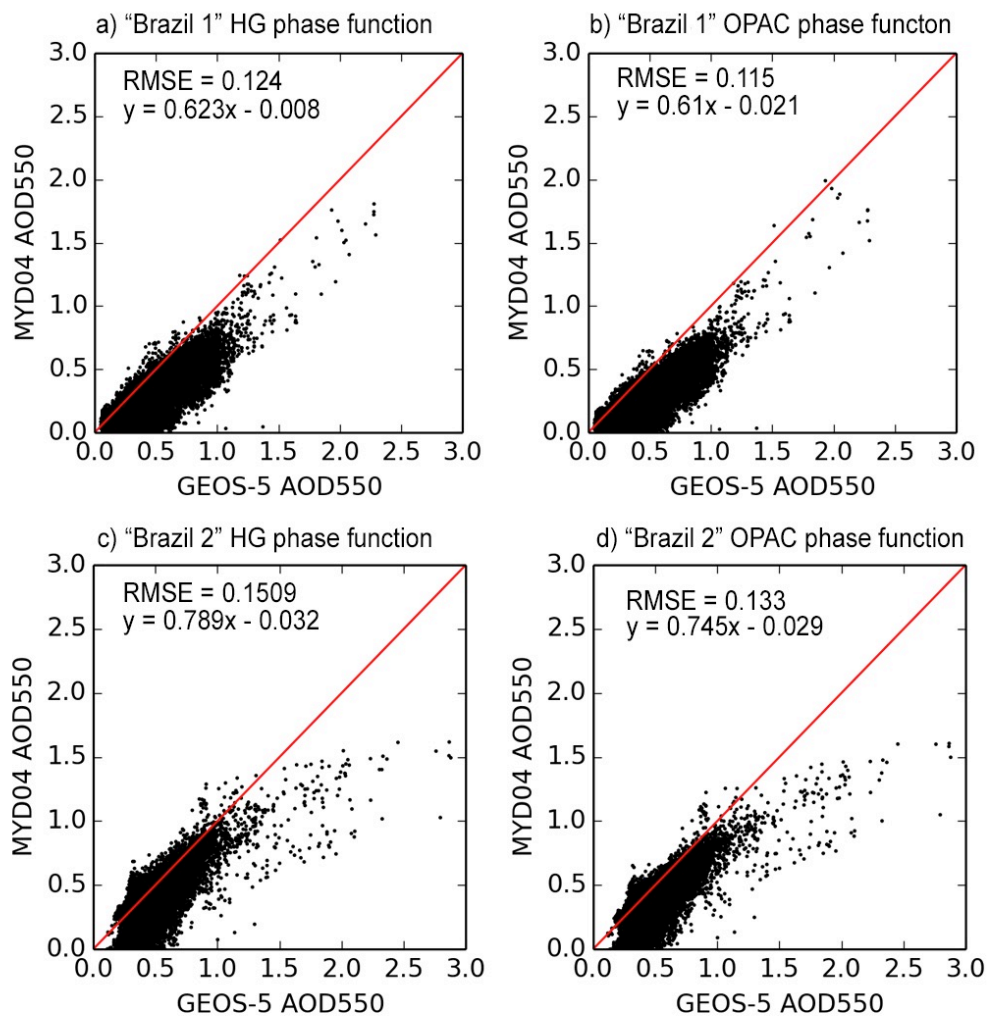
4 CUIABA-MIRANDA in the general area of MCARS granules.

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 2 Figure 4. GEOS-5 aerosol species mixture for attempted MYD04 retrievals in figure 2. Panel
 3 a) shows the “Brazil 1” case (2012 day 252) and panel b) shows the “Brazil 2” case (2012 day
 4 254). Both are dominated by carbon (smoke) aerosol.

5



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2 Figure 5. Effect of aerosol phase function shape on Brazil smoke cases. Panels a) and c) show
3 the runs with HG phase function. Panels b) and d) show use of the OPAC composite phase
4 function.

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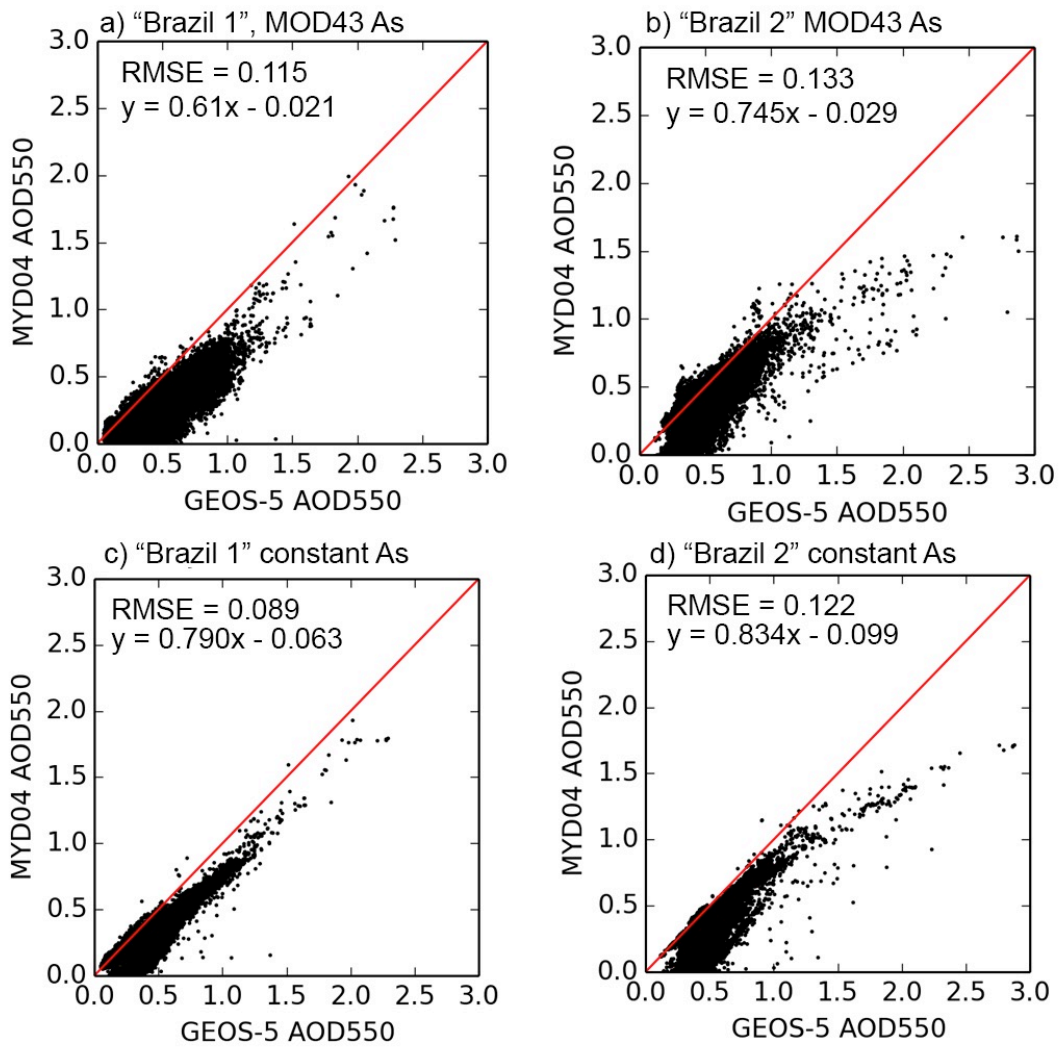
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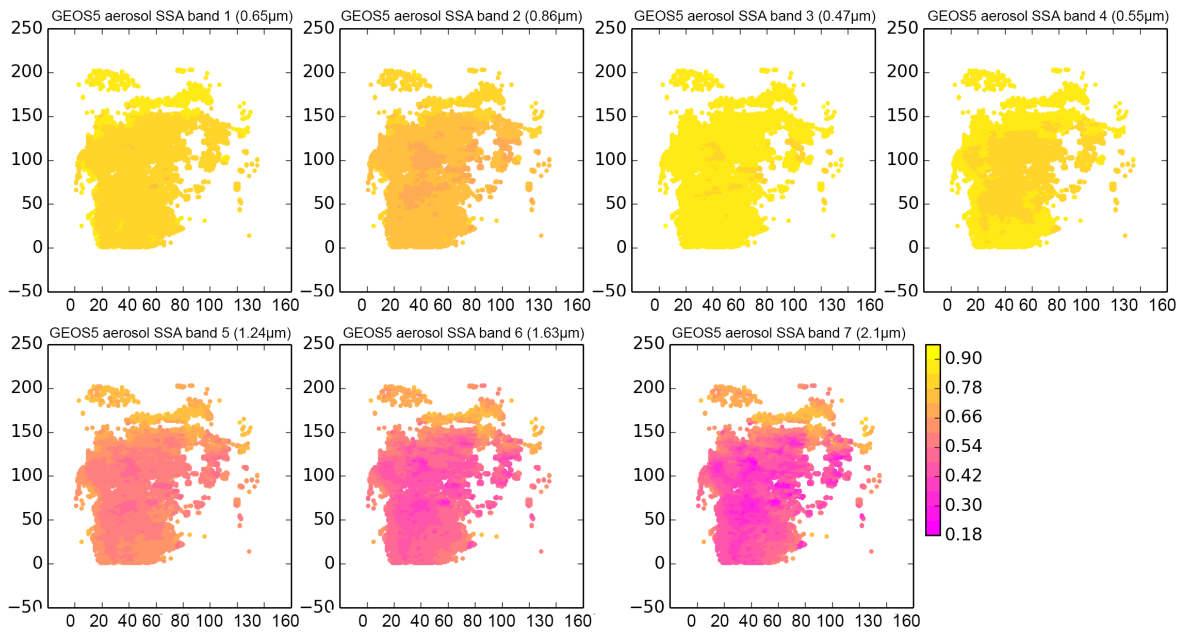
9

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2 Figure 6. Surface albedo effect on Brazil smoke cases. Panels a) and c) show the runs with
3 MOD43-derived surface albedo. Panels b) and d) show the effect of selection of a constant
4 dark land surface albedo.

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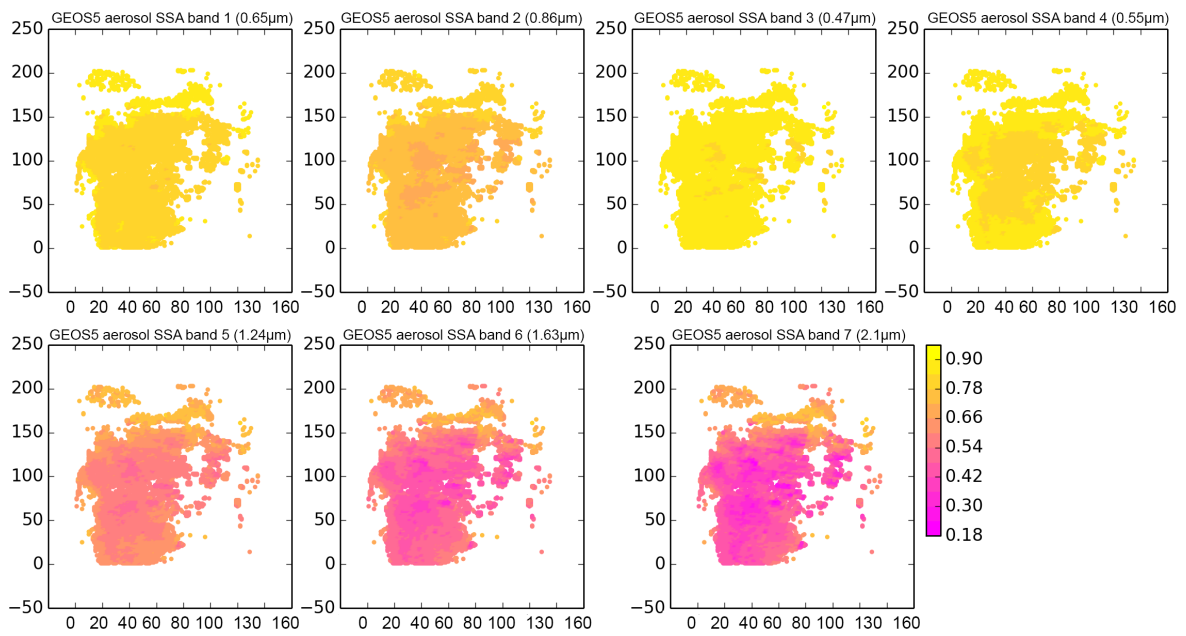


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2 Figure 7. Bulk aerosol single scattering albedo for “Brazil 1” case for MODIS channels 1-7.

3 This single scattering albedo combines all aerosol species present in the scene.

4

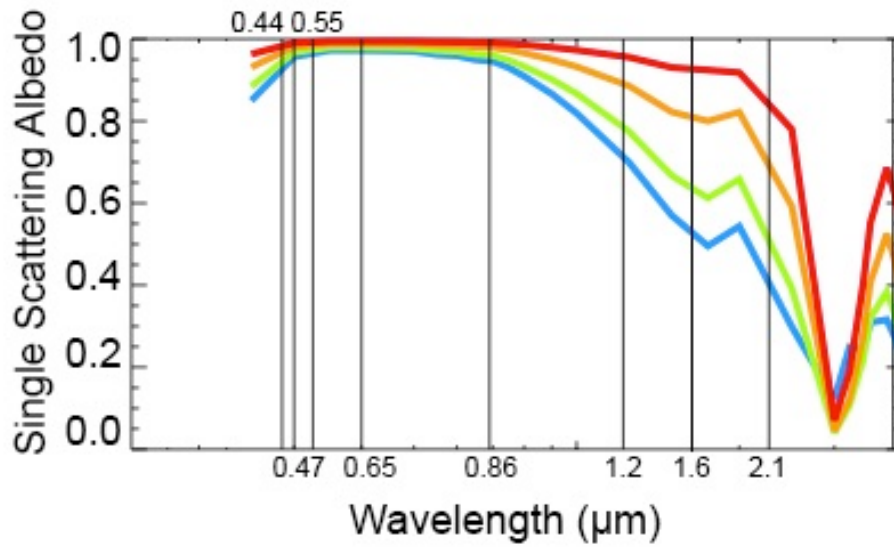
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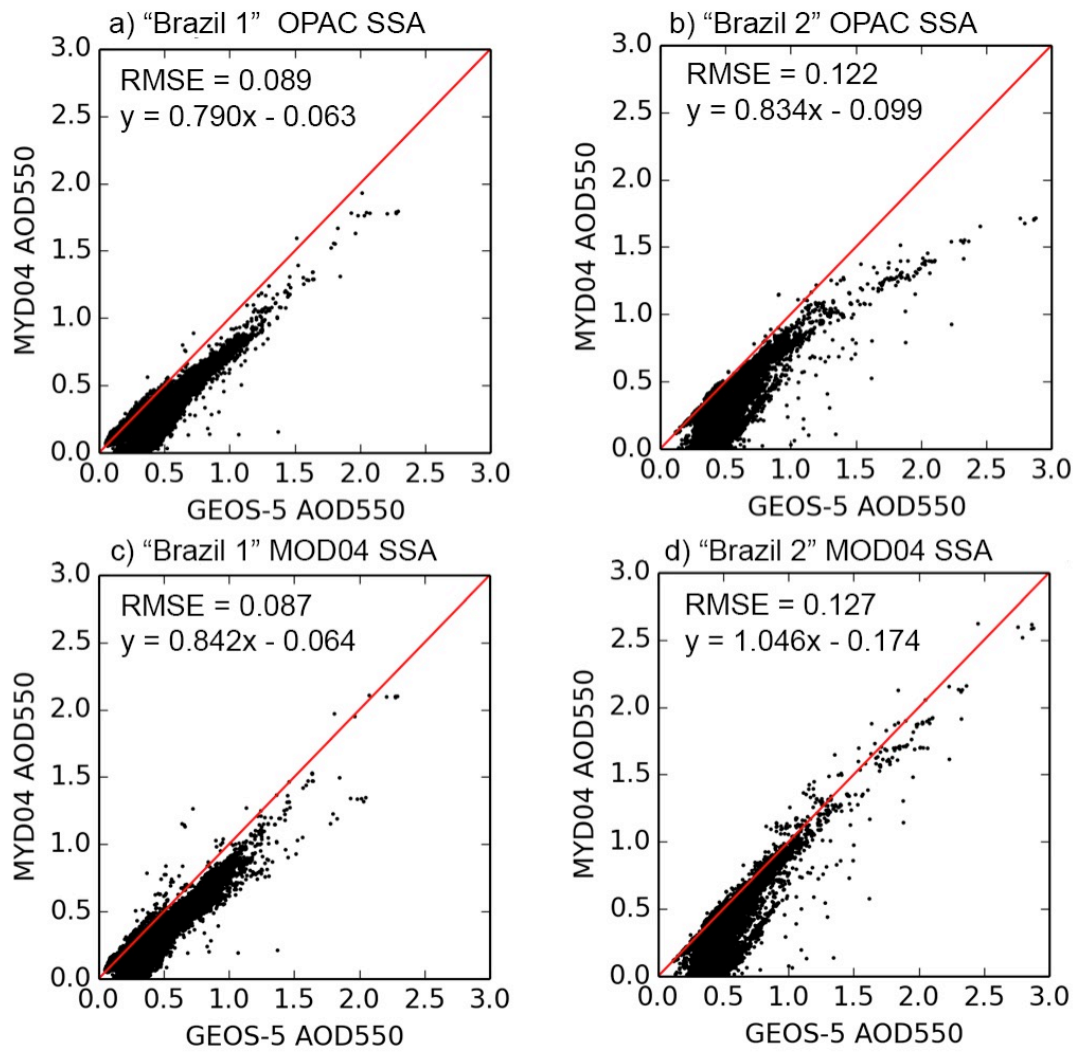
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2 Figure 8. Bulk aerosol single scattering albedo for “Brazil 2” case for MODIS channels 1-7.

3 This single scattering albedo combines all aerosol species present in the scene.

4

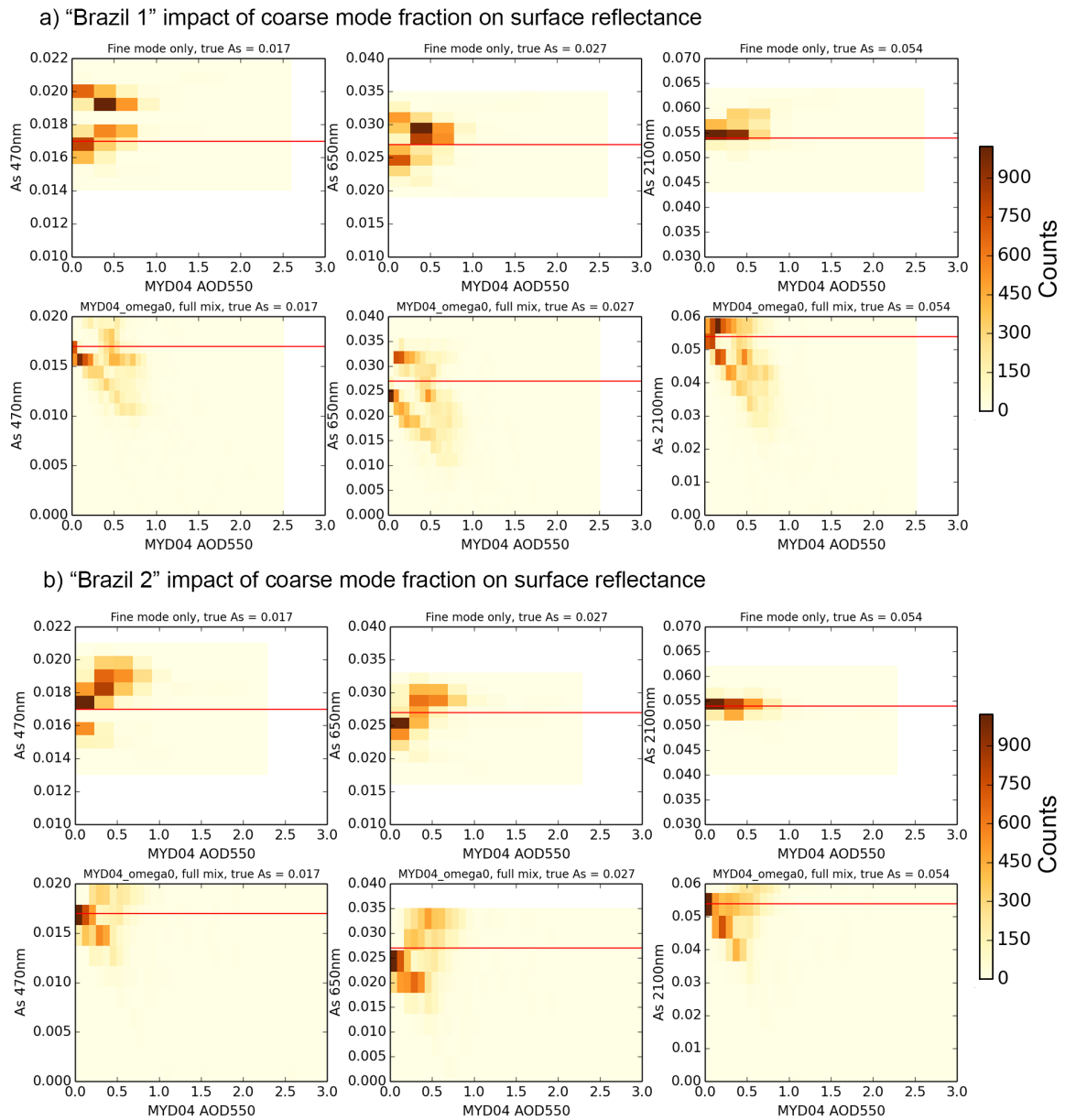


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 2 Figure 9. OPAC single scattering albedo as a function of humidity (color) and wavelength.
 3 The various relative humidity levels are in order (red, orange, green and blue) for 95, 80, 30
 4 and 0% column relative humidity.



1
2 Figure 10. Impact of humidity on MOD04 retrieval illustrated via single scattering albedo
3 selection. Panels a) and c) show the "Brazil 1" case before and after the SSA adjustment.
4 Panels b) and d) show the same for "Brazil 2".

5



1
 2 Figure 11. Impact of coarse mode fraction on MOD04 retrieved surface reflectance. Set a)
 3 shows the "Brazil 1" case and set b) shows "Brazil 2".