

## Authors' response to the review comments #1

Title: OMI NO<sub>2</sub> column densities over North American urban cities: The effect of satellite footprint resolution

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First of all, the authors express their appreciation to the two reviewers and the editor. We believe that their comments are very productive and substantially contributed to improving the manuscript. We offer point-by-point responses to the issues and comments addressed by reviewers. Reviews' comments are shown in italics.

***“The manuscript addresses an innovative way of enhancing the spatial resolution of OMI NO<sub>2</sub> columns for studies of the urban plumes in the US by adopting the spatial distributions of the NO<sub>2</sub> columns from the CMAQ model. Another important point the manuscript emphasizes is careful ways of processing the satellite retrievals and model results for quantitative comparisons that were often neglected. The IDL-based routine developed in this study (Figure 3) will be useful for many users of OMI retrievals. I suggest the authors to share this routine with potential users through the GMD journal.”***

We thank the reviewer. We will include the IDL routines of “conservative spatial regridding” and “downscaling” of OMI and CMAQ NO<sub>2</sub> VCDs in the supplementary materials with brief descriptions. Users will be able to download and test sample codes, and further modify the codes for their own interest.

***“\* Page 8457, Figure 4: An interpolation routine should be applied to make plots in Figure 4 from Figure 3. I suggest the authors to explain this part. It would be helpful if the names of cities in the text are given on the map.”***

Thanks for the comment. We have included city names on the NO<sub>2</sub> VCD spatial plots.

In order to convert irregular-shaped satellite data into model grid, we use a conservative spatial regridding technique based on polygon clipping algorithms instead of traditional interpolation method. We have included descriptions of the method below. More detailed descriptions can be found in Kim et al. (2013).

Regridding of model output or satellite data with different map projection settings is very important for inter-comparisons of modeled results and/or satellite outputs. Spatial regridding is a commonly performed procedure in satellite data processing. It converts a data set between different map projections and resolutions. Among numerous spatial regridding methods, interpolation and pixel aggregation are two of the most common methods. Interpolation is preferred when the target domain resolution is finer than the raw data pixels, on the other hand, pixel aggregation is the preferred way to average all the pixels inside each domain cell when the grid cell size is bigger than the raw data pixel size. Despite their popularity, both methodologies for interpolation and aggregation have numerical limitation especially in dealing with fine resolution data and/or where conservation of measured quantities is required. More mathematically complete methods for spatial regridding is to handle the geospatial data (e.g. satellite data) as “polygon with area” instead of “(dimensionless) pixels”. It requires the calculation of fractional areas of overlapping polygons between raw data pixels and modeling grid cells.

The IDL-based Geospatial Data Processor can provide exact fractions using the polygon clipping algorithm, and this information can be used for lossless (zero-loss) spatial regridding in the conservative remapping method. This method reconstructs raw data pixels (e.g. satellite data) into target domain grid cells, by calculating fractional weighting of each overlapping portions between data pixels and domain grid cells. If the raw pixel data is in density units (e.g. concentration) we can calculate the overlapping fractions for each data pixel and grid cell. The grid cell concentration can be calculated as a weighted average of data pixels and fractions. (Fig. R1)

$$f_{i,j} = \frac{Area(P_i \cap C_j)}{Area(C_j)}$$

$$C_j = \frac{\sum P_i \cdot f_{i,j}}{\sum f_{i,j}}$$

where  $i$  and  $j$  are indices of data pixel,  $P$ , and grid cells,  $C$ .  $f_{i,j}$  is the overlapping fractions, and  $\sum f_{i,j}=1$  if no missing pixels are involved in grid cell  $C_j$ .

If the satellite pixel data is in mass units, equations for the conservative remapping are slightly different. We need to calculate fractions of overlapped area to raw data pixel size, instead of grid cell size.

$$g_{i,j} = \frac{Area(P_i \cap C_j)}{Area(P_j)}$$

$$C_j = \sum P_i \cdot g_{i,j}$$

where  $g_{i,j}$  is the fraction of overlapped area to the data pixel size.

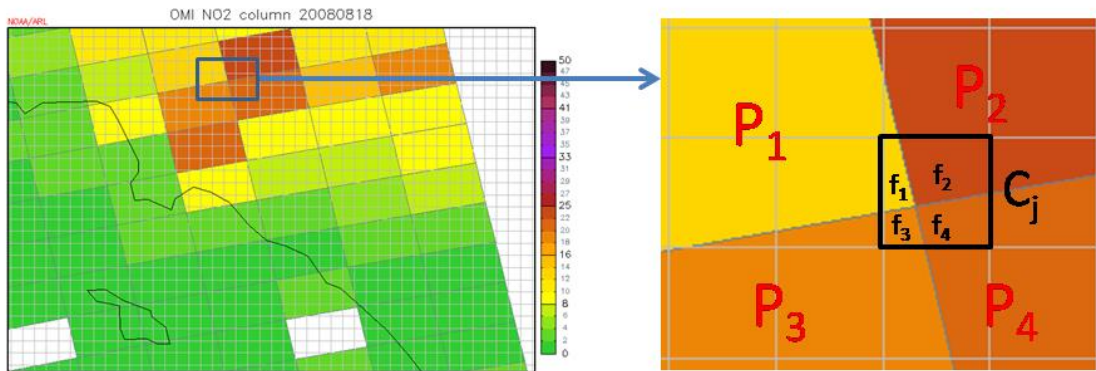


Figure R1. Example of "Conservative spatial regridding" method using variable-pixel linear reconstruction algorithm

***“\* Page 8459, line 17-19: I think the emission problems are large and that certainly affect the spatial distribution of the plumes. In addition to wind errors, the impact of emission inventory errors from various sectors can be large (see Figures 8 and 10 in the manuscript). Potential problems stemming from this error source need to be written clearly. And which emission inventory was utilized for the model simulations? This may determine the limit of the methodology developed in this study.”***

Thanks for the comment. We agree that emission information plays a crucial role in the technique described in this study. We have included the descriptions for emission used in the model run. Detailed information on the emission data is also described in (Pan et al., 2014).

We have clarified the limitations of current downscaling technique. Further investigations on the technique using different emission data, different meteorology and/or chemistry model are being conducted, but the results are not included in the current draft yet.

***“\* Page 8460: I think it is best to show the comparison results for other days (May 7, May 16 etc.) and discuss the causes for agreement or disagreement. Was P3 data averaged for comparison with OMI data (at a model resolution)? Was averaging kernel applied to P3 data?”***

Thanks for the comment. Figure 6 already includes measurements from all three days (May 4<sup>th</sup>, 7<sup>th</sup> & 16<sup>th</sup> 2010), and we have clarified it. Spatial plots of the original and adjusted OMI NO<sub>2</sub> VCDs for all days are shown in the Figure R2. Clear enhancements are shown in May 4<sup>th</sup> & 7<sup>th</sup> when P3 measurements show strong spatial gradient, and the impact is weaker on May 16<sup>th</sup> 2010 when its spatial gradient is smoother (Sunday, less traffic due to weekend effect). Current P3 circles are averaged of OMI pixel's coverage since they were initially prepared for the direct comparison between OMI and P3 NO<sub>2</sub> VCDs (Judd et al., in preparation)

Since observations (e.g. OMI and P3) are column-integrated 2 dimensional data and model has 3 dimensional structures, we applied the averaging kernel information to 3 dimensional model structure and converted the model NO<sub>2</sub> concentration into column data (2 dimensional) format (e.g. NO<sub>2</sub> VCD) for the comparison with observations. OMI and P3 are compared directly.

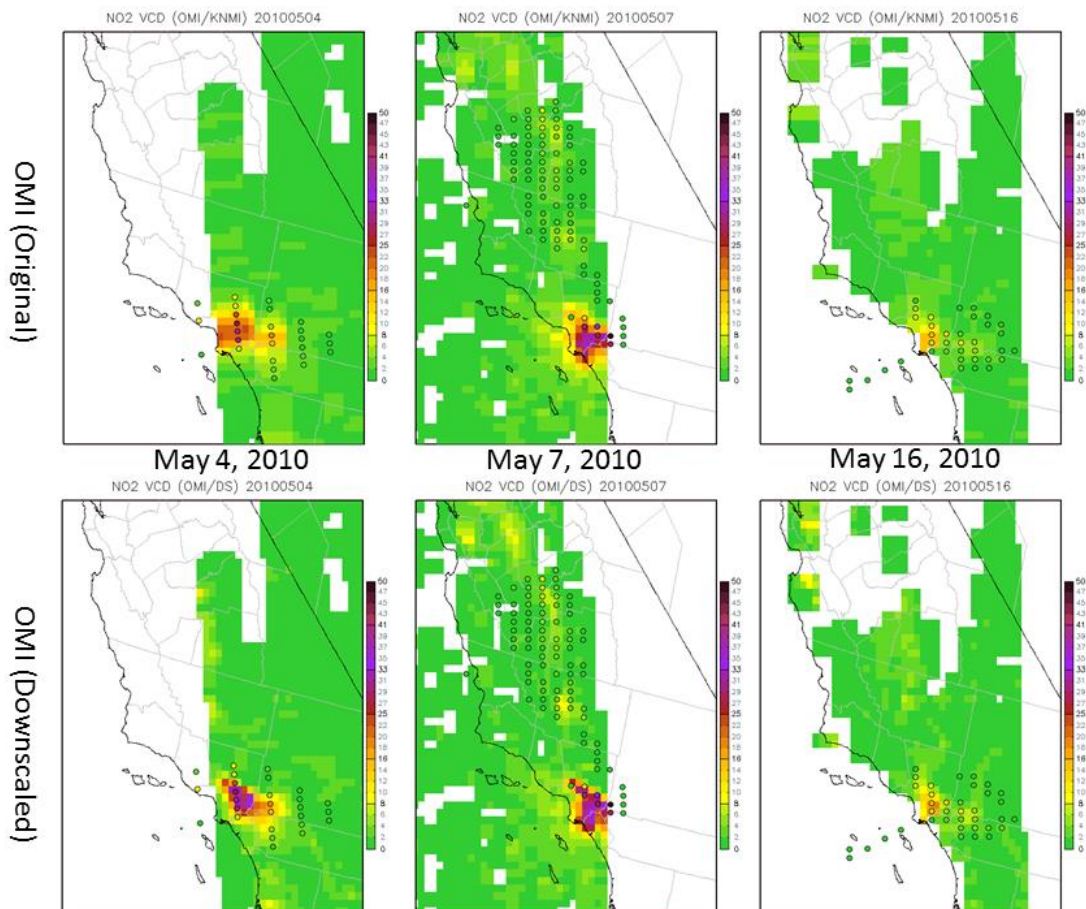


Figure R2. Comparisons of spatial distributions of OMI and P3 NO<sub>2</sub> VCDs for May 4<sup>th</sup>, 7<sup>th</sup>, & 15<sup>th</sup>, 2010.

***“\* Page 8462: For Figure 9, the period of analysis needs to be given in the main text. The results in this manuscript are based on a short-term analysis. Please mention this clearly in the many plots and analyses in the manuscript. Explain the differences in Figure 9d. Which points show large discrepancies between the OMI data and the model results in Figure 9d?”***

Thanks for the comment. We have included that Figure 9 is for a one month period of September 2013. In addition, we like to note that we have tested all months in 2013 & 2014 and results are mostly consistent.

Since this study mainly focuses on the uncertainty of satellite to model comparison due to spatial resolution differences between satellite footprint pixels and model grid cells, we did not emphasize on the implication of the comparison. However, we notice that the comparison in this draft shows general agreement with previously research. For urban locations (e.g. higher NO<sub>2</sub> VCD values), the trend of continuous NO<sub>x</sub> emissions reduction, especially from the mobile sources, might be the main reason of the overestimated CMAQ NO<sub>2</sub> VCDs. On the other hand, the underestimation of CMAQ NO<sub>2</sub> VCDs in the rural areas (e.g. lower NO<sub>2</sub> VCD points) might be attributed to the lack of natural NO<sub>x</sub> emission sources in the current modeling system, especially the soil NO<sub>x</sub> emissions. It also should be noted the rural NO<sub>2</sub>

