

1 **Summary of edits to ‘The location of the thermodynamic**
2 **atmosphere-ice interface in fully-coupled models’ in**
3 **response to reviews and comments**

4 **Alex West, 17th February 2016**

5 This document describes the main edits to the initial discussion paper, and the reasoning
6 behind these. The document is structured in three sections:

- 7 a) The reviews of Dirk Notz (DN) and Anton Beljaars (AB), with inline responses, as
8 available on the GMD Discussion page
- 9 b) A full description of the changes carried out to the paper in light of the reviews and
10 comments, with reasons;
- 11 c) A copy of the revised document with changes relative to the original fully-tracked.

12 It should be noted that it was necessary to convert the manuscript to the new Copernicus
13 Word template before submitting the revised manuscript.

14

15 ***a) Reviewers’ comments and responses***

16 In each case, the comment is shown in italic, with inline reply as normal font. In the cases
17 that the reply was given without quoting the initial comment, the inline version is a
18 paraphrasing of the original.

19

20 **Astrid Kergman (AK) comment with reply paraphrased inline**

21 *Dear authors,*

22 *In my role as Executive editor of GMD, I would like to bring to your attention our Editorial*
23 *version 1.1:*

24 *<http://www.geosci-model-dev.net/8/3487/2015/gmd-8-3487-2015.html>*

1 *This highlights some requirements of papers published in GMD, which is also available on*
2 *the GMD website in the 'Manuscript Types' section:*

3 *http://www.geoscientific-model-development.net/submission/manuscript_types.html*

4 *In particular, please note that for your paper, the following requirements have not been met*
5 *in the Discussions paper:*

6 • *"The main paper must give the model name and version number (or other unique identifier)*
7 *in the title."*

8 Thanks for your comment. After having read the guidelines you mention, I think that our
9 paper comes under the heading of 'Development and technical papers'. I do not think that it
10 would be appropriate to mention HadGEM3 in the heading as our paper is an idealised case
11 study with a toy model built from two very small components of the submodels CICE (for sea
12 ice) and JULES (for surface exchange). We have not tested the two coupling methods with
13 the fully-coupled HadGEM3 because it would not be practical to do so (as mentioned in
14 Section 5).

15 Therefore I suggest that in the final revised version, the title should be amended to the
16 following for clarity:

17 "The location of the thermodynamic atmosphere-ice interface in fully-coupled models: a case
18 study with CICE and JULES"

19 I am not sure that a version number for either component would be meaningful or helpful for
20 this purpose, as they are not being used in their original form.

21 • *"All papers must include a section, at the end of the paper, entitled 'Code availability'.*
22 *Here, either instructions for obtaining the code, or the reasons why the code is not available*
23 *should be clearly stated. It is preferred for the code to be uploaded as a supplement or to be*
24 *made available at a data repository with an associated DOI (digital object identifier) for the*
25 *exact model version described in the paper. Alternatively, for established models, there may*
26 *be an existing means of accessing the code through a particular system. In this case, there*
27 *must exist a means of permanently accessing the precise model version described in the*
28 *paper. In some cases, authors may prefer to put models on their own website, or to act as a*
29 *point of contact for obtaining the code. Given the impermanence of websites and email*
30 *addresses, this is not encouraged, and authors should consider improving the availability*

1 *with a more permanent arrangement. After the paper is accepted the model archive should be*
2 *updated to include a link to the GMD paper."*

3 The code for the toy model used can easily be made available in its full form as a supplement,
4 along with code used in producing the plots

5 *It is not fully clear to me, if you used HadGEM to produce your results or if you just used 2*
6 *component models also included in HadGEM. If fitting I suggest to change the title to "The*
7 *location of the thermodynamic atmosphere-ice interface in fully-coupled models: a case study*
8 *with HadGEM3".*

9 *Additionally, the 'Code Availability' section at the end of the article is missing.*

10 *Please correct these items in your revised submission to GMD.*

11 *Yours,*

12 *Astrid Kerkweg*

13

14 **Dirk Notz (DN) review with reply paraphrased inline**

15 *In this short study, the authors examine how the two most widely used methods for*
16 *thermodynamically coupling the sea-ice surface to an atmosphere model affect simulation*
17 *results. They find that a tight coupling of the sea-ice surface to the atmospheric state*
18 *significantly improves the simulation as opposed to a setup where the ice surface is only*
19 *loosely tied to the atmosphere state at each coupling time step.*

20 *I find this study relevant, well written and easy to follow and recommend publication with*
21 *very minor revision, which should address the following few items:*

22 *p.9710, l.9: The coupling across the interface could be implicit, too, if the entire sea-ice*
23 *temperature field is updated by the atmosphere solver. This is for example sometimes done in*
24 *land models for the calculation of soil-temperature profiles, based on the description by*
25 *Richtmyer and Morton (1967). The coupling of Winton's model in GFDL behaves like an*
26 *implicit scheme, too (Winton, A reformulated three layer model, 2000)*

27 Yes, this is a good point, and as you say is how GFDL manage the problem. But I think that
28 in the framework described in this paper, this would be equivalent to choosing the
29 atmosphere-ice model interface to lie immediately above the base of the sea ice. The

1 coupling across this interface would still be explicit, but this would matter less if the sea ice
2 base was assumed to be at the ocean freezing temperature. And the thermodynamics above
3 the interface – i.e. throughout the atmosphere and ice – would be implicit.

4 A sentence will be added to the paragraph in question to note this possibility in the final
5 version.

6 *p.9711, Eq. (1): kappa is usually used for heat diffusivity, while heat conductivity is denoted*
7 *by k. ($\kappa = k/(\rho c)$). I suggest following this standard for clarity.*

8 *p.9714, l.6: This sounds as if the surface temperature directly controls incoming shortwave*
9 *and incoming longwave, which is not the case. It might help to make more explicit that the*
10 *entire atmospheric state is affected by surface temperature, which then indirectly affects the*
11 *incoming fluxes.*

12 *p.9716, l.17: It'd be helpful to briefly discuss how an *increased* amplitude at the*
13 *surface can cause a *decreased* amplitude further down in the ice.*

14 *p.9716, l.23: I could not identify any solid grey lines.*

15 This was probably not very clearly worded. The lines in question do not plot any particular
16 quantity – they are vertical, and are placed at 3h intervals to indicate exchange of coupling
17 variables, corresponding to the major tick marks. I think they are clearly visible on the figure,
18 but I notice now that these have been incorrectly placed for Figures 2 and 4, where they
19 should be at 1h intervals – this will be corrected.

20 The reference in the text could be amended to ‘vertical solid grey lines’.

21 *p.9721, l.9ff: The CICE documentation suggests that "accuracy may be significantly reduced"*
22 *by placing the interface below the surface. It'd be helpful to here briefly explain as to why the*
23 *present study reaches a different conclusion. In that context, it might also be helpful to briefly*
24 *discuss other model setups, in particular forced ocean-model simulations. While this*
25 *obviously goes beyond the current focus on "fully-coupled models", this study provides*
26 *helpful context for such discussion.*

27 placing the interface below the surface...”

28 This suggestion from the CICE documentation (Section 2 introduction, final paragraph)
29 appears to relate to the theoretical necessity of reducing the conductivity of the top layer to
30 aid convergence in the case of thin ice (when the ‘JULES’ method might become unstable).

1 It is true that if it became necessary to do this, the results of the study would no longer hold.
2 But in practice, we find that setting a minimum ice thickness of 20cm is sufficient to ensure
3 stability in our coupled model, as mentioned at the end of Section 5, so this situation would
4 not arise.

5 The stability analysis of the Appendix describes how instability arises not in the limit of thin
6 ice, but rather in the limit of strong turbulent heat flux coupling (e.g. during storms), for an
7 'intermediate' band of ice thicknesses. Very thin ice appears to be unconditionally stable,
8 precisely because disturbances to the top conductive flux are able to propagate downwards
9 very quickly, meaning the temperature gradient is always very close to linear.

10 It should also be noted that in situations when large, rapid changes in conductive flux cause
11 convergence failures in the thermodynamic solver, reducing the effective conductivity by
12 itself does not help, as on short timescales it has no effect whatsoever on the top conductive
13 flux forcing the ice, which is calculated in the atmosphere model. One problem we came up
14 against while implementing this method in our coupled model, with multilayer CICE, was
15 that in cases of slow convergence CICE was prone to reducing the effective conductivity
16 without limit; this had no effect on the strong top conductive flux, and served only to
17 decouple the top layer from the layers below, rendering it actually more vulnerable to
18 instability.

19 In the final paragraph of Section 5, when the stability, and minimum ice thickness are
20 mentioned, a reference to the suggestion in the CICE documentation will be added, with an
21 explanation as to why it is not necessary to use it in this case.

22 – *Some typos etc. I spotted:*

23 *p.9709, l.20: I recommend putting "(HadGEM3)" after "Centre" in the following line*

24 *l.26: no comma after "calculated"*

25 *p.9714, l.4: Not clear what "this difficulty" refers to, no real difficulty was mentioned*

26 *before.*

27 *p.9716, l.26: Something is wrong with "our 'truth' the 'CICE' method"*

28 *p.9720, l.25: "T_{atmos}"*

29

1 **Anton Beljaars (AB) review and inline reply**

2 Dear Anton,

3 Thank you for your review. I will list our response to your comments, and suggested edits,
4 below.

5 *This paper explores two thermal coupling methods between an atmospheric model and a sea
6 ice model. The paper is a welcome contribution to literature for a few reasons: (i) the paper
7 describes a well known scientific/technical issue, (ii) a sensible testing and evaluation
8 procedure is described, and (iii) it is good to have this work in open literature because often it
9 ends up in obscure technical reports only. The topic is also highly suitable as a contribution
10 to the discussion on atmosphere to surface coupling.*

11 *Coupling through turbulent diffusion in the atmosphere and thermal diffusion in the surface
12 has a few facets: (1) Numerical stability, (2) Conservation, (3) Code modularity, and (4)
13 Accuracy. Numerical accuracy is obviously the highest priority; without stability, there is no
14 solution. Conservation (of energy) is my view also a high priority, because it is a basic
15 physical property of the coupled system. Often (also in the current paper, I think), it is
16 sacrificed to code modularity. Code modularity is obviously important; without it, code
17 becomes unmanageable. Finally, numerical accuracy is important of course, but given the
18 uncertainty in processes and diffusion coefficients, it may not be the highest priority, although
19 it is good to separate numerical errors from parametrisation errors.*

20 In fact, the system described in Sections 1 and 2 is fully energy-conserving, regardless of
21 which coupling method is used. It is true that the separation of atmospheric and ice
22 thermodynamic processes, and the consequent delay in response of the two systems, results in
23 a less accurate simulation of the surface flux, which passes energy from the atmosphere to the
24 ice, and vice versa. But this does not imply a lack of energy conservation. The amount of
25 energy lost by the atmosphere will be equal to that received by the ice, and vice versa, even
26 though that amount will not in itself be exactly the same as that which would have been
27 passed in reality.

28 *>> Although I am quite familiar with atmosphere / surface coupling issues, it took me
29 multiple readings to understand how the two coupling methods work. In fact coupling only
30 becomes an issue due to the combination of long time steps requiring implicit solvers in both
31 atmosphere and sea ice and the technical separation of the atmospheric and sea ice codes.*

1 *Ideally, one would solve the atmospheric turbulent diffusion and the sea ice diffusion*
2 *equations simultaneously in a fully implicit and coupled way. Some models follow this route*
3 *but it is often thought that it requires full integration of the sea ice and atmospheric codes.*
4 *However, it would be possible to define a proper interface to exchange information between*
5 *the two models. The information to exchange is a linear relation between temperature and*
6 *heat flux from both the atmospheric and sea ice models. Such relations can be obtained from*
7 *the downward elimination sweep of the tridiagonal solver of the atmospheric diffusion*
8 *problem and the upward elimination sweep of the sea ice problem. In future, I feel that*
9 *models should aim for this, not only for stability but also for conservation.*

10 Thank you for describing this – it was interesting to hear how an implicit coupling scheme
11 between atmosphere and ice might work. Martin Best explained your idea further. It looks as
12 if it might work well for coupling between the atmosphere and land, but because it requires
13 the exchange of information mid-timestep would not work, in the current framework, for
14 coupling between atmosphere and ice. I have added a brief description of this method to the
15 introduction, with an explanation as to why it was not thought an option for us.

16 *In addition, the issue of snow on top of ice is not discussed, although it has a big impact on*
17 *the heat transport into the ice layer. It also has a big impact on the diurnal cycle of*
18 *temperature (when the sun is above the horizon), which can be seen from ice buoy data.*

19 This was a good point. We have now repeated the experiment with a snow layer, and under
20 another alternative condition. The final revised version will describe these experiments in a
21 new subsection, 4.3. Although all variations of the experiment have the effect of increasing
22 the surface flux error of the ‘JULES’ method relative to that of the ‘CICE’ method, the
23 ‘JULES’ errors are still substantially smaller in magnitude.

24 *A few suggestions to improve the manuscript:*

25 *1. Please consider the points above; some of them may be worth discussing in the*
26 *introduction.*

27 *2. The main difficulty with the manuscript is the interpretation of the results. It is*
28 *concluded that the flux coupling below the surface is best, but what is the reason. In the*
29 *simple configuration that is tested (sensible heat flux from the atmosphere matches the heat*
30 *flux into the ice), the diffusion problem from atmosphere to ice is just a continuous diffusion*
31 *problem in which the diffusion coefficients vary. So why does it matter whether to shift the*

1 coupling level by one layer? I can see three possible reasons: (i) There is a jump of diffusion
2 coefficients near the surface that makes one method of coupling better than the other? (ii)
3 Deeper coupling is always better because more fast responding layers are included in the
4 atmospheric problem (where the diurnal forcing is)? (iii) The coupling below the surface
5 avoids the derivative of fluxes with respect to surface temperature (which causes non-
6 conservation; cf. eq. 10), i.e. it is the conservation that improves the accuracy? It would be
7 nice to discuss the possible reasons for the advantage of one coupling method over the other.

8 The reason is closest to (ii) – the forcing comes from above, not from below (as is mostly the
9 case in reality) and therefore the simulation benefits from a larger proportion of the system
10 being in the atmosphere. An explanation has been added to the discussion section for the
11 final revised version.

12 3. p.9712 l.9 The expression for K_k is not correct; it has a different dimension than in in
13 equation (9). It appears that K_k is scaled with the layer thickness, but not in equation (9).

14 Yes – equation (9) was written wrongly. The denominator h_k^2 should just be h_k .

15 4. p.9712 eq. (10) It is commented that equation (10) is an approximation because of the non-
16 linearity of the outgoing long wave radiation. However, if F_o^* is updated after each
17 iteration the equation could be exact? Below eq. (10), the iteration procedure is described.
18 Is it correct that the result is fully implicit in the sense that also the diffusion
19 coefficients correspond to the new time level? At the end of the iteration with full
20 convergence, T^{m+1} should be the same as T^* , so I do not see a reason that conservation is
21 compromised? Is it because for this way of coupling, the atmosphere does not use the same
22 surface temperature as the ice model? Please explain.

23 This was probably not written very clearly. In fact equation (10), which is part of the CICE
24 thermodynamic solver, is iterated, along with the rest of the solver, until an accurate energy-
25 conserving solution is achieved. The iteration is carried out for two reasons: (i) because of
26 the nonlinear dependence of outgoing longwave on surface temperature, and (ii) because the
27 specific heat capacity of the ice itself varies with temperature.

28 In fact, conductivities (or diffusion coefficients) are not updated with each iteration, contrary
29 to what was stated in the discussion paper. This is because conductivity carries no direct
30 implications for energy conservation – it only affects how much energy is passed from one
31 layer to the next. This paragraph has been rewritten for the final revised version.

1 5. p. 9713 l.19-22 *The solution method for equation (11) is explained here in a single*
2 *sentence, which is difficult to digest. It is not clear how JULES computes transfer*
3 *coefficients. Does it need the Richard number as input (i.e. temperature difference and wind)*
4 *or does it need fluxes? The sentence suggests that it uses temperature first and then fluxes?*

5 JULES actually calculates the surface energy balance over sea ice in exactly the same way as
6 it computes it over land, as described in Best et al (2011). The temperature of the top layer of
7 sea ice is analogous to the temperature of the top soil layer; the conductivity of sea ice plays
8 the same role as the conductivity of the soil. This paragraph has been clarified.

9

10 ***b) Description and explanation of manuscript changes***

11 **Additional analysis carried out for this revision**

12 In the review of Anton Beljaars, it was suggested that it would be useful to examine the
13 performance of the two coupling methods with a snow layer added to the ice in the 1D model.
14 The authors considered this to be a good idea; the solver was modified, and the experiments
15 were repeated.

16 However, in the course of this, two additional issues were discovered: (a) that when the wind
17 speed was varied (as in the stability experiments of the Appendix), the results altered
18 noticeably; (b) that instead of the HadGEM3-like ‘parallel’ coupling framework, the solver
19 had been configured for the more common, and more accurate ‘serial’ coupling framework; a
20 ‘parallel’ version of the solver again produced noticeably different results, although without
21 changing the overall conclusion of the study. (For an explanation of the ‘serial’ and ‘parallel’
22 terms, see Section 4.4 of the revised version).

23 In the light of these results, and to provide as comprehensive and accurate as possible an
24 account of the performance of the two coupling methods under different conditions, Section 4
25 was reconfigured to allow these to be discussed. It was decided that the basic analysis of
26 Sections 4.1 and 4.2 would not be altered to focus on parallel rather than serial coupling; as
27 long as the experiments were clearly described as such, the results would probably be more
28 useful to the community in this form, as the parallel coupling framework introduces its own,

1 separate, inaccuracies. Instead, Section 2.3 was reworked slightly, in order that it clearly
2 described the two coupling methods in the ‘serial’ framework.

3 A new section, 4.3, was then added, to discuss the results of adding a snow layer (the original
4 analysis requested by Anton Beljaars), and that of changing the wind speed. While both
5 modifications have the effect of degrading the ‘JULES’ simulation relative to the ‘CICE
6 simulation’, the surface flux errors are still considerably lower in the ‘JULES’ simulation, and
7 the conclusion is not altered.

8 Finally, Section 4.4 was added to discuss the serial versus parallel coupling issue; the precise
9 difference between the two frameworks was described, and the way in which the results
10 changed when parallel coupling was employed was discussed. Again the result is a
11 degradation of the ‘JULES’ simulation relative to the ‘CICE’ one; but the surface flux errors
12 are still smaller in the former case.

13 Substantial changes were also made to the figures to accommodate the new analysis. The
14 original Figure 6, a schematic demonstrating ease of transfer of information between
15 variables, was removed, as it was considered that this was the least necessary figure. It was
16 replaced with a new Figure 6 demonstrating the performance of the two coupling methods in
17 simulating surface flux and top layer temperature in the ‘perturbed parameter’ experiments,
18 and in the ‘parallel framework’ experiments (along with the original experiment which is
19 shown as a control). The appropriate panels of this figure are referenced from Sections 4.3
20 and 4.4. Finally, a schematic demonstrating the difference between serial and parallel
21 coupling was added as Figure 7, referenced from Section 4.4.

22

23 **Major changes to existing sections**

- 24
- 25 • In response to requests from the two reviewers, two other possible methods of
26 resolving the ‘surface variables’ issue were described in Section 1; that of solving the
27 entire ice column in the atmosphere model (Dirk Notz), and that of enabling the
28 atmosphere-ice coupler to pass surface exchange coefficients mid-timestep, thereby
allowing the coupling to be implicit (Anton Beljaars).

- 1 • In Section 2.1, the description of the CICE thermodynamic solver, particularly in
2 relation to the surface energy balance, was substantially reworked.
- 3 • In Section 2.3, besides the modifications related to ‘serial coupling’ mentioned above,
4 the sentence describing how fluxes are passed in the 3D model HadGEM3 was
5 extended, to better set the description in context.
- 6 • In Section 3.2, the likely reasons for the differing effects of decreased vertical
7 resolution on surface temperature and top-layer temperature were discussed.
- 8 • In Section 5, a discussion of the likely reasons for the better simulation of the ‘JULES’
9 method in the basic case was added; this additional paragraph then continues, in order
10 to discuss the results of the additional sections, 4.3 and 4.4. Later in Section 5, the
11 discussion of the implications of the results for 3D modelling is extended to discuss
12 the implications of the perturbed parameter experiments.

13

14 **Minor changes to existing sections**

15 A number of other corrections and clarifications have been made to the document, each of
16 which can be seen in the ‘tracked changes’ version below. Most of these are in response to
17 reviewers (and are set out in the original responses), however a few are in addition to these.

- 18 • Title: ‘A case study using JULES and CICE’ was added to the title as requested by
19 AK. Because the 1D solver based on these models had been extensively modified and
20 restructured in the course of building, it was considered that a revision number for
21 either model could not be clearly defined. (It should also be noted that all of the code
22 used is attached to the revised version as supplementary material).
- 23 • Abstract: A sentence referring to the new ‘perturbed parameter’ experiments has been
24 added.
- 25 • Section 1, paragraph 3: DN rewording accepted
- 26 • Section 1, paragraph 6: document description amended to include reference to the
27 additional analysis

- 1 • Section 2.1 equations 1 and 2: κ changed to k , as in DN's suggestion.
- 2 • Section 2.1 equation 9: h_k^2 changed to h_k ; as AB noted this equation as stated was
3 incorrect.
- 4 • Section 2.1, paragraph following equation 9: on the RHS of the expression, K is
5 changed to k for consistency with previous equations.
- 6 • Section 2.1, final paragraph: sentence modified to reflect the fact that a snow layer is
7 being investigated later on.
- 8 • Section 2.2, paragraph 2; explanatory sentence added to JULES surface energy
9 balance solver description, in response to AB's 5th query. As the solver is described in
10 detail in Best et al, already referenced, it was thought that a more detailed description
11 was not necessary. Further reasoning can be seen in our response to AB.
- 12 • Section 2.3, paragraph 1: 'difficulty' altered to 'redundancy', as DN had suggested
13 this wording was problematic. It is hoped that the new wording reflects more clearly
14 what has gone before.
- 15 • Section 3.2, paragraph 3: It was noticed that the phase shift in the decreased vertical
16 resolution had been incorrectly described here, as a 'lag' rather than a 'lead'; this has
17 been corrected, and does not affect the subsequent discussion.
- 18 • Section 3.2, paragraph 4: 'solid grey lines' changed to 'vertical solid grey lines' in
19 response to DN's comment.
- 20 • Section 4.1, paragraph 3: It was noted, in light of the subsequent experiments, that
21 initially wind speed was set to 5 m/s.
- 22 • Section 4.2.1, paragraph 3: 'our truth' deleted (DN comment); also some formatting
23 corrected for variables in the following sentences.
- 24 • Section 4.2.2, paragraph 3: Figure 6 reference removed, as this figure has been
25 replaced.

- 1 • Section 5, paragraph 4: The Met Office model has been renamed ‘HadGEM3-GC3’ to
2 specify the version at which multilayer CICE will be implemented.
- 3 • Section 5, paragraph 5: ‘sensitive heat flux’ corrected to ‘sensible heat flux’.
- 4 • Author contribution: Updated to reflect additional analysis.
- 5 • Code availability: Section added as requested by AK
- 6 • Acknowledgements: Updated to include reviewers, and slightly reworded.
- 7 • Figures: Figure 2 and Figure 4 have been edited in order that the solid grey vertical
8 lines fall at 1 hour intervals, rather than 3 hour, to reflect accurately the coupling
9 period length in their relevant experiments.
- 10
- 11

1 ***c) Tracked-changes version of revised document***

2
3
4 **The location of the thermodynamic atmosphere-ice**
5 **interface in fully-coupled models – a case study using**
6 **JULES and CICE**
7

8 **A. E. West¹, A. J. McLaren¹, H. T. Hewitt¹, M. J. Best¹**

9 [1]{Met Office Hadley Centre, Exeter, Devon}

10 Correspondence to: A. E. West (alex.west@metoffice.gov.uk)

11
12 **Abstract**

13 In fully-coupled climate models, it is now normal to include a sea ice component with
14 multiple layers, each having their own temperature. When coupling this component to an
15 atmosphere model, it is more common for surface variables to be calculated in the sea ice
16 component of the model, the equivalent of placing an interface immediately above the
17 surface. This study uses a one-dimensional (1D) version of the Los Alamos sea ice model
18 (CICE) thermodynamic solver and the Met Office atmospheric surface exchange solver
19 (JULES) to compare this method with that of allowing the surface variables to be calculated
20 instead in the atmosphere, the equivalent of placing an interface immediately below the
21 surface.

22 The model is forced with a sensible heat flux derived from a sinusoidally varying near-surface
23 air temperature. The two coupling methods are tested first with a 1-h coupling frequency, and
24 then a 3-h coupling frequency, both commonly-used. With an above-surface interface, the
25 resulting surface temperature and flux cycles contain large phase and amplitude errors, as well
26 as having a very 'blocky' shape. The simulation of both quantities is greatly improved when
27 the interface is instead placed within the top ice layer, allowing surface variables to be

1 calculated on the shorter timescale of the atmosphere. There is also an unexpected slight
2 improvement in the simulation of the top-layer ice temperature by the ice model. [The surface](#)
3 [flux improvement remains when a snow layer is added to the ice, and when the wind speed is](#)
4 [increased.](#) The study concludes with a discussion of the implications of these results to three-
5 dimensional modelling. An appendix examines the stability of the alternative method of
6 coupling under various physically realistic scenarios.

7 **1 Introduction**

8 Sea ice has long been recognised as an important component of the climate system, and all
9 climate models taking part in the CMIP5 project now include a sea ice component. Much
10 progress has been made in sea ice modelling since the 1970s. Maykut and Untersteiner (1971)
11 derived governing equations of sea ice thermodynamics, with temperature and salinity-
12 dependent heat capacity and conductivity, and allowing for a snow layer above the ice.
13 Semtner (1975) devised a simple numerical model of sea ice thermodynamics based on a
14 simplification of the Maykut and Untersteiner equations, designed for incorporation in
15 coupled climate models. An appendix to Semtner's study detailed an even simpler model in
16 which the ice had no heat capacity at all, the so-called 'zero-layer' method. The simulation of
17 the spatial coverage of sea ice by even this highly simplified model was found to be
18 reasonably accurate; for example, Johns et al. (2006) and Gordon et al. (2000) describe the
19 sea ice simulations of HadGEM1 and HadCM3 respectively, both coupled models
20 incorporating this scheme. Hence this method became the basis of the thermodynamics of
21 many sea ice models, with its low computational costs.

22 As computing power increases, however, the multi-layer model of Semtner is becoming the
23 more commonly-used version. In particular, the Los Alamos sea ice model CICE (Hunke et
24 al., 2013), which is the focus of the present study, bases its thermodynamics on a more
25 complex multi-layer discretisation of the Maykut and Untersteiner equations, as updated by
26 Bitz and Lipscomb (1999), with heat capacity and conductivity fully dependent on salinity
27 and temperature.

28 Currently, the configuration of models used for climate projections (~~HadGEM3~~) at the Met
29 Office Hadley Centre ([HadGEM3](#)) uses the zero-layer version of CICE (Hewitt et al, 2011).
30 The present study arose out of a desire to couple the multi-layer version of CICE to the Met
31 Office atmosphere model, the Unified Model (UM) (Walters et al., 2011), and in particular its
32 surface exchange scheme JULES (Best et al., 2011). Both CICE and JULES perform

1 integrations using a forwards-implicit timestepping method, with much greater stability than
2 would be associated with an explicit calculation; in CICE new ice temperatures are calculated,
3 based on future values of temperature, conductivity, and heat capacity, while in JULES
4 surface temperature and fluxes are calculated, based on future values of the surface exchange
5 coefficients. CICE calculates temperatures for each of the individual ice layers, and the ice
6 surface; JULES calculates all surface variables. Hence a conflict arises when trying to couple
7 the two components; each 'wants' to calculate the surface variables itself, but in practice only
8 one must be allowed to do so, as two different values of surface variables would be associated
9 with two subsequently different model evolutions.

10 At the root of the problem is that whereas in physical reality the ice and atmospheric
11 temperatures are intimately related, and vary in one system, in the model an explicit interface
12 must be placed between them. Ideally one would solve implicitly for the whole ice and
13 atmosphere column, but in practice while the two systems are separately implicit, the
14 coupling across the interface must be explicit. CICE assumes the interface to lie above the ice
15 surface; the JULES surface exchange scheme assumes it to lie below the ice surface. (Note
16 that the same problem does not arise for the ice and ocean systems, because the base of the ice
17 is at present always assumed to be at the freezing point of seawater).

18 One possible solution is to place the entire ice column within the atmospheric thermodynamic
19 solver, equivalent to locating the thermodynamic interface at the base of the ice, but this
20 approach would necessitate passing a very large number of fields between the two models,
21 and has been deemed impractical at the Met Office. It is also, in theory, possible to design an
22 implicit scheme for atmosphere and ice in which the two thermodynamic solvers are in
23 different code bases, but in this case it is necessary to pass information between the two
24 components at an instant while the solvers are calculating new temperatures. This would
25 require coupling every atmospheric timestep, which would be too computationally expensive.

26 The purpose of this study is to examine the two coupling methods under idealised conditions,
27 using a one-dimensional version of the CICE temperature solver, and a miniature version of
28 the JULES surface exchange scheme, under realistic timestep lengths, coupling period
29 lengths, and vertical resolutions, and in particular to determine which gives the more accurate
30 simulation. In section 2, the CICE thermodynamic solver and the JULES surface energy
31 balance solver are described in more detail, along with the two coupling methods. In section
32 3, the performance of the CICE temperature solver is examined using its own coupling

1 method, under varying vertical and temporal resolutions. In section 4, the CICE and JULES
 2 components are run together using the two different coupling methods, under a variety of
 3 different conditions, and the results compared. Finally, in section 5 we discuss the results,
 4 and their applicability to fully-coupled models. In the Appendix, the stability of the
 5 alternative coupling method under the limits of physically realistic conditions is examined.

6

7 **2 Description of the models and experiments**

8 **2.1 The models: CICE**

9 The fundamental equation solved by the CICE temperature solver is the heat diffusion
 10 equation:

$$11 \quad \rho c_p(S, T) \frac{\partial T}{\partial t} = \frac{\partial}{\partial z} \left(\kappa(S, T) \frac{\partial T}{\partial z} \right) \quad \underline{\underline{\rho c_p(S, T) \frac{\partial T}{\partial t} = \frac{\partial}{\partial z} \left(k(S, T) \frac{\partial T}{\partial z} \right)}} \quad (1)$$

12

13 where ρ , c_p , S , T , t , z , and ~~κ~~ k denote ice density, heat capacity, salinity, temperature, time,
 14 depth and conductivity respectively. CICE includes an additional term representing
 15 penetrating solar radiation, which we neglect for the purposes of this study. Conductivity and
 16 heat capacity are parametrised as

$$17 \quad \kappa(S, T) = K_0 + \frac{\beta S}{T} \quad (2)$$

$$18 \quad k(S, T) = K_0 + \frac{\beta S}{T} \quad (2)$$

19 where

$$20 \quad K_0 = 2.03 \text{ W m}^{-1} \text{ K}^{-1} \quad (3)$$

21 and

$$22 \quad \beta = 0.13 \text{ W m}^{-1} \quad (4)$$

23 after Untersteiner (1964) and

$$24 \quad c_p = c_{p0} + \frac{L_0 \mu S}{T^2} \quad (5)$$

1 where

$$2 \quad c_{p0} = 2106 \text{ J kg}^{-1} \text{ K}^{-1}, \quad (6)$$

$$3 \quad L_0 = 3.354 \times 10 \text{ J kg}^{-1} \quad (7)$$

4 and

$$5 \quad \mu = 0.054 \text{ K}. \quad (8)$$

6 after Ono (1967), respectively.

7 The heat diffusion equation is discretised by splitting the ice into N layers of thickness h_i , and
8 using finite timestepping in the usual way. To ensure stability, temperatures are updated
9 using variables from the next timestep, the so-called ‘implicit’ method:

$$10 \quad \rho_k c_{pk} \frac{T_k^{m+1} - T_k^m}{\Delta t} = \frac{1}{h_k^2} [K_k (T_{k-1}^{m+1} - T_k^{m+1}) - K_{k+1} (T_k^{m+1} - T_{k+1}^{m+1})] \quad (9)$$

$$11 \quad \rho_k c_{pk} \frac{T_k^{m+1} - T_k^m}{\Delta t} = \frac{1}{h_k} [K_k (T_{k-1}^{m+1} - T_k^{m+1}) - K_{k+1} (T_k^{m+1} - T_{k+1}^{m+1})] \quad (9)$$

12 where the subscripts m and k denote timestep number and vertical layer number respectively,

13 and $K_k = \frac{2K_{k-1}K_k}{K_{k-1}h_k + K_k h_{k-1}}$ is the ‘effective conductivity’ at the interface

14 between layers k and $k-1$.

15 There is an additional equation for the change in surface temperature, T_{sf} :

$$16 \quad F_0^* + \left(\frac{dF_0}{dT_{sf}} \right) (T_{sf}^{m+1} - T_{sf}^*) = K_1 (T_{sf}^{m+1} - T_1^{m+1}) \quad (10)$$

17 Here, F_0^* represents the sum of radiative, sensible and latent heat fluxes arriving at the ice
18 surface from above; in the absence of melting this is equal to $F_{condtop}$, the conductive flux
19 travelling downwards into the ice.

20 In this way a linear system of equations for the new layer temperatures (plus the surface
21 temperature) is created, $\mathbf{A}T_{new} = \mathbf{R}$, where \mathbf{A} is a tridiagonal matrix and T_{new} is the vector of
22 new layer temperatures. The parameter c_{pk} depends itself upon the layer temperature, T_k^m ; in
23 addition. Equation (10) is an approximation, as in reality upwelling longwave radiation has a

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1 nonlinear dependence on surface temperature. *Because of these factors, it is necessary to*
 2 *iterate the linear solver, updating outgoing longwave radiation, F and c_p at each iteration, to*
 3 *achieve an accurate and energy-conserving solution. (Note that although k also depends upon*
 4 *T , as this variable carries no direct implications for energy conservation it is not updated at*
 5 *each iteration.) CICE allows up to 100 iterations, although generally fewer than 10 will*
 6 *suffice to reduce the energy imbalance to acceptable levels. Hence, in equation 10, s*
 7 variables represent variables from the preceding iteration.

8 ~~In this way a linear system of equations for the new layer temperatures (plus the surface~~
 9 ~~temperature) is created, $\mathbf{A}T_{new} = \mathbf{R}$, where \mathbf{A} is a tridiagonal matrix and T_{new} is the vector of~~
 10 ~~new layer temperatures. Because the parameters c_p and K depend themselves upon the ice~~
 11 ~~temperature, and because of the linear approximation in the surface equation, it is necessary to~~
 12 ~~repeat the linear solver, updating outgoing longwave radiation, c_p and K at each iteration, to~~
 13 ~~achieve an accurate and energy-conserving solution. CICE allows up to 100 iterations,~~
 14 ~~although in general fewer than 10 will suffice to reduce the energy imbalance to acceptable~~
 15 ~~levels.~~

16 It should be noted that CICE also allows for the presence of a snow layer on top of the ice,
 17 which introduces an extra row into the matrix equation, with accordingly different heat
 18 capacity and conductivity. For this study, however, we assume *initially that* no snow is
 19 present.

21 2.2 The models: JULES

22 The principal function of the surface-exchange scheme JULES is to solve the surface energy
 23 balance equation, in which a surface temperature is calculated such that incoming fluxes of
 24 shortwave and longwave radiation are in balance with outgoing turbulent, radiative and
 25 conductive fluxes:

$$26 \quad (1 - \alpha)SW_{in} + LW_{in} - \epsilon\sigma T_{sfc}^4 + F_{sens}(T_{sfc}, T_{air}) + F_{lat}(T_{sfc}, T_{air}, q_{air}) = k_{eff}(T_{sfc} - T_{ice}) + F_{melt} \quad (11)$$

27 In this equation SW_{in} , LW_{in} refer to the incoming shortwave and longwave fluxes respectively;
 28 F_{sens} and F_{lat} to the net inward sensible and latent heat fluxes respectively; T_{sfc} , T_{air} and T_{ice} to
 29 surface temperature, lowest-layer air temperature and uppermost layer ice temperature
 30 respectively, q_{air} to lowest layer air specific humidity, k_{eff} to effective conductivity of the top
 31 ice layer, α to surface albedo and F_{melt} to the sea ice melt flux. JULES solves this equation by

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1 first calculating a 'first guess' explicit solution, calculating fluxes and surface temperature
2 based on surface temperature at the previous timestep, and then calculating an implicit
3 updated solution, in which the exchange coefficients are modified by considering the initial
4 solution. JULES computes surface exchange coefficients over sea ice using the same method
5 as is used over land, as described in Section 2.1 of Best et al (2011). Because the surface
6 temperature simulation carries no implications for energy conservation, the calculation is not
7 iterated.

9 **2.3 The coupling methods and experiments**

10 In their standard formulations, both the CICE thermodynamic solver and the JULES surface
11 exchange solver calculate surface variables. The two coupling methods under investigation
12 arise from opposite methods of resolving this difficultyredundancy.

13 In the standard 'CICE' coupling method (Figure 1a), the atmosphere, or surface exchange
14 scheme, calculates fluxes of incoming shortwave and longwave radiation based on the
15 evolving atmospheric state whose lower boundary condition is the ice surface temperature
16 from the previous coupling instant, The atmosphere then averages these over the coupling
17 period, and passes them to CICE at the end of thate period. CICE then uses these incoming
18 fluxes throughout the samenext coupling period in the first row of the tridiagonal matrix
19 equation the row concerning the surface temperature (equation 10), each time iterating the
20 solver until convergence is achieved. In the process, CICE computes the remaining surface
21 fluxes (outgoing radiative, turbulent and conductive fluxes) and hence the net surface flux.
22 This approach is equivalent to placing an interface between JULES and CICE immediately
23 above the ice surface.

24 In the alternative, 'JULES' coupling method under investigation (Figure 1b), the surface
25 temperature is a prognostic variable of the atmosphere or surface exchange model, and is not
26 passed from CICE; instead, the temperature and effective conductivity (the latter defined as
27 $\frac{2K_1}{h_1}$) of the top ice layer are passed at each coupling instant. The surface exchange scheme
28 calculates an updated surface temperature, along with radiative fluxes, turbulent fluxes,
29 surface ice melt, and downward conductive flux into the top layer of ice from the surface, in a
30 fully implicit boundary layer solution, given these lower boundary conditions. The downward
31 conductive flux and ice melt flux are averaged over a coupling period and passed to CICE for

1 use in the same coupling period. CICE proceeds to solve the tridiagonal matrix occasion in
 2 the normal way, except that the top row of the equation is removed; the downwards
 3 conductive flux provided by the surface exchange scheme is then used as forcing for the top
 4 ice layer. At the end of the coupling period, the new temperature and effective conductivity
 5 of the top ice layer are passed back to the atmosphere. This approach is equivalent to placing
 6 an interface between JULES and CICE immediately below the ice surface.

7 It should also be noted that in HadGEM3, ~~the two models run in parallel, with variables~~
 8 ~~exchanged in each direction at every coupling instant; also, that in the 'JULES' coupling~~
 9 ~~method,~~ fluxes are always passed as gridbox means, to ensure conservation. This point only
 10 becomes relevant in 3D modelling, where sea ice may cover only part of a grid cell; in this
 11 case, the relevant flux is multiplied by the grid cell ice concentration before being passed to
 12 the coupler for regridding. This is necessary because of the parallel coupling of HadGEM3
 13 (see Section 4.4); underlying ice concentration may change during a coupling period, and
 14 hence the amount of energy being passed must be correctly represented by multiplying,
 15 effectively, by the area over which it is valid.

17 3 Testing the impact of varying resolution on an idealised solver

18 3.1 Setup

19 In this experiment, the penetrating solar radiation term was ignored, and the ice was assumed
 20 to be fresh, in order that the conductivity and specific heat capacity are constant. The ice was
 21 assumed to be 1m thick, and there is no snow cover. The diffusion equation was forced at the
 22 top of the ice by a sinusoidally varying heat flux:

$$23 F_{sf} = A \operatorname{Re}(\exp i \omega t) \quad (12)$$

24 There exists an exact analytical solution to the diffusion equation with this surface forcing, for
 25 an infinitely deep ice cover (after Best et al, 2005):

$$26 T = T_B + \frac{A}{\sqrt{\rho c \omega \kappa}} \operatorname{Re} \left(\exp \frac{-z}{l} \exp i \left(\frac{-z}{l} + \omega t - \frac{\pi}{4} \right) \right) \quad (13)$$

27 Where $T \rightarrow T_B$ as $z \rightarrow \infty$. $l = \sqrt{\frac{2\kappa}{\rho c \omega}}$ is the e-folding depth.

1 This analytical solution was compared to the solution from the CICE temperature solver
2 under 6 different conditions, summarised in Table 1. In these experiments, the timestep
3 length, coupling period length and vertical resolution were varied, from extremely low values
4 designed to give results as close as possible to 'truth', to higher values considered to be
5 typical of coupled model experiments.

6 **3.2 Results**

7 Figure 2 displays the simulation of two key variables by the temperature solver: the surface
8 temperature, and the temperature at a depth of .125m (roughly analogous to the top layer
9 temperature in standard CICE, which uses 4 vertical layers). It is clear that under very high
10 temporal and vertical resolution, CICE produces a simulation that is virtually
11 indistinguishable from the analytic solution. As one would expect, when these resolutions are
12 reduced to more realistic levels inaccuracies appear.

13 When the timestep length is increased to 1 hour (but the high vertical resolution is
14 maintained), there is a slight increase in the error of the surface temperature simulation, which
15 is still very small in proportion to the cycle amplitude. For the .125m temperature, a small
16 phase lead of around 30 minutes is introduced, and the amplitude is reduced by a tiny amount
17 (0.02°C); the diurnal cycle of .125m temperature error has an amplitude of about 0.03°C .

18 The effect of decreasing the vertical resolution is more marked. For the surface temperature,
19 we see a large phase lead introduced, of 90 minutes, but also a marked increase in
20 amplitude, from 1.2 to 1.5°C ; this results in some comparatively high errors, of up to 0.6°C .

21 On the other hand, the diurnal cycle of .125m temperature is reduced in amplitude slightly,
22 and has a lower phase shift of about 1 hour. The errors have magnitude of up to 0.09°C .

23 The contrasting effects of the decreased vertical resolution on surface and top layer
24 temperature can be understood by considering that the surface temperature is forced by the air
25 temperature, and damped by the ice temperature. A top ice layer of thickness 1cm can warm
26 or cool more easily for a given forcing than can a top ice layer of thickness 25cm; therefore,
27 when the entire top 25cm of ice has to vary in unison, the amplitude of its cycle is reduced,
28 and its damping effect on the surface temperature is correspondingly reduced, which can
29 hence vary more strongly in response to the air temperature forcing.

30 Lastly, we look at the effects of moving to a 3-hour coupling period, with timestep length
31 maintained at 1 hour (Figure 3). It is apparent that this change has little effect on the phase or

1 amplitude of the surface temperature simulation, and only serves to make the diurnal cycle
2 more 'jagged'; at each coupling period, indicated by the vertical solid grey lines, the surface
3 temperature jumps by a large amount, and over the following two (non-coupling) timesteps,
4 moves backwards by a smaller amount as the sea ice adjusts towards a new equilibrium.

5 The error in the 4-layer experiment should give cause for concern, as this is a fairly realistic
6 resolution for most implementations of CICE in coupled models. In the next section,
7 therefore, we compare the simulations at realistic resolution, using the two different coupling
8 methods.

9

10 **4 Comparing the two coupling methods under realistic resolution**

11 **4.1 Setup**

12 For this experiment, the solver was run under 6 different setups. Firstly, two 'control'
13 experiments were undertaken, in which the ice, atmosphere and coupling timesteps were each
14 1 second. In the first control, the ice was given 100 layers, to provide a 'truth' against which
15 to compare subsequent experiments; in the second control, the ice was given 4 layers, to
16 separate the effects of high timestep values from the effects of low vertical resolution. The
17 two control experiments were run using the 'CICE' coupling method, with the surface
18 variables calculated by the ice model, but at these timestep values the coupling method has
19 negligible impact on the simulation.

20 The solver was then run with 4 vertical layers, an ice timestep of 1 hour, atmosphere timestep
21 20 minutes, and coupling period of 1 hour, fairly realistic values for a coupled model, using
22 the two different coupling methods, 'CICE' and 'JULES'. A further two experiments were
23 then performed, using a coupling period of 3 hours, also a common period found in coupled
24 model runs.

25 The solver was forced with incoming sensible heat flux only, driven by a diurnal cycle of
26 atmospheric surface temperature $T_{atmos} = A_T \exp i \omega t$, with wind speed set to 5 m/s. For the
27 'CICE' coupling, T_{atmos} is averaged over a coupling period and passed to the ice model,
28 which calculates from this the incoming sensible heat flux, and uses this as forcing for the
29 temperature solver to calculate internal and surface ice temperatures. For the 'JULES'
30 coupling, a self-contained 'atmosphere model' uses T_{atmos} and T_I (top-layer ice temperature)
31 to implicitly calculate surface fluxes, including $F_{condtop}$, downwards conductive flux,

1 accumulates and averages this over the coupling period and passes it to the ice model as
2 forcing for the solver.

3

4 **4.2 Results**

5 **4.2.1 1-h coupling**

6 Figure 4 displays the simulation of key variables by the high-resolution control runs and by
7 the test runs, using a 1-hour coupling period length. The forcing atmospheric temperature is
8 indicated in Figure 4a. First examining the surface flux (Figure 4b), we compare the two
9 control runs and note that the decrease in vertical resolution is associated with a slight
10 decrease in amplitude and a phase lag. We then see that when the ‘JULES’ coupling method
11 is used, there is little further error associated with the decrease in temporal resolution (blue
12 line). When the ‘CICE’ coupling method is used, however, there is an additional phase lag
13 and amplitude decrease, and in addition the diurnal cycle becomes more jagged.

14 Interpreting these results, it is likely that the additional phase lag is a consequence of the
15 atmosphere model ‘seeing’ a surface flux calculated in the previous CICE coupling period,
16 which is itself based on an atmospheric temperature valid for the period before that, up to 2
17 hours previously. With the ‘JULES’ method, however, the surface flux is able to respond
18 immediately to the changing atmospheric temperature. There is a corresponding delay in the
19 atmosphere model ‘sensing’ the damping response of the top layer ice temperature to the
20 changing surface flux. However, the resulting phase lead is tiny in comparison to the phase
21 lag of the ‘CICE’ method.

22 We now consider the atmosphere model surface temperature (Figure 4c). In this variable, a
23 decreasing vertical resolution is associated with an increase in amplitude and a phase lead.
24 Again, using the ‘JULES’ method, a decreasing temporal resolution makes little difference,
25 causing a tiny phase lag and a slightly less smooth shape compared to the 4-layer control.
26 Using the ‘CICE’ method produces a much more blocky shape, and a substantial phase lag.
27 However, as the 4-layer control itself has a phase lead relative to the high-resolution control,
28 ~~our ‘truth’~~ the ‘CICE’ method actually has a more accurate phase; the temporal and vertical
29 errors ‘cancel’, while the ‘JULES’ method maintains a phase lead.

30 How the ice model ‘sees’ the surface temperature is demonstrated in Figure 4d. The diurnal
31 cycle is very similar to that of the atmosphere model surface temperature for the two control

1 runs, due to their low timestep length. The ice model does not have knowledge of the surface
2 temperature in the 'JULES' coupling method and this line is not plotted. The surface
3 temperature simulation in the 'CICE' method is very similar to the control; the phase lag
4 experienced by the atmosphere model is due to the coupling delay only.

5 Conversely, Figure 4e demonstrates how the atmosphere model 'sees' the top layer
6 temperature, in the 4-layer control and in the 'JULES' coupling method (as in the 'CICE'
7 method the atmosphere has no knowledge of this variable). There is a slight phase lag
8 relative to the control, and associated jaggedness of the diurnal cycle, owing to the need to
9 hold the temperature constant over each coupling period, rather than update it every
10 atmospheric timestep.

11 The lower panels (Figure 4f and 4g) compare the internal ice temperatures at .125m (top
12 layer) and .625m (third layer) depth in the four experiments. For both variables, the decrease
13 in vertical resolution is characterised by a decrease in amplitude and a phase lead which are
14 both more severe in the deeper variable. The decrease in timestep length produces additional
15 amplitude decrease and phase lead which are very similar in the two coupling methods. It is
16 interesting to note that the errors are marginally smaller for the 'JULES' method. This is
17 likely due to the fact that in the 'JULES' method, changes in T_{atmos} can propagate quickly
18 downwards to changes to f_{surf} on the 20-minute atmospheric timestep, the main bottleneck
19 occurring in the coupling, as f_{surf} forces changes in T_I on the slower 1-hour coupling period.
20 In contrast, in the 'CICE' method, each link in the chain – from T_{air} , to T_{sfc} and $f_{condtop}$, to T_I –
21 must communicate on a slow 1-hour timestep. In consequence, the 'JULES' method
22 simulation is slightly closer to that of the 4-layer control.

23

24 **4.2.2 3-h coupling**

25 The results of the experiments when 3-hour coupling is used are shown in Figure 5. For the
26 surface flux (Figure 5b), again, decreasing temporal resolution is identified with a small phase
27 lag and amplitude decrease in the 'JULES' method; the simulation is very similar to that with
28 the 1-hour coupling period, although slightly less smooth. For the 'CICE' method, however,
29 the phase lag and amplitude decrease are greatly magnified; the peak of the diurnal cycle
30 occurs 2-3 hours too late, and the cycle has a very discontinuous shape.

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1 Considering the surface temperature (Figure 5c), the 'JULES' method again produces a
2 simulation with a 3-hour coupling period which is quite similar to that with the 1- hour
3 period, though less smooth. Again the effect of the 'CICE' method is to produce a phase lag.
4 Whereas in the 1-hour coupling period case, however, this phase lag almost exactly cancelled
5 the lead of the increased vertical resolution, in the 3-hour case the lead is much greater, and
6 the absolute phase error of the method is actually greater than that of the 'JULES' method, in
7 an interesting demonstration of the dangers of cancelling errors.

8 When considering the ice variables (Figure 5f and 5g) there are again few clear differences
9 between the simulations, but again the error is marginally smaller for the 'JULES' method
10 than for the 'CICE' method. Again this is likely related to the 'chain' by which changes
11 propagate from T_{atmos} , via T_{sfc} and f_{surf} to T_I . The 'JULES' method involves a 'fast' link, on
12 the 20-minute atmospheric timestep, from T_{atmos} to T_{sfc} and f_{surf} , and a 'very slow' link, on the
13 3-hour coupling timestep, from f_{surf} to T_I . By contrast, the 'CICE' method involves a 'very
14 slow' link, on the 3-hour coupling timestep, from T_{atmos} to T_{sfc} and f_{surf} , and a 'slow' link, on
15 the 1-hour CICE timestep, from T_{sfc} to T_I . While the rate of propagation is for both methods
16 dominated by the 3-hour coupling 'bottleneck', therefore, changes in T_{atmos} are still able to
17 propagate slightly more quickly with the 'JULES' method. ~~This is demonstrated~~
18 ~~schematically in Figure 6.~~

19 In summary, the deterioration in simulation of the atmospheric variables that is associated
20 with decreased temporal resolution is significantly reduced by using the 'JULES' coupling
21 method. There is also a small improvement in the simulation of the ice variables, although
22 this is very marginal.

24 4.3 Varying the parameters of the experiment

25 To gain some idea of the generality of the results, the parameters of the experiment were
26 varied. Firstly, the coupling methods were tested with an 11cm snow layer present above the
27 ice. Secondly, they were tested without a snow layer, but with the wind speed increased from
28 5 m/s to 20 m/s, to examine the impact of strengthening the coupling between the forcing air
29 temperature and the surface.

30 The results are presented in Figure 6a-6f, in which for each additional experiment, and for the
31 original experiment, the surface flux and the top layer temperature are plotted. (For the snow

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1 layer experiment, the top layer temperature corresponds to the snow layer temperature; for the
2 other experiments, to the top ice layer temperature). For clarity, only the two ‘control’
3 experiments and the two 3-h coupling experiments are shown.

4 Looking first at the ‘snow layer’ experiment, it can be seen that the surface flux diurnal cycle
5 displays greatly reduced amplitude in all setups (Figure 6a, 6c), a consequence of the extra
6 insulation provided by the snow layer decreasing conduction through the ice. The ‘JULES’
7 method here displays a slight amplitude increase relative to the 4-layer control, a result of the
8 3 hour delay in the atmosphere ‘sensing’ the damping snow layer temperature, and thus
9 allowing the surface flux to overshoot. However, the errors are still far smaller than those of
10 the ‘CICE’ method. The snow layer temperature (Figure 6b, 6d) has a much larger diurnal
11 cycle than does the top ice layer temperature in the original experiment, due to its much lower
12 heat capacity. Relative to the 4-layer control, the ‘JULES’ method overestimates the
13 amplitude, while the ‘CICE’ method underestimates the amplitude, precisely as is the case for
14 the surface flux.

15 Next examining the ‘wind speed’ experiment, in this case the surface flux diurnal cycle
16 (Figure 6e) is greatly increased in magnitude under all setups, as the increased wind speed
17 facilitates heat loss from the surface to the air (and vice versa). Similarly to the snow layer
18 experiment, the ‘JULES’ method develops an anomalously high amplitude, related to the
19 persistent ‘overshoot’ in surface flux during each coupling period. This is because the rate at
20 which the surface flux changes during each coupling period is directly proportional to the
21 wind speed, and is therefore four times greater in this experiment; the overall surface flux
22 amplitude, although larger than in the 5 m/s experiment, does not increase in direct
23 proportion. Hence the overshoot is higher in proportion here. However, the ‘JULES’ method
24 errors are still considerably lower than those of the ‘CICE’ method. For the top layer ice
25 temperature (Figure 6f), both methods produce simulations very close to those of the 4-layer
26 control.

27 28 **4.4 Serial versus parallel coupling**

29 In the experiments described above, the forcing flux being passed from the atmosphere to the
30 ice was used as forcing for the ice model for the same coupling period as that during which it
31 was calculated. This is a framework in which atmosphere and ice models are run in sequence,
32 the so-called ‘serial’ coupling method. While many coupled models function in this way,

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1 some (including HadGEM3) use the alternative ‘parallel’ method, in which atmosphere and
2 ice models are run concurrently. This entails that the atmosphere-to-ice forcing flux is used
3 instead as forcing for the ice during the coupling period after that in which it was calculated.
4 The serial and parallel frameworks are demonstrated schematically in Figure 7.

5 The parallel method can be more computationally efficient, but is less accurate (as is
6 demonstrated below). The tests of Section 4.1-4.3 were carried out below using the series
7 method, despite HadGEM3 using the parallel method, in order to eliminate the additional
8 source of inaccuracy caused by parallel coupling and therefore enable the results to be more
9 relevant to the wider community. However, it is also useful to compare the relative
10 performance of the ‘CICE’ and ‘JULES’ methods under parallel conditions. The tests were
11 therefore carried out again, with the 1D solver edited to mimic a parallel system, rather than a
12 serial one.

13 The results are shown in Figure 6a-6b (serial coupling) and Figure 6g-6h (parallel coupling)
14 As seen in the sensitivity experiments of Section 4.3, the ‘JULES’ method displays a
15 deterioration in the surface flux simulation relative to the control (series coupling), shown in
16 Figure 6g, with the surface flux ‘overshoot’ again enhanced, and the amplitude increased
17 accordingly, a result of the extra 3 hours of delay in the atmosphere receiving a damping
18 response from the top layer temperature to the original overshoot. The reason that the ‘CICE’
19 method does not display a similar deterioration is that for this method, one of the variables
20 immediately adjacent to the interface (the air temperature), is not free to vary in this
21 experiment, but prescribed, and therefore the atmosphere ‘pays no penalty’ for the delay in
22 receiving the forcing from below – a situation which would not occur in a fully coupled
23 model. The three hour lag introduced to the top layer temperature simulation (Figure 6h) is
24 noticeable in both the ‘JULES’ and ‘CICE’ methods, and incidentally demonstrates,
25 independently of this study, the drawbacks of using parallel coupling as opposed to serial. It
26 should be pointed out however that this drawback is much reduced when 1-h coupling is used;
27 also, that despite the deterioration, the surface flux errors for the ‘JULES’ method are still
28 substantially lower than those of the ‘CICE’ method.

30 **5 Discussion and conclusions**

31 This study has compared, under idealised conditions, the performance of the CICE
32 temperature solver under varying resolutions, and using two different methods of coupling

1 with an atmospheric model. It has been shown that low vertical resolution within the ice can
2 be the source of significant errors in simulating the diurnal cycle. It has been shown that in
3 simulating an idealised diurnal cycle of ice temperatures and surface fluxes, a coupled model
4 in which an atmosphere-ice interface is placed within the ice performs considerably better
5 than one in which an interface is placed at the ice surface, under typical temporal and vertical
6 resolutions; the simulation of surface temperature and surface flux are in general significantly
7 improved, and the simulation of within-ice variables also improves slightly. It is seen that if a
8 thin snow layer is present, or if the wind speed is increased, the 'JULES' method still
9 simulates the surface flux more accurately, although the margin is reduced.

10 What is the reason for the improved simulation obtained by simulating surface variables
11 within the atmosphere model, rather than the ice model? The root cause is probably that in
12 the experiments, as is usually the case in coupled models and in the real world, the principal
13 thermodynamic forcing on the surface, and the ice, comes from above rather than below. Air
14 temperature and radiation conditions usually change more rapidly than do properties of the
15 underlying ocean, and of the sub-surface ice. Therefore it is not surprising that an improved
16 simulation is obtained by placing a higher proportion of the ice-surface system within the
17 atmosphere model, from which the forcing comes. With a thin snow cover present, or with
18 increased windspeed, the improvements offered by the 'JULES' method grow slightly less.
19 The reason is likely that both modifications have the effect, for the 'JULES' method, of
20 increasing the magnitude of the surface flux response during each coupling period relative to
21 the surface flux amplitude, thus allowing the overestimation of the amplitude to be worsened.
22 There is no corresponding deterioration for the 'CICE' method, as here the surface flux does
23 not change during the coupling period. However, the 'JULES' method still produces
24 substantially lower surface flux errors. It can be concluded that although the top layer
25 temperature simulation is not systematically better in either method, the 'JULES' method
26 produces a better surface flux simulation under most circumstances.

27 At first sight, this conclusion appears to disagree with the statement in the introduction to
28 Section 2 of the CICE documentation (Hunke et al. 2013), that 'accuracy may be significantly
29 reduced' by solving for surface temperature in the atmosphere model. However, this
30 statement relates specifically to the hypothetical necessity of artificially reducing effective
31 conductivity to ensure stability in such a situation, rather than the inherent accuracy of the

1 [coupling method. In practice, we have found that reducing effective conductivity is not](#)
2 [necessary \(see Appendix\).](#)

3 This prompts the question: how realistic were the conditions under which the one-dimensional
4 experiments were held, and to what degree would this improvement carry across to the
5 simulation of ice and atmospheric variables in a non-idealised setting? Clearly the best way
6 to answer this question would be to test two coupled models, one using each method.
7 However, the differences between the two setups involve substantial structural changes to all
8 components of the HadGEM3 model, and this option was deemed impractical. Following the
9 results of these experiments, the 'JULES' coupling method is being implemented in the
10 ~~Hadley Centre's coupled model HadGEM3~~ [Met Office HadGEM3-GC3 coupled model](#) for use
11 with CICE's capability for multilayer thermodynamics, and when this becomes operational
12 there will be an opportunity to compare the simulation of processes over sea ice to other fully-
13 coupled models which use CICE with the standard 'CICE' coupling method. It is
14 nevertheless possible to use the insight provided by the idealised experiments to gain some
15 idea of the likely effects of the different coupling methods in a 3-D simulation.

16 The principal effect of the 'CICE' coupling, as opposed to the 'JULES' coupling, is to damp
17 and delay the response of the surface flux (equal in these experiments to the ~~sensitive~~ [sensitive](#) heat
18 flux) to changes in surface air temperature. These changes are applied in the experiments as
19 variations of around 5°C in the course of about 12 hours. Variations in air temperature of this
20 rate and magnitude are common in the Arctic Ocean, although often they occur in response to
21 changes in cloud cover, or the passage of frontal boundaries, rather than to the diurnal cycle
22 (e.g. Persson et al, 2002). Nevertheless, the implication of the 1-D experiments is that a
23 model using the 'CICE' coupling method will simulate a surface flux response that is overly
24 delayed and damped, relative to a model using the 'JULES' coupling. In effect, the coupling
25 between the atmosphere and the underlying sea ice is weaker, and the atmosphere is likely to
26 behave more like an isolated system.

27 The effects of this would be complex. A mild airmass moving over cold sea ice tends to be
28 diabatically cooled at the surface via the surface flux response, while the opposite will occur
29 when a cold airmass moves over less cold sea ice. A delayed and damped surface flux
30 response would tend to reduce the rate of modification of airmasses, allowing them to retain
31 characteristics for longer. A similar effect would be likely to be seen in the event of air
32 temperatures responding to changes in radiative forcing due to cloud cover. Normally, the

1 response of surface flux would likely be to moderate diabatic heating or cooling of air masses
2 due to these radiative effects, by transferring some of this heating or cooling into the sea ice; a
3 delayed, damped response would hinder this modification. In this way, it is possible that
4 anomalous characteristics of neighbouring airmasses would become more exaggerated,
5 relative to the real world, when using the 'CICE' coupling method, with unpredictable
6 consequences for atmospheric dynamics. The perturbed parameter experiments demonstrate
7 that under very windy, stormy conditions, the reverse effect might be seen; the surface flux
8 could respond too quickly, and too strongly, thus allowing airmass modification to take place
9 too quickly.

10 It is seen in Section 4 that the choice of coupling method has little direct impact on the
11 internal sea ice simulation. However, the sea ice simulation will be strongly affected through
12 the atmospheric response described above, whose dynamics will affect advection of warm and
13 cold air over the ice, as well as advection of the ice itself. As the 'JULES' coupling method
14 produces a more realistic surface flux response to changes in air temperature, it appears clear
15 that, all other factors being equal, this coupling method would simulate a more accurate
16 evolution of atmosphere and sea ice.

17 A secondary finding of this study has been that the vertical resolution at the top of the sea ice
18 is of similar importance to the coupling method used in terms of simulating a realistic surface
19 flux, as demonstrated in Figure 4b. In the current configuration of CICE, whereby all layers
20 are equally spaced within the ice, this implies that surface flux response will tend to be
21 stronger, and more realistic, in regions of thin ice. This suggests that the implementation of
22 variably-spaced layers, with higher resolution near the top of the ice, would be a logical
23 objective to pursue subsequently, to further improve surface flux simulation.

24 The main focus of this study has been the accuracy of the two coupling methods; a separate
25 question is their stability. The 'CICE' method of coupling is known to have major problems
26 of instability arising from the explicit interface in the surface exchange, an area where
27 processes occur relatively quickly (e.g. Best et al, 2004). However, the 'JULES' method has
28 its own explicit interface, below the ice surface, and is therefore also likely to become
29 unstable under certain conditions. A detailed analysis of the stability of the 'JULES' method
30 in the one-dimensional case is described in Appendix A. The principal factors affecting
31 stability are found to be ice thickness and wind speed; a prediction from this analysis is that
32 setting a minimum ice thickness of 30cm in a coupled model is sufficient to avoid instability

1 in all situations. In practice, however, in test runs of the coupled model a minimum ice
2 thickness of 20cm has been found to be sufficient to avoid instability. This is probably
3 because in the fully-coupled model, other negative feedbacks are at work in the atmosphere
4 that act to damp oscillations caused by the explicit coupling, and prevent instability.

5 It is planned to follow this paper with a study examining the simulation of sea ice in
6 HadGEM3 resulting from the implementation of multilayer sea ice, using the 'JULES'
7 coupling method.

8

9 **Appendix A: Stability of the 'JULES' method of coupling**

10 In this section, the one-dimensional model is used to investigate the conditions under which
11 the solver becomes unstable, prior to its implementation in the Met Office coupled model.

12 In the stability experiment, the model was run for 5 days; for the first day, the atmospheric
13 temperature was held constant at -20°C, but at the beginning of the second day, the
14 atmospheric temperature was abruptly changed to -15°C; the solver was judged to be stable or
15 unstable according to whether the variables converged to a new solution, and the nature of the
16 convergence was examined. The test was performed under typical modelling conditions of 4
17 ice layers, ice timestep 1 hour, atmospheric timestep 20 minutes, and of coupling period
18 length 3 hours. The initial parameter that was varied was the ice thickness; the test was
19 performed for six different thicknesses of ice: 1m, 20cm, 10cm, 5cm, 1cm and 1mm. In each
20 case, the top layer ice temperature converged to a new solution, the convergence tending to be
21 most rapid for the thinnest ice (Figure A1).

22 From this it appears that under normal modelling conditions, the 'JULES' coupling method is
23 not inherently unstable to sudden perturbations, and tends to be more, rather than less stable,
24 for thin ice. This is perhaps surprising, as it would be thought that thin ice would tend to react
25 more sensitively to perturbations in conductive flux, given its lower thermal inertia.
26 However, counteracting this is the higher effective conductivity of thin ice, meaning that
27 perturbations in top conductive flux will tend to propagate more rapidly through the ice
28 during a coupling period, reducing the resulting change in top layer ice temperature. It also
29 means that as ice thins, the response of the conductive flux comes to dominate the surface
30 energy balance, effectively 'locking' surface temperature to top layer ice temperature, and
31 reducing variation in conductive flux.

1 To examine the reasons for the stability more carefully, we derive theoretical limits on
 2 perturbations to top layer temperature and conductive flux. Given an equilibrium solution to
 3 the coupled system $(F_{eq}, T_{1_eq}, T_{sfc_eq})$, and perturbations around this solution $(\hat{F}, \hat{T}_1, \hat{T}_{sfc})$, it can
 4 be shown from the surface energy balance equation that the perturbation conductive flux
 5 produced by the atmosphere is constrained by the perturbation top layer ice temperature in the
 6 following way:

$$7 \quad |\hat{F}| \leq \frac{k_{eff} OFE}{k_{eff} + OFE} \bullet |\hat{T}_1| \quad (A1)$$

8 where $k_{eff} = 2k_1/h_1$ is the effective conductivity of the top layer and
 9 $OFE = \dot{f}_{sens}(T_{sfc_eq}) + \dot{f}_{lat}(T_{sfc_eq}) + \dot{f}_{rad}(T_{sfc_eq})$ represents the total rate of change of the
 10 surface radiative, sensible and latent heat fluxes with respect to surface temperature at
 11 $T_{sfc} = T_{sfc_eq}$, and tends to reach its highest values under very windy, stormy conditions. It
 12 can be seen that the controlling constant here tends to the finite limit OFE as $h_1 \rightarrow 0$.

13 Meanwhile, in the ice thermodynamic solver, energy balance considerations provide a
 14 constraint on the magnitude of the change in \hat{T}_1 during a coupling period:

$$15 \quad |\Delta T_1| \leq \frac{t_c}{c_p \rho_I h_1} |F| \quad (A2)$$

16 where t_c , c_p , ρ_I and h_I represent coupling period length, ice heat capacity, ice density and top
 17 layer ice thickness respectively. This, together with equation (A1), prevents instability for
 18 $\frac{t_c OFE}{h_1} < c_p \rho_I$. The system is therefore stable for $h_I > 5\text{cm}$ (equivalently total ice thickness
 19 $< 20\text{cm}$) in all but the most extreme atmospheric conditions, and for $h_I > 10\text{cm}$ (equivalently
 20 ice thickness $< 40\text{cm}$) under all realistic atmospheric conditions.

21 However, for thin ice a second constraint becomes important. A dimensional analysis of the
 22 heat diffusion equation for ice shows that with 3 hour coupling, the thermal inertia term can
 23 no longer provide the dominant balance to top conductive flux for ice of layer thickness under
 24 about 10cm, and becomes negligible for ice of layer thickness under about 2cm, causing the
 25 dominant balance in the equation to be between top conductive flux and conduction with the
 26 layer below. In this situation, given a top conductive forcing, the ice temperatures will

1 converge very quickly to a linear temperature profile with uniform conductive flux, meaning
2 that

$$3 \quad |\hat{T}_1| = \frac{h_1}{2k_1} |\hat{F}_1| \quad (A3)$$

4 Combined with equation (A1), this prevents instability completely.

5 In summary, equations (A1), (A2) and (A3) show that instability cannot occur in the limit of
6 very thick ice (when thermal inertia dominates), due to a highly damped response of top layer
7 temperature to perturbations of conductive flux, and also cannot occur in the limit of very thin
8 ice (when conduction to the ocean dominates), due to the surface temperature becoming
9 virtually ‘locked’ to top layer ice temperature, perturbations in conductive flux becoming
10 correspondingly small (i.e. when $k_{eff} \gg OFE$), and these perturbations very easily
11 propagating through the ice to the ocean. It is noticeable that in Figure A1, the least stable
12 solutions appear to occur for intermediate ice thicknesses (5cm, 10cm), when neither
13 conduction nor thermal inertia dominates, but the ‘overlap’ in the two conditions is
14 nevertheless sufficient to allow a relatively rapid convergence.

15 The question arises as to whether the solver would continue to converge for all ice thicknesses
16 were any of the parameters in equations (A1), (A2) or (A3) altered. Parameters c_p , ρ_I and t_c
17 are assumed to be at the lower, lower and upper limits of physical plausibility respectively in
18 equation (2), and to vary them in the opposite direction would serve only to strengthen the
19 limits on convergence. The parameter OFE , however, depends strongly on the rate of change
20 of turbulent fluxes with respect to surface temperature, and therefore on wind speed. In the
21 initial stability experiments, wind speed was set to 5 m/s, a fairly typical value for many
22 synoptic situations. Particularly with the passage of extratropical depressions, however, wind
23 speeds can reach much higher values.

24 The perturbation experiment was repeated, but this time two parameters were varied: ice
25 thickness from 1mm to 1m, and wind speed from 0 m/s to 50 m/s, the upper limit roughly
26 representing the very highest wind speeds possible during extratropical storms. The results
27 are shown in Figure A2. It is seen that the solver is no longer unconditionally stable, with
28 instability setting in at a wind speed of around 23 m/s, at first for a narrow band of ice
29 thicknesses close to 10cm, a band which steadily widens as wind speed increases. At all wind

1 speeds the solver remains stable in the limit of thin ice. However, at the upper limit of wind
2 speed, the solver is unstable for ice thicknesses of between roughly 4cm and 25cm.

3 This result holds for $t_c = 3$ hours, but $t_c = 1$ hour is also a fairly widely used coupling period,
4 and is likely to become more so as computing power increases. The experiment was repeated
5 for $t_c = 1$ hour (Figure A3). In this case, the solver is stable for all ice thicknesses and wind
6 speeds, although at the upper limit of wind speed, convergence is extremely slow for ice
7 thicknesses of around 7cm. (Clearly the second region of slow convergence, to the right of
8 the figure, is not a concern, as this is caused by higher thermal inertia of thick ice, is entirely
9 physically realistic, and will not lead to instability).

10 In summary, it is found that the coupled solver system is stable under all physically realistic
11 situations when 1-hour coupling is used, but may become unstable in very windy conditions
12 when 3-hour coupling is used, for certain values of ice thickness.

13

14 **Author contribution**

15 The 'JULES' method of coupling was originally devised by Martin Best. The one-
16 dimensional experiments of Sections 3 and 4.1 were designed and carried out by Alison
17 McLaren. The perturbation experiments of Section 4.3, the 'parallel coupling' experiments of
18 Section 4.4, and the stability experiments of the Appendix were designed and carried out by
19 Alex West. All results were plotted and analysed by Alex West with advice and assistance
20 from Alison McLaren, Martin Best and Helene Hewitt. The paper was written in its final
21 form by Alex West with input from all three contributing authors.

22

23 **Code availability**

24 All code used in the production of this study is available as a supplement to the article,
25 together with a file giving instructions for its use (README).

26

27 **Acknowledgements**

28 The authors thank to Ann Keen and Ed Blockley for help and advice prior to submission,
29 and also thank Dirk Notz and Anton Beljaars for their insightful reviews.-

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2 Programme (GA01101).
3

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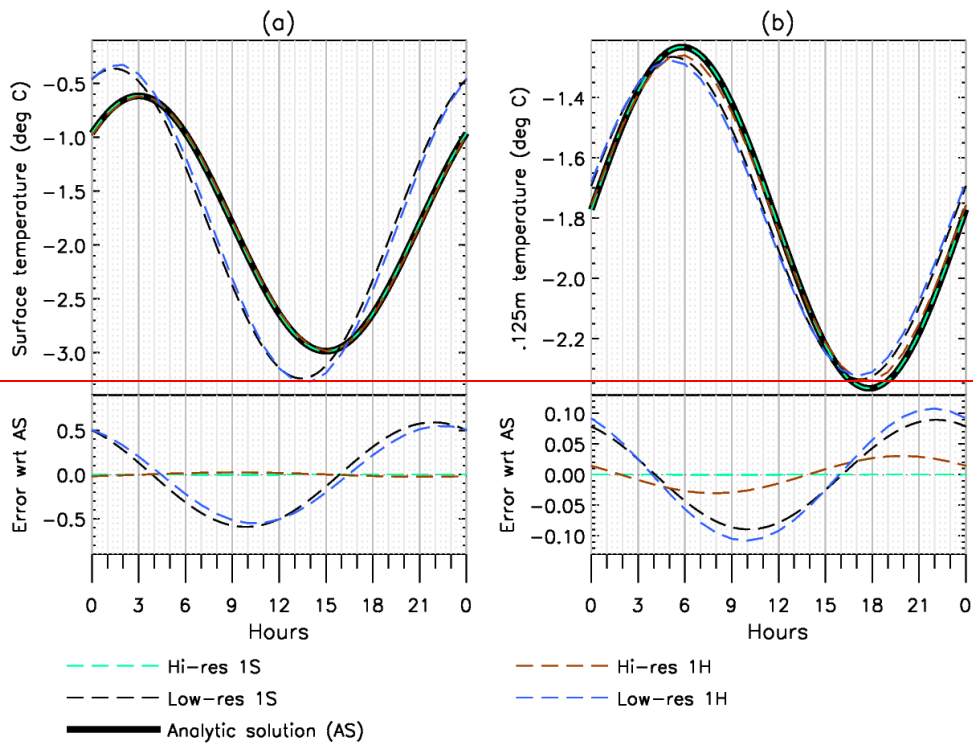
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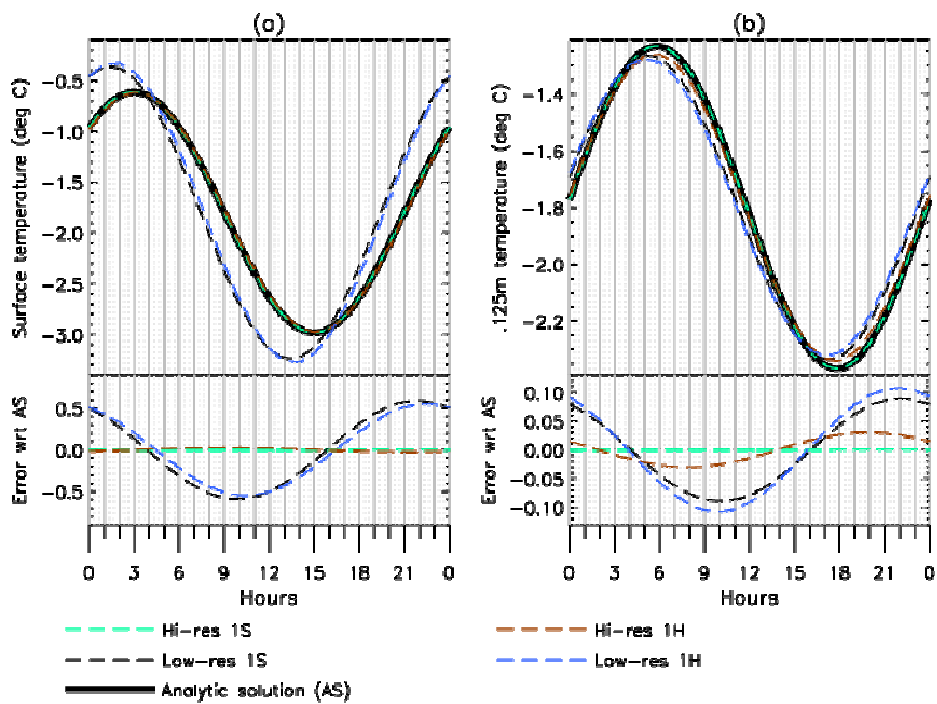
1 Table 1. Initial experiments comparing CICE under 6 different resolutions

Experiment	Vertical resolution	Timestep length	Coupling period length
1 (Hi-res 1S)	1 cm (100 layers)	1 second	1 second
2 (Low-res 1S)	25 cm (4 layers)	1 second	1 second
3 (Hi-res 1H)	1 cm (100 layers)	1 hour	1 hour
4 (Low-res 1H)	25 cm (4 layers)	1 hour	1 hour
5 (Hi-res 3H)	1 cm (100 layers)	1 hour	3 hours
6 (Low-res 3H)	25 cm (4 layers)	1 hour	3 hours

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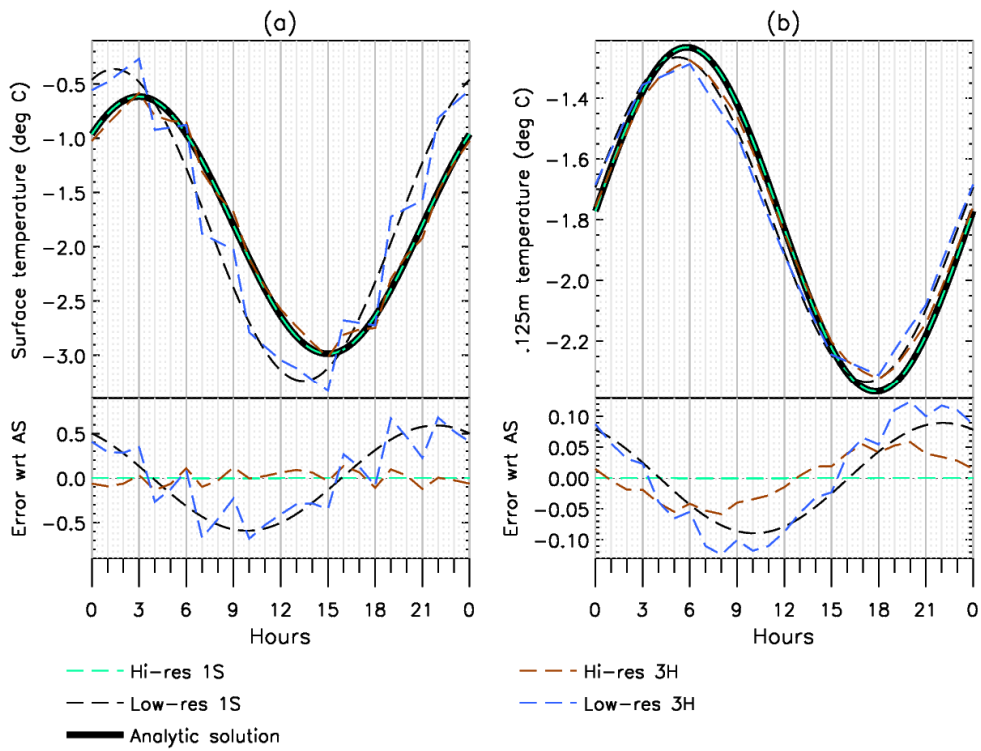


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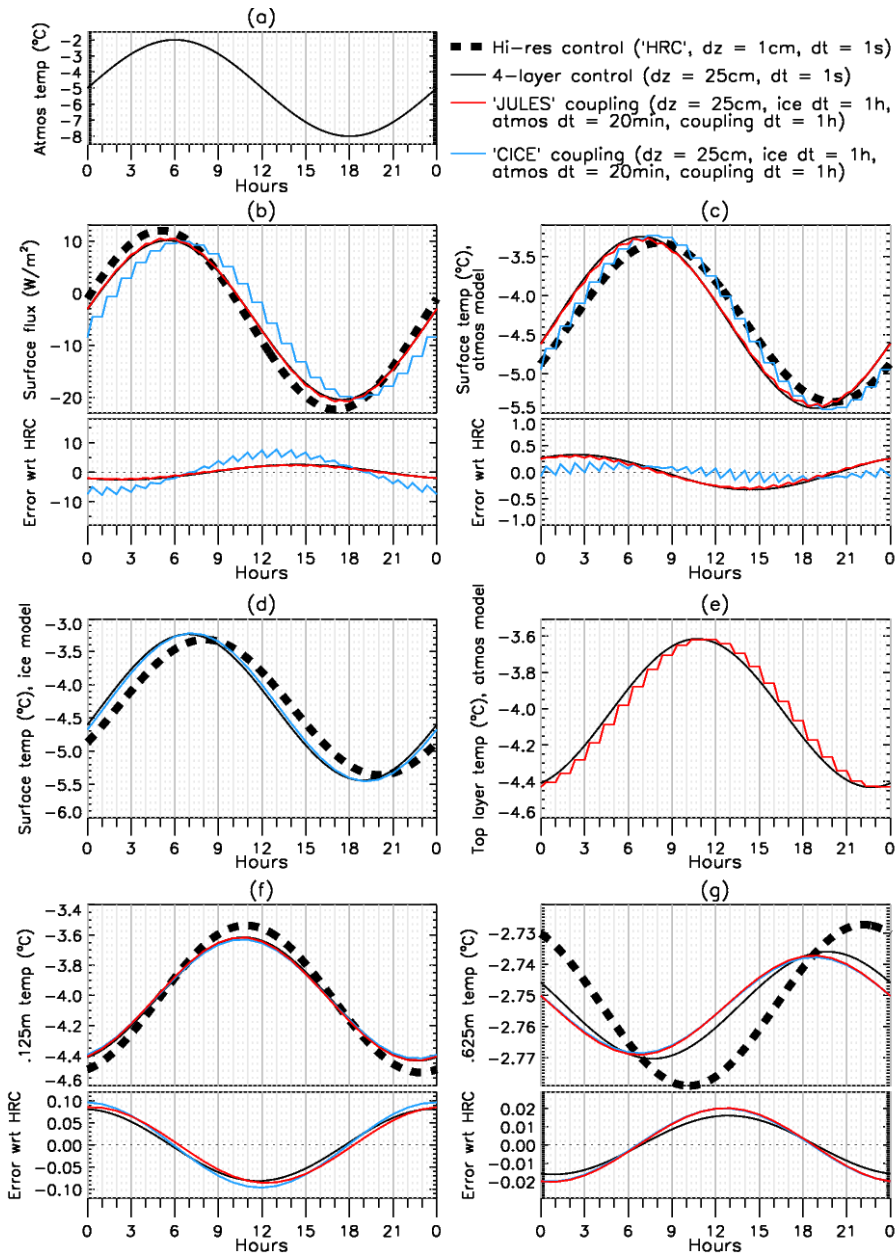
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2 Figure 2. The performance of the CICE temperature solver under varying spatial resolution
3 and timestep length, with coupling period 1 hour. Showing a) surface temperature; b)
4 temperature at .125m depth.
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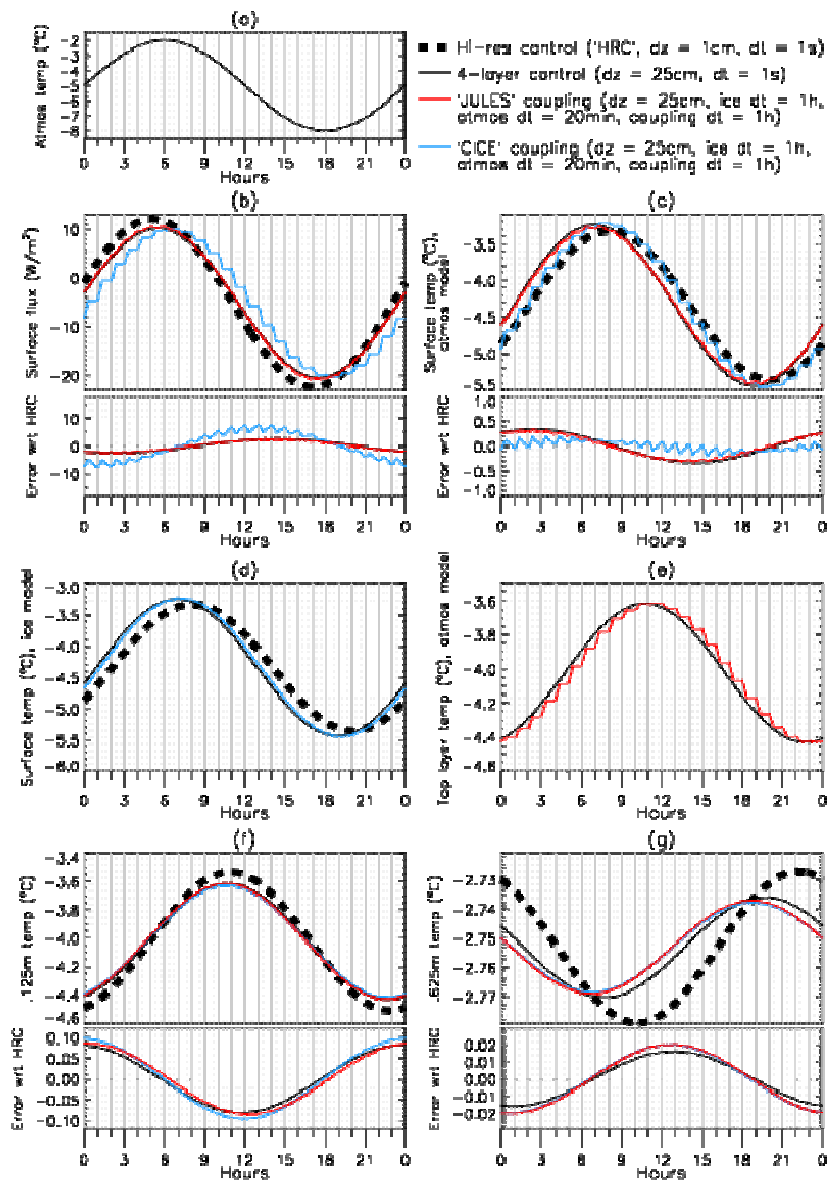


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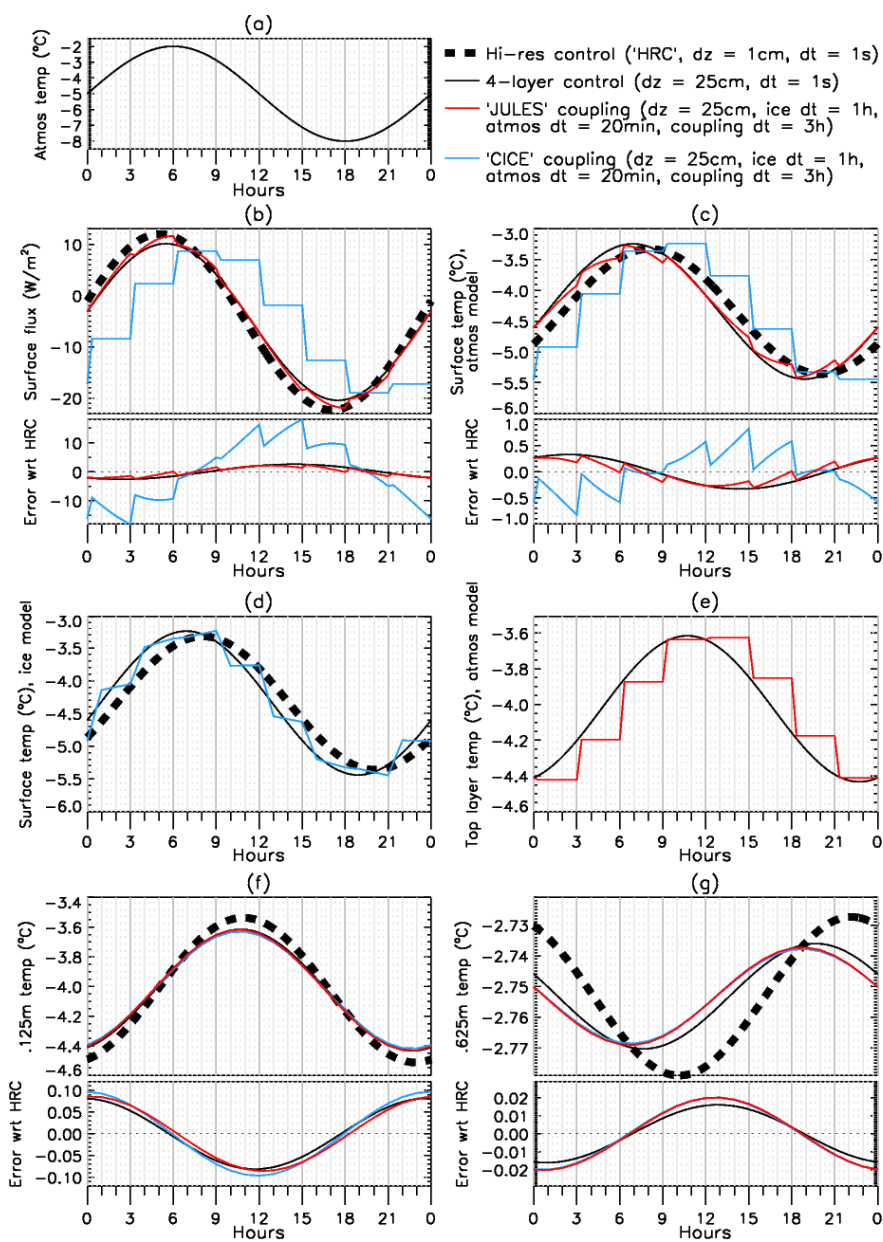
Figure 3. The performance of the CICE temperature solver under varying spatial resolution and timestep length, with coupling period 3 hours. Showing a) surface temperature; b) temperature at .125m depth.



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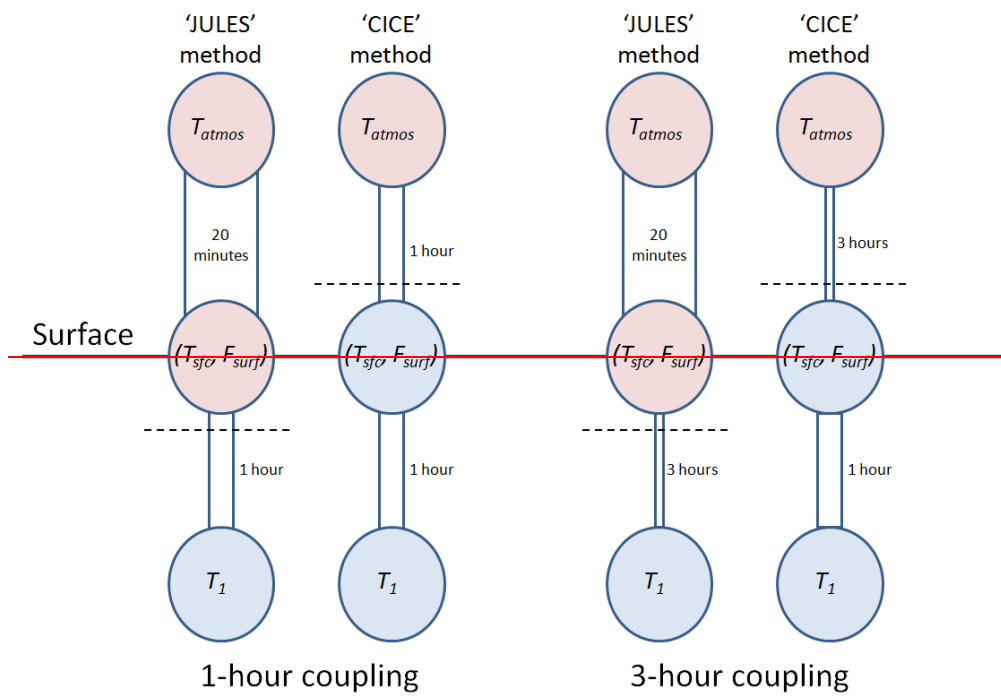


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3 Figure 4. Comparing the two coupling methods, with a 1 hour coupling period. Showing a)
4 atmospheric air temperature (the experiment forcing); b) surface flux; c) surface temperature,
5 as seen by the atmosphere; d) surface temperature as seen by the ice; e) .125m ice temperature
6 as seen by the atmosphere; f) .125m temperature as seen by the ice; g) .625m temperature.



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Figure 5. Comparing the two coupling methods, with a 3 hour coupling period. Showing a) atmospheric air temperature (the experiment forcing); b) surface flux; c) surface temperature, as seen by the atmosphere; d) surface temperature as seen by the ice; e) .125m ice temperature as seen by the atmosphere; f) .125m temperature as seen by the ice; g) .625m temperature.

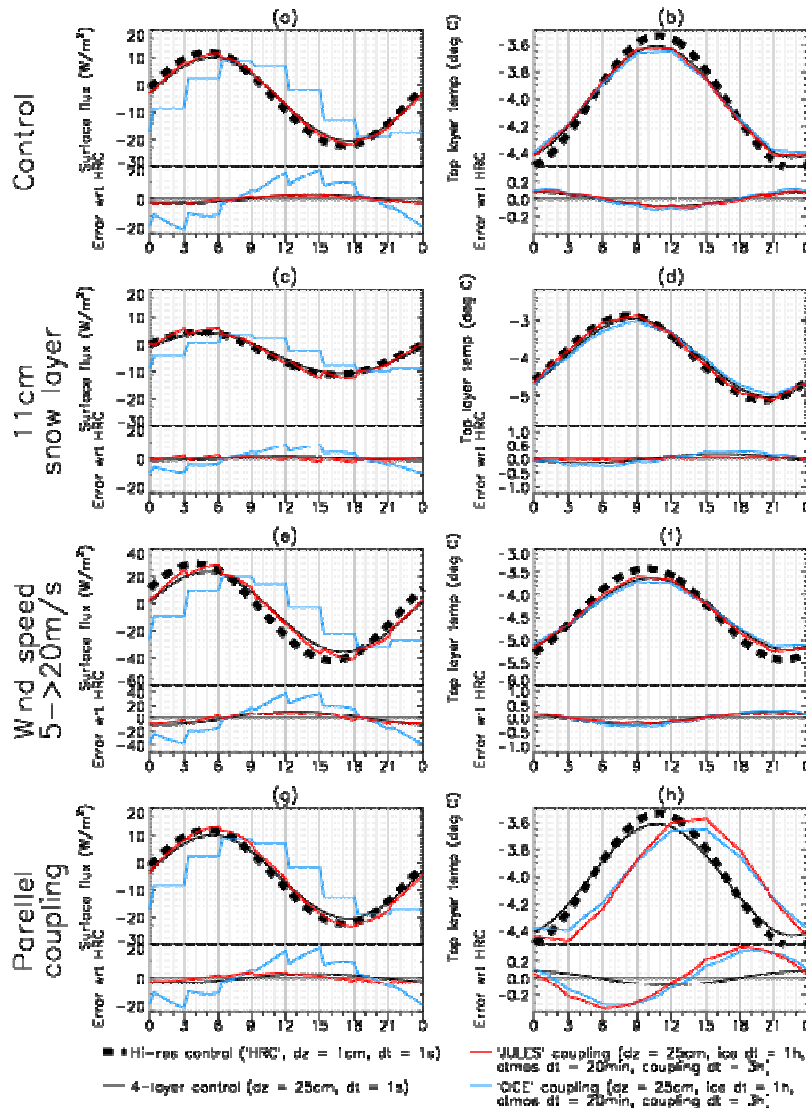


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Figure 6. Demonstrating how quickly information regarding changes in variables can propagate downwards through the atmosphere-ice interface in the two coupling methods. The

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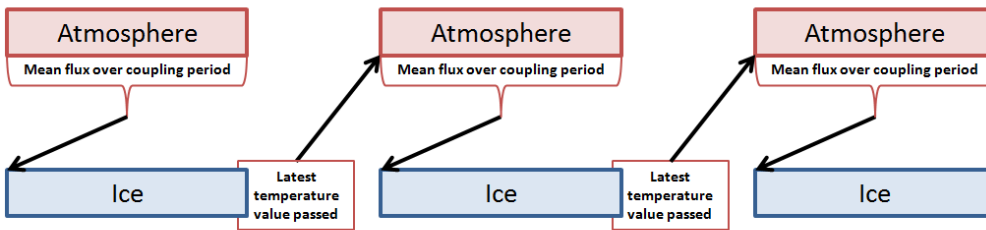
width of each 'pipe' is inversely proportional to the timestep length in each case.



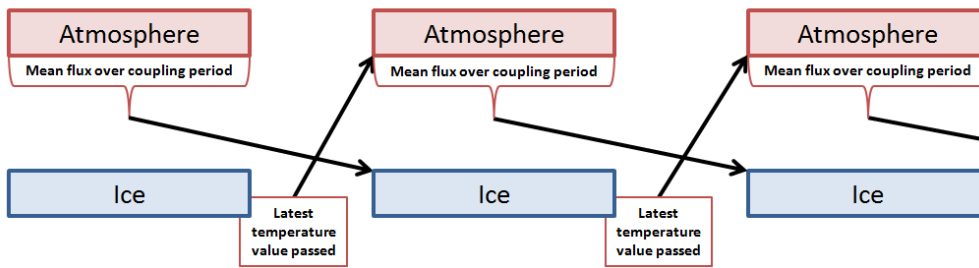
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3 Figure 6. Demonstrating the performance of the two coupling methods when the parameters
 4 of the experiment are varied. Showing surface flux (left) and top-layer temperature (right) for
 5 (a,b) Original experiment; (c,d) an experiment in which an 11cm snow layer was present on
 6 the ice; (e,f) an experiment in which wind speed was increased from 5 m/s to 20 m/s; (g,h) an
 7 experiment in which parallel, rather than serial, coupling was employed. For the snow layer
 8 experiment, the top-layer temperature represents the temperature of the snow layer; for all
 9 others, it represents the temperature of the top ice layer.

(a) Serial coupling

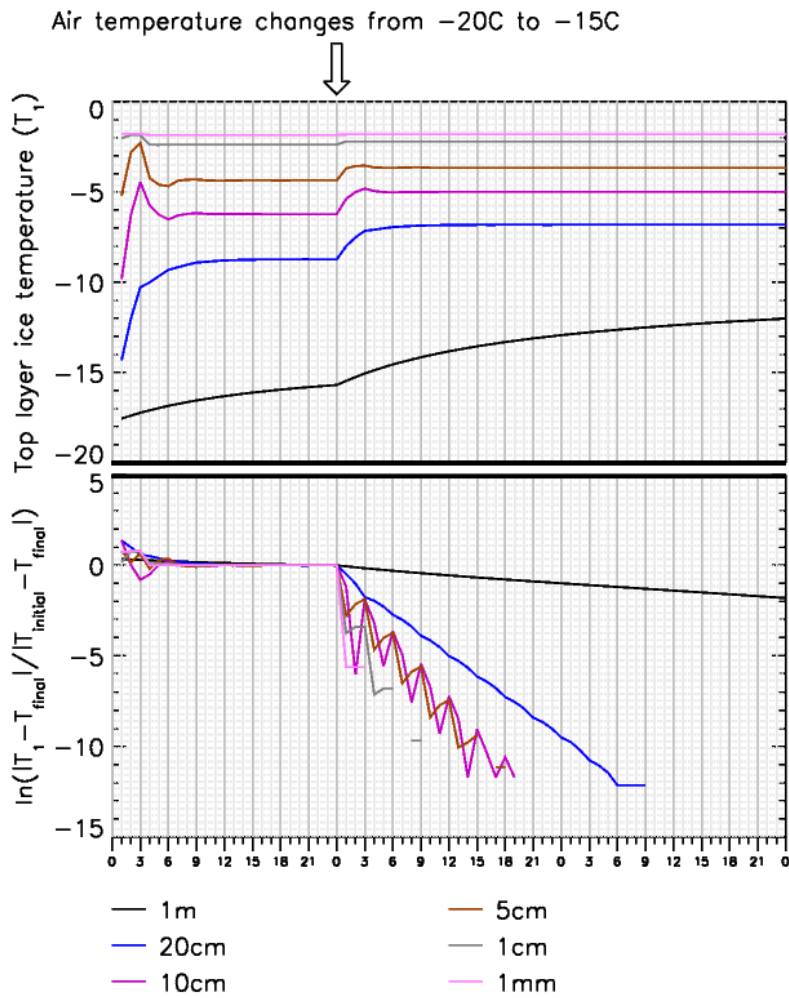


(b) Parallel coupling



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Figure 7. Schematic demonstrating the (a) serial and (b) parallel coupling frameworks, as described in Section 4.4.



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3 Figure A1. Showing the evolution of top layer ice temperature following a sudden change in

4 air temperature, under the 'JULES' coupling method. The lower panel shows the evolution of

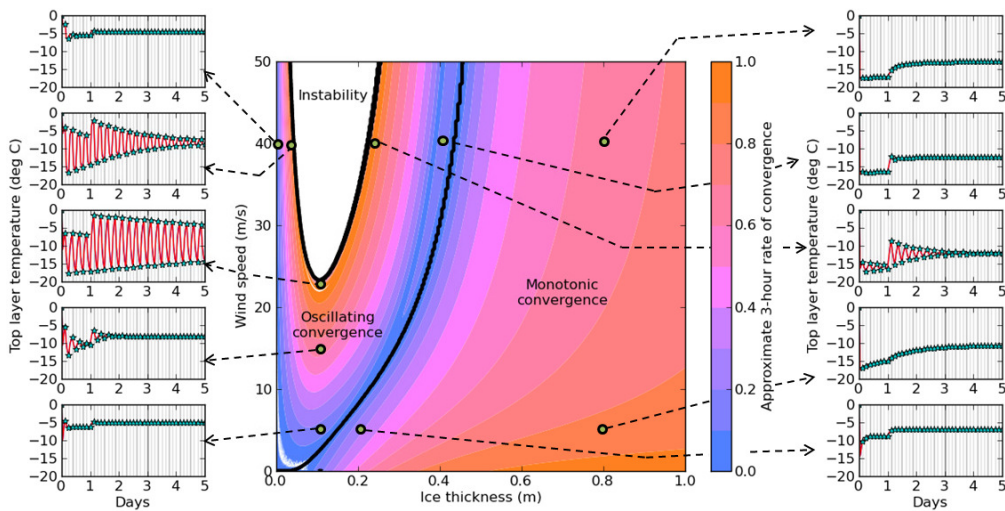
5 $\ln\left(\frac{|T_1 - T_{final}|}{|T_{initial} - T_{final}|}\right)$ to allow easy comparison of the rates of convergence for differing ice

6 thicknesses, where T_1 , T_{final} and $T_{initial}$ respectively refer to the evolving top layer ice

7 temperature, the value of top layer ice temperature after 3 days, and the value at 1 day, at the

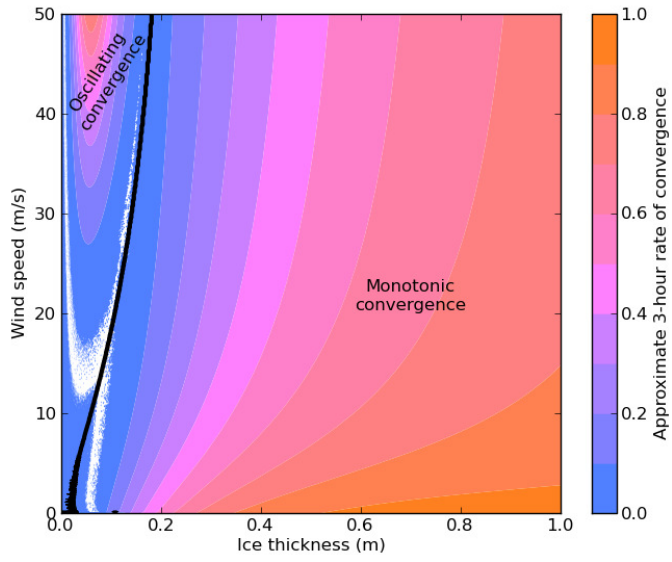
8 time of the perturbation.. The graph 'disappears' when the difference falls below minimum

9 precision.



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Figure A2. ‘Map’ of stability of the coupled ice and surface solvers, as ice thickness and wind speed are varied, with a 3-hour coupling period. Speed of convergence is indicated in colour, with blue = rapid convergence, red = slow convergence. Regions of 3-hour monotonic convergence, 3-hour oscillating convergence and instability are indicated. Timeseries of top layer ice temperature are shown for 10 representative points of the variable space.



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3 Figure A3. 'Map' of stability of the coupled ice and surface solvers, as ice thickness and
4 wind speed are varied, with a 1-hour coupling period.