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Upscaling methane emission hotspots in boreal peatlands

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Abstract

Upscaling the properties and the effects of small-scale surface heterogeneities to larger scales is a challenging issue in land surface modeling. We developed a novel approach to upscale local methane emissions in a boreal peatland from the micro-topographic scale to the landscape-scale. We based this new parameterization on the analysis of the water table pattern generated by the Hummock–Hollow model, a micro-topography resolving model for peatland hydrology. We introduce this parameterization of methane hotspots in a global model-like version of the Hummock–Hollow model, that underestimates methane emissions. We tested the robustness of the parameterization by simulating methane emissions for the next century forcing the model with three different RCP scenarios. The *Hotspot* parameterization, despite being calibrated for the 1976–2005 climatology, mimics the output of the micro-topography resolving model for all the simulated scenarios. The new approach bridges the scale gap of methane emissions between this version of the model and the configuration explicitly resolving micro-topography.

1 Introduction

The Earth's land surface is a heterogeneous mixture of vegetation types, lakes, wetlands, and bare soil. Correct representation of such small-scale heterogeneities in climate system models is a challenge. How can models better account for the small-scale features in the large-scale climate system? Proposing a new numerical approach to fill a scaling gap between local and larger scales is the main focus of this paper. Many recent studies focused on different approaches to simulate local small-scale characteristics of the land surface, with climate enforcing evolution of different soil surface heterogeneities and small-scale vegetation patterns (Shur and Jorgenson, 2007; Couwenberg and Joosten, 2005; Rietkerk and van de Koppel, 2008). In turn, small-scale heterogeneity could influence the land–atmosphere fluxes on larger scale. Several studies

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have addressed the hydrological cycle in drylands, where water recycled by vegetation may play an important role in the local water budget (Dekker and Rietkerk, 2007; Janssen et al., 2008). In particular, Baudena et al. (2013) showed that the amount of water transferred through transpiration may change up to 10 % if one considers different vegetation patterns, even with the same biomass density and the same spatial scale. Recent efforts have also been focused on downscaling remote sensing information to simulate subgrid surface heterogeneities (e. g., Peng et al., 2015; Stoy and Quaife, 2015).

Effects of small-scale heterogeneities on land–atmosphere fluxes are of especial interest in northern peatlands because of the great amount of carbon stored in the soil (Hugelius et al., 2013; Tarnocai et al., 2009). Recent studies showed that greenhouse gas fluxes, in particular of methane, strongly depend on the micro-topographic features of such environments (Gong et al., 2013; Couwenberg and Fritz, 2012), and that local hydrology is regulated by micro-reliefs (Gong et al., 2012; Bohn et al., 2013; Van der Ploeg et al., 2012). In particular, a typical feature of methane emitting landscape is the non linear relationship between fluxes and emitting surface. A small fraction of the total landscape can therefore function as a "hotspot" for methane fluxes. Recent eddy covariance measurements in northern peatlands showed how the saturated surface, with water table near to the surface level, despite covering only 10 % of the total landscape, is responsible for up to 45 % of the total methane emissions (Sachs et al., 2010).

This "hotspot" feature of methane emissions potentially constitutes a large local and even regional feedback to the climate system, which is neglected in the current Global Circulation Models (GCMs), as shown e. g. by Baird et al. (2009). Because of the complexity of the small scale biogeochemical and hydrological interactions that regulate this "hotspot" effect, it is computationally feasible to represent such nonlinear phenomena only in local mechanistic models (i. e., Nungesser, 2003; Acharya et al., 2015; Cresto Aleina et al., 2013), with a fine grained resolution (10^{-2}–10^{0} m). The "hotspot" effect is due to the nonlinear relationships between decomposition and its drivers (e. g., soil temperature and water level), and therefore a spatially explicit model able to

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identify such "hotspots" is likely to perform better in representing methane emissions (Schmidt et al., 2011).

Cresto Aleina et al. (2015) developed the Hummock–Hollow (HH) model, a model for resolving micro-relief features in a typical boreal peatland (hummocks and hollows) and coupled this hydrological model to a process-based model for methane emissions developed by Walter and Heimann (2000). They found that a micro-topography representation is necessary to correctly capture hydrology dynamics and methane fluxes, as the water table position regulates the depth of the oxic zone, where part of methane coming from the anoxic zone is oxidized and emitted to atmosphere as CO_2.

Global land surface models such as JSBACH (Raddatz et al., 2007; Reick et al., 2013), the land component of the Max Planck Institute Earth System Model MPI-ESM (Giorgetta et al., 2013), operate at a spatial resolution analogous to the atmospheric one, which is of about 50 km × 50 km at the finest feasible scale. To include a representation of the "hotspot effect" on this scale, new sub-grid scale parameterizations are needed.

In the present paper we propose a novel method to fill the scaling gap from local mechanistic models to large-scale mean field approximations, using the output of the local fine grained model to tune and modify the coarse grained bucket-like model, in order to upscale the local information (10^0–10^1 m) to the landscape-scale (e. g., 10^3 m). We present an application of this upscaling method to the HH model, where we analyze the dynamics of the area which we assume being a hotspot for methane emissions. We then use this information to modify a version of the HH model without micro-topography representation, which originally failed to represent the magnitude of methane fluxes. In this paper we present (i) results for the average climatology of the past 30 years, for which we calibrated the parameterization, and (ii) for the next century, testing the robustness of the parameterization under a different forcing.

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2 Methods

2.1 The HH model

The Hummock–Hollow (HH) model (Cresto Aleina et al., 2015) simulates peatland micro-topographic controls on land–atmosphere fluxes. It is suited to work at a 1 m × 1 m resolution, which is the typical spatial scale of peatland micro-topography. Each grid cell of the HH model represents just one micro-topographic feature, namely a hummock or a hollow. The model simulates a 1 km × 1 km peatland and its parameters are tuned with values for a typical peatland in Northwest Russia. In particular, we use the model to simulate the Ust–Pojeg mire in the Komi Republic (61°56′ N, 50°13′ E, 119 m a.s.l.). The micro-topography is initialized with micro-topographic data collected through surveying with a theodolite. An elevation distribution is derived from the data, and it is possible to randomly assign an elevation at each grid cell (for more information, Cresto Aleina et al., 2015). Depending on the elevation, the grid cell is therefore either a hollow or a hummock (Fig. 1).

For each grid cell (i. e., for each micro-topographic unit) we compute the water balance as:

$$\frac{\mathrm{d}W_{i,j}}{\mathrm{d}t} = \frac{Sn + P - \mathrm{ET}_{i,j} - R_{i,j}}{s_{i,j}} \tag{1}$$

where $W_{i,j}$ is the water table level in the grid cell at the position (i, j) relative to the surface level, S is the snowmelt, P is the precipitation input, $\mathrm{ET}_{i,j}$ is the evapotranspiration, $R_{i,j}$ is the lateral runoff, $s_{i,j}$ is the drainable porosity, and t is time. The time step is $\delta t = 1$ day. Terms without the indices (i, j) are applied uniformly over the model domain. For a description of the parameterization of S and $\mathrm{ET}_{i,j}$ see Appendix. This version of the model with the explicit representation of hummocks and hollows is called the *Microtopography* configuration.

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The HH model can also run in a *Single Bucket* configuration, where all quantities are averaged over the model domain. Equation (1) becomes therefore:

$$\frac{dW}{dt} = \frac{Sn + P - ET - R}{s} \quad (2)$$

Cresto Aleina et al. (2015) showed that the *Single Bucket* configuration, despite being computationally much faster, fails to represent the peatland hydrology, constantly underestimating the water table position in comparison to measurements. This is due to the strong runoff that washes away the water at the beginning of the simulation. Because of the more rugged, hummocky surface represented in the *Microtopography* version, the runoff is delayed. This behavior better agrees with in situ measurements for water table position (Schneider et al., 2012), whereas the water table position simulated by the HH model in the *Single Bucket* configuration is overly deep. Table 1 describes the main differences between the two configurations of the HH model, and the *Hotspot* parameterization we present in this paper.

2.2 Coupling to a process-based methane emission model

The HH model is coupled to a process-based model for methane emissions, in order to quantify the effect of surface heterogeneities on GHG fluxes. The model developed by Walter and Heimann (2000) is a quite general model for methane emissions, and can be applied to peatlands in different environments. It is the same model that is used and coupled with some Dynamical Global Vegetation Model (DGVMs) (e.g., Kleinen et al., 2012). We tuned the model to perform in a typical peatland at the latitude of the Ust–Pojeg mire complex. In the *Microtopography* configuration, we computed methane fluxes locally and we averaged over the model domain in order to upscale the local fluxes at the landscape-scale. The process-based model for methane emissions provides an output of methane fluxes $F_{CH_4}^{i,j}$ as a function of water table (computed by the

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HH model), net primary productivity (NPP), and soil temperature (T):

$$F_{CH_4}^{i,j}(t) = f(W_{i,j}(t), \mathrm{NPP}(t), T(t)) \quad (3)$$

Where $W_{i,j}$ is the water table depth with respect to the surface computed at each position (i, j). All variables are at the daily time step. We force the model with time series of T and NPP taken from CMIP5 experiments performed by the MPI-ESM model. We then considered the model output for the grid cell which corresponds to the Ust–Pojeg mire (see Sect. 2.4). The amount of methane which is emitted by each kind of surface class changes according to the relative position of water table and surface. In the process-based methane emission model developed by Walter and Heimann (2000), the water table is a key variable in methane fluxes, because of the oxidation processes simulated as the water table drops below the surface and as the oxic zone deepens. The HH model in the *Microtopography* configuration reasonably represents the hydrological interactions among hummocks and hollows and the variability of emissions within the peatland. In the *Single Bucket* configuration the water table deepens quickly after the snow melt due to a strong runoff, and thus most of the methane transported from below ground is oxidized. Parameters for the methane emission model are described in the Appendix.

2.3 The *Hotspot* parameterization

The HH Model has a critical scale of about 0.01 km^2 at which seasonal results do not change for finer resolutions (Cresto Aleina et al., 2015). Even at this resolution, though, it is unfeasible to include a micro-topography parameterization in the current GCMs.

The general purpose of our *Hotspot* parameterization is to upscale information from the local to the atmospheric scale. The HH model identifies different surface types

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depending on the relative position of the water table W_t and the surface S:

$$\begin{aligned} S - W_t > \epsilon_a &\quad \Rightarrow \quad \text{wet surface} \\ -\epsilon_b \leq S - W_t \leq \epsilon_a &\quad \Rightarrow \quad \text{saturated surface} \\ S - W_t < -\epsilon_b &\quad \Rightarrow \quad \text{dry surface} \end{aligned}$$

Here we assume, after Couwenberg and Fritz (2012):

$\epsilon_a = 15\,\text{cm}$

$\epsilon_b = 10\,\text{cm}$

because of the importance of such thresholds for methane emissions. We assume the *saturated* surface to be the surface class which dominates the methane emission dynamics, as a water table near to the surface prevents most of the oxidation to happen.

After obtaining the seasonal behavior of the desired surface class, we aim to parameterize of the area covered by the *saturated* surface class with a fractional number q, which represents the fraction of the total surface which is saturated at each time step. This information translates in a different water table behavior which in turns controls methane emissions. By knowing the fraction q of saturated surface at each time step t we implicitly subdivide the domain of the HH model in the *Single Bucket* version A in unsaturated surface A_{unsat} and saturated surface A_{sat}:

$$A = (1 - q)A_{\text{unsat}} + qA_{\text{sat}} \tag{4}$$

The position of the water table in A_{sat} stays between $-\epsilon_b \leq W_t^{\text{sat}} \leq \epsilon_a$, which is given by the definition of the saturated surface, and therefore we assume:

$$W_t^s = -\epsilon_b + (\epsilon_a + \epsilon_b)r \tag{5}$$

where r is a random number. The position of the water table in A_{unsat}, instead, is the one computed by the HH model in the *Single Bucket* configuration, i. e., W_t in Eq. (1).

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Methane fluxes are calculated as a function of the water table assuming a linear relationship between emitting area and methane fluxes:

$$F_{CH_4} = (1 - q)F^{SB}_{CH_4}(W_t) + qF^{sat}_{CH_4}(W^s_t) \quad (6)$$

where F_{CH_4} is the methane flux from the whole domain, $F^{SB}_{CH_4}$ the flux from the HH model in the *Single Bucket* version, and $F^{sat}_{CH_4}$ the flux from the saturated area A_{sat}. The other forcing variables for F_{CH_4} stay unchanged, as in Eq. (3).

The specific form of q as a function of time will be inferred by the analysis of the saturated area dynamics, an output of the HH model in the *Microtopography* configuration.

2.4 Forcing data

The HH model is forced with prescribed snowmelt, precipitation, and evapotranspiration (Eq. 1). The simulated Sn is a stochastic input that functions as initialization parameter for the water table. It is parameterized to gain the same magnitude of the observational data (Schneider et al., 2012; Runkle et al., 2014). Evapotranspiration is simulated according to observations of Runkle et al. (2014) using an empirical parameterization. All parameterizations are described in more detail in the Appendix. In Eq. (1) we assumed Sn and P to be uniform over the whole simulated domain and we did not apply any downscaling further.

We forced the process-based model for methane emissions developed by Walter and Heimann (2000) (Eq. 3) and the water balance (Eq. 1) with prescribed time series of NPP and T, and of precipitation P respectively. The time series are computed from simulations performed for the CMIP5 experiments with the MPI-ESM model at T63 resolution for the grid cell which corresponds to the Ust–Pojeg mire. The potential bias introduced by using NPP of C3 grasses and not the one for mosses (not included in the MPI-ESM model) is negligible as discussed by Cresto Aleina et al. (2015).

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We used the P, T, and NPP from the last 30 years of the IPCC historical simulations and forced the model to infer a parameterization of the saturated area (Eqs. 4 and 6) for the past 30 year climatology. To assess the robustness of our parameterization for future simulations we chose three Representative Concentration Pathways (RCP) scenarios, and we therefore considered the identical set of variables from the RCP2.6, RCP4.5, and RCP8.5 experiments from year 2006 to 2099 on daily resolution (Giorgetta et al., 2013).

3 Results and discussion

3.1 Hotspot area dynamics

By averaging the output of the model over 30 years of simulations, from 1976 to 2005 we calculated the average dynamics of the three surface classes. In particular, we are interested in the 30 year average of the *saturated* area A_{sat} dynamics (Eq. 4). After snowmelt, most of the simulated peatland surface is either *saturated*, or *wet* (Fig. 2). As the simulations continue, surface and subsurface runoff wash water out of the peatland, changing the relative composition of the area densities. More and more cells become *dry* by having a water table lower than 10 cm below the surface. Grid cells belonging to the *wet* surface class, with a high water table, become saturated and towards the beginning of August virtually no grid cell displays a water table higher than 15 cm above the surface level. At the end of the simulations, almost in all grid cells the water table lays more than 10 cm below the surface level, and the peatland is relatively dry by the end of October.

We used the output of the spatially explicit HH model to describe the dynamics of methane emission hotspots, assuming that the *saturated* grid cells are the ones where methane emissions are higher. We therefore infer the dynamics of the *saturated* grid cells from Fig. 2, and obtain the following parameterization for methane emission

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hotspots:

$$q(t) = \begin{cases} q_{\text{in}} + \frac{q_{\text{max}} - q_{\text{in}}}{t_1 - t_0}(t - t_0) & \text{if } t \le t_1 \\ q_{\text{max}} & \text{if } t_1 < t \le t_2 \\ q_{\text{max}} + \frac{q_{\text{min}} - q_{\text{max}}}{t_3 - t_2}(t - t_2) & \text{if } t_2 < t \le t_3 \\ q_{\text{min}} & \text{otherwise} \end{cases} \quad (7)$$

where t is the daily time step of the simulation, and the parameters t_i and q_j are tuned quantities obtained according to the dynamics of *saturated* grid cells in Fig. 2. Values for the parameterization are described in Table 2. We slightly overestimate the amount of *saturated* grid cells in order to take into account the potential methane emission hotspots belonging to the *wet* surface class.

We illustrate the empirical parameterization of the area density computed by Eq. (7) in Fig. 2 (black dotted line). This parameterization represents the average dynamics of methane emission hotspots for the 30 year-period 1976–2005.

3.2 Methane emissions for 1976–2005

We compared methane emissions from the Ust–Pojeg mire simulated over a 30 year period (1976–2005) in the three versions of the HH model (Table 1). We then averaged the 30 simulations and studied the differences in dynamics among the different HH model versions. The *Microtopography* configuration (black line in Fig. 3) produces seasonal fluxes that more than double the cumulative methane fluxes produced by the HH model in the *Single Bucket* configuration (red line in Fig. 3). In particular towards July and August, when temperatures are higher and methane fluxes larger, the two versions of the HH model diverge in flux estimation and the *Single Bucket* configuration largely underestimates methane fluxes (Cresto Aleina et al., 2015).

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Combining Eqs. (4) and (6), and the empirical parameterization of the hotspot area density $q(t)$ (Eq. 7), we obtain a new flux dynamics (blue line in Fig. 3). The new parameterized fluxes display similar magnitude and dynamics as the fluxes simulated by the *Microtopography* configuration, but at a much lower computational cost. The main difference between the emissions from the *Single Bucket* and the *Microtopography* configuration is the large underestimation in the central part of the summer season, i. e. in July and August. The *Hotspot* parameterization, by changing the saturated area, improved this feature. The visual improvement is confirmed by the large differences in the seasonally cumulated methane emissions. The differences in cumulative emissions from the three model configurations are summarized in Table 3.

The *Hotspot* parameterization mimics the general magnitude and dynamics of the emissions from the *Microtopography* configuration, but fails to capture the whole amplitude of methane emissions at the beginning and at the end of the simulations. Such discrepancies might be caused by other variables which, differently from the water table, remain averaged over the domain. In particular, peat depth is uniform and the model does not have a heterogeneous peat profile as in the *Microtopography* configuration. This difference may influence the carbon available for methane emissions.

3.3 Future projections with the *Hotspot* parameterization

The *Hotspot* parameterization mimics the simulated methane emissions of the *Microtopography* configuration for the 1976–2005 period for which it has been tuned. We now force the model for the 2006–2099 period with data from the CMIP5 experiments. The HH model does not simulate an increasing trend for methane emissions for the next 100 years, despite the generally higher temperatures (Fig. 4a–c). Even in the RCP8.5 scenario, despite an increase of 4 K in average temperature in year 2099 in respect to the RCP4.5 and the RCP2.6 simulations, we can not find any significant trend. This result is in agreement with the findings from the The Wetland and Wetland CH_4 Intercomparison of Models Project (WETCHIMP) experiments (Melton et al., 2013), that attributed the future projected increase in methane emissions to increased atmospheric

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CO_2 concentrations, which we ignore for the scope of this paper. Such an increase is suggested to reduce stomatal conductance, with the same amount of evapotranspiration, thus increasing waterlogged surface area. In particular, Melton et al. (2013) did not find a large significant trend in methane emissions simulated by the model participating in the inter-comparison project because of increased temperature or of precipitation trends, which are the two variables we use to force the HH model coupled with the methane emission model.

The *Single Bucket* configuration estimates 42.8–50.8 % of the methane emissions cumulated over the season simulated by the *Microtopography* configuration with the RCP8.5 scenario forcing. Numbers are very similar with forcing from the RCP4.5 scenario (44.3–50.4 %) and from the RCP2.6 scenario (43.0–50.6 %). If we include the *Hotspot* parameterization the simulated methane emissions range $[2.831–4.321] \times 10^4\,\mathrm{mg\,m^{-2}}$ with forcing from the RCP8.5, depending on year-to-year variability, which accounts for 83.9–101.5 % of the emissions in the *Microtopography* configuration. As for the *Single Bucket* configuration, the numbers are similar for the other forcing scenarios. The simulated emissions range $[2.771–4.056] \times 10^4\,\mathrm{mg\,m^{-2}}$ (88.4–100.1 % of the emissions in the *Microtopography* configuration) for the RCP4.5 scenario, and $[2.648–4.102] \times 10^4\,\mathrm{mg\,m^{-2}}$ (87.7–104.3 % of the emissions in the *Microtopography* configuration) for the RCP2.6 scenario. The amplitude and timing of year-to-year variability of cumulative methane emissions with the *Hotspot* parameterization are also comparable to the ones simulated by the *Microtopography* configuration in all simulated scenarios.

These results increase the applicability of the *Hotspot* parameterization. Despite being tuned for the 1976–2005 climatology, it works for the next century of simulations under very different forcing scenarios. This is due to the large differences in hydrological representations between *Microtopography* and *Single Bucket* configuration. Such differences are almost totally overcome with the use of the *Hotspot* parameterization. These improvements make the parameterization applicable also for future time slices,

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despite the differences in temperature, precipitation, and NPP forcing between in the time period used for the parameterization tuning and the predicted future ones.

We also tested the effectiveness of the *Hotspot* parameterization over the seasonal cycle. We averaged for each simulated day the methane emissions over the 2005–2099 period for all model configurations, and for all scenarios. We then divided the daily emissions from the *Microtopography* configuration by the emissions from the *Single bucket* configuration and from the *Hotspot* parameterization, to investigate the impact of the new parameterization on the seasonal cycle. In all simulated scenarios, the *Hotspot* parameterization works very well during the mid season. From mid-May till the beginning of October, when methane emissions are higher, the ratio between the *Microtopography* configuration and the *Hotspot* parameterization being near to 1 for this period (Fig. 4b, d, and f). The ratio between emissions from the *Microtopography* and the *Single bucket* configuration reaches its maximum only towards the end of the simulations, therefore missing the larger methane emissions peaks in June, July, and August.

4 Summary and conclusions

We developed a new parameterization to bridge the scaling gap between a process-based, small-scale hydrological model for peatlands, and a mean field approximation, analogous to a large-scale parameterization in a DGVM. The *Hotspot* parameterization uses the output of the HH (Hummock–Hollow) model (Cresto Aleina et al., 2015) which simulates a 1 km × 1 km peatland. The HH model can work in both configurations, a spatially explicit one working at 1 m × 1 m scale, simulating explicitly hummocks and hollow (the *Microtopography* configuration) and a mean field approximation of it, where all quantities are averaged over the domain (the *Single Bucket* configuration). If coupled to a process-based methane emission model (Walter and Heimann, 2000) the *Microtopography* configuration simulates more realistic methane fluxes because of the better representation of hydrology due to the explicit description of processes at

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1 m scale, but at a much higher computational cost. We assumed that the lack of representation of saturated areas in the *Single Bucket* configuration, which are methane emission hotspots, diminish the cumulative emissions over the season by half.

We inferred a parameterization of this hotspot area for emissions for the period 1976–2005, which are the last 30 years of the historical simulations from the CMIP5 experiments. We analyzed the spatial pattern of the HH model output in the *Microtopography* configuration averaged over the 30 simulated years. We introduced this information in the *Single Bucket* configuration, modifying the hydrology of the mean field approximation, obtaining the *Hotspot* parameterization. This novel approach that takes into account the information from the spatially explicit simulations bridges the gaps between the simulated methane emissions. The *Hotspot* parameterization, due to its higher modified water table, is able to mimic the general magnitude and dynamics of the emissions from the model with micro-topography representation.

By forcing the model with time series of temperature, NPP, and precipitation for the next century from CMIP5 experiments in the RCP8.5, RCP4.5, and RCP2.6 scenarios, we assessed the robustness of the *Hotspot* parameterization under forcing for which it was not originally calibrated. The parameterization holds for years 2006–2099 for all three scenarios. Overall, the ratio between the seasonally cumulated emissions from the HH model in the *Microtopography* configuration and the ones simulated by the *Hotspot* parameterization ranges between 0.84 and 1.04. This is a substantial improvement in comparison to the methane emissions simulated by the *Single Bucket* configuration, which only produces between 43 and 51 % of the seasonally cumulated methane emissions. The *Hotspot* parameterization at almost no computational costs therefore qualitatively changes and improves the simulated system response for methane emissions.

We only applied this method to the HH model simulating a single peatland in west Russia. This method, though, uses the information of a mechanistic spatially explicit model and it is a significant first step towards a full parameterization of the microtopographic impacts on complex ecosystems at the DGVM-scale. In order to develop

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such a parameterization we would need a comprehensive and statistical analysis on the response of the mechanistic local-scale model to different climatic forcing, i.e. we would need HH-like models working at the micro-topographic scale applied at different peatlands in other climatic zones. Another limitation of the applicability of this study is its dependency on the availability of data to calibrate the original HH model in its *Microtopography* configuration, as accurate measurements of peatland micro-relieves are needed to initialize surface height.

Introducing the analysis of spatial patterns produced by different mechanistic models in multiple ecosystems is a powerful method to infer landscape-scale dynamics and characteristics of patterns.

Appendix A: Climatology parameterization

Snow melt Sn represents the water input at the beginning of the warm season. The cold season is not represented in the model, because we assume that snow covers the area (almost) uniformly. We compute the snowmelt as a random number varying between 200 and 300 mm. We used this range for Sn in order to obtain an initial water table level on the same order of magnitude of the one observed by Schneider et al. (2012); Runkle et al. (2014).

Evapotranspiration is dependent on the soil dryness and patchiness. We refer to former studies (Nichols and Brown, 1980), which extensively analyzed the evaporation rate from sphagnum moss surface. Evapotranspiration rate depends on the day of the season, the surface wetness, and on the micro-topographic features.

$$\mathrm{ET}_{i,j} = \begin{cases} \frac{\mathrm{ET}^{\max}_{i,j}}{fr(W_{i,j})} \sin\left(\frac{(t-4t_0)\pi}{6t_0}\right) & \text{if } 180 < t < 300 \\ \frac{\mathrm{ET}^{\max}_{i,j}}{fr(W_{i,j})} & \text{otherwise} \end{cases} \quad \text{(A1)}$$

where t is the daily time step in days of Gregorian calendar, $t_0 = 30$ days is a time constant and $\mathrm{ET}^{\max}_{i,j}$ is a function of the micro-topographic features for the cell at the

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position i, j:

$$ET_{i,j}^{max} = \begin{cases} 6\,mm\,d^{-1} & \text{if Hummock} \\ 3\,mm\,d^{-1} & \text{if Hollow} \end{cases} \quad (A2)$$

$fr(W_{i,j})$ takes into account the fact that evaporation takes place at a higher rate if water table is above the surface:

$$fr(W_{i,j}) = \begin{cases} 1 & \text{if } W_{i,j} \text{ above the surface level} \\ 2 & \text{if } W_{i,j} \text{ below the surface level} \end{cases} \quad (A3)$$

We use this very simple parameterization of evapotranspiration rate in order to study the general response of the model to random climatic conditions and to produce quantities in the order of the ones measured by (Runkle et al., 2014).

Appendix B: Parameters for the methane emission model

We tuned the parameters used in the process-based model for methane emissions (Walter and Heimann, 2000) in order to apply the model at the latitude of the Ust–Pojeg Mire complex, in the Komi Republic, Russia (61°56′ N, 50°13′ E, 119 m a.s.l.). Walter and Heimann (2000) used a tuning parameter for the model, R_0, which we fix at 0.30. Other parameters needed for the coupling with the methane emission model is the soil depth, which we fixed at 150 cm following in situ observation.

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Table 1. Description of the different configurations of the Hummock–Hollow (HH) model used in the present paper.

Configuration	Properties	Resolution
Microtopography	Explicitly resolves micro-topography. Computationally expensive and requires fine scale data for initialization.	1 m × 1 m
Single Bucket	Averages quantities over the domain. Does not consider micro-topography. Computationally fast and requires minimal information for initialization.	1 km × 1 km
Hotspot	Averages quantities over the domain. Considers micro-topographic information. Computationally fast and requires minimal information for initialization.	1 km × 1 km

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Table 2. Parameter values for Eq. (7). We infer the values from the dynamics of the grid cells belonging to the *saturated* surface class as in Fig. 2. Days are computed according to the Julian calendar.

Symbol	Meaning	Value
t_0	Initial day of the year of simulation	79
t_1	Initial day of the year of maximum saturation	110
t_2	Final day of the year of maximum saturation	170
t_3	Initial day of minimum saturation	260
q_{in}	Initial saturation area density	0.52
q_{max}	Maximum saturation area density	0.8
q_{min}	Minimum saturation area density	0.5

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Table 3. Cumulative emissions from different model configurations. The *Single Bucket* configuration produces less than the half of the cumulative methane emissions with respect to the model with micro-topography representation. By inserting a simple parameterization of the *saturated* surface dynamics, we improve significantly the seasonal methane emissions.

Symbol	Meaning	Value	Units
CH_4^{SB}	Cumulative emissions from the *Single Bucket* configuration	$1.70 \pm 0.11 \times 10^4$	mg m^{-2}
CH_4^{Mic}	Cumulative emissions from the *Microtopography* configuration	$3.82 \pm 0.30 \times 10^4$	mg m^{-2}
CH_4^{HS}	Cumulative emissions from the *Single Bucket* configuration with the *Hotspot* parameterization	$3.47 \pm 0.25 \times 10^4$	mg m^{-2}

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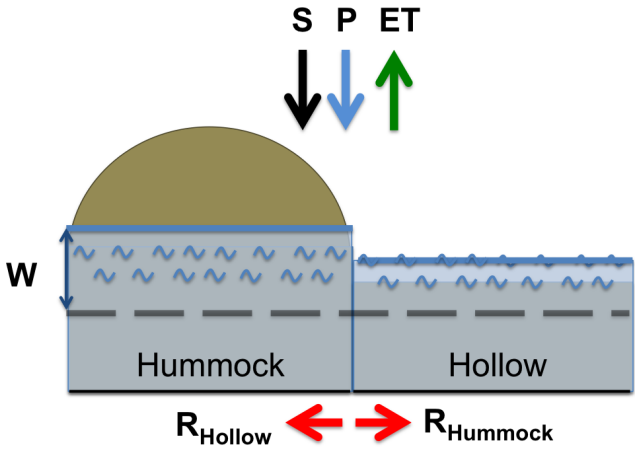

Figure 1. Schematics of the HH model showing two grid cells, a hummock and a hollow. The model represents a 1 km × 1 km peatland, and works at a 1 m × 1 m grid cell. It is therefore able to resolve the micro-topographical features such as hummocks and hollows. The figure shows two typical grid cells, a hummock and a hollow, and the variables needed for the water table dynamics (Eq. 1 in the text). Each grid cell has an elevation which is randomly assigned from the distribution of elevation data collected in situ. For each grid cell we simulate a dynamical water table, which changes with snowmelt (S), precipitation (P), evapotranspiration (ET), and lateral runoff among the different grid cells ($R_{\text{Hummock/Hollow}}$). These quantities regulate the change in water table depth (W).

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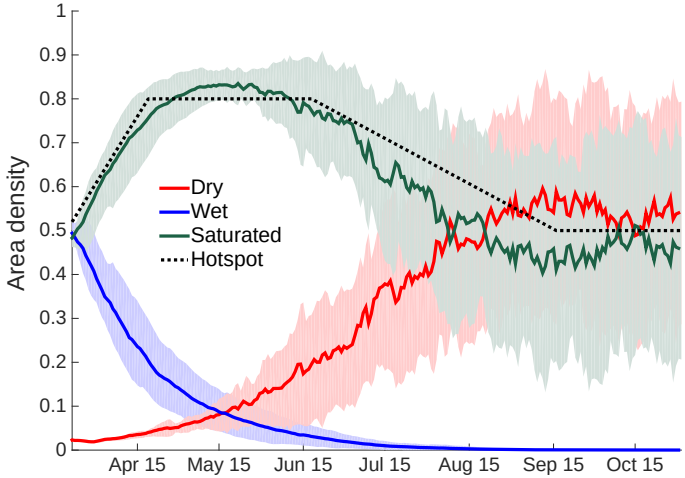

Figure 2. Area densities for *dry* (red line), *wet* (blue line), and *saturated* (green line) grid cells. The solid lines represent the different surface class dynamics averaged over 30 years, from 1976 to 2005. Shaded areas represent standard deviations over the same period of time. The dynamics of the *saturated* grid cells are mimicked by the empirical *Hotspot* parameterization (black dotted line), Eq. (7) in the text.

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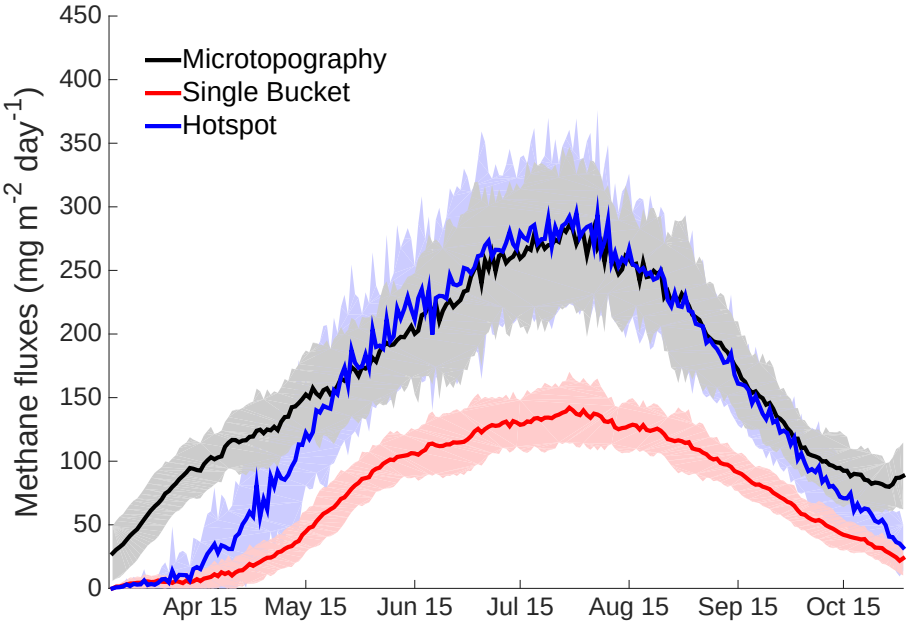

Figure 3. Methane emissions from the HH model coupled with the Walter and Heimann (2000) model. Solid lines are averages over 30 years (1976–2005) and shaded areas represent standard deviations. Emissions are computed using the HH model in the *Microtopography* configuration (black line), in the *Single Bucket* configuration (red line), and in the *Single Bucket* configuration with the *Hotspot* parameterization (blue line).

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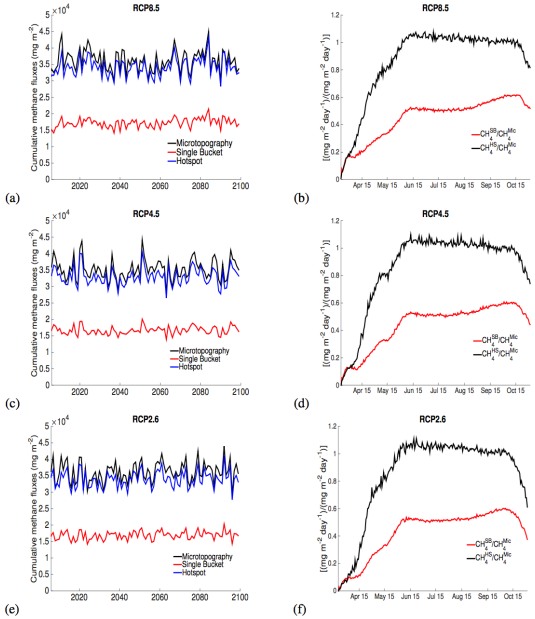

Figure 4. Performances of the three configurations of the HH model for future projections in different scenarios. Panels **(a)**, **(c)**, and **(e)** represent seasonally cumulated methane emissions computed by the HH model forced with CMIP5 data for the time period 2006–2099 from the RCP8.5, 4.5, and 2.6 experiments respectively. Panels **(b)**, **(d)**, and **(f)** represent the seasonal effectiveness of the *Hotspot* parameterization for future projections, forced with CMIP5 data for the time period 2006–2099 from the RCP8.5, 4.5, and 2.6 experiments respectively. We illustrate the ratio between the methane emitted from the *Microtopography* configuration and from the *Single bucket* configuration (red lines) and from the *Microtopography* configuration and from the *Hotspot* parameterization (black lines). We averaged each day of simulation over the 2006–2099 period.

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