

# *GA*SAKe : forecasting landslide activations by a Genetic-Algorithms based hydrological model

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## ABSTRACT

*GA*SAKe is a new hydrological model aimed at forecasting the triggering of landslides. The model is based on Genetic-Algorithms and allows to obtaining thresholds of landslide activation from the set of historical occurrences and from the rainfall series.

*GA*SAKe can be applied to either single landslides or set of similar slope movements in a homogeneous environment. Calibration of the model is based on Genetic Algorithms, and provides for families of optimal, discretized solutions (kernels) that maximize the fitness function. Starting from these latter, the corresponding mobility functions (i.e. the predictive tools) can be obtained through convolution with the rain series. The base time of the kernel is related to the magnitude of the considered slope movement, as well as to hydro-geological complexity of the site. Generally, smaller values are expected for shallow slope instabilities with respect to large-scale phenomena. Once validated, the model can be applied to estimate the timing of future landslide activations in the same study area, by employing recorded or forecasted rainfall series.

Example of application of *GA*SAKe to a medium-size slope movement (the Uncino landslide at San Fili, in Calabria, Southern Italy) and to a set of shallow landslides (in the Sorrento Peninsula, Campania, Southern Italy) are discussed. In both cases, a successful calibration of the model has been achieved, despite unavoidable uncertainties concerning the dates of landslide occurrence. In particular, for the Sorrento Peninsula case, a fitness of 0.81 has been obtained by calibrating the model against 10 dates of landslide activation; in the Uncino case, a fitness of 1 (i.e. neither missing nor false alarms) has been achieved against 5 activations. As for temporal validation, the experiments performed by considering the extra dates of landslide activation have also proved satisfactory.

In view of early-warning applications for civil protection purposes, the capability of the model to simulate the occurrences of the Uncino landslide has been tested by means of a progressive, self-adaptive procedure. Finally, a sensitivity analysis has been performed by taking into account the main parameters of the model.

The obtained results are quite promising, given the high performance of the model obtained against different types of slope instabilities, characterized by several historical activations. Nevertheless, further refinements are still needed for applications to landslide risk mitigation within early-warning and decision-support systems.

**Key words:** hydrological model, rainfall threshold, landslide triggering, genetic algorithm

## 46 1 INTRODUCTION

47 A nationwide investigation, carried out by the National Geological Survey, identified approximately  
48  $5 \times 10^5$  slope movements in Italy, an average of 1.6 failures per square kilometre (Trigila, 2007).

49 According to other investigations, this figure would rather be a lower estimate (cf. Servizio  
50 Geologico, Sismico dei Suoli, 1999; Guzzetti et al., 2008). In the period 1950–2009, at least 6349  
51 persons were killed, went missing, or were injured by landslides, with an average of 16 harmful  
52 events per year, thus confirming the notable risk posed to population (Guzzetti, 2000; Salvati et al.,  
53 2010).

54 Petley (2008) estimated that about 90% of worldwide casualties can be attributed to landslides  
55 triggered by rainfall. With reference to the Italian territory, about 70% of landslides result to be  
56 triggered by rainfall (cf. CNR-GNDCI AVI Project, Alfieri et al., 2012).

57 In more general terms, slope instability conditions are influenced by rainfall that, allowing  
58 infiltration into the slopes, cause temporary changes in groundwater dynamics (Van Asch et al.,  
59 1999). Actually, rainfall infiltrates the slopes only partially, the remaining aliquots being involved  
60 into evapo-transpiration and runoff processes. The combination of rainfall infiltration and runoff  
61 may cause different types of mass-movements (either slope failure or erosion processes) depending  
62 on the intensity and duration of the rainfall and the values of soil suction (Cuomo and Della Sala,  
63 2013). Concentration of water deriving from either contemporary or antecedent storms at specific  
64 sites plays a major role in triggering landslides – as testified by slope instabilities that commonly  
65 follow the heaviest phases of rainfall events.

66 To model the relationships between rainfall and landslide occurrence, two distinct approaches are  
67 generally adopted in literature. The first, “complete” or “physically-based”, attempt to determine  
68 the influence of rainfall on slope stability by modelling its effects in terms of overland flow,  
69 groundwater infiltration, pore pressures and related balance of shear stress and resistance (cf. e.g.  
70 Montgomery and Dietrich, 1994; Wilson and Wieczorek, 1995; Crosta, 1998; Terlien, 1998; Crosta  
71 et al., 2003; Pisani et al., 2010). At this latter purpose, numerical models are employed, and a  
72 notable (and expensive) amount of detailed data is commonly required to define the geological  
73 scheme of the slope in litho-structural, hydrogeological, morphologic and geotechnical terms. The  
74 second approach (adopted in the present study), named “empirical” or “hydrological” (Cascini and  
75 Versace, 1988), is based on a statistical-probabilistic analysis of rainfall series and of dates of  
76 occurrence of landslide activation (see, among the others, Campbell, 1975; Caine, 1980; UNDRO,  
77 1991; Sirangelo and Versace, 1996; Guzzetti et al., 2007; 2008, Brunetti et al. 2010, Gariano et al.,  
78 2015). Methodological examples in literature generally focus on thresholds obtained for *i*) single  
79 phenomena or *ii*) given types of slope movements within a homogeneous geo-environmental setting  
80 (cf. e.g. Jakob and Weatherly, 2003).

81 In this study, the hydrological model  $^{GA}SAKe$  (i.e., the Genetic-Algorithm based release of the  
82 model *Self Adaptive Kernel*) to forecast the triggering of slope movements is described. The model  
83 can be applied to either single landslides or to a set of similar phenomena within a homogeneous  
84 study area. Model calibration is performed by means of Genetic Algorithms: in this way, a family of  
85 optimal, discretized kernels can iteratively be obtained from initial tentative solutions. In another  
86 release of the model ( $^{CM}SAKe$  – i.e., *Cluster model SAKe*) the calibration could instead be  
87 performed through an iterative procedure (Terranova et al., 2013).

88 Examples of application of the model to a medium-size landslide (the Uncino landslide at San Fili)  
89 and to shallow slope movements in the Sorrento Peninsula are discussed in the following sections.

90 Temporal validation is discussed for both cases, in view of early-warning applications of  $^{GA}SAKe$

91 for Civil Protection purposes. Moreover, a progressive, self-adaptive procedure of calibration and  
92 validation is discussed, by considering the Uncino case study, to verify changes in fitness,  
93 predictive ability and base time when an increasing number of dates of activation is employed. In  
94 addition, the results of preliminary, parametric analyses are presented, aimed at investigating the  
95 role of the main parameters of the model.

96

## 97 **2 BACKGROUND**

98 Physical systems evolve in time due to their own inner dynamics and/or as a consequence of  
99 external causes. Suitable observational tools can be employed to monitor their evolution. They can  
100 be arranged to promptly send reports or warnings to the authorities of civil protection to support the  
101 management of emergencies (Cauvin et al., 1998; for applications to landslides, cf. also Keefer et  
102 al., 1987; Iovine et al., 2009; Capparelli and Versace, 2011; Pradhan and Buchroithner, 2012).

103 In the case of complex systems (e.g. nuclear power stations, telecommunication networks, etc.),  
104 many parameters, in part interdependent, have to be monitored. Missing an automated phase of  
105 analysis and proper filtering, a great number of reports may be delivered by the monitoring  
106 apparatus in few seconds. At this purpose, the concepts of threshold (Carter, 2010), event and  
107 warning must therefore be suitably defined.

108 Regarding slope movements, the notions of threshold and warning have long been investigated. In  
109 particular, a threshold constitutes a condition - generally expressed in quantitative terms or through  
110 a mathematical law - whose occurrence implies a change of state (White et al., 1996). According to  
111 the ALARM study group (Cauvin et al., 1998), an event is *i*) a portion of information extracted  
112 from either continuous or discrete signals (i.e. a significant variation), transmitted by a component  
113 of the monitoring network; or *ii*) a set of data concerning the considered context (e.g. restorations,  
114 actions, observations). According to such definition, an event must be instantaneous and dated. As  
115 for warning, its definition derives from that of event: it is a discrete indicator aimed at triggering a  
116 human or an automated reaction. The warning can be classified into distinct levels (e.g. in terms of  
117 security) or by type (e.g. related to a distinct component of the dynamic system under  
118 consideration), to be transmitted by the monitoring system.

119 In complex systems, causal factors responsible for emergency conditions may be difficult to  
120 identify. Therefore, warnings may be issued according to pre-fixed thresholds related to suitable  
121 physical properties of the system. In these cases, the timing of data sampling of the monitoring  
122 instruments should be progressively adapted to the evolution of the phenomenon. A further issue  
123 concerns the chances of missing alarms and of false alarms, as well as the camouflage of an alarm  
124 among simultaneous others.

125 In physical terms, slope instability can occur when the shear strength gets lower than a given  
126 threshold (Terzaghi, 1962). Rain infiltration may temporarily change the dynamics of ground water  
127 (Van Asch et al., 1999): due to an increase in pore water pressure, the effective shear strength of the  
128 material decreases, and a slope movement can be triggered.

129 Groundwater may reach a given location within the slope by different paths. The main natural  
130 mechanisms include: *i*) surface flow, strongly influenced by morphology; *ii*) direct infiltration from  
131 the surface; *iii*) flow within the soil mantle (*throughflow*) from upslope and sideslopes; *iv*) seepage  
132 from the bedrock toward the overlying colluvium. The length of the different paths may be quite  
133 different, and characterized by distinct velocities: as a consequence, aliquots of the same rainfall  
134 event may reach a given site at different times, variously combining with other groundwater  
135 amounts (Ellen, 1988).

136 Aiming at applying a hydrological approach, empirical relations have to be determined by means of  
137 thresholds to distinguish among conditions which likely correspond to landslide occurrence or not.  
138 To this aim, different hydrological parameters can be selected (Guzzetti et al., 2007; 2008 and  
139 <http://rainfallthresholds.irpi.cnr.it/>): the cumulative rain recorded in a given temporal window  
140 (hours/days/months) before landslide activation; the average rain intensity in the same temporal  
141 window; normalized rains to reference values (e.g. annual averages). Simplified hydrological  
142 balances can also be adopted in empirical approaches, by considering losses of aliquots of rains by  
143 run-off, evapo-transpiration, etc.

144 As concerns superficial landslide, triggering thresholds can be derived from relations between the  
145 “triggering” rain (daily, hourly or shorter), corresponding to the onset of the slope movement, and  
146 the cumulative rain in an antecedent period (usually, few days to two weeks before landslide  
147 activation) (e.g. Campbell, 1975; Cannon and Ellen, 1985; Wieczorek, 1987; Terlien, 1996; Crosta,  
148 1998; Zêzere and Rodrigues, 2002). In other cases, thresholds refer to relations between rain  
149 intensity,  $I$ , and duration,  $D$ , (e.g., Brunetti et al., 2010, Berti et al., 2012, Peres and Cancelliere,  
150 2014). In some studies, antecedent rains were also considered, allowing to obtain better results (e.g.  
151 Campbell, 1975). Larger amounts of antecedent rain should allow slope movements to be activated  
152 by less severe triggering storms. In general, a direct relationship between antecedent rain and  
153 landslide dimension can be observed (Cascini and Versace, 1986); though, in some peculiar  
154 conditions (e.g. Hong Kong case studies, caused by suction reduction - Brand et al., 1984) this is  
155 not the case, and the role of antecedent rains looks less important. In addition, as underlined by  
156 Cuomo and Della Sala (2013), among other authors, in unsaturated shallow deposits, time to runoff,  
157 time to failure and runoff rates strongly depend on soil water characteristic curves, soil initial  
158 conditions, rainfall intensity and slope angle. Moreover, soil mechanical parameters affect the time  
159 to failure that can result either shorter or longer than time to runoff.

160 Difficulties in hydrological modelling of landslides generally increase, due to physical and  
161 economic issues, when dealing with deeper and larger phenomena (Cascini and Versace, 1986). In  
162 such cases, landslide activation depends on the dynamics of deeper groundwater bodies. By the  
163 way, it is not by chance that most studies do refer to small and superficial slope movements. Large  
164 slope movements usually show complex relationships with rains, as different groundwater aliquots  
165 may combine and reach the site of landslide triggering. Depending on type (cf. dimension, material,  
166 kinematics, etc.), different hydrological mechanisms should be considered, thus limiting the  
167 possibility of generalization of the thresholds (Dikau and Schrott, 1999; Corominas, 2001; Marques  
168 et al., 2008). Again, the mobilization of deeper phenomena commonly requires greater rainfall  
169 amounts with respect to shallow landslides, spanned over longer periods (Aleotti, 2004; Terranova  
170 et al., 2004; Guzzetti et al., 2007; 2008;). In these cases, rain durations responsible for landslide  
171 activations commonly range from ca. 30 days to several months, even beyond a single rainy season  
172 (Brunsden, 1984; Van Asch et al., 1999; Gullà et al., 2004; Trigo et al., 2005).

173 To analyse the triggering conditions of slope movements – either shallow or deep-seated – a  
174 modelling approach can be employed that is based on the threshold concept. For landslides (e.g.  
175 Aleotti, 2004; Wieczorek and Glade, 2005; Terranova et al., 2004; Vennari et al., 2014), empirical  
176 thresholds can be expressed in terms of curves, delimiting the portion of the Cartesian plane which  
177 contains “all and only” the hydrological conditions related to known activations (cf. e.g. the  $I$ - $D$   
178 chart proposed by Caine, 1980). A further improvement to this approach can be obtained by  
179 considering hydrological conditions not related to landslide activations (Crozier, 1997; Sengupta et  
180 al., 2010; Gariano et al., 2015).

181 In general, no changes of state are assumed to occur below the threshold ( $z_t$ ), while they do happen  
182 above it. Alternatively (Crozier, 1997), a range of conditions can be defined, delimited by:

- 183 ✓ a lower threshold ( $z_{low}$ ), below which changes of state do never occur, and
- 184 ✓ an upper threshold ( $z_{upp}$ ), above which changes always happen.

185 For values between  $z_{upp}$  and  $z_{low}$ , a probability of state change can be defined, essentially depending  
186 on *i*) the incompleteness of knowledge on the physical process under investigation, and *ii*) the  
187 incapacity of the model to fully replicate the behaviour of the same process. In probabilistic terms:

$$\begin{aligned} P(E_t) &= 0 \text{ for } z(t) < z_{low} \\ P(E_t) &= 1 \text{ for } z(t) > z_{upp} \\ P(E_t) &= G[z(t)] \text{ for } z_{low} \leq z(t) \leq z_{upp} \end{aligned} \quad (1)$$

188 in which:  $P$  is the probability of occurrence (1=success, 0=unsuccess);  $E_t$  is a process (succession of  
189 events) whose states change with time  $t$ ;  $z(t)$  is the value assumed, at time  $t$ , by the variable that  
190 determines the change of state;  $z_{low}$  and  $z_{upp}$  are the minimum and maximum thresholds,  
191 respectively;  $G[z(t)]$  is a probability function, monotonically increasing with  $t$  in the range ]0,1[.

192 In hydrological models, to express the influence of rainfalls on runoff and groundwater dynamics, a  
193 “kernel” (also named “filter function”) can be employed, usually defined in terms of simple,  
194 continuous analytical functions (Chow et al., 1988). In such a way, suitable weights can be assigned  
195 to the precipitations occurred in the last hours/days before a given geo-hydrological process (e.g.  
196 discharge, measured at a generic river cross section; landslide activation), as well as to earlier rains  
197 recorded weeks/months before. The following types of kernels are among the most utilized: Beta,  
198 Gamma, Nash, negative exponential distribution. Furthermore, in this type of models, the “base  
199 time” ( $t_b$ ) expresses a sort of memory with respect to rainfalls. For instance, in classic rainfall-  
200 runoff modelling,  $t_b$  defines the time of concentration, while in slope stability analyses it represents  
201 the time interval, measured backward from landslide activation, during which rainfall is deemed to  
202 effectively affect groundwater dynamics, contributing to destabilization.

203 To modelling slope stability, both the shape and the base time of the kernel must be properly  
204 selected by considering type and dimension of the investigated phenomena, as well as geo-structural  
205 and hydrogeological characteristics. Unfortunately, in several real cases, the above-mentioned  
206 analytical functions may fail in capturing the complexity of groundwater dynamics properly, as well  
207 as the related landslide activations. In this respect, the adoption of discretized kernels, automatically  
208 calibrated through iterative computational techniques, may offer effective solutions.

209

### 210 **3 THE MODEL *GASAKe***

211 *GASAKe* is an empirical-hydrological model for predicting the activation of slope movements of  
212 different types. It is based on a classic threshold scheme: the exceedance of the threshold  
213 determines a change of state, i.e. the triggering of the landslide. The scheme is inspired from the  
214 *FLaIR* model (*F*orecasting *L*andslides *I*nduced by *R*ainfall), proposed by Sirangelo and Versace  
215 (1996): through changes of state in time, the variable  $z(t)$  assumes the meaning of “*mobilization*  
216 *function*”. In other terms, the values of  $z(t)$  depend on the amount of rain stored in the aquifer.

217 In hydrology, rainfall-runoff modelling is commonly performed by adopting a linear, steady scheme  
218 (Chow et al., 1988). Such approach implies that the transformation of rainfall in runoff can be  
219 described by an integral of convolution between a unitary impulsive response of the basin – the  
220 kernel,  $h(t)$  – and the rainfall,  $p(t)$ .

221 The *kernel* (*filter function*) represents the unitary volume influx in an infinitesimal period, and is  
222 defined as:

$$\int_0^{\infty} h(t)dt = 1 \quad (2)$$

223 in which  $h(t)=h(-t)$ ,  $h(t) \geq 0$ ,  $\forall t$ .

224 In practical applications, the lower bound ( $t=0$ ) corresponds to the beginning of the flood-wave  
 225 rising, and the kernel assumes a finite duration ( $t_b$ ). The integral of convolution is therefore  
 226 expressed as:

$$z(t) = \int_0^{t_b} h(t - \tau) p(\tau)d\tau = \int_0^{t_b} h(\tau) p(t - \tau)d\tau \quad (3)$$

227 in which  $z(t)$  represents the discharge at the time  $t$ . For a specific case study, the kernel can be  
 228 determined by means of calibration procedures, by relating discharge measurements to rains.

229 In discretized terms, the elements of the kernel are characterized by width  $\Delta t$  and height  $h_i$ , and  
 230 equation (3) can be written as:

$$z_u = \sum_{i=1}^u h_i \cdot p_{u-i+1} \cdot \Delta t \quad (4)$$

231  
 232 Sirangelo and Versace (1996) proved that the same approach may turn out promising also for slope-  
 233 stability modelling. Capparelli and Versace (2011) stressed that the *I-D* chart of Caine (1980)  
 234 corresponds to a kernel defined by a power function  $h(t) = a t^b$ , with  $b < 0$ . The main difficulty in  
 235 exporting the well-established knowledge of rainfall-runoff modelling, usually based on many  
 236 measurements, to rainfall-landslide modelling lies in the scarcity of adequate information for proper  
 237 calibration. In the latter case, only few dates of activation are in fact commonly available (often  
 238 with unsatisfactory details on location and phenomena), and the values of  $z(t)$  are unknown. From a  
 239 mathematical point of view, such a problem can be handled by assuming that the timing of the  
 240 maxima of  $z(t)$  corresponds to the dates of landslide activation. When studying the triggering  
 241 conditions of landslides, calibration can be therefore performed by maximizing the mobilization  
 242 function in correspondence of the dates of activation.

243 Scarcity of information inevitably reflects on the resulting kernel, whose shape may turn out highly  
 244 indeterminate: different functions, or different parameters of the same function, can in fact  
 245 maximize  $z(t)$  in correspondence of the dates of mobilization. Model optimization – and its reliable  
 246 utilization for early-warning purposes – can turn out an awkward issue.

247 In this work, an innovative modelling approach – based on discretized kernels, automatically  
 248 calibrated through iterative computational techniques – is proposed, which may help in facing the  
 249 above-cited difficulties. For modelling purposes, the rainfall series and a coherent set of dates of  
 250 landslide occurrence – either related to a given slope movement, or to a set of landslides of the same  
 251 type in a homogeneous geo-environmental zone – must be given as input to *G<sup>A</sup>SAKe*.

252 Unfortunately, when dealing with the timing of occurrence, historical notices may refer either to  
 253 portions of the considered phenomena or to entire landslide bodies. Therefore, dates should be  
 254 properly selected to consider only consistent cases. Moreover, dates of activation are usually known  
 255 with only a broad approximation: with respect to the reports, the actual timing of occurrence may be  
 256 located backward (documents may assign a later date) or forward (in case of later, more relevant  
 257 movements). For modelling purposes, it is then useful to specify a temporal window, lasting from  
 258 an initial ( $d_{t-from}$ ) to a final date ( $d_{t-to}$ ), containing the presumable date of occurrence.

259 Rainfall series are commonly reconstructed from data recorded at rain gauges located in a  
 260 reasonable proximity of the study area. The temporal window of the hydrological analysis is

261 defined by the intersection of *i*) the period of observation of the rains and *ii*) that delimited by the  
262 ancientmost and the recentmost dates of activation of the landslide. A potential source of  
263 uncertainty lies in the fact that, occasionally, the considered rain gauge records amounts that  
264 notably differ from those actually experienced at landslide location. Furthermore, landslide  
265 triggering may also be due to causes different from rainfall (e.g. human activity, earthquakes): a  
266 thorough preliminary analysis must always be performed to verify the significance of rainfall  
267 preceding landslide activation, to detecting cases not to be considered in the hydrological study.  
268 In the model, rains older than  $t_b$  are neglected. Suitable maximum and minimum values ( $t_{b-max}$  and  
269  $t_{b-min}$ ) must be initialized to allow the model to determine optimal values. Commonly,  $t_b$  ranging  
270 from few hours to some weeks are suggested for shallow landslides, while greater values (up to  
271 several months) sound suitable for deep-seated phenomena.  
272 Based on the geological knowledge of the phenomenon under investigation, the initial shape of the  
273 kernel can be selected among a set of basic types. Among these, *i*) a “rectangular” shape can be  
274 adopted if older precipitations must have the same weight of more recent rains; *ii*) a “decreasing  
275 triangular”, if older precipitations are assumed to have a progressively smaller weight than more  
276 recent rains; *iii*) “increasing triangular”, if older precipitations are assumed to have a progressively  
277 greater weight than more recent rains. A casual shape or any other function can also be  
278 implemented in the model (e.g., Beta, Gamma, Nash, Negative exponential distribution).

279

### 280 3.1 Model Calibration

281 In  $GA^{SAKe}$ , model calibration is performed against real case studies through Genetic Algorithms  
282 (GAs). These latter are general-purpose, iterative search algorithms inspired by natural selection  
283 and genetics (Holland, 1975). Since 1970’s, GAs have been applied to several fields of research,  
284 from applied mathematics (Poon and Sparks, 1992), to evolution of learning (Hinton and Nowlan,  
285 1987), evolutionary robotics (Nolfi and Marocco, 2001), and debris-flow modelling (Iovine et al.,  
286 2005; D’Ambrosio et al., 2006). GAs simulate the evolution of a population of candidate solutions  
287 to a given problem by favouring the reproduction of the best individuals. The candidate solutions  
288 are codified by genotypes, typically using strings, whose elements are called genes.  
289 GAs explore the solution space, defined as the set of all possible values of the genes. At the  
290 beginning of a given optimization experiment, the members of the initial population of genotypes  
291 (in this study, the *kernels*) are usually generated at random. The performance of each solution, in  
292 terms of phenotype (i.e. the *mobilization function*), is evaluated by applying a suitable *fitness*  
293 *function*, so determining its “adaptability”, i.e. the measure of its goodness in resolving the problem.  
294 The sequence of random genetic operators “selection, crossover and mutation”, constrained by  
295 prefixed probabilities, constitutes a single GA-iteration that generates a new population of candidate  
296 solutions. At each iteration, best individuals are in fact chosen by applying the selection operator.  
297 To form a new population of offspring, crossover is employed by combining parents’ genes.  
298 Mutation is successively applied to each gene, by randomly changing its value within the allowed  
299 range.

300 Thanks to the GA approach, better individuals (i.e. characterized by higher fitness values) can be  
301 obtained over time. In fact, according to individual probabilities of selection, any change that  
302 increases the fitness tends to be preserved over the GA iterations (Holland, 1975). For further  
303 details on GAs, cf. Goldberg (1989) and Mitchell (1996).

304 In the present study, a steady-state and elitist GA (cf. De Jong, 1975) was employed to obtain the  
305 family of optimal kernels that maximize the mobility function in correspondence with known dates

306 of landslide activations. The procedure employed for calibration of  $GA\text{SAKe}$  is schematized in Figure  
307 1.

308 At the beginning of an optimization experiment, the initial population of  $N$  kernels is generated at  
309 random, and the fitness of the related mobility functions is evaluated (cf. below). In order to evolve  
310 the initial population of candidate solutions and progressively obtaining better solutions, a total  
311 number of  $A$  GA-iterations follows.

312 At each iteration of the GA, the operators selection, crossover and mutation are applied as follows  
313 (Fig. 2):

314 • *selection*

315 *i.*  $n_e$  “elitist” individuals are merely copied in a “mating pool” from the previous generation, by  
316 choosing the best ones;

317 *ii.* the remaining  $N-n_e$  candidate solutions are chosen by applying the “*tournament without*  
318 *replacement*” selection operator. More in detail, a series of tournaments are performed by  
319 selecting two individuals at random from the previous generation: the winner (i.e. the one  
320 characterized by the highest fitness) is copied into the mating pool, according to a prefixed  
321 surviving probability ( $p_s$ ), which is set greater for the fittest individual. Note that, when  
322 choosing the  $N-n_e$  candidate solutions, a given individual cannot be selected more than once.

323 • *crossover*

324 After the mating pool is filled with  $N$  individuals, the crossover operator is applied, according to  
325 a prefixed probability ( $p_c$ ):

326 *i.* two parent individuals are chosen from the mating pool at random;

327 *ii.* a cutting point (*crossover point*) is then selected at random in the range  $]t_{b-min}, t_{b-max}[$ ;

328 *iii.* the so-obtained portions of parents’ strings are exchanged, thus mixing the genetic information  
329 and resulting in two children (Fig. 3).

330 When the crossover is not applied, the two parents are merely copied into  $P_{new}$ .

331 • *mutation*

332 Based on a prefixed probability ( $p_m$ ), a random number of elements of the kernel ( $p_{me}$ , expressed  
333 as a percentage of  $t_b$ ) is mutated, by adding to each element an amount  $dh$  that is randomly  
334 obtained in the range  $[p_{mh1}, p_{mh2}]$ , as a function of the maximum value of the kernel ( $h_{max}$ ). Then  
335  $dh$  ranges from  $dh_1$  to  $dh_2$ :

$$\begin{aligned} dh_1 &= p_{mh1} \cdot h_{max} \\ dh_2 &= p_{mh2} \cdot h_{max} \end{aligned} \quad (5)$$

336 Furthermore, the base time is also mutated (increased or decreased) within the bounds  $[t_{b-min}, t_{b-}$   
337  $max]$ , according to a random factor  $dt_b$  selected in the range  $[1/p_{mtb}, p_{mtb}]$  (Fig. 4).

338 Note that the children obtained after both crossover and mutation must be normalized, before they  
339 can be included in the population  $P_{new}$ , by properly scaling the elements of the kernels to ensure  
340 validity of equation 2.

341 During calibration, the shape of the kernel and its  $t_b$  are iteratively refined. Note that the shape is not  
342 subject to any constraint, while  $t_b$  is allowed to vary in the range  $[t_{b-min} - t_{b-max}]$ . The fitness is  
343 computed for each examined mobilization function, and new populations of kernels are generated as  
344 described above.

345 As for the fitness function, in  $GA\text{SAKe}$  it is defined as follows:

346 • the  $L$  available dates of landslide activation – as derived from the historical analyses – are  
347 arranged in a vector  $\mathcal{S} = \{S_1, S_2, \dots, S_i, \dots, S_L\}$ ;

- 348 • the vector of the relative maxima of the mobility function,  $\mathbf{Z} = \{z_1, z_2, \dots, z_j, \dots, z_M\}$ , is sorted
- 349 in decreasing order ( $M =$  number of relative maxima);
- 350 • the vector of the partial fitness is  $\boldsymbol{\varphi} = \{\varphi_1, \varphi_2, \dots, \varphi_i, \dots, \varphi_L\}$ , where  $\varphi_i = k^{-l}$  depends on the rank  $k$
- 351 of the relative maxima of  $z_j$  that coincide with known dates of activation  $S_i$ . In case  $S_i$  does not
- 352 correspond to any relative maximum, it is  $\varphi_i = 0$ .

353 With reference to a given kernel, the resulting fitness is expressed by  $\Phi_u = \sum_{i=1}^L \varphi_i$ . Aiming at

354 generalizing the results for easier comparison to other study cases, a normalized fitness index is

355 adopted,  $\Phi = \Phi_u / \Phi_{max}$ , defined in the range  $[0,1]$ , being  $\Phi_{max} = \sum_{i=1}^L 1/i$ .

356 For instance, if two dates of activation are available, the obtained fitness is  $\Phi_u = 1 + 1/2 = 1.5$  if both

357 are well captured by the mobility function (i.e. they correspond to the highest peaks). On the other

358 hand, in case only one of the dates is captured and the remaining one ranks fifth,  $\Phi_u = 1 + 1/5 = 1.2$ .

359 Thanks to the above procedure, a family of “optimal kernels” which maximizes the fitness can be

360 determined. The mobility function is in fact forced toward a shape characterized by relative maxima

361 ( $z_j$ ) coinciding with the dates of landslide occurrence ( $S_i$ ). An optimal solution leads to a mobility

362 function having the highest peaks in correspondence with such dates; further peaks may also be

363 present, characterized by lower values. Nevertheless, kernel solutions generally determine mobility

364 functions whose highest peaks only partly match with the dates of landslide occurrence (i.e. some

365 dates may not correspond to the highest peaks nor to any peak at all).

366 To selecting the most suitable kernel from a given family of optimal ones, let’s define:

- 367 •  $z_{j-min}$  as the lowest of the peaks of the mobility function in correspondence with one of the dates
- 368 of activation ( $S_i$ );
- 369 •  $z_{cr}$  as the “critical threshold”, i.e. the highest peak of the mobility function just below  $z_{j-min}$ ;
- 370 • the “safety margin”,  $\Delta z_{cr} = (z_{j-min} - z_{cr}) / z_{j-min}$ .

371 When applying the fitness function to evaluate a given kernel, either incompleteness or low

372 accuracy of input data may lead to “false alarms” – i.e. peaks of the mobility function ( $z_j$ ) which are

373 greater than the threshold  $z_{cr}$ , but do not correspond to any of the known dates of activation. Such

374 alarms can actually be of two different types: 1) “untrue false”, due to an informative gap in the

375 archive (i.e. correct prediction); 2) “true false”, in case of real misprediction of the model. On such

376 cases, further historical investigations may help to discriminating between the mentioned types of

377 false alarms.

378 Also depending on the specific purpose of the analysis, the most suitable kernel can therefore be

379 selected by one or more of the following criteria: *i*) the greatest  $\Delta z_{cr}$ ; *ii*) the shortest  $t_b$ ; *iii*) the

380 smallest  $\mu_0 = \sum_{i \leq t_b} (i - 0.5) h_i \Delta t$ , i.e. the first-order momentum of the kernel with respect to the

381 vertical axis. The first criterion allows for activating early-warning procedures with greatest

382 advance; the remaining ones (to be employed when  $\Delta z_{cr}$  is too small) generally correspond to more

383 impulsive responses to rainfall.

384 Differently from what usually experienced in rainfall-runoff models, <sup>GA</sup>*SAKe* therefore provide

385 multiple equivalent solutions - i.e. a number of optimal kernels with same fitness,  $\Phi_u$ , despite

386 different shapes. This may depend on the limited number of available dates of activations, and on

387 other noises in input data (e.g. rain gauges located too far from the site of landslide activation;

388 inaccurate information on dates of activation or on the phenomenon). The adoption of synthetic

389 kernels – e.g. obtained by averaging a suitable set of optimal kernels – allows to synthesize the

390 family of results for successive practical applications: in this work, the best 100 kernels obtained for

391 each case study were in fact utilized to synthesize average kernels to be employed for validation  
392 purposes.

393

#### 394 **4 CASE STUDIES**

395 The case studies considered in this paper are: *i*) a set of shallow landslides in the Sorrento Peninsula  
396 between Gragnano and Castellammare di Stabia (Campania, Southern Italy); and *ii*) the Uncino  
397 landslide at San Fili (Calabria, Southern Italy).

398 Note that, as the numbers of known historical activations in the study areas were adequate, some  
399 dates could be excluded from calibration, and were successively employed for validation purposes.

400 In particular, the recentmost dates of landslide activation (cf. Tables 1 and 2) were considered to  
401 validating the “average kernels” (see below), as obtained from the families of optimal solutions  
402 defined through calibration. The procedure employed for validation is schematized in Figure 5.

403

##### 404 **4.1 Shallow landslides in the Sorrento Peninsula - Campania**

405 The Sorrento Peninsula is located in western Campania, Southern Italy (Fig. 6). In the area,  
406 Mesozoic limestone mainly crop out, covered by Miocene flysch, Pleistocene volcanic deposits  
407 (pyroclastic fall, ignimbrite), and Pleistocene detritical-alluvial deposits (Di Crescenzo and  
408 Santo, 1999). The carbonate bedrock constitutes a monocline, gently dipping towards WNW,  
409 mantled by sedimentary and volcanoclastic deposits, with thickness ranging from few decimetres to  
410 tens of meters.

411 Rainfall-induced shallow landslides are widespread in the pyroclastic soils covering the slopes of  
412 the study area. Among the various factors affecting the spatial distribution and the type of slope  
413 instability, Cascini et al. (2014) pointed out that both the rainfall conditions and the consequent  
414 seasonal variations of soil suction play a significant role. In particular, when suction is low and  
415 frontal rainfall occurs (from November to May) first time shallow landslides are triggered; when  
416 suction is high or very high and convective or hurricane-type rainfall occurs (from June to October)  
417 mostly erosion phenomena occur, often turning into hyperconcentrated flows.

418 The study area is characterized by hot, dry summers and moderately cold and rainy winters.  
419 Consequently, its climate can be classified as Mediterranean (Csa in the Köppen-Geiger's  
420 classification). In particular, the mean annual temperature ranges from 8-9°C, at the highest  
421 elevations of M. Faito and M. Cerreto, to 17-18°C along coasts and valleys. Average annual rainfall  
422 varies from 900 mm west of Sorrento to 1500 mm at M. Faito; moving inland to the East, it reaches  
423 1600 mm at M. Cerreto and 1700 mm at the Chiunzi pass (Ducci and Tranfaglia, 2005). On  
424 average, annual totals are concentrated in about 95 rainy days. During the driest six months (from  
425 April to September), only 30% of the annual rainfall is recorded in about 30 rainy days. During the  
426 three wettest months (November, October, and December), a similar amount is recorded in about 34  
427 rainy days (Servizio Idrografico, 1948-1999). In the area, convective rainstorms may occur,  
428 characterized by a very high intensity, at the beginning of the rainy season (from September to  
429 October). In Autumn-Winter, either high intensity or long duration rainfall are usually recorded,  
430 while uniformly distributed rains generally occur in Spring (Fiorillo and Wilson, 2004). As for  
431 annual maxima of daily rainfall recorded at the sea level, the Amalfi coast (southern border of the  
432 Sorrento Peninsula) is characterized by smaller values (59 mm) of average annual maxima of daily  
433 rainfall than the Sorrento coast (86 mm), on the northern border. Such difference seems to persist  
434 even at higher elevations (up to 1000 m a.s.l.), with 84 mm vs. 116 mm for the southern and  
435 northern mountain slopes, respectively (Rossi and Villani, 1994).

436 Severe storms frequently affect the study area, triggering shallow landslides that propagate seaward,  
437 often causing casualties and serious damage to urbanized areas and transportation facilities (Mele  
438 and Del Prete, 1999; Calcaterra and Santo, 2004; Di Crescenzo and Santo, 2005). In the second half  
439 of the XX century, several shallow landslides activated nearby Castellammare di Stabia: in Table 1,  
440 the major events recorded between Vico Equense and Gragnano are listed, with details on types of  
441 events, affected sites and references. Shallow landslides listed in Table 1 occurred between  
442 November and March, a period characterised by a medium to low suction range and included in the  
443 rainy season (October to April) according to Cascini et al. (2014). The same Authors pointed out  
444 that, in this period, frontal rainfall typically occurs and may trigger widespread first-time shallow  
445 landslides later propagating as debris flow or debris avalanches.  
446 Rainfall responsible for landslide occurrences in the Sorrento Peninsula are shown in Fig. 7, in  
447 terms of cumulated antecedent rains, extracted from the records of the nearest gauges (Tramonti,  
448 Castellammare, and Tramonti-Chiunzi – cf. Fig. 6). The trends of antecedent rains look quite  
449 differentiated, ranging from abrupt (cf. curves 5, 6, 7) to progressive increases (cf. 2, 4, 10). On the  
450 other hand, the curve 0 does not highlight significant amounts of rainfall in the 14 days preceding  
451 landslide activation: therefore, the occurrence recorded on 14 April 1967 was excluded by the  
452 hydrological analysis. Quite moderate amounts of cases 6 and 7 (occurred on 4 November 1980 and  
453 14 November 1982, resp.) were instead recorded in short periods, thus resulting into high-intensity  
454 events that could be considered as triggering factor of the observed landslides.  
455 As a result, the dates of activation from #1 to #10 were selected for calibration, whilst #11 was  
456 employed for validation. As shallow landslides were being considered, the rainfall period employed  
457 for calibration spanned from 17 January 1963 to 10 December 1996; for validation, the rainfall  
458 series terminates on 10 February 1997 – i.e. the validation date  $+t_b$  (this latter as obtained from  
459 calibration).

#### 461 **4.2 The Uncino landslide - San Fili (Northern Calabria)**

462 San Fili (Fig. 8) is located on the western margin of the Crati *graben*, a tectonic depression  
463 belonging to the active Calabrian-Sicilian Rift Zone (Monaco and Tortorici, 2000). In the area,  
464 vicarious, N-S trending normal faults mark the base of the Coastal Chain, at the transition between  
465 Palaeozoic metamorphic rocks, to the west, and Pliocene-Quaternary sediments, to the east  
466 (Amodio Morelli et al., 1976). Nearby San Fili, Palaeozoic migmatitic gneiss and biotitic schist,  
467 generally weathered, are mantled by a Late Miocene sedimentary cover of reddish continental  
468 conglomerates, followed by marine sandstone and clays (CASMEZ, 1967).

469 In particular, the village lies in the intermediate sector between the two faults, marked by a NE-SW  
470 trending connection fault, delimiting the Miocene sediments on the north from the gneissic rocks on  
471 the South.

472 The Calabrian Tyrrhenian sector (including the study area) results rainier than the Ionian (about  
473 1200-2000 mm vs. 500 mm), although the most severe storms are more frequently recorded on the  
474 Ionian sector (Terranova, 2004). The average annual temperature is about 15°C: the coldest months  
475 are January and February (in average 5°C), followed by December (8°C); the hottest months are  
476 July and August (24°C), followed by June (22°C).

477 The climate at San Fili, like in most of Calabria, is Mediterranean (Csa), according to Köppen  
478 (1948). Being located on the Eastern side of a ridge, the area is subject to *Staii* conditions with  
479 respect to perturbations coming from the Tyrrhenian sea. It is characterized by heavy and frequent  
480 Winter rainfall, caused by cold fronts mainly approaching from North-West, and Autumn rains,

481 determined by cold air masses from North-East. In Spring, rains show lower intensities than in  
482 Autumn, whilst strong convective storms are common at the end of Summer.  
483 The average monthly rains recorded at the Montalto Uffugo gauge (the closest to San Fili) are listed  
484 in Table 2. From October to March (i.e. the wet semester), 77% of the annual rainfall is totalized in  
485 about 77 rainy days and 36% is recorded in 38 days, during the three wettest months; finally, from  
486 June to August (i.e. the three driest months), 6% of the annual rains fall in 11 days.  
487 The Uncino landslide is located at the western margin of San Fili (Fig. 8). The rock slide is of  
488 medium-size (maximum width = 200 m, length > 650 m, estimated maximum vertical depth = 25  
489 m), with a deep-seatedness factor (sensu Hutchinson, 1995) that may be classified as  
490 “intermediate”. It involves Late Miocene conglomerate, arenite and marly clay overlaying  
491 Palaeozoic gneiss and biotitic schist. The slope movement repeatedly affected the village, damaging  
492 the railway and the local road network, in addition to some buildings: the ancientmost known  
493 activation dates back to the beginning of the XX Century (Sorriso-Valvo et al., 1996); from 1960 to  
494 1990, a set of 7 dates of mobilization are listed in Table 3. On such events, the railroad connecting  
495 Cosenza to Paola was damaged or even interrupted. Note that, having not been recorded by  
496 landslide experts, such type of information is usually affected by intrinsic uncertainty (e.g.  
497 concerning the dates of activity) and may be related to either partial or total activations of the  
498 phenomenon, with unavoidable problems of homogeneity of the set employed for model calibration.  
499 By the way, on 28 April 1987, the railway was put out of service, hence the relevance of the  
500 infrastructure decreased, together with media attention.  
501 The informative content of the Uncino case study is quite high, and allows for a more accurate  
502 calibration of the kernel with respect to the Sorrento Peninsula case: consequently, a smaller family  
503 of optimal solutions are expected. Nevertheless, the known activations still suffer from uncertainties  
504 related to dates and affected volumes.  
505 Cumulated antecedent rains, corresponding to the Uncino landslide occurrences, are shown in Fig.  
506 9. Rainfall data were extracted from the records of the nearest rain gauge, located at Montalto  
507 Uffugo (cf. Fig. 8). The trends of antecedent rains may be distinguished into 3 main patterns: the  
508 curve 2 shows a constant increase of rainfall in time, totalizing the greatest amounts from ca. 90 to  
509 180 days. On the other hand, the case 0 shows the lowest values throughout the considered  
510 accumulation period. The curves 1, 3, 4, and 5 totalize intermediate values, with abrupt increases  
511 shown by 3 and 5 from 120 to 180 days. Finally, the case 6 looks similar to case 2 between 30 and  
512 90 days, but shows no more increases in the remaining period (analogously to 1 and 4).  
513 The curve 0 does not highlight significant amounts of rainfall in the 30-180 days preceding the  
514 landslide activation: for this reason, the occurrence recorded on 23 November 1988 was excluded  
515 from the hydrological analysis. Of the remaining curves, case 1 generally shows the lowest amounts  
516 from ca. 40 to 180 days.  
517 As a result, the dates of activation from #1 to #5 were selected for calibration, whilst #6 was  
518 employed for validation. As a medium-size landslide was being considered, the rainfall period  
519 employed for calibration spans from 1 September 1959 to 31 August 1980; for validation, it ranges  
520 from 1 September 1980 to 31 March 1981 - i.e. including the validation date by ca.  $\pm t_b$  (this latter  
521 as obtained from calibration).

## 522

## 523 **5 RESULTS**

524 <sup>GA</sup>SAKe was applied to shallow-landslide occurrences in the Sorrento Peninsula and to a medium-  
525 size slope movement at San Fili, by considering the dates of activation and the daily rainfall series  
526 mentioned in section §4.1 and §4.2, and adopting the values of parameters listed in Table 4.  
527 As several kernels, among those obtained from calibration, usually allow obtaining similar fitness  
528 values, “average kernels” were computed for the considered case studies, by averaging the best 100  
529 kernels.

530

### 531 **5.1 Application to shallow landslides in the Sorrento Peninsula**

532 In Table 5, the statistics related to the family of optimal kernels (made of the best 100 filter  
533 functions, as obtained from calibration) are summarized. From such values, a low variability of  $\Phi$ ,  
534  $t_b$  and  $\mu_0$  can be appreciated;  $\Delta z_{cr}$  shows instead a greater range of values. The average kernel for the  
535 Sorrento Peninsula case study is shown in Figure 10: it is characterized by fitness = 0.806, with  $\Delta z_{cr}$   
536 = 0.00282, and  $t_b = 28$  days. From such kernel, antecedent rainfall mostly affecting landslide  
537 instability range from 1 to 12 days, and subordinately from 25 to 26 days. Negligible weights refer  
538 to rains occurred in the remaining period.

539 In Fig. 11, the mobility function related to the average kernel is shown. In this case, 4 out of 10  
540 dates of landslide activation are well captured by the model (being ranked at the first 7 positions of  
541 the mobility function maxima); the remaining 6 dates do also correspond to relative maxima of the  
542 function, but are ranked from the 43<sup>rd</sup> to the 151<sup>st</sup> position. When considering the remaining relative  
543 maxima, several false positives can be recognized, mainly up to 1979.

544 During calibration, the best fitness ( $\Phi=0.807$ ) was first reached after 1749 iterations (at 6<sup>th</sup>  
545 individual), with  $\Delta z_{cr} = 0.00441$  and  $t_b = 26$  days. The kernel corresponding to such individual looks  
546 similar to the best one in terms of  $t_b$ ,  $\Delta z_{cr}$ , and  $\mu_0$  (Fig. 12). The pattern of the best kernel is only  
547 slightly dissimilar from the average one: significant weights can in fact be appreciated up to 14  
548 days, and then between 20-22 and 25-26 days.

549 By applying the average kernel, a validation was performed against the remaining date of activation  
550 (cf. Table 1, #11, multiple event occurred on 10 January 1997). Validation resulted fully satisfied,  
551 as shown in Fig. 13: the value of the mobilization function for the event #11, in fact, is well above  
552 the  $z_{cr}$  threshold (49.01 vs. 18.05), and is ranked as II highest value among the function maxima  
553 (Fig. 13a). The same peak can also be appreciated as the maximum of the period  $\pm t_b$  (Fig. 13b).  
554 Accordingly, if adopting the average kernel, the event #11 of landslide activation could properly be  
555 predicted by the model.

556

### 557 **5.2 Application to the Uncino landslide**

558 In Table 6, the statistics related to the family of optimal kernels are summarized. From such values,  
559 a low variability of  $t_b$  and  $\Delta z_{cr}$  can be appreciated. The average kernel for the Uncino case study is  
560 shown in Fig. 14.

561 The average kernel is characterized by fitness = 1,  $\Delta z_{cr} = 0.0644$ , and  $t_b = 66$  days. Based on such  
562 kernel, antecedent rains from 1 to 17 days, and from 27 to 45 days, mainly affect landslide  
563 instability. Relatively smaller weights pertain to the rains occurred more than 53 days before the  
564 triggering; for periods older than 66 days, the weights are negligible.

565 In Fig. 15, the mobility function related to the average kernel highlights that all the 5 dates of  
566 activation are well captured by the model (they are ranked at the first 5 positions among the

567 function maxima). When considering the remaining relative maxima of the function, only 4 of them  
568 evidence quasi-critical situations (between 1965 and 1966, and subordinately in 1970 and 1977).  
569 During calibration, the best fitness ( $\Phi=1$ ) was first reached after 684 iterations (at 13<sup>th</sup> individual)  
570 with  $\Delta z_{cr} = 0.0595$ . The best kernel (Fig. 16) was obtained at iteration 993, at 8<sup>th</sup> individual, with  
571  $\Delta z_{cr} = 0.0631$ . Its pattern results very similar to the average one, with a  $t_b$  of 66 days.  
572 By applying the average kernel, a validation was performed against the last known date of  
573 activation (cf. Table 3, #6, occurred on December 1980). Validation resulted fully satisfied, as  
574 shown in Fig. 17: the value of the mobilization function for the event #6, in fact, is well above the  
575  $z_{cr}$  threshold (17.49 vs. 16.87), and is ranked as the sixth highest value among the function maxima  
576 (Fig. 17a). The same peak can be appreciated as the maximum of the period  $\pm t_b$  (Fig. 17b).  
577 Accordingly, if adopting the average kernel, the event #6 could properly be predicted by the model.  
578

## 579 **6 SELF-ADAPTIVE PROCEDURE AND SENSITIVITY ANALYSES**

580 The capability of the model to react and self-adapt to input changes, like new dates of landslide  
581 activation, was evaluated by a progressive, self-adaptive procedure of calibration and validation,  
582 using the information available for the Uncino case study. To simulate the adoption of *GA SAKe* in a  
583 landslide warning system, the model was iteratively calibrated by the first 2, 3, 4, and 5 dates of  
584 activation ( $L$ ), and validated against the remaining 4, 3, 2, 1 dates, respectively. In each experiment,  
585 the GA-parameters listed in Table 4 were adopted. Finally, the model was merely calibrated by  
586 considering all the 6 dates of activation. The results of the self-adaptive procedure are listed in  
587 Table 7. The related kernels are shown in Fig. 18. As a result, a progressive increase in fitness and  
588 predictive ability ( $\Delta z_{cr}$ ), together with the base time (ranging from 30 to 80 days), can be  
589 appreciated when employing a greater number of dates of activation.

590 Furthermore, aiming at evaluating the sensitivity of the model with respect to the GA parameters, a  
591 series of analyses was performed by considering the Uncino case study. More in detail, the  
592 experiments carried out are listed in Table 8. Each simulation stopped after 1500 iterations: GA-  
593 parameters were initialized by considering the “benchmark experiment” (cf. values in Table 4),  
594 except for the parameter that was in turn varied as indicated in Table 8.

595 By varying the GA parameters listed in Table 8, the maximum fitness ( $\Phi_{max}$ ), the safety margin  
596 ( $\Delta z_{cr}$ ), the number ( $n_i$ ) of iterations needed to first reach  $\Phi_{max}$ , and the base time ( $t_b$ ) of the average  
597 kernel are shown in Fig. 19. If experiments with  $\Phi_{max} = 1$  are only taken into account, the minimum  
598 and maximum numbers ( $min\_A$ ,  $max\_A$ ) of GA-iterations needed to reach  $\Phi_{max}$ , the minimum and  
599 maximum base times ( $min\_t_b$ ,  $max\_t_b$ ) of the average kernel, and the minimum and maximum safety  
600 margins ( $min\_ \Delta z_{cr}$ ,  $max\_ \Delta z_{cr}$ ) of the average kernel are listed in Tables 9, 10 and 11.  
601

## 602 **7 DISCUSSION E CONCLUSIONS**

603 In the present paper, the model *GA SAKe* is presented with examples of application to shallow-  
604 landslides in Sorrento Peninsula (Campania), and to the medium-size Uncino landslide at San Fili  
605 (Calabria). Furthermore, the capability of the model to simulate the occurrence of known landslide  
606 activations was evaluated by a progressive, self-adaptive procedure of calibration and validation  
607 against the Uncino case study. Finally, the sensitivity of the model with respect to the GA  
608 parameters was analysed by a series of experiments, performed again by considering the latter  
609 landslide.

610 As concerns the Sorrento Peninsula case study, the maximum fitness obtained during calibration is  
611 smaller than unity. For the best 100 kernels,  $\Phi_{max}$ ,  $\Delta z_{cr}$  and  $t_b$  vary in a small range (ca. 0.1%, 4.8%,  
612 and 13%, respectively). Furthermore, as mentioned above, for specific types of application (e.g.  
613 civil protection), the observed small values of  $\Delta z_{cr}$  would imply short warning times. Consequently,  
614 a suitable kernel should be rather selected by privileging the shortest  $t_b$  or the smallest  $\mu_0$ . In Fig.  
615 12, the four kernels point out that the greatest weights for the first 12-15 days are obtained by  
616 selecting the kernel with smallest  $\mu_0$ , thus allowing for the most timely advice if used within an  
617 early-warning system.

618 In the average kernel, the greatest weight can be attributable to the first 12 days, with a maximum  
619 base time of about 4 weeks, reflecting the general shape of the curves in Fig. 7, and in good  
620 agreement with the shallow type of slope instability considered.

621 Furthermore, the validation of the average kernel is satisfactory, as the validation date (#11 in Table  
622 1) corresponds to the second highest peak of the mobility function. In addition, no missing alarms  
623 and only four false alarms in about 5 years are to be found (i.e. in the period from the last date used  
624 for calibration to the one for validation). The peaks of the mobility function corresponding to the  
625 activation dates can roughly be grouped in two sets, characterized by distinct values: a first set, with  
626  $z(t) > 40$ , generally includes the ancientmost plus the validation dates (#1, #2, #4, #5, #6, and #11); a  
627 second set (#3, #7, #8, #9, and #10), with  $18 < z(t) < 25$ . False alarms result more frequent and higher  
628 in the first period (from 1963 to 1980), presumably due to lack of information on landslide  
629 activations.

630 Regarding the Uncino case study, the maximum fitness in calibration reaches unity. With respect to  
631 the Sorrento Peninsula case study,  $\Delta z_{cr}$  and  $t_b$  of the best 100 kernels vary in a greater range (ca.  
632 25%, and 30.5%, respectively), with  $\Delta z_{cr}$  one order of magnitude greater. In this case, the kernel  
633 would in fact allow for a safety margin of ca. 5%.

634 In the average kernel, three main periods can be recognized with heavier weights, attributable to *i*)  
635 the first 17 days, *ii*) 27-45 days, and *iii*) 54-58 days. The base time ranges from about 8 to 12 weeks,  
636 in good agreement with the medium-size type of slope instability considered.

637 Furthermore, the validation of the average kernel performed successfully: in fact, the validation date  
638 (#6 in Table 3) corresponds to the third highest peak of the mobility function; even in this case,  
639 neither missing alarms nor false alarms in about 2 years (from the last date calibration date to the  
640 validation one) are to be found. The peaks of the mobility function corresponding to the activation  
641 dates are characterized by  $z(t) > 18$ .

642 In the self-adaptive procedure applied to the same Uncino case study, values for  $L=6$  merely refer to  
643 calibration, whilst the ones for  $2 \leq L \leq 5$  concern validation. With regard to Table 7 and Fig. 20, it can  
644 be noticed that:

- 645 • for  $2 \leq L \leq 5$ ,  $t_b$  increases 2.7 times with  $L$ , and then remains constant for  $L \geq 5$ ;
- 646 • from  $L=2$  to  $L=4$ ,  $z_{j-min}$  and  $z_{cr}$  slightly decrease, and then abruptly increase for  $L \geq 5$ ;
- 647 • for  $L \geq 4$ ,  $\Delta z_{cr}$  monotonically increases 72 times with  $L$  (being almost constant in the 2-4  
648 transition);
- 649 •  $\Phi_v$  monotonically increases 1.7 times with  $L$ .

650 As a whole, a satisfying performance is obtained starting from 3 dates (i.e. correct predictions in  
651 more than 3 out of 4 times). For  $L=5$ , only one false alarm is observed. Finally, the calibration  
652 performed by considering all the 6 dates of activation provided fully satisfying results. Accordingly,

653 the results of the progressive procedure underlined how  $GA_{SAKe}$  can easily self-adapt to external  
654 changes by optimizing its performances, providing increasing fitness values.

655 The average kernels obtained by considering from 2 to 6 dates of landslide activation point out  
656 increasing base times, with significant weights for the ancientmost rains of the temporal range (Fig.  
657 18). Such results is in good accordance with the extent of the slope movement and, therefore, with  
658 the expected prolonged travel times of the groundwater affecting landslide activation.

659 In the sensitivity analyses, again performed by considering the Uncino landslide,  $\Phi_{max} = 1$  was  
660 obtained in 60% of the experiments (cf. Table 8). The results, shown in Fig. 19, and listed in Tables  
661 9, 10, and 11, permit to select the set of parameters that allow for faster GA performances. More in  
662 detail:

- 663 • a ratio between the number of elitist individuals and the whole population of  $n_e/N=10/20$  or  
664  $8/15$  allow for the fastest GA performances ( $min\_A_i \sim 41\%$  of the reference value).  
665 Nevertheless, for increasing both  $n_e$  and  $N$ , this effect seems to vanish (e.g.  $n_e/N=12/25$ ).
- 666 • with respect to the benchmark experiment, the explored changes in  $p_c, p_m, p_{mhl}, p_{me},$  and  $p_{mtb}$  do  
667 not substantially affect the GA performances with respect to  $min\_A_i$ .
- 668 • with respect to the benchmark experiment, the explored changes of parameters determine  
669 variation of  $t_b$  from 66 to 219%.
- 670 • in case of civil protection applications, the combination of parameters with  $p_{mhl}=55$  allows for  
671 activating early-warning procedures with the greatest advance.
- 672 • concerning  $max\_ \Delta z_{cr}$ , the best result (increase by 10 times) is obtained when reducing  $N$  to 15.

673 The calibration experiments discussed in this paper were performed on a standard PC platform  
674 (CPU 3 GHz, RAM 4 GB, standalone system SQL and application process). For the study cases of  
675 Sorrento Peninsula and Uncino landslide, 2.5 and 1.1 GA-iterations were respectively performed  
676 per minute, reaching  $\Phi_{max}$  in  $11^h40^m$  and  $10^h20^m$ . Depending on availability of High-Performance  
677 Computing Clusters, the mentioned durations may strongly be reduced, thus allowing for prompt  
678 Civil Protection applications, e.g. based on short-term weather forecasts. By the way, the time  
679 needed to calibrate the model can profitably be shortened by properly initializing the kernel, based  
680 on expected characteristics of the phenomena under consideration (e.g. the range of  $t_b$  strongly  
681 depends on landslide size).

682 In this study, a 2-steps efficiency criterion was employed: the relative position of the peaks of the  
683 mobility function with respect to the dates of landslide activation was first considered, and the  
684 fitness computed. Based on the value of  $\Delta z_{cr}$ , the obtained solutions were further ranked. Average,  
685 synthetic filter functions can then be computed by selecting the best 100 kernels for successive  
686 validation purposes. Alternative metrics (cf., among the others, Krause et al., 2005) for the fitness  
687 function are being tested. However, due to uncertainties concerning input data (i.e. rainfall and  
688 dates of landslide activation), the adoption of sophisticated techniques does not sound very  
689 promising. In addition, problems of over-fitting may depend on both data uncertainties and number  
690 of parameters. Commonly, kernels characterized by a complex pattern (and then by many  
691 parameters) are needed for simulating groundwater dynamics (Pinault et al., 2001). Nevertheless,  
692 more complex kernels do not necessarily imply higher predictive uncertainties (Fienen et al., 2010;  
693 Long, 2015). Still, the adopted discrete approach allows focusing only on the timing of the peaks of  
694 the mobility function, thus somehow relieving the computational effort. Due to the cited  
695 uncertainties in input data, a “temporal window” was in fact employed to help matching dates of  
696 activation with the peaks of the mobility function. Further attempts of defining the fitness function

697 by different metrics, and the analysis of its effects on calibration and validation, are being  
698 considered against another case study (San Benedetto Ullano, in Calabria, Southern Italy), whose  
699 mobility phases have been recently monitored by the same authors (Iovine et al., 2010; Capparelli et  
700 al., 2012).

701 As mentioned above, model calibration may be hampered by either quality or completeness of input  
702 data. Commonly, missing dates of activation (mainly in remote periods or in isolated areas) and  
703 unsuitability of the rain gauge network (e.g. due to excessive distance of gauges from the  
704 landslides) negatively affect model results. Depending on availability of new dates of activation,  
705 stemming from further mobilizations or improvement of historical investigations, the predictive  
706 capability of the model can be increased through additional calibrations, hence providing new  
707 families of optimal solutions, constituted by fewer, higher-significance kernels.

708 The above considerations suggest an indirect link between the model – despite empirical in type –  
709 and the physical characteristics of the slope movements (e.g. dimensions, permeability, initial water  
710 content of the slope, length of subsurface water paths). In general, to select the kernel to be applied,  
711 it is rather preferable to consider a set of optimal kernels or the average one, instead of a single  
712 solution.

713 Further efforts are in progress to improve the model and its chances of practical application, mainly  
714 concerning the implementation of different GA techniques of optimization (in addition to the elitist  
715 here employed), the parallelization of the model, and the adoption of a Genetic Programming  
716 approach. Finally, through the analytical study of the optimal kernels, a mathematical formulation  
717 of discrete filter functions is presently being attempted, aiming at synthetizing optimal and average  
718 kernels for an easier comparison with the results of other models available in literature.

## 720 **8 CODE AVAILABILITY**

721 The release <sup>GA</sup>SAKe of the Self-Adapting Kernel model, discussed in this paper, has been developed  
722 by scientists working at CNR-IRPI under Microsoft Windows and Visual Studio integrated  
723 development environment. The above release can be requested by the public to the corresponding  
724 author of the paper, together with examples of input data and technical support (a user manual is not  
725 available yet, but it should be released soon). The model is presently undergoing further refinements  
726 and developments, mainly concerning types of GA-selection techniques, the post-processing of  
727 results in terms of continuous analytical functions, and the implementation of a library of case  
728 studies. Authors are willing to cooperate with external users to further improving the model through  
729 applications to case studies from different geo-environmental contexts.

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741

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969

970 **Table 1.** Dates of activation of the shallow landslides in the Sorrento Peninsula. Key: date = day of occurrence; type =  
971 widespread (multiple) or few (single) activation; site = municipality including the affected location; period employed =  
972 dates used for calibration (except for #11); rank = relative position of the corresponding maximum of the mobility  
973 function obtained by calibration. An asterisk marks the date employed for validation. In Italics, the activation date (#0)  
974 excluded due to hydrological constraints.  
975

| #  | Date                            | type                  | site   | reference                                    | period employed | rank                 |
|----|---------------------------------|-----------------------|--|--|-----------------|----------------------|
| 1  | 17 February 1963                | multiple;<br>single   | Gragnano, Pimonte; Castellammare                               | Del Prete et al. 1998                        | 17 Feb 1963     | 17 Feb 1963 (1)      |
| 2  | 23 November 1966                | single                | Vico Equense (Scrajo), Arola,<br>Ticciano                      | Del Prete et al. 1998                        | 23 Nov 1966     | 24 Nov 1966 (4)      |
| 0  | <i>14 April 1967</i>            | <i>single</i>         | <i>Castellammare (Pozzano)</i>                                 | <i>Del Prete et al. 1998;<br/>AMRA, 2012</i> | -               | -                    |
| 3  | 15 March 1969;<br>24 March 1969 | multiple;<br>multiple | Cava de' Tirreni, Agerola, Scrajo<br>Seiano                    | Del Prete et al. 1998;<br>AMRA, 2012         | 15-24 Mar 1969  | 25 Mar 1969<br>(65)  |
| 4  | 02 January 1971                 | single                | Gragnano   | Del Prete et al. 1998                        | 02 Jan 1971     | 3 Jan 1971 (3)       |
| 5  | 21 January 1971                 | single                | Gragnano   | Del Prete et al. 1998                        | 21 Jan 1971     | 21 Jan 1971 (7)      |
| 6  | 04 November 1980                | single                | Vico Equense (Scrajo)  | Del Prete et al. 1998                        | 04 Nov 1980     | 6 Nov 1980 (94)      |
| 7  | 14 November 1982                | single                | Pozzano  | Del Prete et al. 1998                        | 14 Nov 1982     | 15 Nov 1982<br>(151) |
| 8  | 22 February 1986                | multiple              | Palma Campania, Castellammare,<br>Vico Equense                 | Del Prete et al. 1998                        | 22 Feb 1986     | 24 Feb 1986<br>(120) |
| 9  | 23 February 1987                | single                | Gragnano, Castellammare  | Del Prete et al. 1998;<br>AMRA, 2012         | 23 Feb 1987     | 23 Feb 1987<br>(73)  |
| 10 | 23 November 1991                | single                | Pozzano  | Del Prete et al. 1998                        | 23 Nov 1991     | 24 Nov 1991<br>(43)  |
| 11 | 10 January 1997                 | multiple              | Pozzano;<br>Castellammare, Nocera, Pagani,<br>Amalfitana Coast | Del Prete et al. 1998<br>AMRA, 2012          | 10 Jan 1997     | *                    |

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**Table 2.** Average monthly rainfall and number of rainy days at the Montalto Uffugo rain gauge (468 m a.s.l.).

|               | Sep  | Oct   | Nov   | Dec   | Jan   | Feb   | Mar   | Apr  | May  | Jun  | Jul  | Aug  | year   |
|---------------|------|-------|-------|-------|-------|-------|-------|------|------|------|------|------|--------|
| rainfall (mm) | 70.4 | 125.1 | 187.9 | 220.8 | 198.1 | 160.3 | 132.8 | 98.9 | 64.6 | 27.8 | 18.3 | 28.6 | 1333.6 |
| rainy days    | 6.9  | 10.6  | 12.8  | 14.3  | 14.3  | 12.5  | 12.6  | 10.7 | 8.26 | 4.7  | 2.62 | 3.84 | 114.0  |

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982 **Table 3.** Dates of activation of the Uncino landslide. Periods (instead of singular dates) were considered in case of  
 983 uncertain timing of activation. Key = #: Identification number of the date (in bold, used for calibration); dates/periods  
 984 derived from literature; dates/periods employed for calibration or validation; references: sources of information on  
 985 activation dates; rank: relative position and dates of the maxima of the mobility function during calibration. An asterisk  
 986 marks the activation employed for validation. In *Italics*, the activation date (#0) excluded due to hydrological  
 987 constraints.  
 988

| #        | date                    | reference                         | period                       | rank            |
|----------|-------------------------|-----------------------------------|------------------------------|-----------------|
| <b>1</b> | 16, 21 January 1960     | Sorriso-Valvo et al., 1996        | 16-21 Jan 1960               | 18 Jan 1960 (5) |
| <b>2</b> | Winter 1963             | Sorriso-Valvo et al., 1994        | 01 Nov 1962 –<br>14 Apr 1963 | 29 Mar 1963 (1) |
| <b>3</b> | 15 April 1964 (h 22:00) | Sorriso-Valvo et al., 1994        | 15 Apr 1964                  | 14 Apr 1964 (3) |
| <b>4</b> | 14 December 1966        | Lanzafame and Mercuri,<br>1975    | 14 Dec 1966                  | 16 Dec 1966 (2) |
| <b>5</b> | 10-14, 21 February 1979 | Sorriso-Valvo et al., 1994        | 10-21 Feb 1979               | 15 Feb 1979 (4) |
| <b>6</b> | December 1980           | Sorriso-Valvo et al., 1994        | 01-31 Dec 1980               | *               |
| <i>0</i> | <i>23 November 1988</i> | <i>Sorriso-Valvo et al., 1996</i> | -                            | -               |

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**Table 4.** Values of the parameters of  $GA_{SAKe}$  adopted in the calibration procedure (benchmark experiment).

| symbol    | parameter  | value         |
|-----------|--|---------------|
| $N$       | individuals of each GA population  | 20            |
| $t_b$     | base time (Uncino landslide)   | 30 ÷ 180 days |
|           | base time (shallow landslides in the Sorrento Peninsula)                     | 2 ÷ 30 days   |
| $p_{mh1}$ | percentages of the maximum height of the kernel,                             | 50%, 150%     |
| $p_{mh2}$ | used to defining the range in which $dh$ is randomly obtained                |               |
| $p_c$     | probability of crossover   | 75%           |
| $p_m$     | probability of mutation  | 25%           |
| $p_{me}$  | number of mutated elements of the kernel, expressed as a percentage of $t_b$ | 25%           |
| $p_{mtb}$ | factor defining the range in which $dt_b$ is selected                        | 0.2 ÷ 5       |
| $A$       | number of GA-iterations (Uncino landslide case study)                        | 5000          |
|           | number of GA-iterations (Sorrento Peninsula case study)                      | 3000          |
| $n_e$     | number of "elitist" individuals  | 8             |

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995 **Table 5.** Sorrento Peninsula case study. Statistics for the best 100 kernels.  
996

|                 | $\Phi$   | $\Delta z_{cr}$ | $t_b$ | $\mu_0$ |
|-----------------|----------|-----------------|-------|---------|
| <b>min</b>      | 0.806    | 3.82E-05        | 26.0  | 9.460   |
| <b>average</b>  | 0.806    | 0.00418         | 30.4  | 9.567   |
| <b>max</b>      | 0.807    | 0.00801         | 31.0  | 10.448  |
| <b>median</b>   | 0.806    | 0.00499         | 31.0  | 9.567   |
| <b>mode</b>     | 0.806    | 0.00499         | 31.0  | 9.567   |
| <b>dev. st.</b> | 7.65E-05 | 0.00183         | 0.862 | 0.146   |

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**Table 6.** Uncino landslide case study. Statistics for the best 100 kernels.

|                 | $\Delta z_{cr}$ | $t_b$ |
|-----------------|-----------------|-------|
| <b>min</b>      | 0.0524          | 57.0  |
| <b>average</b>  | 0.0581          | 69.5  |
| <b>max</b>      | 0.0692          | 82.0  |
| <b>median</b>   | 0.0581          | 69.0  |
| <b>mode</b>     | 0.0558          | 69.0  |
| <b>dev. st.</b> | 0.00373         | 3.12  |

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1002 **Table 7.** Uncino landslide case study. Results of progressive calibration. Key:  $L$ ,  $t_b$ ,  $z_{j-min}$ ,  $z_{cr}$ ,  $\Delta z_{cr}$ ): model parameters  
 1003 concerning calibration (for explanation, cf. text);  $\Phi_v$ ) fitness obtained by validating the “average kernel”, obtained in  
 1004 calibration, against the 6 dates of activation. In *Italics*, results obtained when calibrating the model by using all the 6  
 1005 available dates (no validation performed).

| $L$      | $t_b$     | $z_{j-min}$  | $z_{cr}$     | $\Delta z_{cr}$ | $\Phi_v$    |
|----------|-----------|--------------|--------------|-----------------|-------------|
| 2        | 30        | 13.93        | 13.89        | 0.0029          | 0.59        |
| 3        | 54        | 11.05        | 11.04        | 0.0009          | 0.78        |
| 4        | 55        | 10.21        | 10.20        | 0.0010          | 0.87        |
| 5        | 80        | 16.44        | 16.34        | 0.0061          | 0.95        |
| <i>6</i> | <i>80</i> | <i>18.63</i> | <i>17.43</i> | 0.0644          | <i>1.00</i> |

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1009 **Table 8.** Uncino landslide case study. Values of the parameters adopted in the sensitivity analyses. In bold, the  
 1010 experiments with  $\Phi_{max} = 1$ . Boxes evidence the worst experiment (in Italics), and the best one (underlined).  
 1011

| <i>symbol</i> | <i>values</i>   |               |                              |                   |                  |
|---------------|-----------------|---------------|------------------------------|-------------------|------------------|
|               | <b>6</b>        | <b>7</b>      | <sup>a)</sup> <b>8</b>       | <b>9</b>          | <u><b>10</b></u> |
| $n_e$         | <b>6</b>        | <b>7</b>      | <sup>a)</sup> <b>8</b>       | <b>9</b>          | <u><b>10</b></u> |
| $p_c$         | 60%             | 67.5%         | <sup>a)</sup> <b>75%</b>     | <u>82.5%</u>      | 90%              |
| $p_m$         | 20%             | <b>22.5%</b>  | <sup>a)</sup> <b>25%</b>     | <b>27.5%</b>      | 30%              |
| $p_{mh1}$     | 60%             | <b>55%</b>    | <sup>a)</sup> <b>50%</b>     | 45%               | 40%              |
| $p_{mh2}$     | 140%            | <b>145%</b>   | <sup>a)</sup> <b>150%</b>    | 155%              | 160%             |
| $p_{me}$      | 20%             | 22.5%         | <sup>a)</sup> <b>25%</b>     | 27.5%             | <b>30%</b>       |
| $p_{mtb}$     | <b>0.25 ÷ 4</b> | 0.22 ÷ 4.5    | <sup>a)</sup> <b>0.2 ÷ 5</b> | <b>0.18 ÷ 5.5</b> | 0.17 ÷ 6         |
| $N, n_e$      |                 | <b>25, 8</b>  | <sup>a)</sup> <b>20, 8</b>   | <b>15, 8</b>      |                  |
| $N, n_e$      |                 | <b>25, 12</b> | <b>25, 10</b>                | <b>25, 8</b>      |                  |

<sup>a)</sup> Reference values (i.e., those of the benchmark experiment - cf. Table 4)

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1014 **Table 9.** Minimum ( $min_{A_i}$ ) and maximum ( $max_{A_i}$ ) numbers of GA iterations needed to reach  $\Phi_{max}$  (only experiments  
1015 with  $\Phi_{max} = 1$  are considered). In the first column, the letters refer to Fig. 19. In bold, the best and worst experiments.  
1016 An asterisk marks the experiment  $e$ , in which  $\Phi_{max}$  was reached only for  $p_c=75$ . In Italics, the combinations of  
1017 parameters of the benchmark experiment (cf. Table 4).  
1018

| $\hat{s}$ | $N$ | <i>parameter</i> | $min_{A_i}$ | $max_{A_i}$ |
|-----------|-----|------------------|-------------|-------------|
| <i>a</i>  | 20  | $n_e=8$          |             | <i>684</i>  |
| <b>a</b>  | 20  | $n_e=10$         | <b>279</b>  |             |
| <i>c</i>  | 25  | $n_e=8$          | 469         |             |
| <i>c</i>  | 25  | $n_e=12$         |             | <b>1477</b> |
| <i>e</i>  | 20  | $p_c=75$         | <i>684*</i> |             |
| <i>g</i>  | 20  | $p_m=25$         | <i>684</i>  |             |
| <i>g</i>  | 20  | $p_m=27.5$       |             | 1086        |
| <i>i</i>  | 20  | $p_{mh1}=50$     | <i>684</i>  |             |
| <i>i</i>  | 20  | $p_{mh1}=55$     |             | 836         |
| <i>k</i>  | 20  | $p_{mc}=25$      | <i>684</i>  |             |
| <i>k</i>  | 20  | $p_{mc}=30$      |             | 996         |
| <i>m</i>  | 20  | $p_{mb}=5$       | <i>684</i>  |             |
| <i>m</i>  | 20  | $p_{mb}=5.5$     |             | 1052        |
| <i>o</i>  | 15  | $n_e=8$          | 405         |             |

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1021 **Table 10.** Minimum ( $min\_t_b$ ) and maximum ( $max\_t_b$ ) base time of the average kernel (only experiments with  $\Phi_{max} = 1$   
1022 are considered). In the first column, the letters refer to Fig. 19. In bold, the best and worst experiments. An asterisk  
1023 marks the experiment  $e$ , in which  $\Phi_{max}$  was reached only for  $p_c=75$ . In Italics, the combinations of parameters of the  
1024 benchmark experiment (cf. Table 4).  
1025

| $\hat{s}$ | $N$ | <i>parameter</i> | <i>min_t_b</i> | <i>max_t_b</i> |
|-----------|-----|------------------|----------------|----------------|
| <i>a</i>  | 20  | $n_e=8$          | <i>66,59</i>   |                |
| a         | 20  | $n_e=10$         |                | 144,85         |
| c         | 25  | $n_e=8$          |                | 132,00         |
| c         | 25  | $n_e=12$         | 56,17          |                |
| <i>e</i>  | 20  | $p_c=75$         | <i>66,59*</i>  |                |
| <i>g</i>  | 20  | $p_m=25$         | <i>66,59</i>   |                |
| g         | 20  | $p_m=27.5$       |                | 139,20         |
| <i>i</i>  | 20  | $p_{mh1}=50$     |                | <i>66,59</i>   |
| i         | 20  | $p_{mh1}=55$     | <b>44,00</b>   |                |
| <i>k</i>  | 20  | $p_{mc}=25$      | <i>66,59</i>   |                |
| k         | 20  | $p_{mc}=30$      |                | <b>146,93</b>  |
| <i>m</i>  | 20  | $p_{mtb}=5$      | <i>66,59</i>   |                |
| m         | 20  | $p_{mtb}=4$      |                | 136,06         |
| <i>o</i>  | 15  | $n_e=8$          |                | <i>145,79</i>  |

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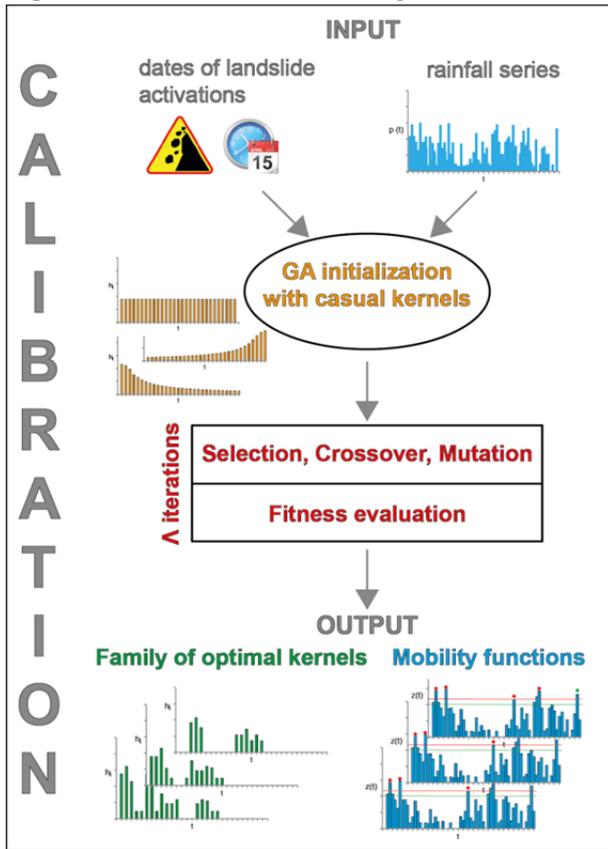
1028 **Table 11.** Minimum ( $min\_ \Delta z_{cr}$ ) and maximum ( $max\_ \Delta z_{cr}$ ) safety margin of the average kernel (only experiments with  
1029  $\Phi_{max} = 1$  are considered). In the first column, the letters refer to Fig. 19. In bold, the best and worst experiments. An  
1030 asterisk marks the experiment  $e$ , in which  $\Phi_{max}$  was reached only for  $p_e=75$ . In Italics, the combinations of parameters of  
1031 the benchmark experiment (cf. Table 4).  
1032

| $\S$     | $N$ | <i>parameter</i> | $min\_ \Delta z_{cr}$ | $max\_ \Delta z_{cr}$ |
|----------|-----|------------------|-----------------------|-----------------------|
| a        | 20  | $n_e=7$          |                       | 0.007                 |
| a        | 20  | $n_e=9$          | 0.002                 |                       |
| c        | 25  | $n_e=8$          |                       | 0.014                 |
| c        | 25  | $n_e=12$         | 0.002                 |                       |
| <i>e</i> | 20  | $p_e=75$         | <i>0.005*</i>         |                       |
| g        | 20  | $p_m=22.5$       |                       | 0.006                 |
| g        | 20  | $p_m=27.5$       | <b>0.001</b>          |                       |
| <i>i</i> | 20  | $p_{mhi}=50$     |                       | <i>0.005</i>          |
| i        | 20  | $p_{mhi}=55$     | 0.004                 |                       |
| <i>k</i> | 20  | $p_{me}=25$      | <i>0.005</i>          |                       |
| k        | 20  | $p_{me}=30$      |                       | 0.006                 |
| <i>m</i> | 20  | $p_{mib}=5$      | <i>0.005</i>          |                       |
| m        | 20  | $p_{mib}=4$      |                       | 0.009                 |
| o        | 15  | $n_e=8$          |                       | <b>0.055</b>          |
| <i>o</i> | 20  | $n_e=8$          | <i>0.005</i>          |                       |

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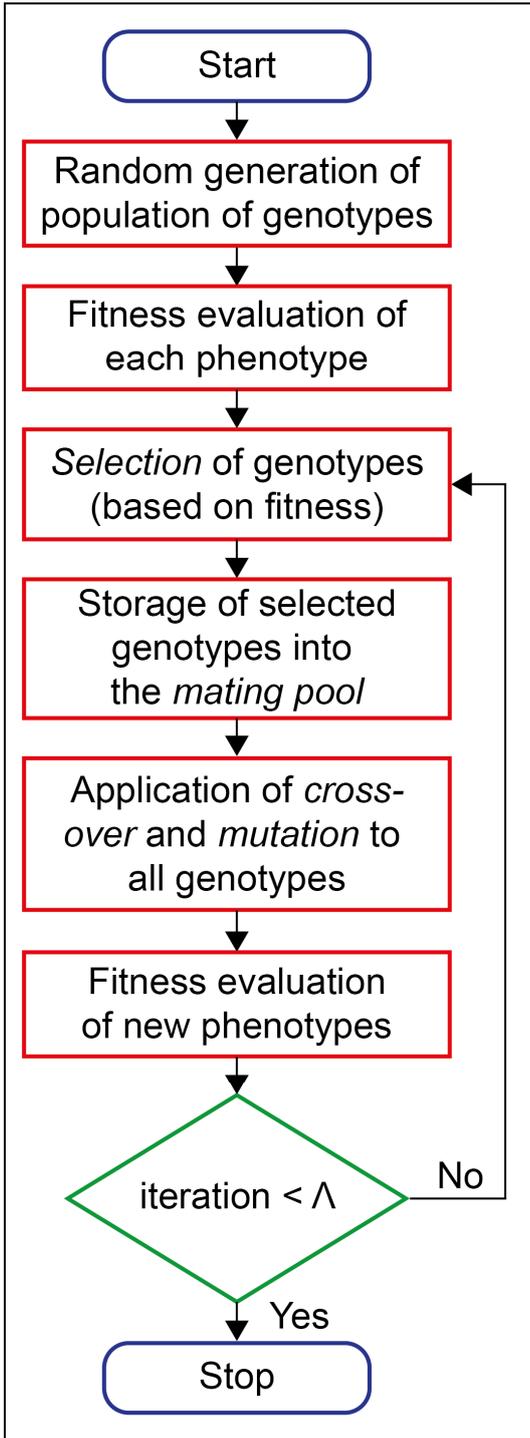
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1035 **Figure 1.** Scheme of the calibration procedure of the model  $GA^{SAKe}$ .



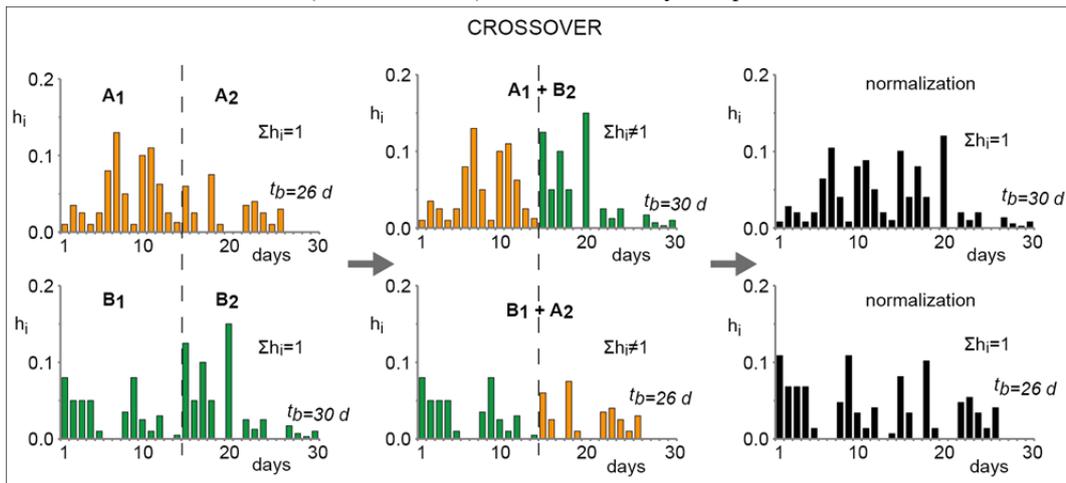
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Figure 2. Scheme of the adopted Genetic Algorithm.



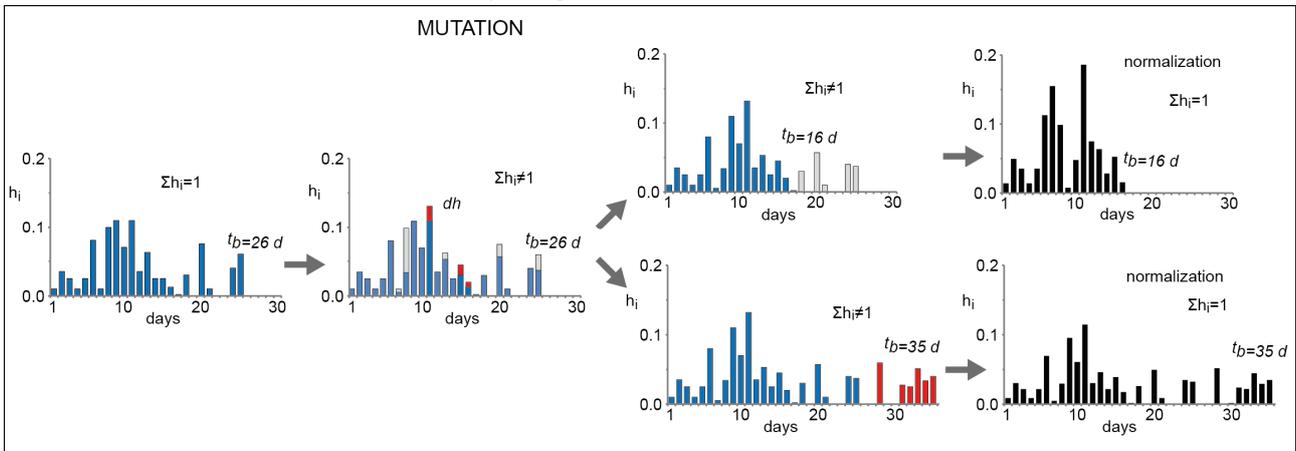
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**Figure 3.** Example of crossover. The genetic codes of the parents (elements in orange and green) are first mixed; then, the children are normalized (black elements) to ensure validity of equation 2.



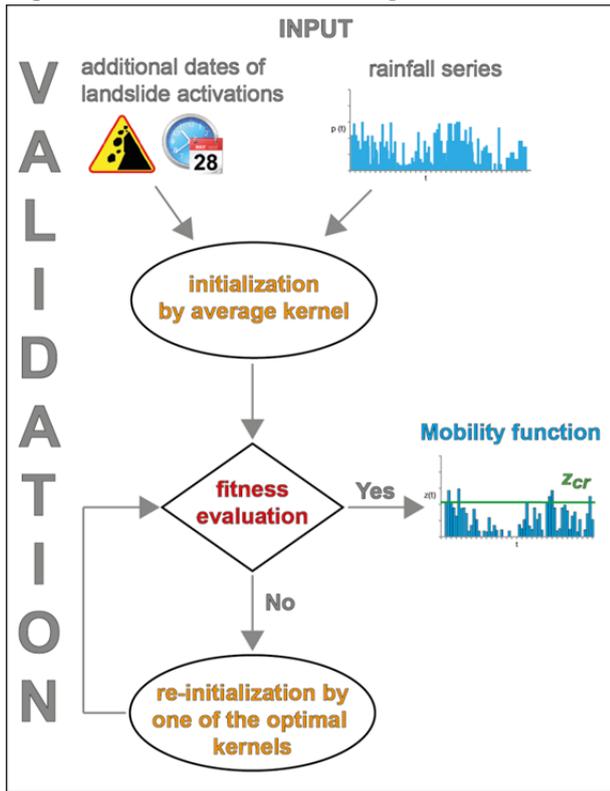
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1045 **Figure 4.** Examples of mutation. On the left, the genetic code of the parent individual (elements in blue). In the second  
 1046 histogram, mutation is applied to some elements of the parent (in red, added amounts; in grey, subtracted amounts).  
 1047 Then, the base time can either be decreased (upper sequence) or increased (lower sequence). Finally, the children  
 1048 are normalized (black elements) to ensure validity of equation 2.



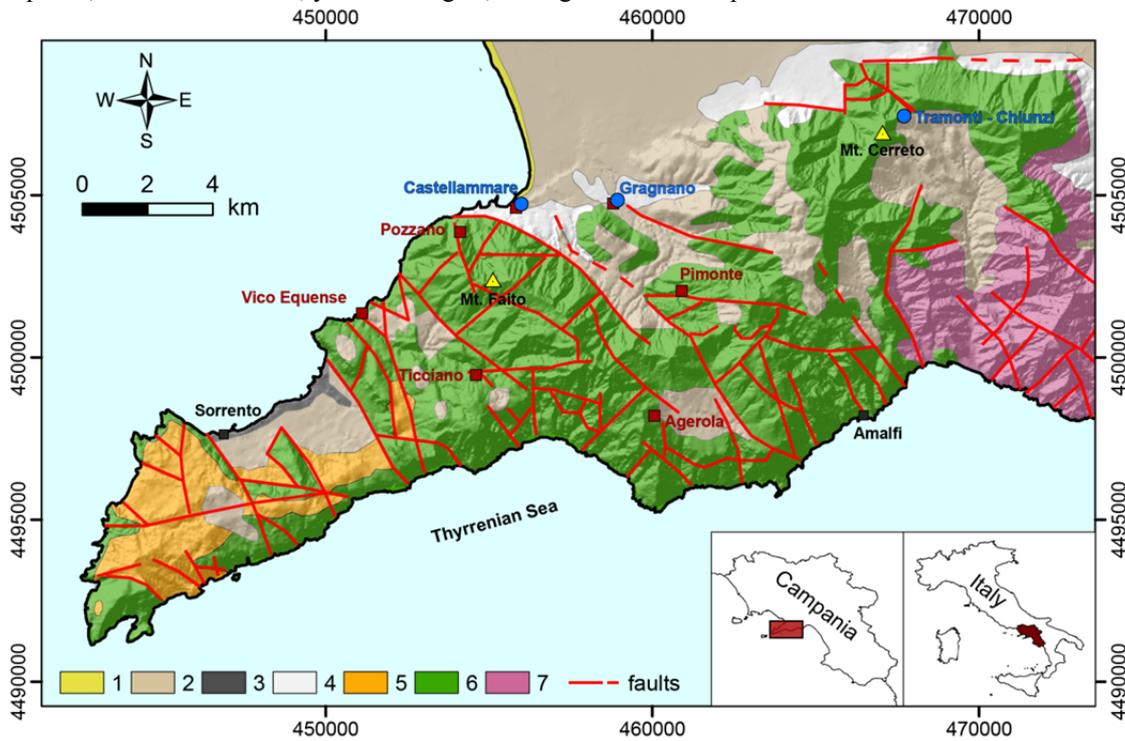
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1051 **Figure 5.** Scheme of the validation procedure of the model  $GA_{SAKe}$ .



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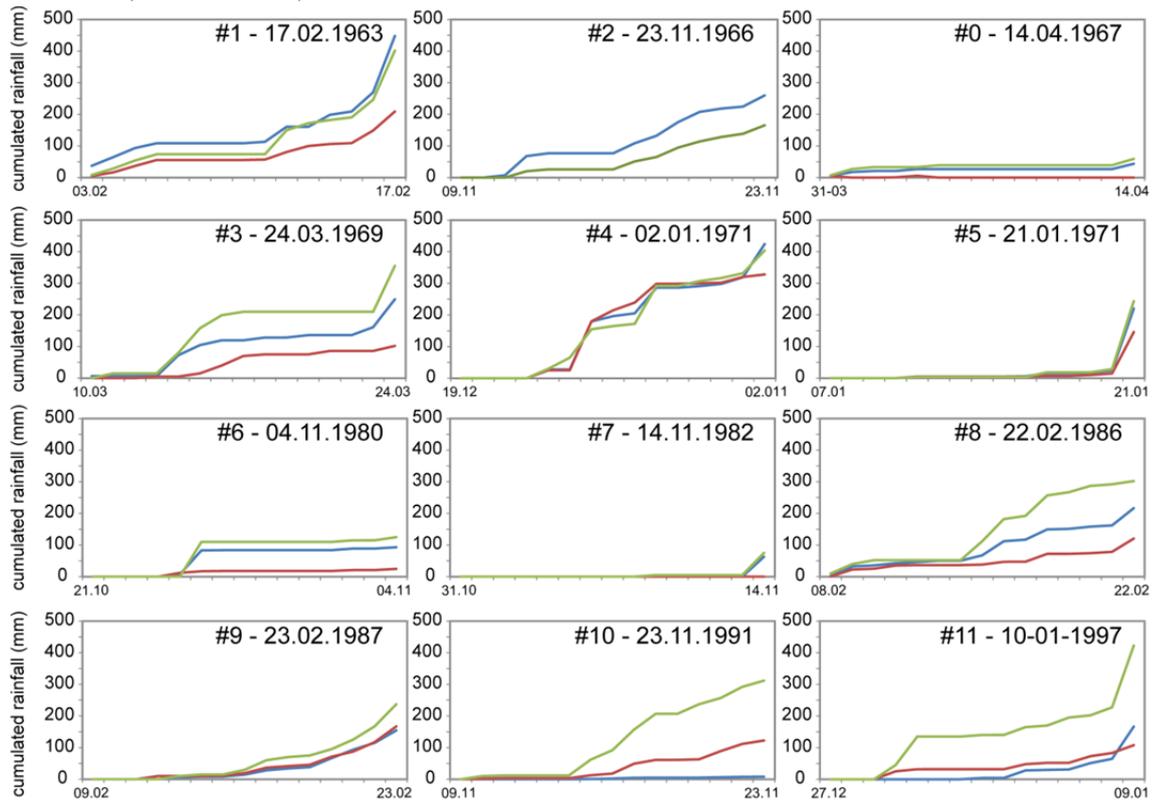
1054 **Figure 6.** Geological map of the Sorrento Peninsula (after Di Crescenzo and Santo, 1999, mod.). Key: 1) beach deposit  
 1055 (Holocene); 2) pyroclastic fall deposit (Late Pleistocene-Holocene); 3) Campanian ignimbrite (Late Pleistocene); 4)  
 1056 detrital alluvial deposit (Pleistocene); 5) flysch deposit (Miocene); 6) limestone (Mesozoic); 7) dolomitic limestone  
 1057 (Mesozoic). Red squares mark sites affected by shallow landslide activations; blue circles, the rain gauges; black  
 1058 squares, the main localities; yellow triangles, the highest mountain peaks.



1059  
 1060

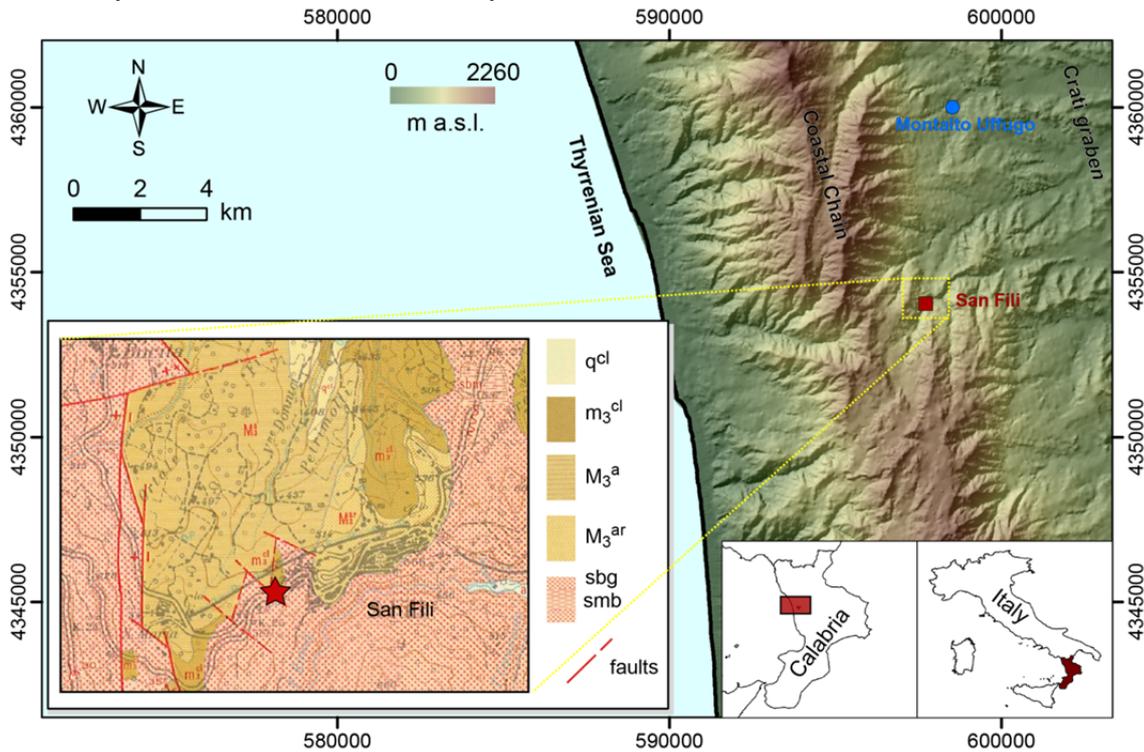
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**Figure 7.** Cumulative daily rainfall (in mm) during the 14 days preceding landslide occurrences. Key: in blu, red, and green = values from the Tramonti, Castellammare, and Tramonti-Chiunzi rain gauges, respectively. Numbers refer to id. in Table 1 (cf. first column).



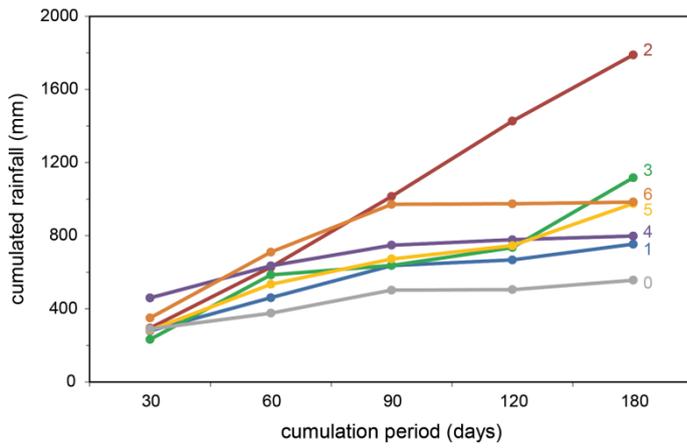
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1066 **Figure 8.** Location of the study area (red square: San Fili village; blue circle: Montalto Uffugo rain gauge). On bottom  
 1067 left, an extract from the geological map of Calabria (CASMEZ, 1967). Key: sbg) gneiss and biotitic schist with garnet  
 1068 (Palaeozoic); sbm) schist including abundant granite and pegmatite veins, forming migmatite zones (Palaeozoic); M<sub>3</sub><sup>ar</sup>)  
 1069 arenite and silt with calcarenite (Late Miocene); M<sub>3</sub><sup>a</sup>) marly clay with arenite and marls (Late Miocene); m<sub>3</sub><sup>cl</sup>) reddish  
 1070 conglomerate with arenite (Late Miocene); q<sup>cl</sup>) loose conglomerate of ancient fluvial terraces (Pleistocene). The site  
 1071 affected by the Uncino landslide is marked by a red star.



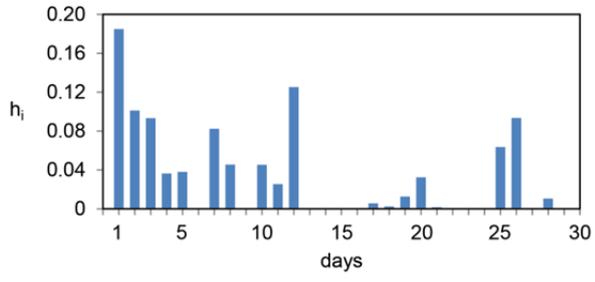
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1074 **Figure 9.** Cumulative daily rainfall (in mm) from 30 to 180 days before landslide occurrences (Montalto Uffugo  
1075 gauge). Numbers refer to identification number (#) in Table 3 (cf. first column).



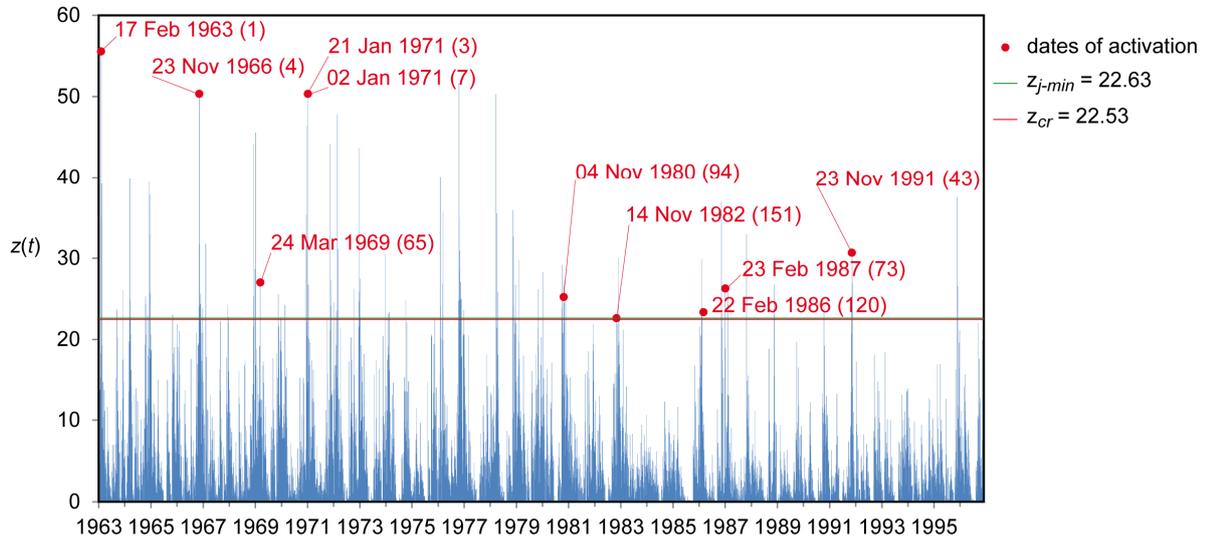
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1078 **Figure 10.** Sorrento Peninsula case study. Average kernel obtained from the best 100 filter functions.



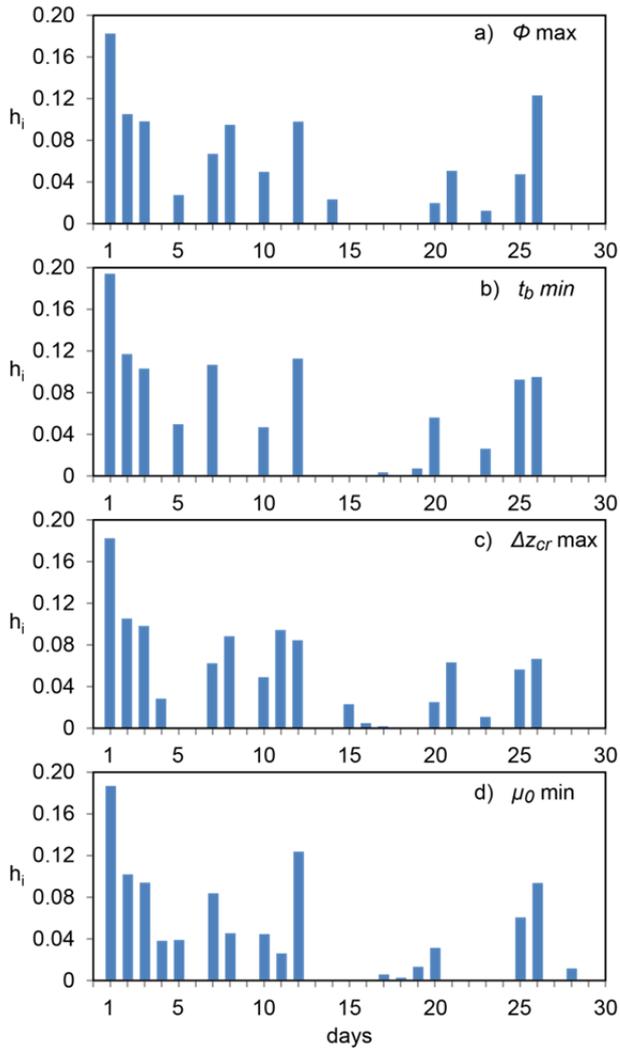
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1081 **Figure 11.** Sorrento Peninsula case study. Mobility function,  $z(t)$ , of the average kernel. The red line ( $z_{cr} = 22.53$ ) shows  
 1082 the maximum value of the mobility function (critical condition) that is unrelated to known landslide activations. The  
 1083 green line ( $z_{j-min} = 22.63$ ) – almost overlapping with the red line in this case – shows the minimum value of the mobility  
 1084 function related to known landslide activations. When the mobility function exceeds the threshold marked by the red  
 1085 line, landslide activation may occur. The red dots represent the maxima of the mobility function corresponding to the  
 1086 dates of landslide activation considered for calibration.



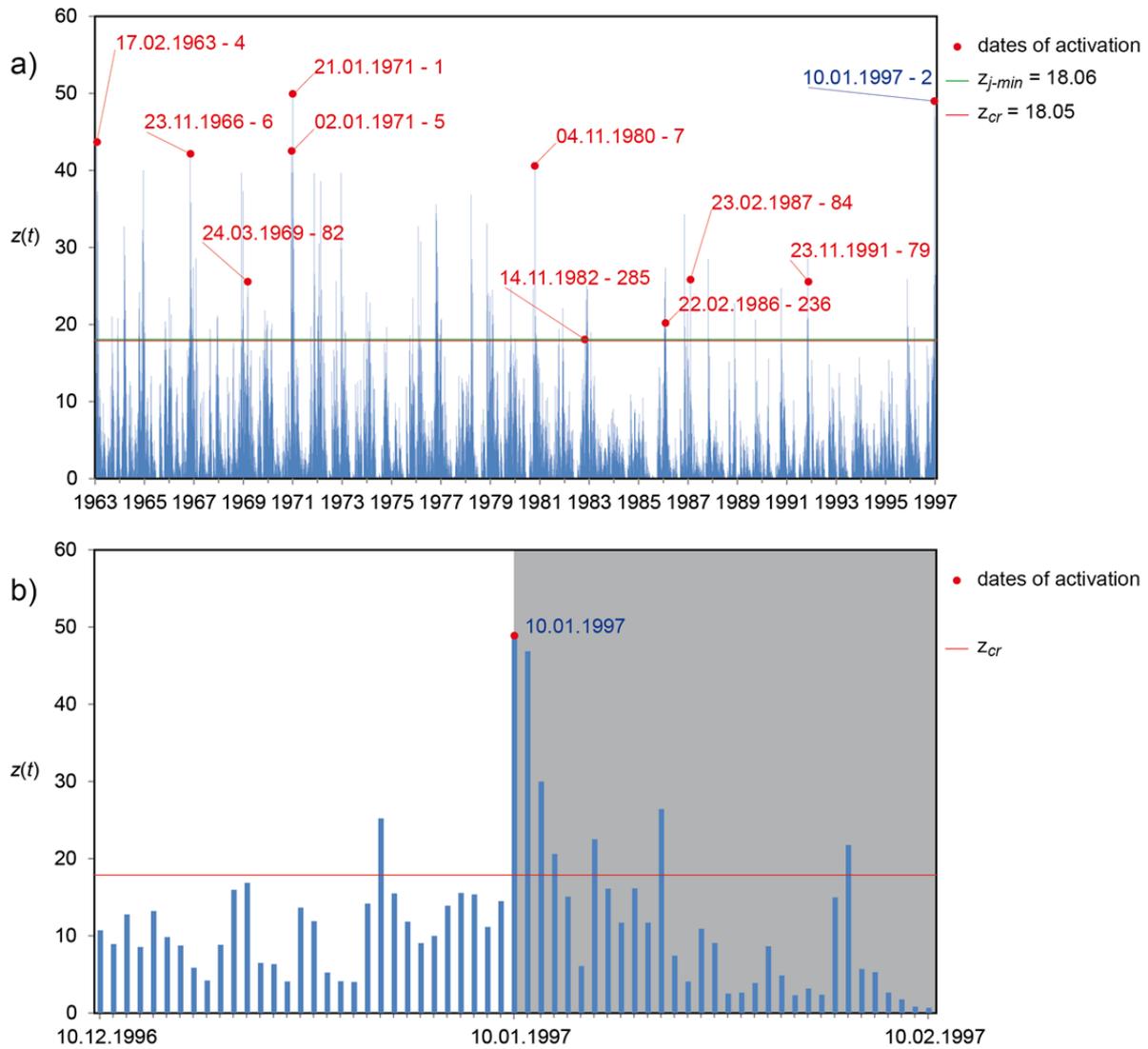
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1089 **Figure 12.** Sorrento Peninsula case study. Kernels providing (a) the best fitness ( $\Phi_{max} = 0.807$ ), (b) the minimum base  
 1090 time  $t_b min$  (26 days), (c) the  $\Delta z_{cr} max$  (0.00801), and (d) the minimum first order momentum,  $\mu_0 min$  (9.460).



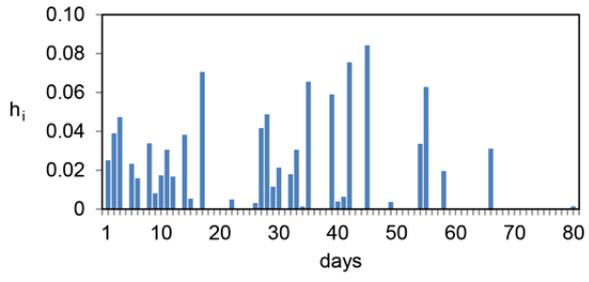
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1093 **Figure 13.** Sorrento Peninsula case study. a) Validation of the average kernel against the #11 event. b) Particular of  
 1094 Fig.13a, limited to the period  $\pm t_b$ , including the date of validation. Key as in Fig.11. The blue label indicates the date of  
 1095 validation. Grey background marks the period after the event that may be employed for re-calibration.



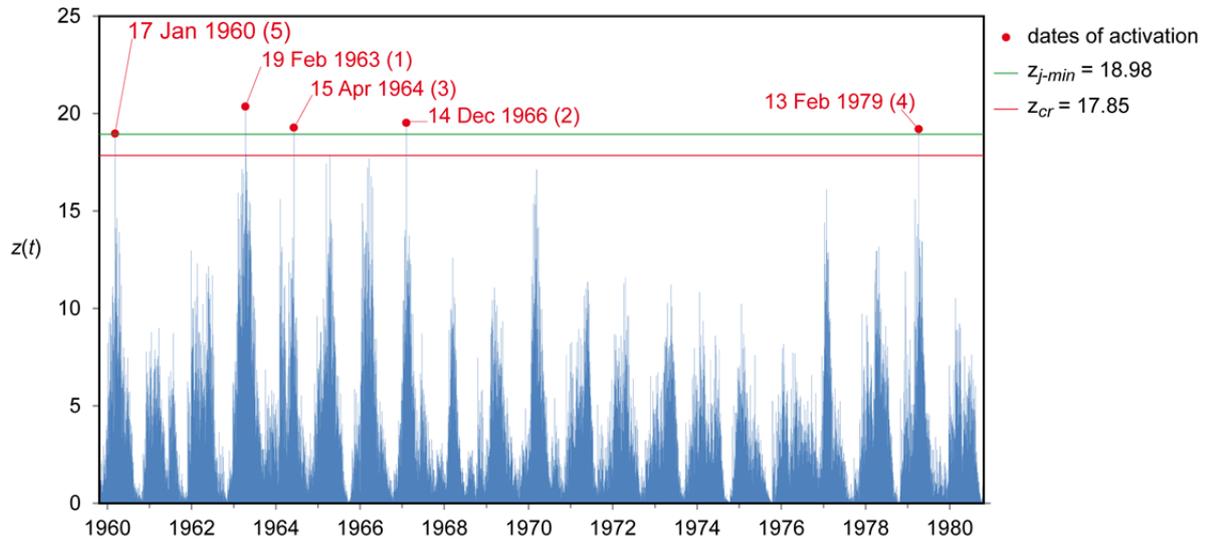
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1098 **Figure 14.** Uncino landslide case study. Average kernel obtained from the best 100 filter functions.



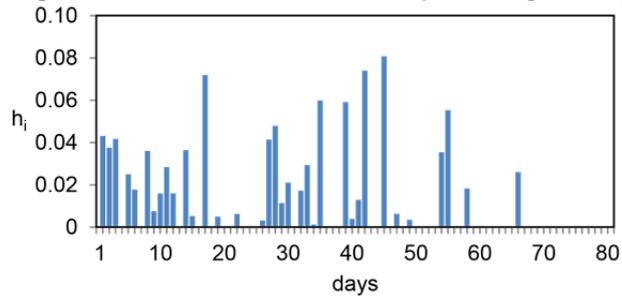
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1101 **Figure 15.** Uncino landslide case study. Mobility function,  $z(t)$ , of the average kernel. The red line ( $z_{cr} = 17.85$ ) shows  
 1102 the maximum value of the mobility function (critical condition) that is unrelated to known activations. The green line  
 1103 ( $z_{j-min} = 18.98$ ) shows the minimum value of the mobility function related to known activations. When the mobility  
 1104 function exceeds the threshold marked by the red line, landslide activation may occur. The red dots represent the  
 1105 maxima of the mobility function corresponding to dates of landslide activation considered for calibration.



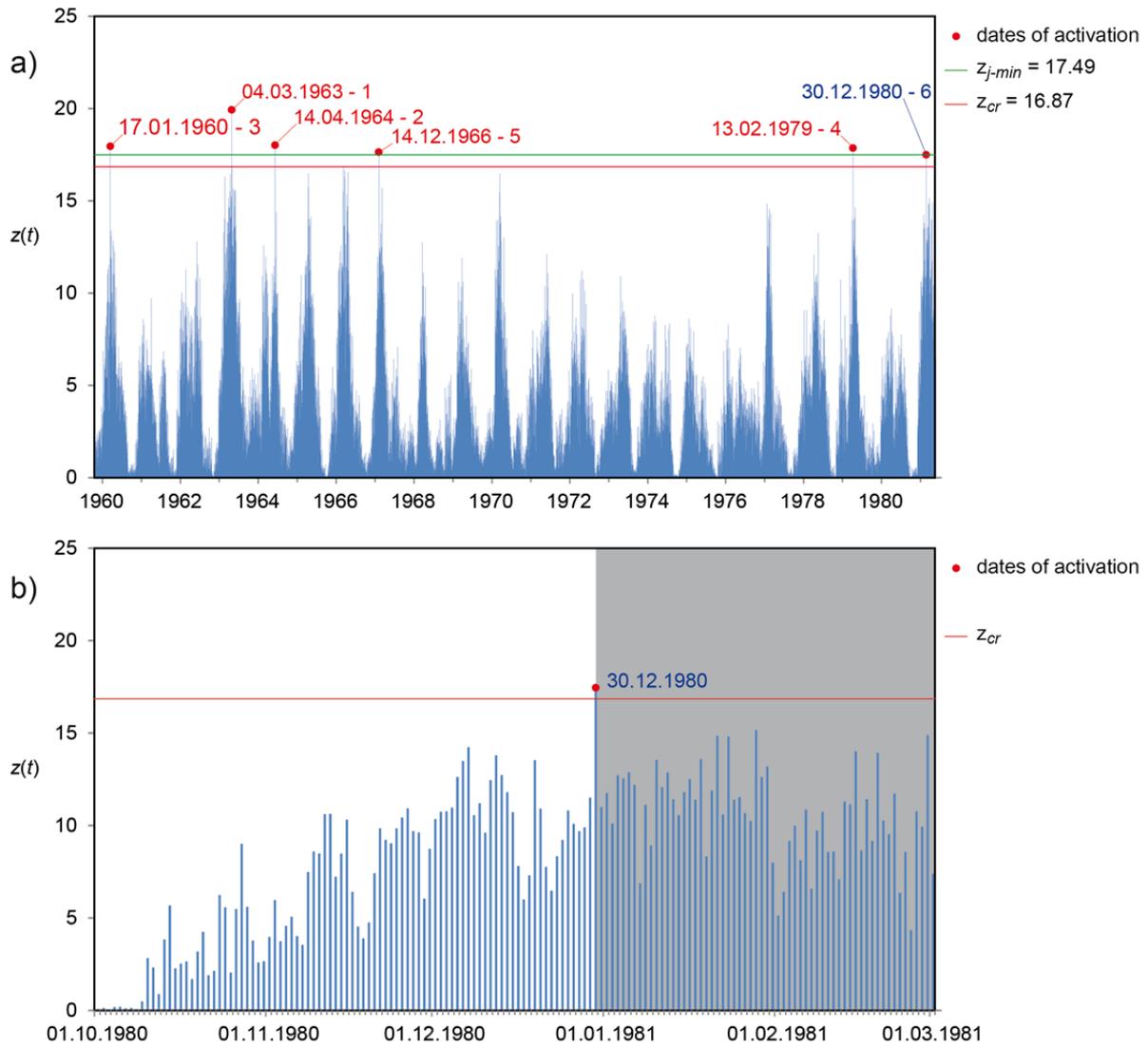
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1108 **Figure 16.** Uncino landslide case study. Kernel providing the best fitness.



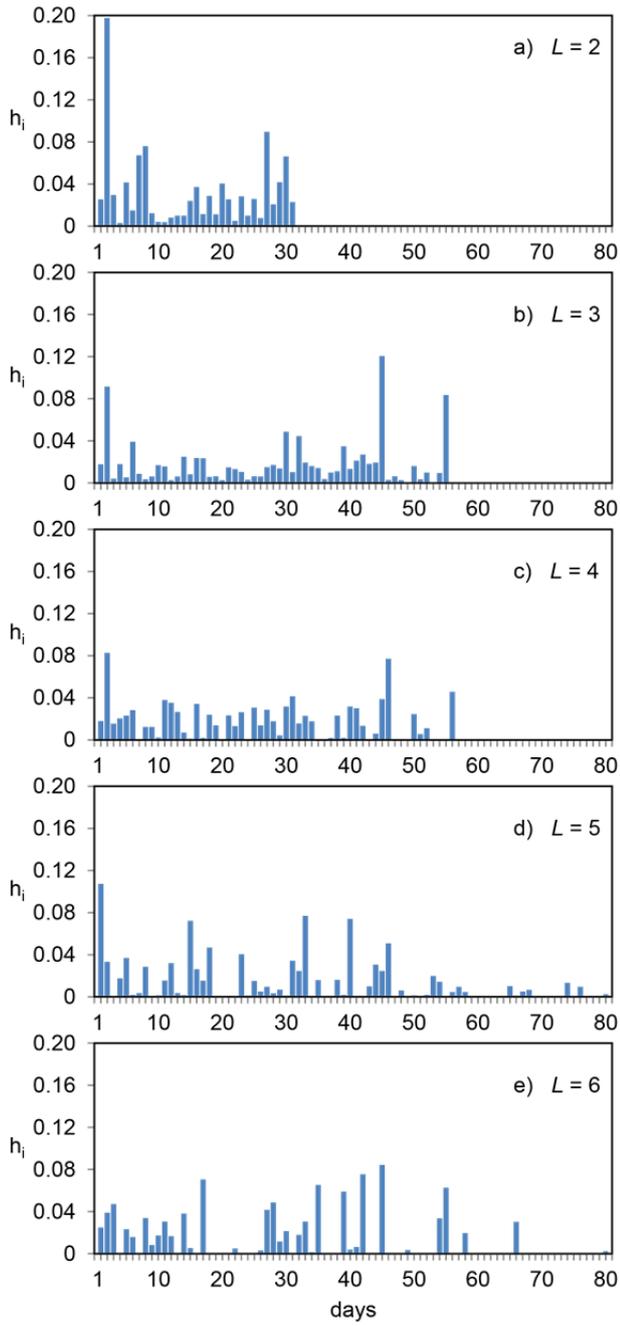
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1111 **Figure 17.** Uncino landslide case study. a) Validation of the average kernel against the #6 event. b) Particular of  
 1112 Fig.17a, limited to the period  $\pm t_b$  including the date of validation. Key as in Fig. 15. The blue label indicates the date of  
 1113 validation. Grey background marks the period after the event that may be employed for re-calibration.



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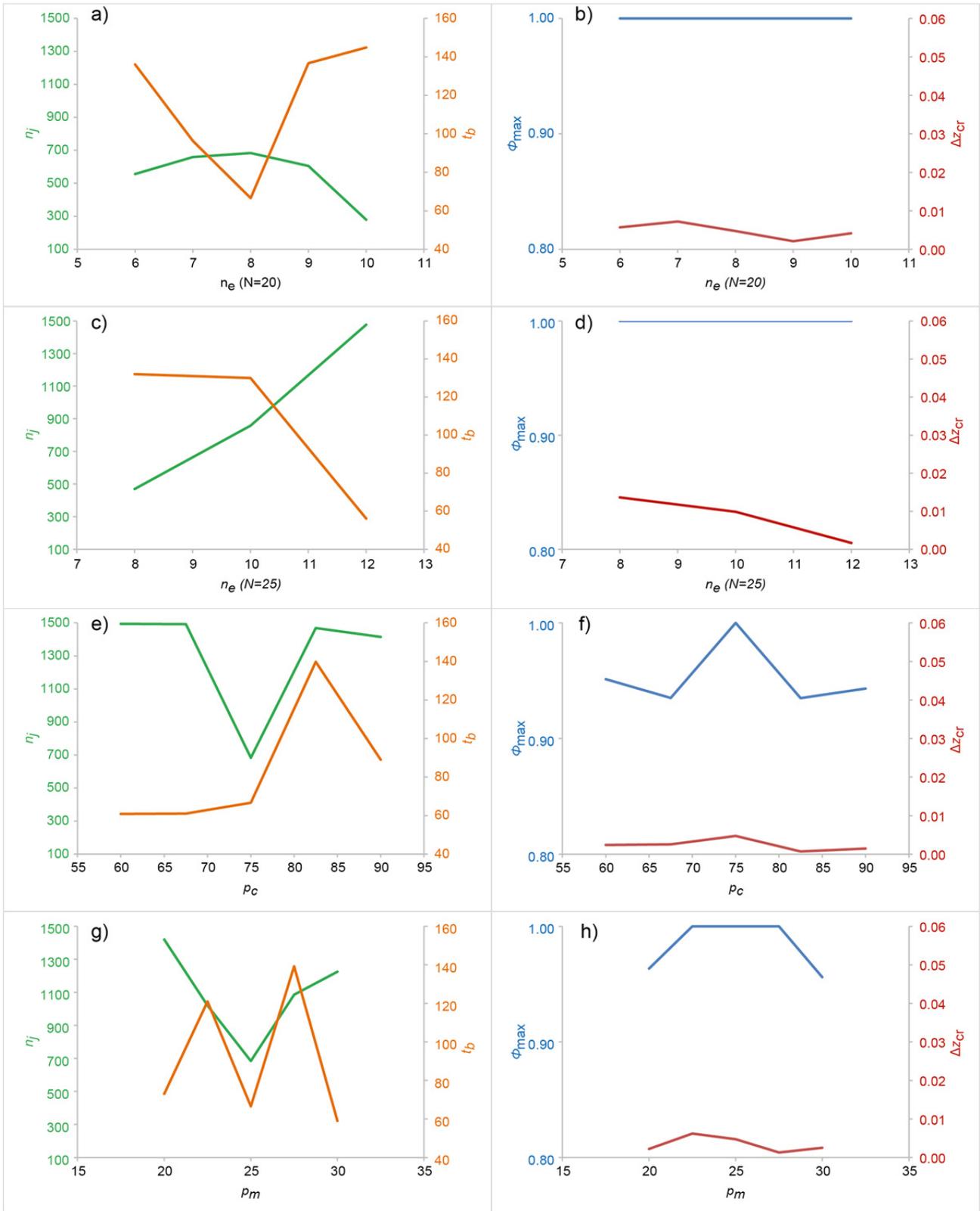
1116 **Figure 18.** Uncino landslide case study. Average kernels obtained in calibration against the 2, 3, 4, 5, and 6 dates of  
1117 activation.



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**Figure 19.** Maximum fitness ( $\Phi_{max}$ ), safety margin ( $\Delta z_{cr}$ ), number ( $n_i$ ) of iterations needed to first reach  $\Phi_{max}$ , and base time ( $t_b$ ) of the average kernel, based on GA parameters listed in Table 8.



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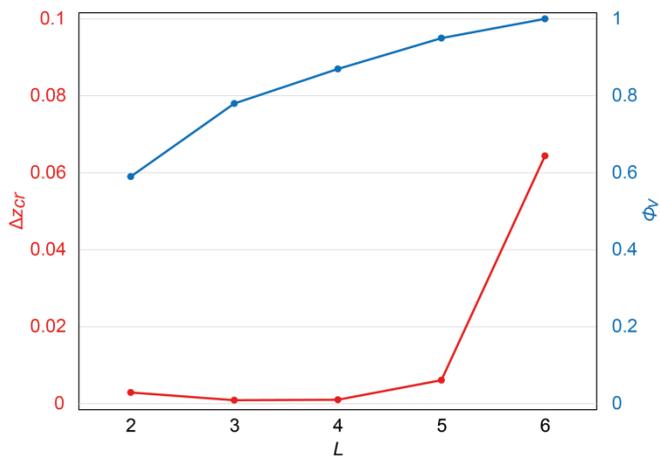
1124 **Figure 19**



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1127 **Figure 20.** Uncino landslide case study. Results of progressive calibration. Variation of  $\Delta z_{cr}$  and  $\Phi_v$  for  $L$  increasing  
1128 from 2 to 6.



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