

Verifications of the high-resolution numerical model and polarization relations of atmospheric acoustic-gravity waves

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Abstract

Comparisons of amplitudes of wave variations of atmospheric characteristics obtained using direct numerical simulation models with polarization relations given by conventional theories of linear acoustic-gravity waves (AGWs) could be helpful for testing these numerical models. In this study, we performed high-resolution numerical simulations of nonlinear AGW propagation at altitudes 0 – 500 km from a plane wave forcing at the Earth's surface and compared them with analytical polarization relations of linear AGW theory. After some transition time t_e (increasing with altitude) subsequent to triggering the wave source, initial wave pulse disappear and the main spectral components of the wave source dominate. The numbers of numerically simulated and analytical pairs of AGW parameters, which are equal with confidence 95%, are largest at altitudes 30 - 60 km at $t > t_e$. At low and high altitudes and at $t < t_e$ numbers of equal pairs are smaller, because of influence of the lower boundary conditions, strong dissipation and AGW transience making substantial inclinations from conditions, assumed in conventional theories of linear nondissipative stationary AGWs in the free atmosphere. Reasonable agreements between simulated and analytical wave parameters satisfying the scope the limitations of the AGW theory proof adequacy of the used wave numerical model. Significant differences between numerical and analytical AGW parameters reveal circumstances, when analytical theories give substantial errors and numerical

1 simulations of wave fields are required. In addition, direct numerical AGW simulations may
2 be useful tools for testing simplified parameterizations of wave effects in the atmosphere.

3 **1 Introduction**

4 Observations show frequent presence of acoustic-gravity waves (AGWs) generating at
5 tropospheric heights and propagating to the middle and upper atmosphere (e.g., Fritts and
6 Alexander, 2003). These AGWs can break and produce turbulence and perturbations in the
7 atmosphere. For example, sources of AGWs could be mesoscale turbulence and convection in
8 the troposphere (e.g., Fritts and Alexander, 2003; Fritts et al., 2006). Turbulent AGW
9 generation may have maxima at altitudes 9–12 km in the regions of tropospheric jet streams
10 (Medvedev and Gavrilov, 1995; Gavrilov and Fukao, 1999; Gavrilov, 2007).

11 Non-hydrostatic models are useful for direct numerical simulations of wave and turbulence in
12 the atmosphere. For example, Baker and Schubert (2000) simulated nonlinear AGWs in the
13 atmosphere of Venus. They modeled waves in the atmospheric region having horizontal and
14 vertical dimensions of 120 and 48 km, respectively. Fritts and Garten (1996), also Andreassen
15 et al. (1998) and Fritts et al. (2009, 2011) simulated instabilities of Kelvin-Helmholtz and
16 turbulence produced by breaking atmospheric waves. These models simulate turbulence and
17 waves in atmospheric regions with limited vertical and horizontal dimensions. The models
18 exploited spectral methods and Galerkin-type series for converting partial differential
19 equations (versus time) into the ordinary differential equations for the spectral series
20 components. Yu and Hickey (2007) and Liu et al. (2008) developed two-dimensional
21 numerical models of atmospheric AGWs.

22 Gavrilov and Kshevetskii (2013) developed a two-dimensional model for high-resolution
23 numerical simulating nonlinear AGWs using a finite-difference scheme taking into account
24 hydrodynamic conservation laws as described by Kshevetskii and Gavrilov (2005). This
25 scheme increases the stability of numerical scheme and allows us obtaining non-smooth
26 solutions of nonlinear wave equations. This permitted getting generalized physically
27 acceptable solutions to the equations (Lax, 1957; Richtmayer and Morton, 1967). Gavrilov
28 and Kshevetskii (2014a) created a three-dimensional version of this algorithm for simulating
29 nonlinear AGWs in the atmosphere. They modeled waves produced by sinusoidal horizontally
30 homogeneous wave forcing at the Earth's surface.

31 Karpov and Kshevetskii (2014) used similar numerical three-dimensional model to study
32 AGW propagation from local non-stationary wave excitation at the Earth's surface. They

1 showed that infrasound going from tropospheric sources could provide substantial mean
2 heating in the upper atmosphere. Dissipating nonlinear AGWs can also create accelerations of
3 the mean flows in the middle atmosphere (e.g., Fritts and Alexander, 2003). However, details
4 of the mean heating and mean flows created by non-stationary nonlinear AGWs in the
5 atmosphere need further studies.

6 Numerical models of atmospheric AGWs require verifications. For plane stationary wave
7 components with small amplitudes conventional linear theories (e.g., Gossard and Hooke,
8 1975) give the dispersion equation and polarization relations, which connect wave frequency,
9 vertical and horizontal wave numbers and ratios of amplitudes of different wave field
10 variations. One can expect that such relations could exist between corresponding parameters
11 of the numerical model solutions. Therefore, theoretical polarization relations could be useful
12 for verifications of direct simulation models of atmospheric AGWs.

13 In this paper, using the high-resolution numerical three-dimensional model by Gavrilov and
14 Kshevetskii (2014a,b), we made comparisons of calculated ratios of amplitudes of different
15 wave fields with polarization relations given by the conventional linear AGW theory. We
16 considered simple AGW forcing by plane wave oscillations of vertical velocity at the surface,
17 which is similar to the assumptions made in analytical wave theory. We found height regions
18 of the atmosphere, where numerical results agree with analytical ones, and regions of their
19 substantial disagreement.

20 Theoretical dispersion equation and polarization relations are widely used for developing
21 simplified parameterizations of AGW dynamical and thermal effects in the general circulation
22 models of the middle atmosphere. Therefore, comparisons of numerically modeled and
23 analytical polarization relations are useful for both verifications of numerical models, and
24 obtaining limits of analytical relation applicability and for verifications of AGW
25 parameterizations.

26 **2 Numerical model.**

27 The three-dimensional numerical AGW model calculates velocity components u , v , and w
28 along horizontal (x , y) and vertical, z , axes, respectively. The model also calculates departures
29 of pressure p' , temperature T' , and density ρ' from background hydrostatic stationary fields
30 p_0 , T_0 and ρ_0 , respectively. Gavrilov and Kshevetskii (2014a) described the set of
31 hydrodynamic nonlinear equations used in the model. The set includes equations of

1 continuity, momentum and heat balance. At the upper boundary $z = 500$ km, the conditions
 2 involve zero vertical gradients of perturbations of temperature, pressure, density and
 3 horizontal velocity, also zero vertical velocity. At the Earth's surface, the lower boundary
 4 conditions consist of zero perturbations of temperature, pressure, density and horizontal
 5 velocity (see Gavrilov and Kshevetskii, 2013; 2014a,b). In this study, we assume horizontal
 6 periodicity of wave solutions:

$$7 \quad r(x, y, z, t) = r(x + L_x, y + L_y, z, t), \quad (1)$$

8 where r denotes any of the calculated variables, and $L_x = m\lambda_x$, $L_y = n\lambda_y$ are the horizontal
 9 dimensions of the considered atmospheric region, m and n are integer constants, λ_x and λ_y
 10 are wavelengths along horizontal axes x and y , respectively. Variations of vertical velocity w_0
 11 $= w(x,y)$ at the ground $z = 0$ generate AGWs in the model.

12 The used numerical scheme is analogous to the two-dimensional algorithm described by
 13 Kshevetskii and Gavrilov (2005). It is a modification of the method by Lax and Wendroff
 14 (1960). This algorithm involves the conservation laws of momentum, mass and energy. The
 15 main difference of our scheme from the classical Lax and Wendroff (1960) algorithm is the
 16 implicit approximating equations of hydrodynamic at first half step in time, which diminish
 17 errors of description of acoustic waves (Kshevetskii, 2001a, b, c).

18 We use numerical scheme similar to the two-dimensional algorithm developed by
 19 Kshevetskii and Gavrilov (2005). Used hydrodynamic equations (see Gavrilov and
 20 Kshevetskii, 2013b, 2014a) can be presented in the conservation law forms

$$21 \quad \frac{\partial s}{\partial t} + \frac{\partial X(s)}{\partial x} + \frac{\partial Y(s)}{\partial y} + \frac{\partial Z(s)}{\partial z} = 0, \quad (2)$$

22 where s represents any of momentum, energy or mass per unit volume, X , Y , Z denote
 23 components of respective quantity fluxes along axes x , y , z . Additionally to the model by
 24 Kshevetskii and Gavrilov (2005), the current energy balance equation contains terms
 25 describing heating caused by viscosity. Used numerical method exploits the Lax and
 26 Wendroff (1960) scheme, which approximates Eq. (2) with the second-order finite-difference
 27 analog

$$28 \quad \frac{s_{i,j,k}^{n+1} - s_{i,j,k}^n}{\Delta t} + \frac{X_{i+1/2,j,k}^{n+1/2} - X_{i-1/2,j,k}^{n+1/2}}{\Delta x} + \frac{Y_{i,j+1/2,k}^{n+1/2} - Y_{i,j-1/2,k}^{n+1/2}}{\Delta y} + \frac{Z_{i,j,k+1/2}^{n+1/2} - Z_{i,j,k-1/2}^{n+1/2}}{\Delta z} = 0, \quad (3)$$

29 where n , i , j , k and Δt , Δx , Δy , Δz , are the grid node numbers and grid spacing in t , x , y , z ,
 30 respectively. This algorithm gives possibilities to select physically appropriate solutions of

1 the equations (Lax, 1957; Richtmayer and Morton, 1967). It keeps the numerical scheme
 2 stability and allows us consideration of non-smooth solutions of nonlinear AGW equations. In
 3 addition we exploit a staggered grid, where temperature, pressure and density are specified at
 4 the same nodes, but for the velocity components u , v , w the mesh points are half grid spacing
 5 shifted along axes x , y , z , respectively. To compute $s^{n+1/2}$ at the first time half step we apply
 6 the implicit equation

$$7 \quad 2 \frac{s_{i,j,k}^{n+1/2} - s_{i,j,k}^n}{\Delta t} + \frac{X_{i+1/2,j,k}^{n+1/2} - X_{i-1/2,j,k}^{n+1/2}}{\Delta x} + \frac{Y_{i,j+1/2,k}^{n+1/2} - Y_{i,j-1/2,k}^{n+1/2}}{\Delta y} + \frac{Z_{i,j,k+1/2}^{n+1/2} - Z_{i,j,k-1/2}^{n+1/2}}{\Delta z} = 0, \quad (4)$$

8 This substantially complicates simulations, but Kshevetskii (2001a, b, c) found that such
 9 structures of finite-difference schemes do not accumulate errors caused by acoustic waves.

10 In this study, we employ vertical profiles of background T_0 , ρ_0 , and p_0 given by the model of
 11 standard atmosphere MSIS-90 (Hedin, 1991) for average geomagnetic activity in January.
 12 The average spacing of height grid is about 170 m, but it is varying from 12 m near the
 13 ground (because of high gradients in the boundary layer) to about 1.2 km at altitudes of about
 14 500 km depending on inhomogeneities of vertical temperature profiles. The horizontal grids
 15 spacing is 1/60 of horizontal wavelengths taken in the wave source Eq. (2). Time spacing is
 16 automatically determined to guarantee stability of the numerical algorithm and is equal to
 17 0.14 s and 0.24 s for analyzed in this study AGWs having period $\tau = 2 \times 10^3$ s and horizontal
 18 phase speeds 30 m/s and 100 m/s, respectively.

19 The numerical model involves kinematic molecular heat conductivity and viscosity increasing
 20 versus altitude inversely proportional to the background density. We also include background
 21 turbulent heat conductivity and viscosity taking their vertical profiles with the maxima of 10
 22 m^2/s near the ground and at altitude of 100 km and the minimum of ~ 0.1 m^2/s in the
 23 stratosphere. The model does not include some effects, for example, wave dissipation caused
 24 by ion drag and radiative heat exchange, which are less important for modeling high
 25 frequency AGWs.

26 **3. AGW polarization relations.**

27 The comparisons considered in this paper used relations obtained from a theoretical model of
 28 monochromatic AGWs in the plain rotating atmosphere. Conventional linear theories
 29 suppose that wave components \mathbf{v}' , p' , ρ' , and T' are small deviations from stationary
 30 background values \mathbf{v}_0 , p_0 , ρ_0 , and T_0 . In agreement with Hines (1960), Beer (1974), and

1 Matsuno and Shimazaki (1981), we can look for solutions to atmospheric wave equations for
 2 AGW spectral components in the following form

$$3 \quad \frac{u'}{U} = \frac{v'}{V} = \frac{w'}{W} = \frac{p'}{p_0 P} = \frac{\rho'}{\rho_0 R} = \frac{T'}{T_0 \Theta} = \sqrt{\frac{p_{0s}}{p_0}} e^{i(\sigma t + \phi)}, \phi = -kx - mz, \quad (5)$$

4 where p_{0s} is the surface pressure; axis x is directed along horizontal wave phase velocity; σ , k
 5 and m are frequency, horizontal and vertical wave numbers; U , V , W , P , R and Θ are complex
 6 amplitudes of respective values. Assuming homogeneity of ν_0 and T_0 , one can obtain (see
 7 Hines, 1960; Beer, 1974) a dispersion equation relating frequency and wave numbers, which
 8 can be written in the form of:

$$9 \quad m^2 = \frac{N^2 - \omega^2}{\omega^2 - f^2} k^2 - \frac{\omega_a^2 - \omega^2}{c^2}, \quad (6)$$

10 where f is the Coriolis parameter, N is the isothermal Brunt-Vaisala frequency, c is the sound
 11 speed, ω_a is highest frequency of acoustic waves, $\omega = \sigma - ku_0$. Beer (1974) found that Eq. (6)
 12 could be appropriate approximation for slowly varying background temperature and wind if
 13 one use the following expressions:

$$14 \quad N^2 = \frac{g}{T_0} \left(\frac{\partial T_0}{\partial z} + \gamma_a \right); \quad \omega_a^2 = \frac{c^2}{4H^2} \left(1 + 2 \frac{\partial H}{\partial z} \right), \quad (7)$$

15 where $\gamma_a = g/c_p$, g is the acceleration by gravity, H is the atmospheric scale height, c_p is the
 16 heat capacity at constant pressure. Applying technique by Beer (1974) we can get the
 17 following polarization relations

$$18 \quad \begin{aligned} U &\propto \omega k c^2 (m - i\Gamma), & W &\propto \omega (\omega^2 - f^2 - k^2 c^2), \\ V &\propto i f k c^2 (m - i\Gamma), & P &\propto \gamma (\omega^2 - f^2) (m - i\Gamma), \\ 19 \quad R &\propto (\omega^2 - f^2) (m - i\alpha) + i k^2 c^2 N^2 / g, & & \\ 20 \quad \Theta &\propto (\gamma - 1) (\omega^2 - f^2) (m + i\alpha) - i k^2 c^2 N^2 / g, & & \end{aligned} \quad (8)$$

21 where $\alpha = 1/(2H)$; $\Gamma = (2-\gamma)/(2\gamma H)$, $\gamma = c_p/c_v$. Eq. (8) does not allow calculating wave
 22 amplitudes, but give opportunity to find their ratios. At $f=0$ Eq. (8) are equivalent to the

1 polarization relations obtained by Hines (1960). In nondissipative atmosphere, according Eq.
 2 (5), AGW amplitudes should grow with altitude, so that

$$3 \quad W = W_0 \sqrt{p_{0s}/p_0} \quad (9)$$

4 An important AGW characteristic is the wave momentum flux, vertical component of which,
 5 F_{mz} , is as follows

$$6 \quad F_{mz} = \rho_0 \langle u' w' \rangle = \rho_0 \operatorname{Re}(UW^*)/2, \quad (10)$$

7 where sign $\langle \rangle$ denotes averaging over the wave period.

8 **4. Comparisons of the numerical model and polarization relations.**

9 In this study, using the high-resolution nonlinear numerical model described in sect. 2, we
 10 simulated hydrodynamic fields produced by spectral AGW components and compared ratios
 11 of their amplitudes with those predicted by the analytical polarization relations Eqs. (7), (8).
 12 To make simulations matching the linear AGW theory (see Eq.(5)), we used nonlinear AGWs
 13 having forms of plane waves and suppose horizontally periodical distributions of vertical
 14 velocity at the Earth's surface moving along axis x of the form of

$$15 \quad (w)_{z=0} = W_0 \cos[k(x - c_x t)], \quad (11)$$

16 where $k = 2\pi/\lambda_x$ and c_x are horizontal wavenumber and phase speed along the horizontal axis x
 17 in the direction of the wave propagation; W_0 is the amplitude. Eq. (11) represents plane wave
 18 of vertical velocity at the lower boundary, which may correspond to spectral components of
 19 convective and turbulent AGW sources (Townsend, 1965, 1966). Medvedev and Gavrilov
 20 (1995) studied AGW generation caused by nonlinear interactions in meteorological and
 21 turbulent atmospheric processes. They found variety of wavelengths, amplitudes and other
 22 parameters of created AGWs. In this paper, we describe simulations for wave modes having
 23 $c_x = 30$ m/s and $c_x = 100$ m/s with unchanged period $\tau = 2 \times 10^3$ s and amplitudes $W_0 = 0.3$
 24 cm/s. The modeling was performed beginning from the MSIS initial state (zero wave fields)
 25 and the windless background flow at $t = 0$, when the wave source Eq. (11) was triggered at
 26 the lower boundary.

27 Gavrilov and Kshevetskii (2014a, b) demonstrated that after triggering the wave source at $t =$
 28 0, fast acoustic and very long gravity wave modes would quickly reach very high altitudes.
 29 Simulations demonstrate that in the horizontally periodic approximation of Eq. (1), these
 30 initial pulses can reach altitudes of 100 km and higher in a few minutes and form quasi-

1 vertical wave fronts analogous to those in Fig. 1a,b,c of the paper by Gavrilov and
2 Kshevetskii (2013, 2014a). These initial waves dissipate because of molecular viscosity and
3 heat conduction. When time increases, more and more of the waves with longer vertical
4 wavelengths are taken away by dissipation, therefore vertical wavelengths should decrease in
5 time at a given height in the middle atmosphere (Heale et al., 2014). After some transition
6 time, initial AGW wave modes disappear and wave vertical structure matches to the main
7 spectral component of the wave source (11) having horizontal wave number k and phase
8 speed c_x .

9 To estimate AGW amplitudes in the numerical model solution we calculated standard
10 deviations of corresponding wave fields over all nodes of the horizontal grid at considered
11 altitude. For sinusoidal wave component, this standard deviation is equal to a half AGW
12 amplitude. Therefore, ratios of amplitudes of horizontally homogeneous stationary sinusoidal
13 AGWs should be equal to the ratios of corresponding standard deviations. Simulated standard
14 deviations of wave fields in horizontal planes located at different heights grow in time
15 throughout transition intervals after activating the wave forcing and then tend to constant
16 values different at each height (see Gavrilov and Kshevetskii, 2014b). In the horizontally
17 periodical approximation of Eq. (1), these standard deviations are approximately equal to a
18 half wave amplitudes at large t , when the AGW process tends to become quasi-stationary. For
19 a plane spectral AGW component with vertical wavelength λ_z , the vertical group velocity is
20 $c_{gz} \approx \lambda_z/\tau$, and the time of its energy arriving to altitude z is $t_e = z/c_{gz}$. For considered main
21 spectral components of the wave source (8) with $\tau = 2 \times 10^3$ s and average $\lambda_z \sim 10$ km for $c_x =$
22 30 ms^{-1} , and $\lambda_z \sim 35$ km for $c_x = 100 \text{ ms}^{-1}$. Therefore, one can get $t_e/\tau = z/\lambda_z \sim 1, 6, 10$ and t_e/τ
23 $\sim 0.3, 1.7, 2.9$ at heights 10, 60, and 100 km, respectively, for both c_x . Thus, lengths of the
24 transition intervals are longer for smaller c_x . These intervals grow with altitude and may be
25 longer than ten wave periods at height of 100 km.

26 Table 1 represents standard deviations at different altitudes calculated with the numerical
27 model and with analytical polarization relations and their ratios for AGW with $c_x = 30$ m/s.
28 The Table 1 contains simulated SDs at each altitude averaged over n model outputs during the
29 initial transient interval $t < t_e$ (bottom part of Table 1) and for quasi-stationary waves $t > t_e$
30 (upper part of Table 1). Respective data numbers n for each altitude are presented in Table 1.
31 Respective values obtained from analytical linear AGW theory (see section 3) are calculated
32 using average background values and are placed to the columns labeled as “Lin” at each

1 altitude in Table 1. Consideration of Fig. 5 of the paper by Gavrilov and Kshevetskii (2014b)
2 shows that standard deviations of wave fields simulated with the numerical model vary in
3 time due to definite variations and irregular perturbations. Standard deviations of each
4 average numerically simulated parameter are given in Table 1.

5 For comparisons of numerically simulated values with analytical ones in Table 1, we use
6 standard t-test giving probability of the null hypothesis about equity of averages of two
7 irregular quantities (Rice, 2006). Approximately, the probability of equity of two respective
8 average values in Table 1 is larger 95%, if difference between them is less than 1.96
9 multiplied by the standard deviation of the average value (Rice, 2006). In this study, we
10 considered only cases, when the standard deviations in Table 1 are smaller than 0.15 of
11 respective average values. Pairs of AGW parameters, which we can consider equal with
12 confidence larger than 95%, are marked with bold font in Table 1. The numbers of those pairs
13 are largest in the upper part of Table 1 at altitudes 30 and 60 km, which correspond to quasi-
14 stationary AGWs in the free atmosphere considered in conventional AGW theory described in
15 sect. 3. Reasonable agreements between simulated and analytical wave parameters in
16 atmospheric regions, which correspond to the scope the limitations of the nondissipative
17 linear AGW theory, may be considered as evidences of adequate descriptions of wave
18 processes by the used nonlinear numerical model.

19 Many numerically simulated AGW parameters do not match to the respective analytical
20 values in Table 1. No matches are in the bottom part of Table 1, which corresponds to the
21 initial transition time interval. Gavrilov and Kshevetskii (2014b) showed that vertical
22 structures of transient waves are different from those predicted by the linear AGW theory
23 during the transition interval after activating the surface wave source Eq. (11). Bottom part of
24 Table 1 shows that numerically simulated wave amplitude W is smaller than that predicted by
25 AGW theory at high altitudes, because these values refer to small $t < t_e$, when energy of the
26 main wave component does not yet reach considered altitude. Numerical and analytical
27 amplitude ratios are also substantially different in the bottom part of Table 1 for $t < t_e$.

28 In the upper part of Table 1 for quasi-stationary AGWs at $t > t_e$, the numerically simulated
29 AGW amplitudes W are slightly smaller than the analytical values at altitudes up to 60 km.
30 This can be caused by small AGW dissipation at low altitudes and by partial reflections of the
31 wave energy from inhomogeneities of background atmospheric fields in the numerical model.
32 Wave dissipation becomes larger at altitude 100 km due to grows in cinematic viscosity and

1 heat conductivity, therefore simulated amplitude W in the upper part of Table 1 become much
2 smaller than that predicted by nondissipative AGW theory. In addition, one can see
3 substantial differences in numerically simulated and analytical ratios of some AGW
4 amplitudes, which can be due to influences of dissipative effects. At low altitudes, differences
5 in simulated and analytical ratios of AGW amplitudes can reflect the influence of lower
6 boundary conditions. In particular, the condition $u = 0$ at the Earth's surface makes AGW
7 amplitudes of horizontal velocity at low altitudes smaller than that predicted by the AGW
8 theory for free atmosphere. The upper part of Table 1 for $t > t_e$, shows that the best
9 agreements exists between numerical and analytical values of the ratio $R/\Theta \approx 1$ at all altitudes.

10 Table 1 reveals numerically simulated AGW momentum fluxes F_{mz} Eq. (10) calculated as
11 $\rho_0 \langle u'w' \rangle$ averaged over horizontal planes at fixed altitudes and over respective time
12 intervals. For comparisons, Table 1 contains also momentum fluxes F_{mz} given by Eq. (10) and
13 calculated from numerically simulated amplitudes W and U . The upper part of Table 1 shows
14 that at $t > t_e$ wave momentum flux F_{mz} is almost constant at altitudes 10 – 60 km due to
15 relatively small dissipation and reflection of wave energy. At altitude of 100 km wave
16 dissipation increases and F_{mz} decreases producing strong wave accelerations of the mean
17 flow, which are proportional to the vertical gradient of F_{mz} . In the bottom part of Table 1 for t
18 $< t_e$, values of F_{mz} are much smaller than respective F_{mz} values for $t > t_e$, because during
19 initial transition interval, energy of the main AGW modes of the wave source (11) does not
20 yet reach high altitudes.

21 Table 2 is the same as Table 1, but for AGW components with $c_x = 100 \text{ ms}^{-1}$, which has
22 longer vertical wavelength. In the upper part of Table 2 for $t > t_e$, we have smaller number of
23 pairs equal with confidence 95% (marked with bold font), than that in the upper part of Table
24 1. This may be connected with stronger influence of vertical inhomogeneities of background
25 temperature profile on faster AGW with longer vertical wavenumber and with larger partial
26 reflection of faster AGW energy. Stronger reflections lead to smaller amplitudes W at
27 altitudes below 100 km in the upper part of Table 2 compared to that in Table 1. On the other
28 hand, W at altitude 100 km in the upper part of Table 2 is larger than that in Table 1 due to
29 smaller dissipation of longer AGWs. Therefore, waves with longer vertical wavelengths can
30 faster propagate from the surface to the upper layers and less dissipate in the middle
31 atmosphere, where they can have larger amplitudes than those with shorter vertical
32 wavelengths (see Gavrilov and Kshevetskii, 2014b). Similar to Table 1, we have larger

1 amounts of equal (with 95% confidence) numerically simulated and analytical AGW
2 parameters at altitudes 30 and 60 km. At low and high altitudes and at $t < t_e$ (in the bottom
3 part of Table 2) numbers of equal pairs are smaller due to influence of the lower boundary
4 conditions, larger dissipation and AGW transience, respectively.

5 Tables 1 and 2 contains comparisons of the numerical results and linear polarization relations
6 at altitudes below 100 km, where considered AGW modes are quasi-linear and almost
7 nondissipative. At higher altitudes growing wave amplitudes and molecular viscosity and heat
8 conduction lead to fast growing wave-induced mean flows, which violate assumptions of
9 conventional AGW theories and change ratios of wave amplitudes of different hydrodynamic
10 fields. Therefore, we found poor agreement between numerical and analytical wave results
11 above altitude 100 km and do not include them into Tables 1 and 2. These disagreements
12 become larger with increases in amplitudes of the lower boundary wave sources due to higher
13 nonlinear effects and faster grows in the wave-induced jet streams above 100 km. To get
14 better agreements, improved analytical AGW theories taking into account transient processes,
15 high wave dissipation and fast changes in background fields are required.

16 In the areas of Tables 1 and 2, where numerical and analytical parameters are close, one can
17 use analytical formulae for descriptions and estimations of the wave fields. Opposite to that,
18 areas of substantial differences between numerical and analytical AGW parameters in Tables
19 1 and 2 reveal regions, where numerical simulations are required.

20 Relations of linear AGW theory are frequently used for simplified parameterizations of AGW
21 dynamical and thermal effects for their use in the numerical models of atmospheric general
22 circulations (e.g., Lindzen, 1981; Holton, 1983; Gavrilov, 1997; etc.). Similar
23 parameterizations are also developing for highly dissipative AGWs in the upper atmosphere
24 (e.g., Vadas and Fritts, 2005; Yigit et al., 2008). Sometimes, different parameterizations give
25 different results. Direct numerical simulation models of atmospheric AGWs may be useful
26 tools for testing and verifications of simplified parameterizations of wave effects.

27 **5. Conclusions**

28 In this study, we performed high-resolution numerical simulations of nonlinear AGW
29 propagation to the middle and upper atmosphere from a plane wave forcing at the Earth's
30 surface and compared them with analytical polarization relations of linear AGW theory. Such
31 comparisons may be used for verifications of numerical models of atmospheric AGWs.
32 Numerical simulations show that after triggering the wave source Eq. (11) at $t = 0$, fast

1 acoustic and very long gravity wave modes would quickly reach very high heights. After
2 some transition time t_e (increasing with altitude), initial AGW wave modes disappear and
3 wave vertical structure matches to the main spectral component of the wave source Eq. (11)
4 having horizontal wave number k and phase speed c_x . The numbers of numerically simulated
5 and analytical pairs of AGW parameters, which are equal with confidence 95%, are largest at
6 altitudes 30 and 60 km at $t > t_e$. At low and high altitudes and at $t < t_e$ numbers of equal pairs
7 are smaller, because of influence of the lower boundary conditions, larger dissipation and
8 AGW transience, which can produce substantial inclinations from conditions, assumed in
9 conventional theories of linear nondissipative stationary AGWs in the free atmosphere.
10 Reasonable agreements between numerically simulated and analytical wave parameters in
11 atmospheric regions, which correspond to the scope the limitations of the AGW theory, may
12 be considered as evidences of adequate descriptions of wave processes by the used nonlinear
13 numerical model. Areas of substantial differences between numerical and analytical AGW
14 parameters reveal atmospheric regions, where analytical theories give substantial errors and
15 numerical simulation of wave fields is required. Direct numerical simulation models of
16 atmospheric AGWs may be useful tools for testing and verifications of simplified
17 parameterizations of wave effects.

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4

Altitude	0.012 km		10 km		30 km		60 km		100 km	
	$t > 0.25\tau$	Lin	$t > t_e$	Lin	$t > t_e$	Lin	$t > t_e$	Lin	$t > t_e$	Lin
n	51		28		23		16		8	
$W, 10^{-3}\text{m/s}$	2.982±0.001	3.00	4.7±0.1	5.18	18.4±0.5	24.4	170±6	190	1730±140	4470
U/W	0.78±0.02	3.17	5.1±0.1	4.48	7.1±0.2	6.83	5.0±0.1	5.04	10.3±1.3	7.51
$\Theta/W, 10^{-3}\text{s/m}$	5.1±0.2	3.56	7.2±0.1	6.78	15.7±0.2	15.4	8.4±0.1	8.56	26.2±3.3	18.9
$R/W, 10^{-3}\text{s/m}$	5.2±0.3	3.55	7.2±0.1	6.77	15.4±0.2	15.4	8.6±0.2	8.56	27.0±3.4	18.8
$P/W, 10^{-3}\text{s/m}$	1.8±0.1	1.15	2.6±0.2	2.10	3.5±0.2	3.16	2.3±0.1	2.13	4.0±0.1	4.03
R/Θ	1.01±0.03	1.00	1.00±0.02	1.00	0.98±0.01	1.00	1.03±0.02	1.00	1.03±0.02	1.00
R/P	3.4±0.4	3.08	3.0±0.2	3.23	4.7±0.2	4.86	3.9±0.1	4.01	7.0±1.2	4.68
$R/U, 10^{-3}\text{s/m}$	6.7±0.4	1.12	1.41±0.03	1.51	2.16±0.03	2.22	1.71±0.02	1.7	2.63±0.03	2.51
$P/U, 10^{-3}\text{s/m}$	2.4±0.1	0.36	0.51±0.03	0.47	0.48±0.02	0.46	0.45±0.02	0.42	0.42±0.05	0.536
$F_{mz}, 10^{-5}\text{kg/m}^2/\text{s}$	0.29±0.02	0.42	2.2±0.1	2.29	2.2±0.1	2.20	2.2±0.2	2.17	0.8±0.1	0.84
	$t < 0.25\tau$	Lin	$t < t_e$	Lin	$t < t_e$	Lin	$t < t_e$	Lin	$t < t_e$	Lin
n	7		16		20		26		32	
$W, 10^{-3}\text{m/s}$	2.983±0.001	3.00	1.3±0.2	5.18	2.9±0.4	24.4	24±4	190	512±60	4470
U/W	0.60±0.07	3.17	4.1±0.5	4.48	4.3±0.7	6.83	2.9±0.4	5.04	3.8±0.5	7.51
$\Theta/W, 10^{-3}\text{s/m}$	3.0±0.7	3.56	5.5±0.8	6.78	7.8±1.3	15.4	4.1±0.7	8.56	9.1±1.5	18.9
$R/W, 10^{-3}\text{s/m}$	3.9±0.7	3.55	6.6±0.8	6.77	10.3±1.6	15.4	6.8±1.2	8.56	11.4±1.9	18.8
$P/W, 10^{-3}\text{s/m}$	1.8±0.3	1.15	7.1±1.0	2.1	8.9±1.7	3.16	6.6±1.5	2.13	8.3±1.9	4.03
R/Θ	3.1±2.0	1.00	2.0±0.5	1.00	1.97±0.5	1.00	4.4±2.0	1.00	3.5±1.3	1.00
R/P	2.5±0.5	3.08	1.1±0.1	3.23	2.1±0.6	4.86	1.7±0.2	4.01	2.0±0.3	4.68
$R/U, 10^{-3}\text{s/m}$	6.6±1.0	1.12	1.9±0.3	1.51	3.6±0.7	2.22	7.1±3.9	1.7	10.1±5.1	2.51
$P/U, 10^{-3}\text{s/m}$	3.1±0.4	0.36	2.0±0.3	0.47	3.6±0.9	0.46	9.0±5.4	0.42	12.6±7.0	0.536
$F_{mz}, 10^{-5}\text{kg/m}^2/\text{s}$	0.07±0.04	0.32	0.12±0.03	0.14	0.03±0.01	0.03	0.05±0.02	0.03	0.04±0.01	0.03

1 **Table 1.** Standard deviations and their ratios for AGW with $c_x = 30$ m/s calculated with the
2 numerical model and with analytical polarization relations (labeled as Lin) at different
3 altitudes averaged over the initial transient interval $t < t_e$ and for quasi-stationary waves $t > t_e$.
4 Bold font shows the data pairs equal with probabilities larger than 95%.
5

Altitude	0.012 km		10 km		30 km		60 km		100 km	
	$t > 0.25\tau$	Lin	$t > t_e$	Lin	$t > t_e$	Lin	$t > t_e$	Lin	$t > t_e$	Lin
n	51		28		23		16		8	
$W, 10^{-3}\text{m/s}$	2.982±0.001	3.00	3.7±0.3	5.18	18.2±1.7	24.4	161±14	190	3000±120	4470
U/W	0.79±0.05	2.96	6.4±0.5	4.42	5.8±0.4	7.22	3.9±0.3	5.25	7.1±0.3	12
$\Theta/W, 10^{-3}\text{s/m}$	6.4±0.3	3.34	8.4±0.5	6.69	13.6±0.7	16.3	8.5±0.4	8.78	19.0±0.3	30
$R/W, 10^{-3}\text{s/m}$	5.9±0.4	3.24	9.4±0.9	6.6	12.4±0.9	16.2	7.9±0.4	8.77	15.0±0.8	30
$P/W, 10^{-3}\text{s/m}$	7.0±0.5	3.59	13.1±1.4	6.89	8.5±0.5	11.1	6.5±0.9	7.4	11.9±0.4	13.8
R/Θ	1.1±0.1	0.97	1.2±0.1	0.99	0.91±0.04	1.00	0.93±0.04	1.00	0.78±0.04	1.00
R/P	1.2±0.2	0.9	0.94±0.1	0.96	1.6±0.2	1.46	1.5±0.1	1.19	1.3±0.1	2.17
$R/U, 10^{-3}\text{s/m}$	11.1±2.6	1.09	1.6±0.1	1.49	2.2±0.1	2.25	2.2±0.1	1.67	2.2±0.1	2.5
$P/U, 10^{-3}\text{s/m}$	10.4±1.4	1.21	2.0±0.1	1.56	1.6±0.1	1.54	1.6±0.2	1.41	1.7±0.1	1.15
$F_{mz}, 10^{-5}\text{kg/m}^2/\text{s}$	0.01±0.04	0.43	1.03±0.05	1.78	1.03±0.1	1.76	0.90±0.09	1.52	0.79±0.09	1.74
	$t < 0.25\tau$	Lin	$t < t_e$	Lin	$t < t_e$	Lin	$t < t_e$	Lin	$t < t_e$	Lin
n	7		16		20		26		32	
$W, 10^{-3}\text{m/s}$	2.983±0.001	3.00	2.3±0.4	5.18	5.9±0.7	24.4	112±4	190	600±110	4470
U/W	1.0±0.1	2.96	7.0±1.5	4.42	5.8±0.7	7.22	4.5±1.0	5.25	4.1±1.1	12
$\Theta/W, 10^{-3}\text{s/m}$	3.6±1.1	3.34	5.9±1.8	6.69	9.5±1.3	16.3	7.3±1.0	8.78	8.8±1.7	30
$R/W, 10^{-3}\text{s/m}$	8.6±0.6	3.24	17.9±2.4	6.6	17.5±1.5	16.2	9.8±1.7	8.77	15.5±3	30
$P/W, 10^{-3}\text{s/m}$	10.5±0.8	3.59	21.2±2.9	6.89	16.7±1.7	11.1	10.1±2	7.4	14.3±2.8	13.8
R/Θ	4.5±1.4	0.97	6.2±2.1	0.99	3.3±0.9	1.00	2.2±0.8	1.00	2.8±0.7	1.00
R/P	0.84±0.05	0.9	0.86±0.06	0.96	1.2±0.1	1.46	1.3±0.1	1.19	1.2±0.2	2.17
$R/U, 10^{-3}\text{s/m}$	9.6±1.7	1.09	4.6±1.8	1.49	4.3±0.8	2.25	9.4±14	1.67	39±22	2.5
$P/U, 10^{-3}\text{s/m}$	11.8±2.1	1.21	5.5±2.1	1.56	4.4±0.9	1.54	11.8±19	1.41	45±29	1.15
$F_{mz}, 10^{-5}\text{kg/m}^2/\text{s}$	0.12±0.06	0.54	0.44±0.11	0.75	0.31±0.09	0.15	0.59±0.01	0.85	0.06±0.03	0.04

1 **Table 2.** Same as Table 1, but for AGW with $c_x = 100$ m/s.

2