

# Reduction of predictive uncertainty in estimating irrigation water requirement through multi-model ensembles and ensemble averaging

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## Abstract

Irrigation agriculture plays an increasingly important role in food supply. Many evapotranspiration models are used today to estimate the water demand for irrigation. They consider different stages of crop growth by empirical crop coefficients to adapt evapotranspiration throughout the vegetation period. We investigate the importance of the model structural versus model parametric uncertainty for irrigation simulations by considering six evapotranspiration models and five crop coefficient sets to estimate irrigation water requirements

1 for growing wheat in the Murray-Darling Basin, Australia. The study is carried out using the  
2 spatial decision support system SPARE:WATER. We find that structural model uncertainty  
3 among reference ET is far more important than model parametric uncertainty introduced by crop  
4 coefficients. These crop coefficients are used to estimate irrigation water requirement following  
5 the single crop coefficient approach. Using the Reliability Ensemble Averaging (REA) technique,  
6 we are able to reduce the overall predictive model uncertainty by more than 10%. The  
7 exceedance probability curve of irrigation water requirements shows that a certain threshold, e.g.  
8 an irrigation water limit due to water right of 400mm, would be less frequently exceeded in case  
9 of the REA ensemble average (45%) in comparison to the equally weighted ensemble average  
10 (66%). We conclude that multi-model ensemble predictions and sophisticated model averaging  
11 techniques are helpful in predicting irrigation demand and provide relevant information for  
12 decision making.

13

14

## 15 **1 Introduction**

### 16 **1.1 Predicting crop water needs**

17 Globally, the proportion of fresh water consumption by agriculture from rainfall as well as  
18 surface and groundwater resources is large ( $9,087 \text{ km}^3 \text{ y}^{-1}$ ) (Hoekstra and Mekonnen, 2012). It is  
19 projected that water demand is increasing in the future, in particular by irrigation agriculture, in  
20 order to support the increasing world population with food (Foley et al., 2011; De Fraiture and  
21 Wichelns, 2010; Hanjra and Qureshi, 2010; Wada and Bierkens, 2014). Therefore, strategies  
22 based on improved irrigation methods and local adaptations of management practices are likely to  
23 be implemented to anticipate this trend. Such strategies are often developed using decision  
24 support systems that are informed by mathematical models. For example, irrigation management  
25 has been optimized by modelling and measurements for crops grown in Central Asia (Pereira et  
26 al., 2009) or for irrigated cotton in the High-Plains region of Texas (Howell et al., 2004). Others  
27 have investigated water use efficiency (Wang et al., 2001) or crop water productivity (Liu et al.,  
28 2007) by modelling experiments for irrigated crops grown in China.

1 All these models depend on the calculation of evapotranspiration (ET) which represents the  
2 evaporation from a surface and transpiration from plants. In the case of agricultural crops, ET is  
3 equal to the crop water needed for crop growth and yield production. Globally,  
4 evapotranspiration represents about two thirds of the total rainfall on land, while  
5 evapotranspiration from crops amounts for about 8% (Oki and Kanae, 2006), and is insofar the  
6 most important term of the water balance. The basic concept for deriving crop water needs of  
7 irrigated crops has been initially reported by Jensen (1968) and is proposed by Allen et al. (1998)  
8 as the single crop coefficient concept. The crop specific evapotranspiration ( $ET_c$ ) is derived from  
9 reference evapotranspiration ( $ET_o$ ) and a crop specific coefficient ( $K_c$ ):

$$10 \quad ET_c = ET_o \cdot K_c \quad (1)$$

11 with  $ET_o$  given in [mm] and dimensionless  $K_c$ .  $ET_o$  can be calculated by standardise potential  
12 evapotranspiration (PET) to a short (grass) or tall (alfalfa) reference crop. In the case of the  
13 Penman-Monteith equation (Monteith, 1965; Penman, 1948) standardized fixed values for albedo  
14 (0.23), plant height (0.12 cm) and surface resistance ( $70 \text{ m s}^{-1}$ ) are assumed (Allen et al., 1998;  
15 Jensen et al., 1990).  $K_c$  is commonly calculated on the basis of field experiments (e.g. Ko et al.,  
16 2009; da Silva et al., 2013) and varies with the crop development.

17 Such an approach is part of many irrigation management models, including Cropwat (Smith,  
18 1992), ISAREG (Pereira et al., 2009), ISM (George et al., 2000) or global crop water models  
19 (Siebert and Döll, 2010). Moreover, the single crop coefficient concept is the basis for the  
20 simulation of crop water needs in many studies. For example, Lathuilière et al. (2012) have  
21 derived water use by terrestrial ecosystems and have shown that actual ET declines over a 10  
22 year period by about 25% in response to deforestation and replacement by agriculture in Brazil.  
23 They showed that irrigation water requirement (IRR) is relevant for terrestrial water fluxes and a  
24 reliable estimation is crucial for the closure of the water cycle. In another study future climate  
25 impacts on groundwater in agriculture areas have been investigated (Toews and Allen, 2009).  
26 They showed that larger return flows to the groundwater can be related to increased IRR under  
27 warmer temperatures and longer vegetation periods. Moreover, the crop coefficient concept is  
28 also the basis for the water footprint (volume of water consumed or polluted to produce one unit  
29 of biomass) assessment of crops (Mekonnen and Hoekstra, 2011) and has been used to determine

1 water requirements and the water footprint of the agriculture sector in Saudi Arabia (Multsch et  
2 al., 2013). In almost all studies, researcher use only one  $ET_o$  method with a single, often spatially  
3 independent  $K_c$  set. As a result, some scientists ask to use locally adapted  $K_c$  sets at least (Ko et  
4 al., 2009; da Silva et al., 2013). For this reason, the investigation of predictive uncertainty of IRR  
5 is needed, in particular in the frame of large scale assessments.

6

## 7 **1.2 Sources of predictive uncertainty**

8 Major sources of uncertainties should be considered in the study design, quantified throughout  
9 the modelling process (Refsgaard et al., 2007) and communicated as part of the results to the end  
10 users. Uncertainties related to large scale estimations of the IRR have only rarely been analysed.  
11 For example, Siebert and Döll (2010) have studied the uncertainty in predicting green (rainfall  
12 consumed by crops) and blue (consumed surface and groundwater by crops in terms of irrigation)  
13 water consumption by using different  $ET_o$  equations on a global scale. They observed a  
14 significant difference of blue water consumption, i.e. required irrigation, and only a small change  
15 in green water consumption between model runs while using two classical  $ET_o$  equations. More  
16 recently, Sheffield et al. (2012) pointed out that using a more up-to-date parameterization of PET  
17 to calculate drought indices led to different conclusions on drought occurrence globally.

18 Generally, model predictive uncertainty can be lead back to four sources, input uncertainty,  
19 output uncertainty, structural uncertainty and parametric uncertainty (Renard et al., 2010). The  
20 last two, structural and parametric uncertainty, are addressed in this study with a focus on the  
21 prediction of IRR. As part of the parametric uncertainty, the parameterization of equations to  
22 quantify natural or anthropogenic processes has received considerable interest, particularly in  
23 conceptual rainfall-runoff modelling (Beven, 2006; Vrugt et al., 2009). In case of modelling crop  
24 water needs according to Eq. 1,  $K_c$  is an important model parameter.  $K_c$  values for a large number  
25 of crops are provided by the FAO56 irrigation guidelines (Allen et al., 1998) which are  
26 commonly used for irrigation planning. However, it has been highlighted that an adjustment to  
27 the global  $K_c$  is needed if the simulations are used for irrigation planning on a local to regional  
28 scale (Ko et al., 2009; da Silva et al., 2013). Nevertheless, it is still unclear whether a local

1 adaption of  $K_c$  leads to a better model performance. For this reason, we quantify the parametric  
2 uncertainty of model parameterisation with different  $K_c$  sets.

3 The model structure also introduces uncertainties, as any model remains a simplification of the  
4 real world. In the context of modelling water resources, all hydrological and crop growth models  
5 rely on the estimation of ET. According to equation 1,  $ET_o$  is required to estimate crop specific  
6 evapotranspiration.  $ET_o$  equations are often divided into categories according to the input data  
7 (Bormann, 2011; Tabari et al., 2013): temperature based equations such as Hargreaves-Samani  
8 (HS) equation (Hargreaves and Samani, 1985), radiation based equations such as Priestley-Taylor  
9 (PT) (Priestley and Taylor, 1972) or combined equations such as the FAO56 Penman-Monteith  
10 (PM56) equation (Allen et al., 1998), that further takes wind speed into account. Nevertheless, in  
11 many cases it was shown that the variability among  $ET_o$  methods is large (Fisher et al., 2011;  
12 Kite and Droogers, 2000). Because most water resources models rely on some calculation of  $ET_o$ ,  
13 we see it as a crucial source of structural uncertainty that is rarely considered.

### 14 **1.3 Reduction of predictive uncertainty by ensemble modelling**

15 Ensembles of model predictions can be developed by different sets of model parameterization  
16 (single-model ensemble) and model structures (multi-model ensemble). The weighting of model  
17 ensembles according to their fit to observational data has become of interest to reduce the  
18 uncertainty and to derive a more robust predictions and projections. Giorgi and Mearns (2002)  
19 have introduced the reliability ensemble averaging technique (REA) in climate research.  
20 Basically, different models are weighted according to their performance in representing measured  
21 data and according to the distance of individual models to the ensemble average prediction to  
22 quantify the convergence of different models. This approach has been applied more recently for  
23 predicting catchment nitrogen fluxes (Exbrayat et al., 2013) and calculating water balances and  
24 land use interaction (Huisman et al., 2009).

25 In a first step, we analyse the relative contributions of the structural and parametric model  
26 uncertainty in hind casts of IRR of wheat across the Murray-Darling-Basin (MDB), Australia.  
27 Simulations are calculated using the spatial decision support system SPARE:WATER (Multsch  
28 et al., 2013). In a second step, we apply the REA methodology to reduce the predictive  
29 uncertainty of IRR. The general procedure is as follows:

- 1 • The applicability of six different  $ET_o$  methods is evaluated by using available measured  
2 class-A-pan evaporation measurements of 34 stations in the MDB over a 21years time  
3 period;
- 4 • 30 different model realisations are setup in a multi-model ensemble by combining various  
5  $ET_o$  equations (n=6) and crop coefficient data sets (n=5);
- 6 • IRR is calculated by forcing the multi-model ensemble with climate time series of 21  
7 years (monthly data) for 3,969 sites (each 1 km<sup>2</sup> x 1km<sup>2</sup>) in the MDB where irrigated  
8 wheat has been grown according to the land use allocation in 2000;
- 9 • The 30 model realisations are weighted according to their performance in representing  
10 measured data and their distance to the ensemble average.

11 By doing so, we quantify structural ( $ET_o$  method) and parametric ( $K_c$  set) uncertainty and apply  
12 REA to provide a robust estimate of IRR and the confidence interval around it. The underlying  
13 research question is how can we derive better predictions by using an ensemble of well-known  
14  $ET_o$  methods as well as  $K_c$  sets and which are the likely causes of predictive uncertainty in IRR  
15 estimations. Finally, we show a procedure to reduce predictive uncertainty of IRR.

16

## 17 **2 Methods and data**

### 18 **2.1 Study site and data**

19 The MDB covers about 1 million km<sup>2</sup> of south-east Australia (Fig. 1). Irrigation agriculture in the  
20 MDB sums up to 17,600 km<sup>2</sup>, which is equal to 65% of the total irrigation agriculture in  
21 Australia. Total water withdrawal for irrigation in 2006 amounted to 7.36 km<sup>3</sup> yr<sup>-1</sup> (ABS, 2006).  
22 Wheat is the second most important crop grown in MDB after grazing pastures, covering 3,969  
23 km<sup>2</sup> in 2006 and was therefore selected for this case study for which IRR and its underlying  
24 uncertainty was calculated. The cropping areas have been taken from a land use map from 2006  
25 (ABARES, 2010) with a spatial resolution of 0.01° x 0.01° (~1 km x 1 km). We assume a fixed  
26 land use distribution over time in our model study to clearly target the uncertainty in  $ET_o$  method  
27 and crop coefficients. Climate data for 1986-2006 were taken from the SILO Data Drill of the

1 Queensland Department of Natural resources and Water (<https://longpaddock.qld.gov.au/silo/>  
2 (Jeffrey et al., 2001)) with a spatial resolution of  $0.05^\circ \times 0.05^\circ$  (~5 km x 5 km). We used the  
3 same weather dataset over all 3,969 1 x 1 km land grid cells overlapped by a 5 x 5 km grid cell in  
4 the weather data. The model was forced with monthly data. For validation, we compared  
5 simulated  $ET_o$  to measured class-A pan data from 34 stations throughout the MDB. The class-A  
6 pan data were obtained from Patched Point Dataset of the Queensland Department of Science,  
7 Information Technology, Innovation and the Arts,  
8 (<http://www.longpaddock.qld.gov.au/silo/ppd/>). Measured data have been adjusted with monthly  
9 pan-coefficients according to McMahon et al. (2013) to represent evaporation from open surface  
10 water. For stations where no pan-coefficient was available we used the one from the nearest  
11 station.

12

## 13 **2.2 Simulation of irrigation requirement with SPARE:WATER**

14 SPARE:WATER (Multsch et al., 2013) is a spatial decision support system for the calculation of  
15 crop specific water requirements and water footprints from local to regional scale. Input  
16 parameter for the simulation are climate data, irrigation management (irrigation water quality,  
17 irrigation efficiency, irrigation method), a digital elevation model and crop characteristics such as  
18 maximum crop height and length of growing season as well as sowing and planting date. In a first  
19 step, the water requirement of growing a crop is simulated for each grid cell according to the  
20 spatial resolution of the input data. In a second step, the water footprint for spatial entities such as  
21 administrative boundaries or catchments is calculated considering statistical data on crop yield  
22 and harvest area. Water footprints for geographic entities are given as volume of water consumed  
23 per year (e.g.  $\text{km}^3 \text{yr}^{-1}$ ) and water footprints for specific crops as volumes of water consumed per  
24 biomass ( $\text{m}^3 \text{t}^{-1}$ ).

25 In this study the calculation of the IRR is calculated as the difference between  $ET_c$  and effective  
26 rainfall ( $P_{\text{eff}}$ ). The latter one is estimated from the difference of surface run-off (RO) and  
27 precipitation (P). RO is derived as a fixed fraction of 20% of total P. The fixed fraction of runoff

1 is adapted from the default setting of the FAO Cropwat model (Smith, 1992). On this basis, IRR  
2 is calculated according to Eq. 2:

$$3 \quad IRR = \max(ET_c - P_{eff}, 0) \quad (2)$$

4 with IRR,  $ET_c$  and  $P_{eff}$  given in [mm].  $ET_c$  is calculated based on the single crop coefficient  
5 approach initially proposed by Jensen (1968) and recommended by Allen et al. (1998) according  
6 to Eq. 1. The input parameters for this method are the length of four individual stages (initial  
7 season, growth season, mid-season and late season) during the growing season and three related  
8 crop coefficients ( $K_c$ ). These define the ratio between  $ET_o$  and  $ET_c$  for each part of the growing  
9 season. We have considered five different  $K_c$  data sets (Table 1). The most common dataset has  
10 been proposed from the FAO56 Irrigation and Drainage Guidelines (Allen et al 1998). This  
11 approach has been applied for calculating crop water footprints (Mekonnen and Hoekstra, 2011)  
12 and is part of the widely used Cropwat model (Smith 1992). It has been discussed that locally  
13 adapted  $K_c$  sets are superior in simulating site-specific crop water requirement than global ones  
14 (Ko et al., 2009; da Silva et al., 2013). Thus, further data sets have been collected from various  
15 sources which represent site-specific relationships between  $ET_o$  and  $ET_c$  for areas in the MDB.

16  $ET_o$  has been calculated with six different methods (Table 2). Two of them are classified as  
17 combined methods (PM56, PPET), three are radiation-based methods (PT, TURC, APET) and  
18 one is a temperature based method (HS). All of them are commonly applied function, e.g. PM56  
19 and HS are included in Cropwat (Smith, 1992) and Aquacrop (Steduto et al., 2009), two models  
20 to quantify crop water and IRR, widely used and promoted by the FAO. The cropping system  
21 model EPIC (Williams, 1989) additionally allows the use of the PT equation, while the global  
22 vegetation model LPJmL (Fader et al., 2010) and the global water model WaterGap (Döll et al.,  
23 2003) are restricted to PT. APET and PPET have been particularly tested for the utilisation under  
24 Australian weather conditions in several (Chiew et al., 2002; Chiew and Leahy, 2003; Donohue  
25 et al., 2010).

26



### 1 2.3 Reliability Ensemble averaging

2 We used two types of ensemble averaging techniques, which differ in the weighing technique.  
3 We calculated an equally weighted average of all 30 model realisations (6 ET<sub>o</sub> methods x 5 K<sub>c</sub>  
4 datasets) for every grid cell which sum up to 3,969 cells (1 x 1 km) in the MDB where irrigated  
5 wheat is grown according to the land use allocation in 2006. However, this method does not  
6 consider the capability of its ensemble members to predict a target value nor does it value the  
7 agreement of model predictions amongst each other. Therefore, we apply the REA technique that  
8 was initially proposed by Giorgi and Mearns (2002) to reduce uncertainties in climate change  
9 projections. Moreover, it was used in impact studies targeting land use change impacts on  
10 hydrology (Huisman et al., 2009) and water quality scenario projections (Exbrayat et al., 2013).

11 The strength of the REA method is that it considers both the quality of a model prediction  
12 (performance) and its position within an ensemble of prediction (convergence). The aim is to  
13 provide a best estimate of predictions and a robust assessment of the confidence interval around  
14 it. The REA weighting scheme estimates two factors, model performance ( $R_B$ ) and model  
15 convergence ( $R_D$ ).  $R_B$  represents the capability of each ensemble member to represent real world  
16 data by its bias  $B$ .  $R_D$  is a measure of the distance  $D$  of a single model to the equally weighted  
17 ensemble average. Both are limited by the natural background variability ( $\varepsilon$ ). The combined  
18 effect known as reliability factor ( $R$ ) is derived as:

$$19 \quad R = \overbrace{\left[ \frac{\varepsilon}{abs(B)} \right]}^{R_B} * \overbrace{\left[ \frac{\varepsilon}{abs(D)} \right]}^{R_D} \quad (3)$$

20 In this study,  $\varepsilon$  is calculated from measured class-A pan evaporation for 34 climate stations in the  
21 study region for the time period from 1986 to 2006. The class-A pan data has been adjusted with  
22 monthly pan coefficients for climate stations in Australia (McMahon et al., 2013). We calculated  
23 the annual mean evaporation [mm] for each year and each station and used the 50% confidence  
24 interval (difference between the 25% and 75% percentile) of 224 mm to define  $\varepsilon$ . The  
25 consideration of the difference between upper and lower percentiles has been recommended by  
26 Giorgi and Mearns (2002). Model performance is measured by the RMSE between measured  
27 (class-A pan) and predicted ET<sub>o</sub> for each model (i).

1 The convergence criterion  $R_D$  is calculated in an iterative procedure. The difference between the  
2 average IRR of each ensemble member  $i$  and the ensemble average is calculated. Under the  
3 consideration of the natural background variability  $\varepsilon$  a first guess of  $R_D$  (for each ensemble  
4 member) is predicted as well as a first guess of the REA average. This procedure is repeated by  
5 considering the newly derived REA average until the ensemble convergence, so that the  
6 difference between ensemble members and the REA average cannot be reduced by additional  
7 iterations (see Giorgi and Mearns (2002) for a complete methodological description). The error of  
8 the equally weighted ensemble average is described by the RMSE between  $IRR_i$  predicted by  
9 model  $i$  (with  $n=30$  models) and the equally weighted ensemble average irrigation water  
10 requirement ( $\overline{IRR}$ ). The error of the reliability ensemble average ( $RMSE_{REA}$ ) is derived from the  
11 reliability factor of each model ( $R_i$ ), the irrigation water requirement predicted by model  $i$  ( $IRR_i$ )  
12 and the REA weighted ensemble average ( $\overline{IRR}_{REA}$ ). The RMSE represents an approximate 60-  
13 70% confidence interval under the assumption that the amount of irrigation is distributed  
14 somewhere between normal and uniform.

15

## 16 **3 Results**

### 17 **3.1 Validation of $ET_o$ methods**

18 We applied six  $ET_o$  equations to 34 sites in the MDB for which measured class-A pan  
19 evaporation data were available from 1986 to 2006 (Fig. 2). Class-A pan data represent the  
20 evaporation from an open water surface and integrate all climate factors driving evaporation such  
21 as radiation, wind speed, humidity and temperature. Pan evaporation differs from evaporation  
22 from a cropped surface through a different albedo, heat storage and humidity above the surface.  
23 For this reason, the class-A pan data have been adjusted with monthly pan coefficients  
24 (McMahon et al., 2013) to better compare them with  $ET_o$  simulations of open surface waters. On  
25 an annual average, class-A pan evaporation of  $1,558 \text{ mm yr}^{-1}$  were reduced by 9% to  $1,422 \text{ mm}$   
26  $\text{yr}^{-1}$  across all stations.

27 The median daily  $ET_o$  for APET is  $3.6 \text{ mm d}^{-1}$ , PM56  $3.9 \text{ mm d}^{-1}$ , HS  $3.8 \text{ mm d}^{-1}$ ,  
28 PPET  $5.2 \text{ mm d}^{-1}$ , PT  $6.4 \text{ mm d}^{-1}$  and TURC  $3.4 \text{ mm d}^{-1}$ . According to the root-mean-squared-

1 error (RMSE) PM56 gave the most reliable results. The median of  $ET_o$  for APET, PM56 and HS  
2 are close to the median of the measured evaporation rate of  $3.7 \text{ mm d}^{-1}$ . Apart from PT and PPET,  
3 the other methods underestimate  $ET_o$ , especially where class-A pan data are larger than  $6 \text{ mm d}^{-1}$ .  
4 The relationship between measured and simulated  $ET_o$  is linear as shown by the coefficients of  
5 determination  $r^2$  ranging from 77% (PT) to 88% (PPET).

6 The simulated  $ET_o$  is normally distributed if a single station and one year is tested (Shapiro test  
7 for normality:  $\alpha > 0.1$  for each year and station). The difference between the 34 stations is up  
8 to two times larger than the inter-annual difference in the 21 years period. Thus, spatial  
9 variability is larger than temporal variability in the MDB. The intra-annual variability shows a  
10 different picture. The median  $ET_o$  in the summer months is up to four times larger than the  $ET_o$   
11 during winter months for all  $ET_o$  methods, except PPET and PT with a six times larger  $ET_o$  in  
12 summer than in winter months.

13 Four of the six methods simulate the measured data with a high  $r^2$  and a low RMSE. The  
14 difference between the methods itself is large, in particular through the high  $ET_o$  estimates by PT  
15 and PPET. Thus, the structural uncertainty through the  $ET_o$  method is substantial and needs to be  
16 considered for the prediction of IRR which is addressed in the next chapters.

17

### 18 **3.2 Irrigation water requirement and its variability**

19 The IRR of wheat has been simulated using an ensemble of thirty model realisations for each of  
20 the 3,969  $1 \text{ km} \times 1 \text{ km}$  irrigated cells in the MDB for 21 years. Average values of IRR for all  
21 model realisations are shown in Table 3. In most cases, the largest estimates are given by the  
22 combinations of the Kc set Hughes with the  $ET_o$  method PT. These are almost 2.5 times higher  
23 than the lowest average IRR calculated by the combination of TURC with the Kc set Harris. It is  
24 obvious that changing  $ET_o$  method results in a larger variation of calculated IRR than using a  
25 different Kc set. Hence, the average IRR give a first idea about variability due to model structures  
26 and parameters.

27 Over a large watershed such as the MDB local differences in IRR may be large while catchment  
28 wide water management plans define thresholds for water withdrawal, for example due to water

1 rights or water resources protection measures. A given threshold may require heterogeneous local  
2 adaptations of irrigation management and a change in cropping patterns. Figure 3 shows the  
3 probability that a certain amount of IRR is exceeded in the MDB on average over the 21 year  
4 period. It illustrates the range of IRR predicted by the ensemble of all 30 model realisations for  
5 each grid cell. Two groups can be identified that are separated by  $ET_0$  methods. The first group is  
6 composed of PPET and PT calculations. In this case, IRR is up to twice as high as compared to  
7 predictions by other models. The second group is formed by APET, HS, PM56 and TURC with  
8 substantially lower calculations of less than 500 mm in most cases. We note that the parametric  
9 uncertainty is almost negligible compared to the uncertainty introduced by the various  $ET_0$   
10 methods.

### 11 **3.3 Ensemble averaging, uncertainty and weighting**

12 Ensemble predictions have become an important tool to account for different model structures  
13 and parameters (Exbrayat et al., 2013; Huisman et al., 2009; Wada et al., 2013). The  
14 consideration of ensembles is especially helpful to increase our confidence in simulations when  
15 no validation data are at hand, such as projections of Earth's future climate under specified  
16 emission scenarios. Here we apply the concept of ensemble prediction to simulations of IRR.  
17 Two different ensemble averages, expressed as the exceedance probability of the IRR of wheat  
18 are shown in Fig. 4. The first one represents the equally weighted average of irrigation ( $\overline{IRR}$ ,  
19 black line). The second one represents a weighted average using the reliability ensemble  
20 averaging ( $\overline{IRR}_{REA}$ , red line, see methods description) that weights predictions based on their  
21 performance and agreement with other ensemble members. This prevents dismissing some model  
22 structure, a process that can be rather subjective. Also, even an overall poorly performing model  
23 can contribute to the optimal information extracted from the ensembles (Viney et al., 2009), or  
24 may outperform better performing models once boundary conditions are changed (Exbrayat et al.,  
25 2013).

26 We use the inverse of the cumulative daily RMSE (Fig. 2) of the  $ET_0$  methods during the  
27 growing season to calculate the criterion  $R_B$  (RMSE 154 mm for APET, 123 mm for PM56,  
28 142 mm HS, 232 mm PPET, 373 mm PT, 166 mm TURC). The convergence criterion  $R_D$  was  
29 calculated based on the difference of the predicted irrigation given by a single ensemble member

1 and the equally weighted ensemble average (see Methods description). Overall, the PT model  
2 combinations have the lowest reliability factors of between 0.51 and 0.6 followed by PPET with  
3 0.96, a result driven by the poorer performance of these methods to simulate pan-evaporation  
4 (Fig. 2), and the outlying positions of simulations using PT and PPET (Fig. 3). All other models  
5 are weighted similarly, a result in accordance with the similar performance and simulated values  
6 exhibited by these methods (see Table 4 for details).

7 The application of the reliability factor leads to a decrease of the calculated total IRR in each grid  
8 cell as well as to a decrease of its overall uncertainty (Fig. 4). The uncertainty range is given by  
9 the ensemble average plus/minus the RMSE in each grid cell, assuming that modelling errors are  
10 normally distributed.

11 Exceedance probability curves might support defining thresholds in irrigation planning with  
12 consequences for decision makers through, for example, the adaptation of improved irrigation  
13 practice (e.g. from full to deficit irrigation, installation of advanced irrigation techniques) or the  
14 purchase of additional water rights. For example, a limit of available irrigation water of 400 mm  
15 per growing season will be exceeded less frequently in the MDB if the REA average IRR is  
16 considered (45%) in comparison to the equally weighted average (66%).

17 The spatial distribution of the equally weighted and the REA weighted ensemble averages are  
18 shown in Fig. 5a and b. The equally weighted average of IRR ranges between 124 and 691 mm  
19 with an average across the MDB of 424 mm (Fig. 5a). Thus, spatial variability is large and  
20 western and northern areas require five to six times more irrigation than in the south-east. The  
21 REA derived average IRR ranges between 104 mm and 663 mm across the river basin (Fig. 5b)  
22 with an average of 405 mm. Depending on the location this value is up to 18% lower as  
23 compared to simulations based on the equally weighted average (Fig. 5c). Also, the uncertainty  
24 range decreases as consequence of the REA method by about 10 % across the MDB with  
25 maximum values of around 26% when comparing equally and REA weighted RMSE (Fig. 5d-f).  
26 The largest change in uncertainty can be found in the south-east of the MDB and also in areas  
27 towards the east (Fig. 5f). Thus, REA not only leads to a decrease of predicted IRR but also to a  
28 reduction of its uncertainty. The uncertainty is reduced because the REA is drawn toward the  
29 group of the better  $ET_0$  methods that also agree well between themselves.

1

## 2 **4 Discussion and conclusions**

3 The simulation of IRR strongly varies amongst  $ET_o$  methods. Bormann (2011) recommended that  
4 the selection of the  $ET_o$  method should be based on the validation of  $ET_o$  with real world  
5 observations rather than only on the availability of climate input data. This is due to the general  
6 large variability among  $ET_o$  methods, which was also revealed in a study where PT was set as a  
7 benchmark model and the RMSE between  $ET_o$  methods was analysed (McMahon et al., 2013).  
8 Likewise, the influence of a single  $ET_o$  method on the prediction of crop yields was also reported  
9 for an agriculture site in Europe (Balkovič et al., 2013) where  $ET_o$  estimates by PT were 40%  
10 higher and those by Penman-Monteith 10% lower in comparison to HS. We also found a large  
11 variability among  $ET_o$  methods in our study. However, similar ranges across Australia for  $ET_o$   
12 have been reported by others (Chiew et al., 2002) for APET, PPET and PM56 as well as lower  
13 values for PT. Lascano *et al* (2010) as well as Lascano and Van Bavel (2007) have shown that  
14 methods to calculate  $ET_o$  based on combination methods, i.e., Penman-Monteith, tend to  
15 underestimate ET by as much as 25%, especially in dry climates.

16 Bormann (2011) further recommended that the reliability of  $ET_o$  equations should be tested in a  
17 spatial context, especially if applied on large scale. For various regions across Australia, a large  
18 range of mean annual  $ET_o$  between 1,700 mm (PT) and 3,670 mm (PPET) was reported  
19 (Donohue et al., 2010). To investigate the spatial heterogeneity within the MDB we analysed  
20 results of the 34 class-A pan stations. Overall, the performance of four of the  $ET_o$  methods was  
21 good with RMSEs around  $1 \text{ mm day}^{-1}$ , except for three stations in the north. PPET performed less  
22 well with RSME increasing to  $2 \text{ mm day}^{-1}$  while the PT value ranged up to  $4 \text{ mm day}^{-1}$ . However,  
23 we found no consistent spatial pattern. We are aware that the utilization of class-A pan data  
24 comes along with uncertainties. We did not assume that the data are error-free, but for the  
25 application of REA, a comparison of model simulations and observations is needed to calculate  
26 the model performance criterion. We could have treated PM56 as being an “observation” in terms  
27 of a benchmark model. However, we think that a more independent test is more appropriate in the  
28 sense of REA and therefore decided to use those observations that are at hand: class-A pan  
29 observations. To account for the difference of class-A pan evaporation and reference crop ET, we

1 used a commonly applied correction factor (pan-coefficients according to McMahon et al.  
2 (2013)) to derive crop ET from class-A pan measurements. Most often, ET estimates are not  
3 compared to any measurements at all, leaving modelers with no information on how good their  
4 model application is. We therefore think that a comparison to class-A pan is for sure not perfect,  
5 but better than not testing at all.

6  $ET_o$  estimates using the PM56 method revealed the best performance criteria in our study. PM56  
7 considers the most meteorological input parameters thereby possibly best representing the  
8 altering dry and wet conditions across the MDB over the year. The better performance of  
9 physically based equations in comparison to more empirical approaches for the simulation of  $ET_o$   
10 has also been reported by others (Donohue et al., 2010). PT performed least well in our study and  
11 resulted in up to two times larger estimates than other  $ET_o$  methods. This is somewhat contrasting  
12 with other studies (Chiew et al., 2002; Donohue et al., 2010) where PT gave lower  $ET_o$  values in  
13 comparison to methods such as APET and PPET. One reason is that Donohue et al. (2010) have  
14 considered the actual albedo from remotely sensed vegetation cover (Donohue et al., 2008) for  
15 the estimation of the net incoming solar radiation. In our calculations, an albedo of a reference  
16 crop 0.23 (short crop, i.e. grass) has been considered according to the guidelines for  $ET_o$  from  
17 Allen et al. (1998). Another likely reason for this observation is that the PT equation is based on  
18 the Penman-Monteith equation in which the aerodynamic term is replaced by a constant ( $\alpha$ )  
19 which is commonly set to 1.26 under Australian climatic conditions (Chiew and Leahy, 2003)  
20 and which we also applied. The consideration of region-specific  $\alpha$  for the MDB could have  
21 increased the performance of PT in our study. The HS equation is commonly applied in situations  
22 where meteorological data are scarce, because the equation depends on more readily available  
23 temperature and extra-terrestrial radiation derived from latitude and day of the year. A reason for  
24 its good performance in our study could be that the semi-arid climate in most of the MDB is  
25 favourable for the HS equation, which is supported by Tabari (2010) who conclude that HS is a  
26 good candidate model for warm humid and semi-arid sites, but fails under cold humid climates.  
27 However, the poor response of HS to changing climatic boundary conditions has also been  
28 criticized in a study on global drought simulations (Sheffield et al., 2012).

29 We combined the six  $ET_o$  methods with five  $K_c$  sets to address stochastic parametric uncertainty  
30 for irrigated wheat in the MDB. We show that the  $ET_o$  method uncertainty range exceeded the

1 uncertainty range of  $K_c$  sets. Thus, the  $K_c$  sets have a minor influence on predicted IRR. At first  
2 sight, this seems to be contrasting to others who have stated that adapted, regional  $K_c$  sets are  
3 required to estimate reliable IRR rates. For instance, da Silva et al. (2013) reported that  $K_c$  sets  
4 from FAO56 lead to errors in plot scale irrigation planning under tropical conditions. Similar  
5 observations were reported for semi-arid conditions in the Texas High Plains region (Ko et al.,  
6 2009), highlighting the importance of regionally based  $K_c$  sets. While regional adaptation of  $K_c$   
7 might be important at smaller scales, e.g. on the farm level, we conclude that large scale  
8 applications do not necessarily need to focus on this potential contribution of uncertainty. Rather,  
9 effort should be put into finding appropriate  $ET_o$  methods, or even better, utilize ensemble  
10 predictions to cover a more realistic range of predictions. Our study confirms this latter  
11 recommendation, as we could not identify a single best  $ET_o$  method for the MDB. Especially in  
12 cases where no data for a direct evaluation of model results are available the application of model  
13 ensembles gives insight to the predictive uncertainty, e.g., being helpful in the development of  
14 best management practices (Exbrayat et al., 2013), study of land use (Huisman et al., 2009) or  
15 climate change (Exbrayat et al., 2014).

16 Besides the uncertainty introduced by local to global  $K_c$  values the utilisation of the single crop  
17 coefficient concept itself comes along with errors, which are not addressed in this study. For  
18 example, Lascano (2000) shows how  $K_c$  varies as a function of time (50 days) and how it  
19 changes when using a daily, 3 and 8-day moving average. Moreover, the temporal resolution of  
20  $ET_o$  calculation, i.e., hourly vs. daily is an important component and errors associated with the  
21 method of irrigation (surface, drip, sprinkler) cannot be neglected, but are beyond the uncertainty  
22 calculation of this study. We acknowledge that we do not consider uncertainties in boundary  
23 conditions (e.g. land-use management options, climatic variability) although these may be non-  
24 negligible. For example, Bocchiola et al. (2013) reported that changes in future precipitation  
25 regimes will have the greatest impact on the calculated water footprint (reflecting high ET rates)  
26 of maize in Italy and that changes in  $CO_2$  and warming were less important. Conversely, water  
27 use was more driven by agricultural management than by regional climatic variation in a water  
28 footprint analysed for an irrigation district in China (Sun et al., 2013). Statistical correction of  
29 model forcing data (such as bias correction of precipitation) has also been reported to alter ET  
30 estimates as shown by Ye et al. (2012) for the Upper Yellow River in China with changes of up



1 to 29% of ET. Beyond that, the forcing data themselves introduce additional uncertainties.  
2 However, this is not part of this study and it would clearly go beyond the scope of our work  
3 presented here. Nevertheless, on the long term more research needs to be put in the investigation  
4 of the global predictive uncertainty of models, where all sources of uncertainty are evaluated, i.e.  
5 spatial input data uncertainty (e.g. soil and land use information), model forcing data uncertainty  
6 (e.g. climate data), parameter uncertainty, and model structure uncertainty. Thus, an even more  
7 complete picture of global model uncertainty can only be shown by considering all sorts of  
8 predictive uncertainty, including model input data, validation data, and spatial input data in  
9 addition to the impact of model structural and parametric uncertainty as presented here.

10 However, we argue that future management practices or the impact of climate change cannot be  
11 reliably evaluated due to the large uncertainty that exists in the  $ET_o$  method, the basis of water  
12 resources modelling. We partially cope with this problem by applying the REA technique to  
13 extract the most relevant information from our simulations. The advantage of REA in decision  
14 making has already been shown for other fields of research, such as the development of N  
15 reduction scenarios to improve surface water quality (Exbrayat et al., 2013) or estimation of the  
16 effect of land use change on water budgets and hydrological fluxes (Huisman et al., 2009).  
17 Despite the growing importance of IRR for today's agriculture (Siebert and Döll, 2010) and the  
18 effect on surface (Hoekstra et al., 2012) and groundwater (Wada et al., 2010) resources, few  
19 studies have dealt with the predictive uncertainty of this requirement (e.g. Wada et al. (2013))  
20 and how to reduce it.

21

## 22 **Acknowledgements**

23 We acknowledge the generous funding of the Deutsche Forschungsgemeinschaft (DFG, grant  
24 BR2238/11-1) that allowed a cooperation visit of the first author to CSIRO Land and Water and  
25 the ARC Centre of Excellence for Climate System Science in Australia. The research was further  
26 supported by a grant from KACST, Saudi-Arabia and the CAWa project (AA7090002).

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- 9

1

2 Table 1. The five crop parameter sets for  $K_c$ .

Name (Reference)	Spatial reference	$K_{c_{ini}}$	$K_{c_{mid}}$	$K_{c_{end}}$
FAO56 (Allen et al., 1998)	Global	0.7	1.15	0.25
Harris (Harris, 2002)	Queensland	0.3	1.15	0.25
Kirby (Kirby et al., 2012)	Murray-Darling Basin	0.4	1.15	0.4
Meyer (Meyer, 1999)	Griffith, MDB	0.4	1.05	0.5
Hughes (Hughes, 1999)	Murray and Murrumbidgee valleys	0.3	1.0	0.6

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2 Table 2. The six equations applied for the calculation of reference evapotranspiration.

Method	Abbreviation	Equation
FAO-56 Penman-Monteith (Allen et al., 1998)	PM56	$ETo_{PM56} = \frac{0.408 \cdot \Delta \cdot (R_n - G) + \gamma \cdot \frac{900}{T_{mean} + 273} \cdot u_2 \cdot (e_s - e_a)}{\Delta + \gamma \cdot (1 + 0.34 \cdot u_2)}$
Priestley-Taylor (Priestley and Taylor, 1972)	PT	$ETo_{PT} = \alpha \cdot \left[ \frac{\Delta}{\Delta + \gamma} \right] \cdot \frac{(R_n - G)}{\lambda}$
Hargreaves-Samani (Hargreaves and Samani, 1985)	HS	$ETo_{HS} = 0.0023 \cdot (T_{mean} + 17.8) \cdot (T_{max} - T_{min})^{0.5} \cdot R_a \cdot 0.408$
Turc (Allen, 2003; Turc, 1961)	TURC	$ETo_{TURC} = \alpha_T \cdot \frac{T_{mean}}{T_{mean} + 15} \cdot \frac{23.8856 \cdot R_s + 50}{\lambda}$
Areal – PET (Morton, 1983)	APET	$ETo_{APET} = b_1 + b_2 \left( \frac{1 + \gamma \cdot p}{\Delta} \right)^{-1} \cdot R_{TP}$
Point – PET (Morton, 1983)	PPET	$ETo_{PPETenergy-balance} = R_n - \lambda_p \cdot f_T \cdot (T_P - T_{mean})$ $ETo_{PPETvapor-transfer} = f_T \cdot (e_s - e_a)$

3 With  $ETo_{PM56}$ ,  $ETo_{PT}$ ,  $ETo_{HS}$ ,  $PET_{TURC}$ ,  $ETo_{APET}$ ,  $ETo_{Energy-Balance}$  and  $ETo_{Vapor-Transfer}$  in [mm], extra-  
4 terrestrial radiation  $R_a$ , solar radiation  $R_s$ , net radiation  $R_n$ , soil heat flux density  $G$  and net radiation at equilibrium  
5 temperature  $R_{TP}$  in [ $MJ\ m^{-2}$ ], equilibrium temperature  $T_P$ , mean  $T_{mean}$ , minimum  $T_{min}$  and maximum  $T_{max}$  air  
6 temperature in [ $^{\circ}C$ ], wind speed  $u_2$  at 2 m height [ $m\ s^{-1}$ ], atmospheric pressure  $p$ , saturated  $e_s$  and actual  $e_a$  vapour  
7 pressure in [kPa], slope of vapour pressure curve  $\Delta$  and the psychrometric constant  $\gamma$  in [ $kPa\ ^{\circ}C^{-1}$ ], latent heat of  
8 vaporization  $\lambda$  in [ $MJ\ kg^{-1}$ ], and the dimensionless empirical constants  $b_1$  and  $b_2$  [-], the heat transfer coefficient  $\lambda_p$  [-]  
9 ], the vapour transfer coefficient  $f_T$  [-] and the humidity based value  $\alpha_T$ .

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2 Table 3. Average equally weighted irrigation water requirement ( $\overline{IRR}$ ) [mm] during the growing  
3 season of wheat in all cells [n=3,969] of the MDB grouped by  $ET_o$  methods and  $K_c$  sets over the  
4 period 1986-2006 (APET: Areal potential evapotranspiration; PM56: FAO56 Penman Monteith;  
5 HS: Hargreaves-Samani; PPET: Point potential evapotranspiration; PT: Priestly-Taylor; TURC:  
6 Turc).

		Kc					$\overline{IRR}$
		Kirby	Hughes	Meyer	FAO56	Harris	
$ET_o$ method	HS	381	381	372	349	336	364
	PT	661	671	654	618	580	637
	PPET	577	577	565	534	514	551
	PM56	365	362	355	344	324	350
	APET	357	354	347	329	315	340
	TURC	315	316	308	289	279	301
	$\overline{IRR}$	443	443	433	410	391	424

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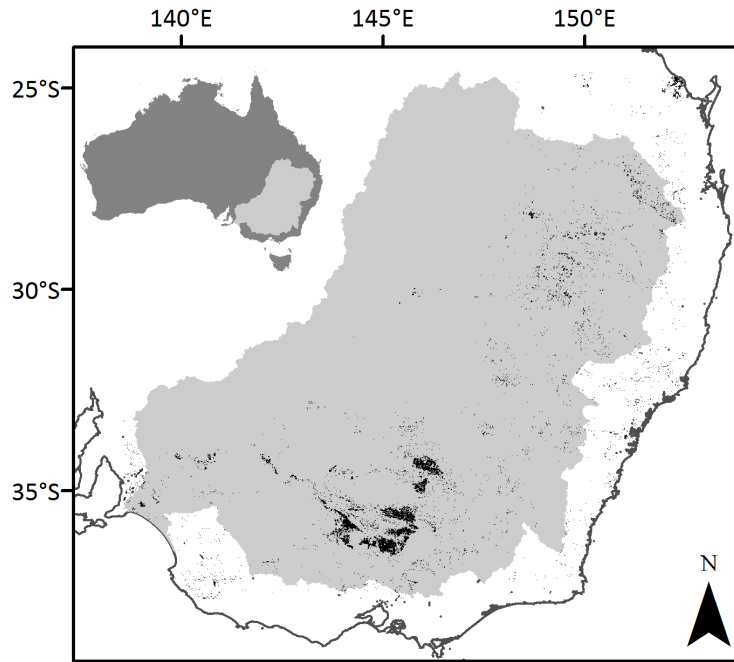
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2 Table 4. Performance ( $R_B$ ) and convergence ( $R_D$ ) and reliability ( $R$ ) coefficient of the ensemble  
3 members.

		FAO56	Harris	Hughes	Kirby	Meyer
APET	$R_B$	1	1	1	1	1
	$R_D$	1	1	1	1	1
	$R$	1	1	1	1	1
PPET	$R_B$	0.96	0.96	0.96	0.96	0.96
	$R_D$	0.99	1.00	0.99	0.99	0.99
	$R$	0.96	0.96	0.96	0.95	0.96
HS	$R_B$	1	1	1	1	1
	$R_D$	1	1	1	1	1
	$R$	1	1	1	1	1
PM56	$R_B$	1	1	1	1	1
	$R_D$	1	1	1	1	1
	$R$	1	1	1	1	1
T	$R_B$	1	1	1	1	1
	$R_D$	1	1	1	1	1
	$R$	1	1	1	1	1
PT	$R_B$	0.60	0.60	0.60	0.60	0.60
	$R_D$	0.98	1.00	0.85	0.88	0.90
	$R$	0.59	0.60	0.51	0.53	0.54

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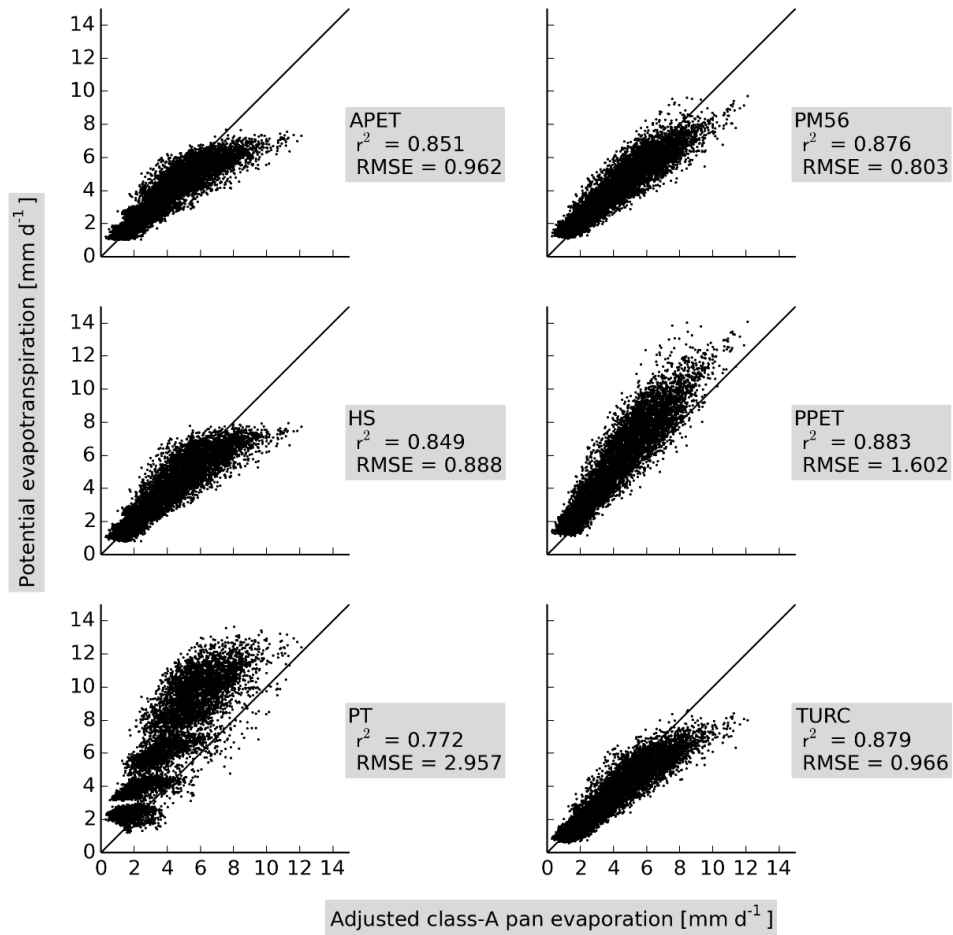


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3 Figure 1. The Murray-Darling basin (MDB) is located in south-east Australia. Irrigated wheat  
4 areas (2005/06) across the MDB are indicated as black dots, n=3,969; cell size=1 x 1 km.

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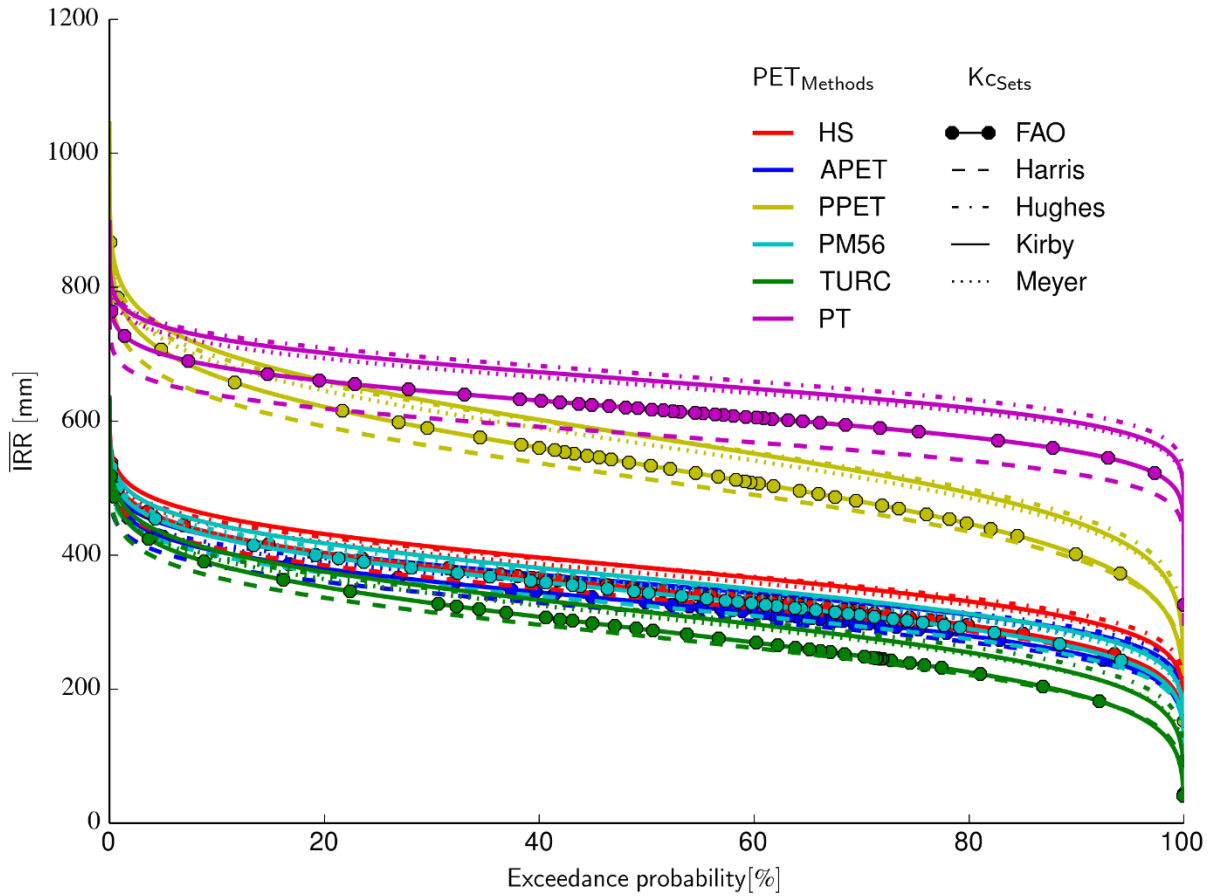
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3 Figure 2. Comparison of daily measured class-A pan evaporation with simulated potential  
4 evapotranspiration at 34 sites in the MDB during the time period from 1986 to 2006. The class-A  
5 pan measurements have been adjusted with site-specific pan coefficients. The coefficient of  
6 determination (r<sup>2</sup>) and the root mean square error (RMSE) are depicted for each ET<sub>0</sub> method  
7 (APET: Areal potential evapotranspiration; PM56: FAO56 Penman-Monteith; HS: Hargreaves-  
8 Samani; PPET: Point potential evapotranspiration; PT: Priestly-Taylor; TURC: Turc).

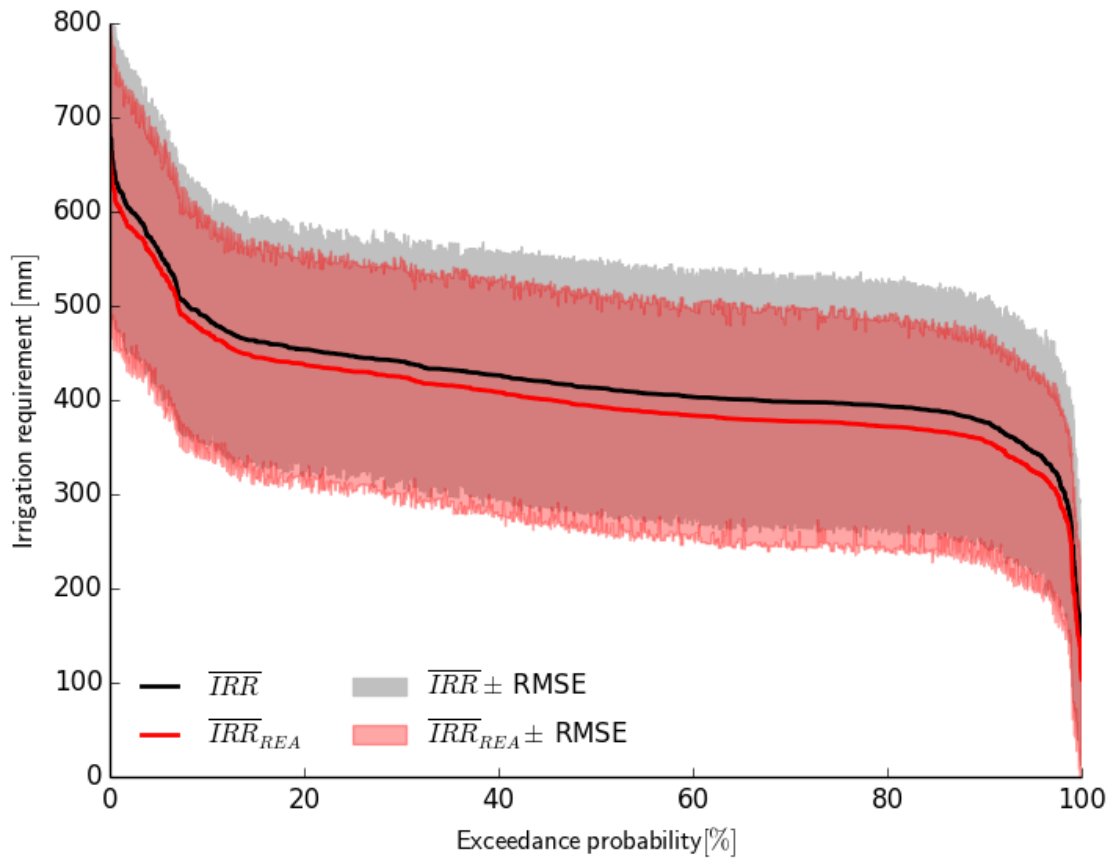
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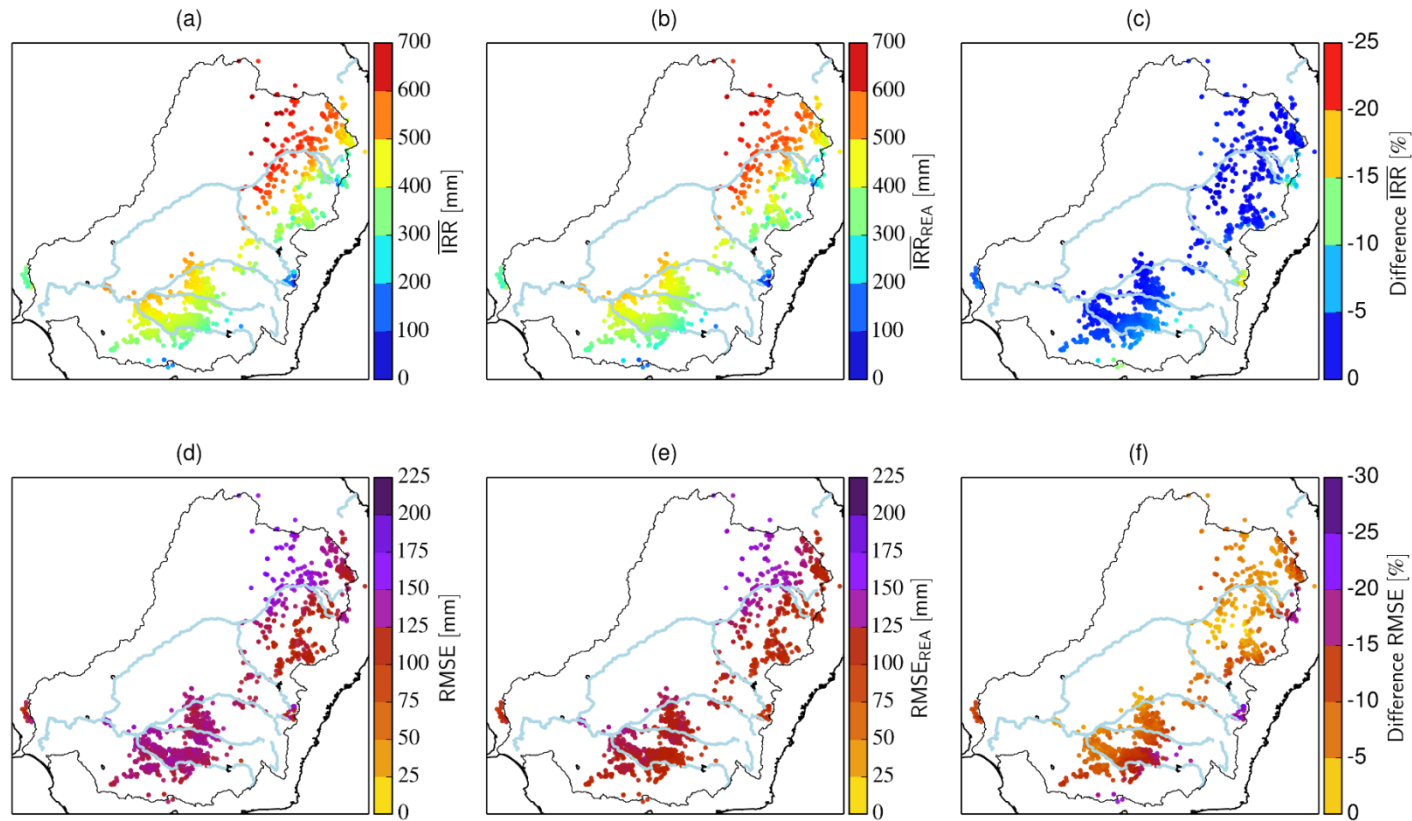
3 Figure 3 Exceedance probability of equally weighted average irrigation water requirement ( $\overline{IRR}$ )  
4 for wheat during the growing season. Averages have been calculated for each cropping area [n =  
5 3969 = 100%] for the period 1986-2006. Colours indicate different ET<sub>o</sub> methods (APET: Areal  
6 potential evapotranspiration; PM56: FAO56 Penman Monteith; HS: Hargreaves-Samani; PPET:  
7 Point potential evapotranspiration; PT: Priestly-Taylor; TURC: Turc) and symbols differentiate  
8 K<sub>c</sub> sets.

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3 Figure 4 Cumulative density function of equally weighted ( $\overline{IRR}$ ) and REA weighted ( $\overline{IRR}_{REA}$ )  
4 average irrigation water requirement for wheat during the growing season. Averages have been  
5 calculated for each cropping area [ $n = 3969 = 100\%$ ] for the period 1986-2006. Colours indicate  
6 the predicted root mean square difference (RMSE) of the ensemble of  $ET_0$  methods and Kc sets  
7 (APET: Areal potential evapotranspiration; PM56: FAO56 Penman Monteith; HS: Hargreaves-  
8 Samani; PPET: Point potential evapotranspiration; PT: Priestly-Taylor; TURC: Turc).



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2 Figure 5. Average equally weighted (a) and REA weighted (b) irrigation water requirement during the growing season of wheat (1986-  
 3 2006). Dots indicate irrigated cropping areas [n=3,969; cell size=1 x 1 km] (note: a buffer has been used to increase the visibility of the  
 4 single grid cells). (c) illustrates the difference between both IRR calculations (b-a). (d) and (e) show the root mean square error between  
 5 the 30 realizations and the equally weighted (d) and REA weighted (e) averages as well as the difference (f) between both calculations,  
 6 respectively.