

Supplement to The Wageningen Lowland Runoff Simulator (WALRUS): a lumped rainfall-runoff model for catchments with shallow groundwater

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1 Introduction

In this supplementary document we provide the main code for the Wageningen Lowland Runoff Simulator (WALRUS). The code is written in R and will be made available on the R CRAN website. WALRUS is licensed under the GPL v3 licence.

2 Script 1: loop over time steps

```
WALRUS_loop = function(p)
{
  # compute number of o_steps
  L = length(output_date)
  # make empty vectors for output states and fluxes
  o = data.frame(matrix(nrow=L, ncol=11, dimnames=list(NULL,
    c("ETact", "Q", "fGS", "fQS", "dV", "dVeq", "dG", "hS", "hQ", "W", "dt_ok"))))

  # look up soil type parameters
  p$b = soil_char[["b"]] [soil_char[["st"]]==p$st]
  p$psi_ae = soil_char[["psi_ae"]] [soil_char[["st"]]==p$st]
  p$theta_s = soil_char[["theta_s"]] [soil_char[["st"]]==p$st]
  p$aG = 1-p$aS

  # INITIAL CONDITIONS
  # Q[1] is necessary for stepsize-check (if dQ too large)
  o$Q [1] = func_Qobs(output_date[2]) / (output_date[2]-output_date[1]) *3600
  # hS from first Q measurement and Qh-relation
  o$hS [1] = uniroot(f=function(x){return(
    func_Q_hS(x,p,hSmin=func_hSmin(output_date[1]))-o$Q[1])},
    lower=0, upper=p$cD)$root

  # dG and hQ
  if(is.null(p$dG0)==FALSE) # if dG0 provided
  {
    o$dG [1] = p$dG0
    if((p$cD-o$dG[1])<o$hS[1]) # if groundwater below surface water level
    {
      o$hQ [1] = o$Q[1]*p$cQ # all Q from quickflow
    }else{ # if groundwater above surface water level
      o$hQ [1] = max(0,(o$Q[1]-(p$cD-o$dG[1]-o$hS[1])*(p$cD-o$dG[1])/p$cG) *p$cQ)
    }
  }
}
```

```

}else{
    # if dG0 not provided
    if(is.null(p$Gfrac)==TRUE){p$Gfrac=1} # if Gfrac also not provided , make Gfrac 1
    # if fGS not possible with current hS and cG, make Gfrac smaller
    while(((p$cD-o$hS[1])*p$cD/p$cG) < (p$Gfrac*o$Q[1])) {p$Gfrac = p$Gfrac/2}
    # compute dG leading to the right fGS
    o$dG [1] = uniroot(f=function(x){return((p$cD-x-o$hS[1])*(p$cD-x)/p$cG - o$Q[1]*p$Gfrac)},
        lower=1, upper=(p$cD-o$hS[1]))$root
    o$hQ [1] = o$Q[1] *(1-p$Gfrac) *p$cQ
}
# dependent variables
o$dVeq [1] = func_dVeq_dG(o$dG[1], p)
o$dV [1] = o$dVeq[1]
o$W [1] = func_W_dV(o$dV[1], p)

#
o_step = o[1,]
i = o[1,]

# RUN FOR-LOOP OVER ALL TIME STEPS
for (t in 2:L)
{
    start_step = output_date[t-1] # start at begin of output step
    end_step = output_date[t] # first try whole output step
    sums_step = rep(0,4) # to sum fluxes of substeps
    # as long as you're not at the end of the original time_step yet
    while(start_step < (output_date[t] - p_num$min_timestep))
    {
        o_step[1,] = WALRUS_step(p=p, i=i, t1=start_step, t2=end_step)
        # if time step too large (and not very small)
        if((o_step$dt_ok == FALSE) & ((end_step-start_step) > p_num$min_timestep))
        {
            end_step = (start_step + end_step)/2 # decrease step and run model
        }else{ # if one step completed (dt small enough)
            start_step = end_step # start of next step
            end_step = output_date[t] # try to the end of the step
            sums_step = sums_step + o_step[1:4] # remember sums of fluxes
            i = o_step # initial conditions for next step
        }
    }
    # final output of the step
    o[t, ] = o_step # keep states of last step
    o[t,1:4] = sums_step # replace fluxes with sums of steps
}

# remove dt_ok column
o = o[,1:10]

return(o)
} # end function

# compile to decrease runtime
WALRUS_loop = cmpfun(WALRUS_loop)

```

3 Script 2: one time step

```

WALRUS_step = function(p, i, t1, t2)
{
  #### FORCING
  # convert input to current stepsize [mm/timestep]
  P_t      = func_P      (t2) - func_P      (t1)
  ETpot_t  = func_ETpot(t2) - func_ETpot(t1)
  fXG_t    = func_fXG   (t2) - func_fXG   (t1)
  fXS_t    = func_fXS   (t2) - func_fXS   (t1)
  hSmin_t  = (func_hSmin(t2) + func_hSmin(t1))/2

  #### STEPSIZE
  dt       = (t2 - t1)/3600          # compute dt (in hours because parameters are in hours)
  dt_ok    = TRUE                    # stepsize small enough as default

  #### FLUXES (based on states from the start of this timestep [mm/timestep])
  PQ       = P_t * i$W                *p$aG
  PV       = P_t * (1-i$W)            *p$aG
  PS       = P_t                       *p$aS
  ETV      = ETpot_t * func_beta_dV(i$dV) *p$aG
  ETS      = ETpot_t                  *p$aS
  if(i$hS < p$num$h*1000){ETS = 0}      # no ET from empty channel
  ETact    = ETV + ETS
  fQS      = i$hQ                      /p$cQ *dt
  fGS      = (p$cD - i$dG - i$hS) * max((p$cD - i$dG), i$hS) /p$cG *dt
  Q        = func_Q_hS(i$hS, p=p, hSmin=hSmin_t) *dt

  #### STATES (at the end of this time step / start of next time step) [mm]
  # note that fluxes are already for the whole time step (multiplied with dt)
  dV       = i$dV - (fXG_t + PV - ETV - fGS) /p$aG
  hQ       = i$hQ + (PQ - fQS) /p$aG
  hS       = i$hS + (fXS_t + PS - ETS + fGS + fQS - Q) /p$aS
  dG       = i$dG + (i$dV - i$dVeq) /p$cV *dt

  #### SPECIAL CASE: LARGE-SCALE PONDING AND FLOODING
  if((dV < 0) | (hS > p$cD))
  {
    if((dV < 0) & (hS <= p$cD))          # if ponding and no flooding
    {
      hS = hS + (-dV) *p$aG /p$aS        # all ponds to surface water
      dV = 0                             # soil moisture deficit to surface
    }
    if((dV >= 0) & (hS > p$cD))          # if no ponding and flooding
    {
      dV = dV - (hS-p$cD) *p$aS /p$aG    # all floods into soil
      hS = p$cD                          # channel bankfull
    }
    if((dV <= 0) & (hS >= p$cD))          # if ponding and flooding
    {
      dV = dV*p$aG - (hS-p$cD)*p$aS      # compute total excess water
      hS = p$cD - dV
    }
  }
}

```

```

    }
    if(dV < 0){dG = dV}           # if ponding, groundwater to pond level
}

#### TEST IF STEP SIZE IS SMALL ENOUGH
if(hS < -p_num$min_h)           # if hS below channel bottom
{
  dt_ok = FALSE
  hS = p_num$min_h*100
}else if(hQ < -p_num$min_h)     # if hQ below bottom Q-res.
{
  dt_ok = FALSE
  hQ = p_num$min_h
}else if(P_t > p_num$max_P_step) # if too much rainfall added
{
  dt_ok = FALSE
}else if(abs(i$Q-Q) > p_num$max_dQ_step) # if change in Q too big
{
  dt_ok = FALSE
}else if(abs(i$hS-hS) > p_num$max_h_change) # if change in hS too big
{
  dt_ok = FALSE
}else if(abs(i$dG-dG) > p_num$max_h_change) # if change in dG too big
{
  dt_ok = FALSE
}

#### OUTPUT
# compute dependent variables (at end of time step)
W      = func_W_dV(dV,p)
dVeq   = func_dVeq_dG(dG,p)

# bind output together in a vector
return(c(ETact, Q, fGS, fQS, dV, dVeq, dG, hS, hQ, W, dt_ok))

} # end function

# compile to decrease runtime
WALRUS_step = cmpfun(WALRUS_step)

```