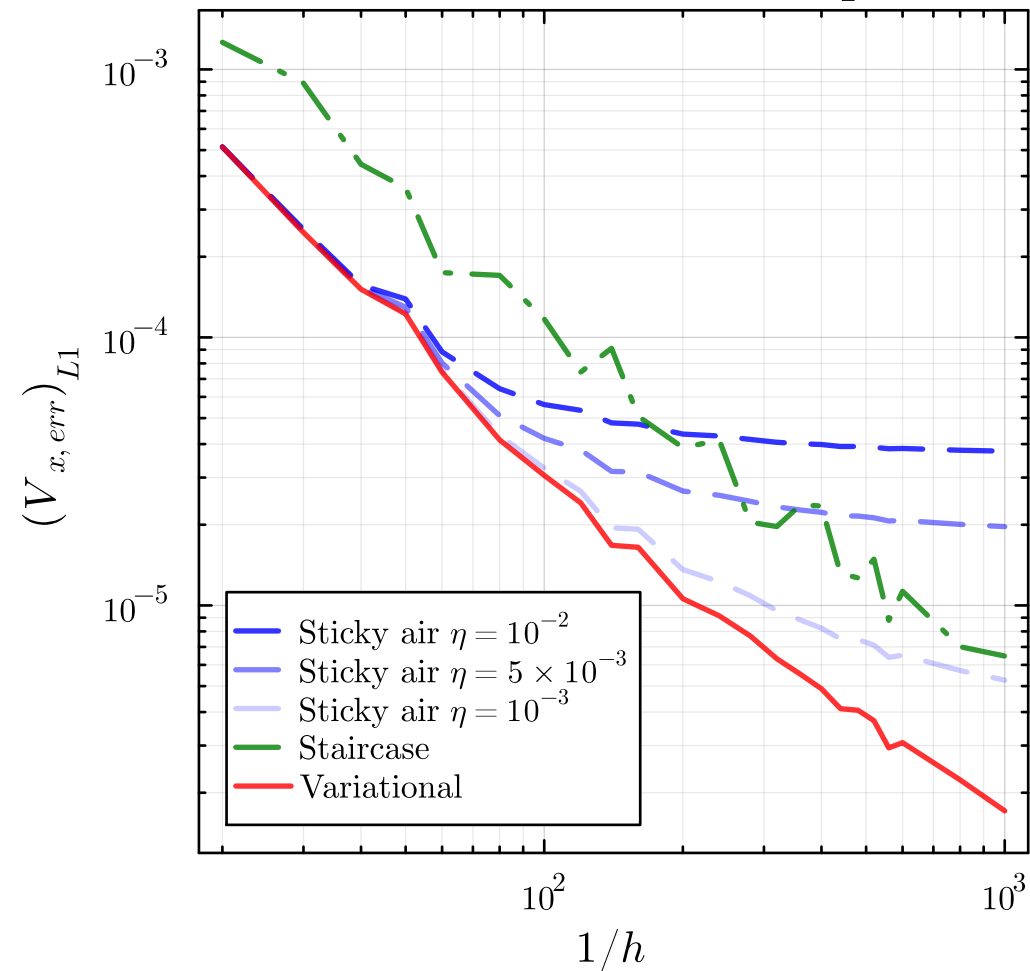


x-velocity errors L_1 y-velocity errors L_1 