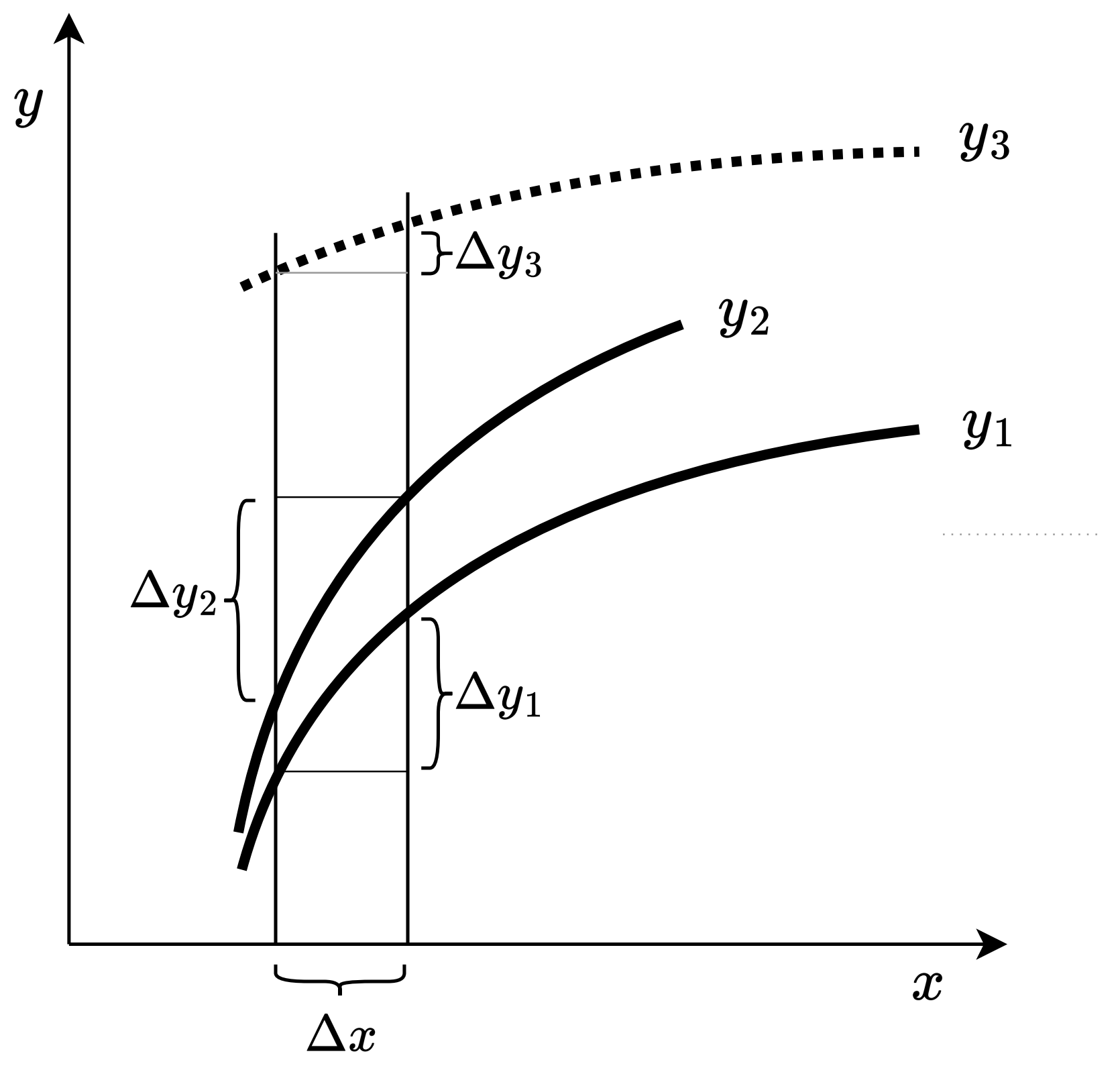
y
x
y_3
y_2
y_1
Δy_3
Δy_2
Δy_1
Δx