

```
import numpy as np
import gstools as gs

# define main axes by yaw, pitch and roll
angles = np.deg2rad([45, 0, 0])
# anisotropy ratios y / x and z / x
anis = [1 / 2, 1 / 4]
model = gs.Exponential(dim=3, anis=anis, angles=angles)
model.plot("cov_spatial")
```

Plane

- x - y
- x - z
- y - z

