



Supplement of

Ground-based lidar processing and simulator framework for comparing models and observations (ALCF 1.0)

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- gmd-14-43-2021-supplement-title-page.pdf
- alcfn-1.0.0
 - .editorconfig
 - .gitignore
 - LICENSE.md
 - Makefile
 - README.md
 - alcfn
 - * __init__.py
 - * algorithms
 - * cmds
 - * lidars
 - * misc.py
 - * models
 - * opt
 - bin
 - * alcfn
 - * cosp_alcf
 - build_dep
 - cmor_patch.diff
 - cosp_patch.diff
 - download_dep
 - mie_scattering
 - * README.md
 - * bin

```
* miev
* out
* plot
- setup.py
- src
  * cosp_run.f03
  * main.f03
  * nc_utils.f03
- watch
```

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