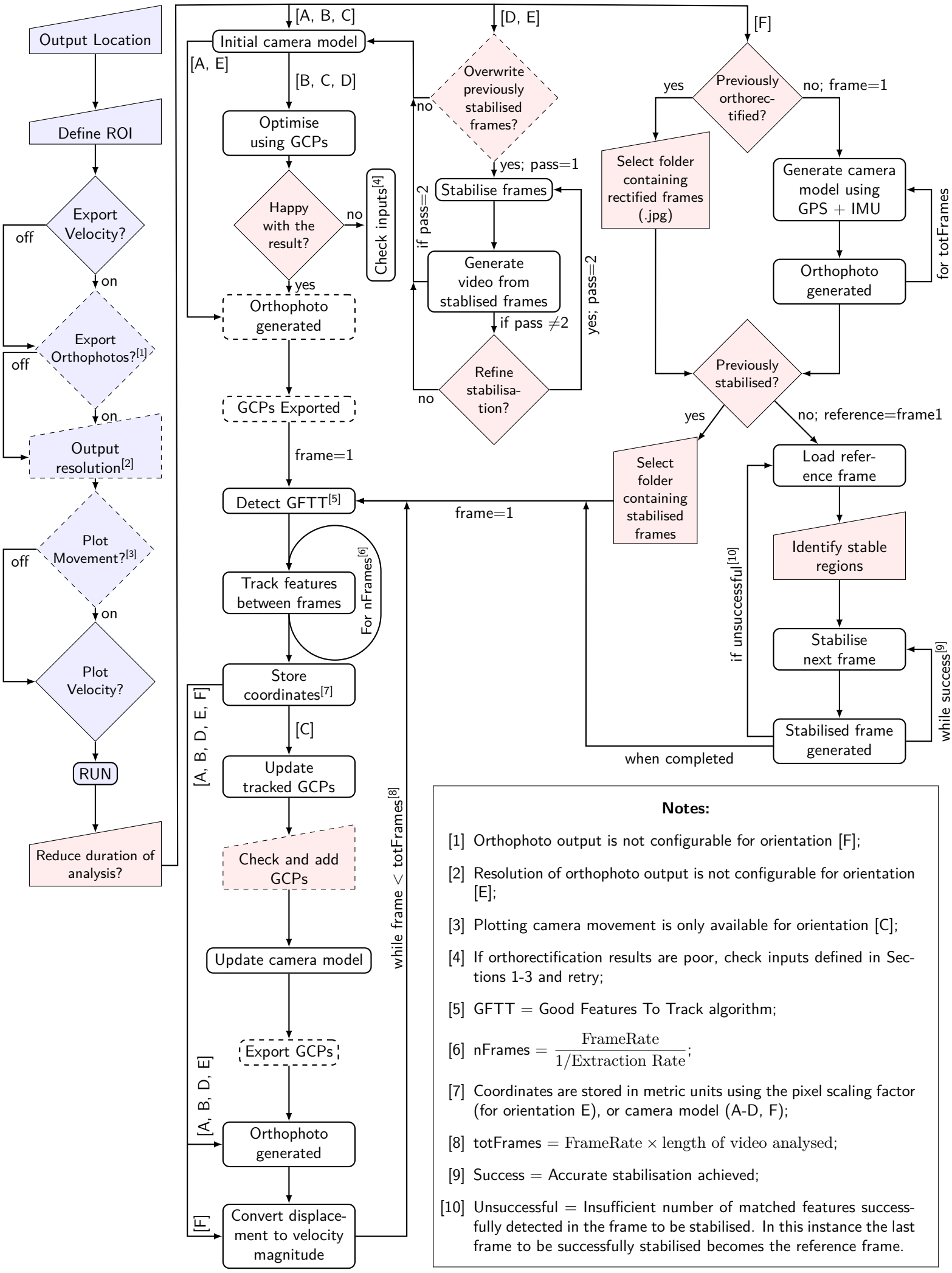

Notes:

[1] Orthophoto output is not configurable for orientation [F];

[2] Resolution of orthophoto output is not configurable for orientation [E];

[3] Plotting camera movement is only available for orientation [C];

[4] If orthorectification results are poor, check inputs defined in Sections 1-3 and retry;

[5] GFTT = Good Features To Track algorithm;

[6] nFrames = $\frac{\text{FrameRate}}{1/\text{Extraction Rate}}$;

[7] Coordinates are stored in metric units using the pixel scaling factor (for orientation E), or camera model (A-D, F);

[8] totFrames = $\text{FrameRate} \times \text{length of video analysed}$;

[9] Success = Accurate stabilisation achieved;

[10] Unsuccessful = Insufficient number of matched features successfully detected in the frame to be stabilised. In this instance the last frame to be successfully stabilised becomes the reference frame.